



TECHNISCHE FAKULTÄT

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AnyDSL - A Framework for Rapid Development of Domain-Specific Libraries



Interactions using Partial Evaluation

The AnyDSL Approach to Code Generation

- Uniform syntax for the static and dynamic parts of a program
- Code generation is triggered through Partial Evaluation
- Typesafe template metaprogramming without additional syntax

Template Metaprogramming in C++ Partial Evaluation in Impala

Kernel Generation through Partial Evaluation

- The execution of a certain computation on a system of particles can be expressed as the following higher-order function:
 - fn execute(particles: Particles, kernel: fn(i32, i32, i32) -> ()) -> ();
- By partially evaluating execute with respect to its second argument, code generation is triggered
- ► All details about the target platform are hidden within its implementation
- ► To generate code for different platforms, different implementations must be provided

Kernel Generation on the CPU

- The AnyDSL runtime library provides functionality for automatic parallelization and vectorization on the CPU
 - fn execute(particles: Particles, @kernel: fn(i32, i32, i32) -> ()) -> () {
 - // Thread-parallel execution
 parallel(get_number_of_threads(), i, 0, particles.number_of_clusters, |ci| {
 - let cluster_size = get_cluster_size();
 - let begin = ci * cluster_size;
 - // Vectorization using RV
 - vectorize(cluster_size, get_alignment(), 0, cluster_size, |i| {
 - let pi = begin + i;
 - kernel(pi, ci, cluster_size);
 - });

});

template <int N> struct Factorial {
 enum{
 value = N*Factorial<N-1>::value
 };
 ;
 template <> struct Factorial<0> {
 enum {value = 1};
 };
 };

Molecular Dynamics



- Simulation of the trajectories of a large number of particles based on their interactions
- The computation of short-range interactions is an important use case in many simulations
- Most implementations employ a combination of cell decomposition and neighbor lists

Computing Pairwise Interactions Efficiently on Modern Architectures

Kernel Generation on the GPU

For execution on GPU hardware, the accelerator struct can be employed, which supports CUDA, NVVM and OpenCL as backend fn execute(particles: Particles, @kernel: fn(i32, i32, i32) -> ()) -> () { let acc = get_accelerator(device_id); let grid = (particles.number_of_clusters * get_cluster_size(), 1, 1); let block = (get_cluster_size(), 1, 1); acc.exec(grid, block, |bid, bdim, gid| { let (gidx, _, _) = gid; let (bidx, _, _) = bid; let (bdimx, _, _) = bdim; kernel(gidx(), bidx(), bdimx()); }); acc.sync(); }

Single-Core Performance in FLOPS/cycle

- ► AnyDSL: LLVM version 5.0.1 with RV for vectorization, -O3, -march=native
- MiniMD: Intel C compiler version 18 with -O3, -xHost, -qopt-zmm-usage=high (SKL)

Processor	AnyDSL	MiniMD
Skylake	5.816 (AVX512)	3.618 (AVX512)
Broadwell	2.928 (AVX2)	1.695 (AVX2)
Ivy Bridge	2.103 (AVX)	1.034 (AVX)

- In 2013 Páll and Hess presented an adaption of the neighbor list scheme to modern SIMD and GPU architectures
- Particles are not treated individually but as a cluster of N particles
- Interactions are computed between clusters
- Choosing N according to the SIMD/SIMT width enables data parallel computation



Acceleration on the GPU

- CPU test platform: Intel Xeon E3-1275 v5 with four cores
- ► GPU test platform: NVIDIA GTX 1080, AnyDSL Backend: NVVM, Cluster size: 32
- Double-precision floating-point computations
- ► The generated GPU code runs around 5 times faster

Particles	AnyDSL (AVX2)	AnyDSL (GPU)
100 000	1044.39 ms	194.101 ms
500 000	4300.2 ms	826.627 ms
1 000 000	7652.97 ms	1684.18 ms
2000000	15014.7 ms	3294.85 ms

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