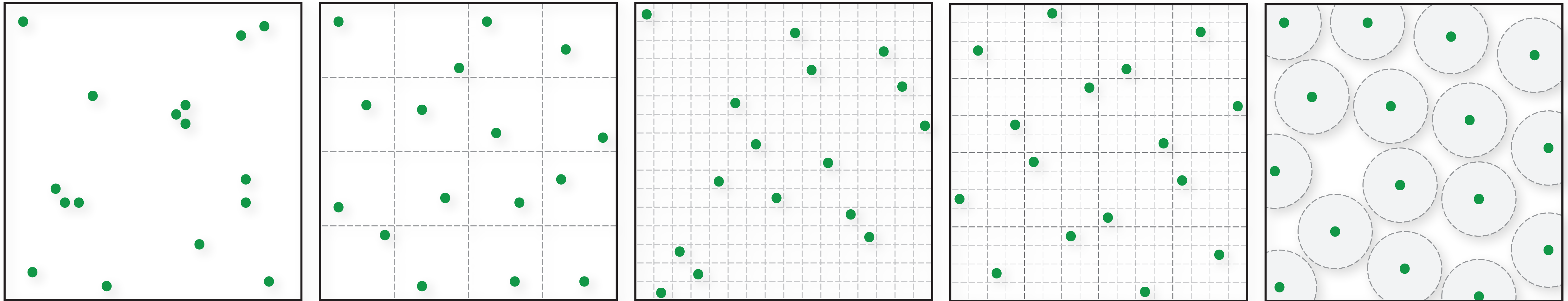


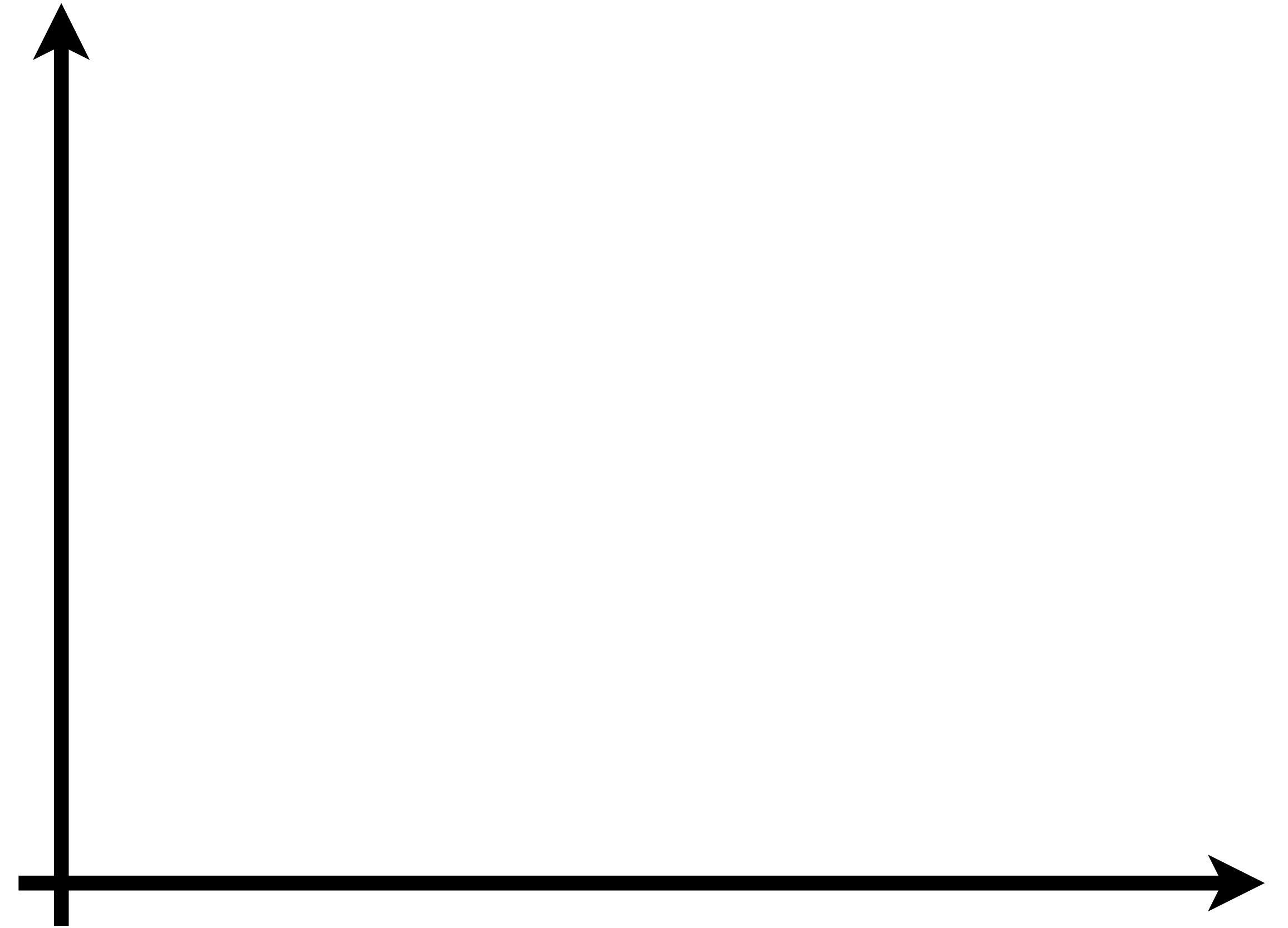
ADVANCED SAMPLING



Philipp Slusallek Karol Myszkowski
Gurprit Singh

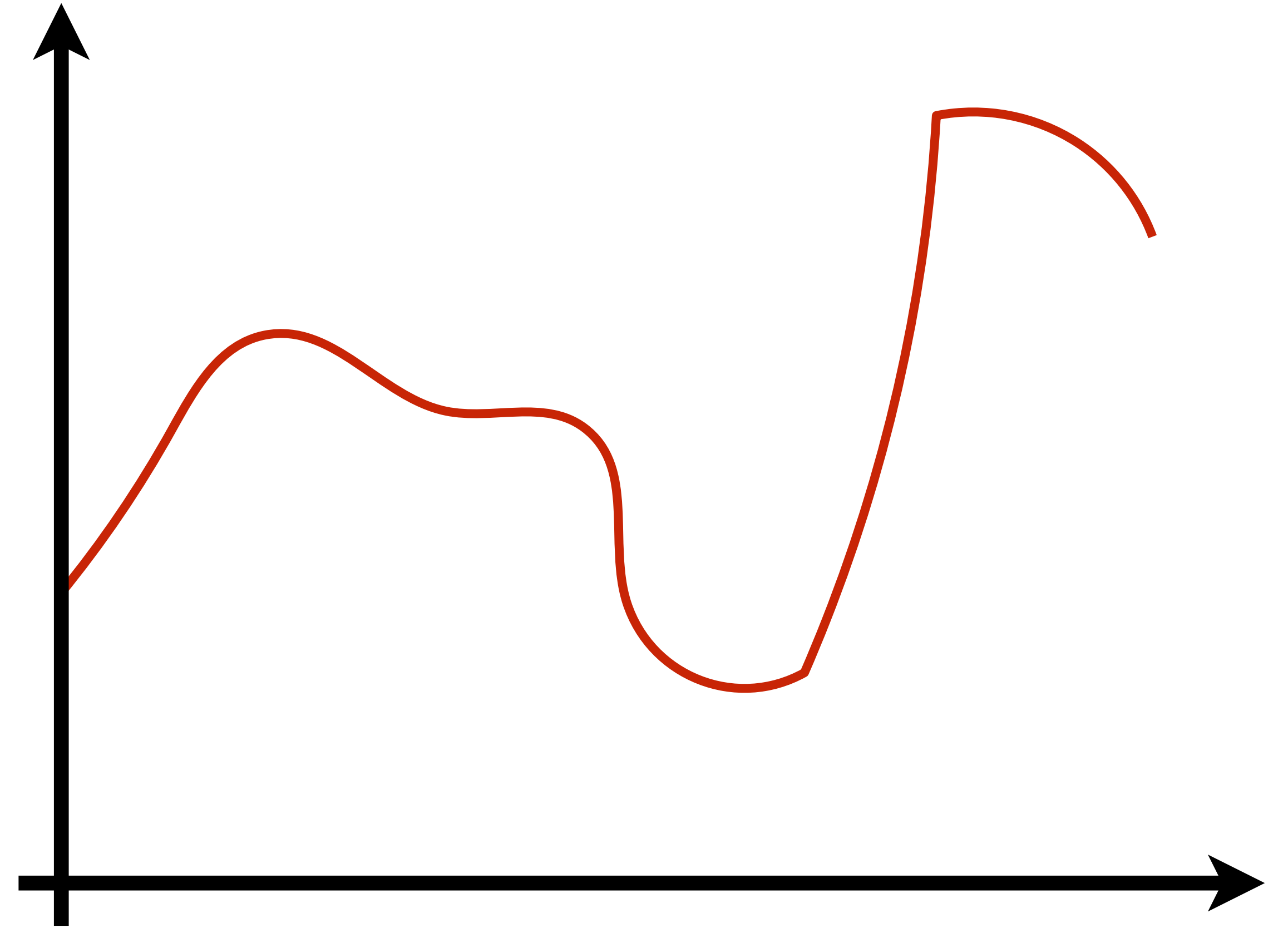
Recall: Monte Carlo Integration

$$I = \int_D f(x) \, dx$$



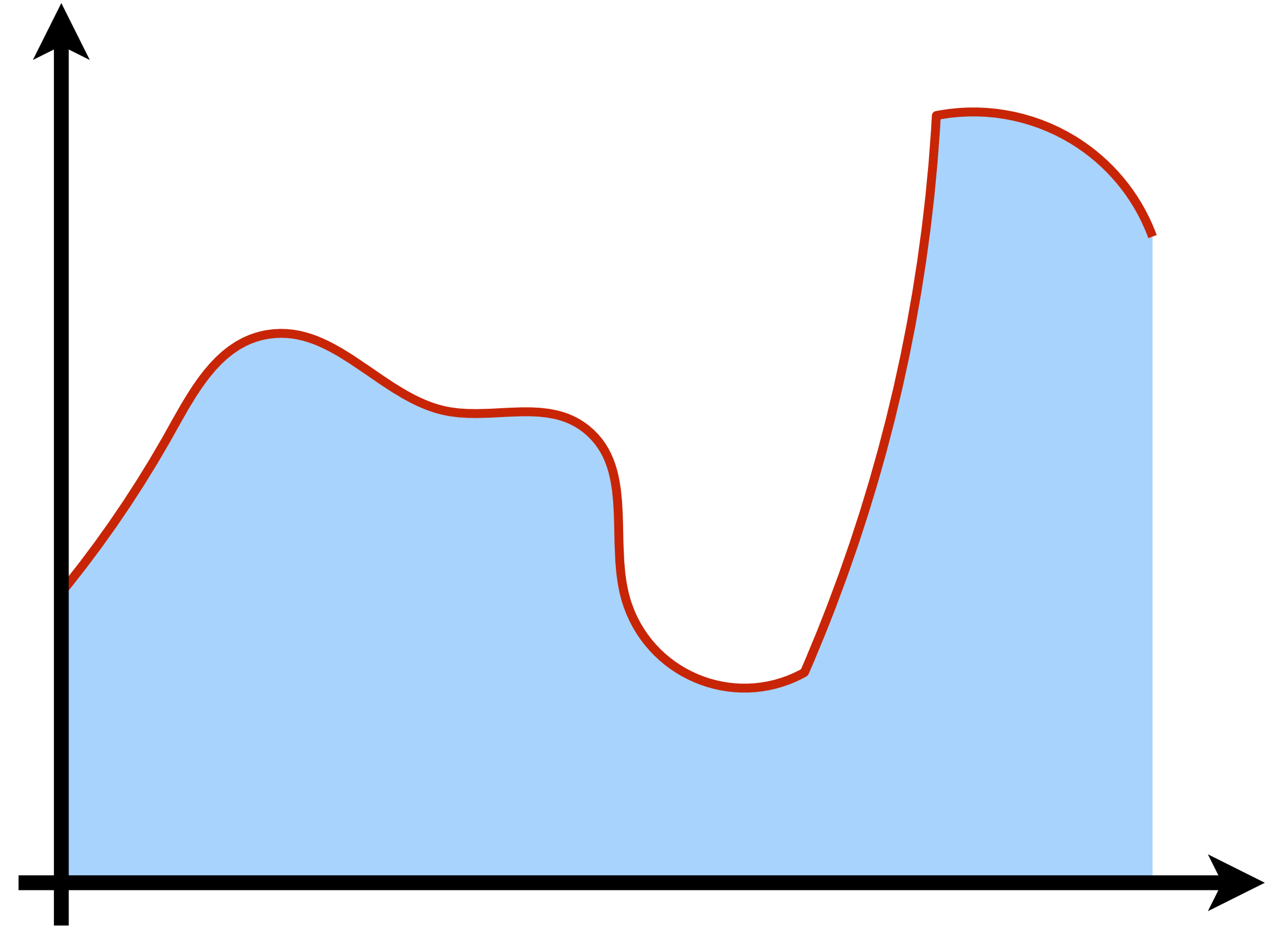
Recall: Monte Carlo Integration

$$I = \int_D f(x) \, dx$$



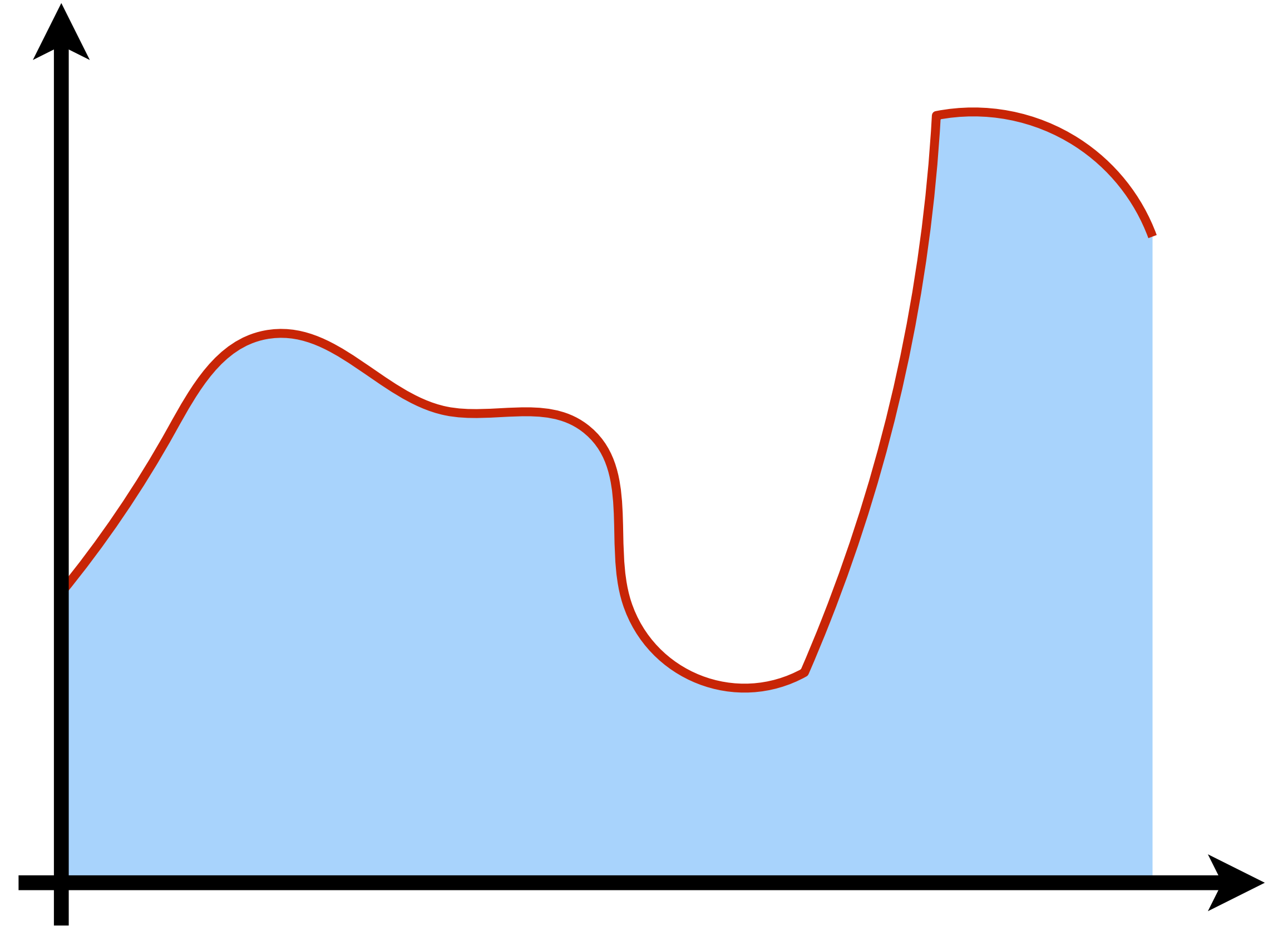
Recall: Monte Carlo Integration

$$I = \int_D f(x) \, dx$$



Recall: Monte Carlo Integration

$$I = \int_D f(x) \, dx$$
$$\approx \int_D f(x) \mathbf{S}(x) \, dx$$

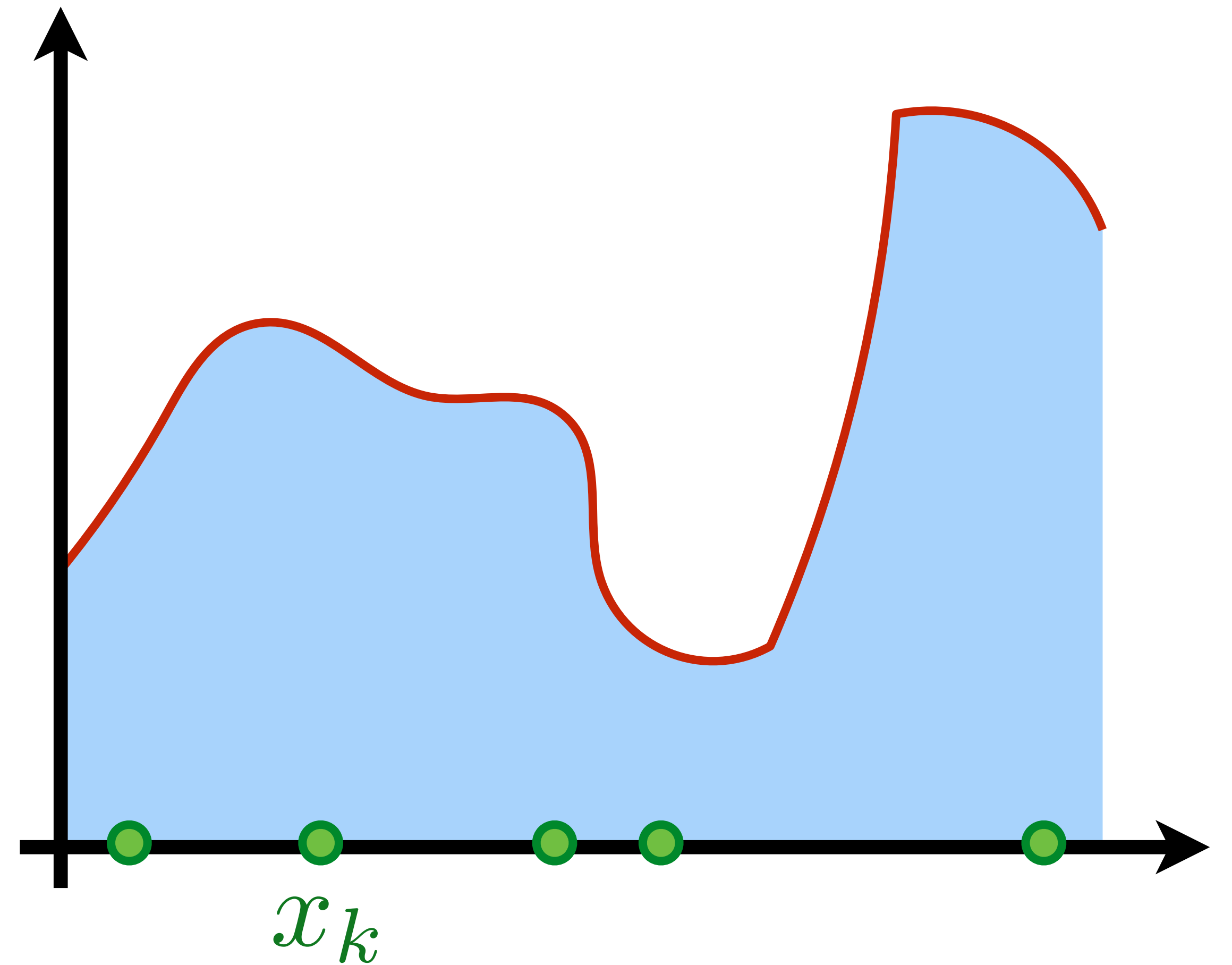


Recall: Monte Carlo Integration

$$I = \int_D f(x) \, dx$$

$$\approx \int_D f(x) \mathbf{S}(x) \, dx$$

$$\mathbf{S}(x) = \frac{1}{N} \sum_{k=1}^N \delta(x - \boxed{x_k})$$

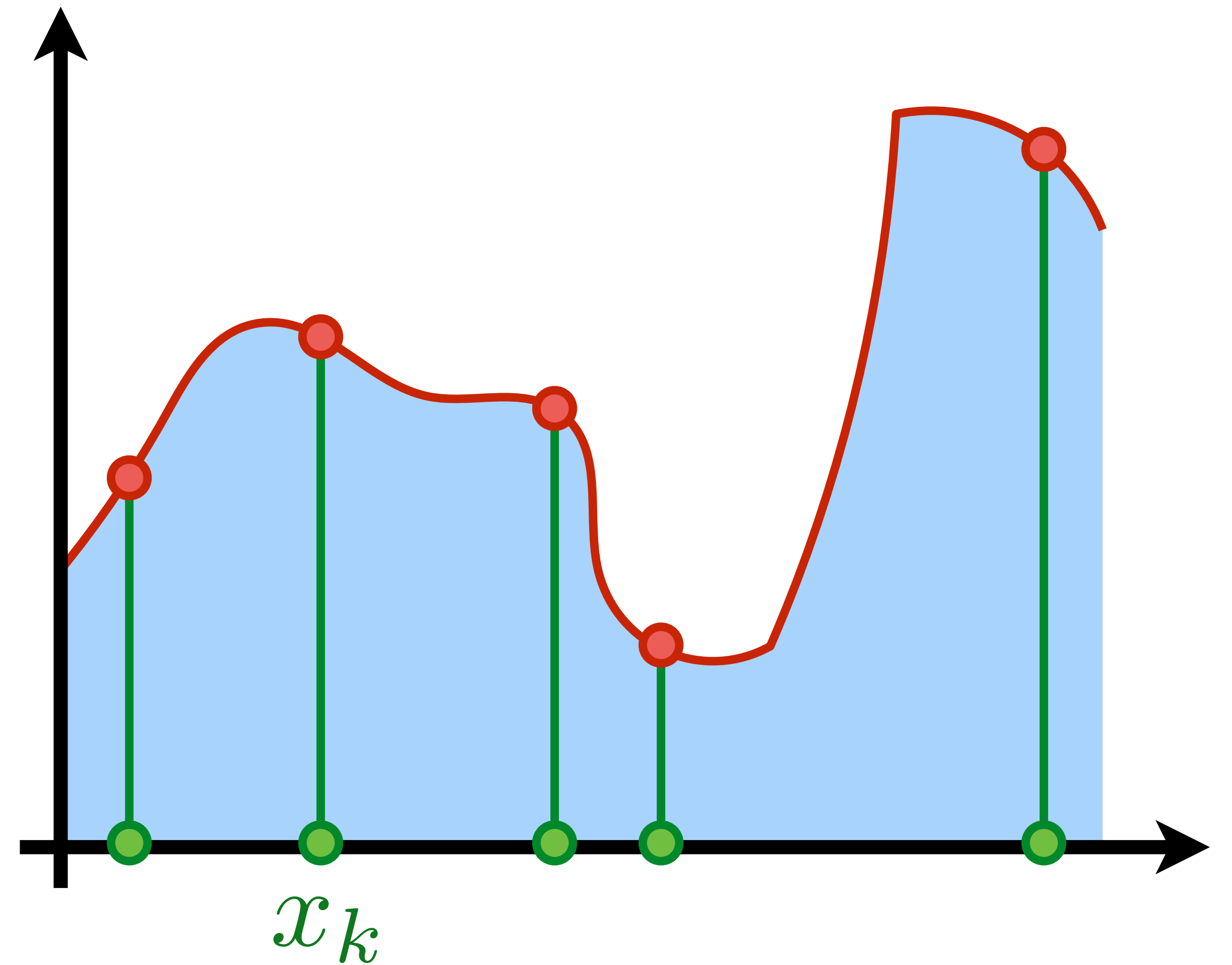


Recall: Monte Carlo Integration

$$I = \int_D f(x) \, dx$$

$$\approx \int_D f(x) \mathbf{S}(x) \, dx$$

$$\mathbf{S}(x) = \frac{1}{N} \sum_{k=1}^N \delta(x - \boxed{x_k})$$



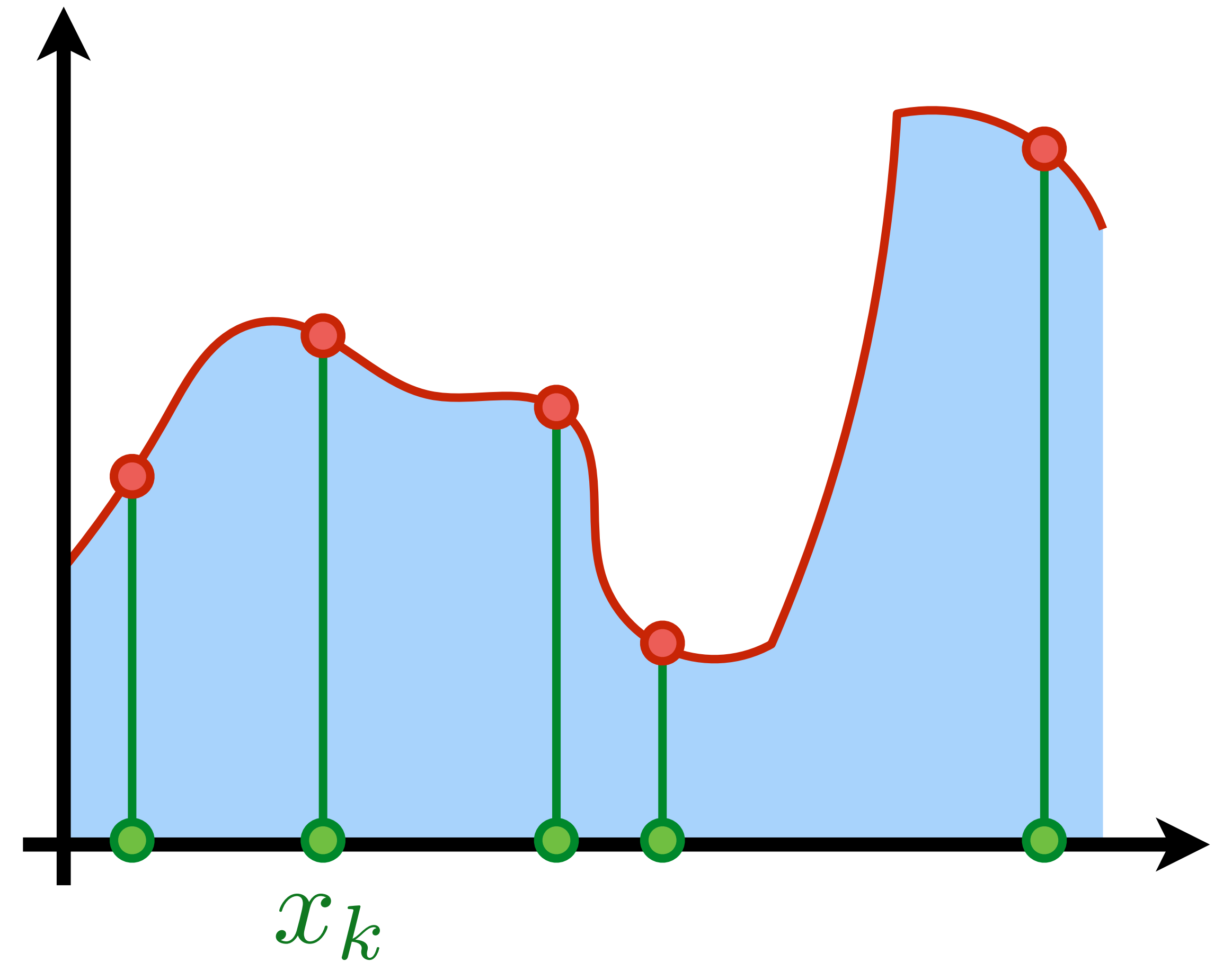
Recall: Monte Carlo Integration

$$I = \int_D f(x) \, dx$$

$$\approx \int_D f(x) \mathbf{S}(x) \, dx$$

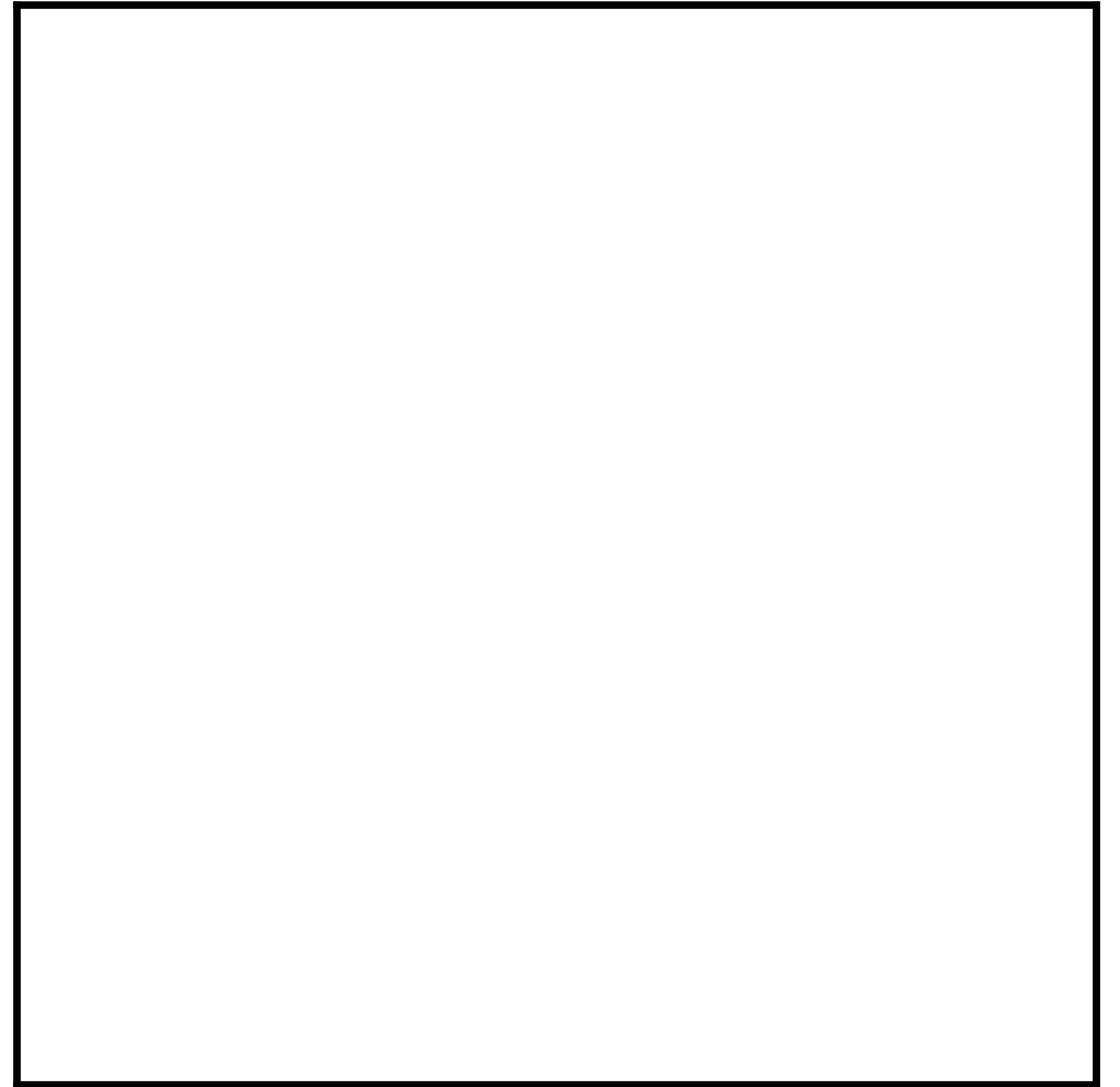
$$\mathbf{S}(x) = \frac{1}{N} \sum_{k=1}^N \delta(x - \boxed{x_k})$$

How to generate the
locations x_k ?



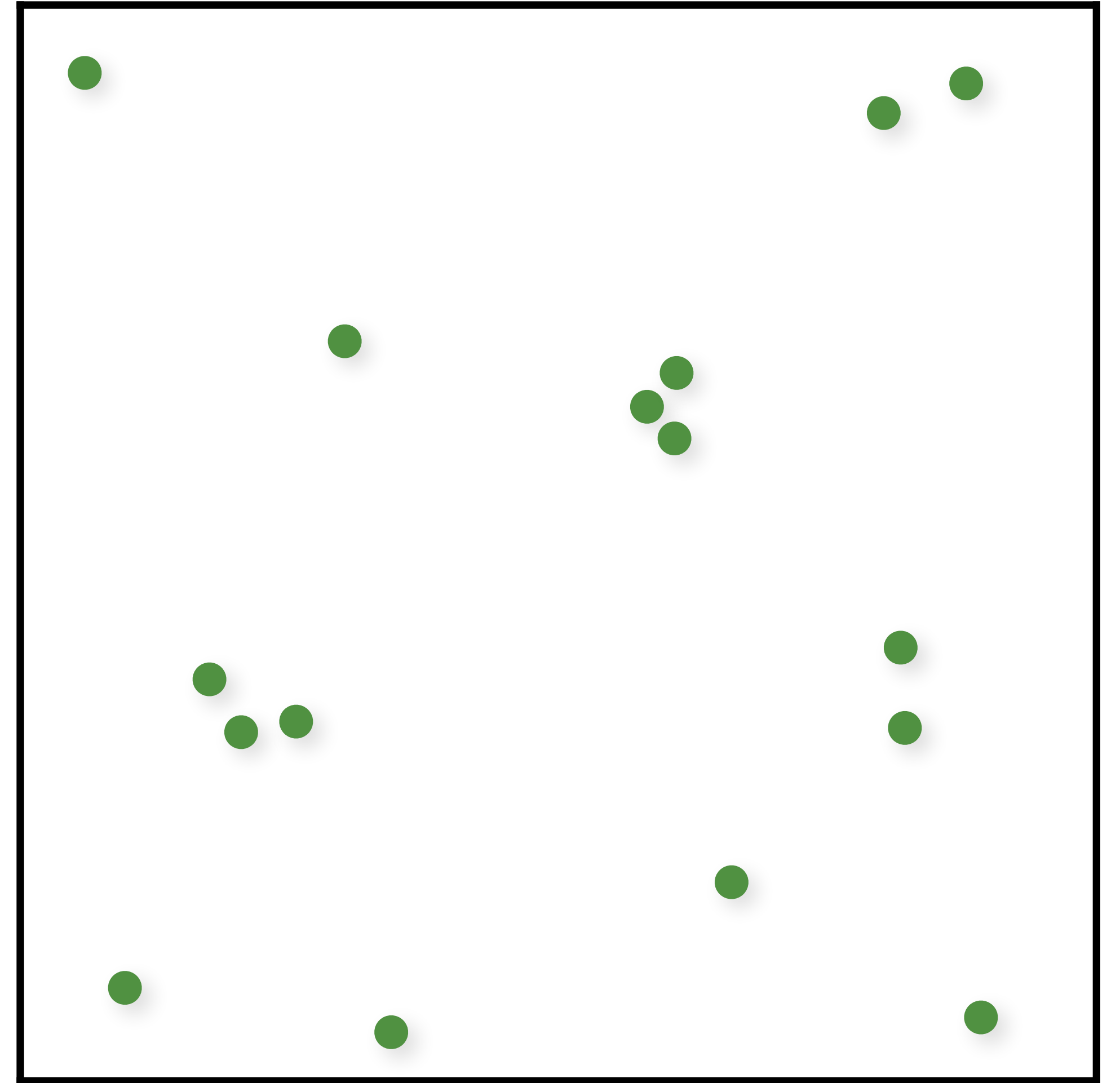
Independent Random Sampling

```
for (int k = 0; k < num; k++)  
{  
    samples(k).x = randf();  
    samples(k).y = randf();  
}
```



Independent Random Sampling

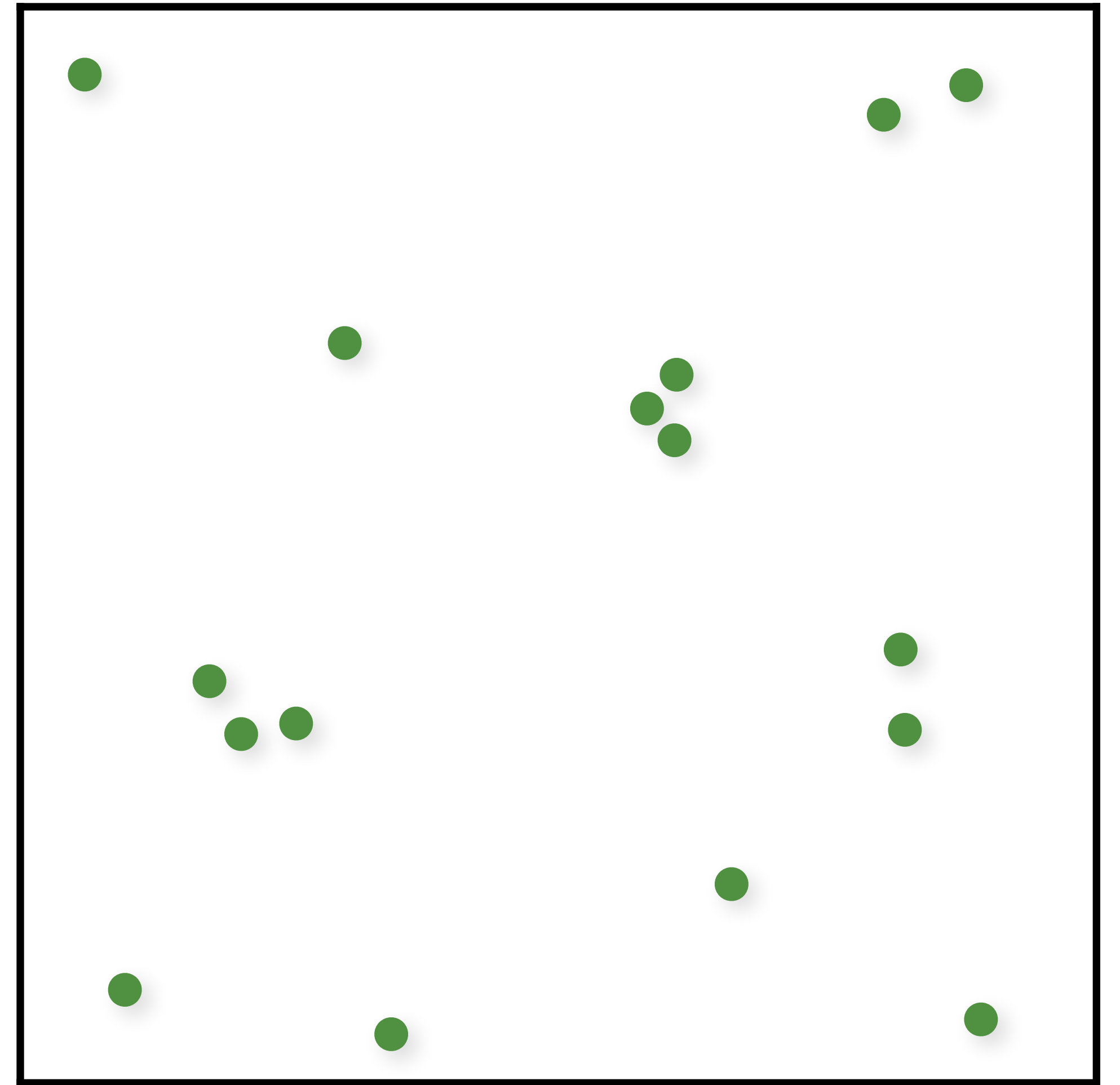
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}
```



Independent Random Sampling

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}
```

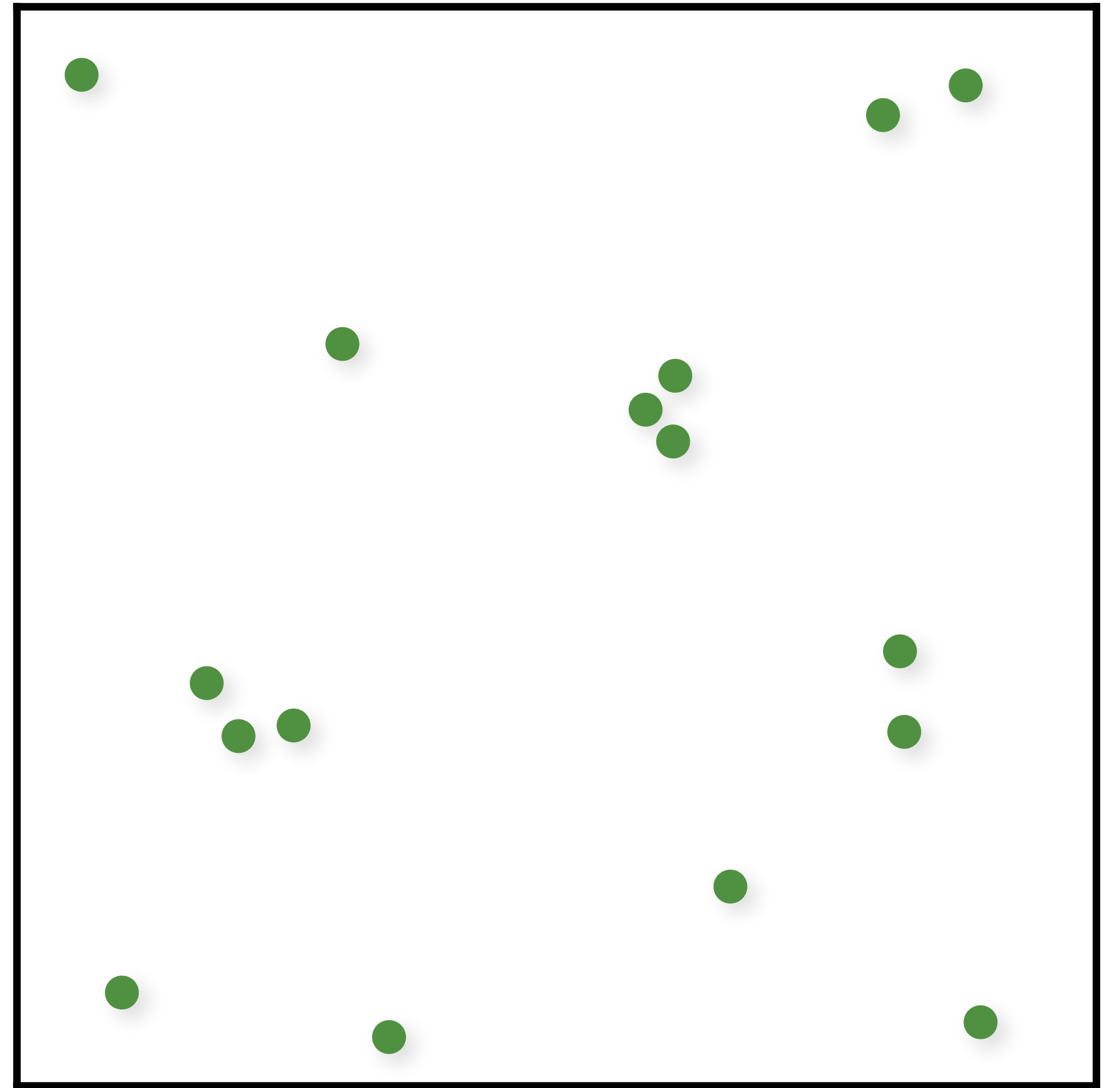
✓ Trivially extends to higher dimensions



Independent Random Sampling

```
for (int k = 0; k < num; k++)  
{  
    samples(k).x = randf();  
    samples(k).y = randf();  
}
```

- ✓ Trivially extends to higher dimensions
- ✓ Trivially progressive and memory-less



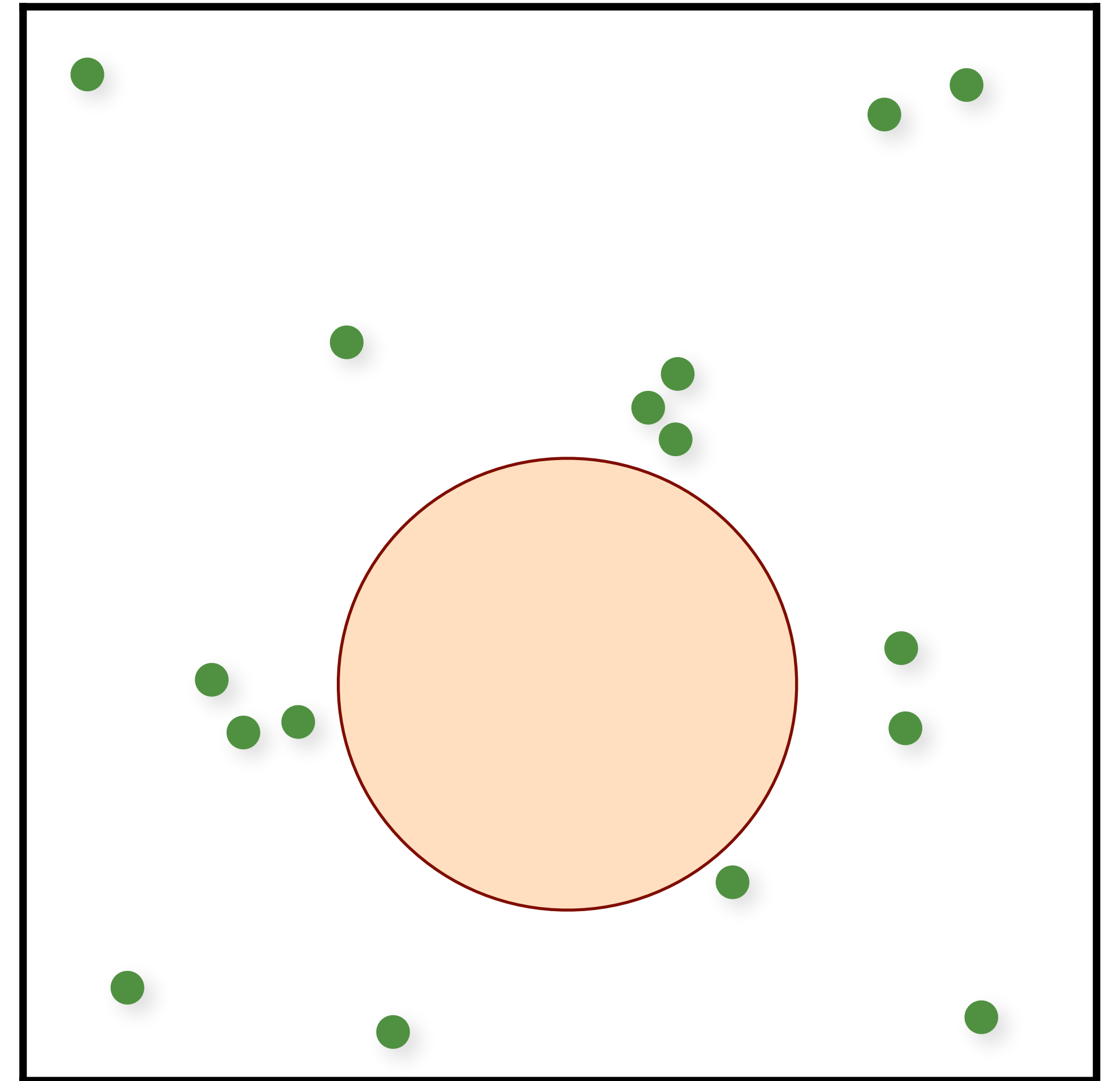
Independent Random Sampling

```
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{  
    samples(k).x = randf();  
    samples(k).y = randf();  
}
```

✓ Trivially extends to higher dimensions

✓ Trivially progressive and memory-less

✗ Big gaps



Independent Random Sampling

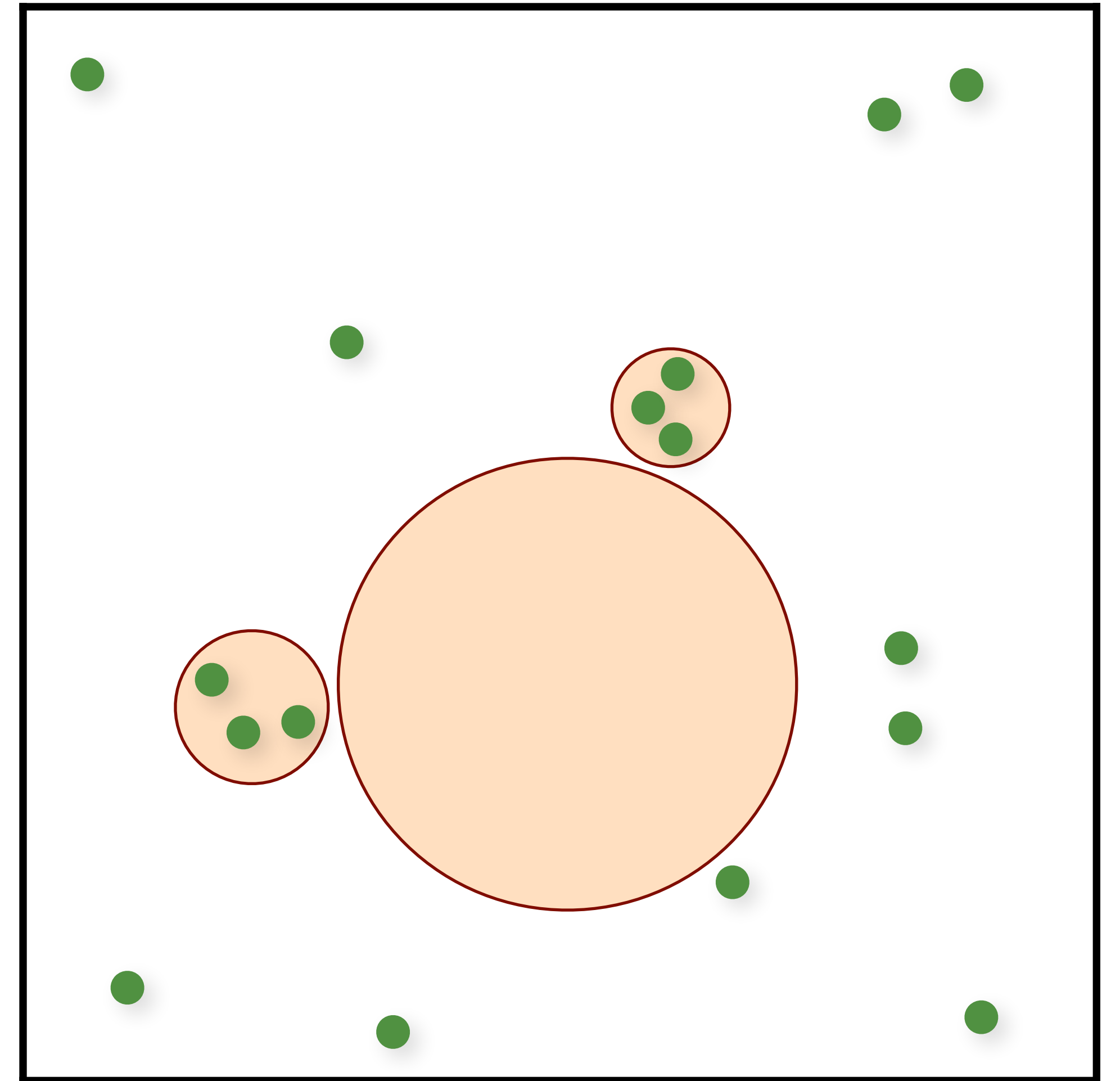
```
for (int k = 0; k < num; k++)  
{  
    samples(k).x = randf();  
    samples(k).y = randf();  
}
```

✓ Trivially extends to higher dimensions

✓ Trivially progressive and memory-less

✗ Big gaps

✗ Clumping



Recall: Fourier Theory

Input Image

Power Spectrum

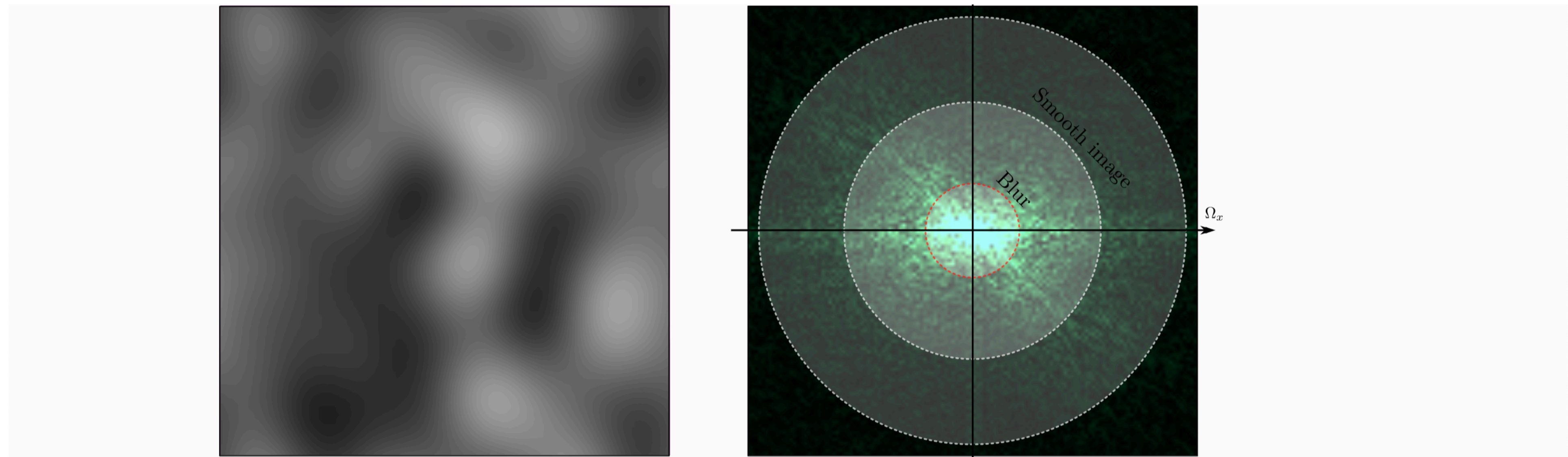


Image courtesy: Laurent Belcour

Recall: Fourier Theory

Input Image



Power Spectrum

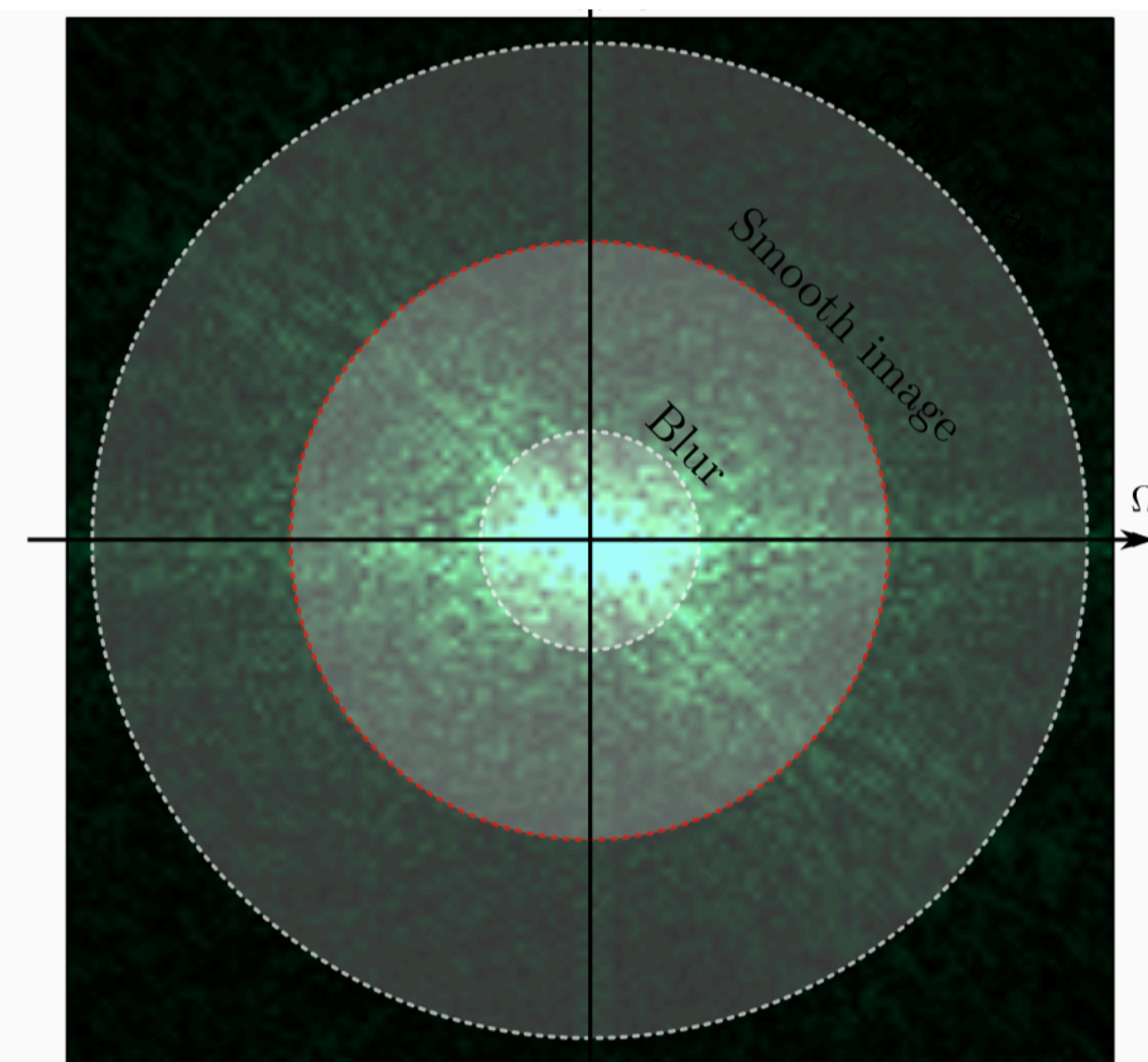


Image courtesy: Laurent Belcour

Recall: Fourier theory

Fourier transform: $\hat{f}(\omega) = \int_D f(x) e^{-2\pi i \omega x} dx$

Recall: Fourier theory

Fourier transform: $\hat{f}(\vec{\omega}) = \int_D f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$

Recall: Fourier theory

Fourier transform: $\hat{f}(\vec{\omega}) = \int_D f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$

Sampling function: $\hat{\mathbf{S}}(\vec{\omega}) = \int_D \mathbf{S}(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$

Recall: Fourier theory

Fourier transform: $\hat{f}(\vec{\omega}) = \int_D f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$

Sampling function: $\hat{\mathbf{S}}(\vec{\omega}) = \int_D \frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$

Recall: Fourier theory

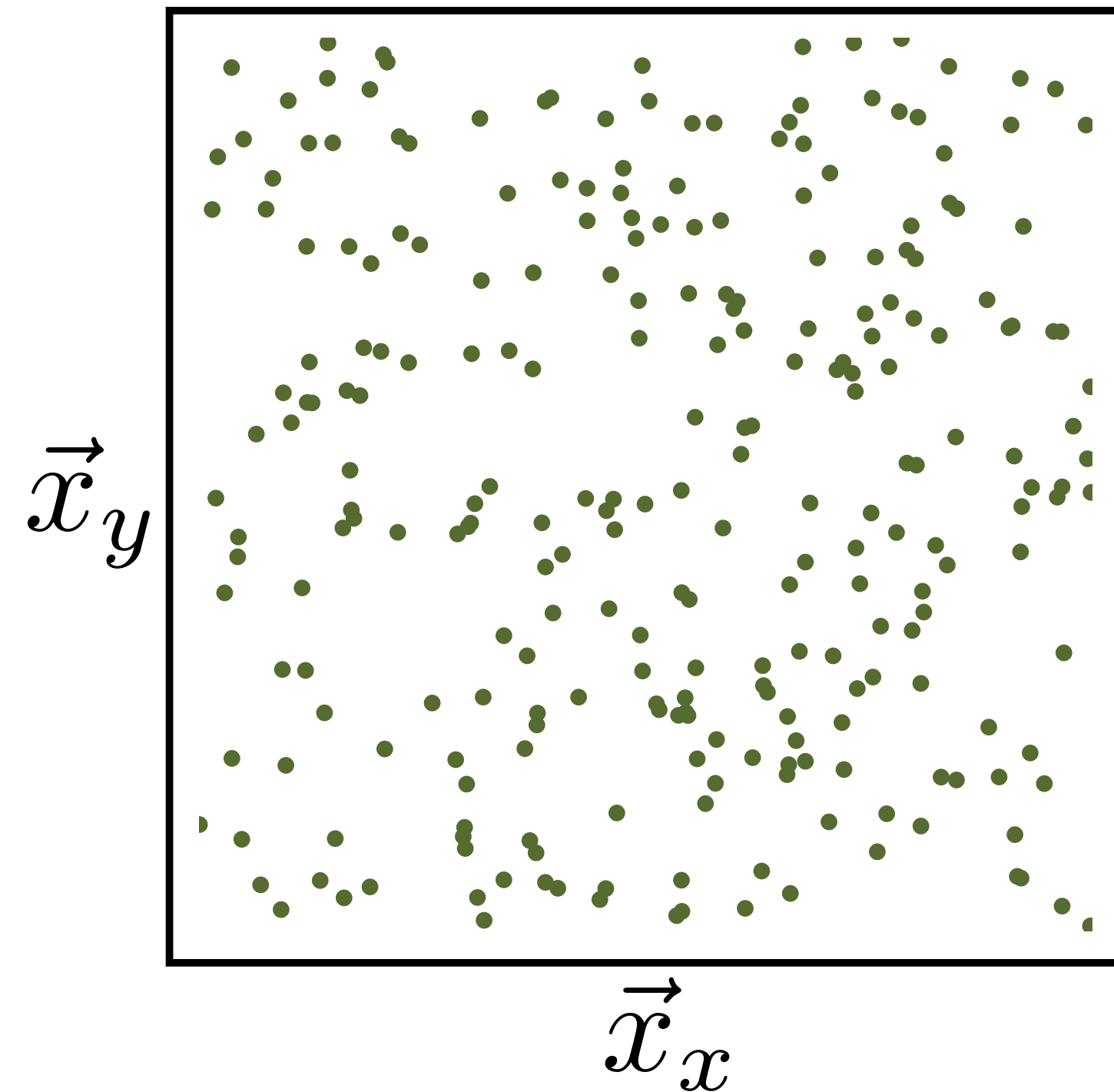
Fourier transform: $\hat{f}(\vec{\omega}) = \int_D f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$

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$$= \frac{1}{N} \sum_{k=1}^N e^{-2\pi i (\vec{\omega} \cdot \vec{x}_k)}$$

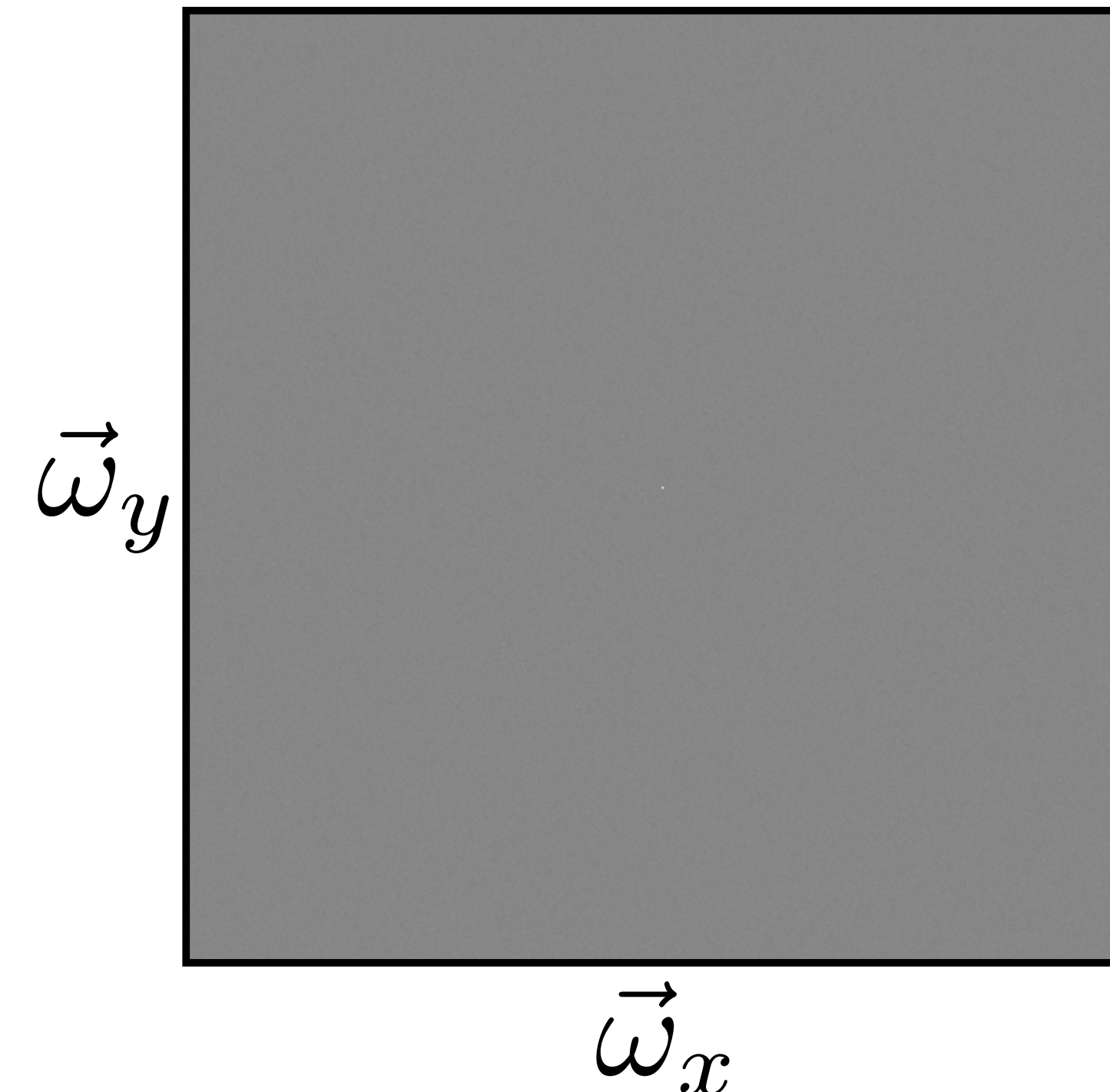
Independent Random Sampling

Samples



$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|)$$

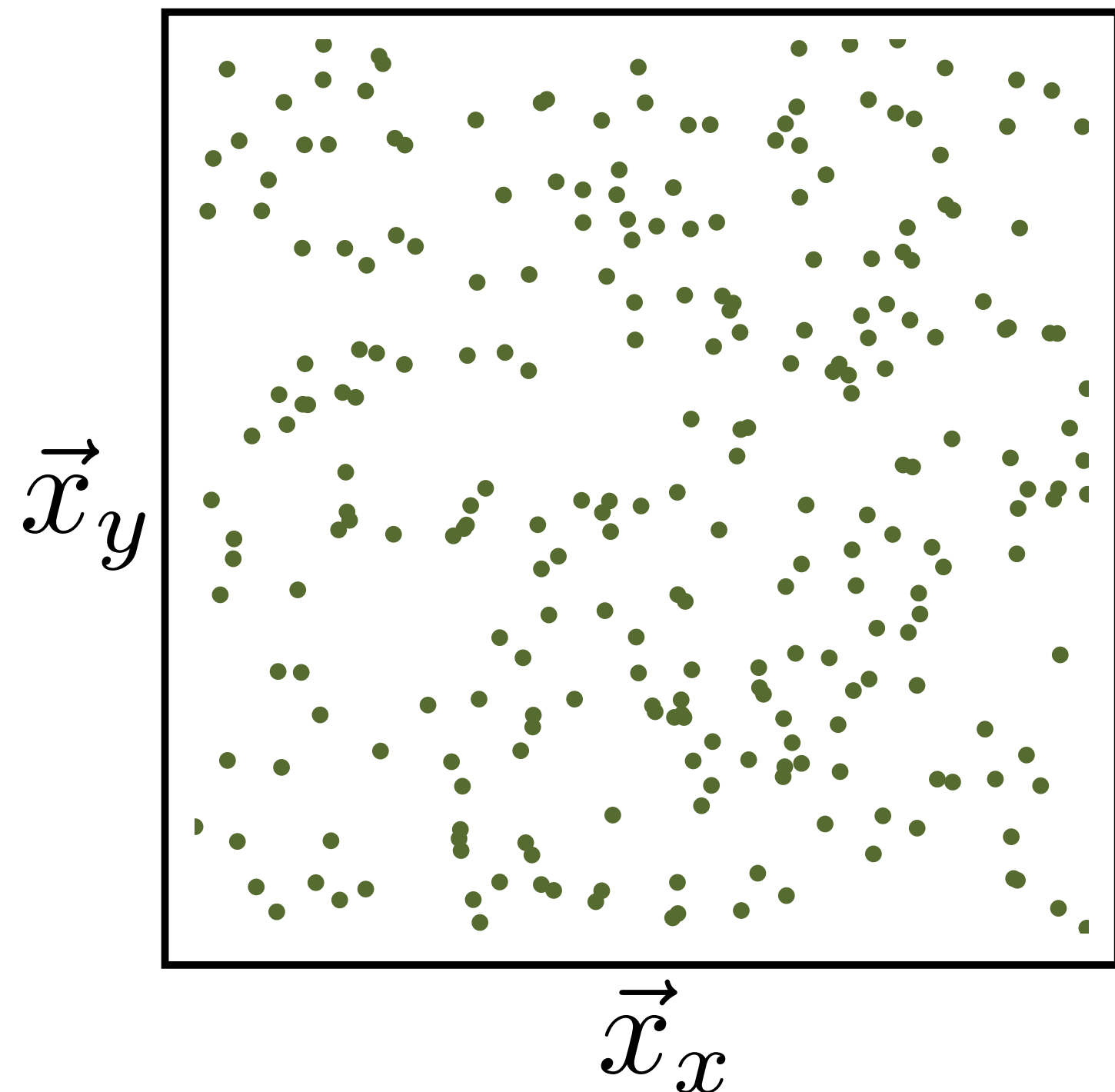
Power spectrum



$$\left| \frac{1}{N} \sum_{k=1}^N e^{-2 \pi i (\vec{w} \cdot \vec{x}_k)} \right|^2$$

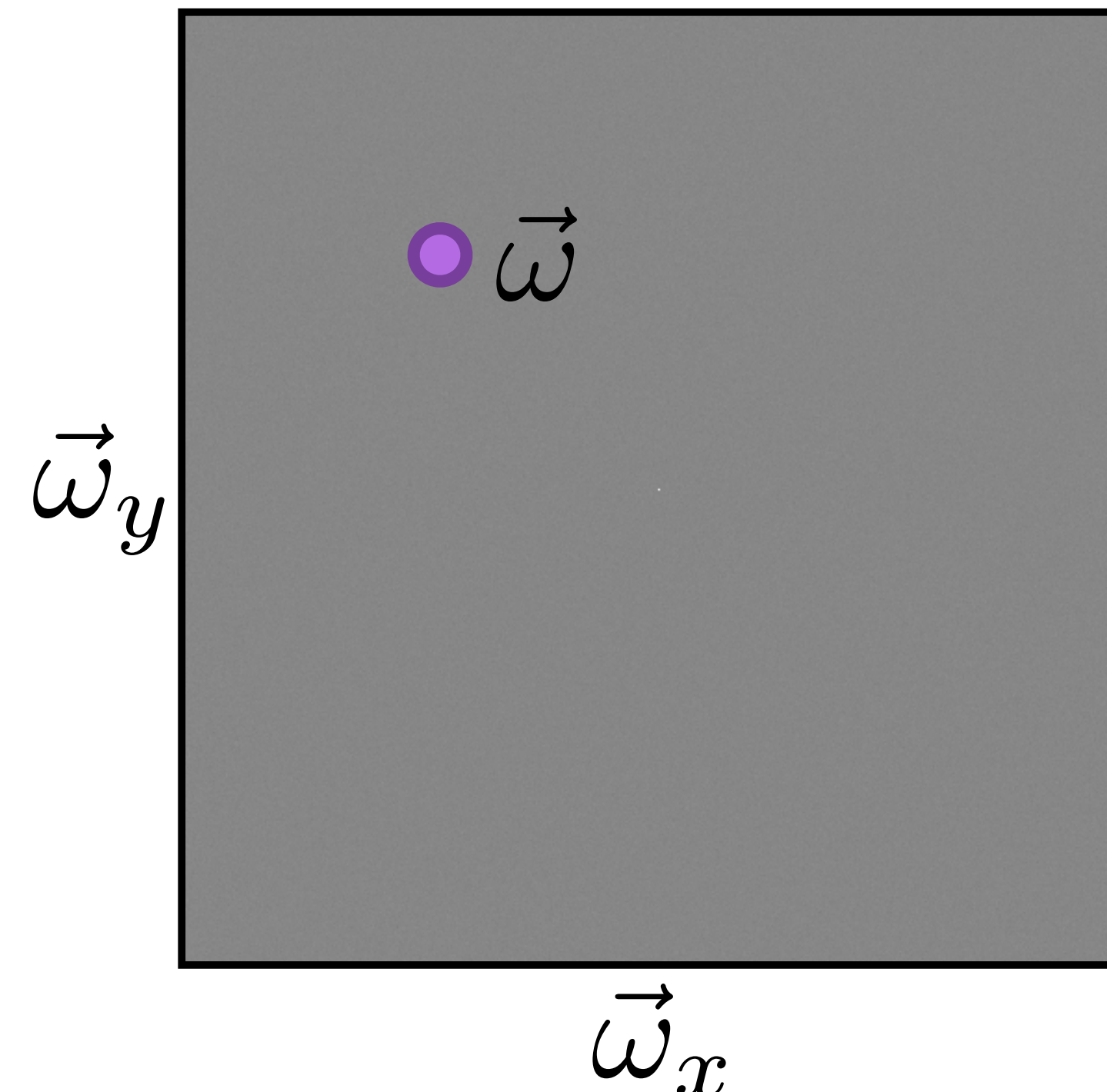
Independent Random Sampling

Samples



$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|)$$

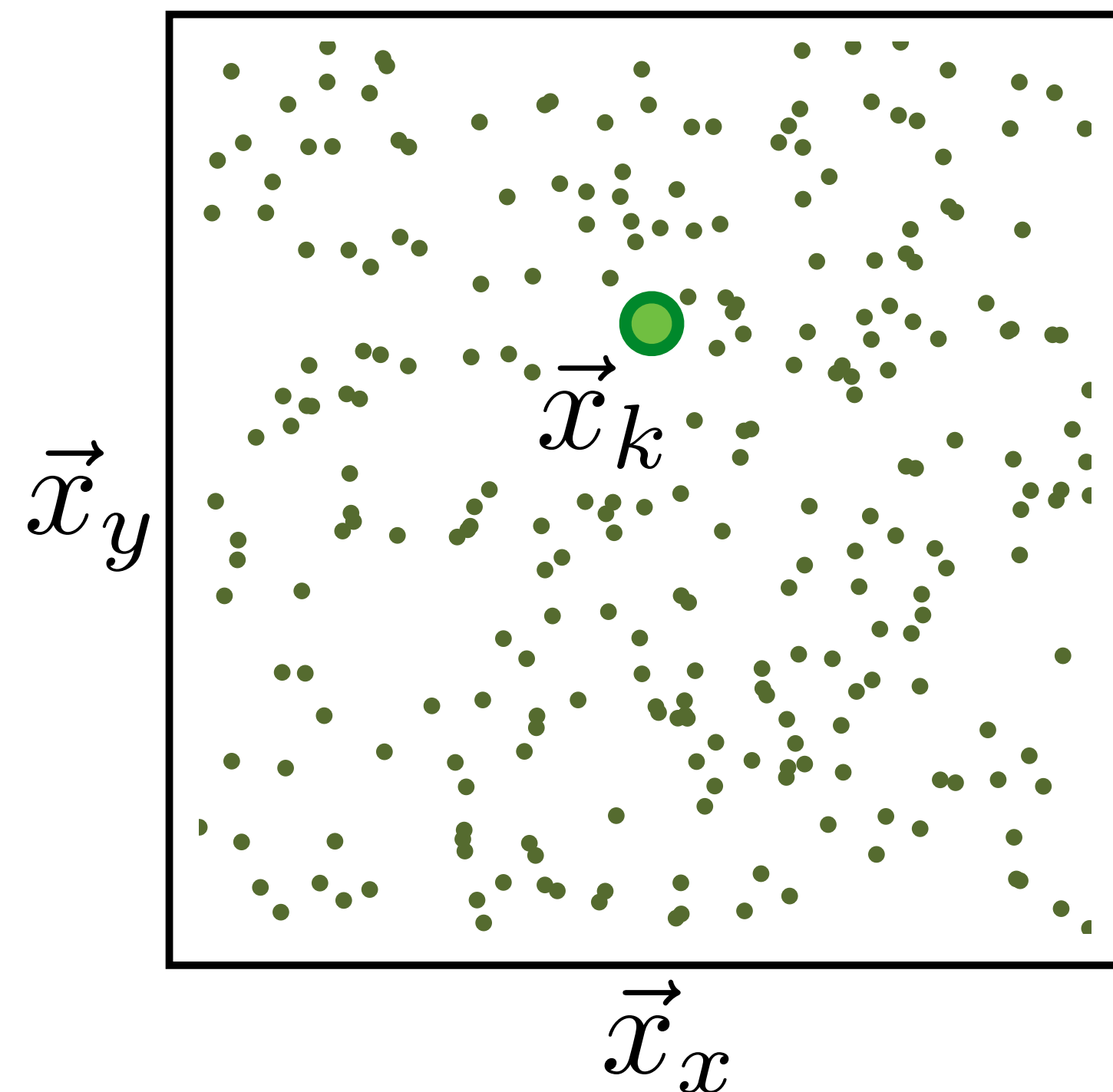
Power spectrum



$$\left| \frac{1}{N} \sum_{k=1}^N e^{-2 \pi i (\vec{w} \cdot \vec{x}_k)} \right|^2$$

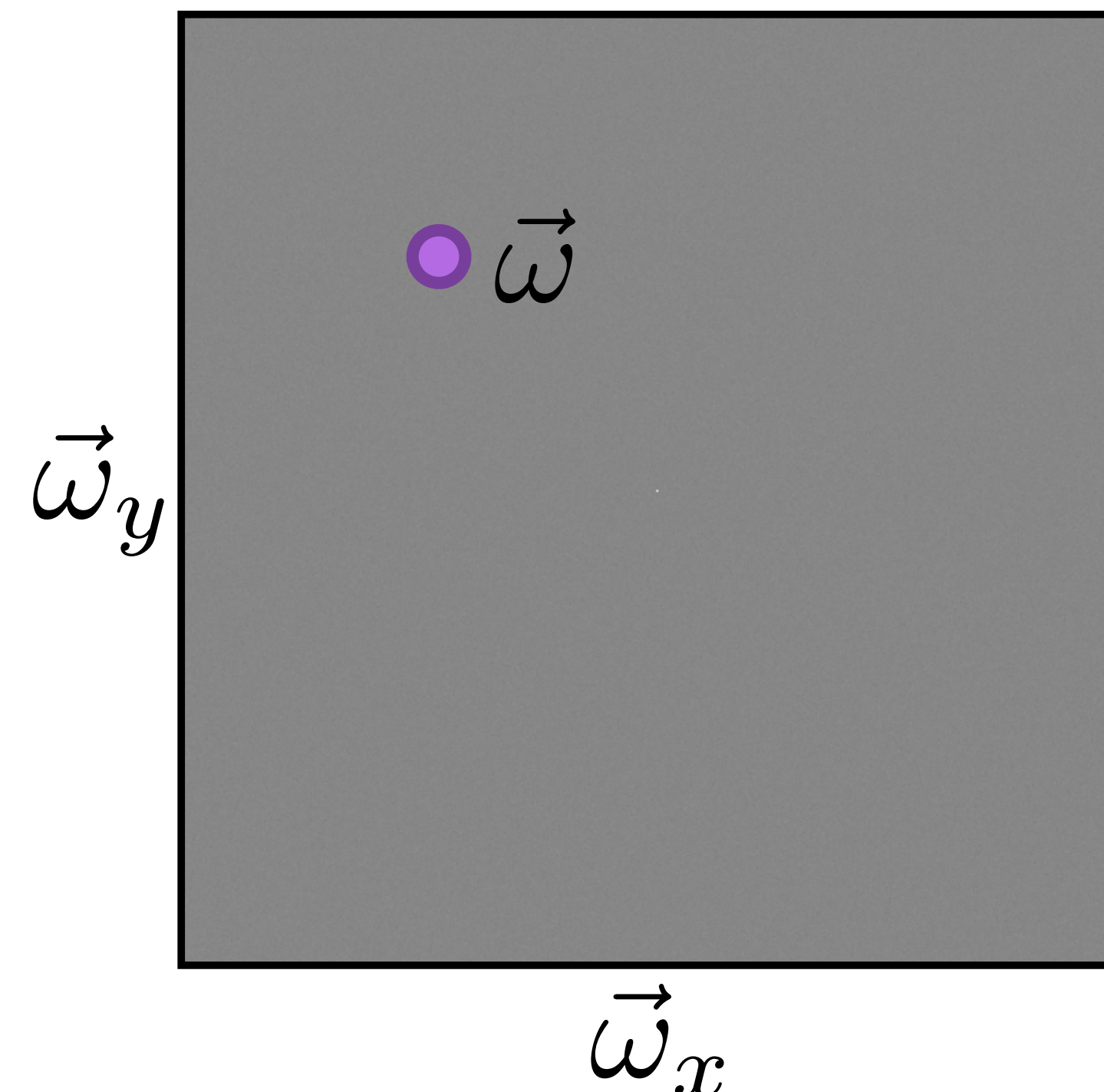
Independent Random Sampling

Samples



$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \boxed{\vec{x}_k}|)$$

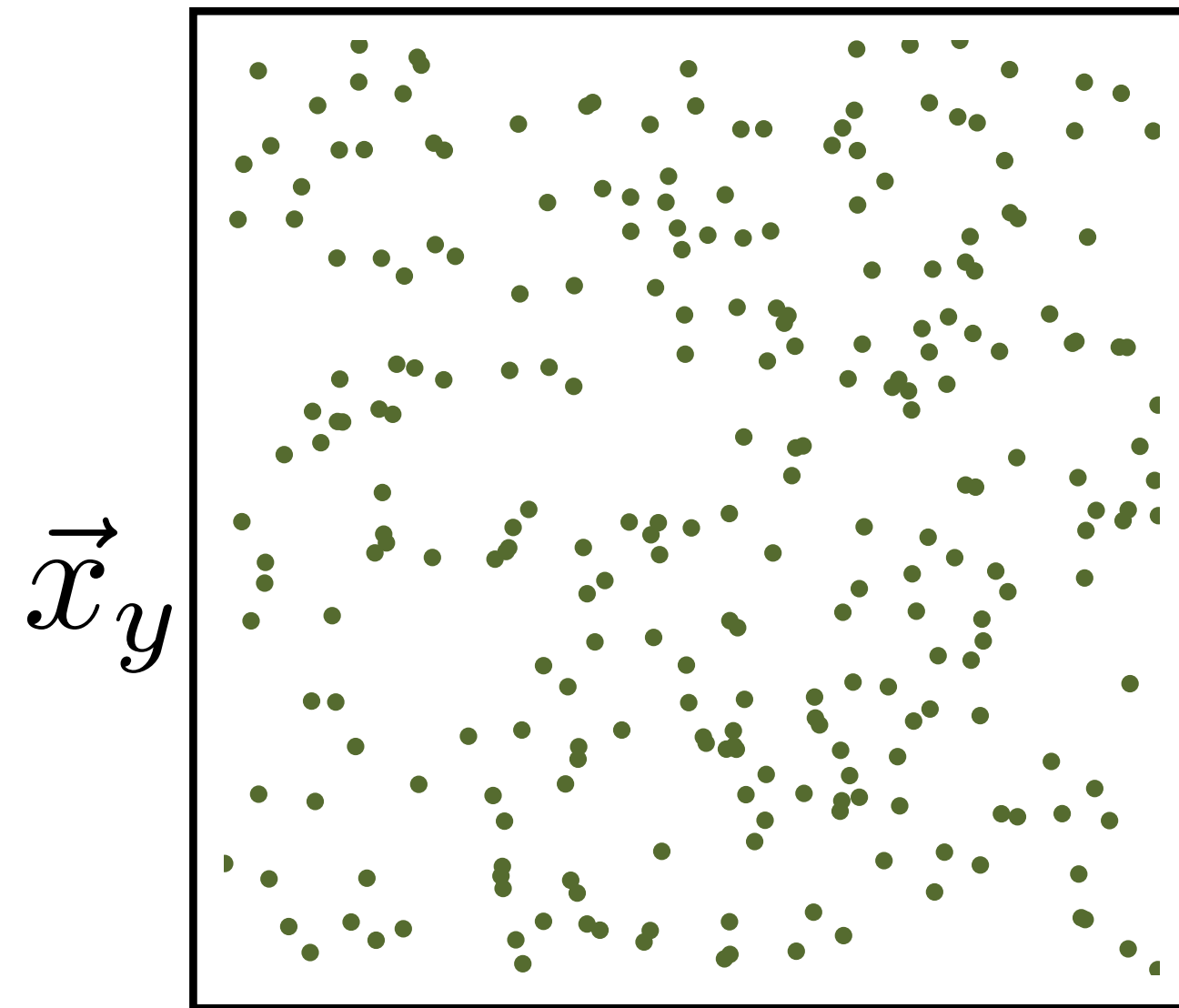
Power spectrum



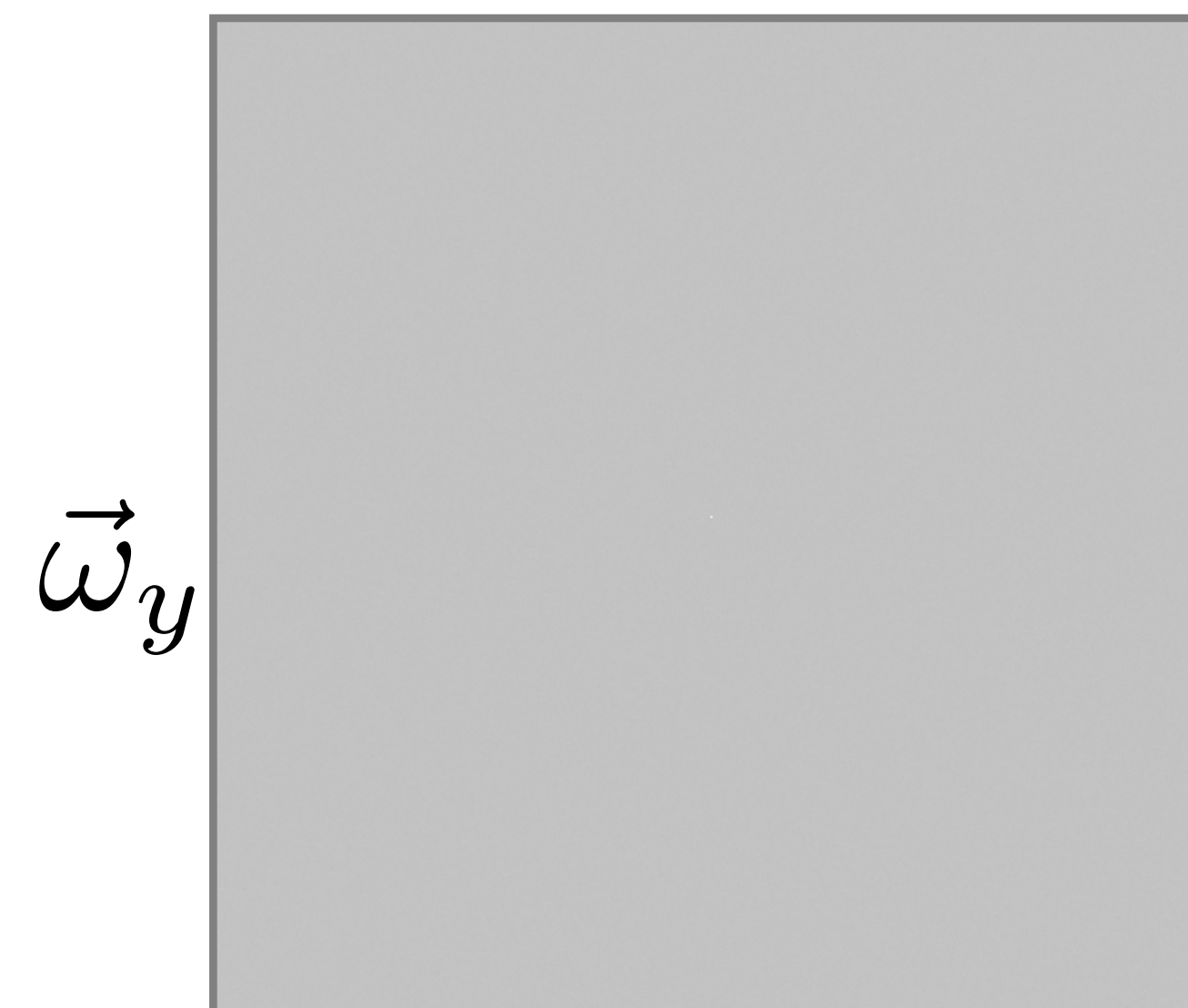
$$\left| \frac{1}{N} \sum_{k=1}^N e^{-2 \pi i (\boxed{\vec{w}} \cdot \boxed{\vec{x}_k})} \right|^2$$

Independent Random Sampling

Many sample set realizations



Expected power spectrum

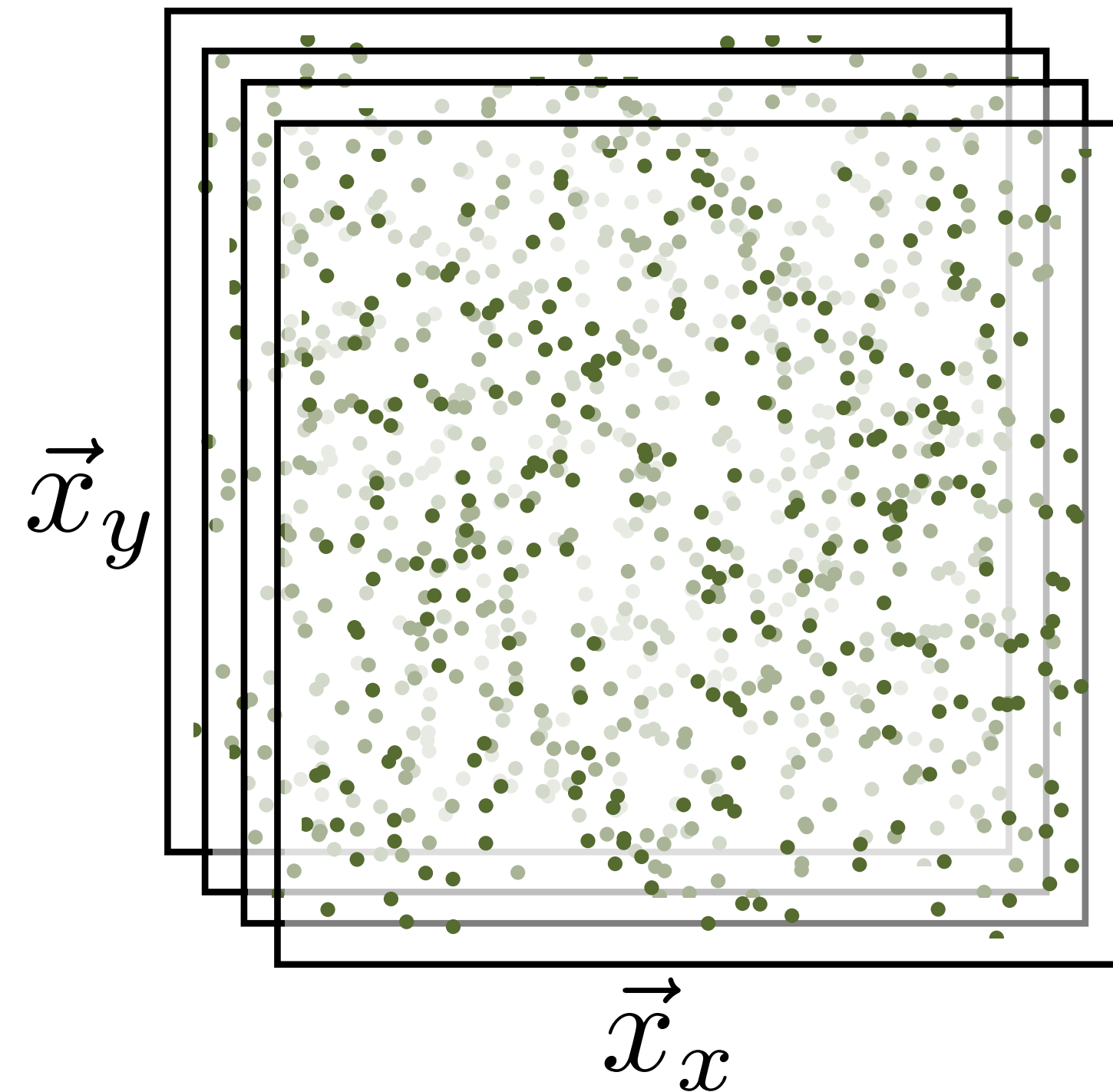


$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|)$$

$$\left| \frac{1}{N} \sum_{k=1}^N e^{-2 \pi i (\vec{\omega} \cdot \vec{x}_k)} \right|^2$$

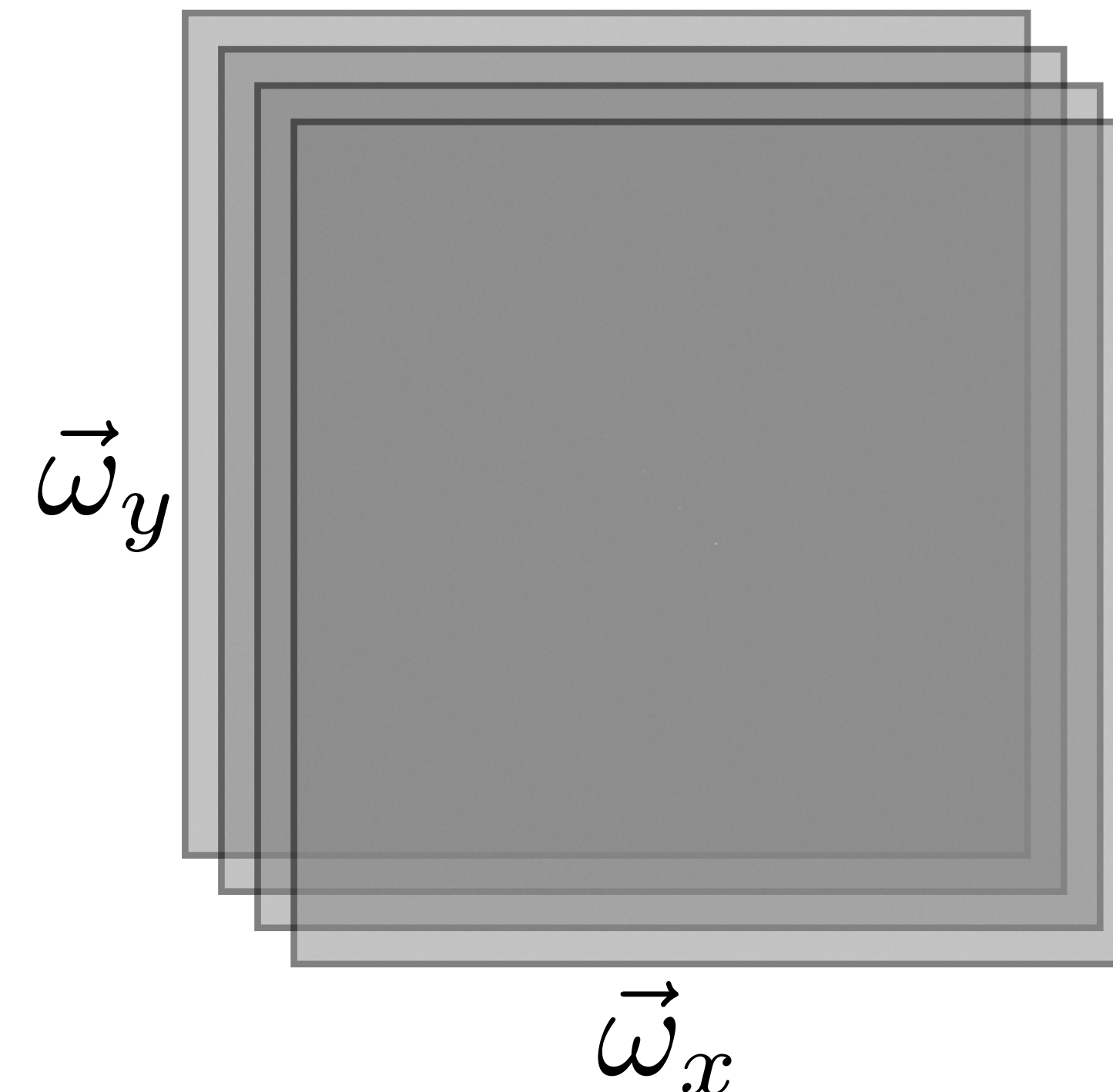
Independent Random Sampling

Many sample set realizations



$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|)$$

Expected power spectrum

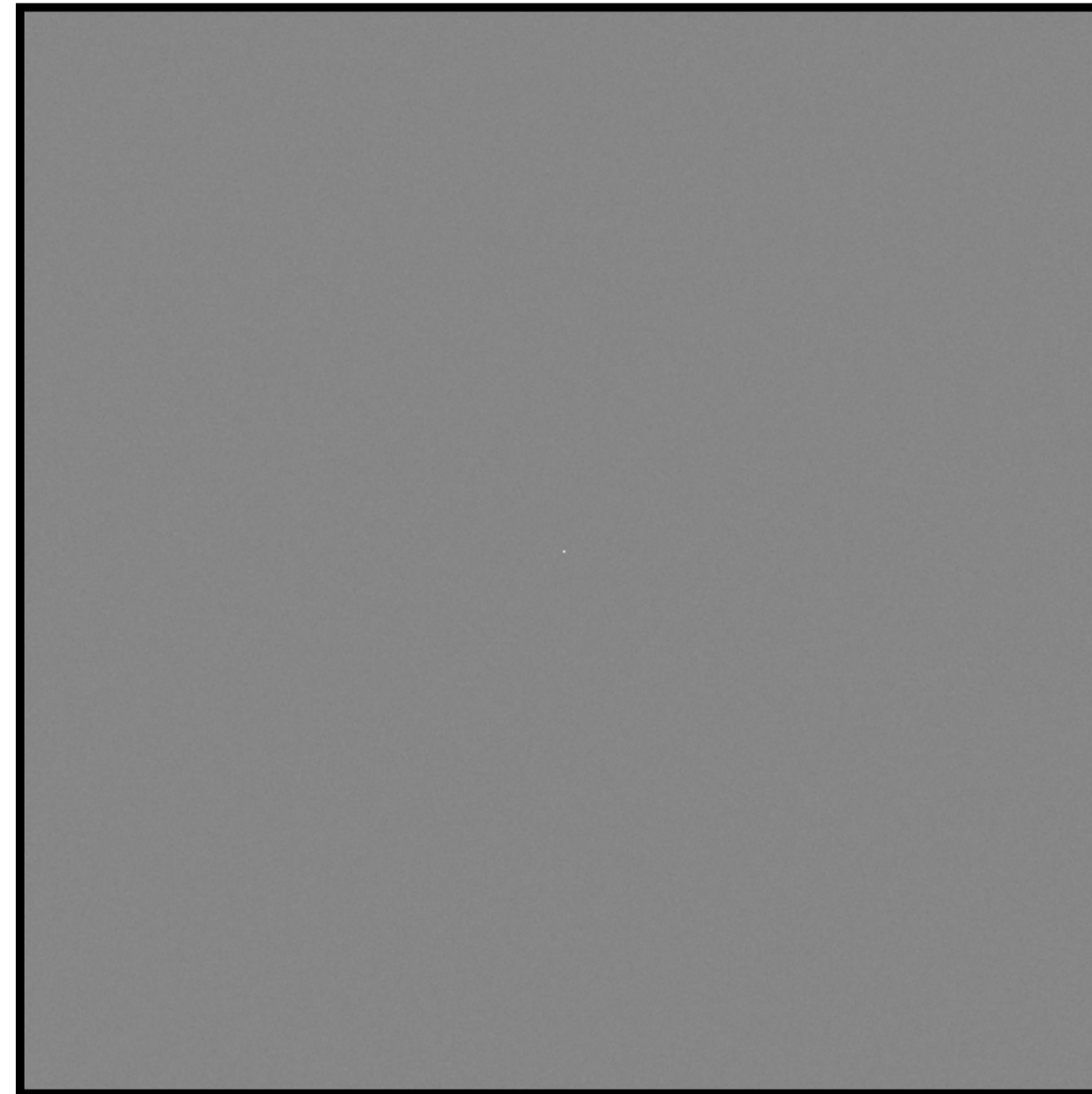
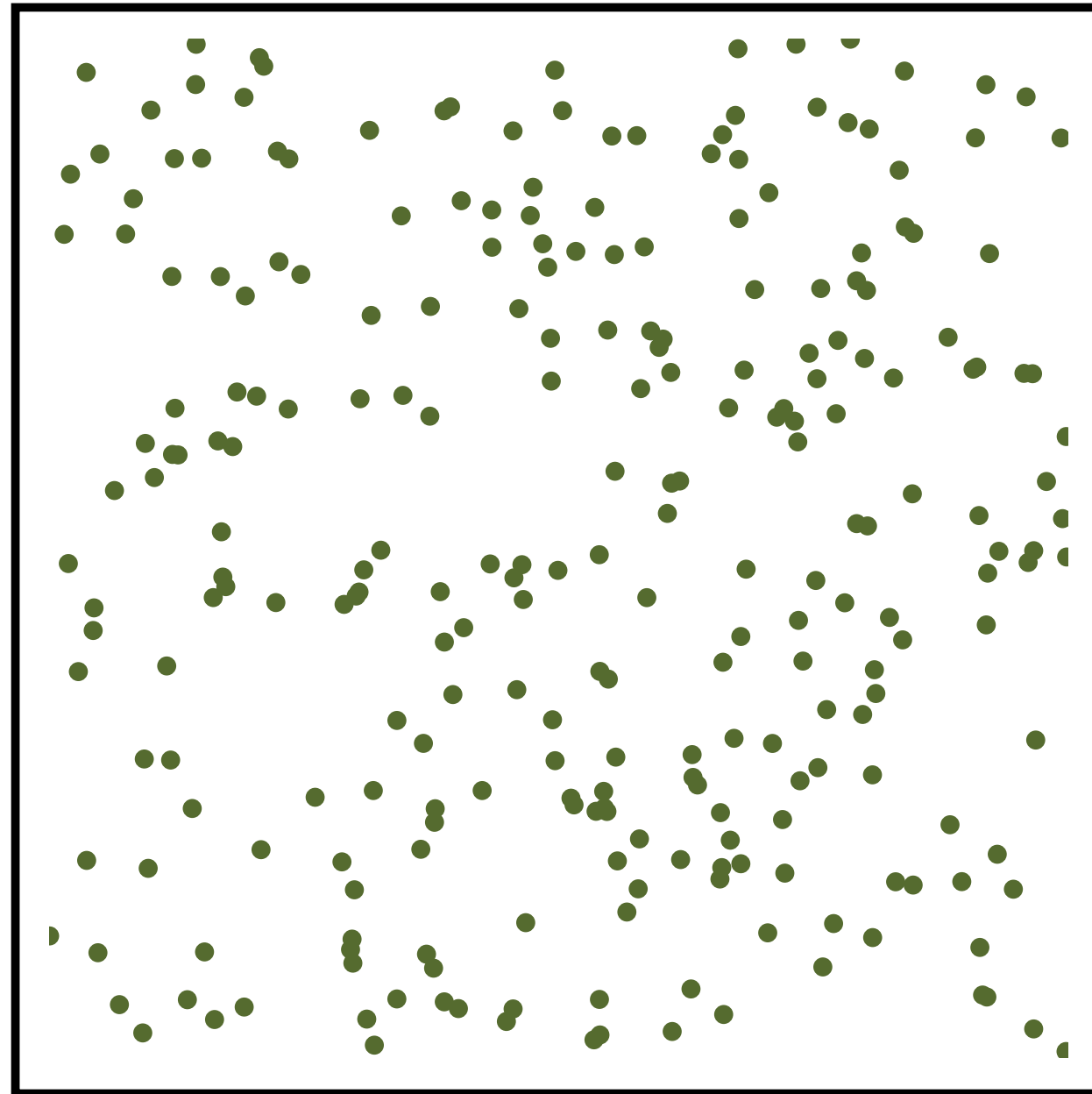


$$\mathbb{E} \left[\left| \frac{1}{N} \sum_{k=1}^N e^{-2 \pi i (\vec{w} \cdot \vec{x}_k)} \right|^2 \right]$$

Independent Random Sampling

Samples

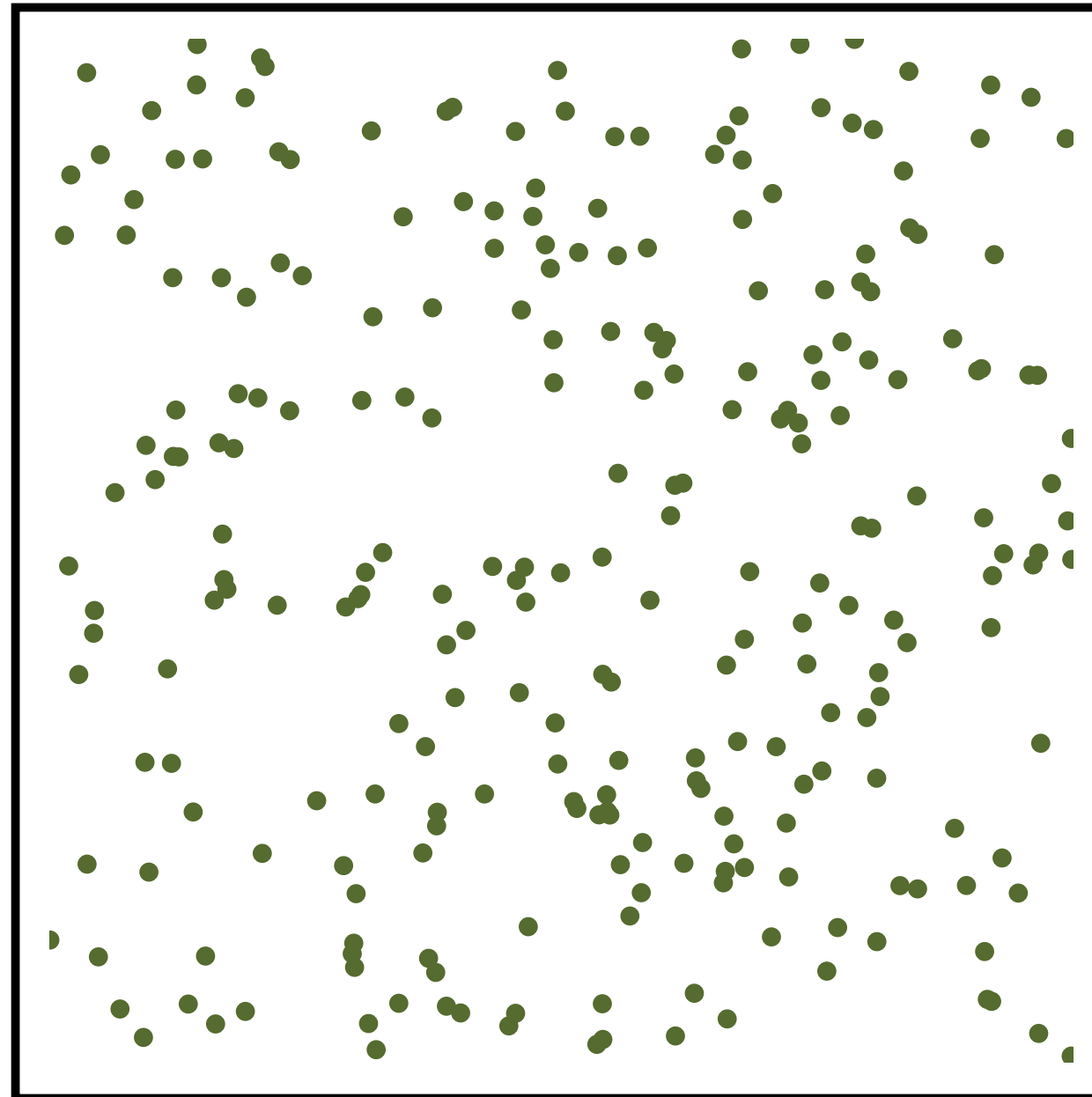
Expected power spectrum



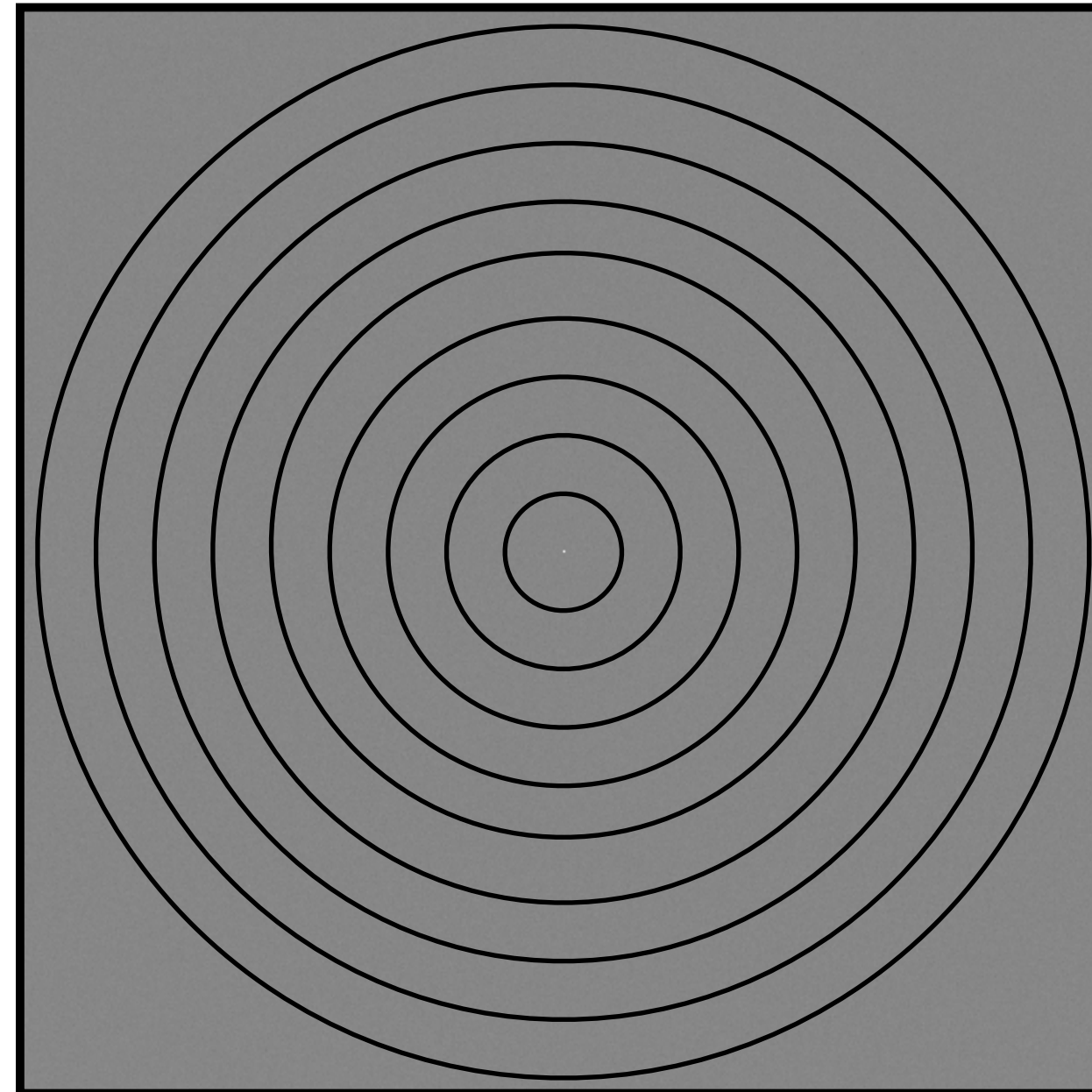
$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|) \quad \mathbb{E} \left[\left| \frac{1}{N} \sum_{k=1}^N e^{-2 \pi i (\vec{\omega} \cdot \vec{x}_k)} \right|^2 \right]$$

Independent Random Sampling

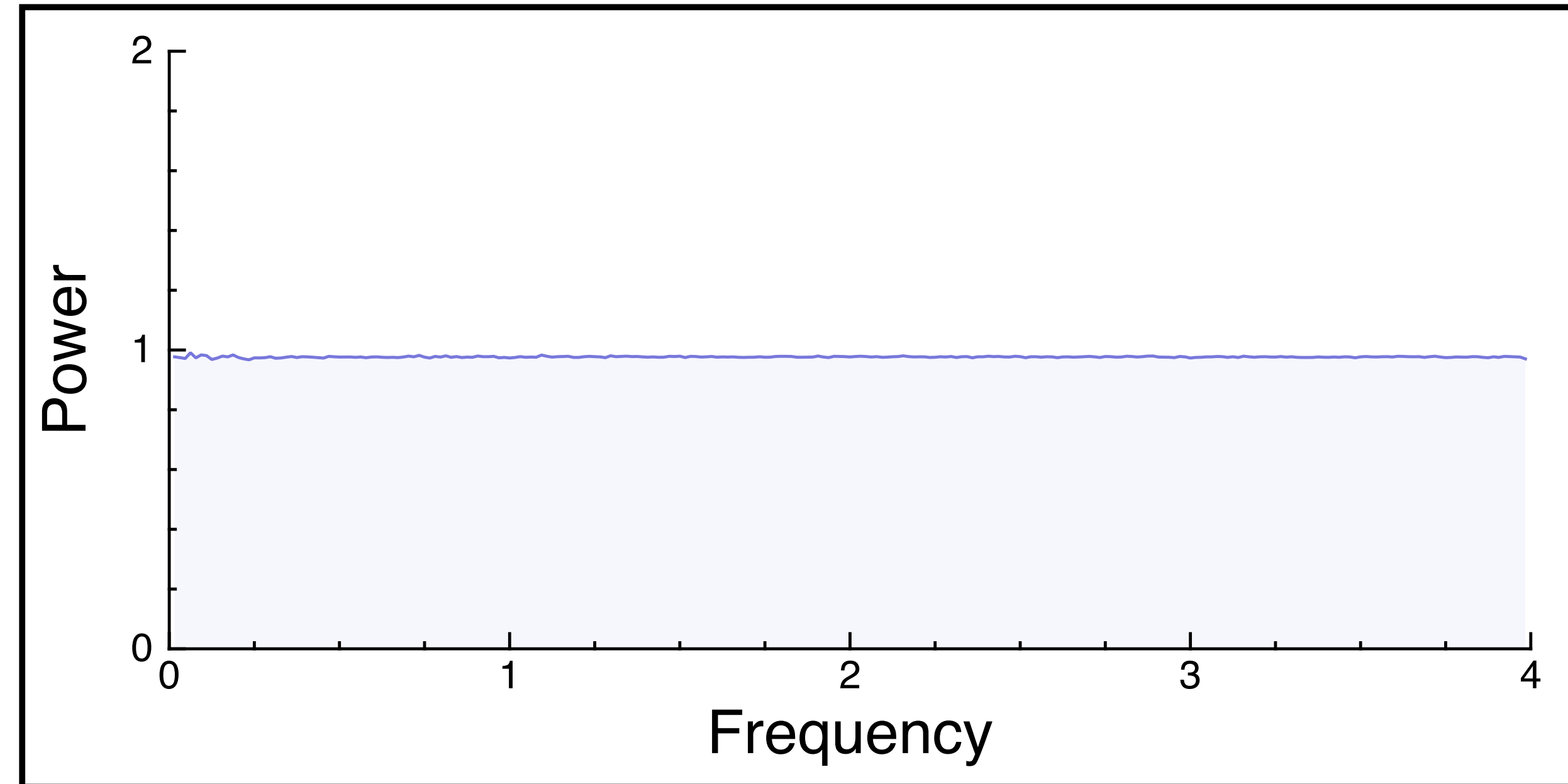
Samples



Expected power spectrum



Radial mean



$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|) \quad \mathbb{E} \left[\left| \frac{1}{N} \sum_{k=1}^N e^{-2\pi i (\vec{\omega} \cdot \vec{x}_k)} \right|^2 \right]$$

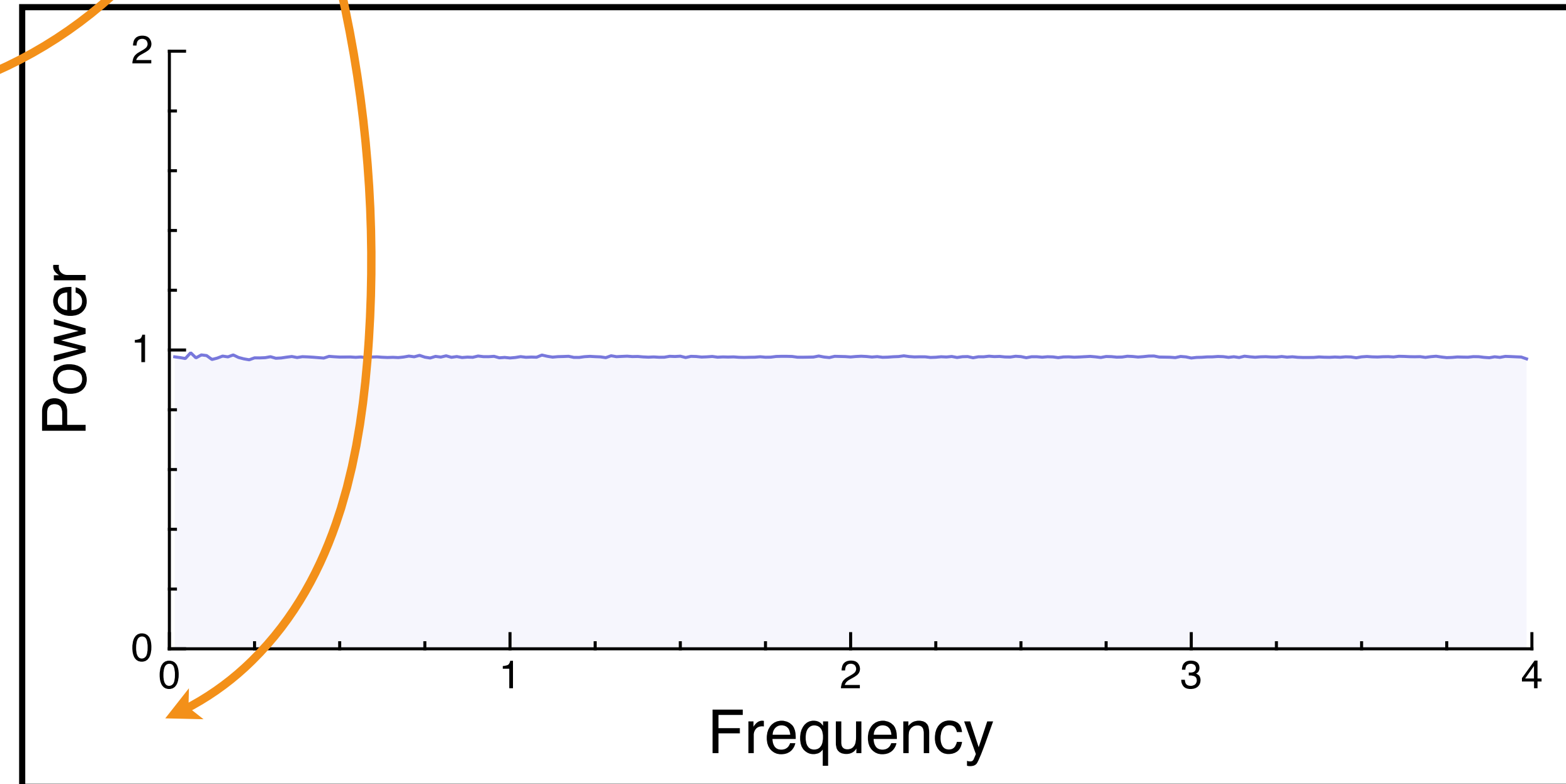
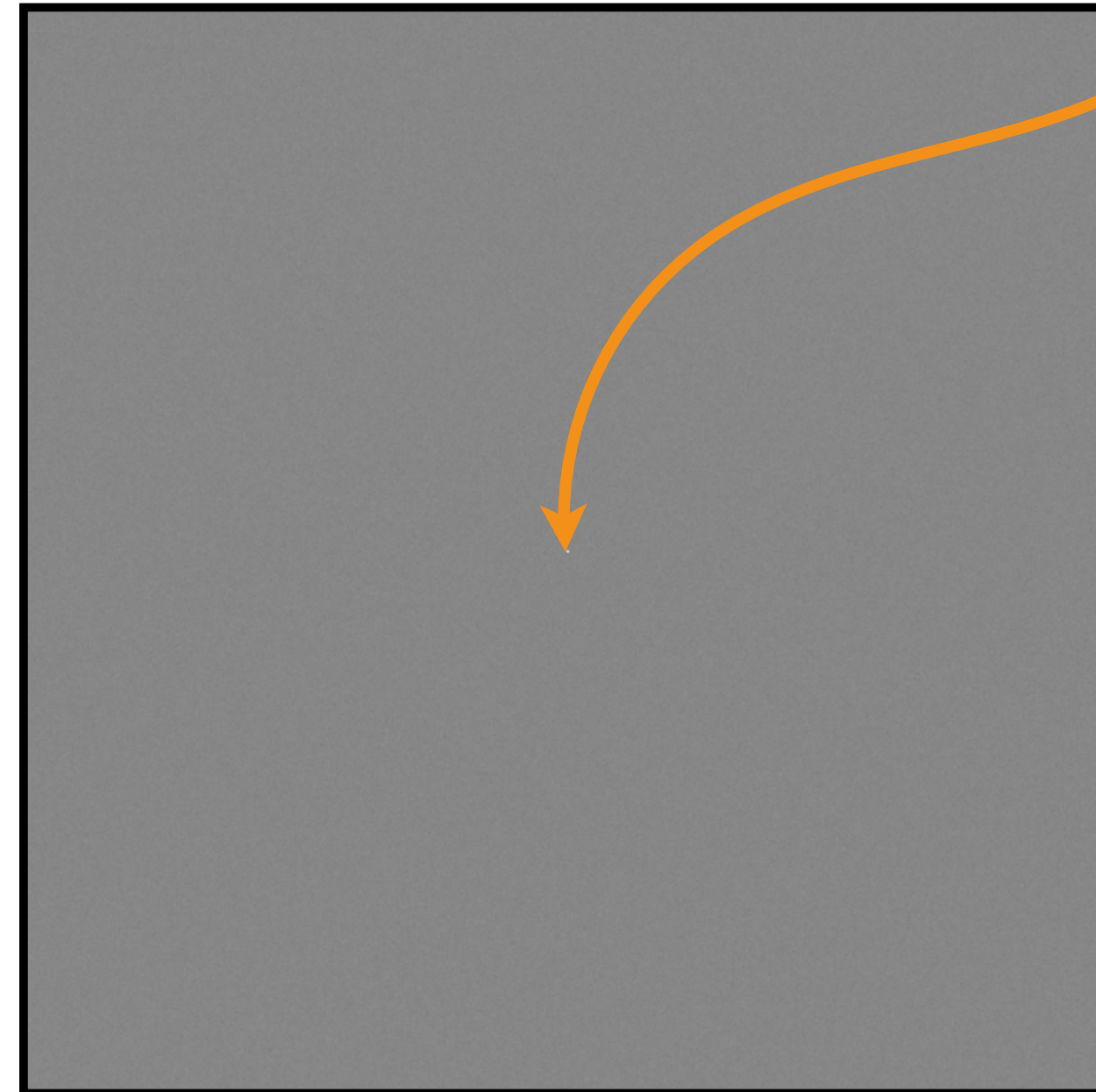
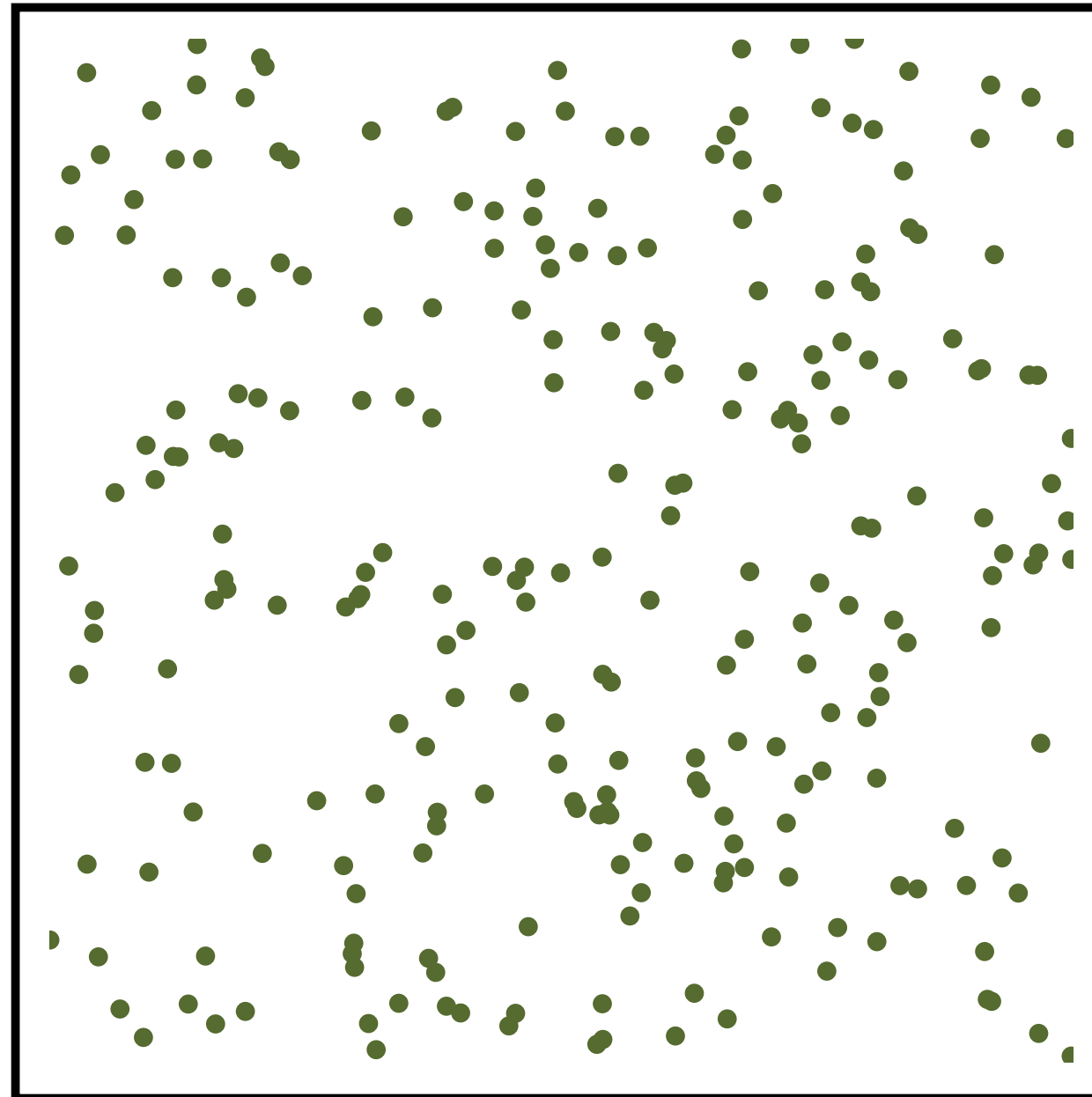
Independent Random Sampling

Samples

Expected power spectrum

DC Peak

Radial mean



$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|) \quad \mathbb{E} \left[\left| \frac{1}{N} \sum_{k=1}^N e^{-2 \pi i (\vec{\omega} \cdot \vec{x}_k)} \right|^2 \right]$$

Source code: Power spectrum

```
procedure powerSpectrum(samples, spectrumWidth, spectrumHeight)
  int N = samples.size()
  for u: 0 → spectrumWidth{
    for v: 0 → spectrumHeight{
      double real = 0, imag = 0;

    }
  }
  return power;
}
```


Source code: Power spectrum

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procedure powerSpectrum(samples, spectrumWidth, spectrumHeight)
  int N = samples.size()
  for u: 0 → spectrumWidth{
    for v: 0 → spectrumHeight{
      double real = 0, imag = 0;

      //compute the real and imaginary fourier coefficients
      for(int k=0;k<N;k++){

      }
    }
  }
  return power;
}
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Source code: Power spectrum

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  int N = samples.size()
  for u: 0 → spectrumWidth{
    for v: 0 → spectrumHeight{
      double real = 0, imag = 0;

      //compute the real and imaginary fourier coefficients
      for(int k=0;k<N;k++){
        real += cos(2 * π * (u * samples[k].x + v * samples[k].y));
        imag += sin(2 * π * (u * samples[k].x + v * samples[k].y));
      }

    }
  }
  return power;
}
```

Source code: Power spectrum

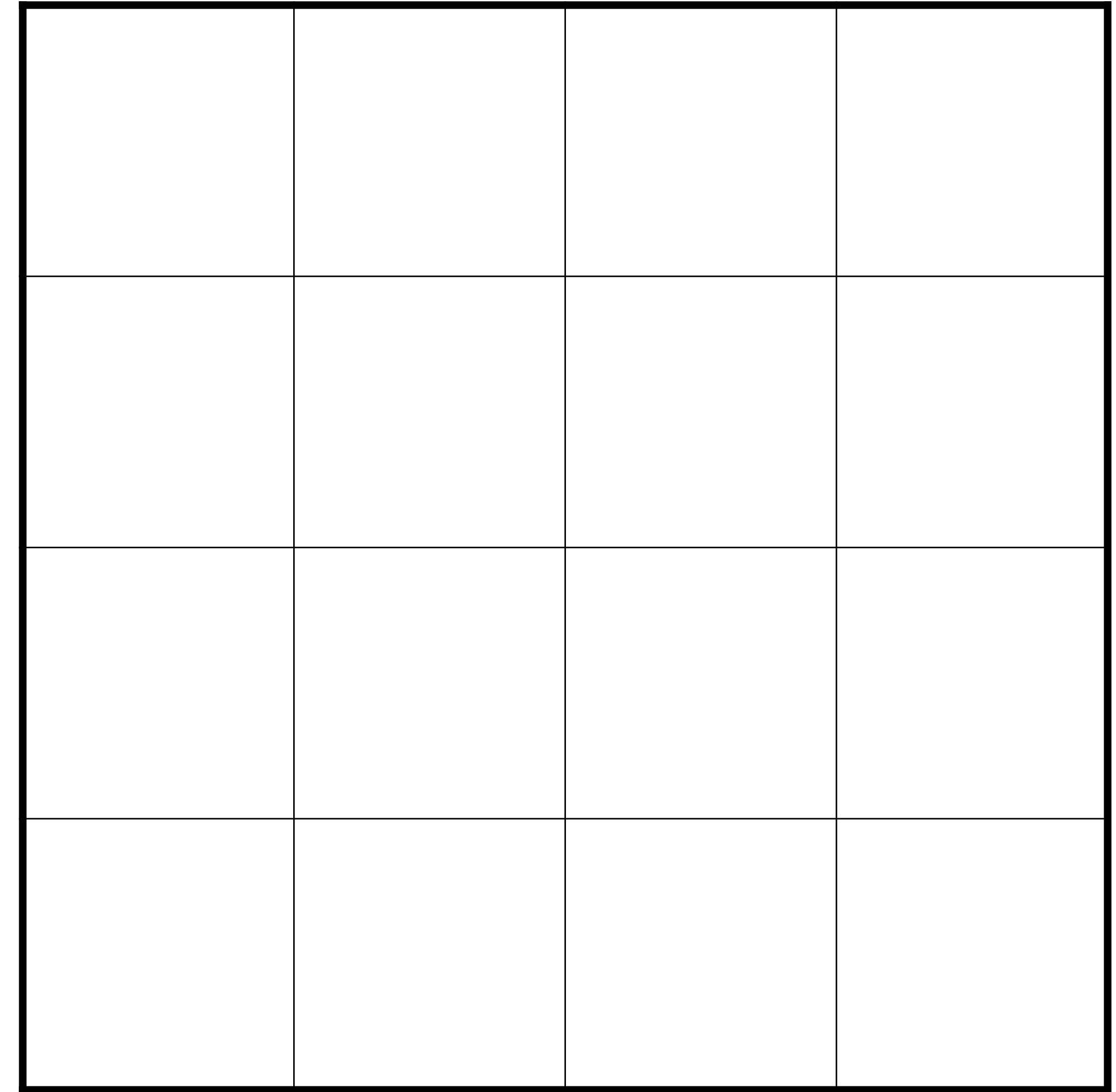
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  for u: 0 → spectrumWidth{
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      double real = 0, imag = 0;

      //compute the real and imaginary fourier coefficients
      for(int k=0;k<N;k++){
        real += cos(2 * π * (u * samples[k].x + v * samples[k].y));
        imag += sin(2 * π * (u * samples[k].x + v * samples[k].y));
      }

      //power spectrum is the magnitude square value of the coefficients
      power[u * spectrumWidth + v] = (real*real + imag * imag) / N;
    }
  }
  return power;
}
```

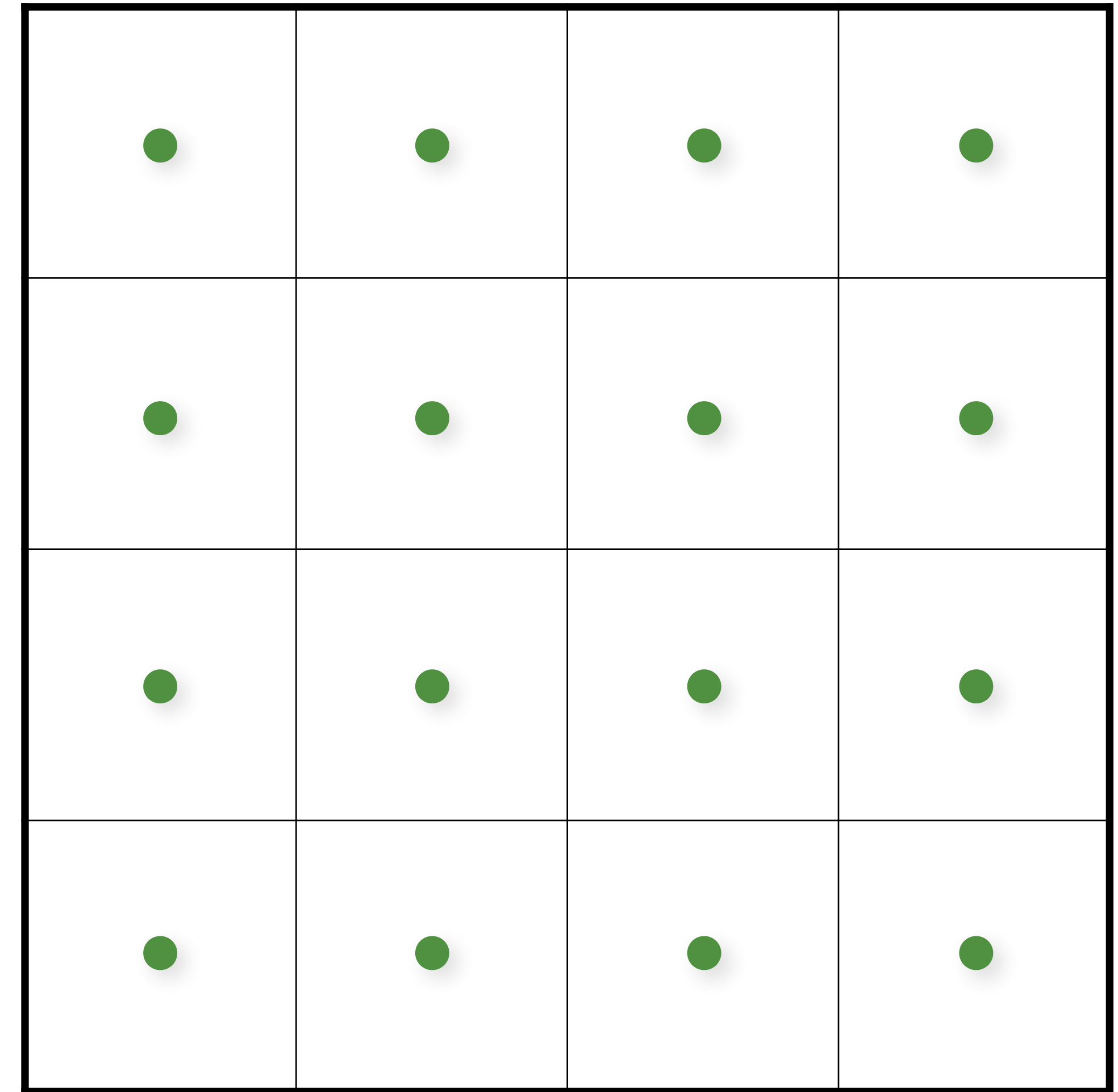
Regular Sampling

```
for (uint i = 0; i < numX; i++)  
    for (uint j = 0; j < numY; j++)  
    {  
        samples(i,j).x = (i + 0.5)/numX;  
        samples(i,j).y = (j + 0.5)/numY;  
    }
```



Regular Sampling

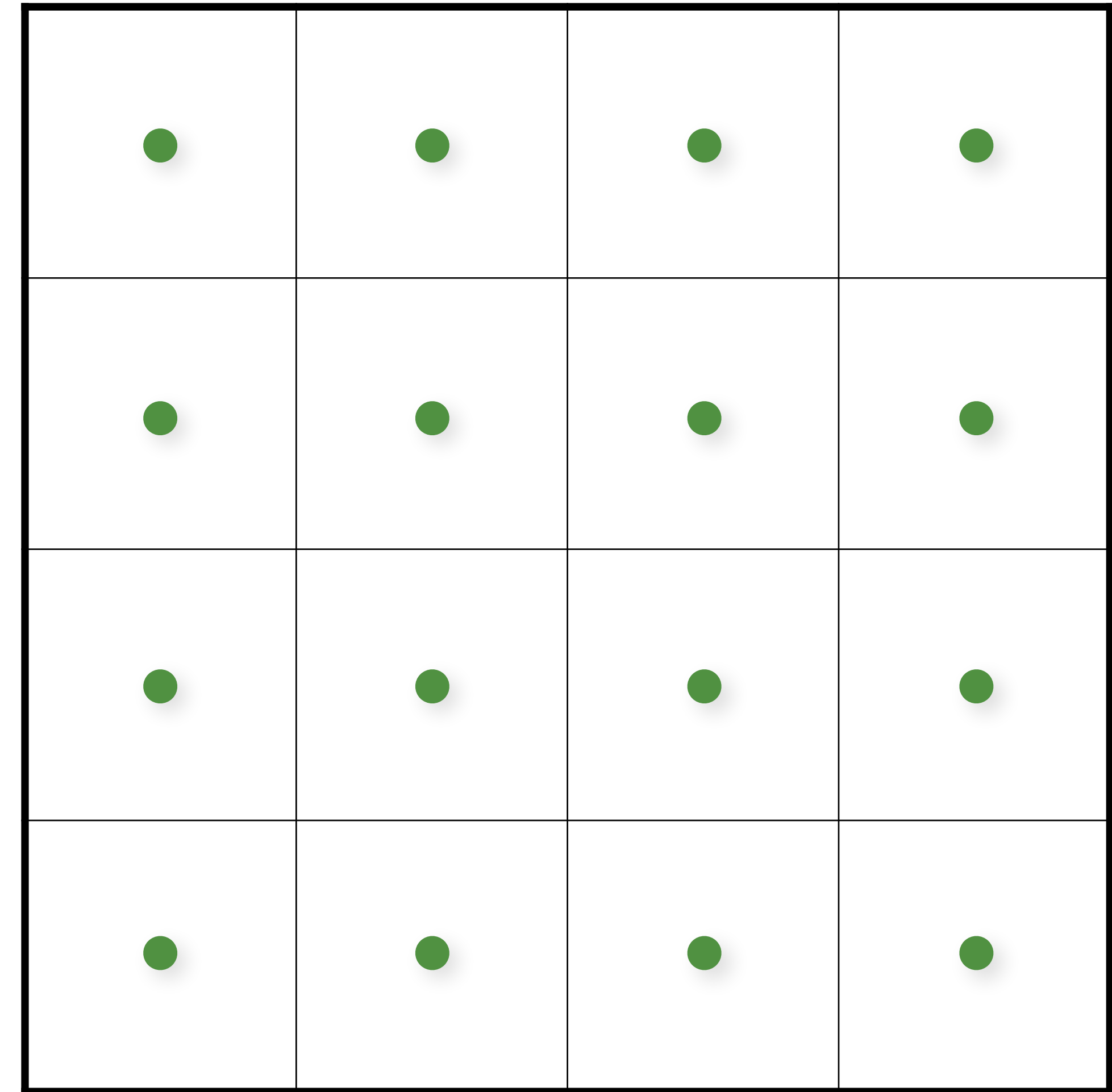
```
for (uint i = 0; i < numX; i++)  
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  }
```

✓ Extends to higher dimensions, but...

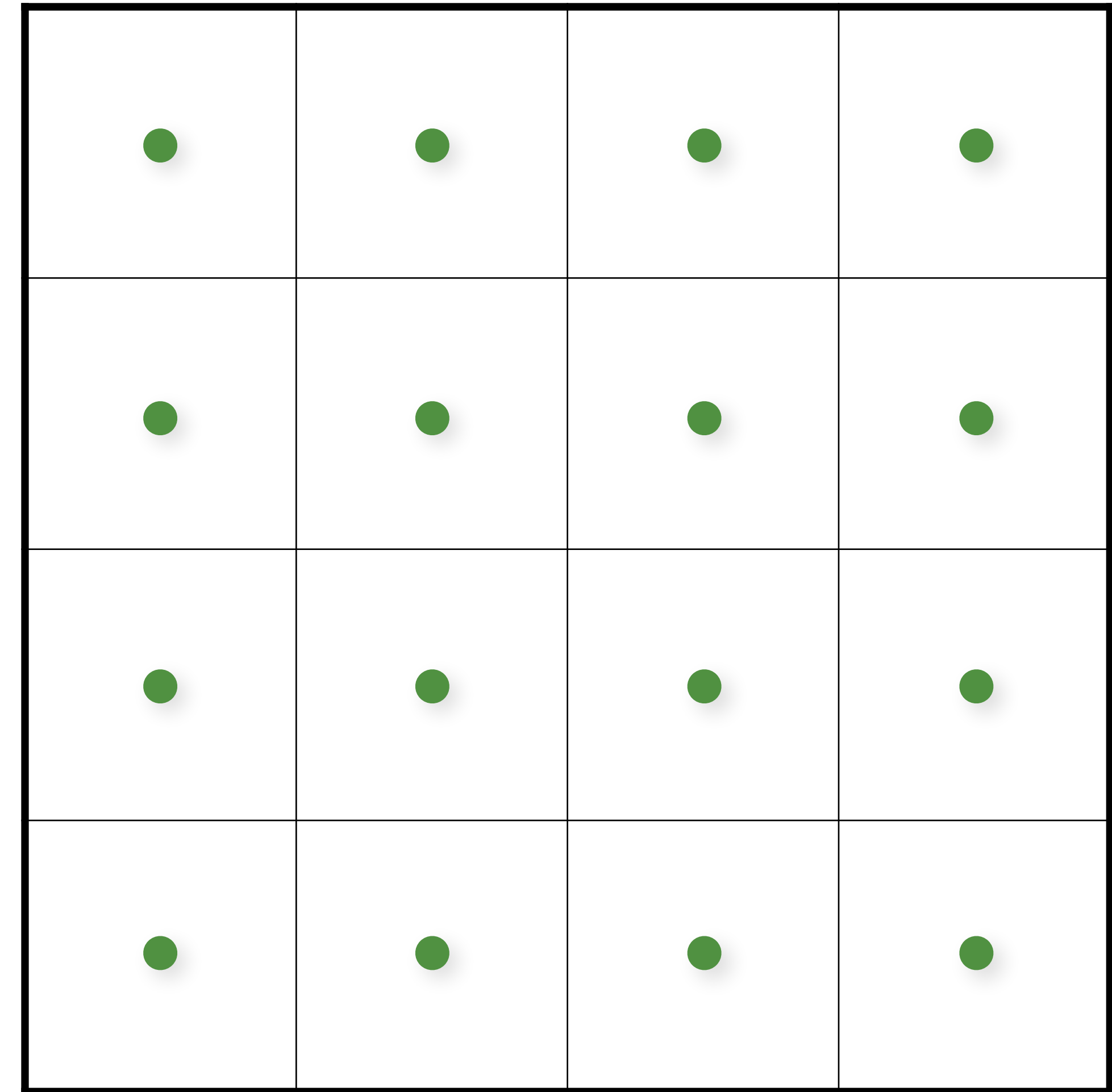


Regular Sampling

```
for (uint i = 0; i < numX; i++)  
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  }
```

✓ Extends to higher dimensions, but...

✗ Curse of dimensionality



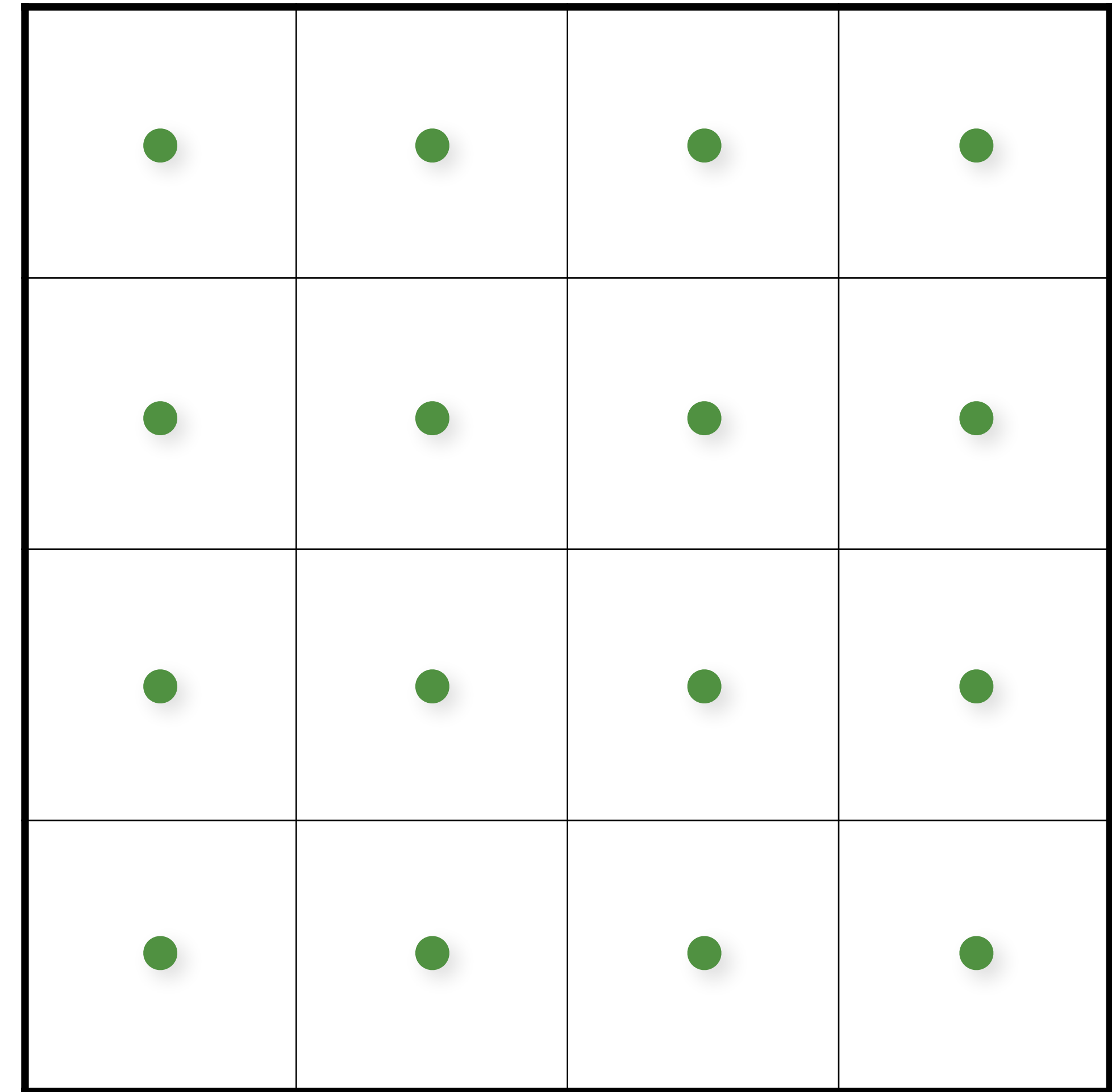
Regular Sampling

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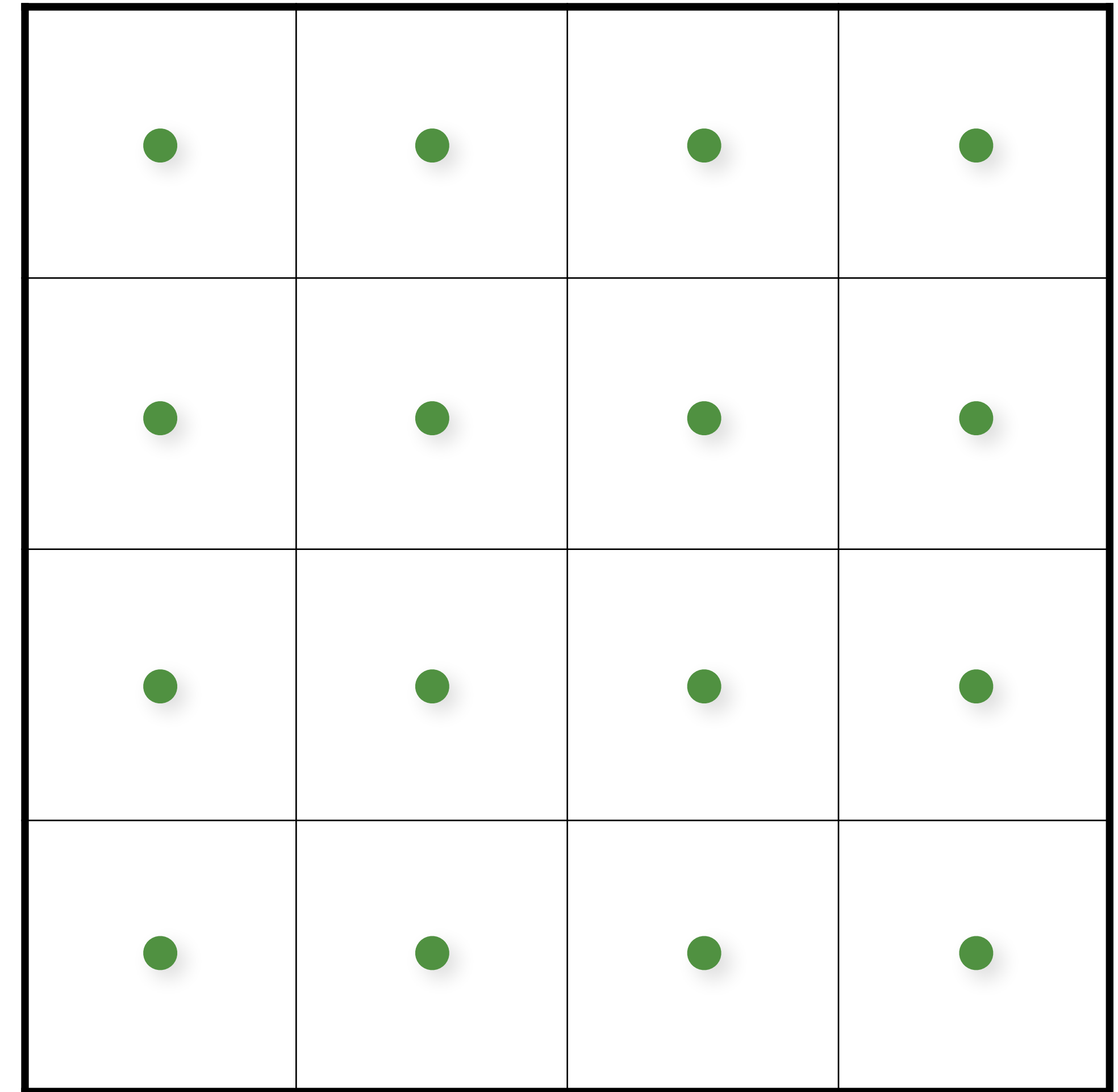
✗ Curse of dimensionality

✗ Aliasing



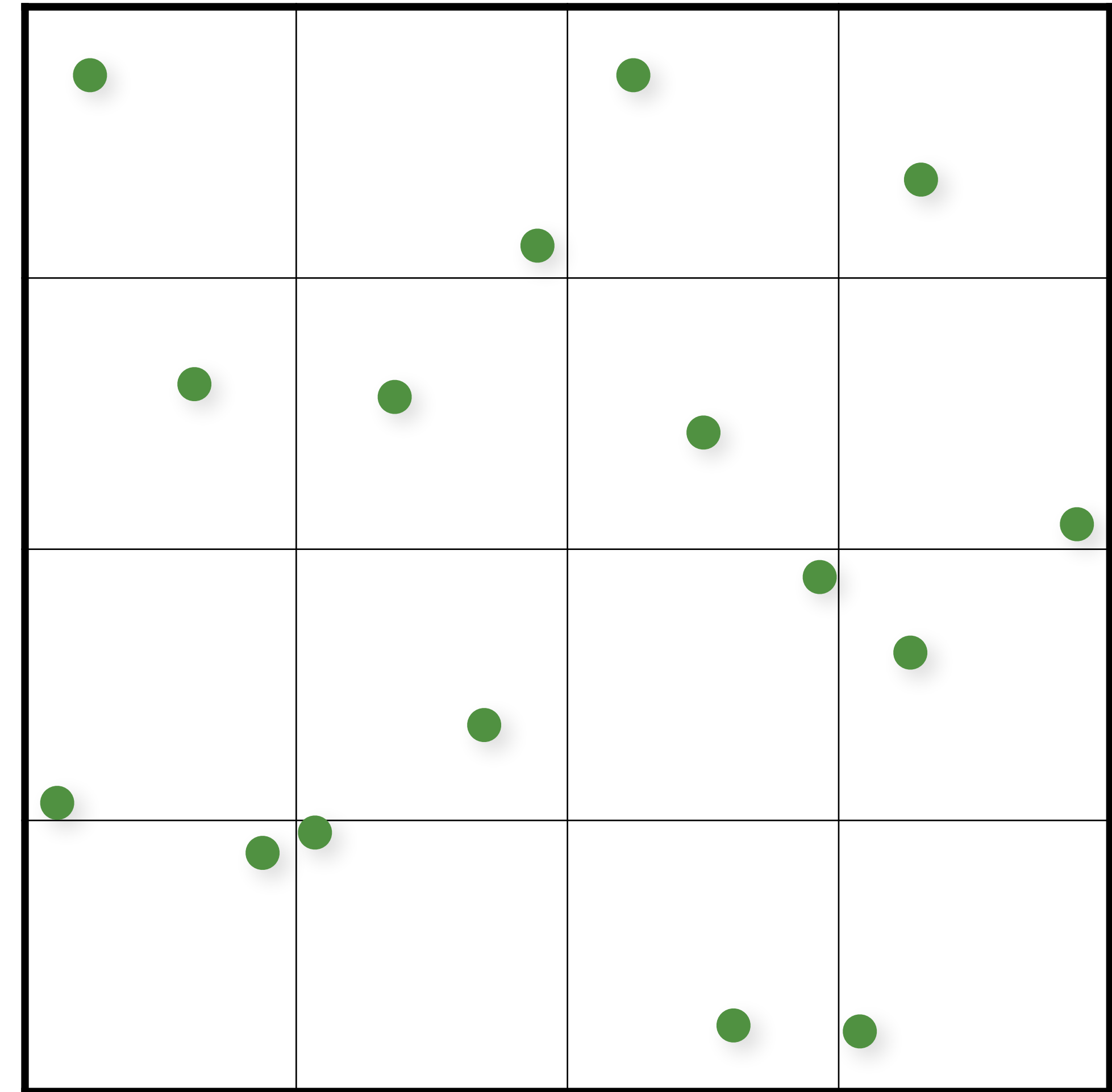
Regular Sampling

```
for (uint i = 0; i < numX; i++)  
  for (uint j = 0; j < numY; j++)  
  {  
    samples(i,j).x = (i + 0.5)/numX;  
    samples(i,j).y = (j + 0.5)/numY;  
  }
```



Jittered/Stratified Sampling

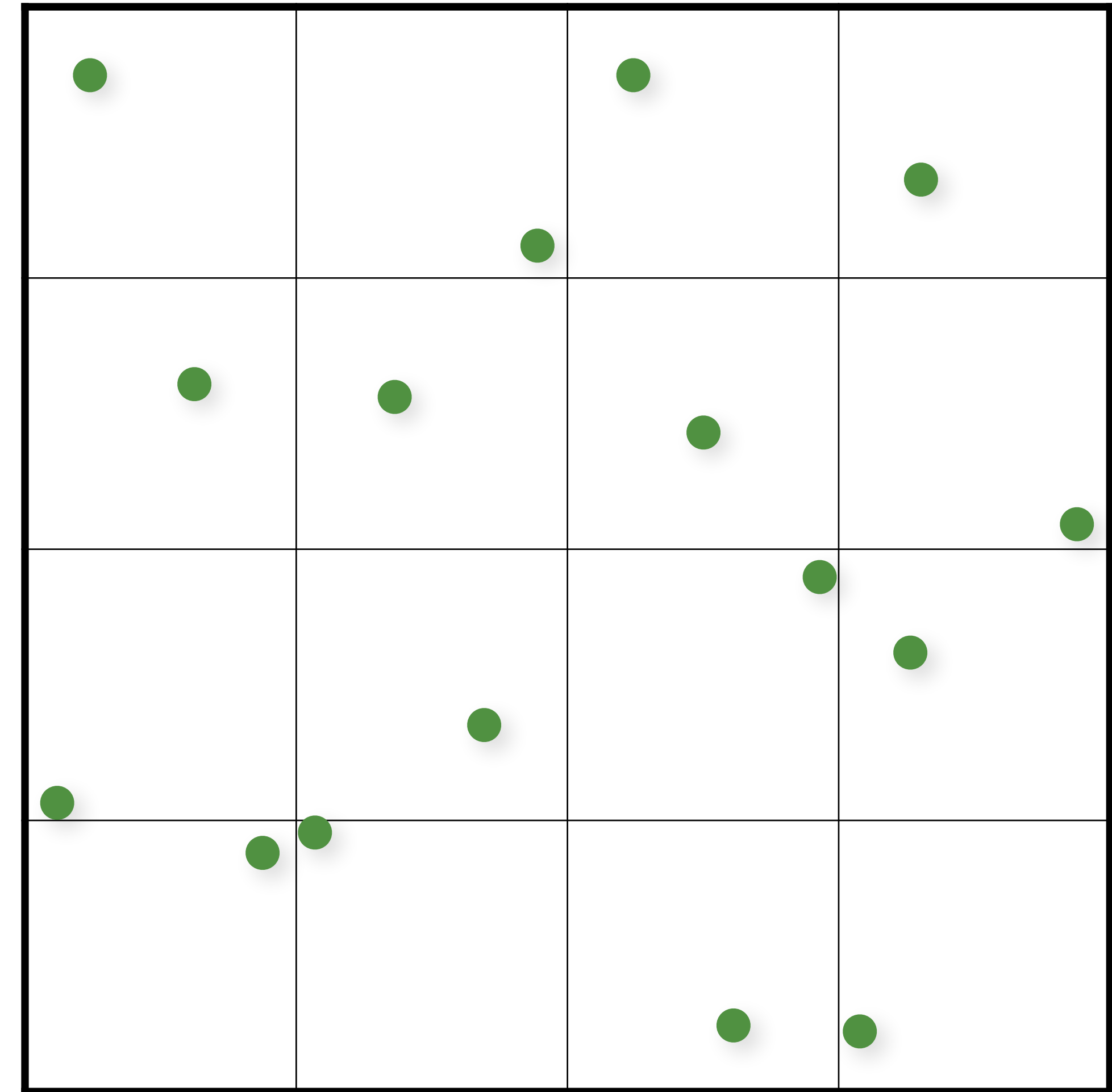
```
for (uint i = 0; i < numX; i++)  
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    {  
        samples(i,j).x = (i + randf())/numX;  
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    }
```



Jittered/Stratified Sampling

```
for (uint i = 0; i < numX; i++)  
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    {  
        samples(i,j).x = (i + randf())/numX;  
        samples(i,j).y = (j + randf())/numY;  
    }
```

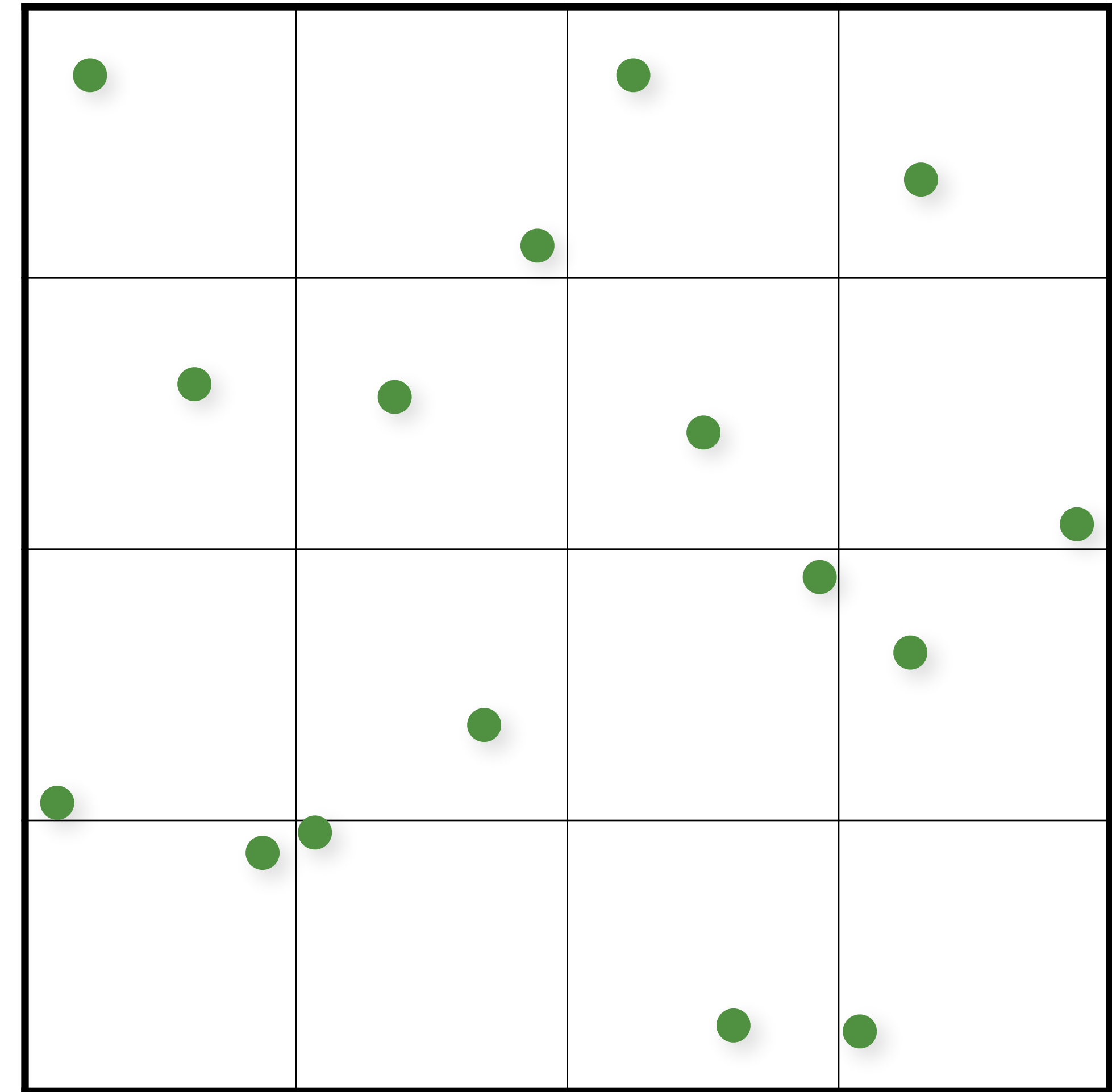
✓ Provably cannot increase variance



Jittered/Stratified Sampling

```
for (uint i = 0; i < numX; i++)  
  for (uint j = 0; j < numY; j++)  
  {  
    samples(i,j).x = (i + randf())/numX;  
    samples(i,j).y = (j + randf())/numY;  
  }
```

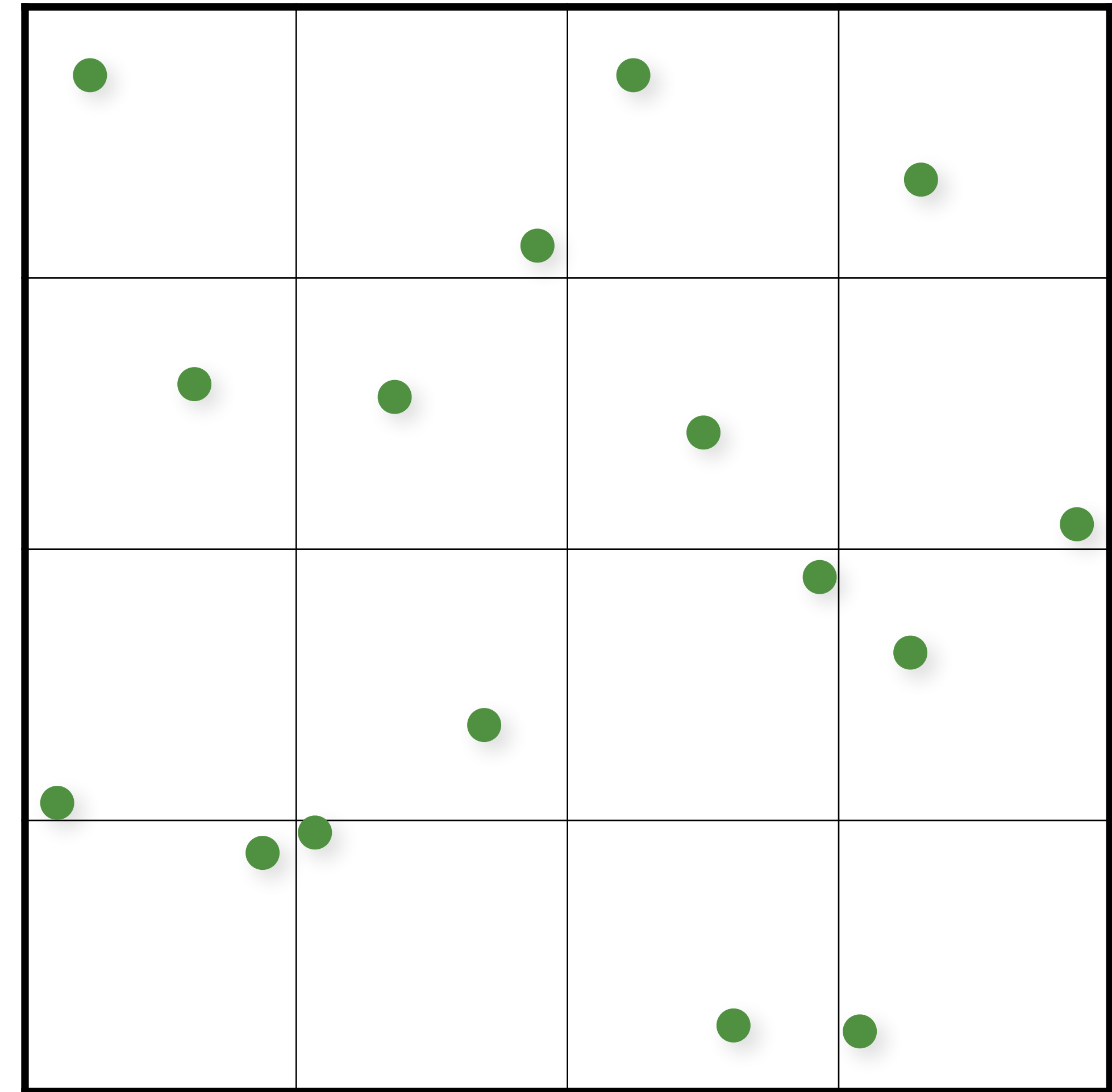
- ✓ Provably cannot increase variance
- ✓ Extends to higher dimensions, but...



Jittered/Stratified Sampling

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  }
```

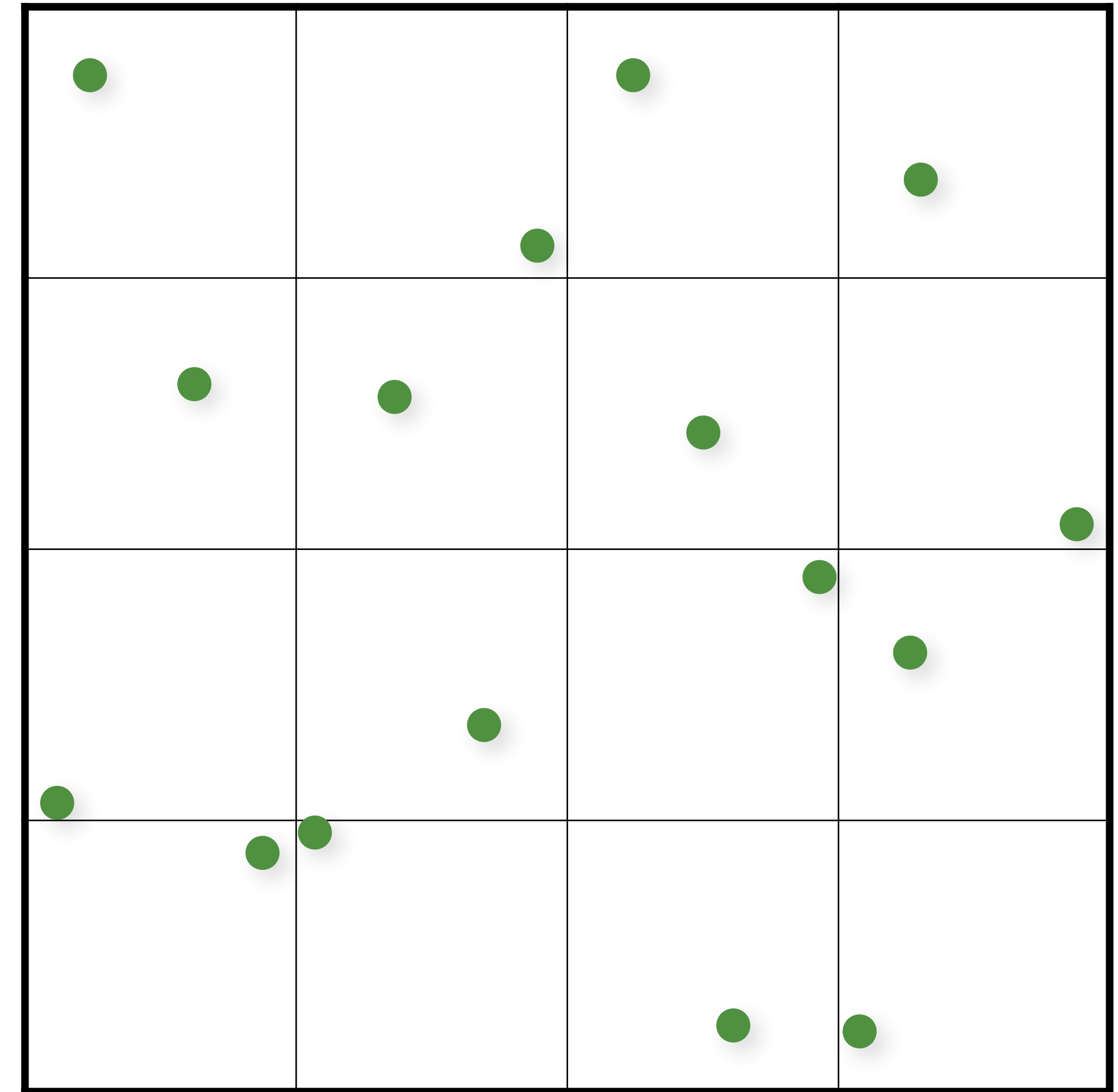
- ✓ Provably cannot increase variance
- ✓ Extends to higher dimensions, but...
- ✗ Curse of dimensionality



Jittered/Stratified Sampling

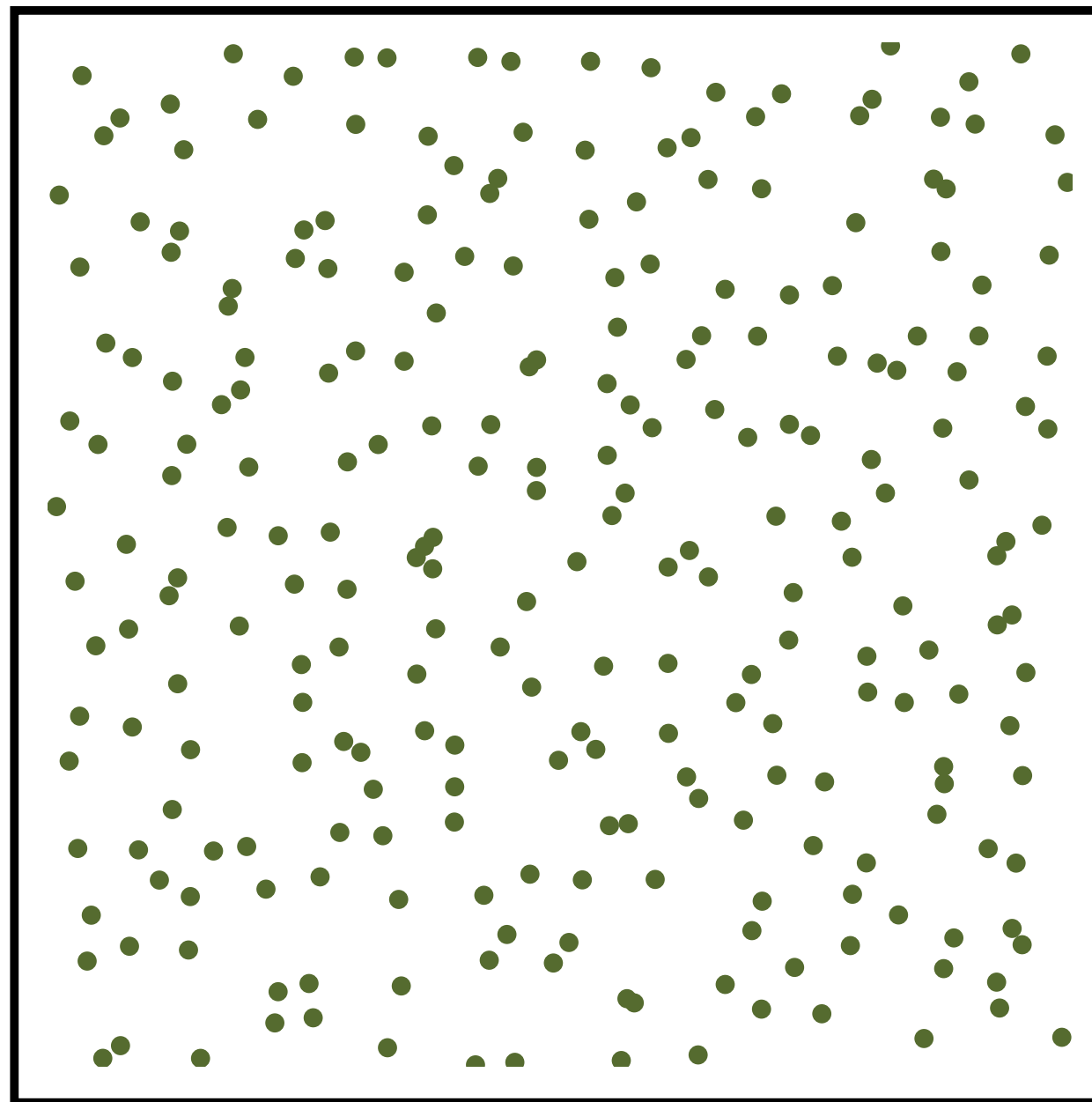
```
for (uint i = 0; i < numX; i++)  
  for (uint j = 0; j < numY; j++)  
  {  
    samples(i,j).x = (i + randf())/numX;  
    samples(i,j).y = (j + randf())/numY;  
  }
```

- ✓ Provably cannot increase variance
- ✓ Extends to higher dimensions, but...
- ✗ Curse of dimensionality
- ✗ Not progressive

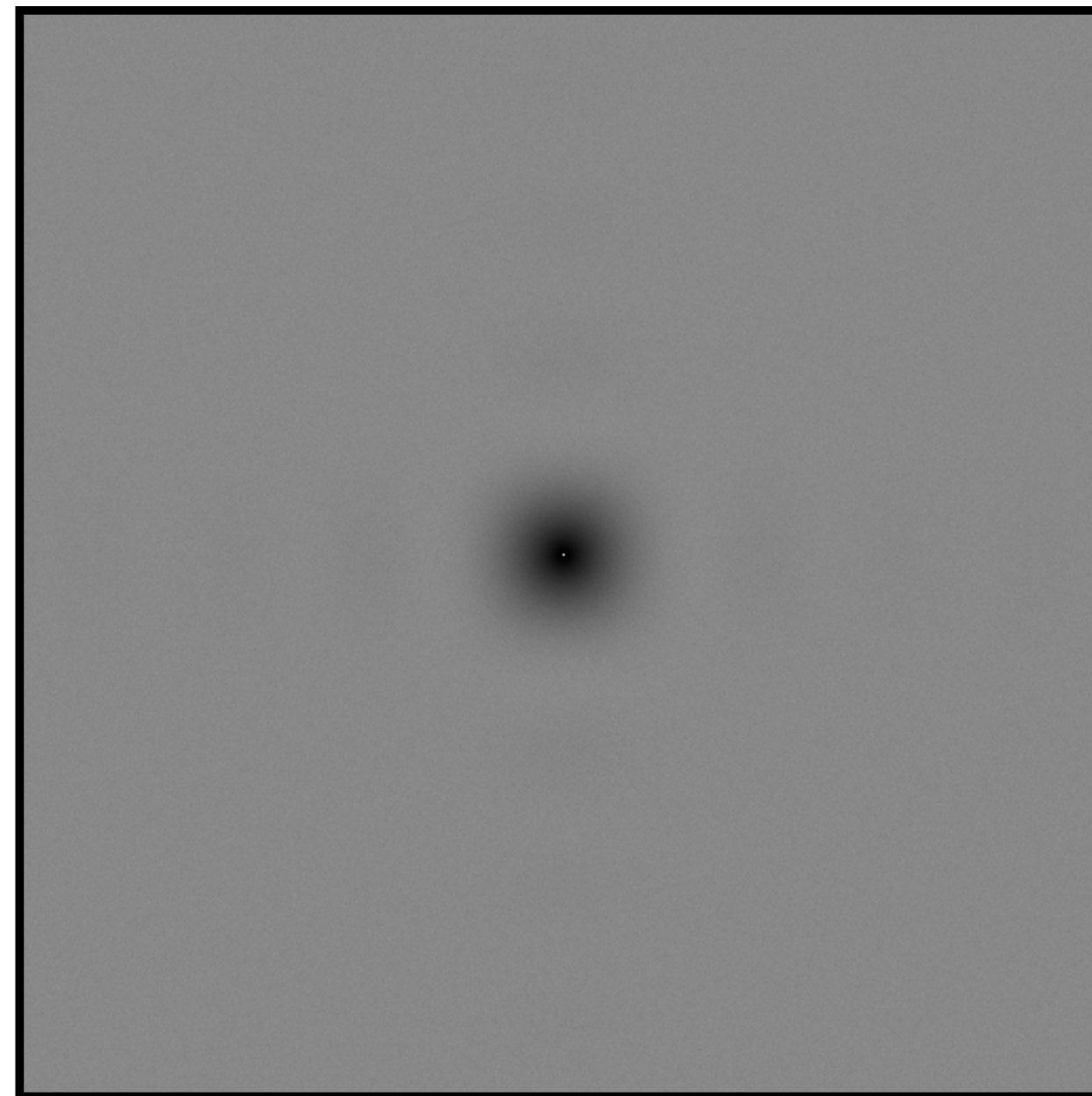


Jittered Sampling

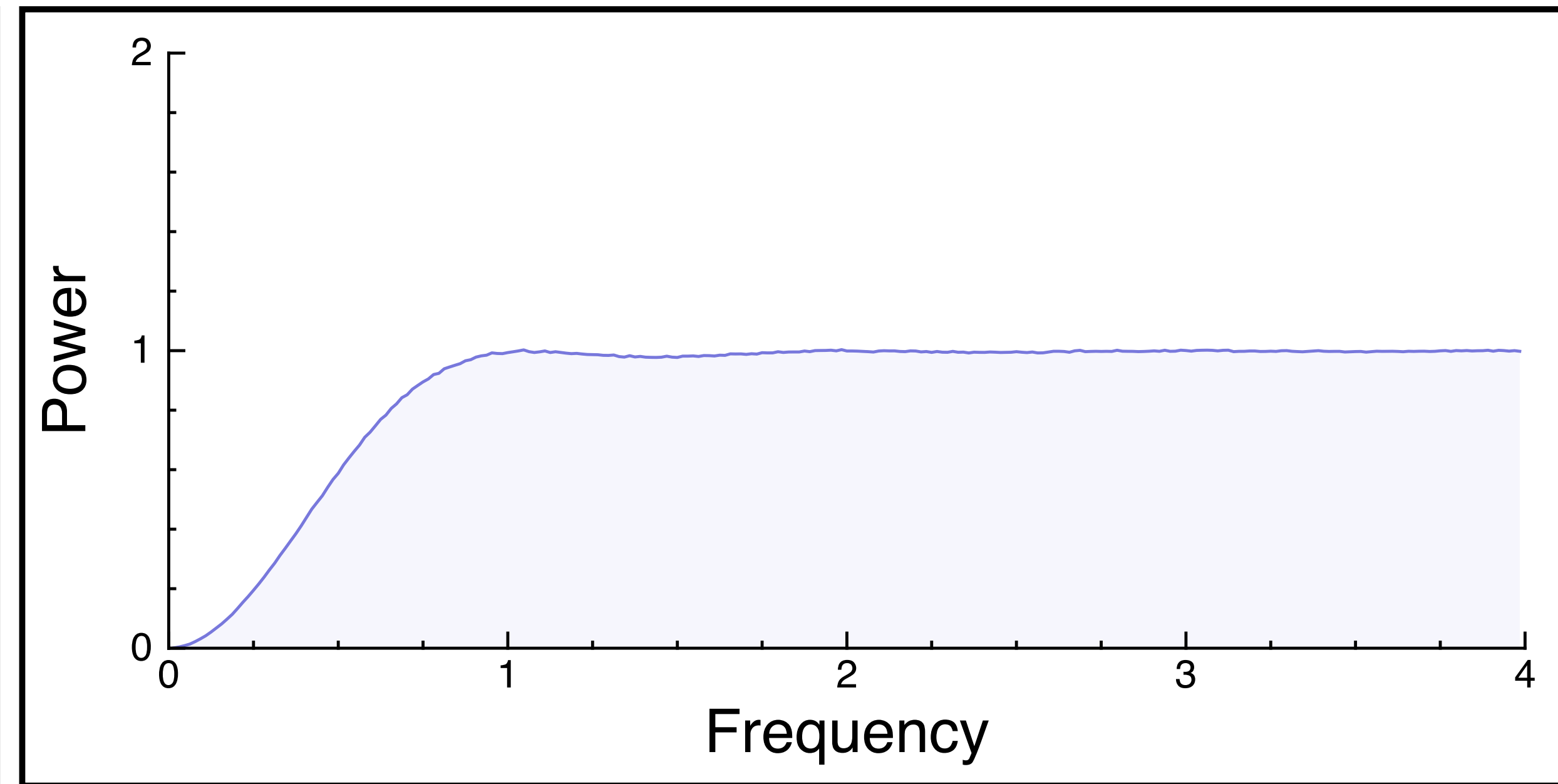
Samples



Expected power spectrum

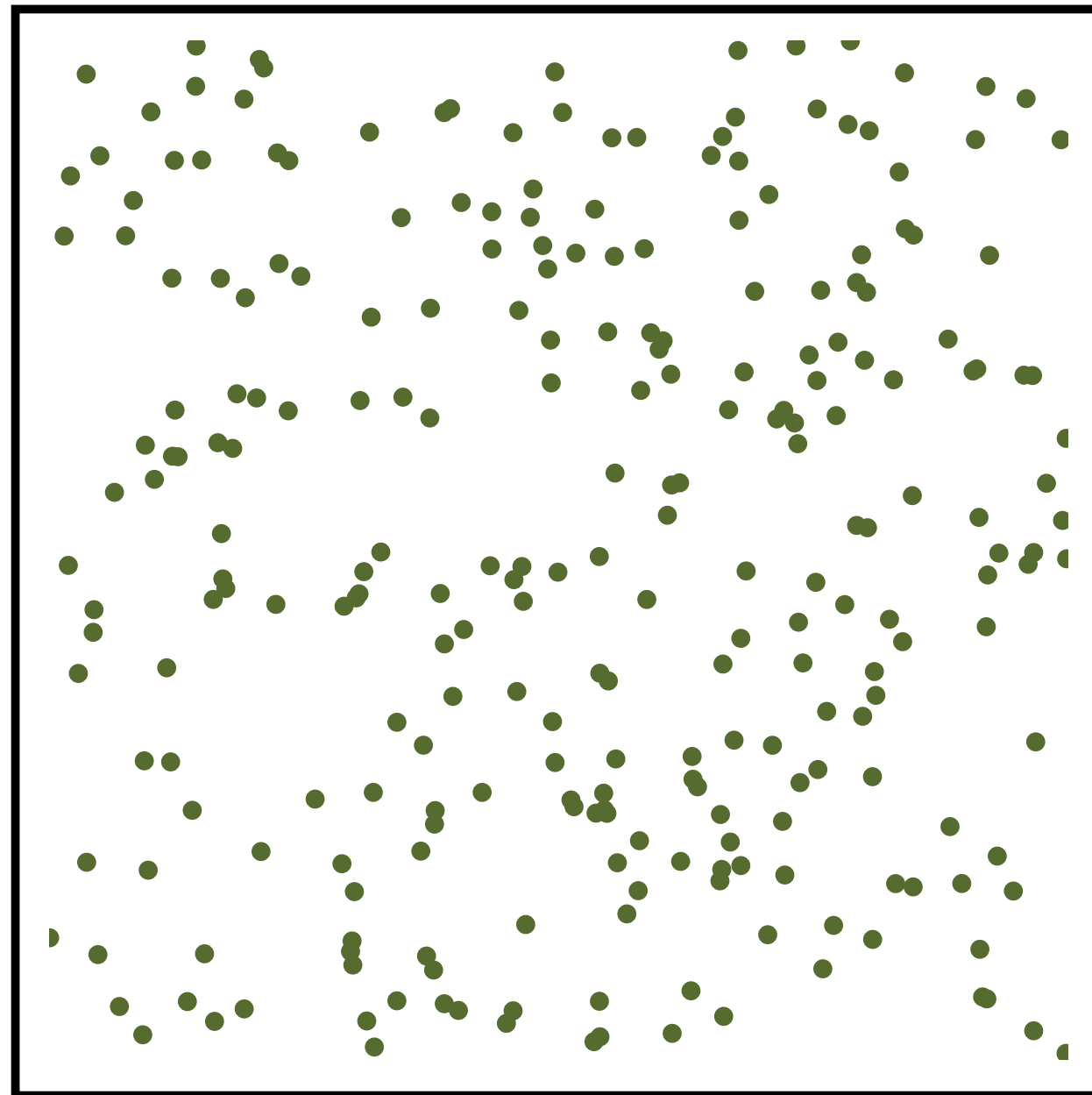


Radial mean



Independent Random Sampling

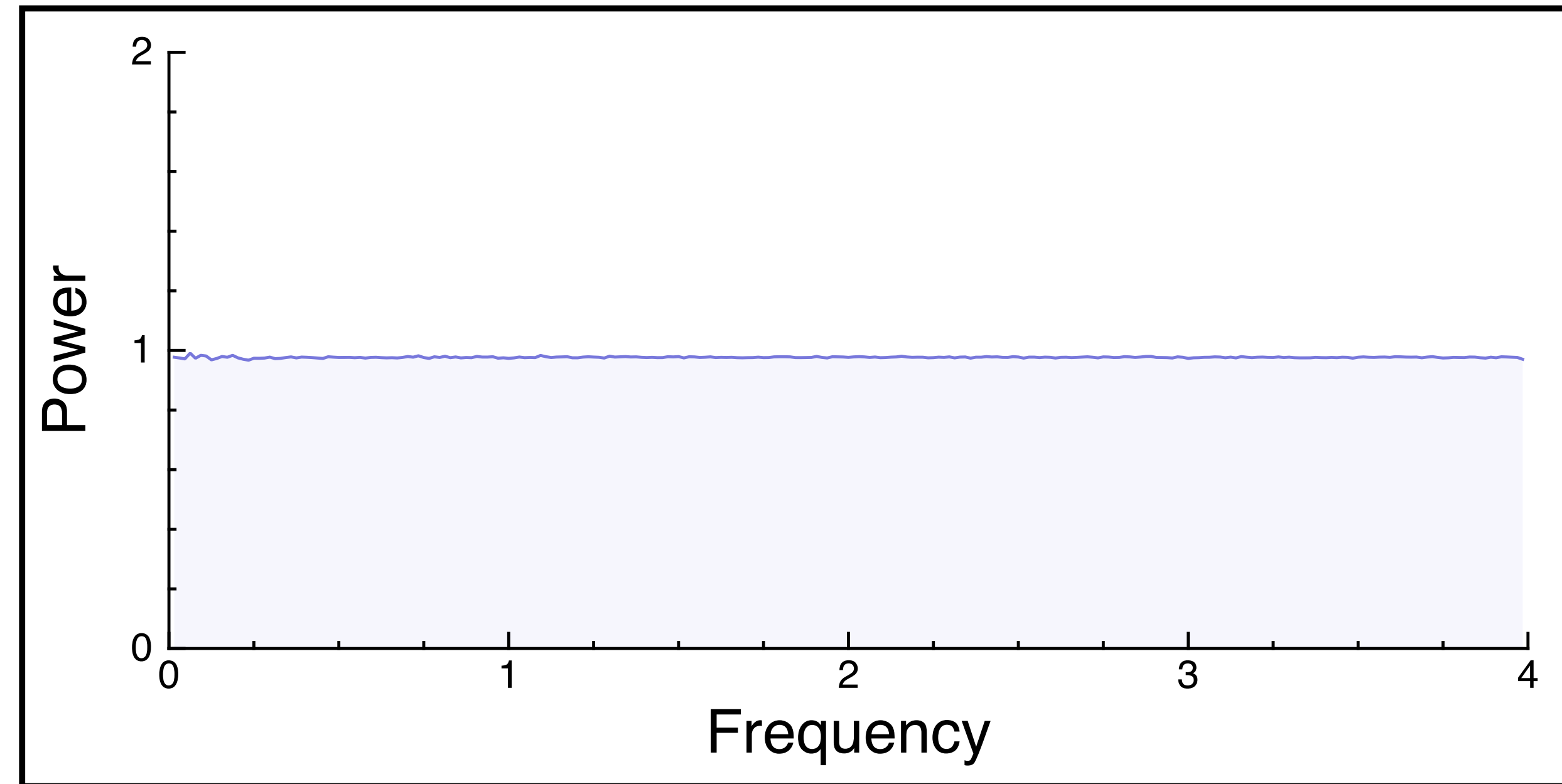
Samples



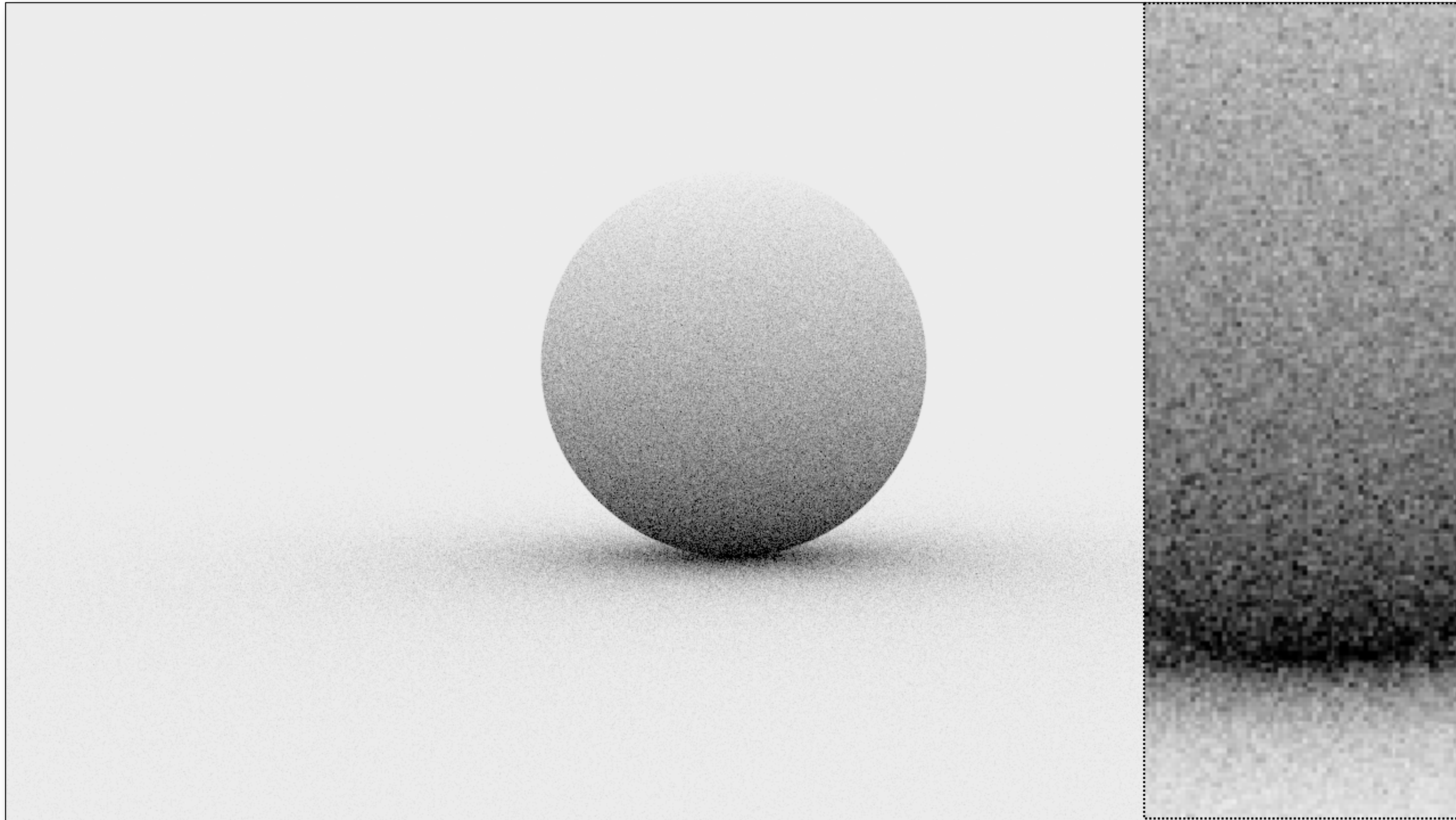
Expected power spectrum



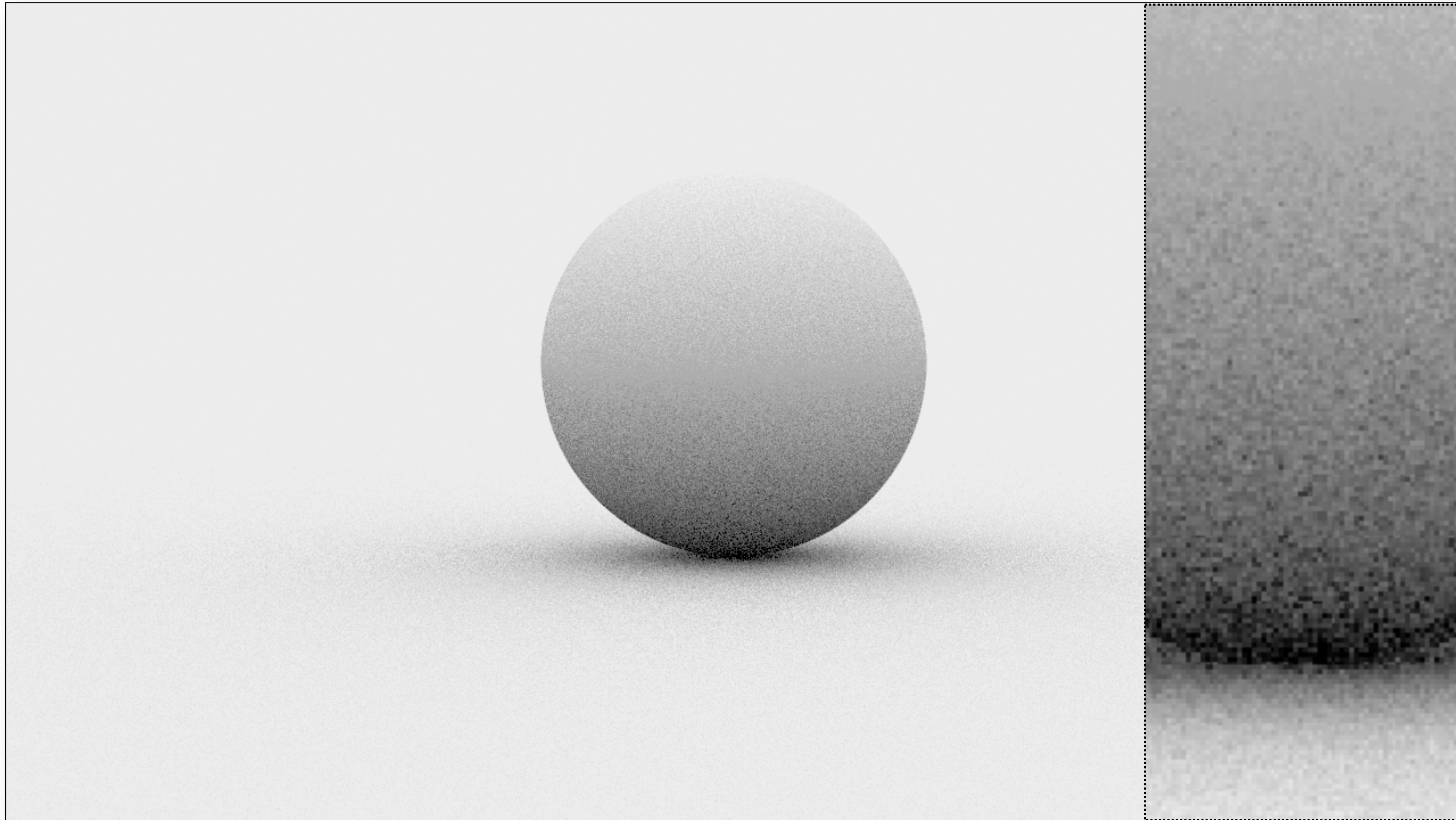
Radial mean



Monte Carlo (16 random samples)



Monte Carlo (16 jittered samples)



Stratifying in Higher Dimensions

Stratification requires $O(N^d)$ samples

- e.g. pixel (2D) + lens (2D) + time (1D) = 5D

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 - splitting 2 times in 5D = $2^5 = 32$ samples
 - splitting 3 times in 5D = $3^5 = 243$ samples!

Stratifying in Higher Dimensions

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 - splitting 2 times in 5D = $2^5 = 32$ samples
 - splitting 3 times in 5D = $3^5 = 243$ samples!

Inconvenient for large d

- cannot select sample count with fine granularity

Uncorrelated Jitter [Cook et al. 84]

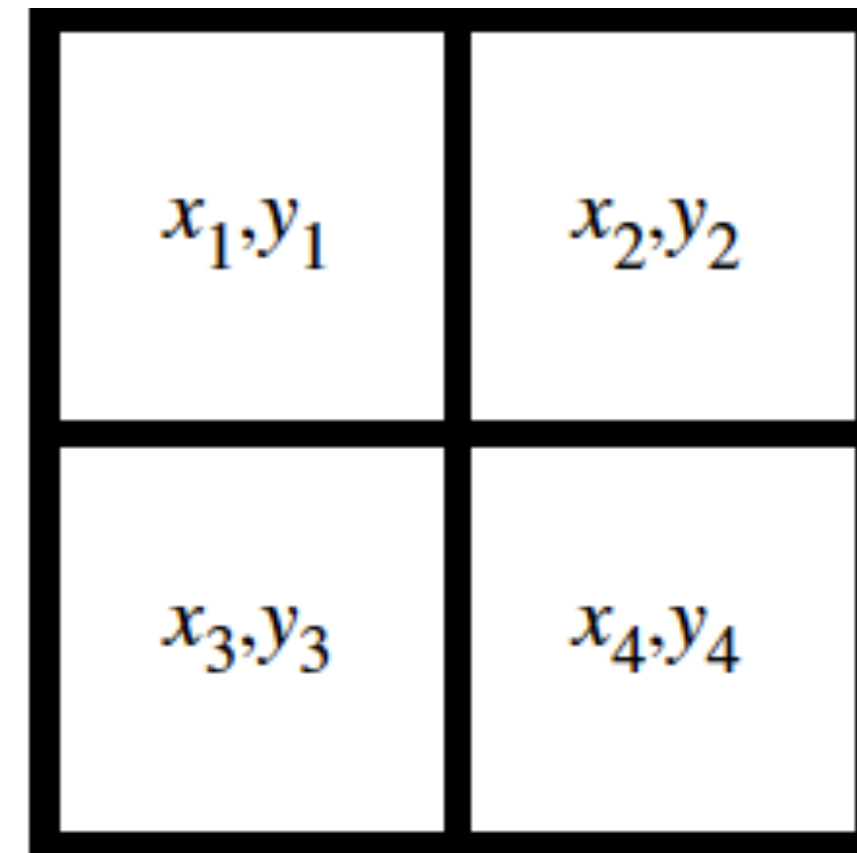
Uncorrelated Jitter [Cook et al. 84]

Compute stratified samples in sub-dimensions

Uncorrelated Jitter [Cook et al. 84]

Compute stratified samples in sub-dimensions

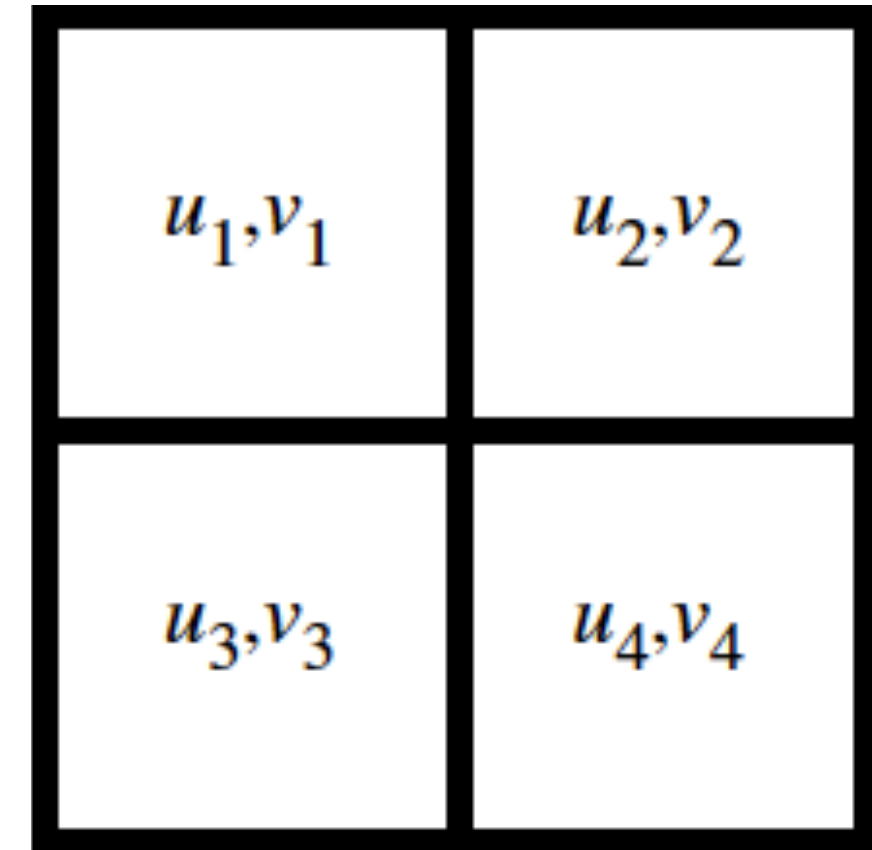
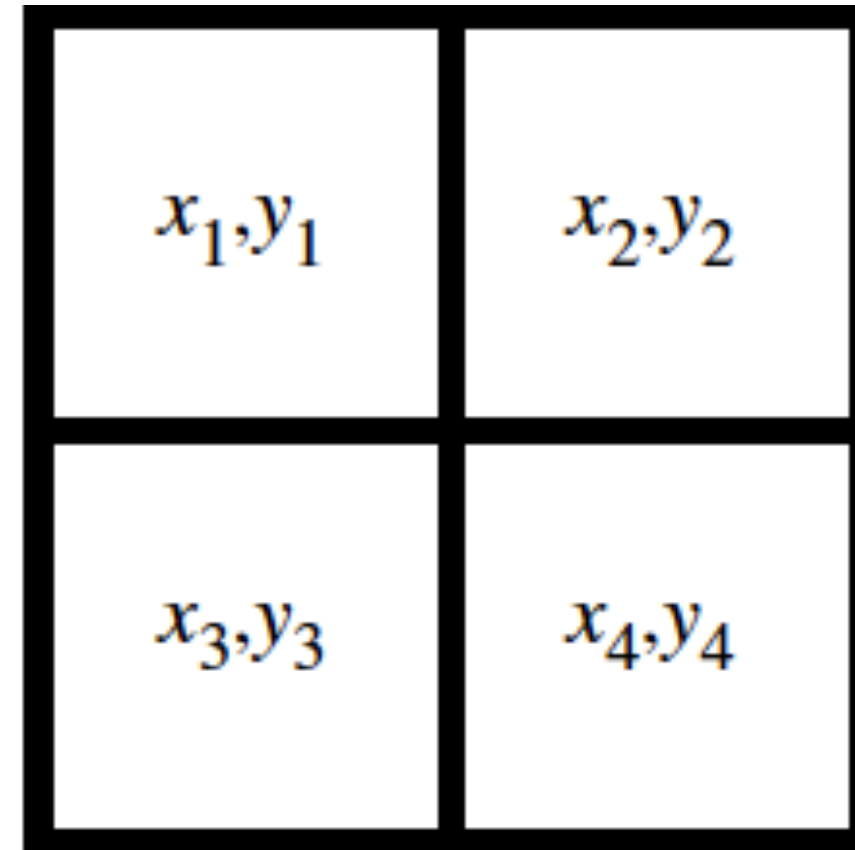
- 2D jittered (x,y) for pixel



Uncorrelated Jitter [Cook et al. 84]

Compute stratified samples in sub-dimensions

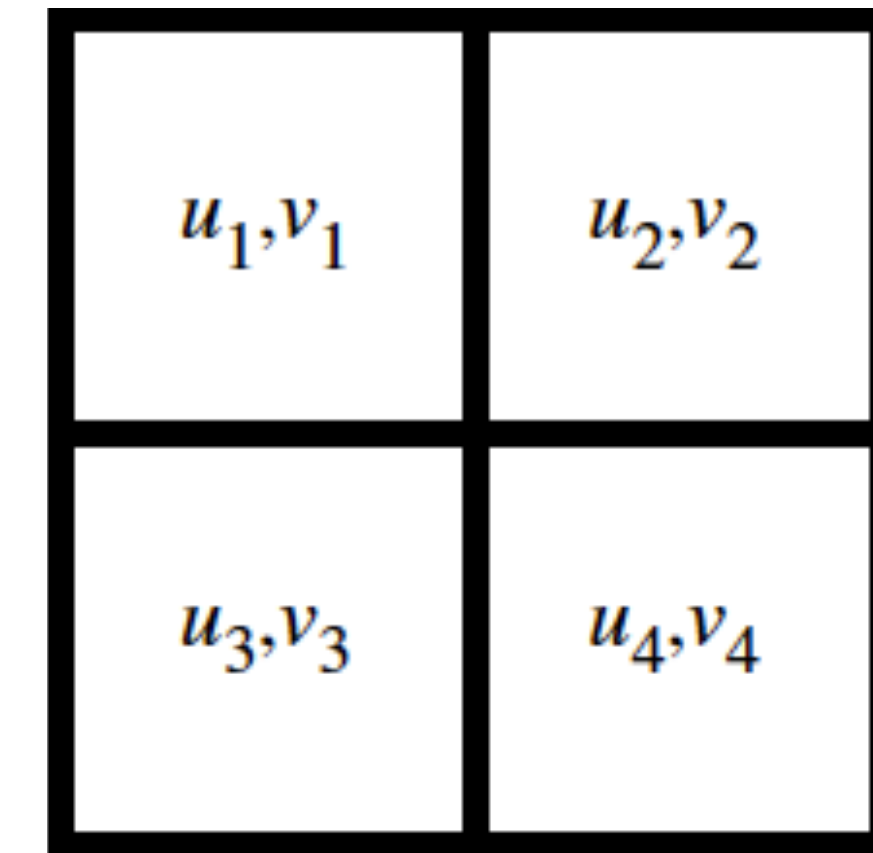
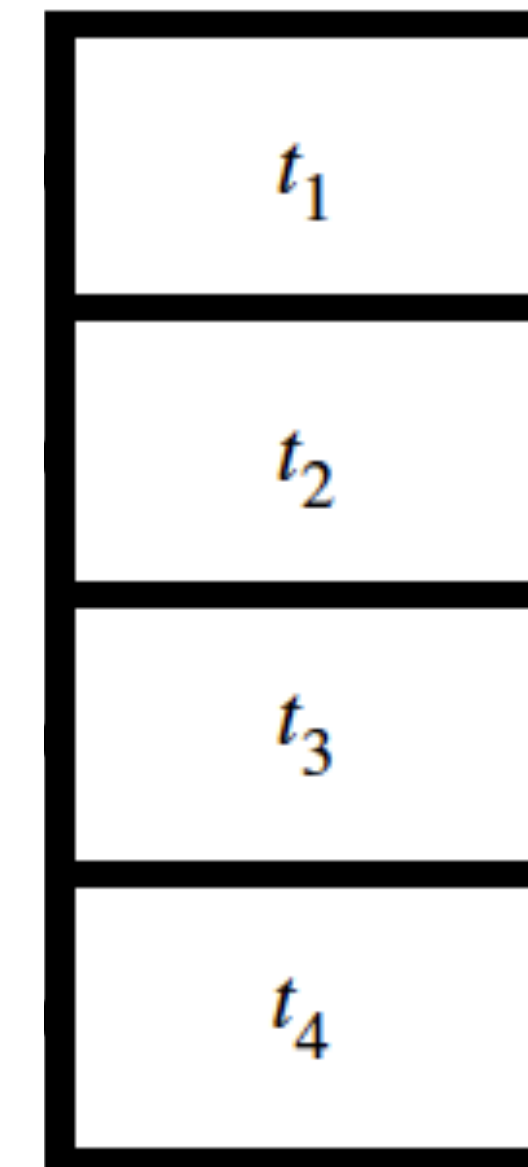
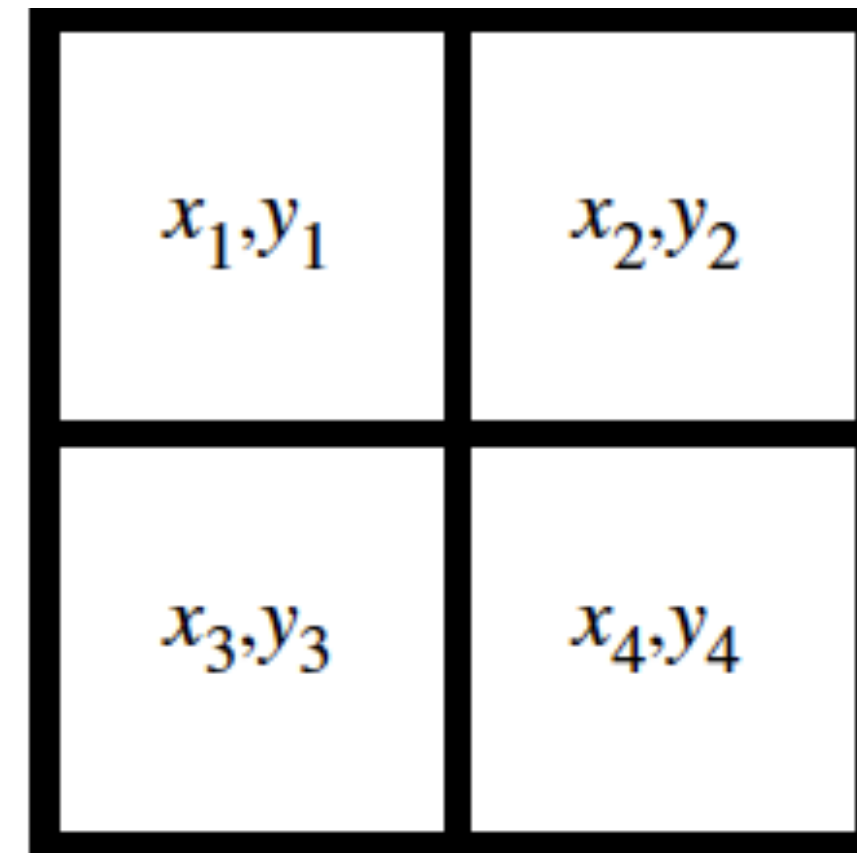
- 2D jittered (x,y) for pixel
- 2D jittered (u,v) for lens



Uncorrelated Jitter [Cook et al. 84]

Compute stratified samples in sub-dimensions

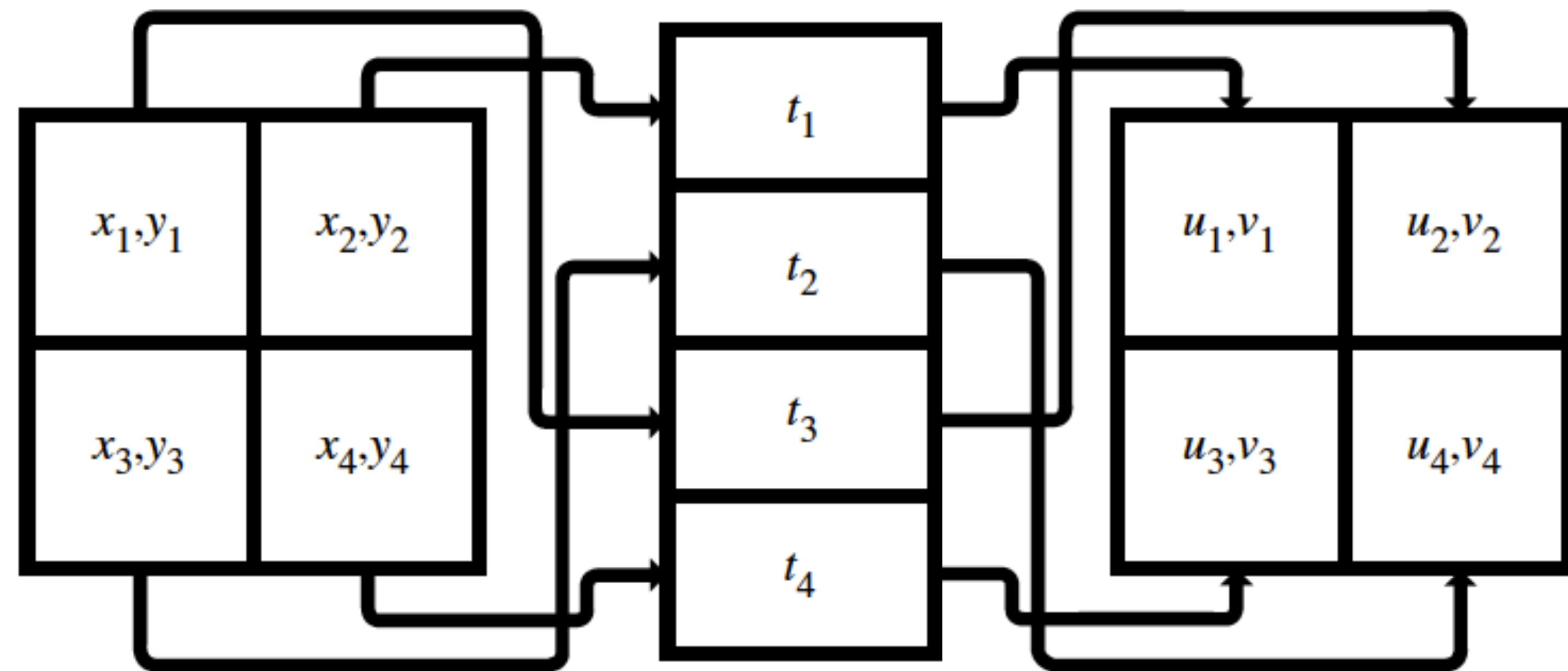
- 2D jittered (x,y) for pixel
- 2D jittered (u,v) for lens
- 1D jittered (t) for time



Uncorrelated Jitter [Cook et al. 84]

Compute stratified samples in sub-dimensions

- 2D jittered (x,y) for pixel
- 2D jittered (u,v) for lens
- 1D jittered (t) for time
- combine dimensions in random order

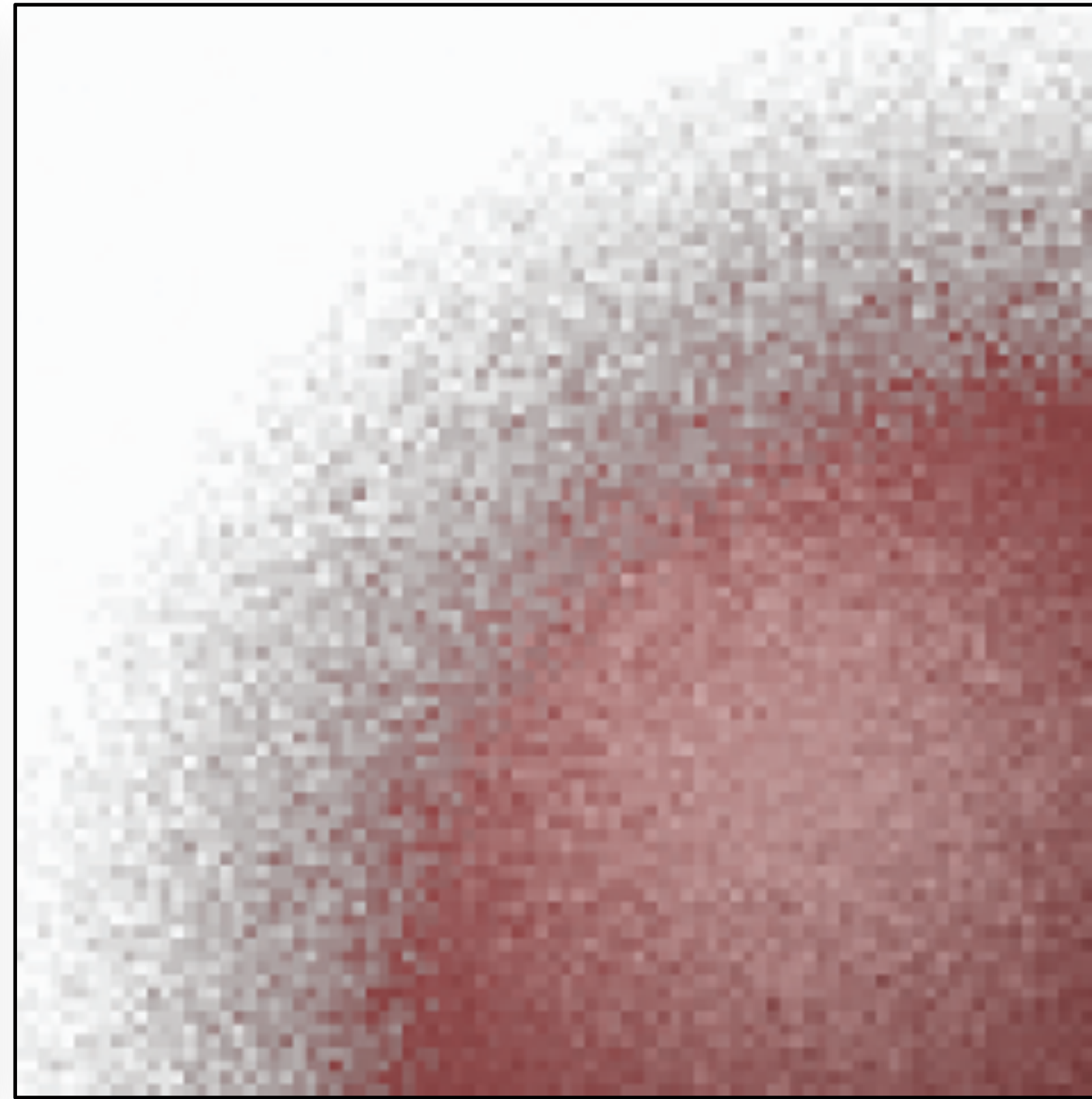


Depth of Field (4D)

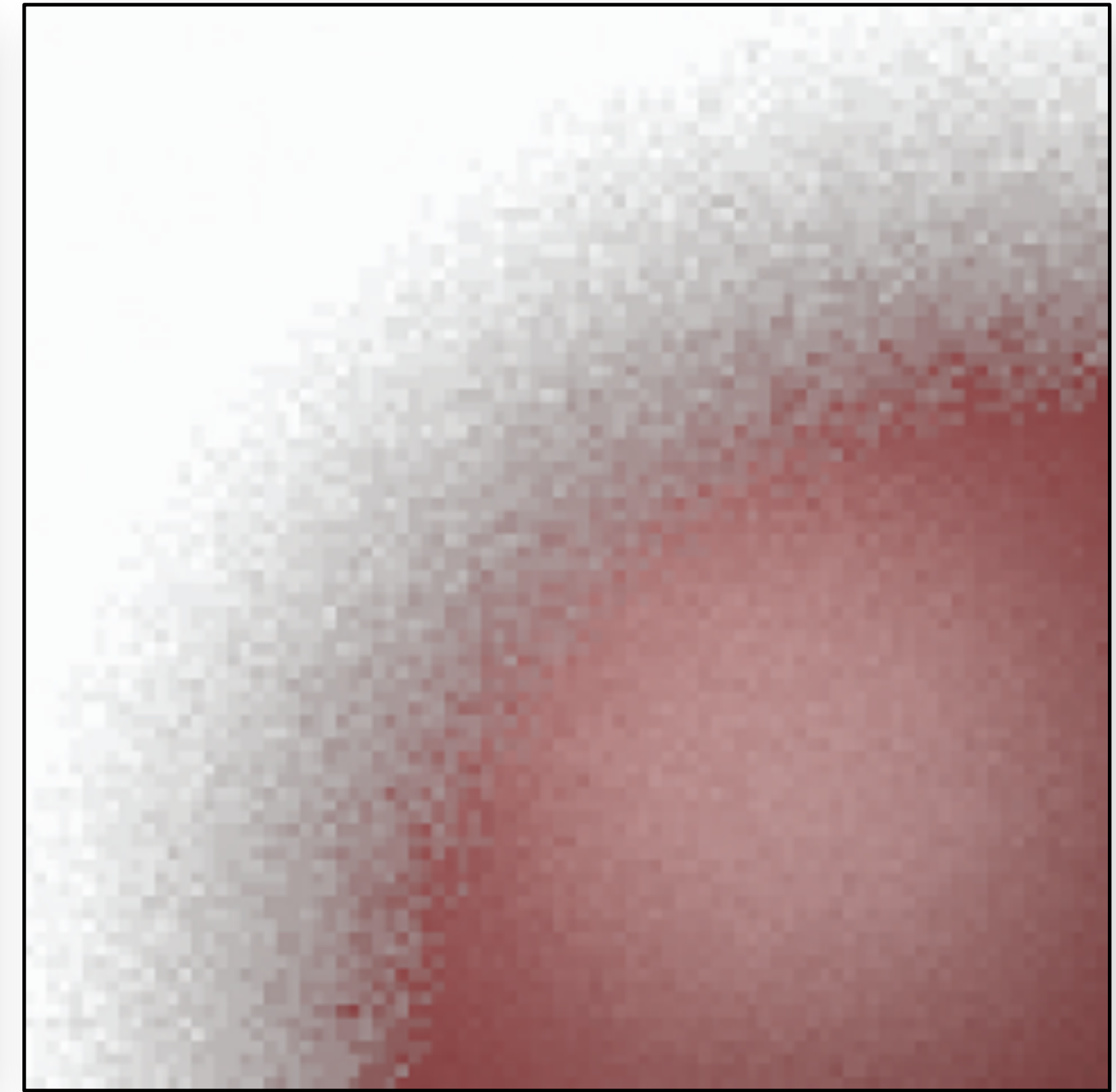
Reference



Random Sampling



Uncorrelated Jitter



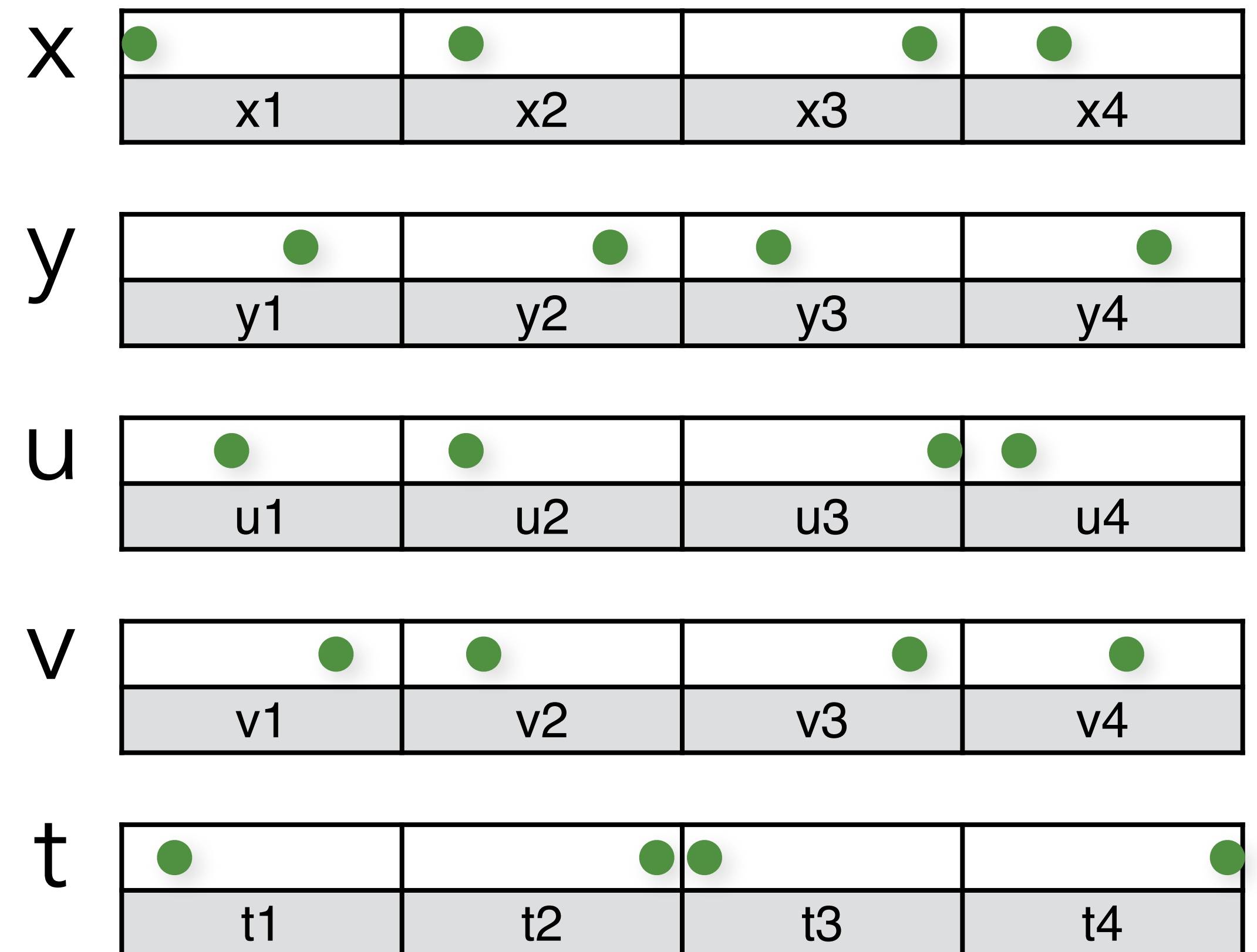
Uncorrelated Jitter → Latin Hypercube

Stratify samples in each dimension separately

Uncorrelated Jitter → Latin Hypercube

Stratify samples in each dimension separately

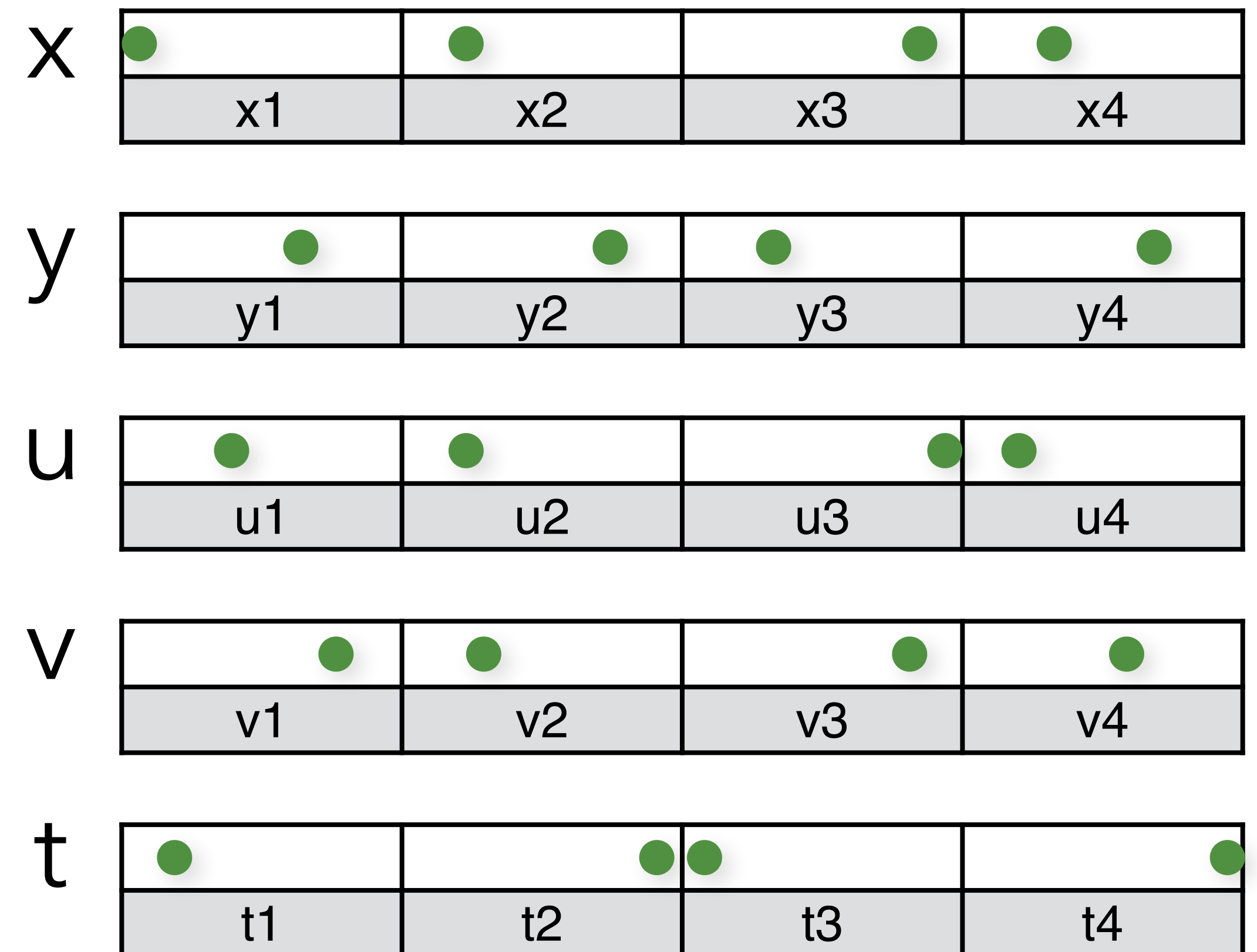
- for 5D: 5 separate 1D jittered point sets



Uncorrelated Jitter → Latin Hypercube

Stratify samples in each dimension separately

- for 5D: 5 separate 1D jittered point sets
- combine dimensions in random order

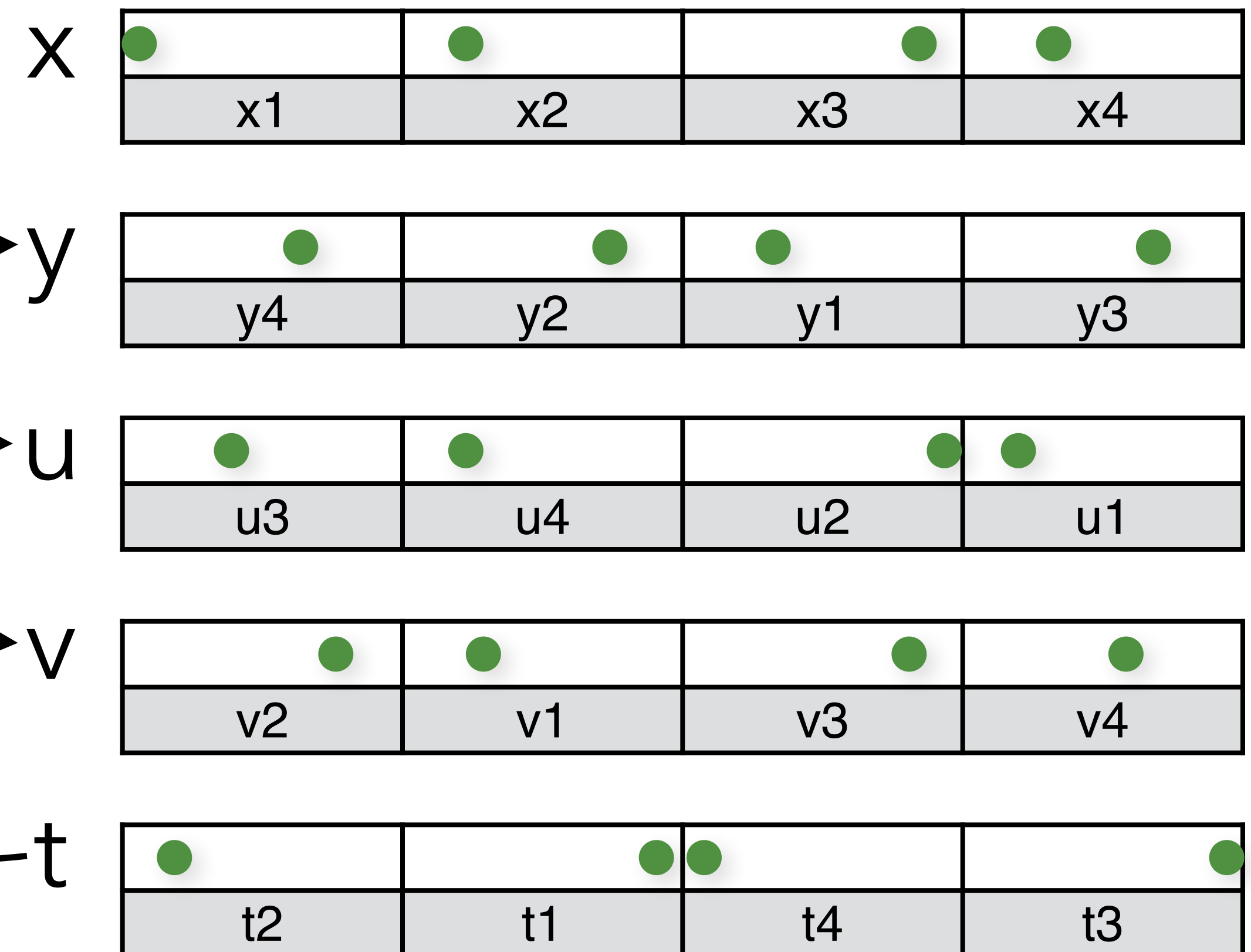


Uncorrelated Jitter → Latin Hypercube

Stratify samples in each dimension separately

- for 5D: 5 separate 1D jittered point sets
- combine dimensions in random order









Shuffle order



N-Rooks = 2D Latin Hypercube [Shirley 91]

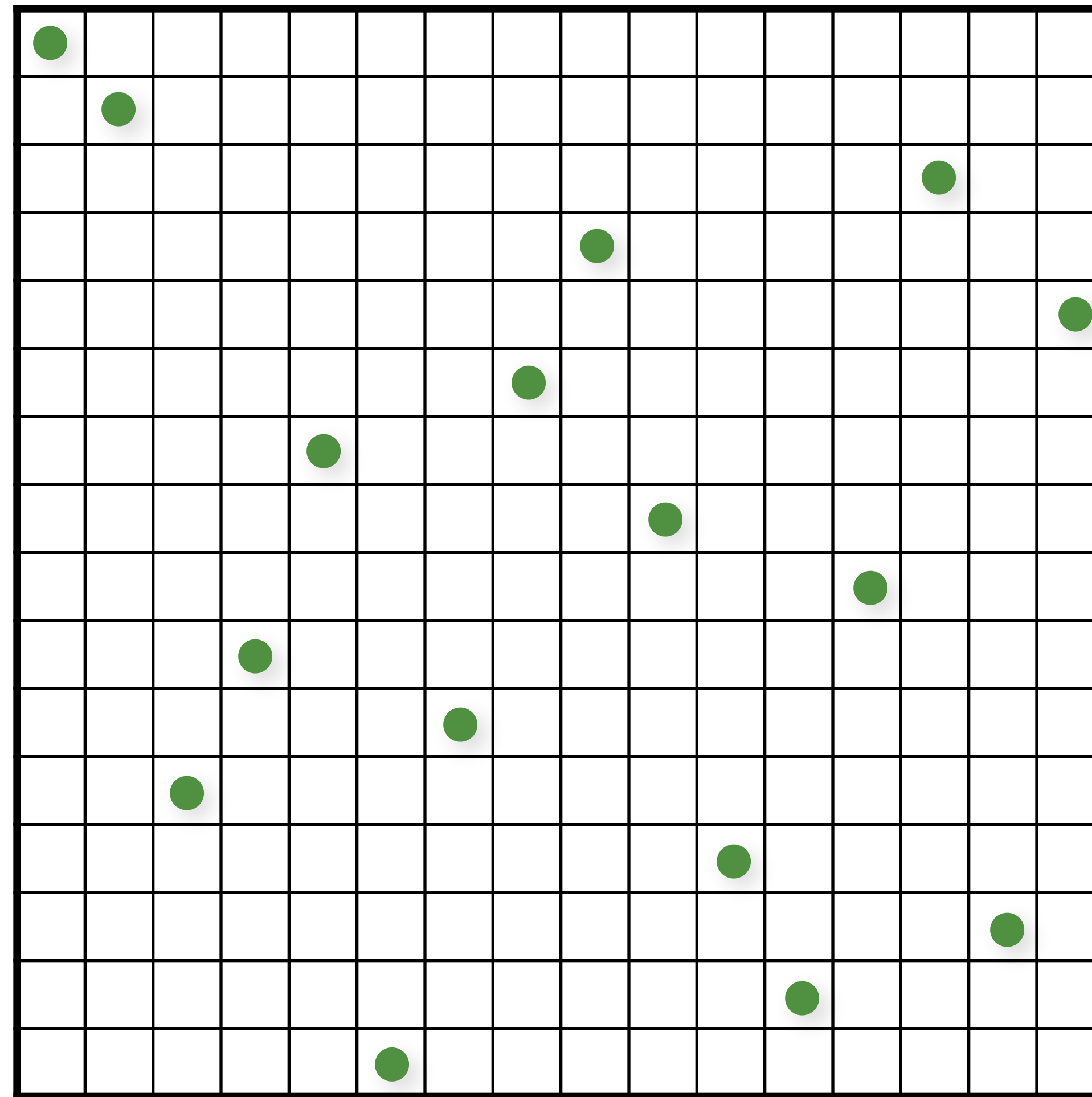
Stratify samples in each dimension separately

- for **2D**: **2** separate 1D jittered point sets
- combine dimensions in random order

x				
	x1	x2	x3	x4
y				
	y4	y2	y1	y3

Latin Hypercube (N-Rooks) Sampling

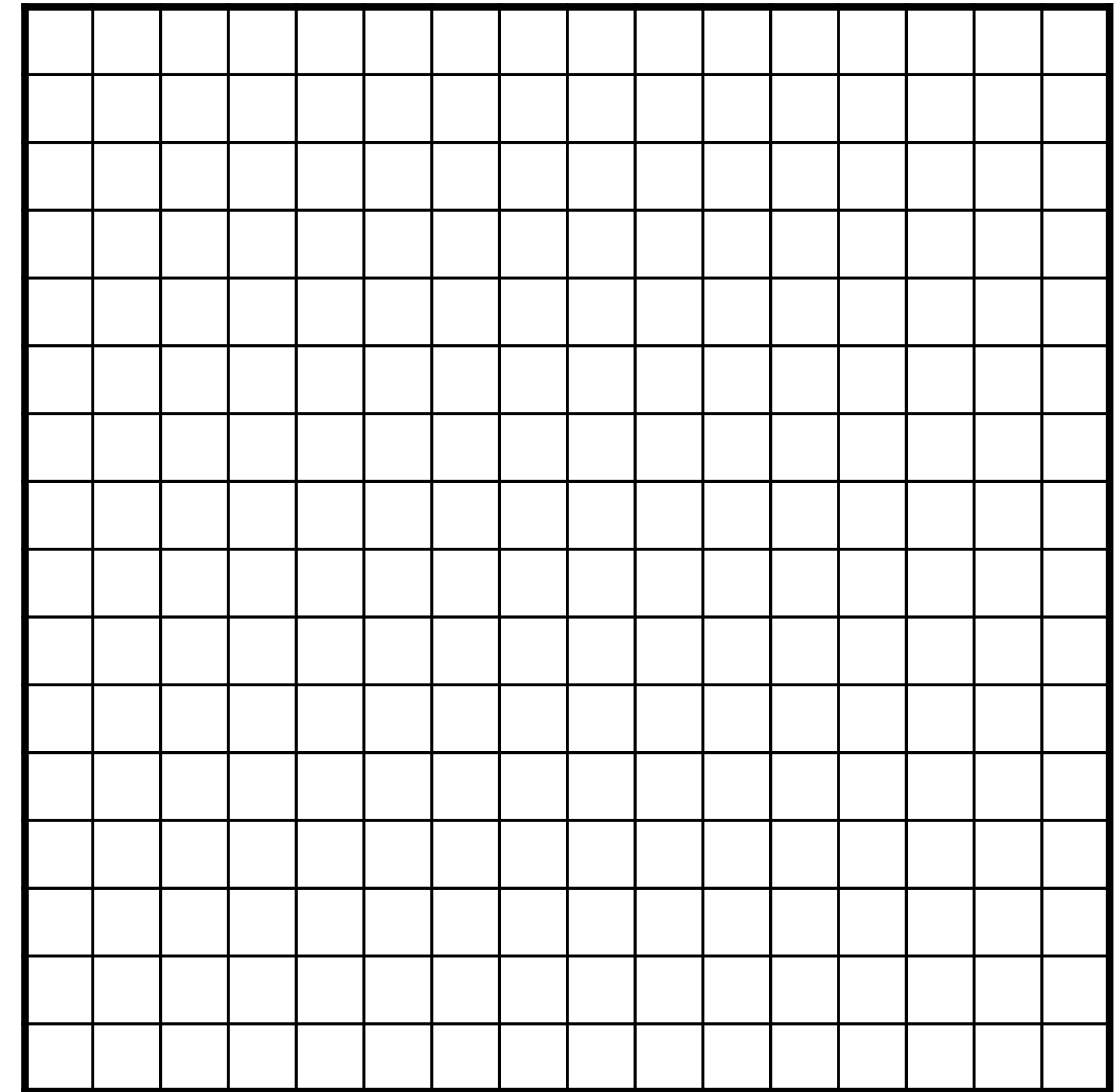
[Shirley 91]



Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;
```

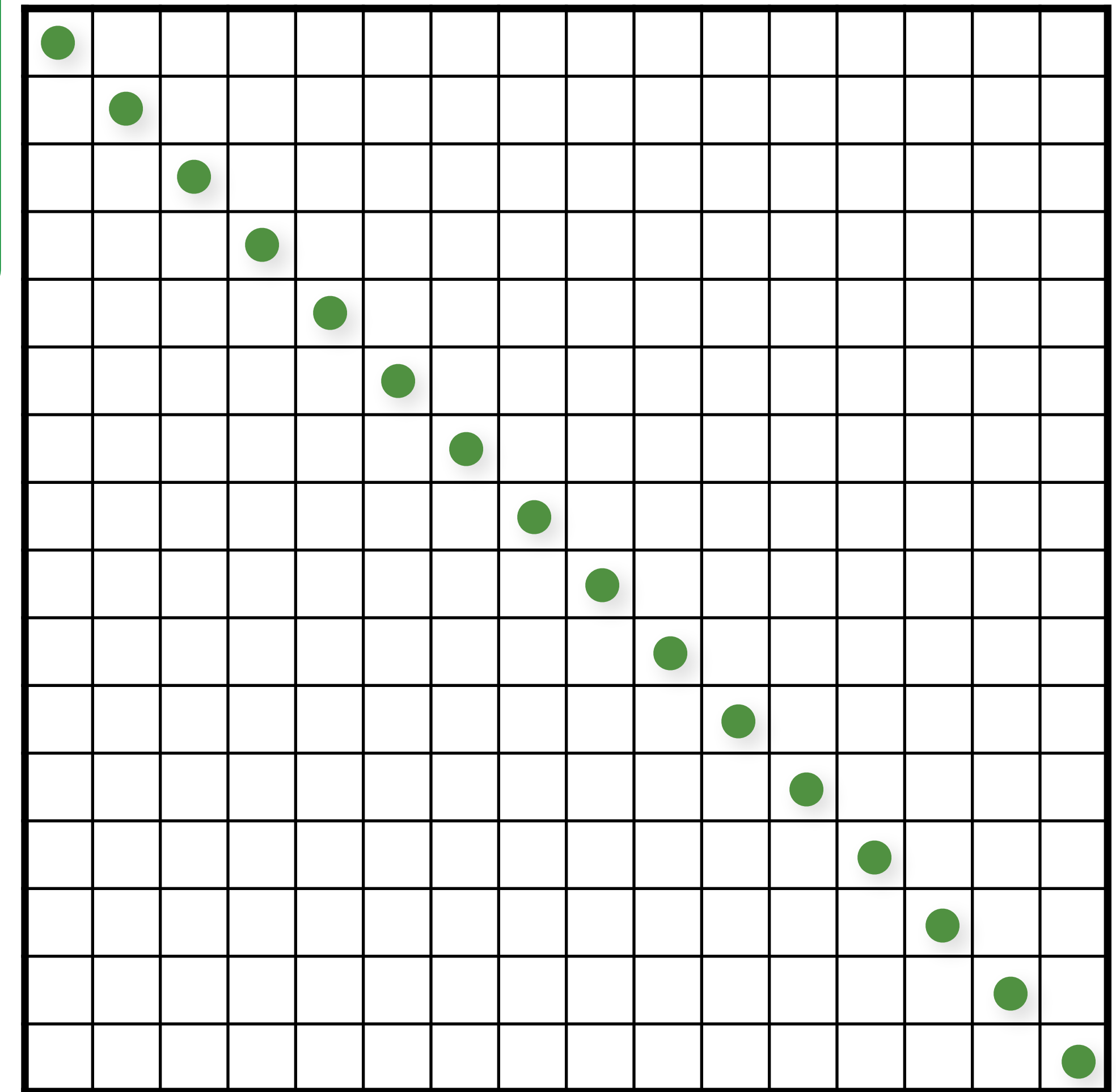
```
// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));
```



Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal  
for (uint d = 0; d < numDimensions; d++)  
    for (uint i = 0; i < numS; i++)  
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```

```
// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```

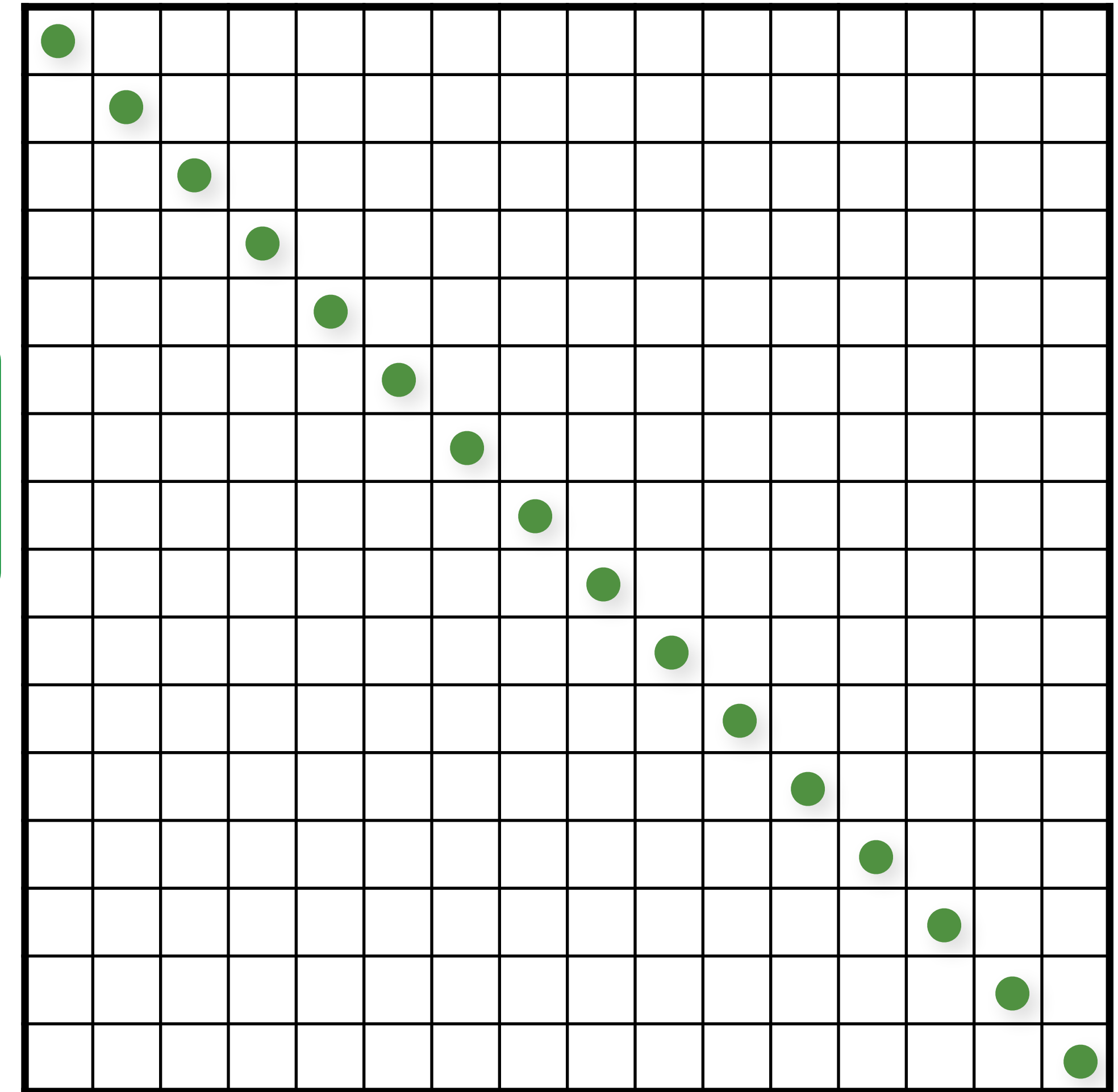


Initialize

Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal  
for (uint d = 0; d < numDimensions; d++)  
    for (uint i = 0; i < numS; i++)  
        samples(d,i) = (i + randf())/numS;
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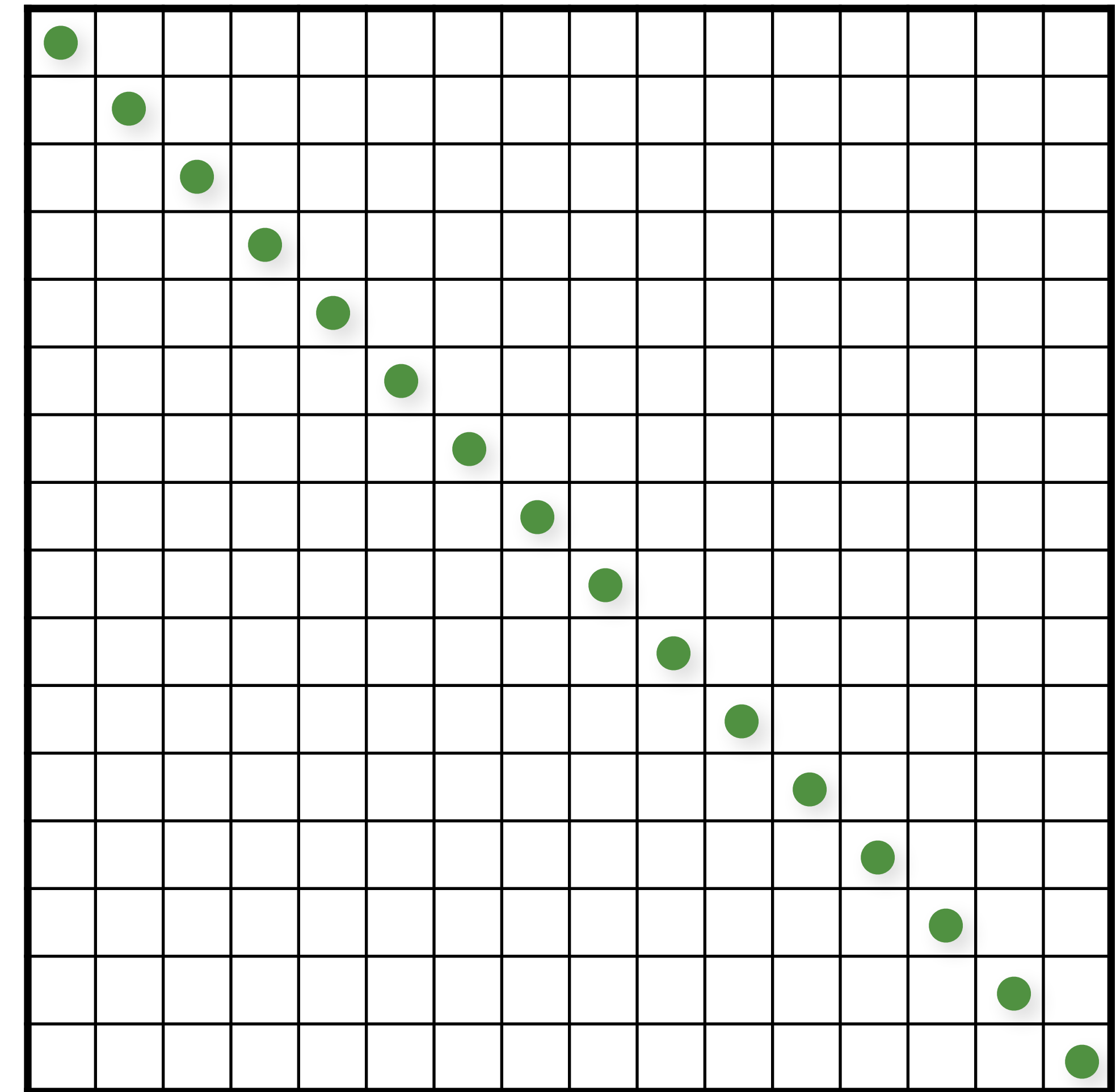
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```

```
// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```

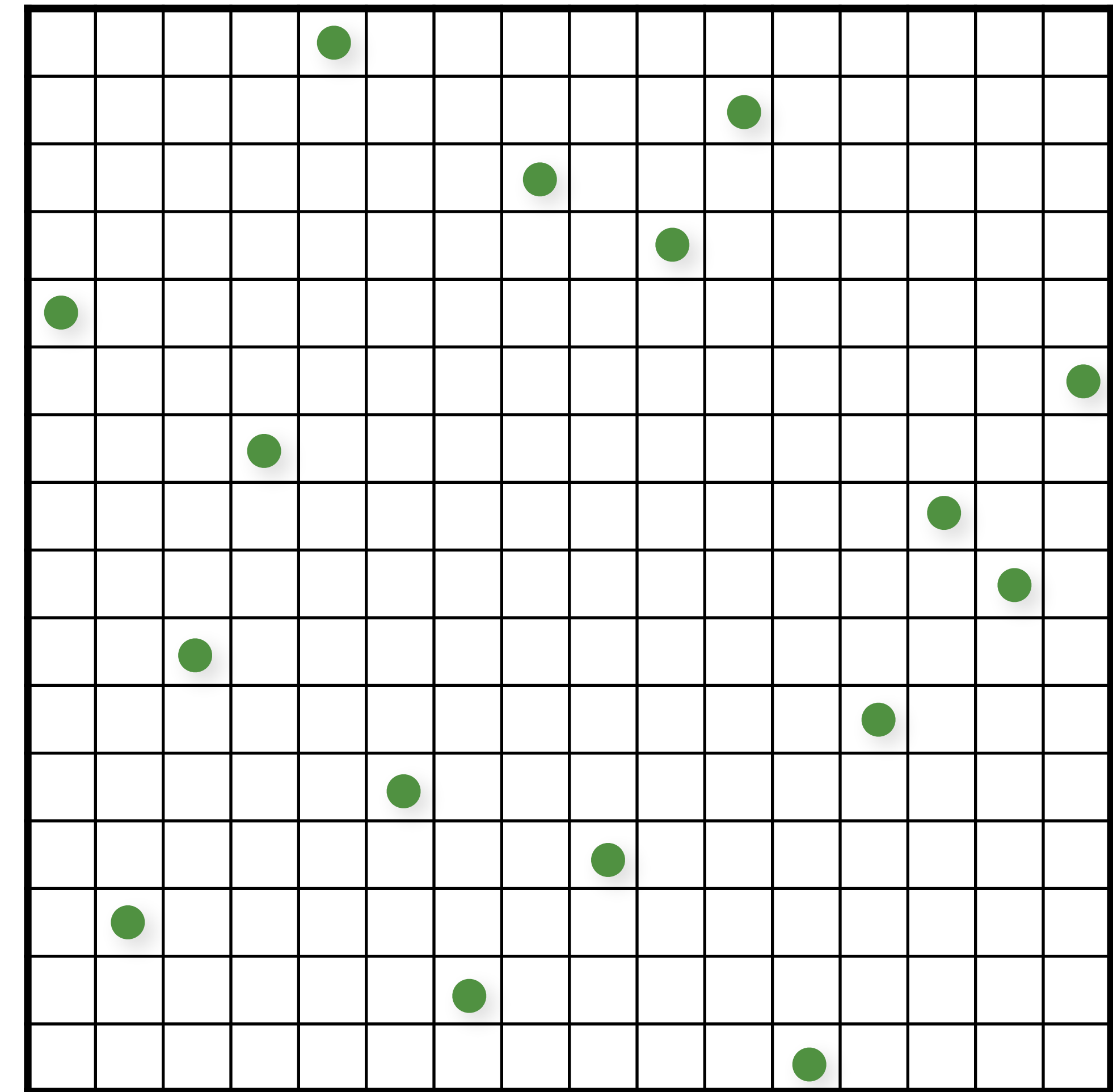


Shuffle rows

Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal  
for (uint d = 0; d < numDimensions; d++)  
    for (uint i = 0; i < numS; i++)  
        samples(d,i) = (i + randf())/numS;
```

```
// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```

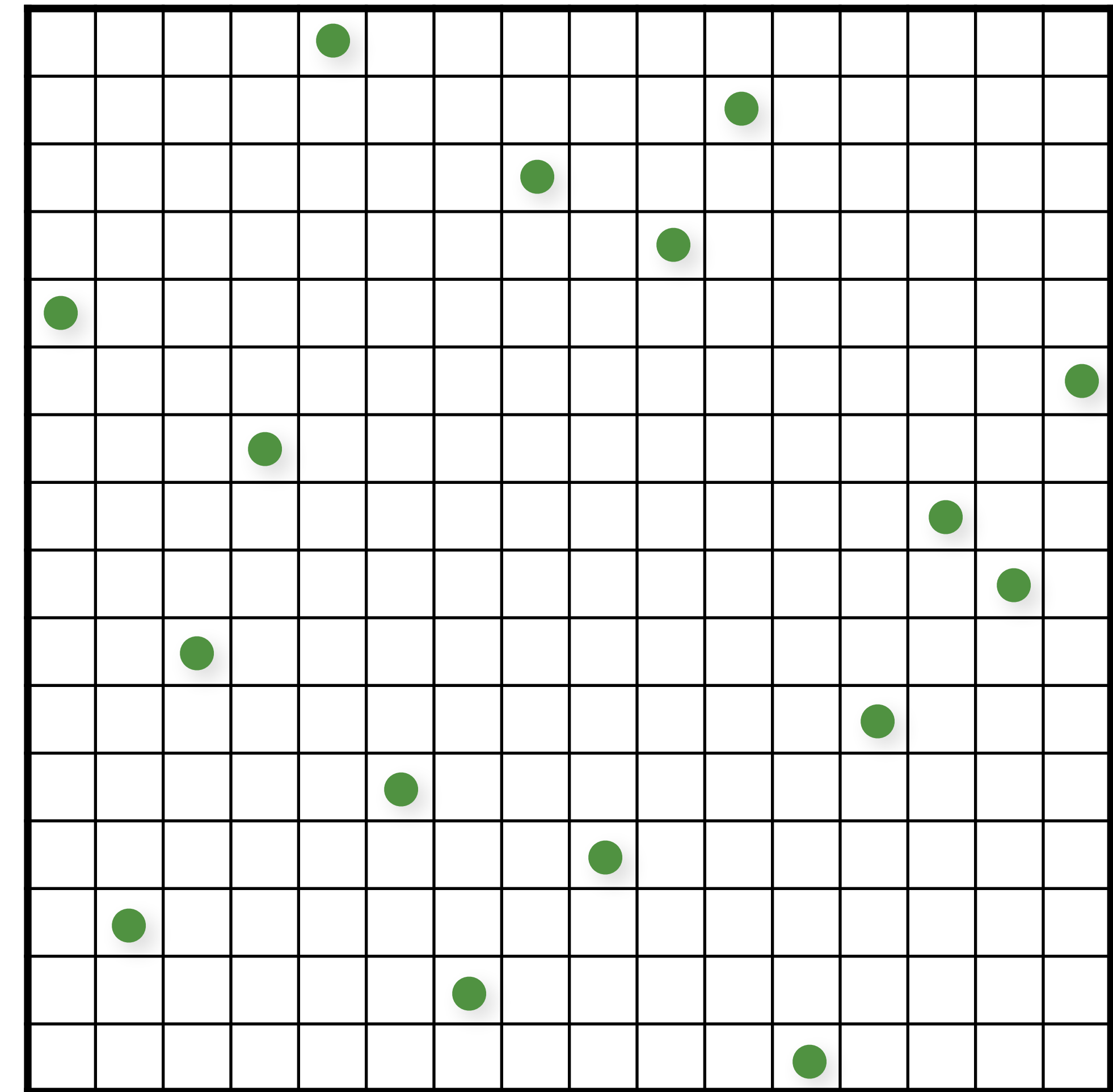


Shuffle rows

Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal  
for (uint d = 0; d < numDimensions; d++)  
    for (uint i = 0; i < numS; i++)  
        samples(d,i) = (i + randf())/numS;
```

```
// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```

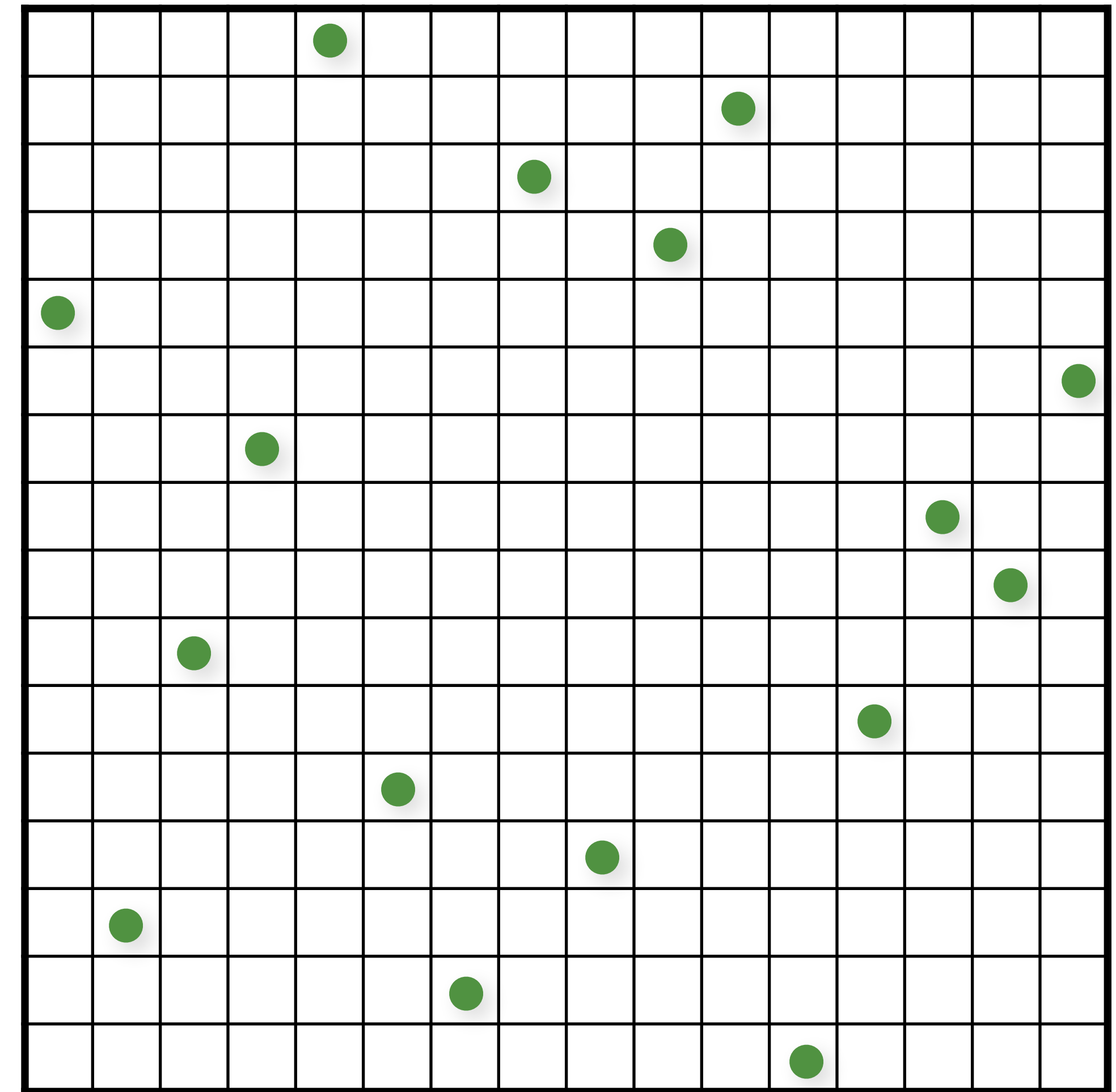


Shuffle rows

Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal  
for (uint d = 0; d < numDimensions; d++)  
    for (uint i = 0; i < numS; i++)  
        samples(d,i) = (i + randf())/numS;
```

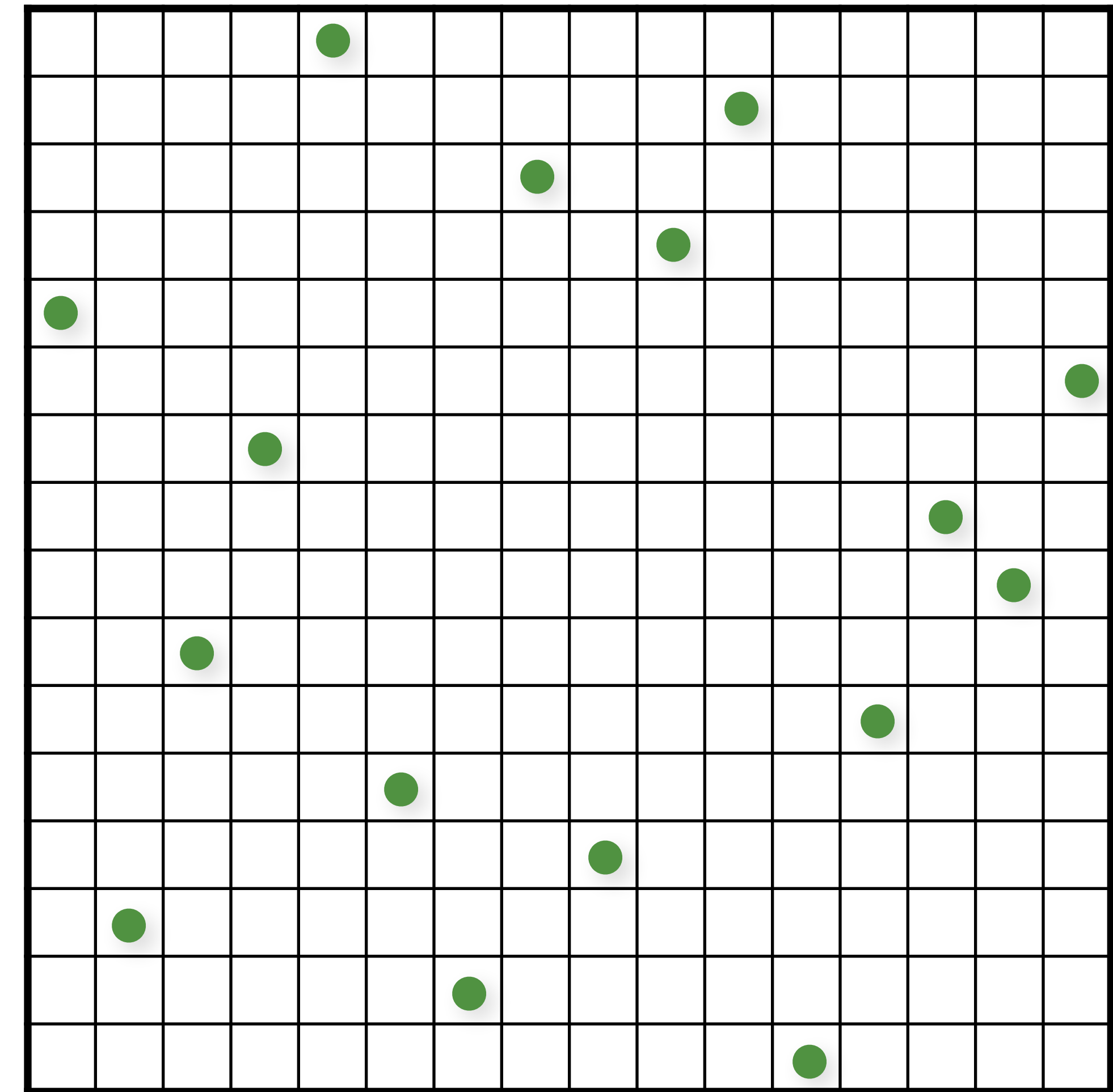
```
// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```



Latin Hypercube (N-Rooks) Sampling

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for (uint d = 0; d < numDimensions; d++)  
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```

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// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```

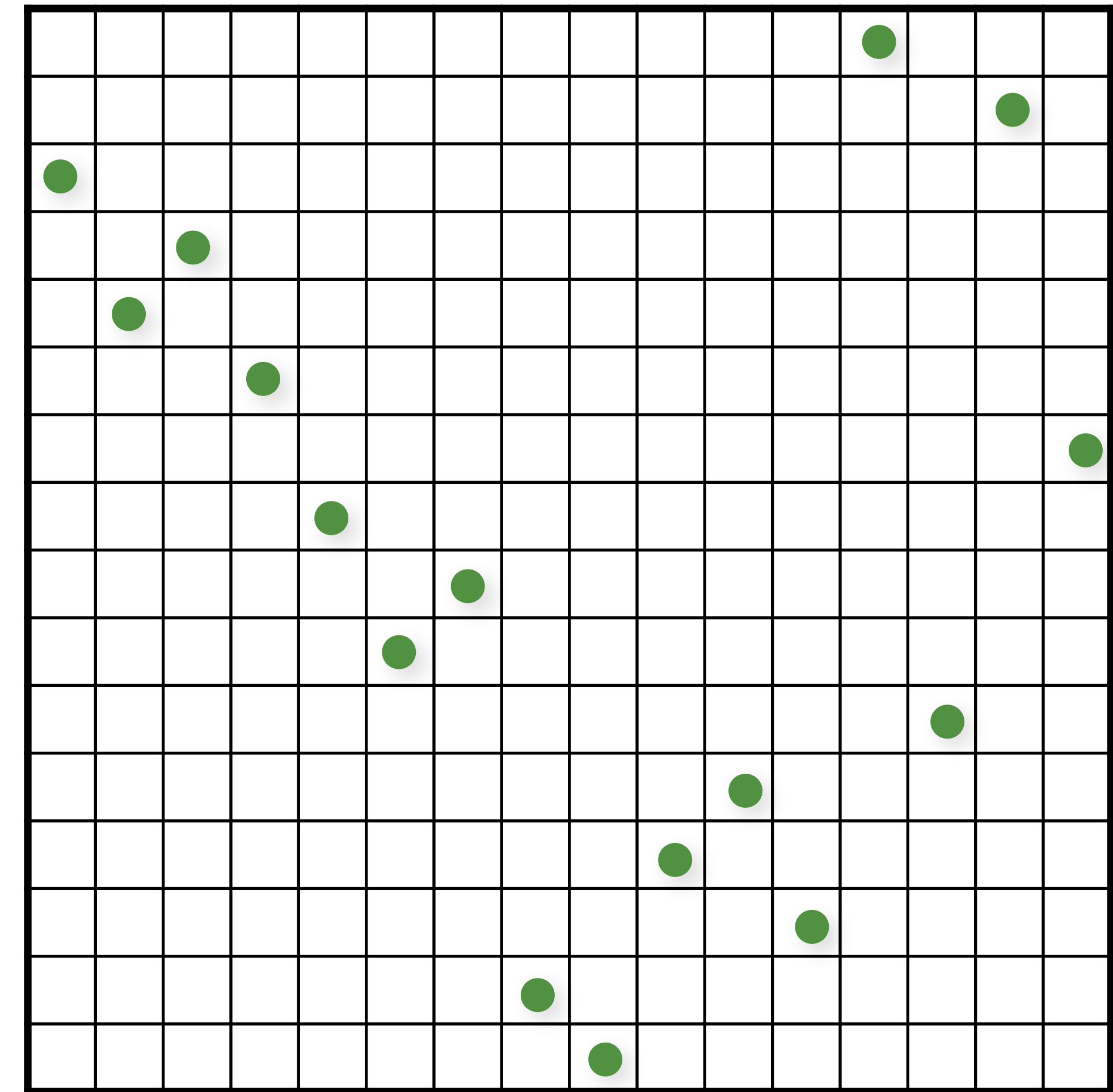


Shuffle columns

Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal  
for (uint d = 0; d < numDimensions; d++)  
    for (uint i = 0; i < numS; i++)  
        samples(d,i) = (i + randf())/numS;
```

```
// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```

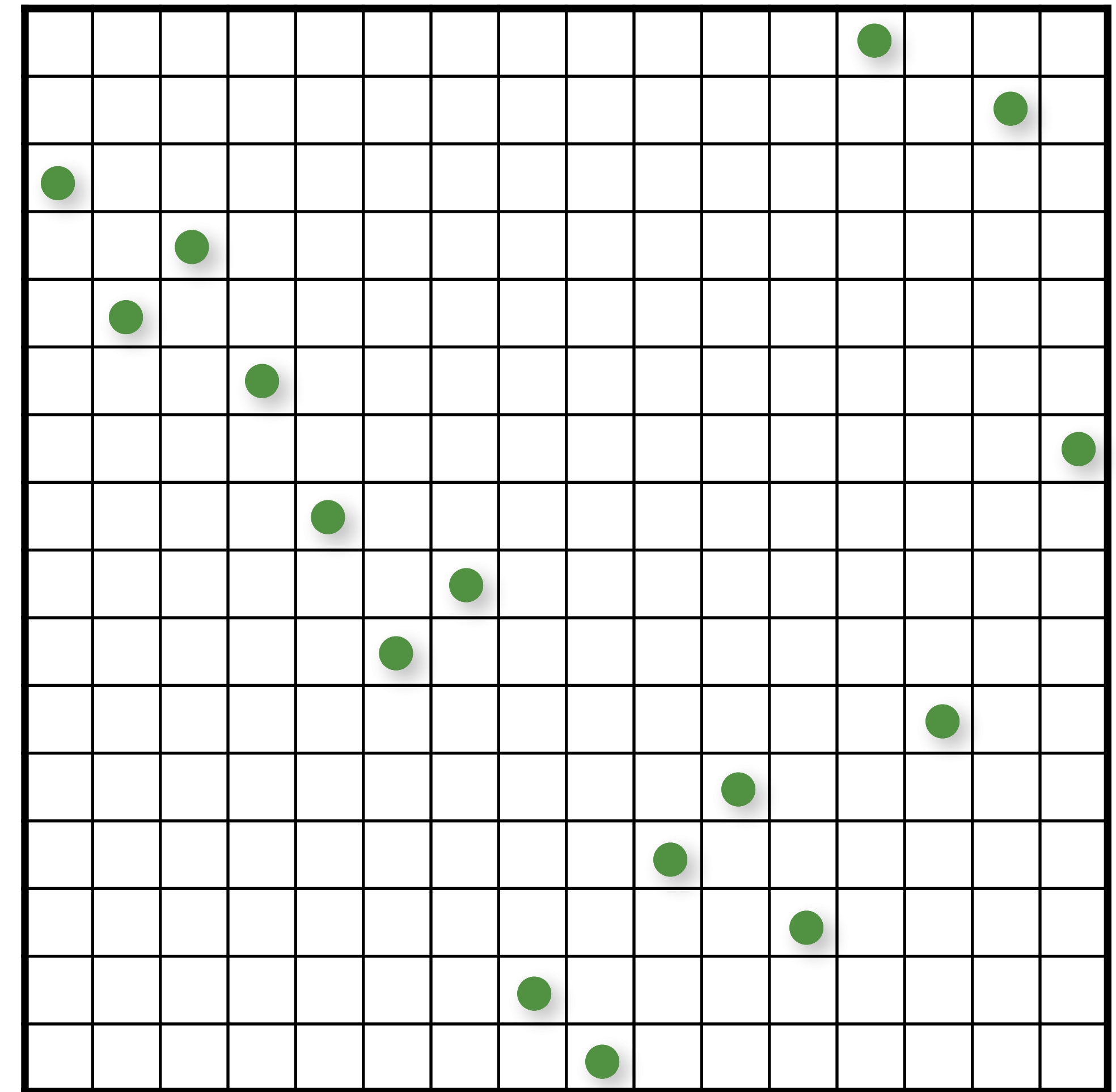


Shuffle columns

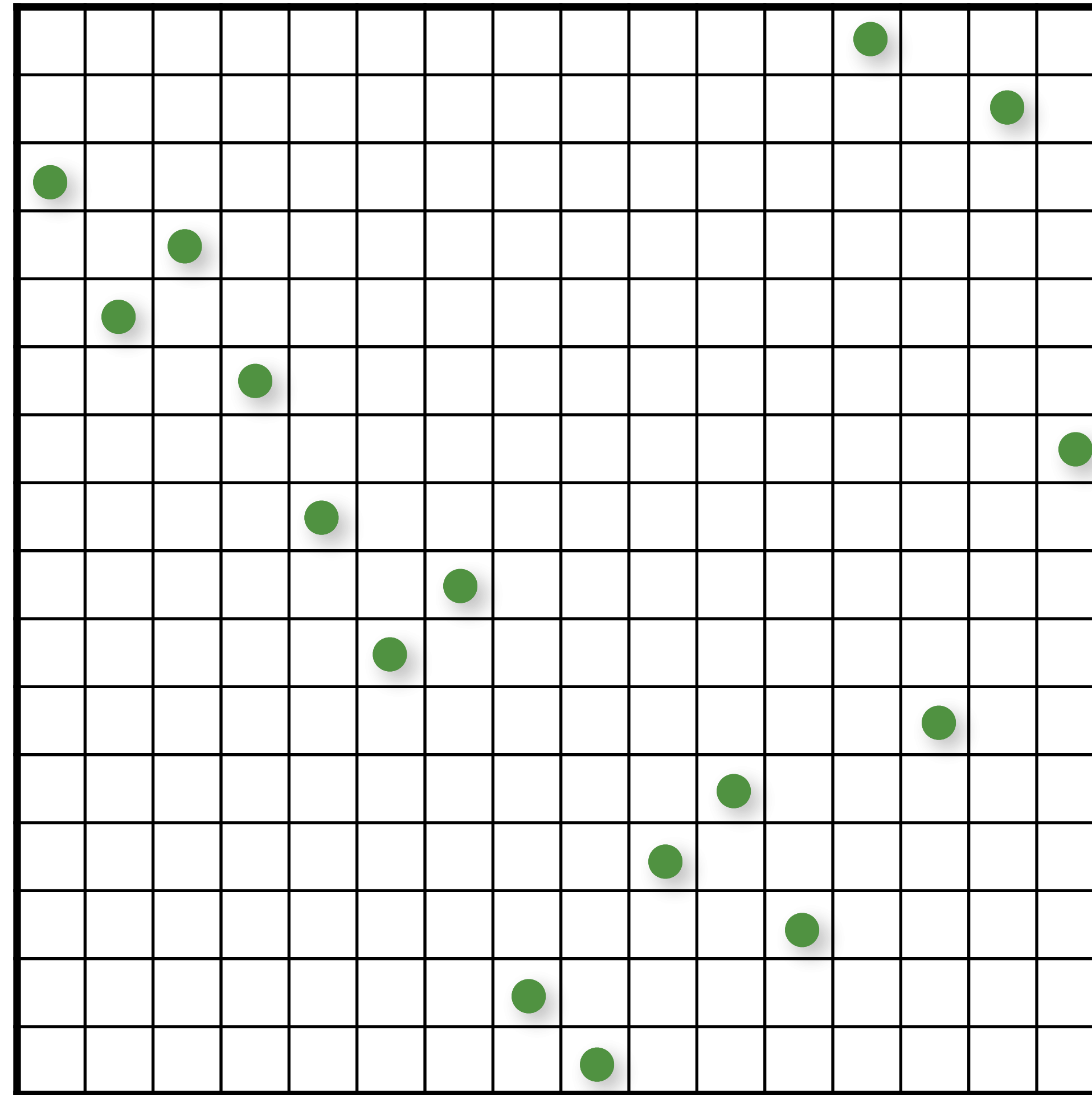
Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal  
for (uint d = 0; d < numDimensions; d++)  
    for (uint i = 0; i < numS; i++)  
        samples(d,i) = (i + randf())/numS;
```

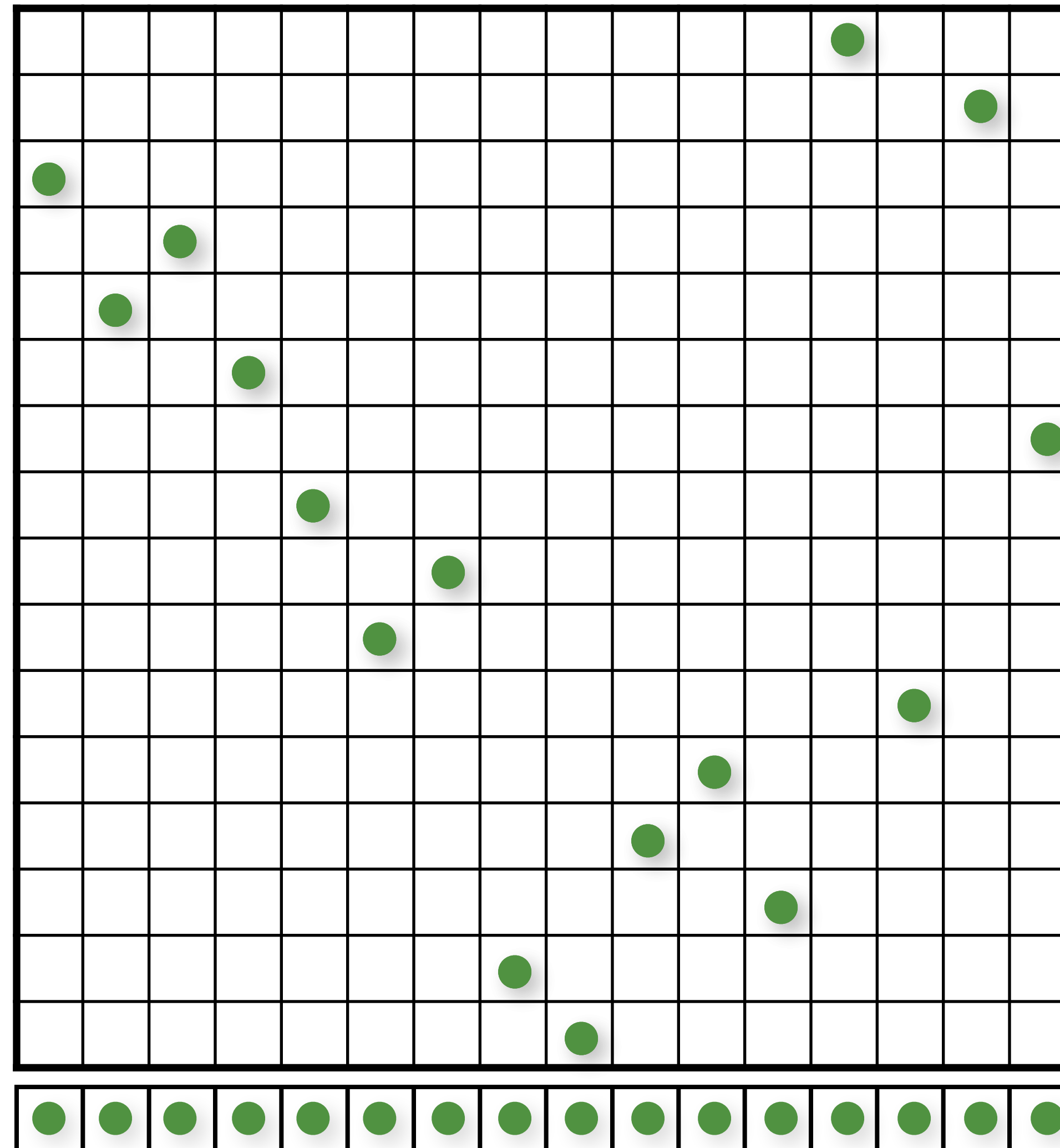
```
// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```



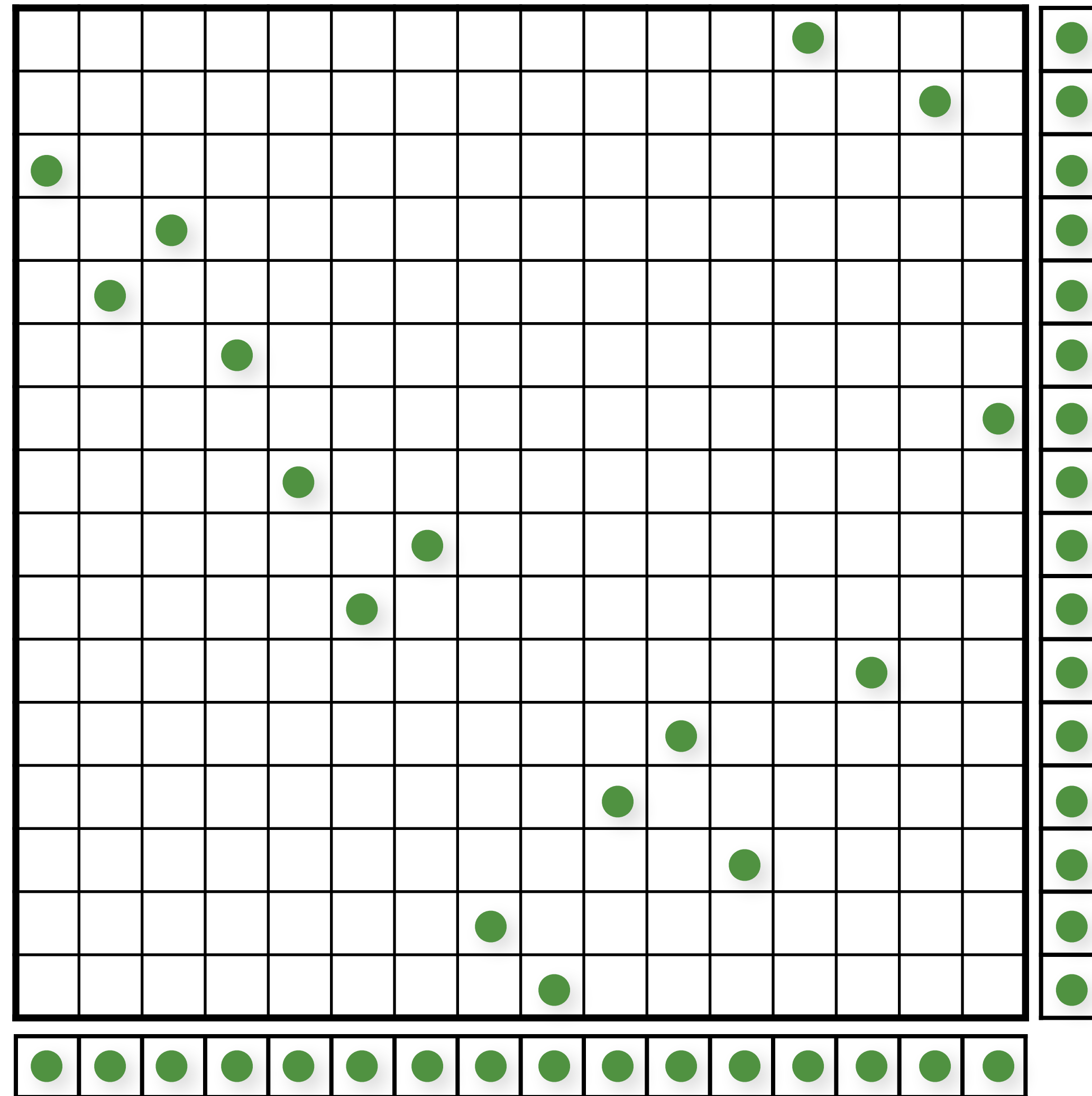
Latin Hypercube (N-Rooks) Sampling



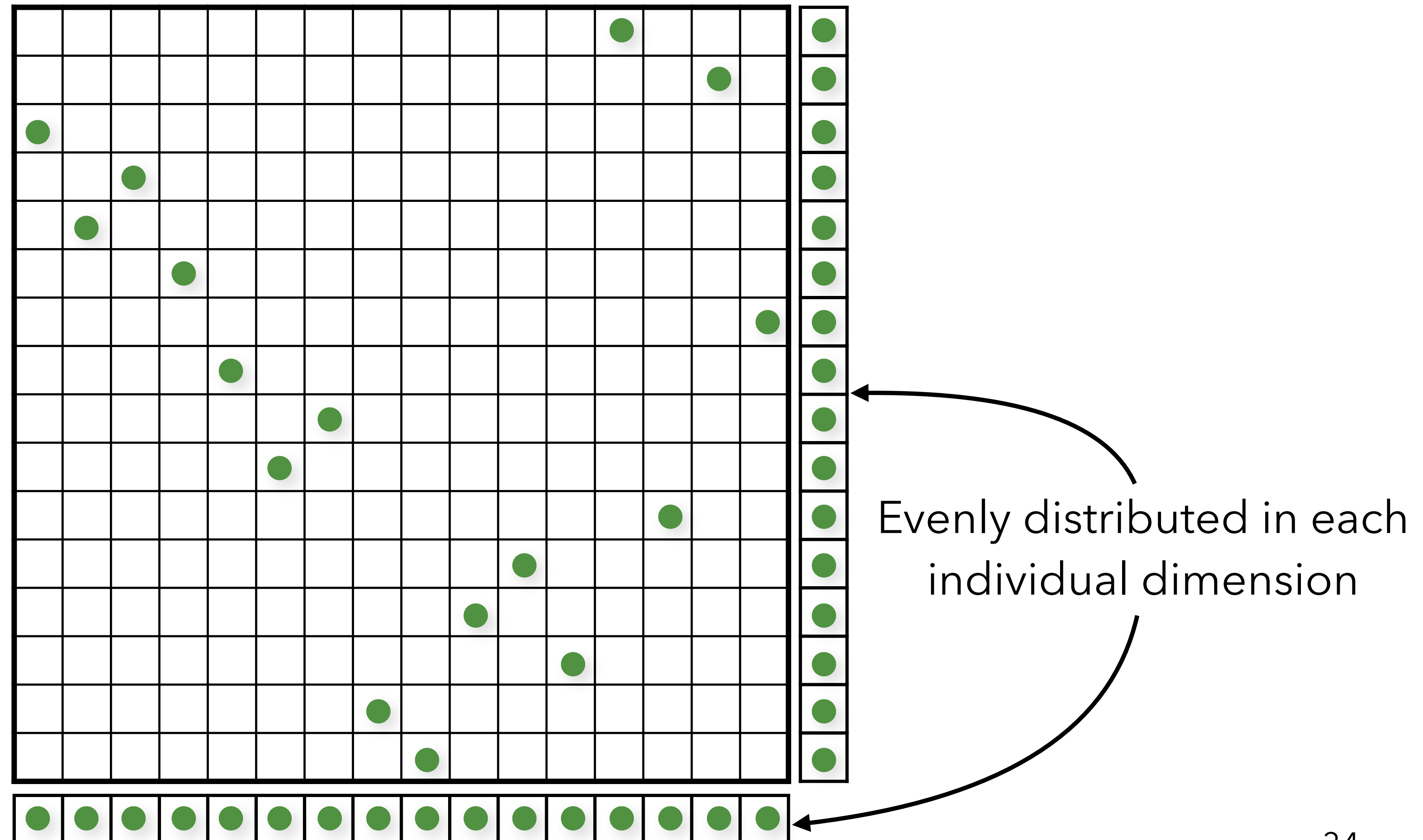
Latin Hypercube (N-Rooks) Sampling



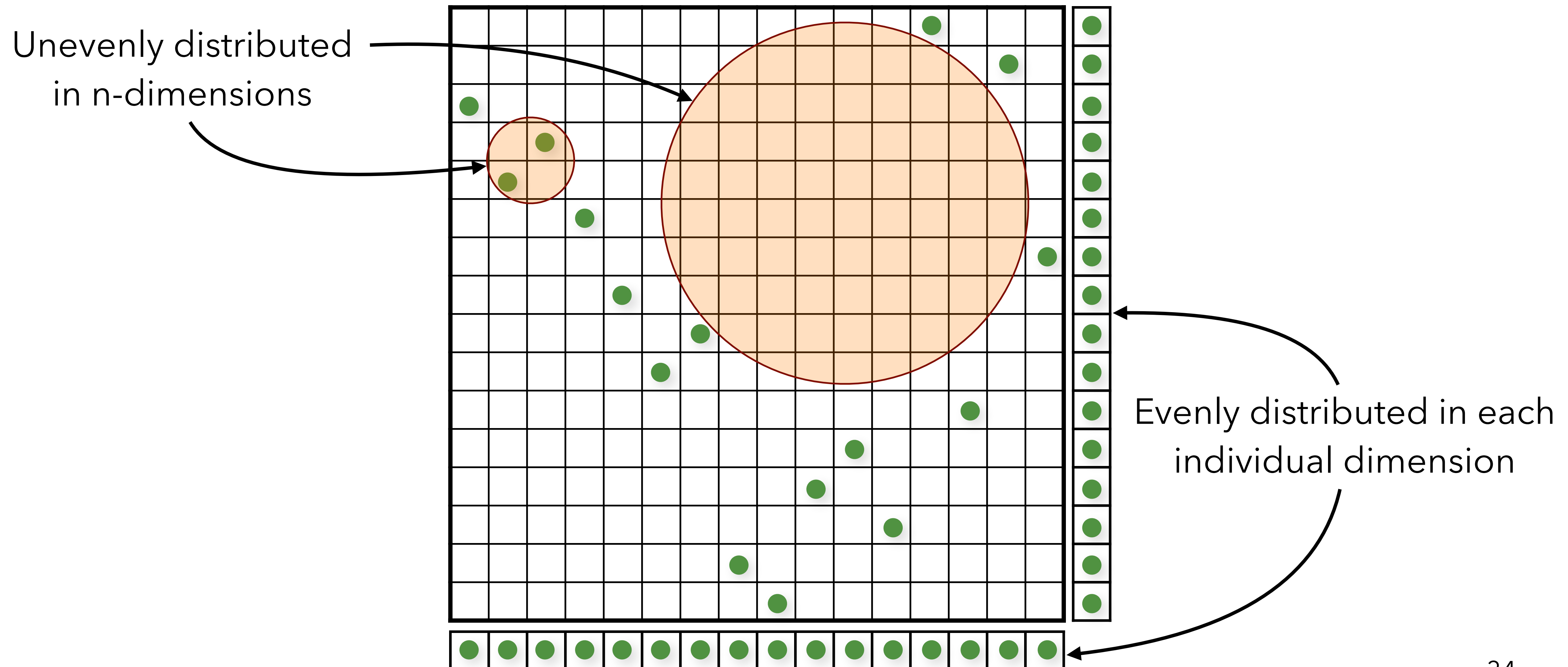
Latin Hypercube (N-Rooks) Sampling



Latin Hypercube (N-Rooks) Sampling

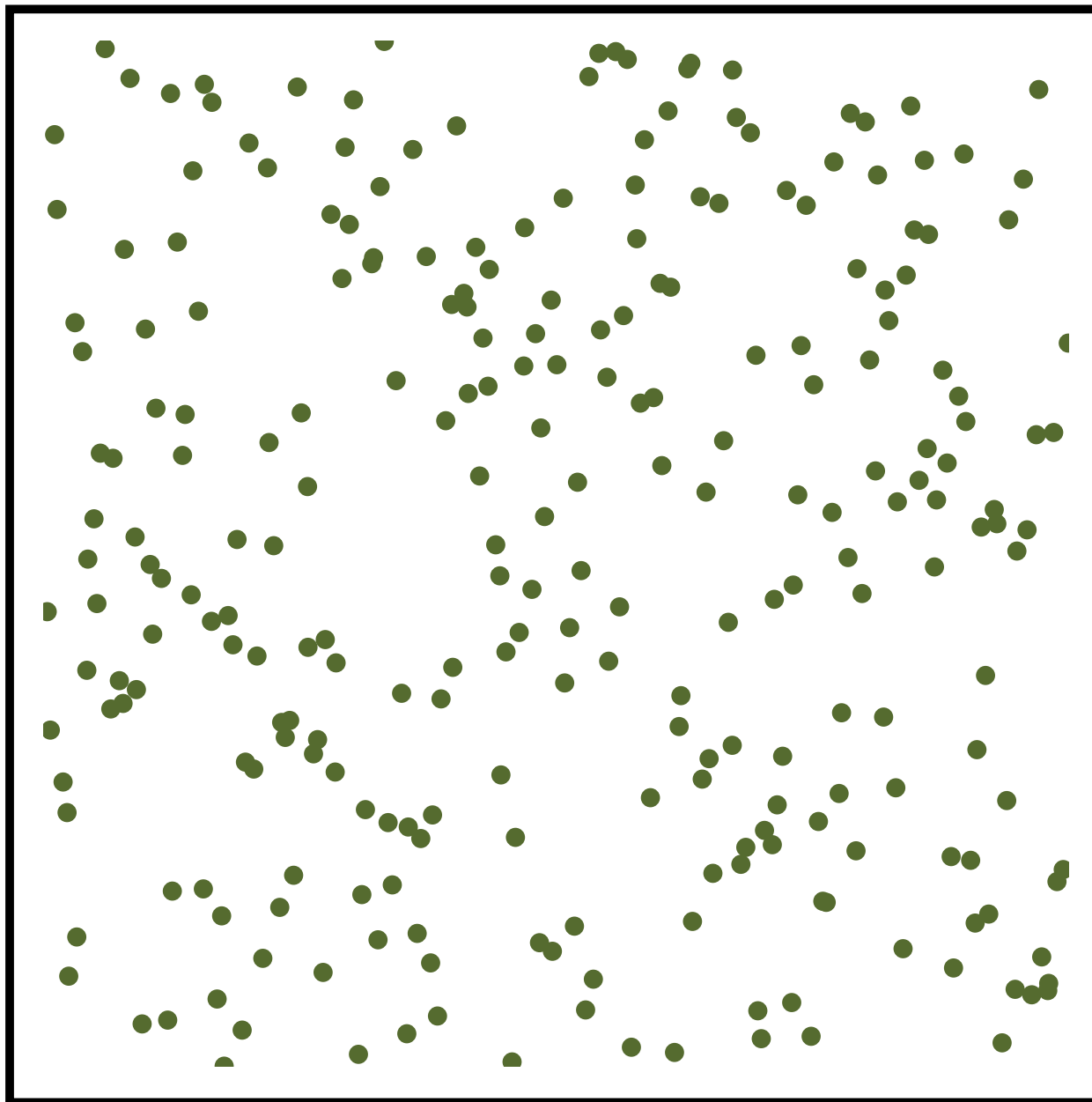


Latin Hypercube (N-Rooks) Sampling

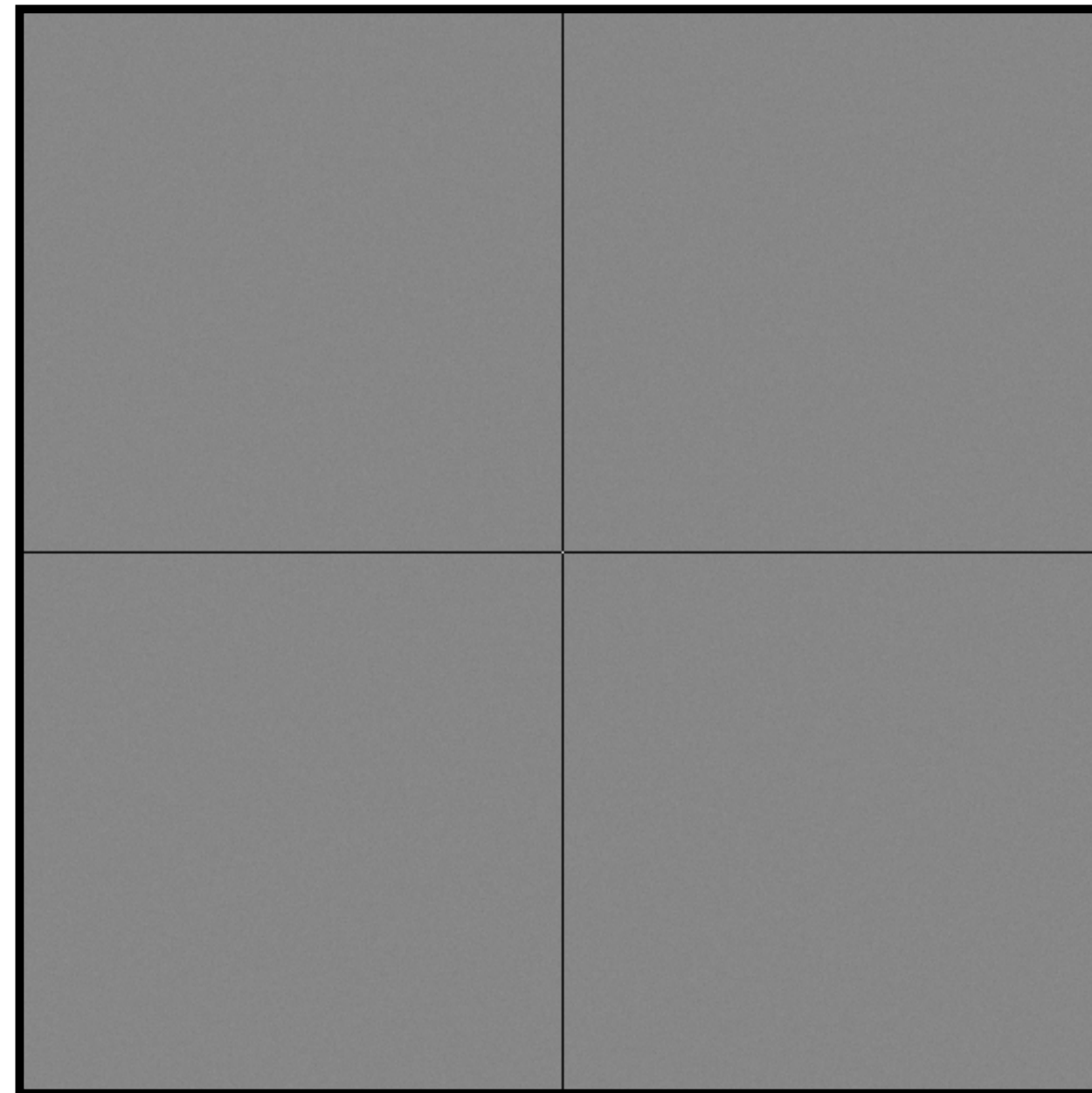


N-Rooks Sampling

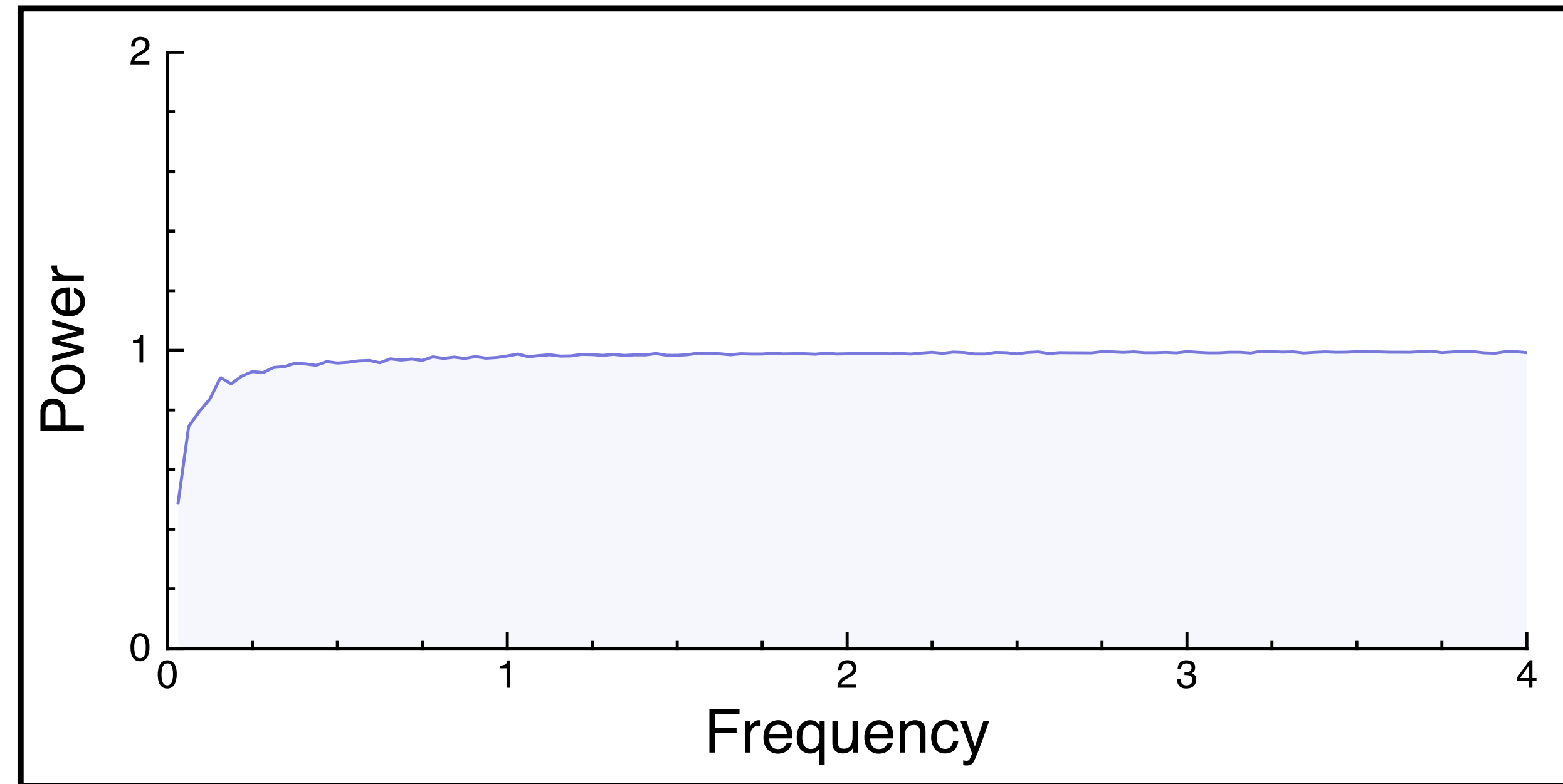
Samples



Expected power spectrum



Radial mean

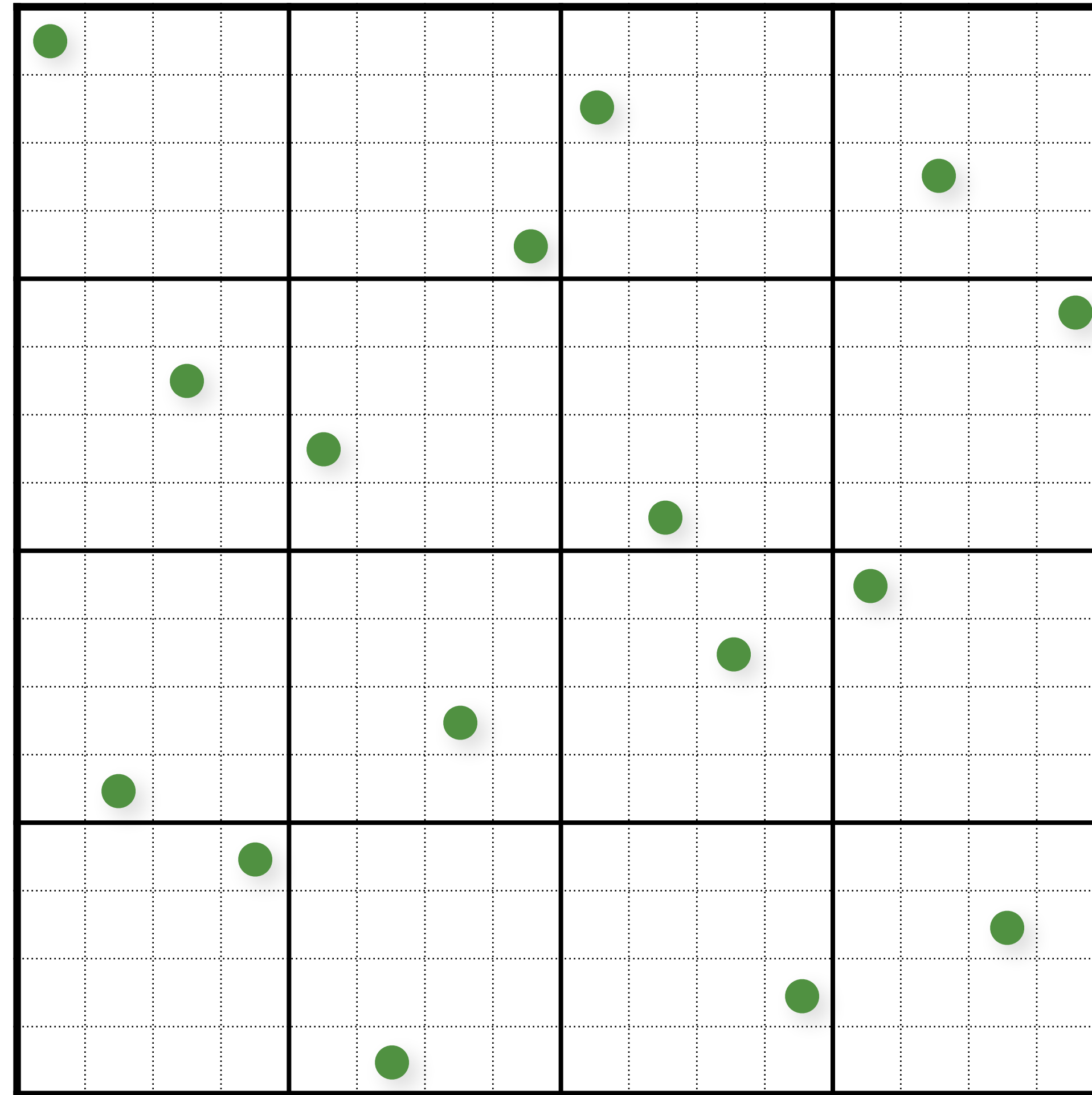


Multi-Jittered Sampling

Kenneth Chiu, Peter Shirley, and Changyaw Wang.
“Multi-jittered sampling.” In *Graphics Gems IV*, pp.
370–374. Academic Press, May 1994.

- combine N-Rooks and Jittered stratification constraints

Multi-Jittered Sampling



Multi-Jittered Sampling

// initialize

```
float cellSize = 1.0 / (resX*resY);  
for (uint i = 0; i < resX; i++)  
    for (uint j = 0; j < resY; j++)  
    {  
        samples(i,j).x = i/resX + (j+randf()) / (resX*resY);  
        samples(i,j).y = j/resY + (i+randf()) / (resX*resY);  
    }
```

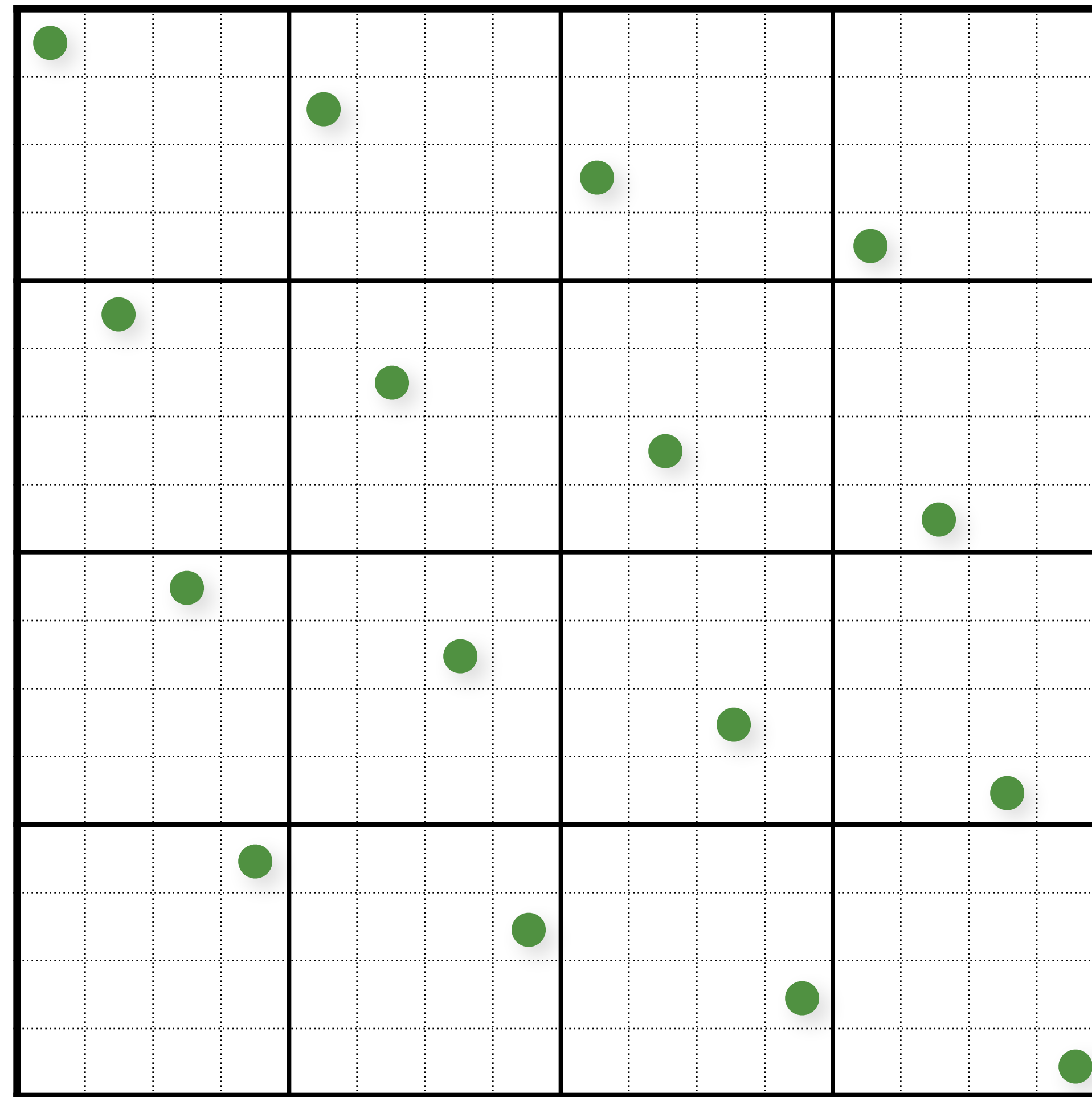
// shuffle x coordinates within each column of cells

```
for (uint i = 0; i < resX; i++)  
    for (uint j = resY-1; j >= 1; j--)  
        swap(samples(i, j).x, samples(i, randi(0, j)).x);
```

// shuffle y coordinates within each row of cells

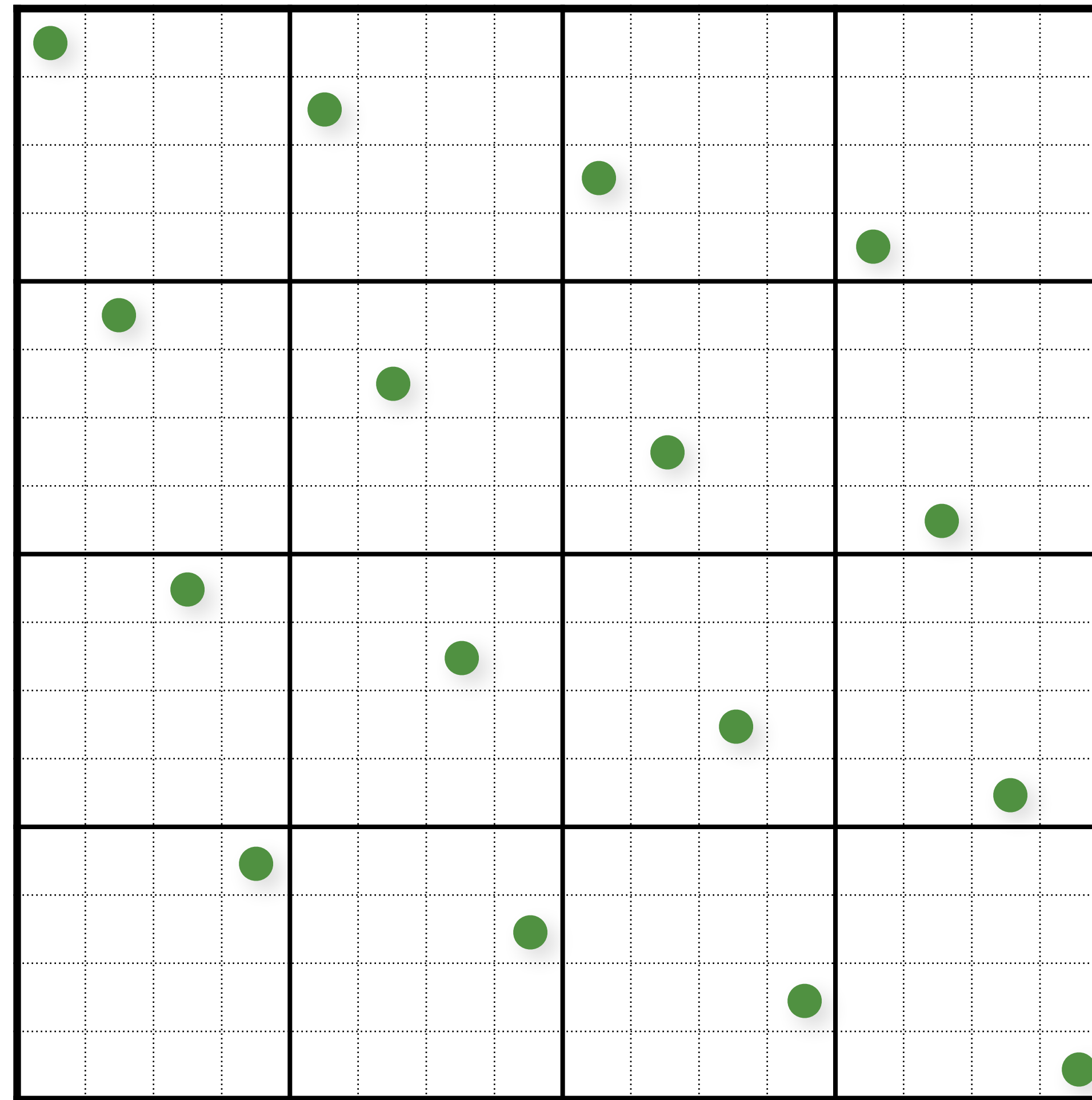
```
for (unsigned j = 0; j < resY; j++)  
    for (unsigned i = resX-1; i >= 1; i--)  
        swap(samples(i, j).y, samples(randi(0, i), j).y);
```

Multi-Jittered Sampling



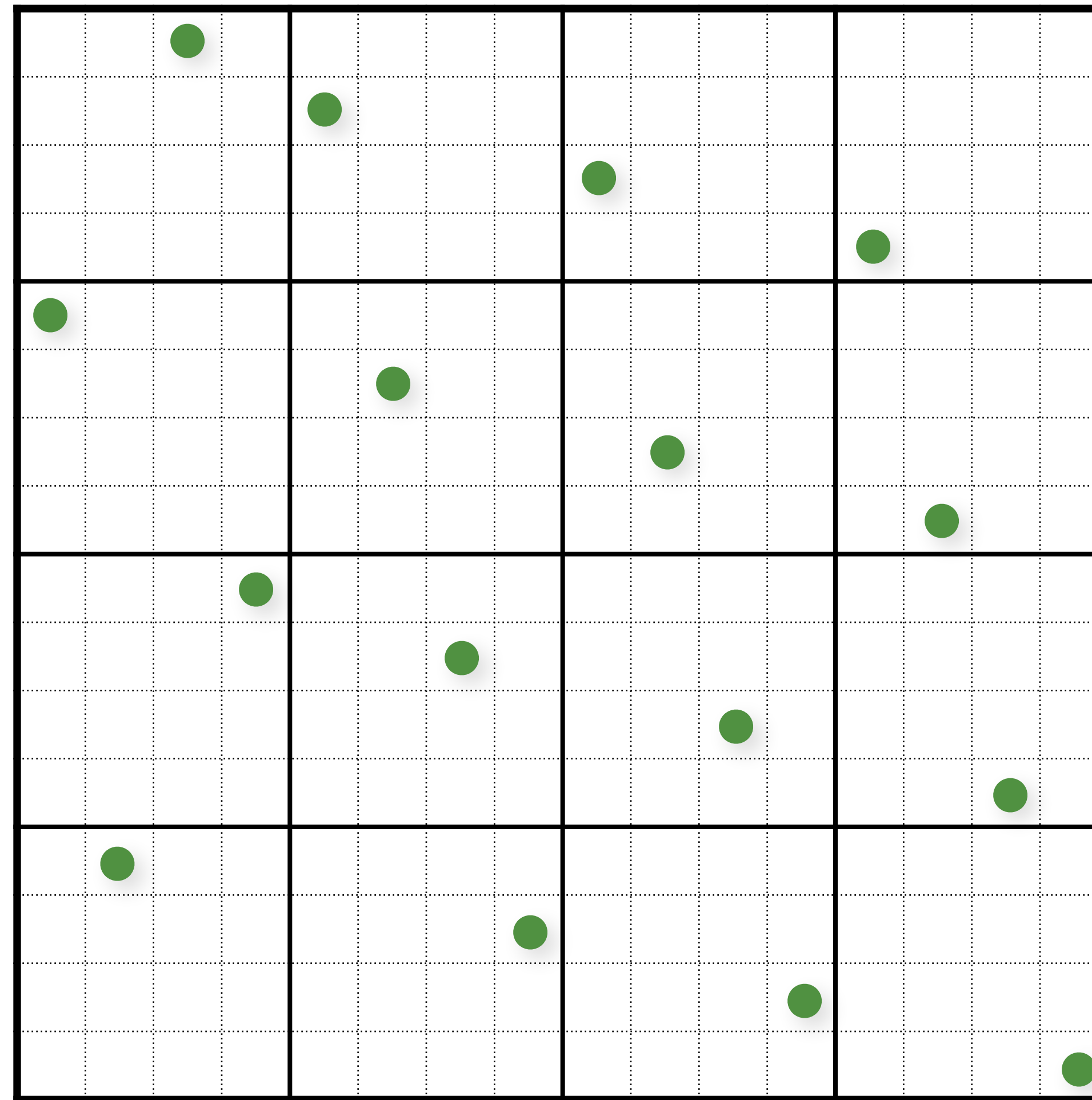
Initialize

Multi-Jittered Sampling



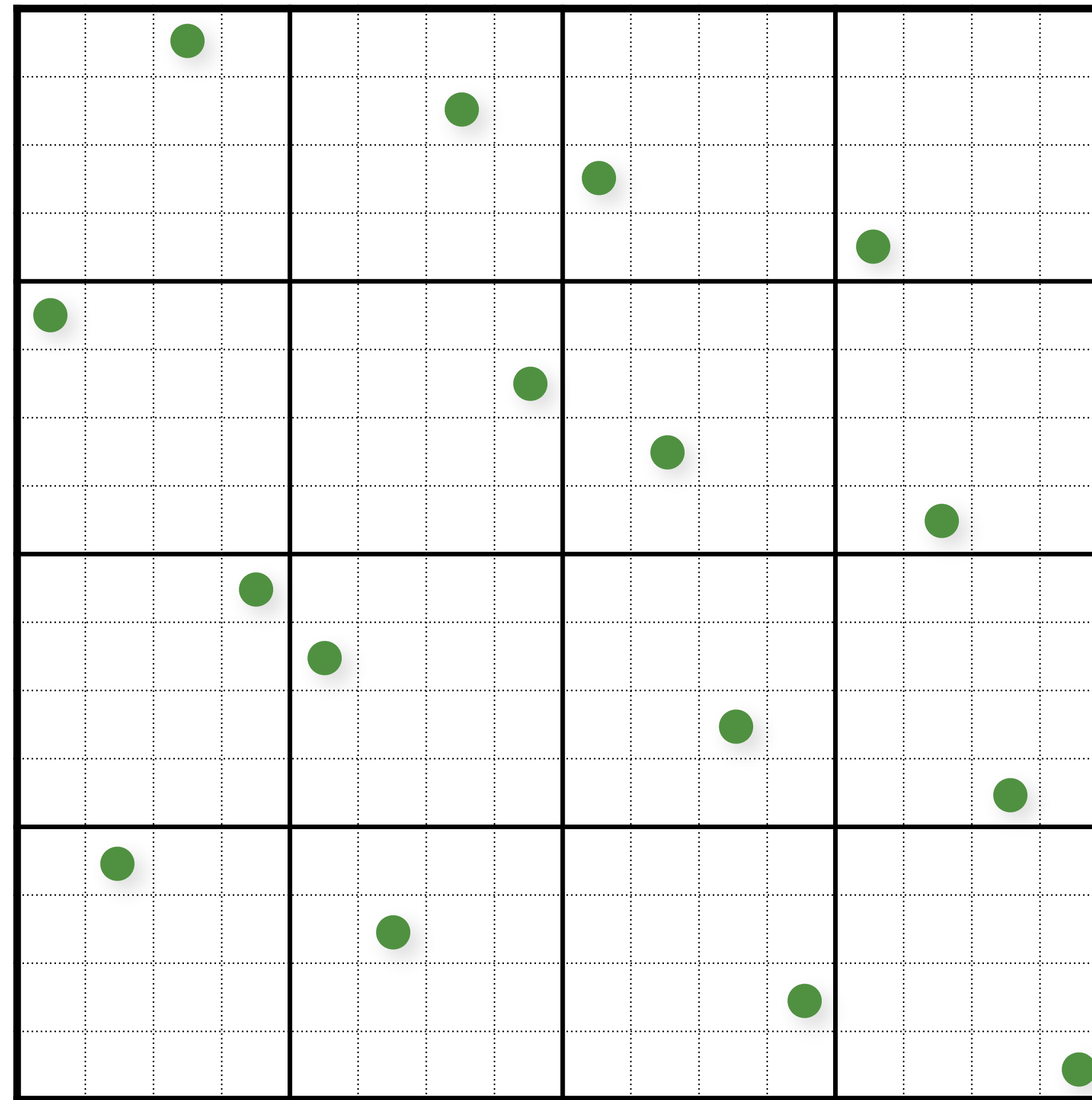
Shuffle x-coords

Multi-Jittered Sampling



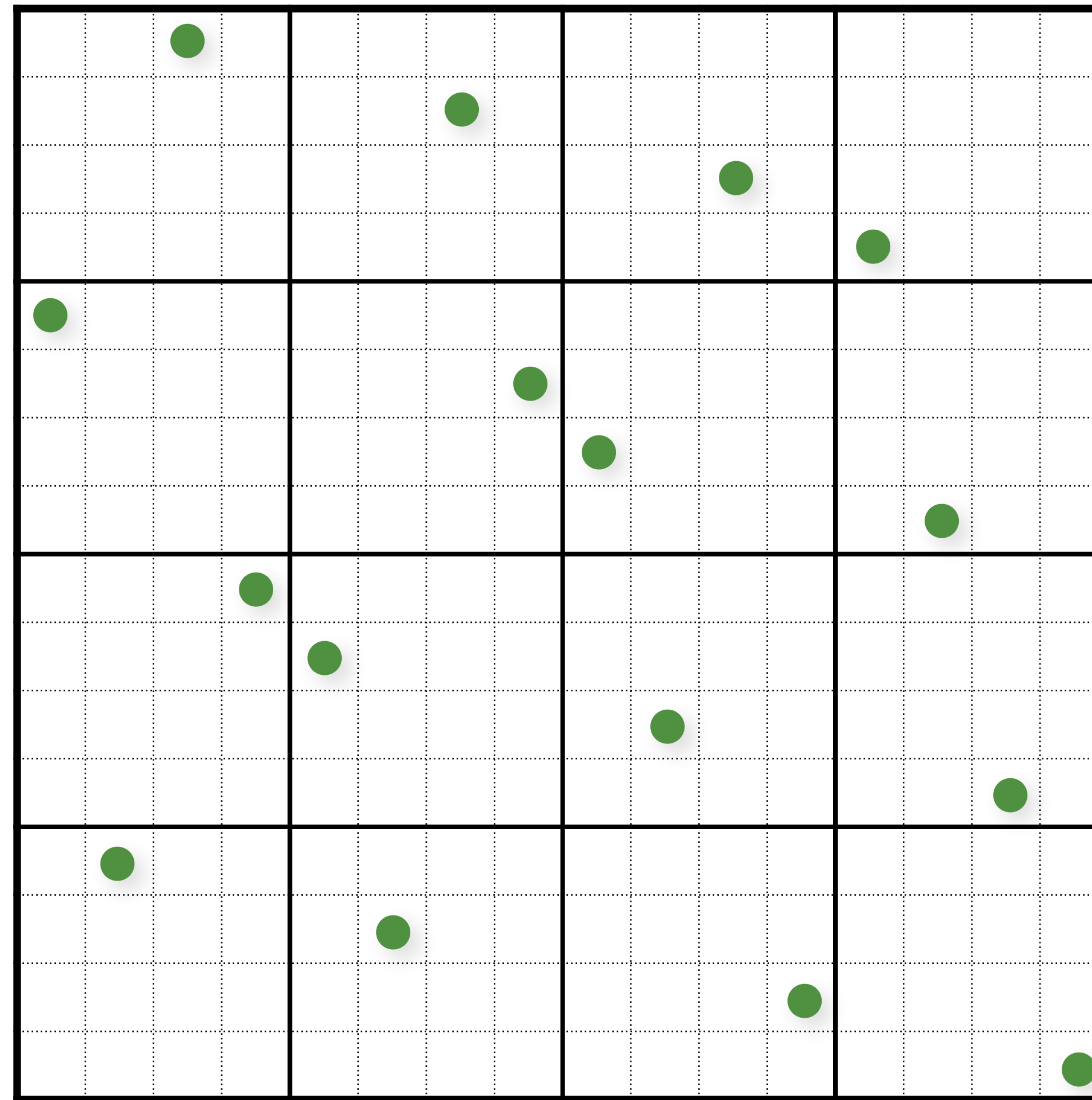
Shuffle x-coords

Multi-Jittered Sampling



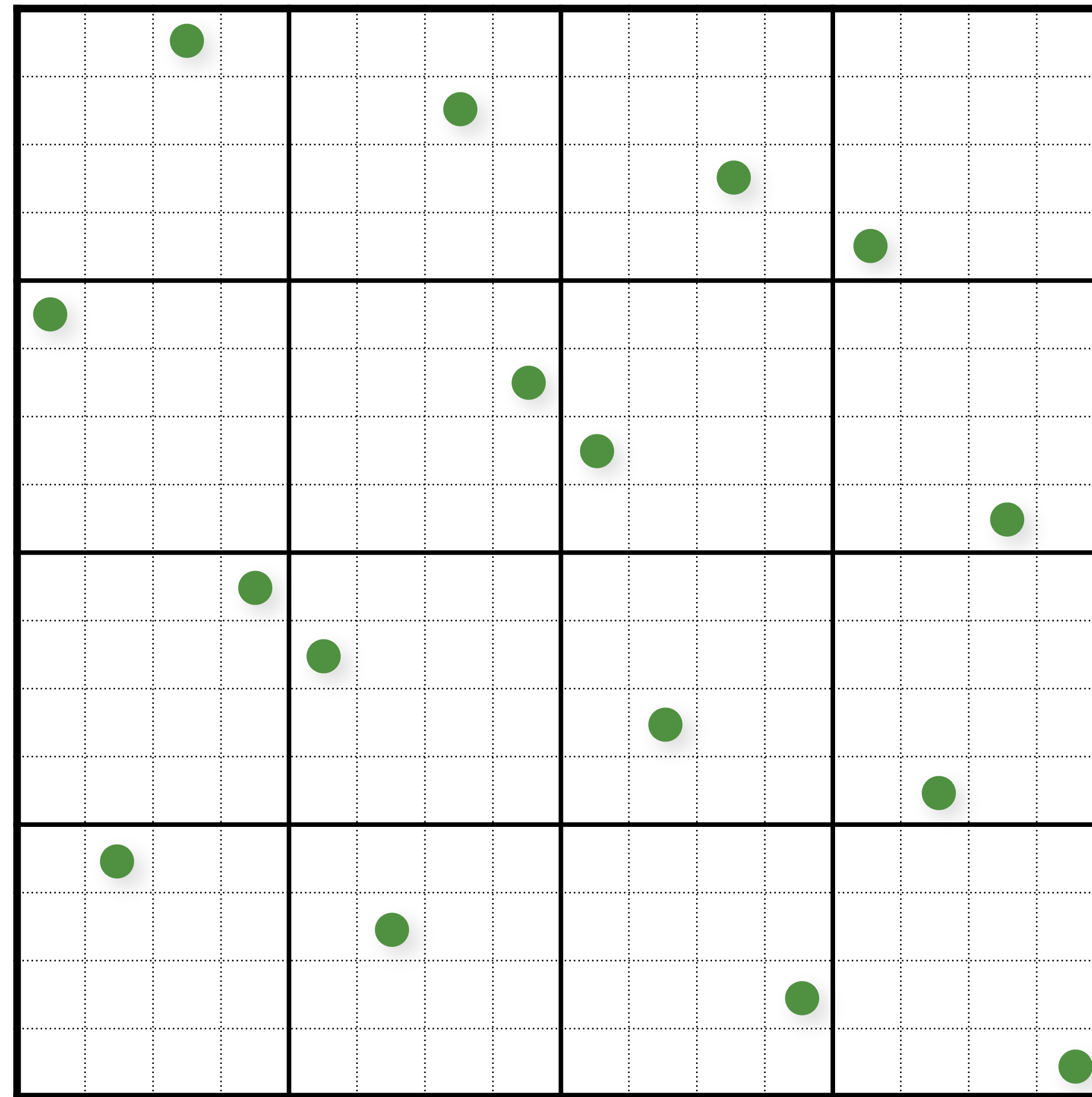
Shuffle x-coords

Multi-Jittered Sampling



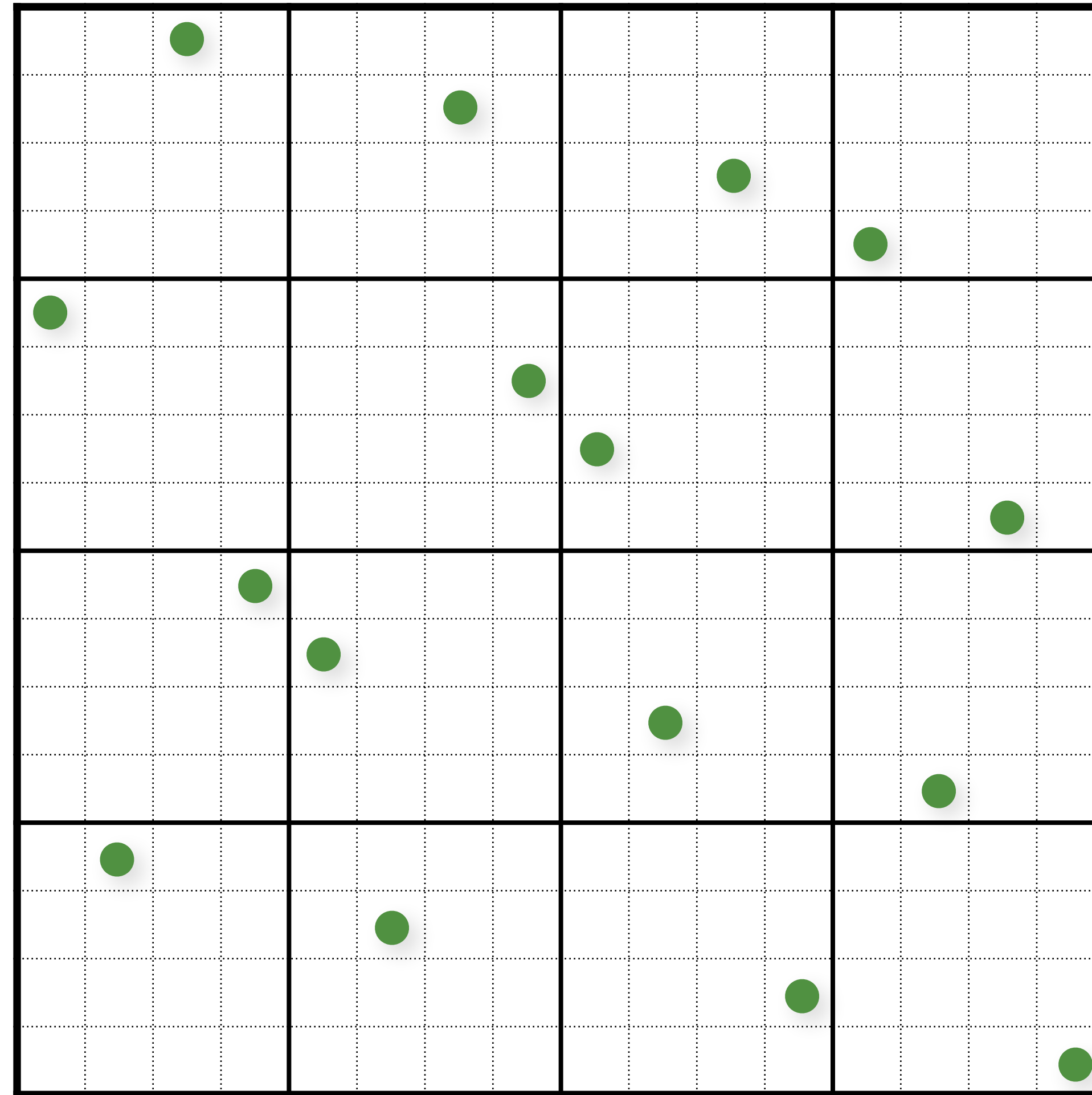
Shuffle x-coords

Multi-Jittered Sampling

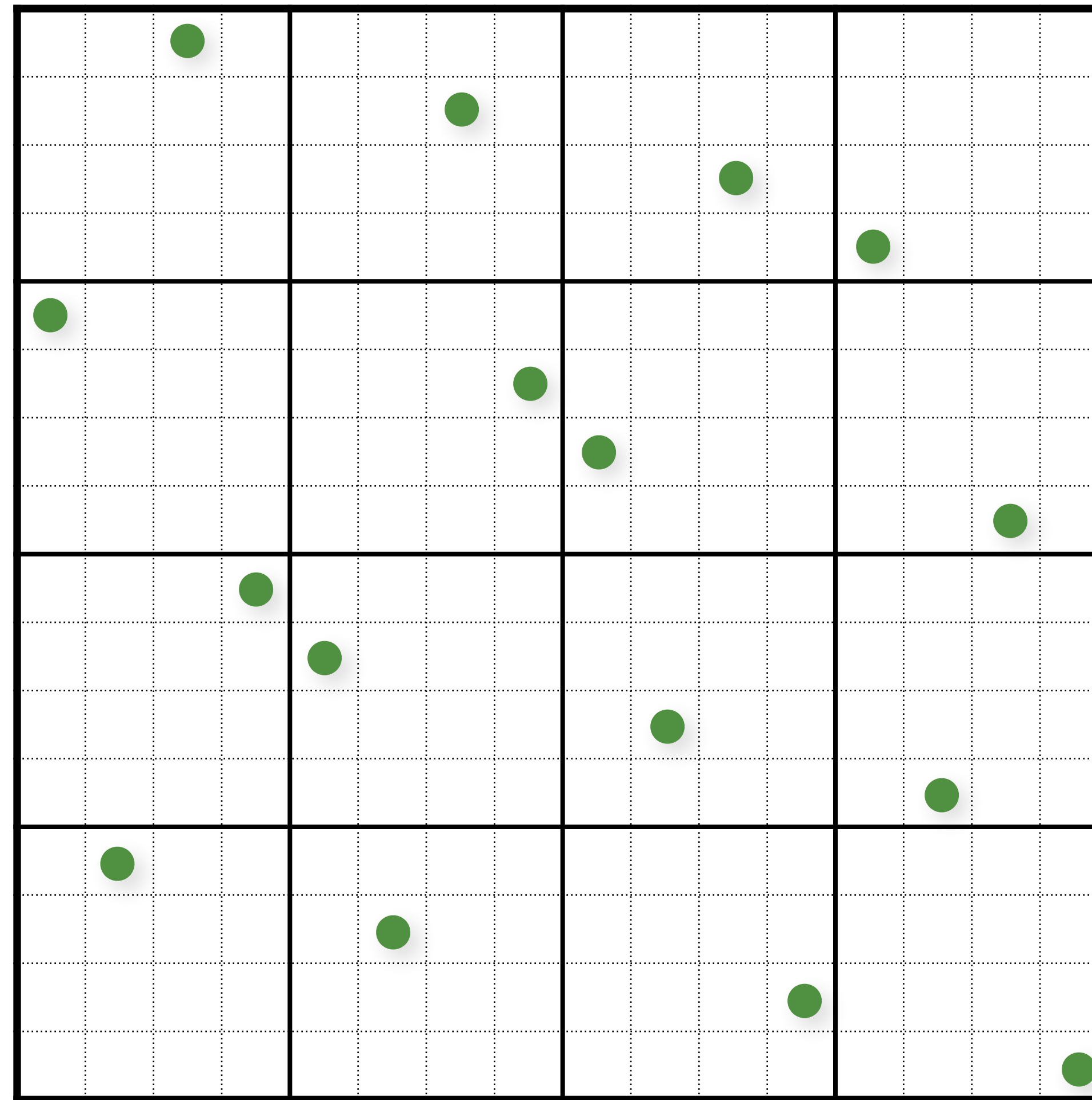


Shuffle x-coords

Multi-Jittered Sampling

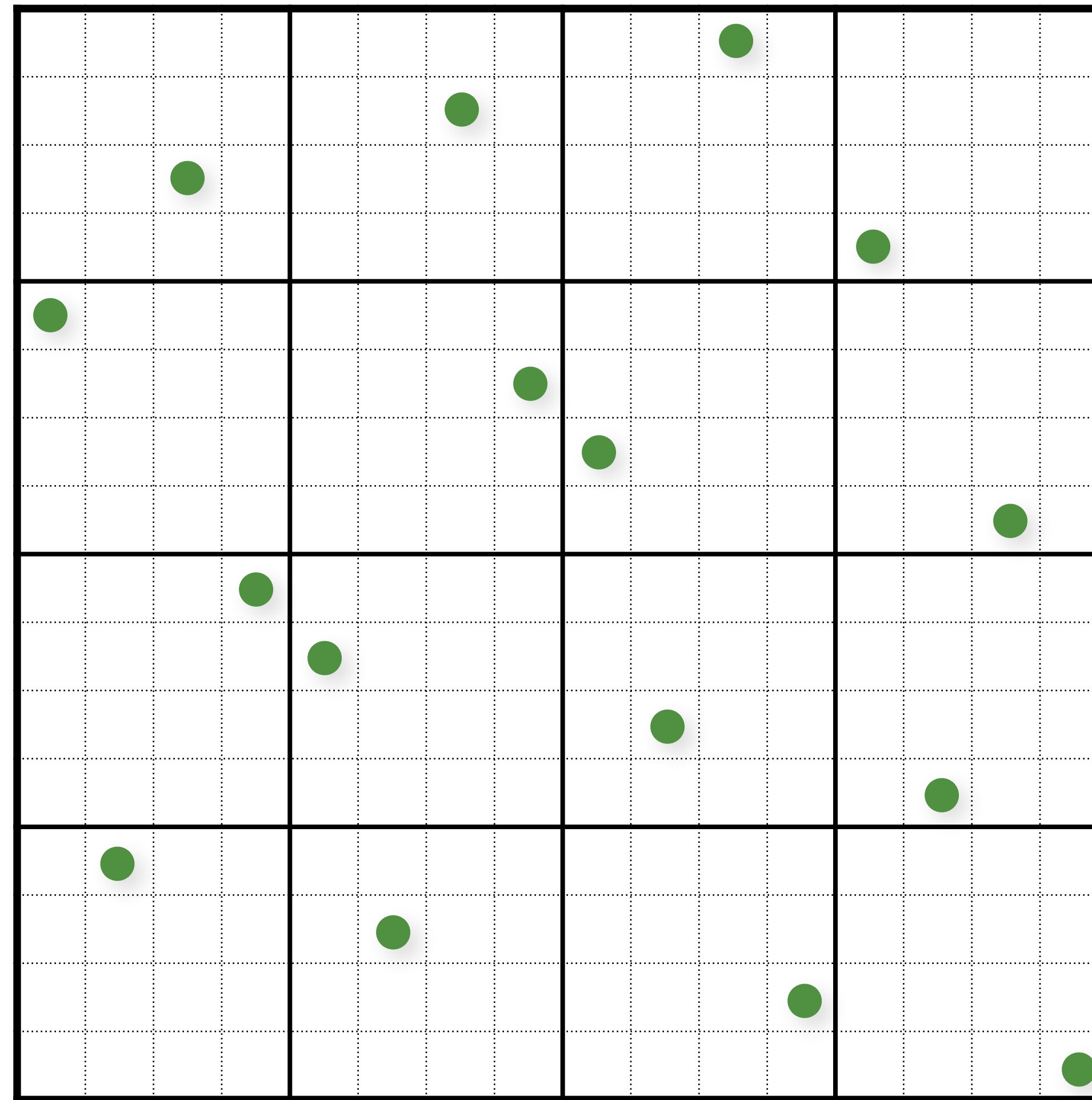


Multi-Jittered Sampling



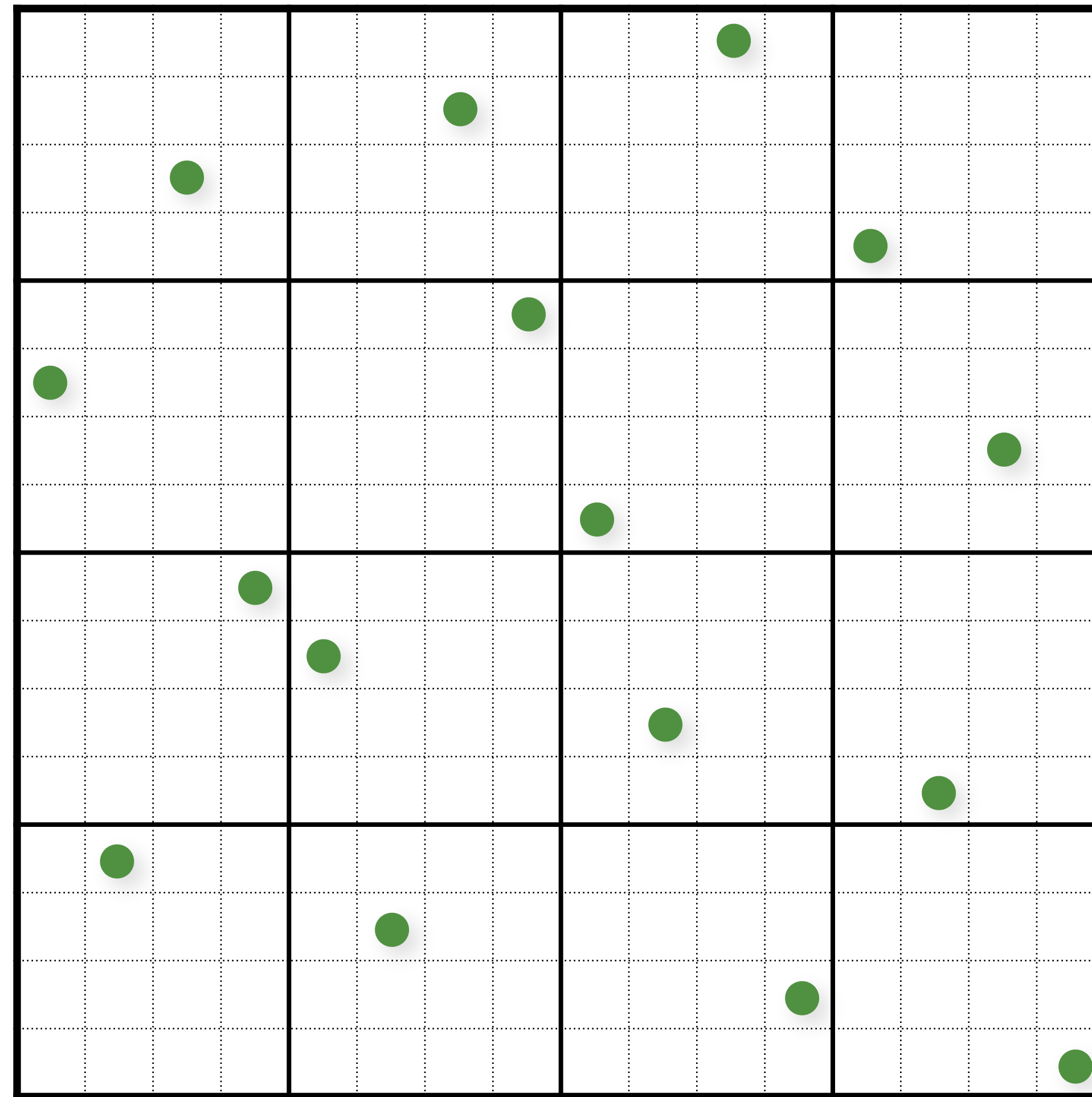
Shuffle y-coords

Multi-Jittered Sampling



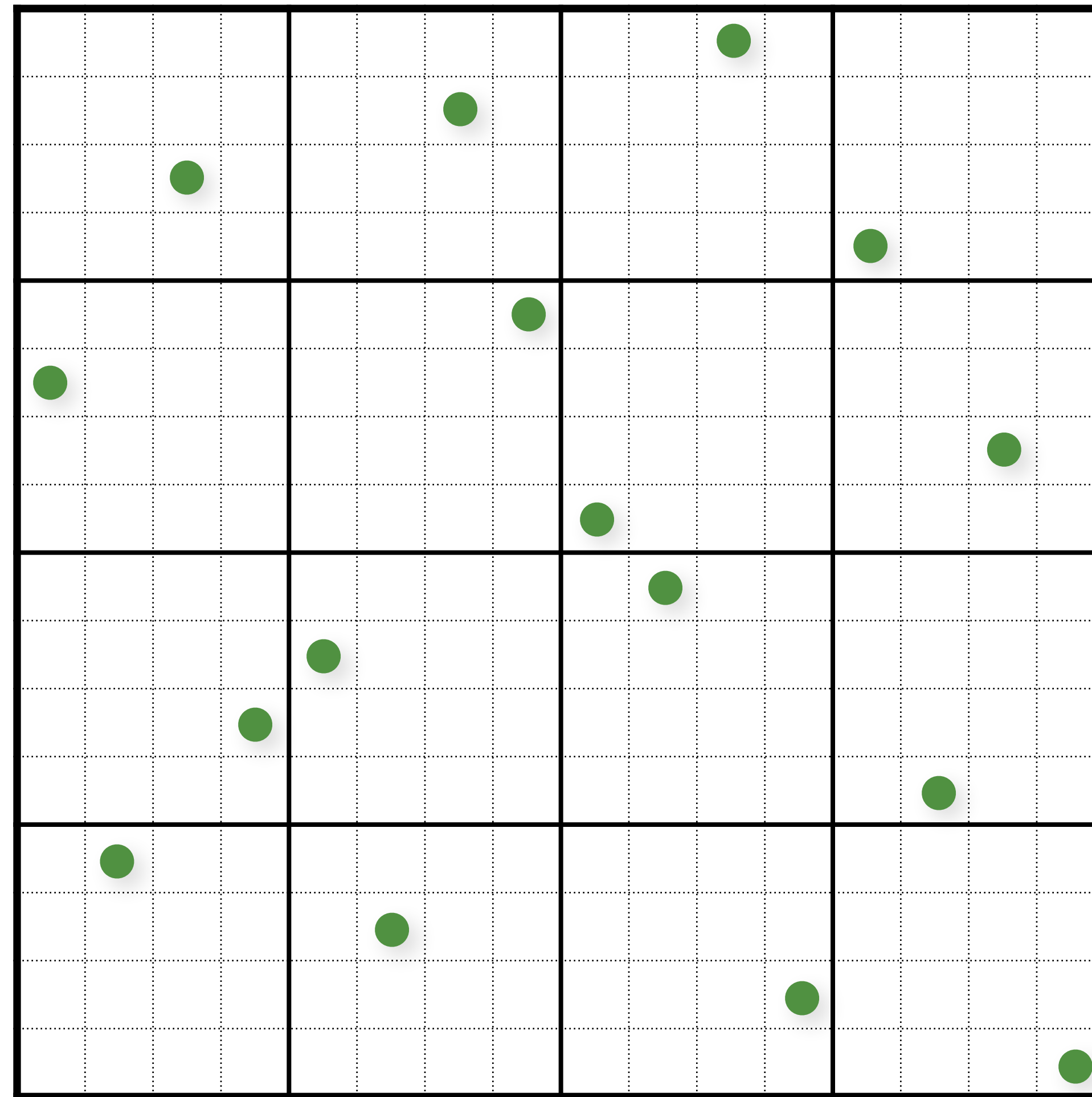
Shuffle y-coords

Multi-Jittered Sampling



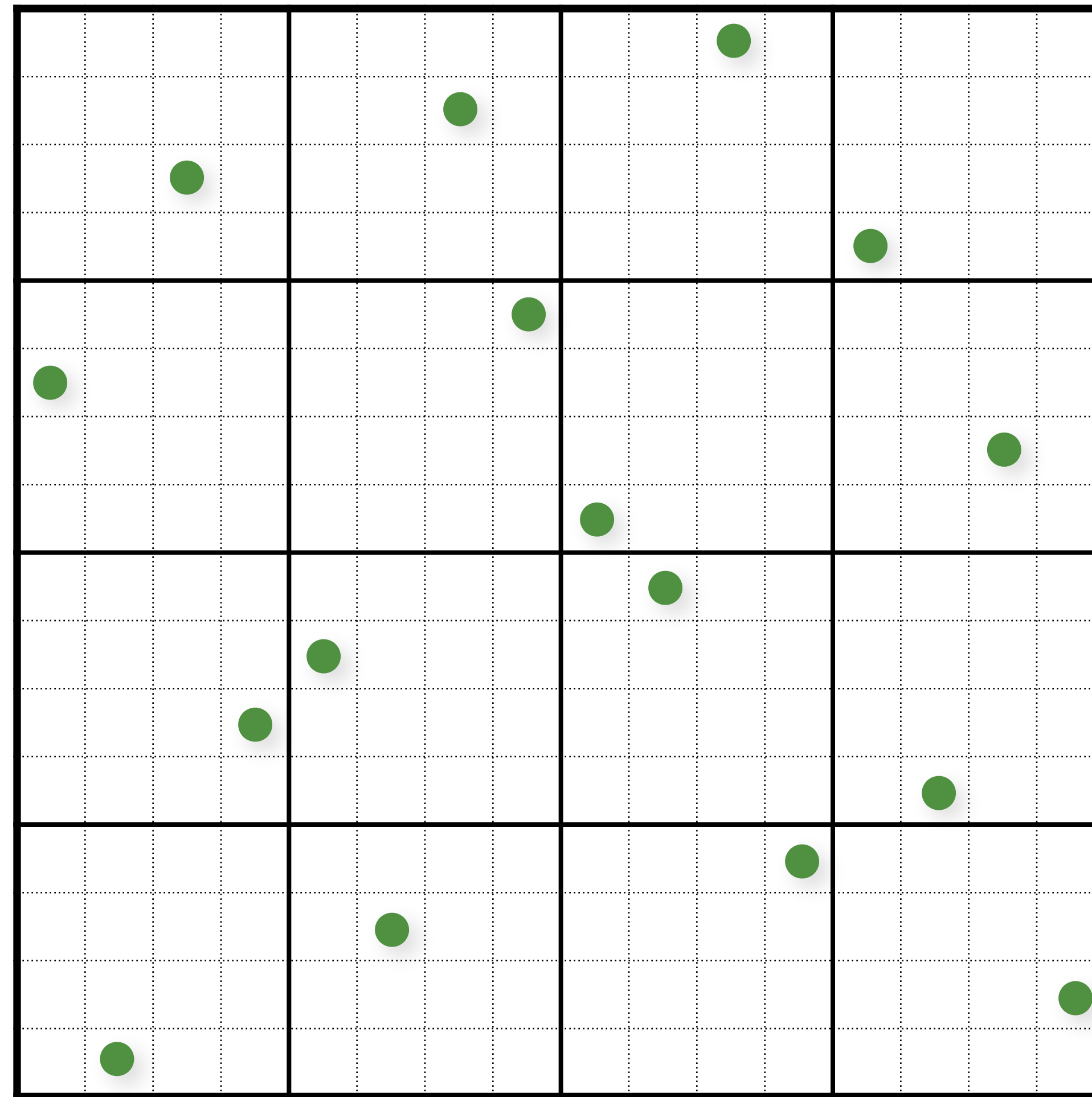
Shuffle y-coords

Multi-Jittered Sampling



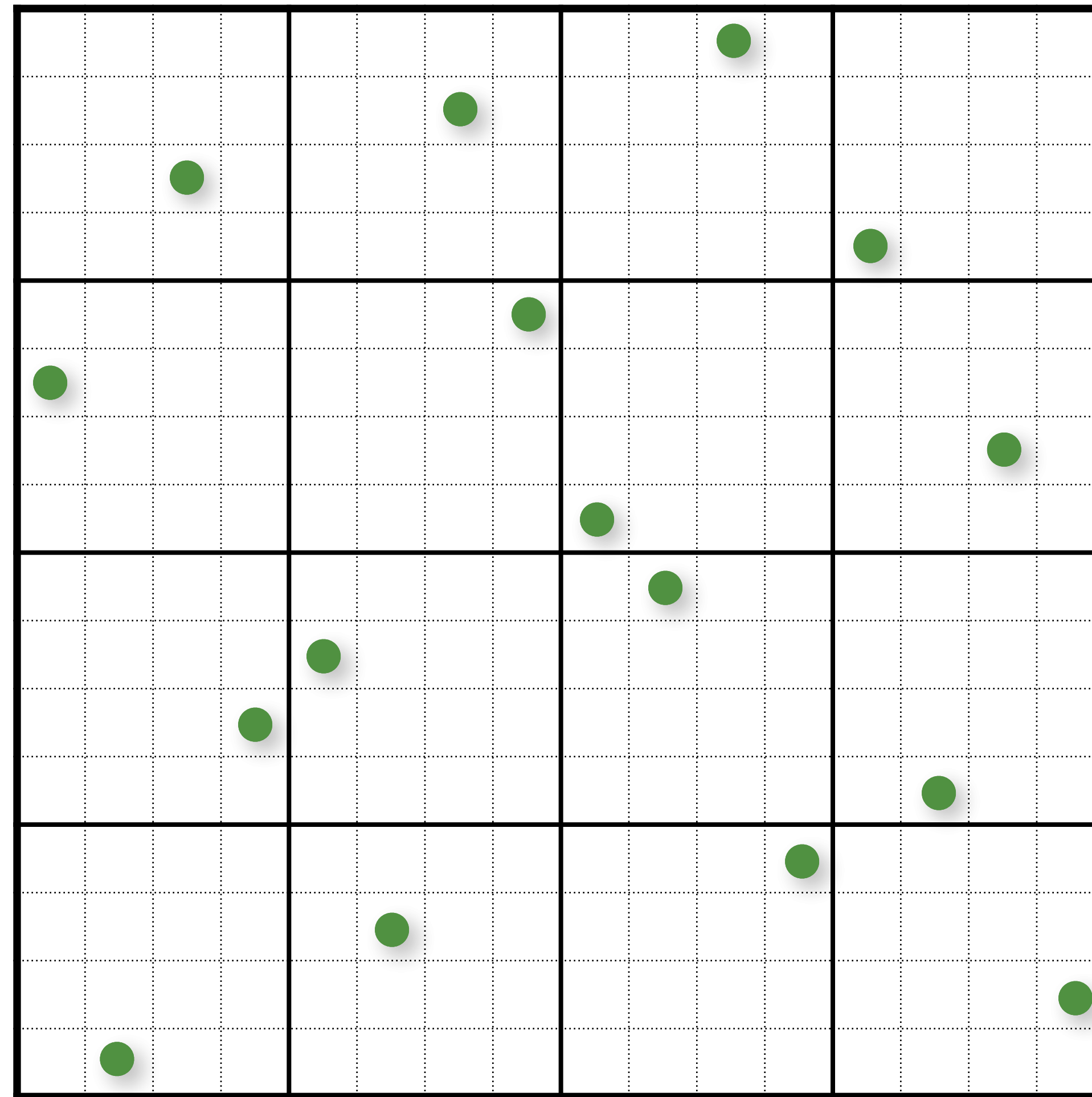
Shuffle y-coords

Multi-Jittered Sampling

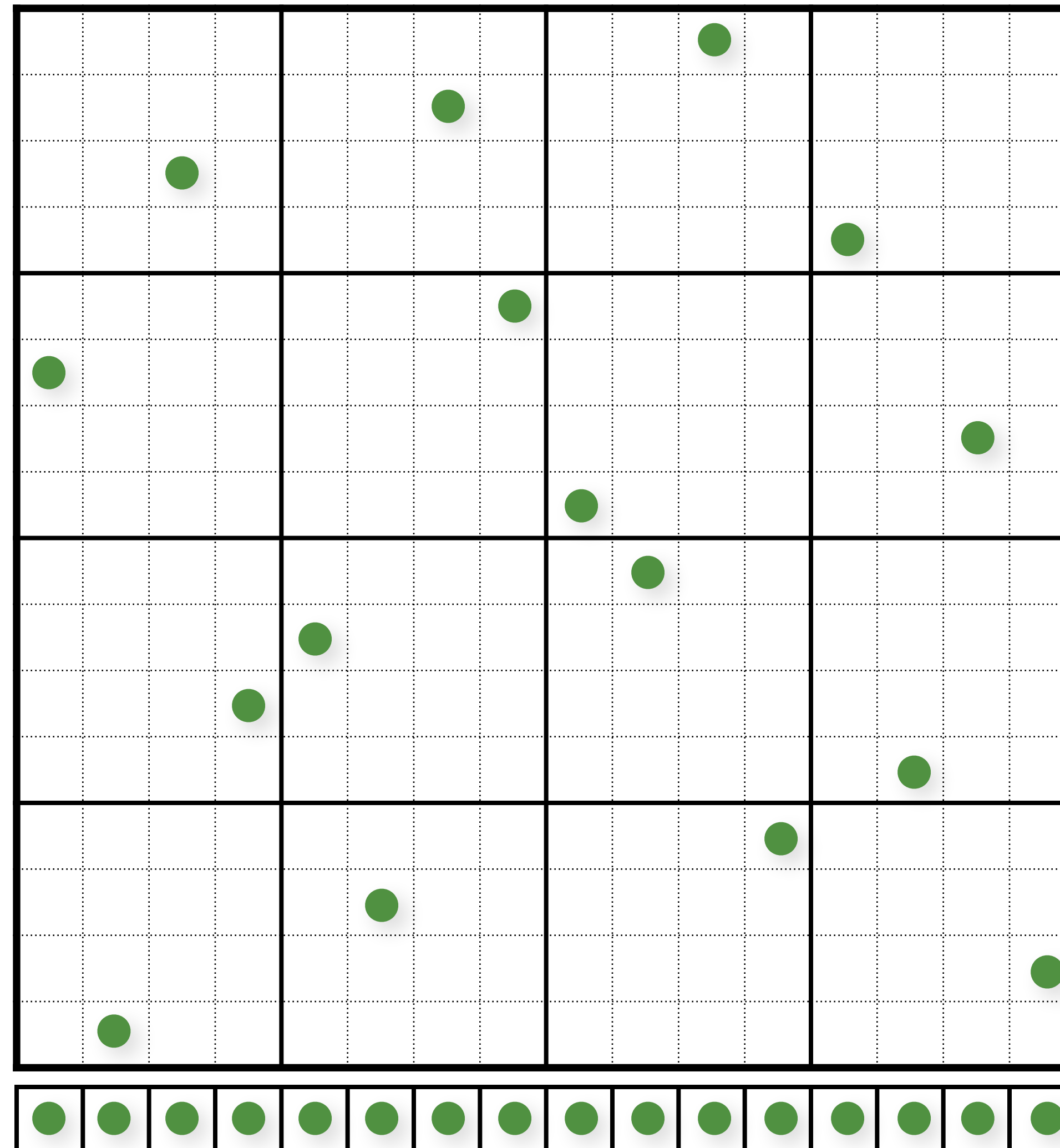


Shuffle y-coords

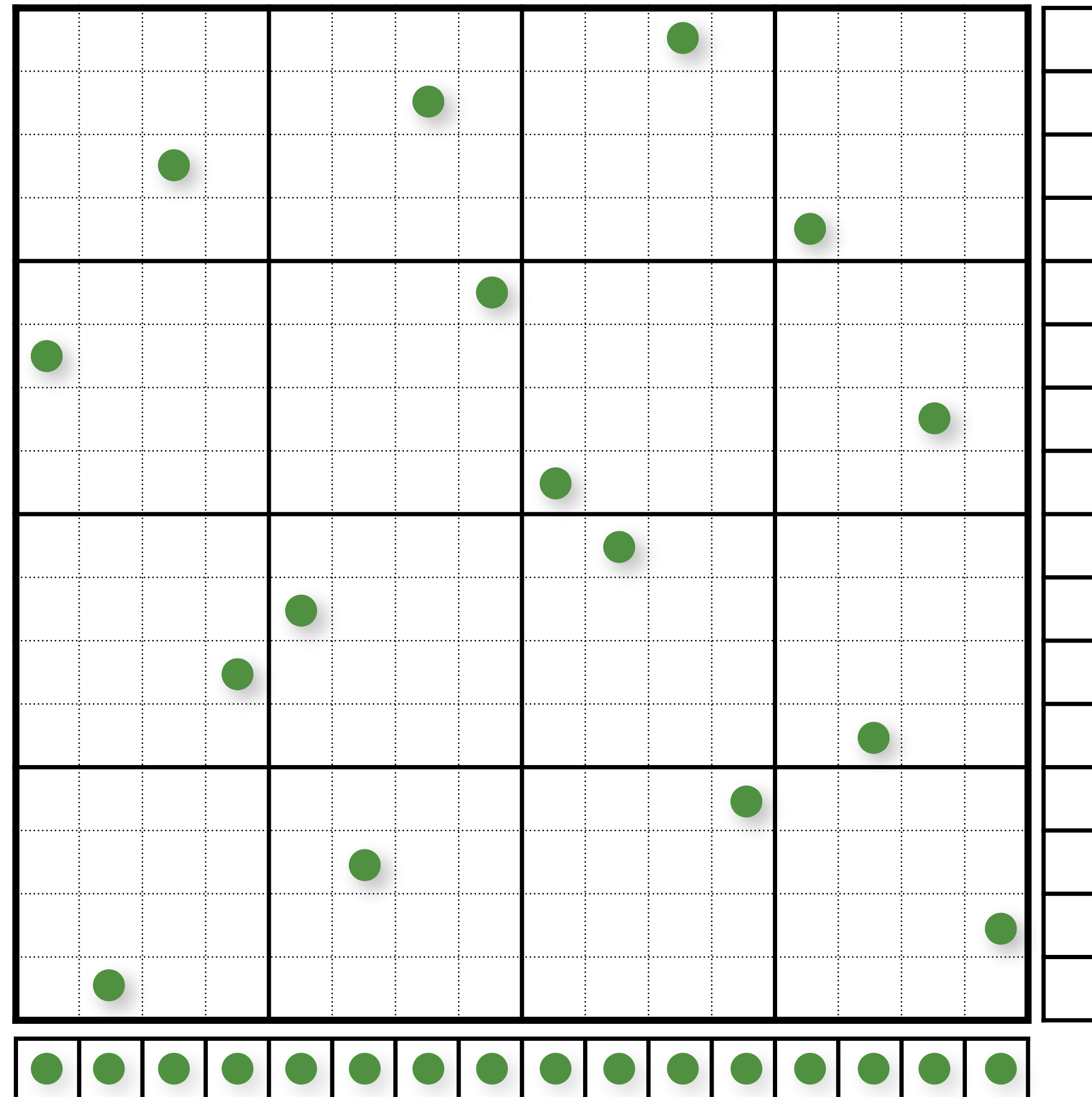
Multi-Jittered Sampling (Projections)



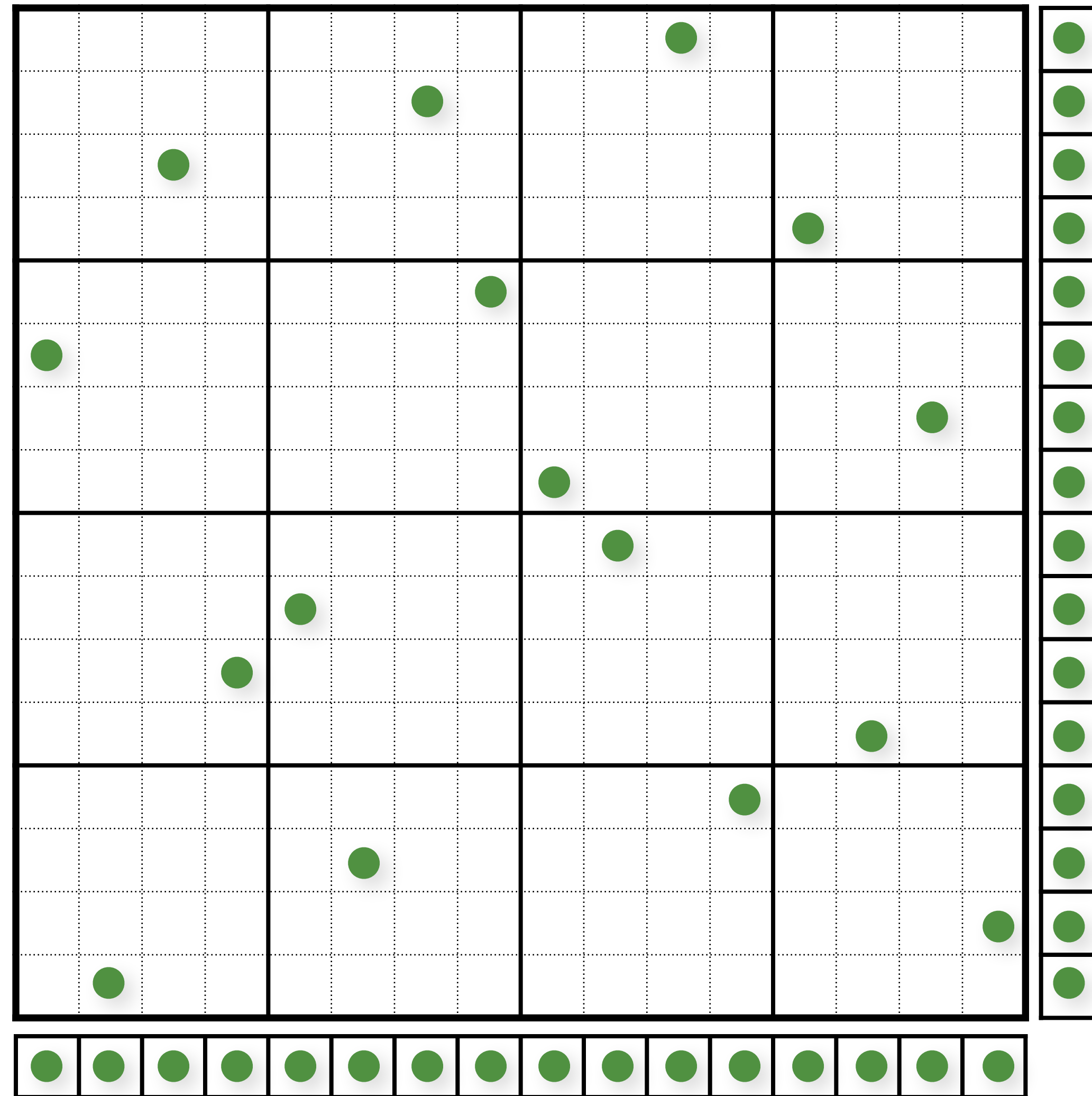
Multi-Jittered Sampling (Projections)



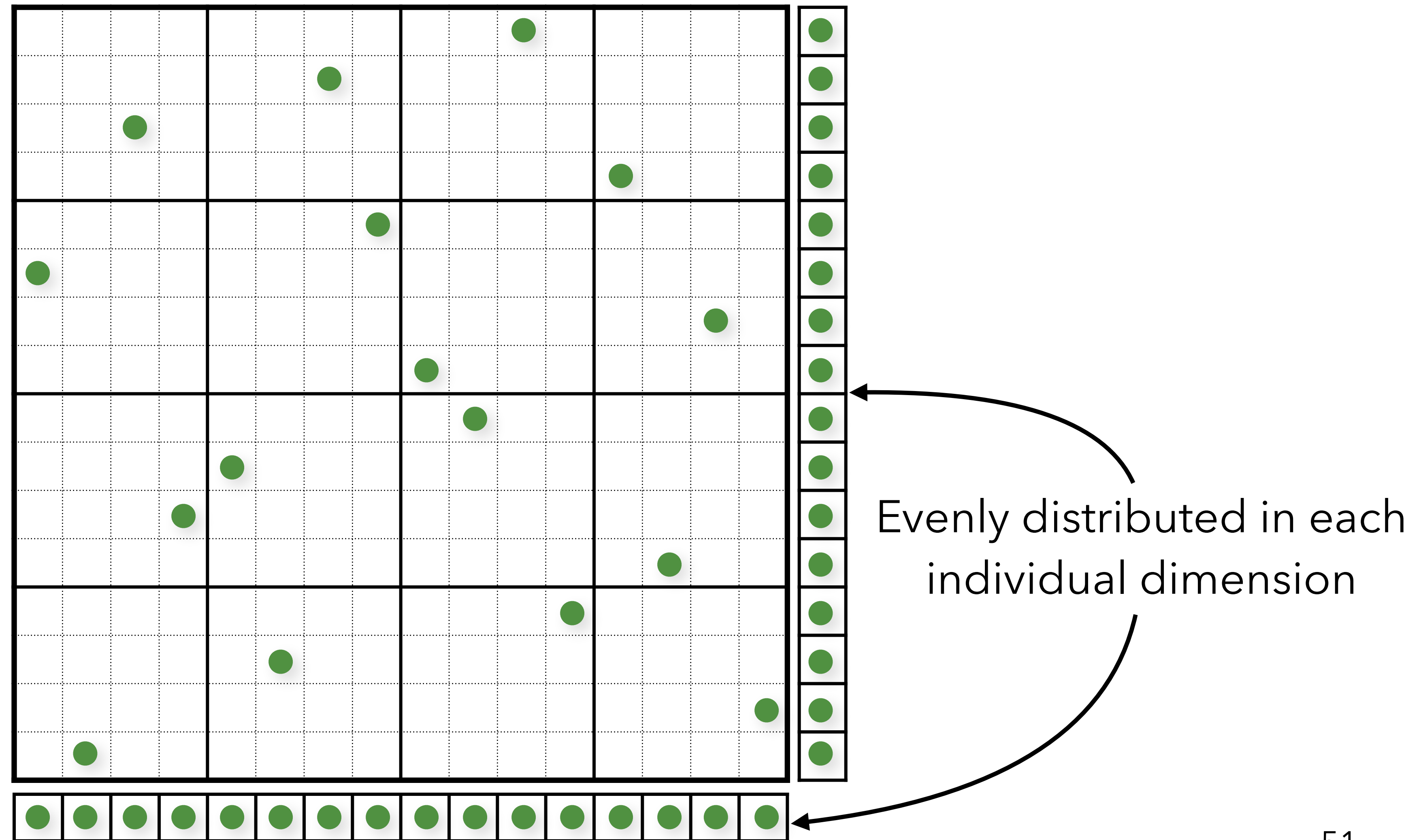
Multi-Jittered Sampling (Projections)



Multi-Jittered Sampling (Projections)

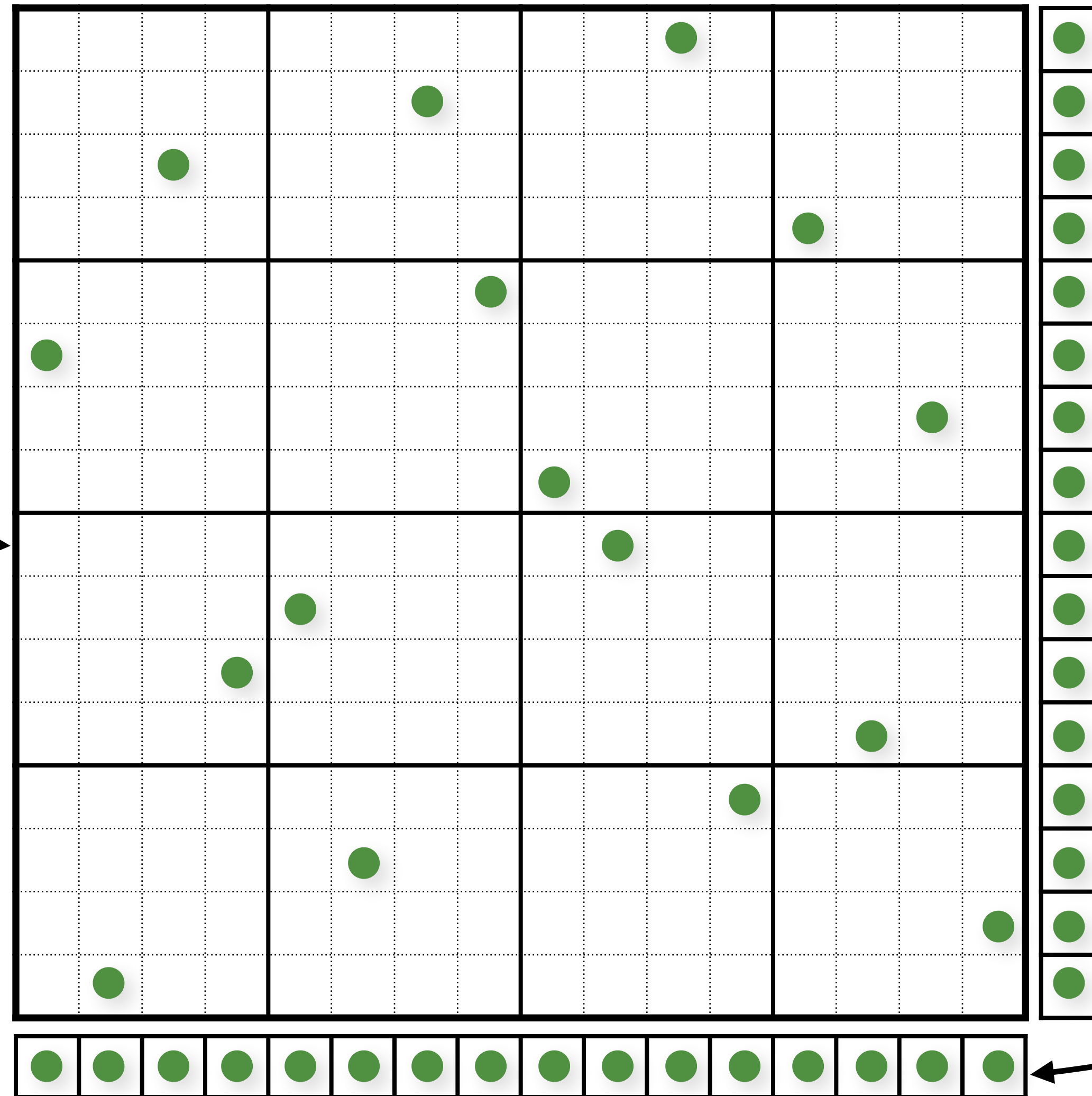


Multi-Jittered Sampling (Projections)



Multi-Jittered Sampling (Projections)

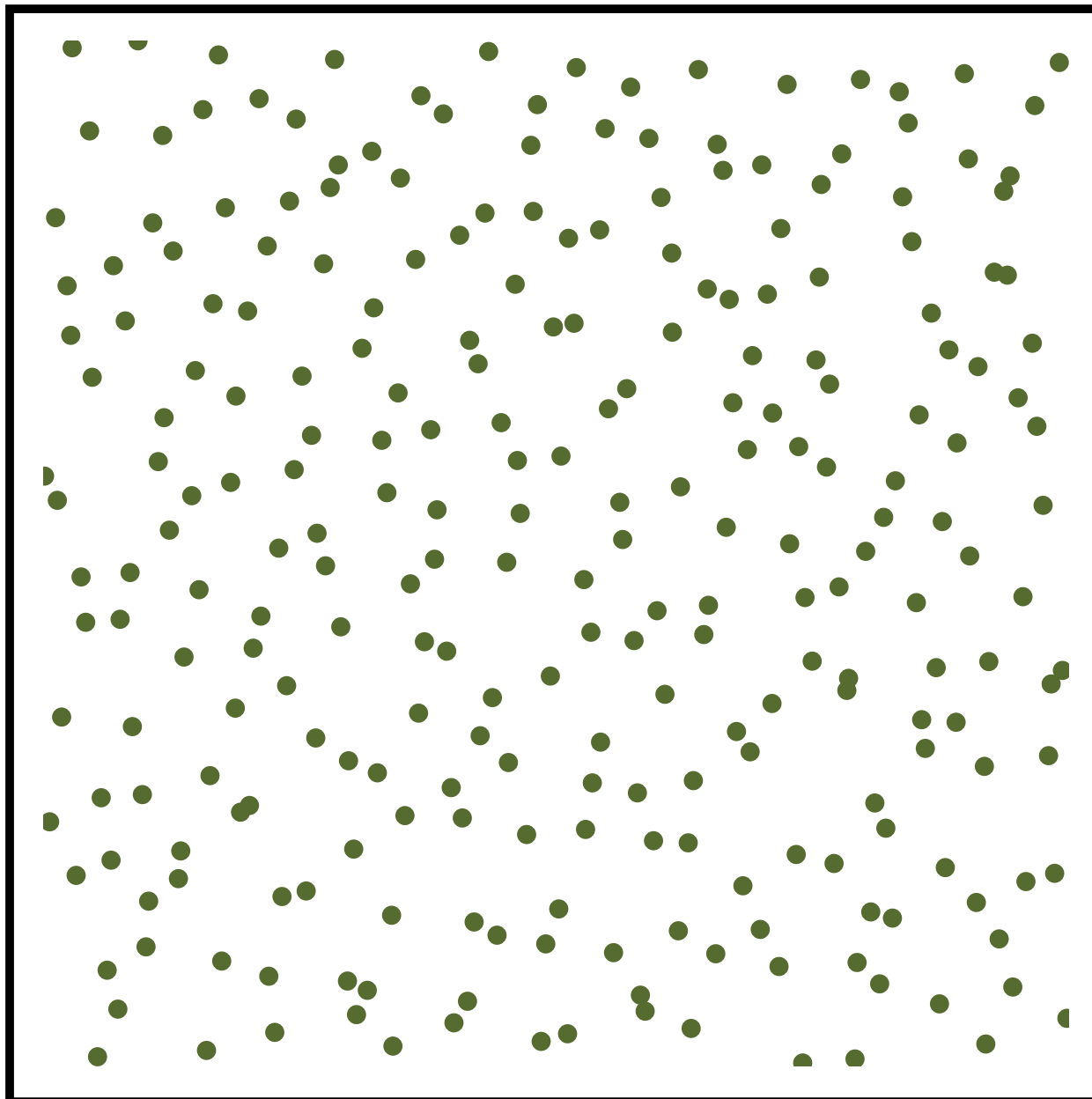
Evenly distributed in 2D!



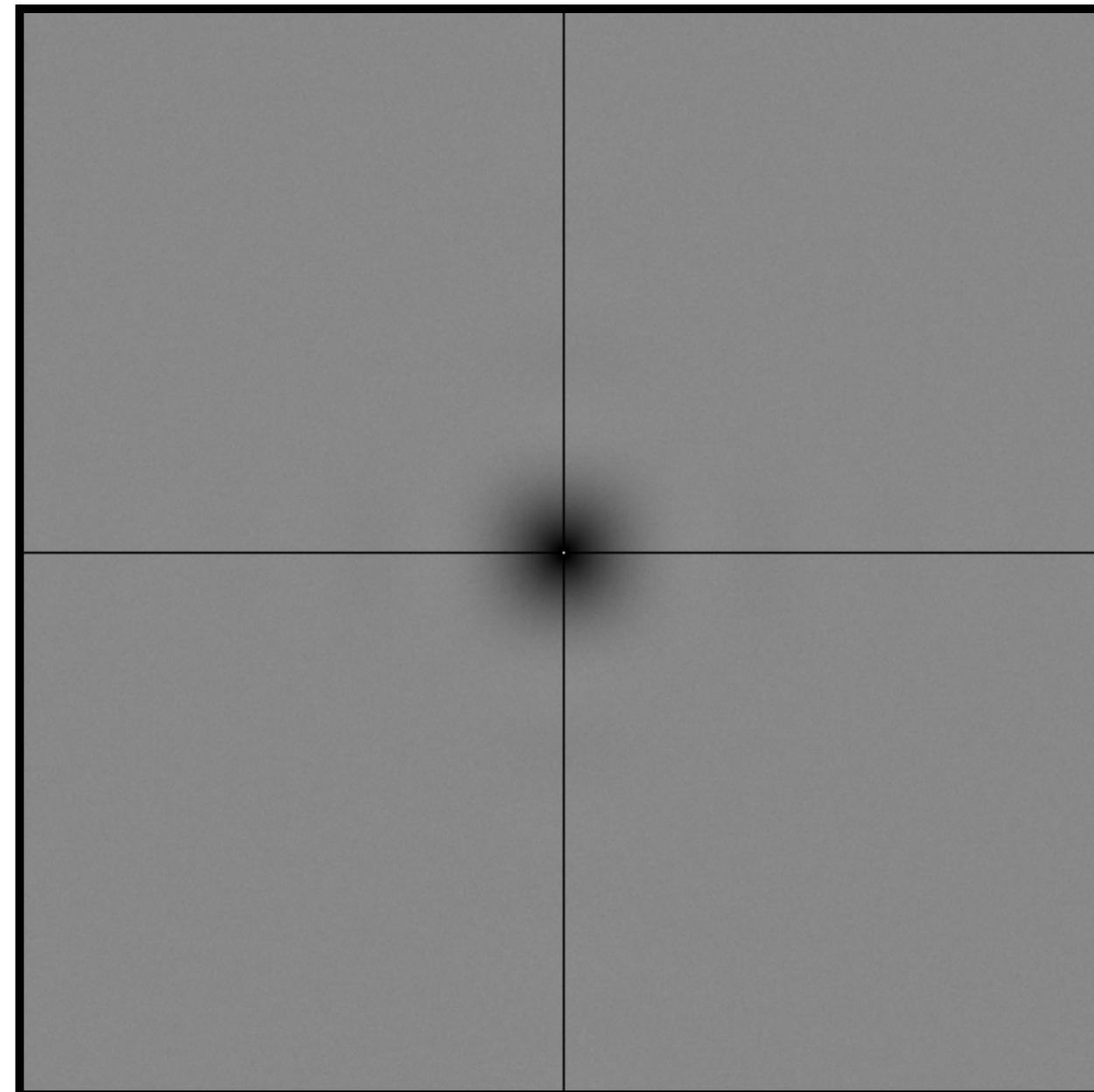
Evenly distributed in each individual dimension

Multi-Jittered Sampling

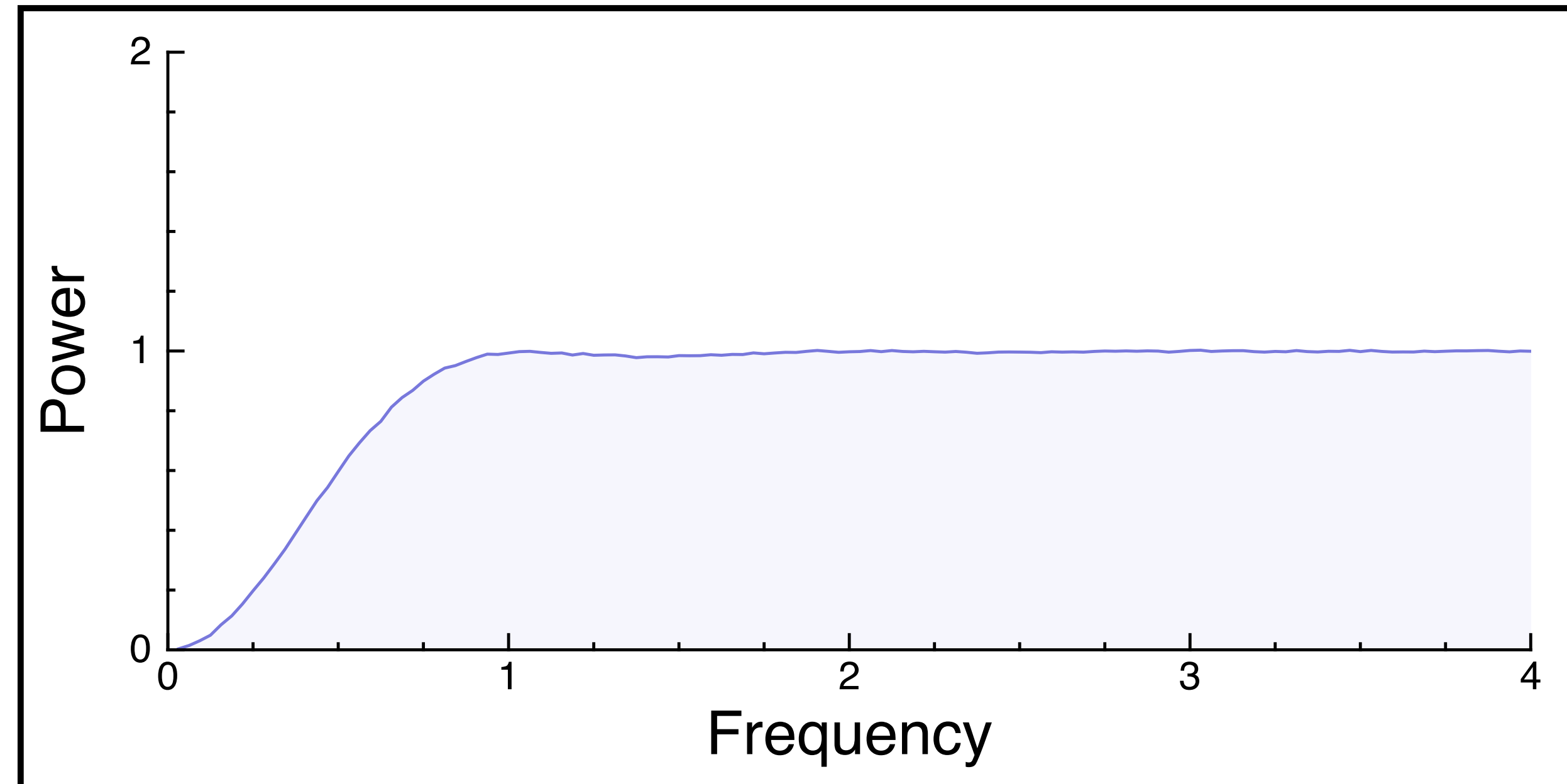
Samples



Expected power spectrum

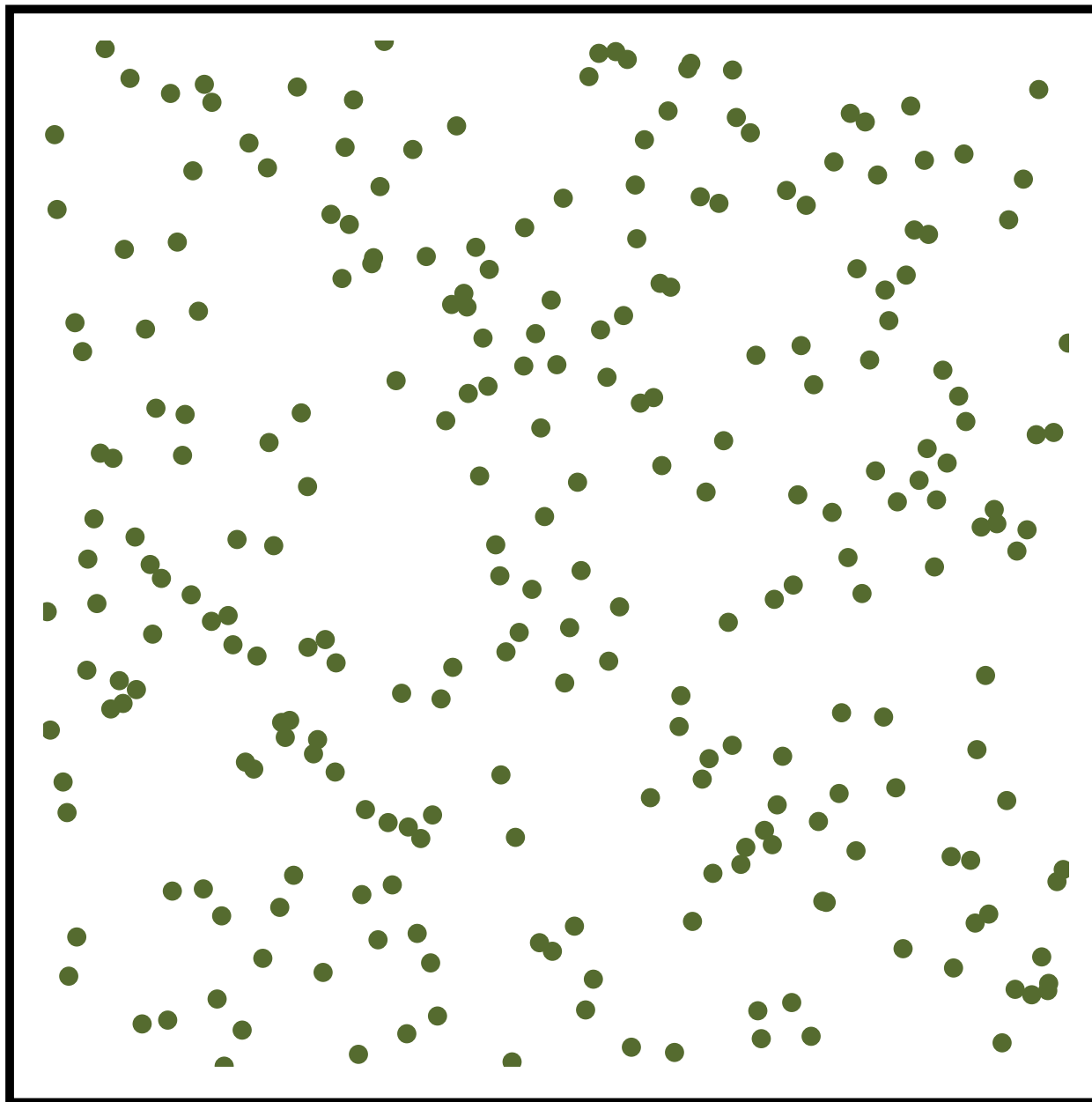


Radial mean

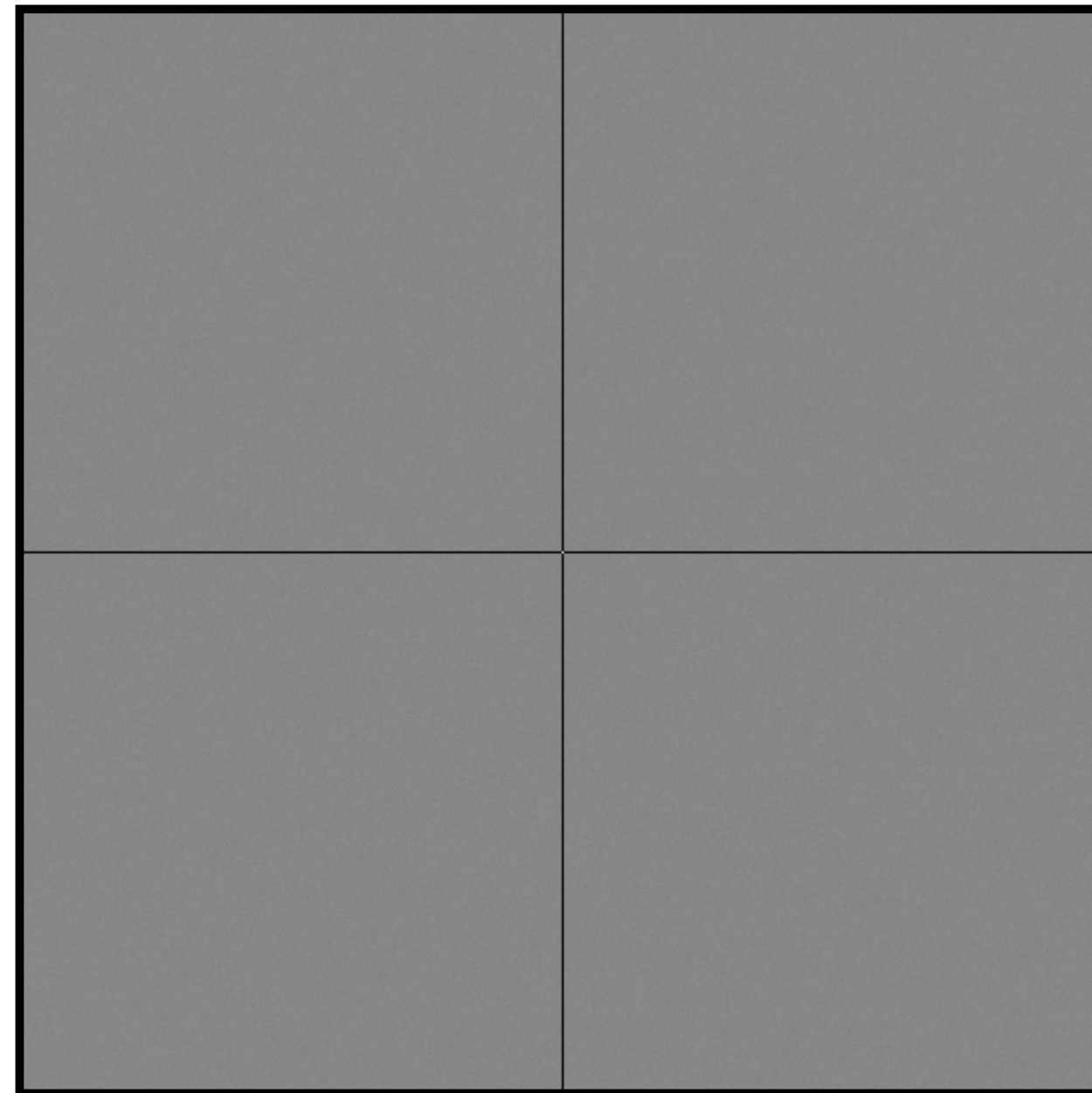


N-Rooks Sampling

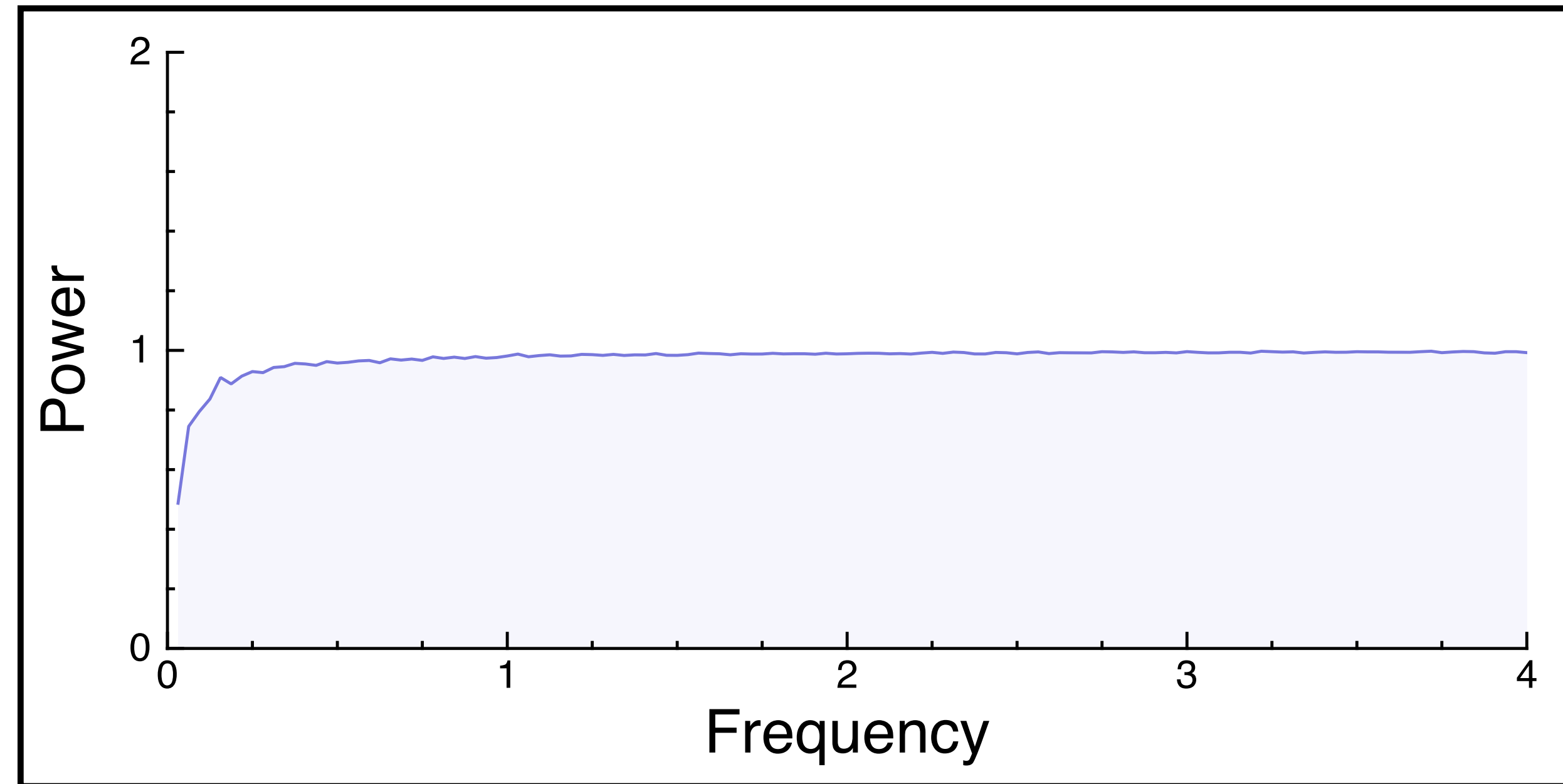
Samples



Expected power spectrum

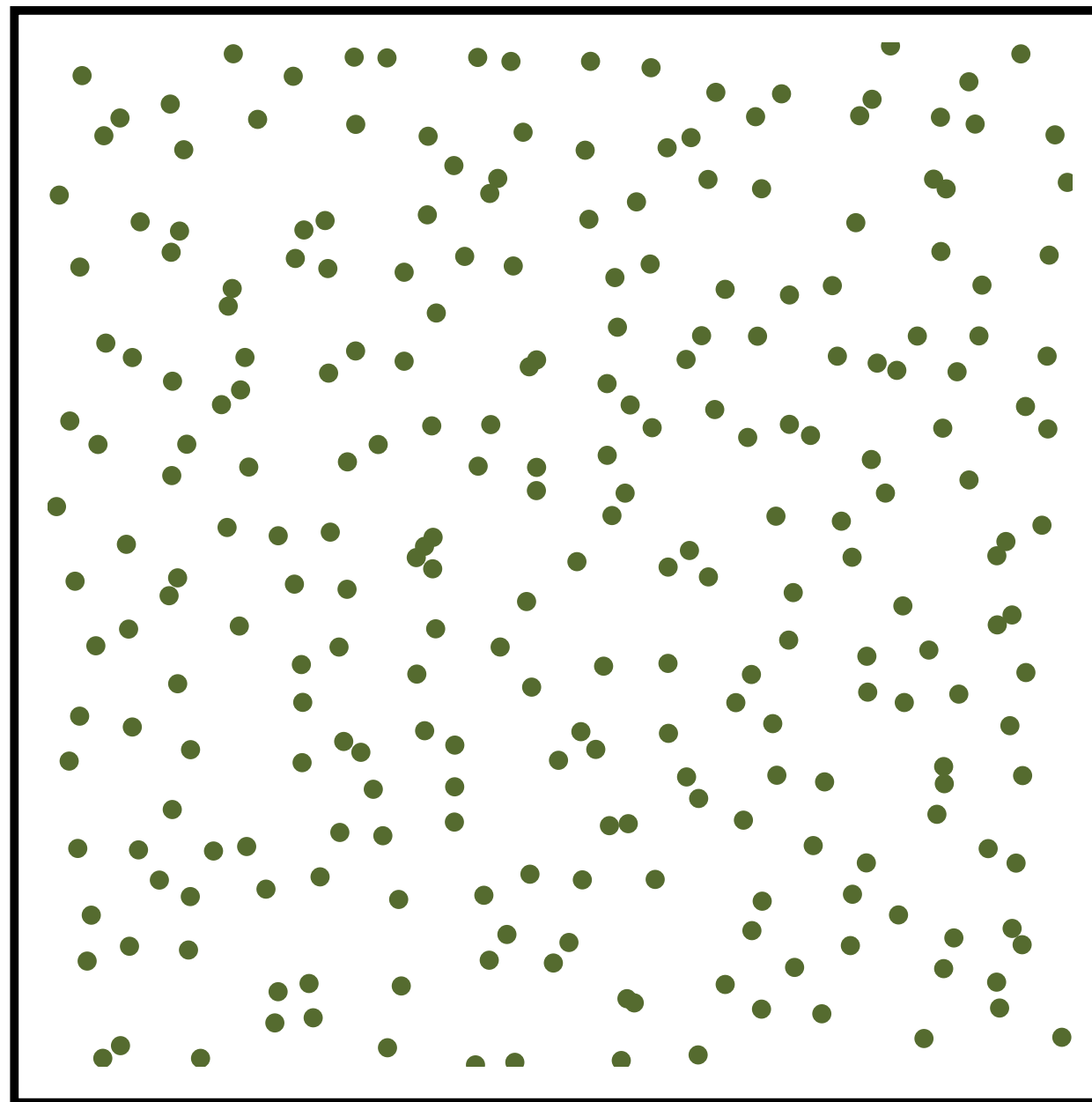


Radial mean

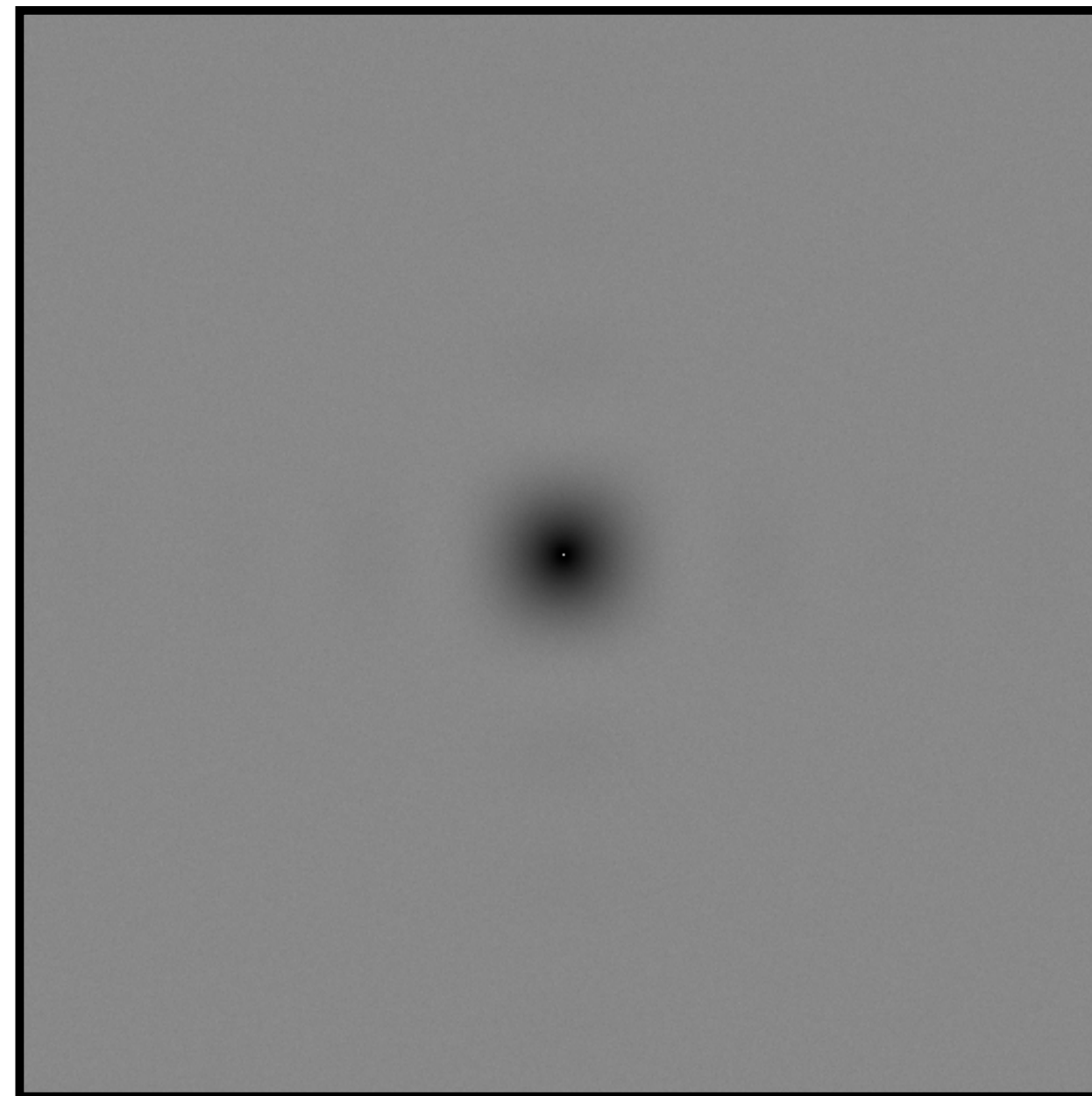


Jittered Sampling

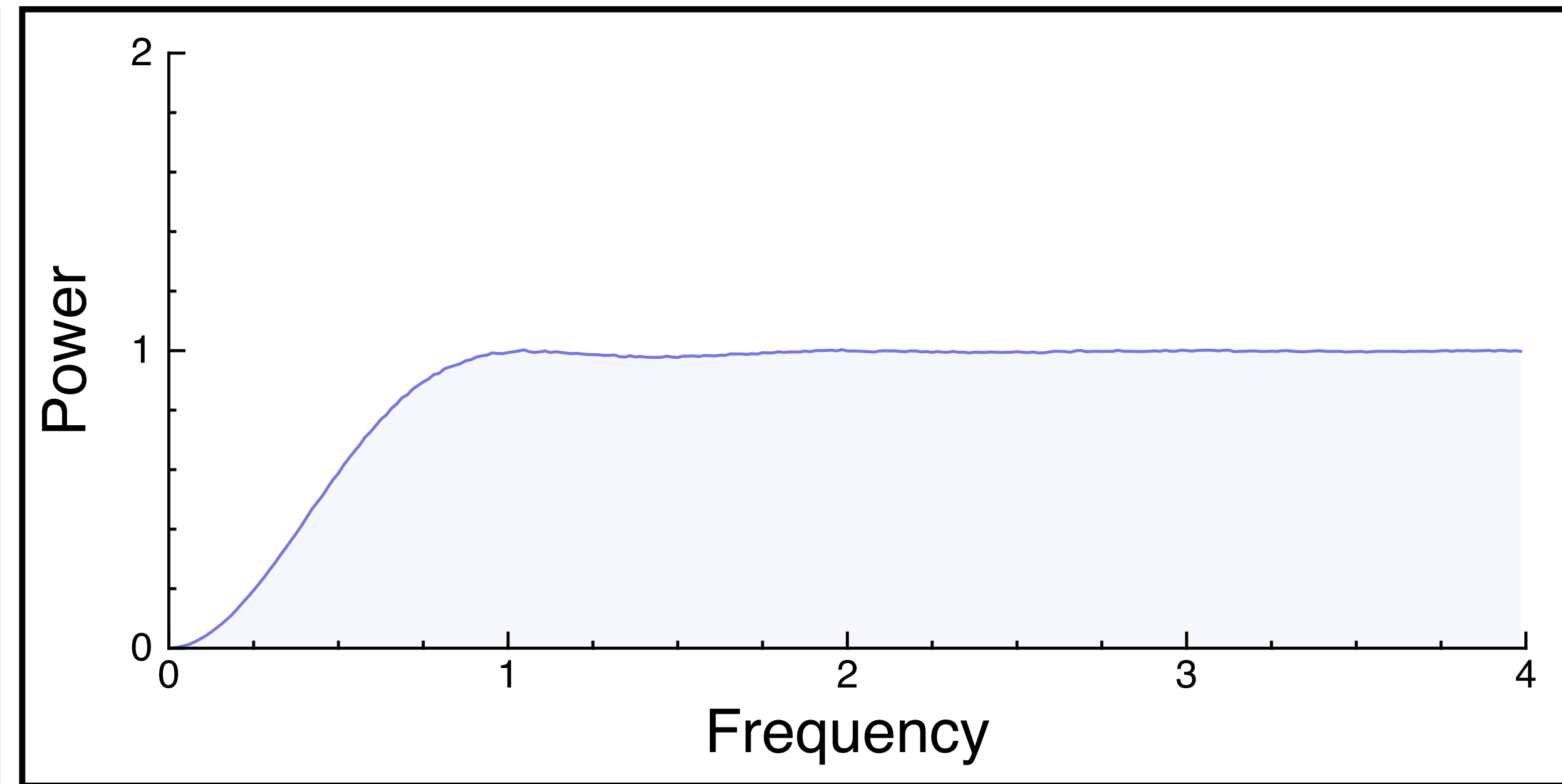
Samples



Expected power spectrum



Radial mean



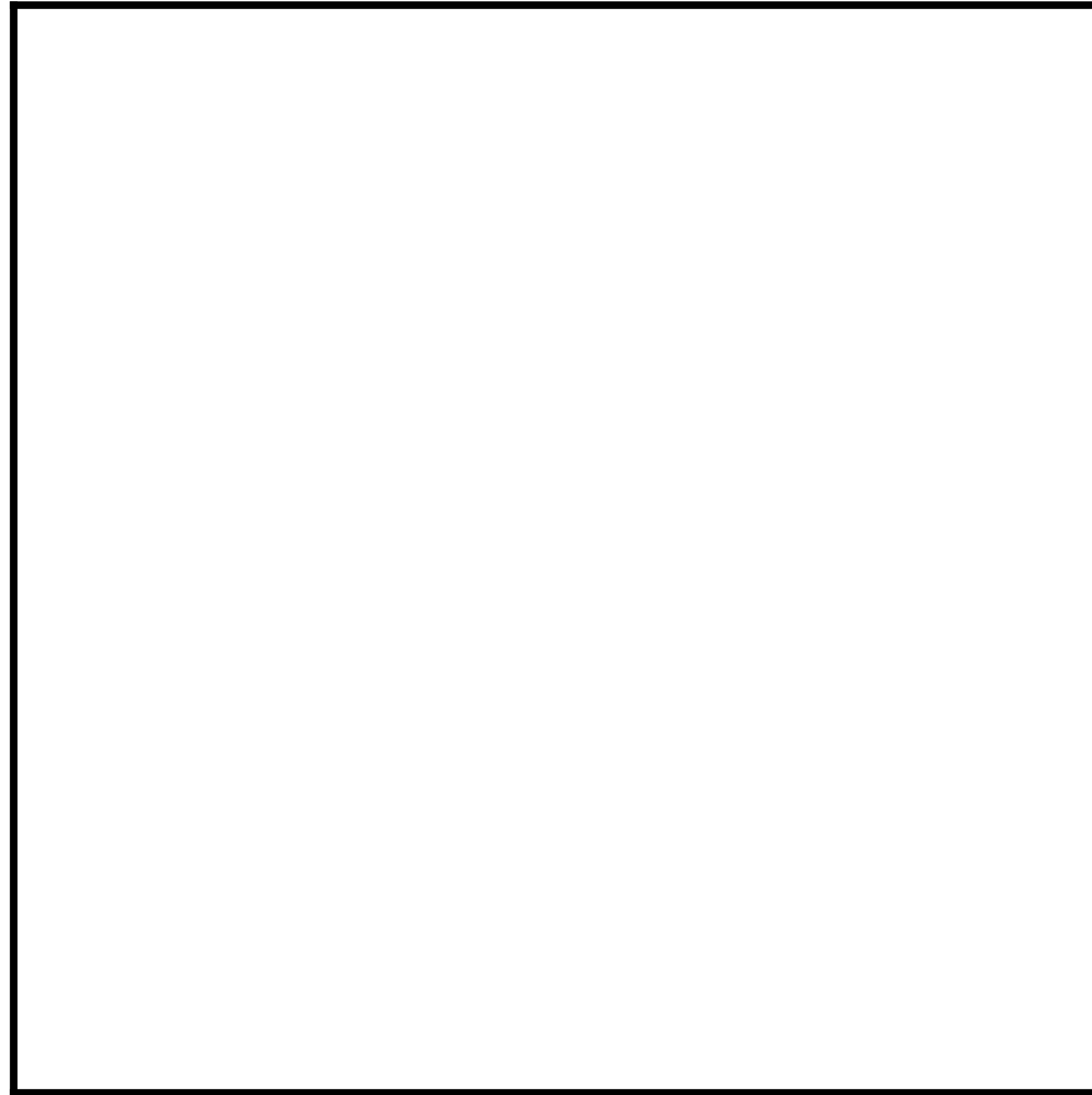
Poisson-Disk/Blue-Noise Sampling

Enforce a minimum distance between points

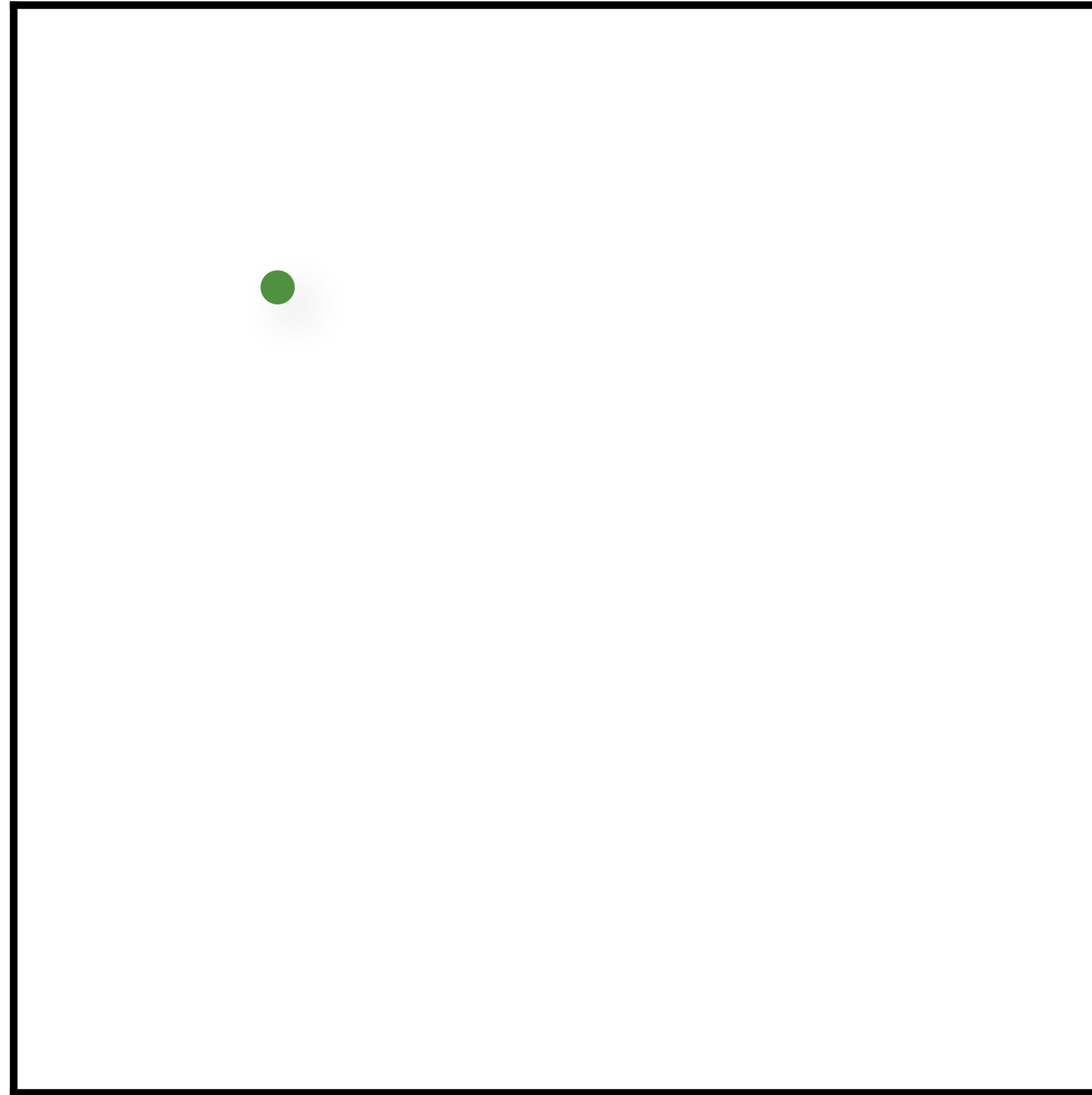
Poisson-Disk Sampling:

- Mark A. Z. Dippé and Erling Henry Wold. "Antialiasing through stochastic sampling." *ACM SIGGRAPH*, 1985.
- Robert L. Cook. "Stochastic sampling in computer graphics." *ACM Transactions on Graphics*, 1986.
- Ares Lagae and Philip Dutré. "A comparison of methods for generating Poisson disk distributions." *Computer Graphics Forum*, 2008.

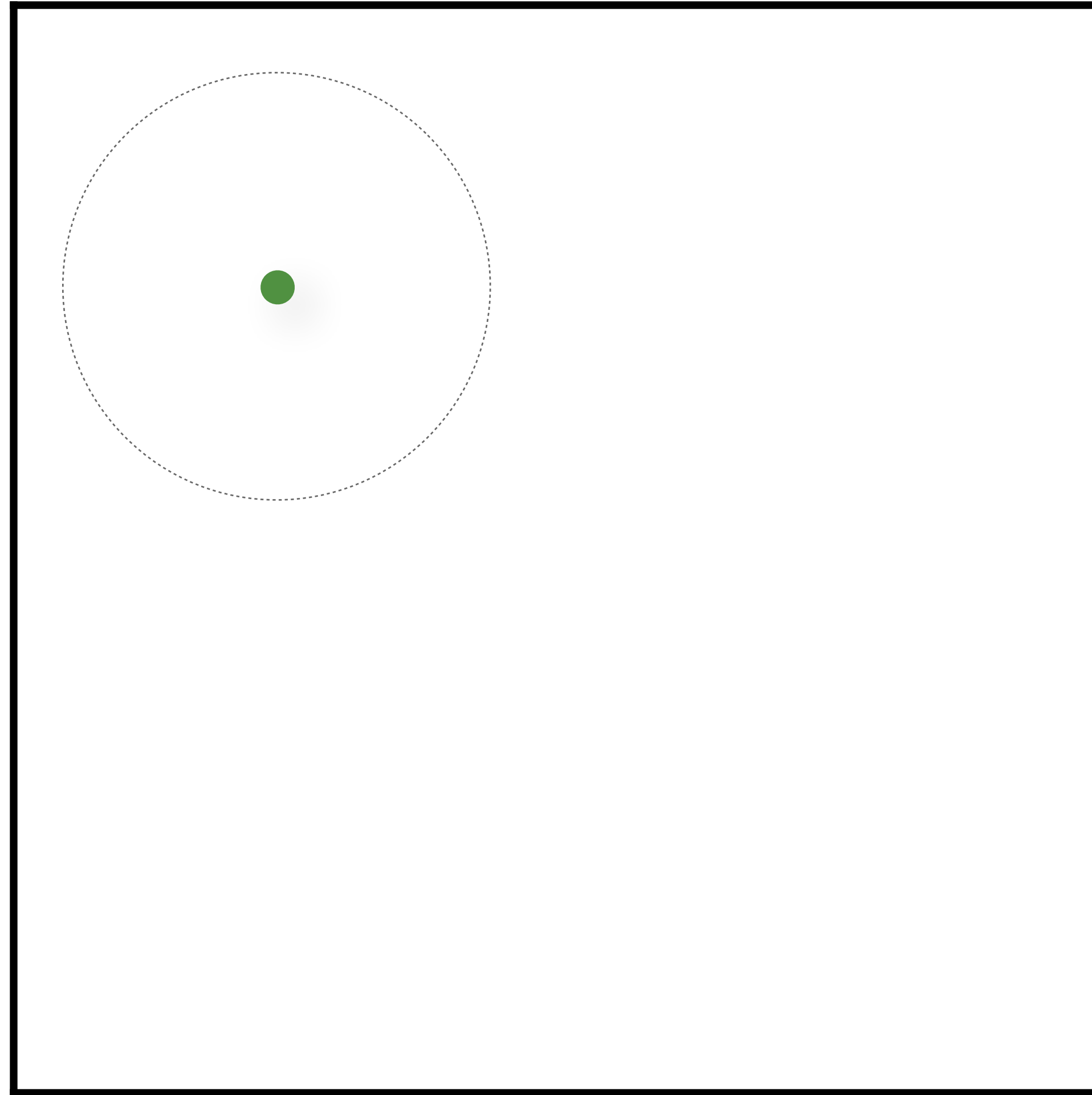
Random Dart Throwing



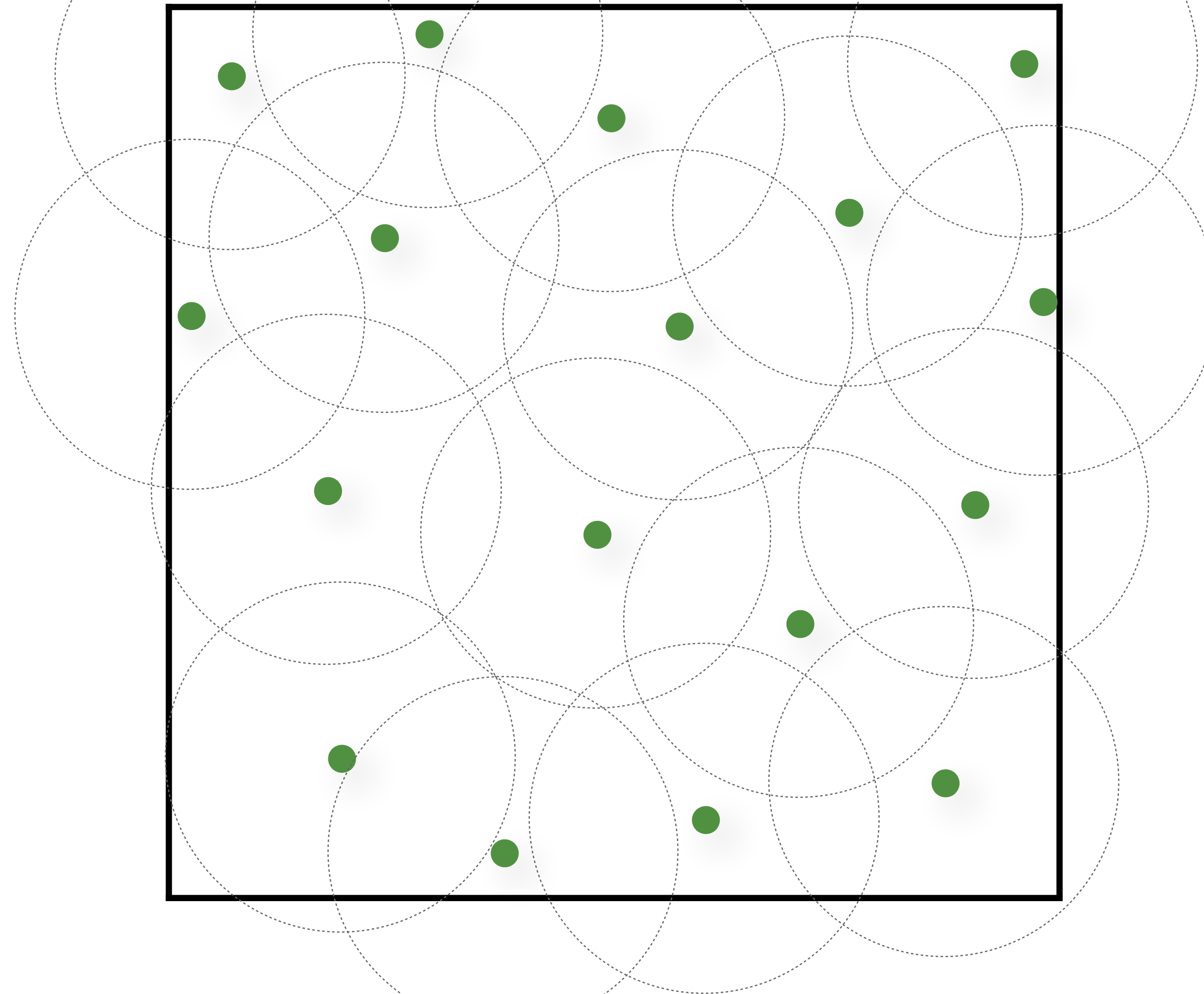
Random Dart Throwing



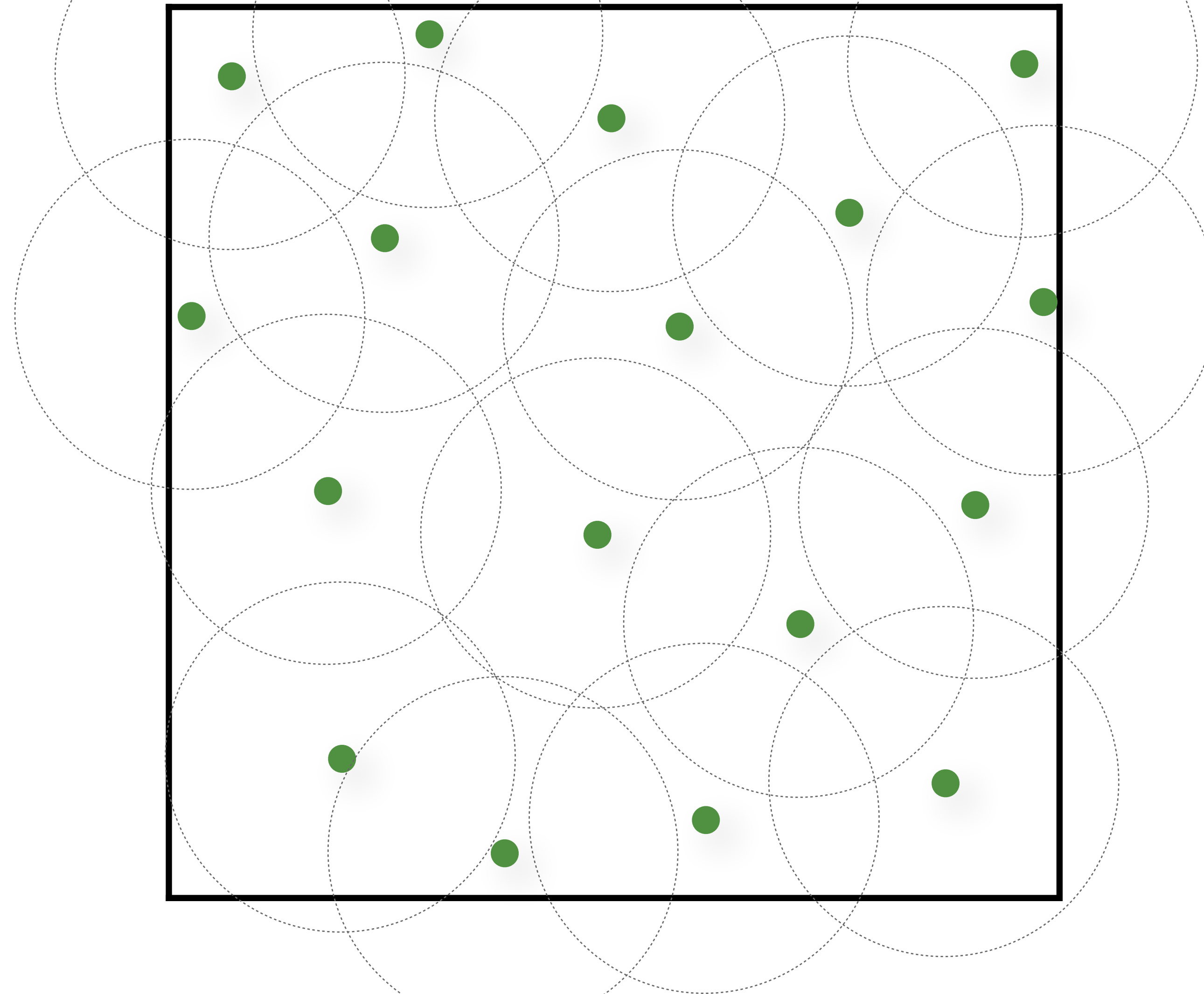
Random Dart Throwing



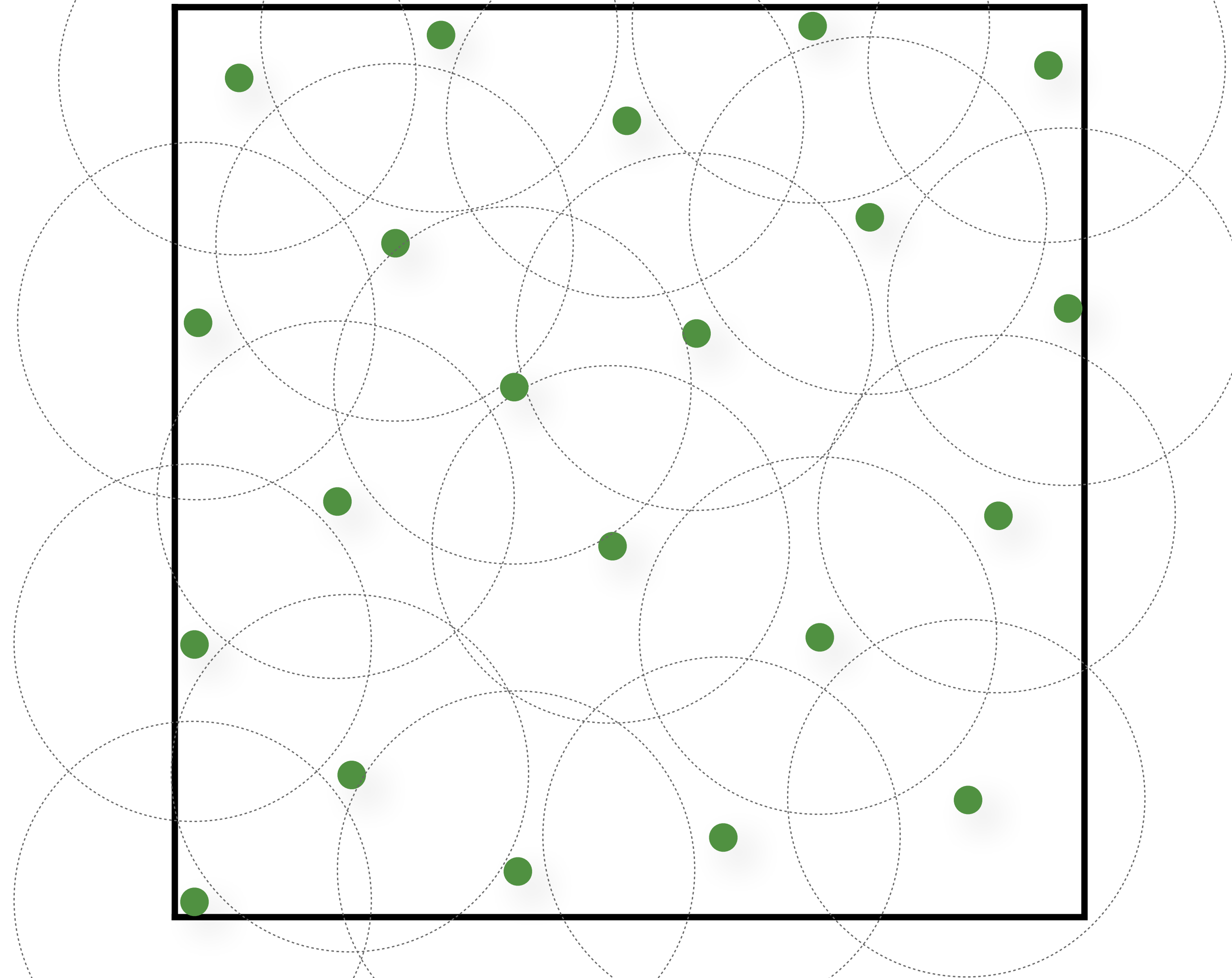
Random Dart Throwing



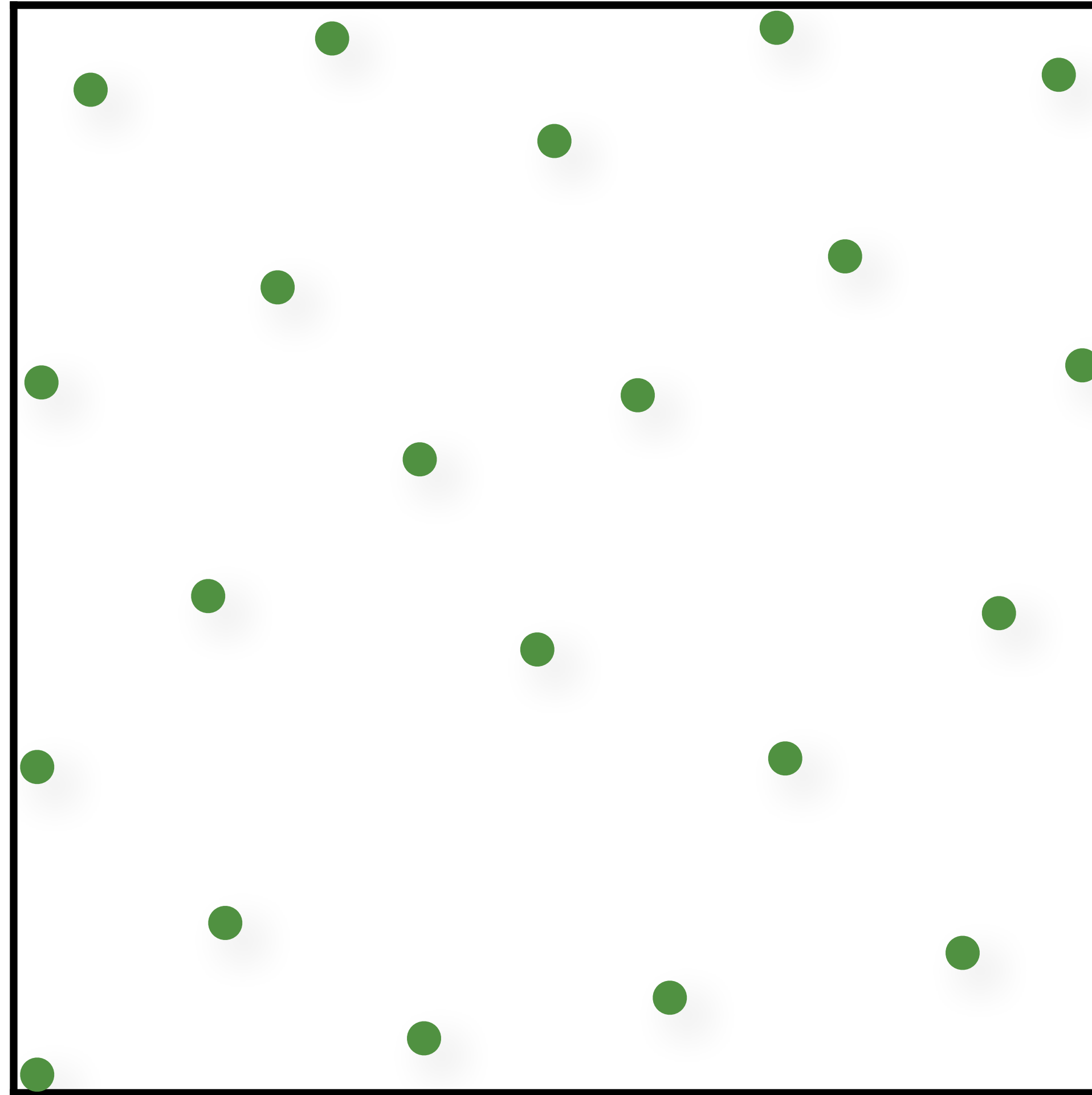
Random Dart Throwing



Random Dart Throwing

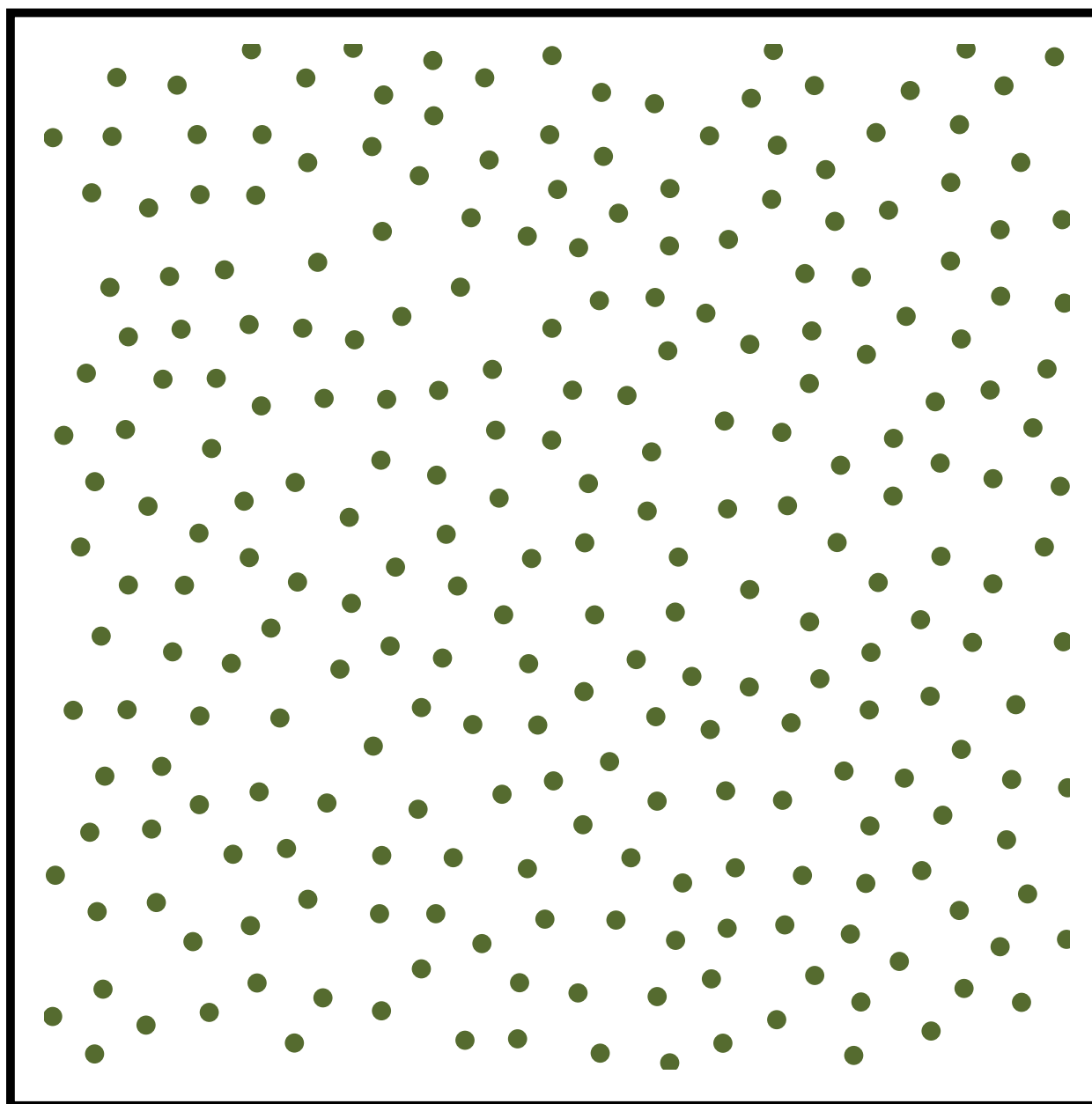


Random Dart Throwing

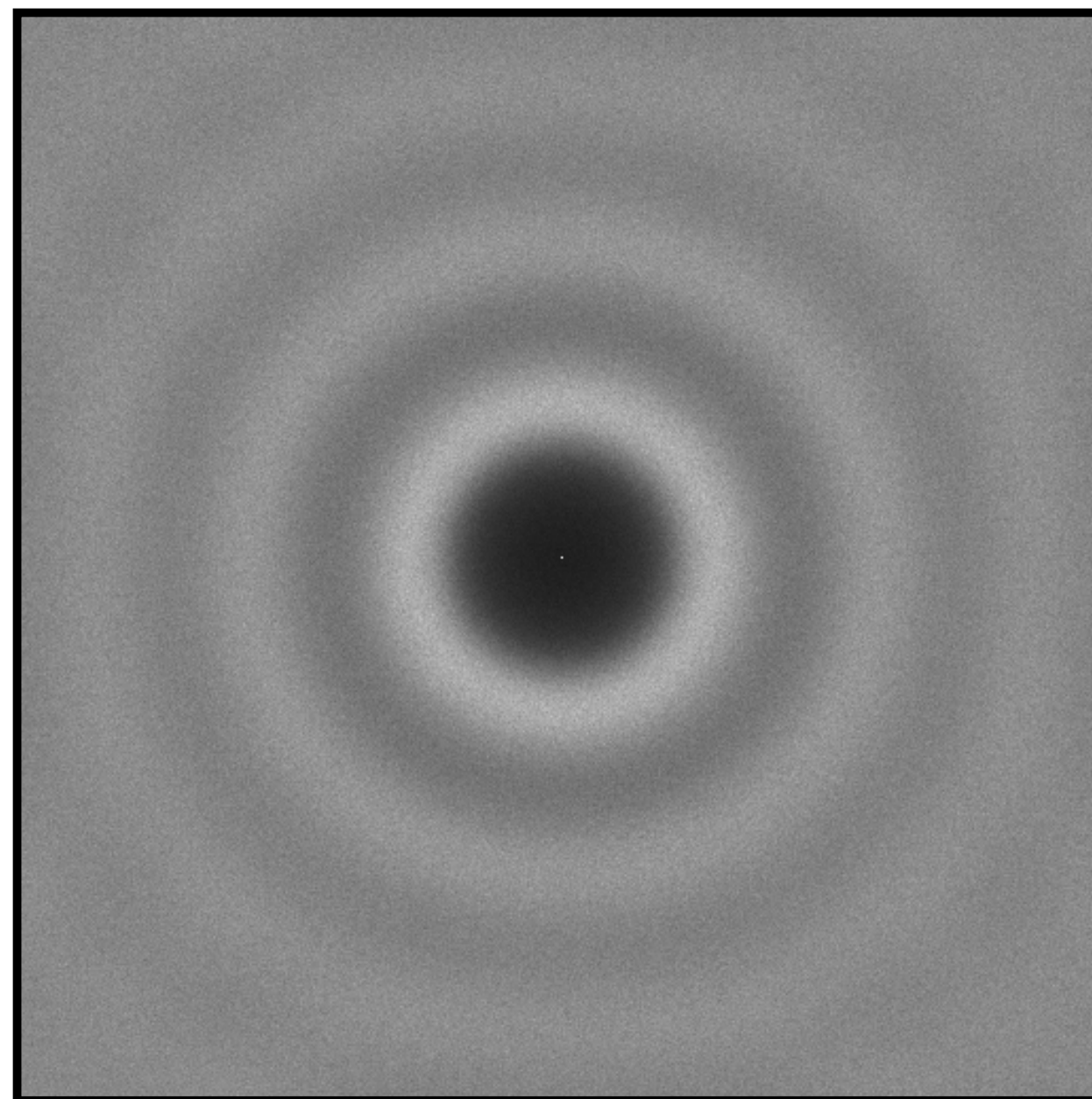


Poisson Disk Sampling

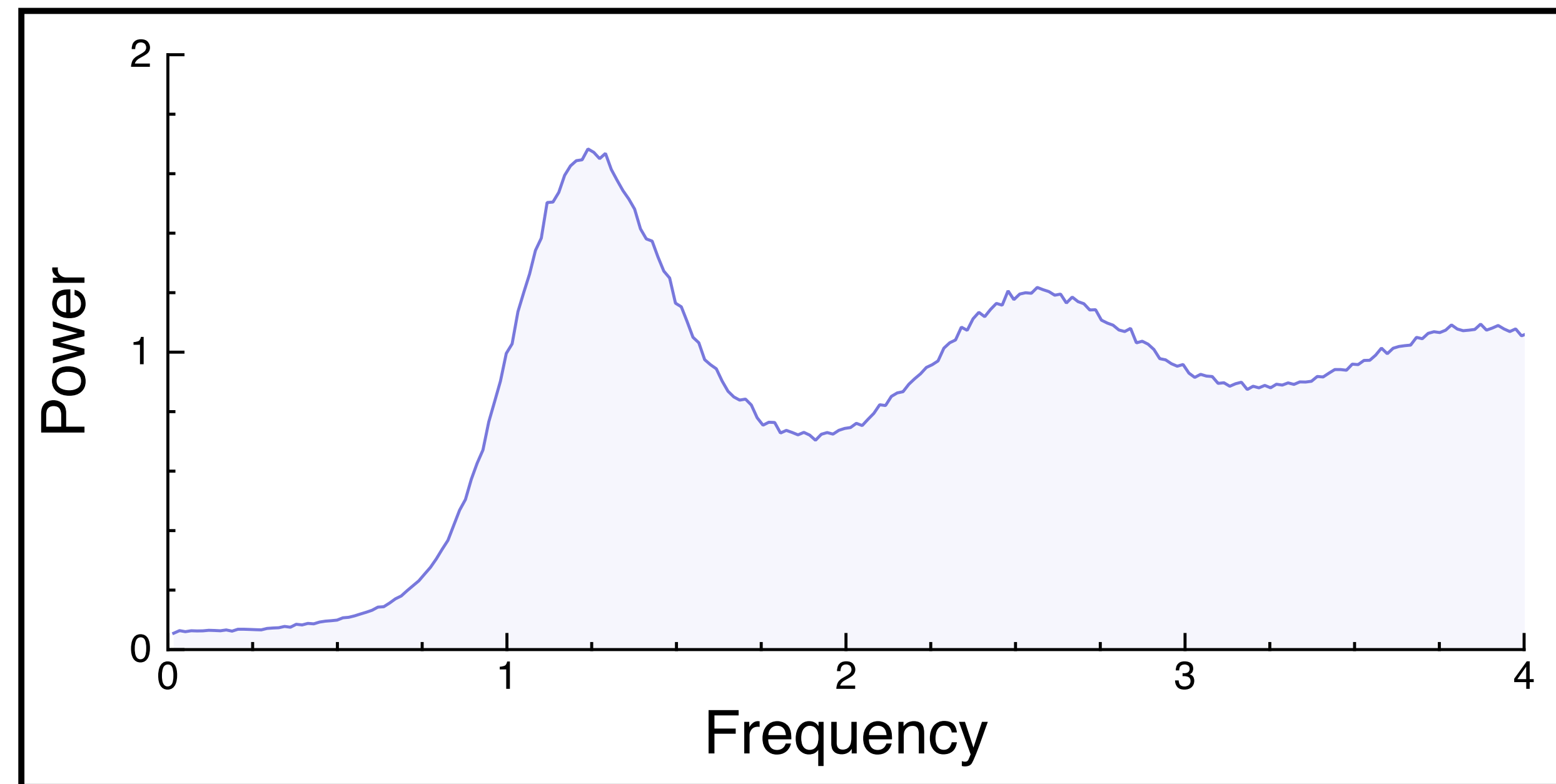
Samples



Expected power spectrum



Radial mean



Blue-Noise Sampling (Relaxation-based)

Blue-Noise Sampling (Relaxation-based)

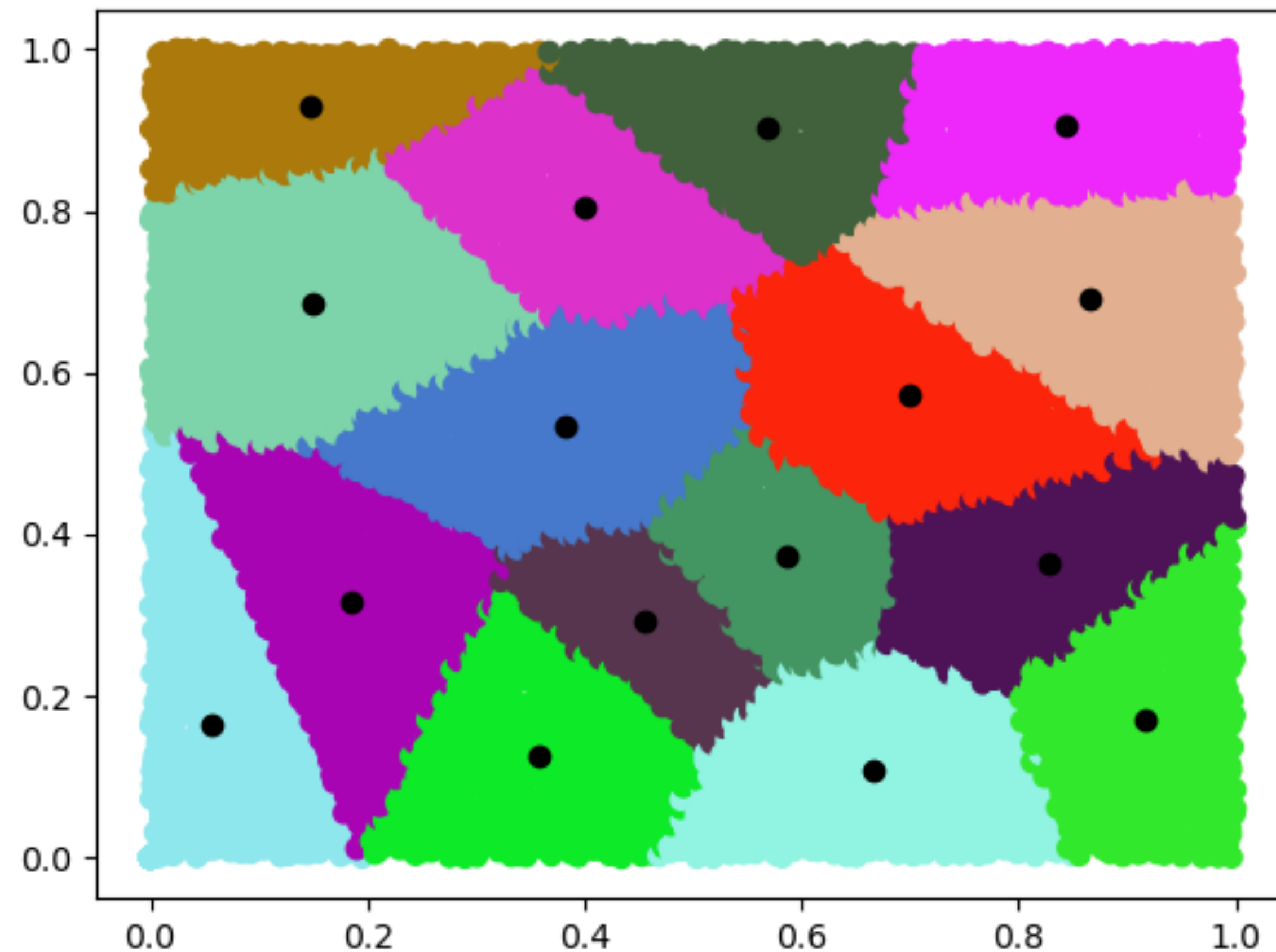
1. Initialize sample positions (e.g. random)

Blue-Noise Sampling (Relaxation-based)

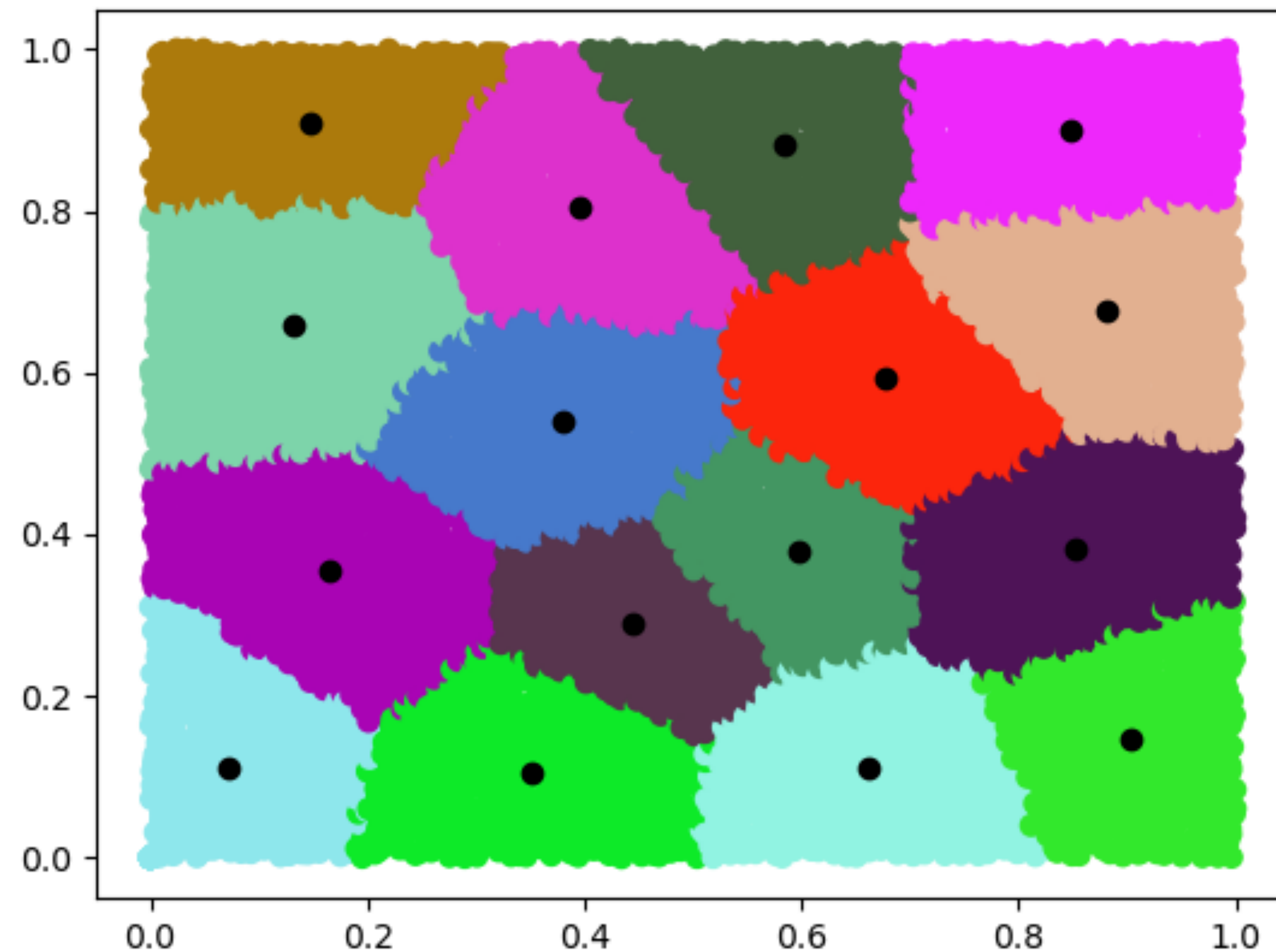
1. Initialize sample positions (e.g. random)
2. Use an iterative relaxation to move samples away from each other.

Lloyd-Relaxation Method

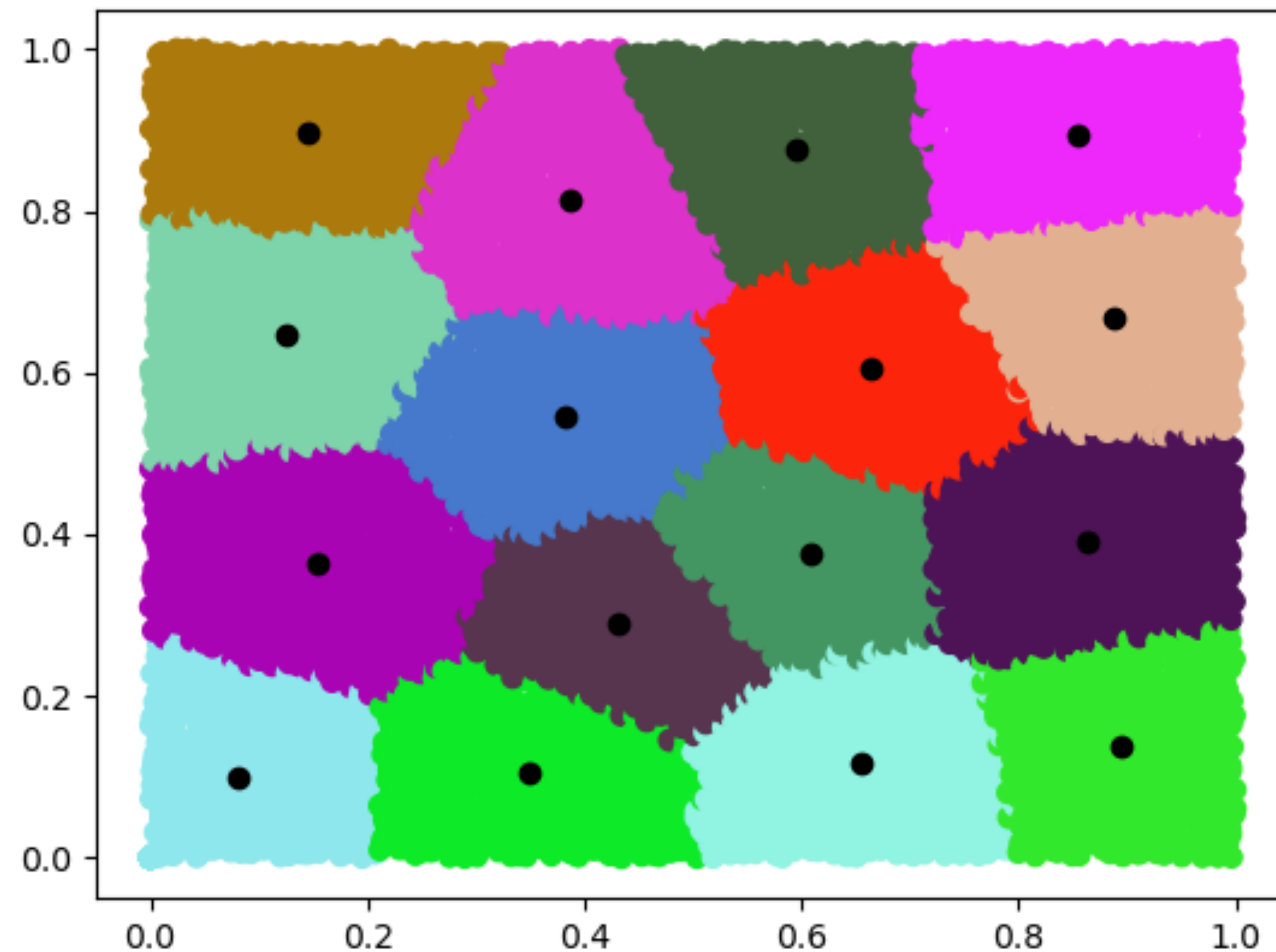
Lloyd-Relaxation Method



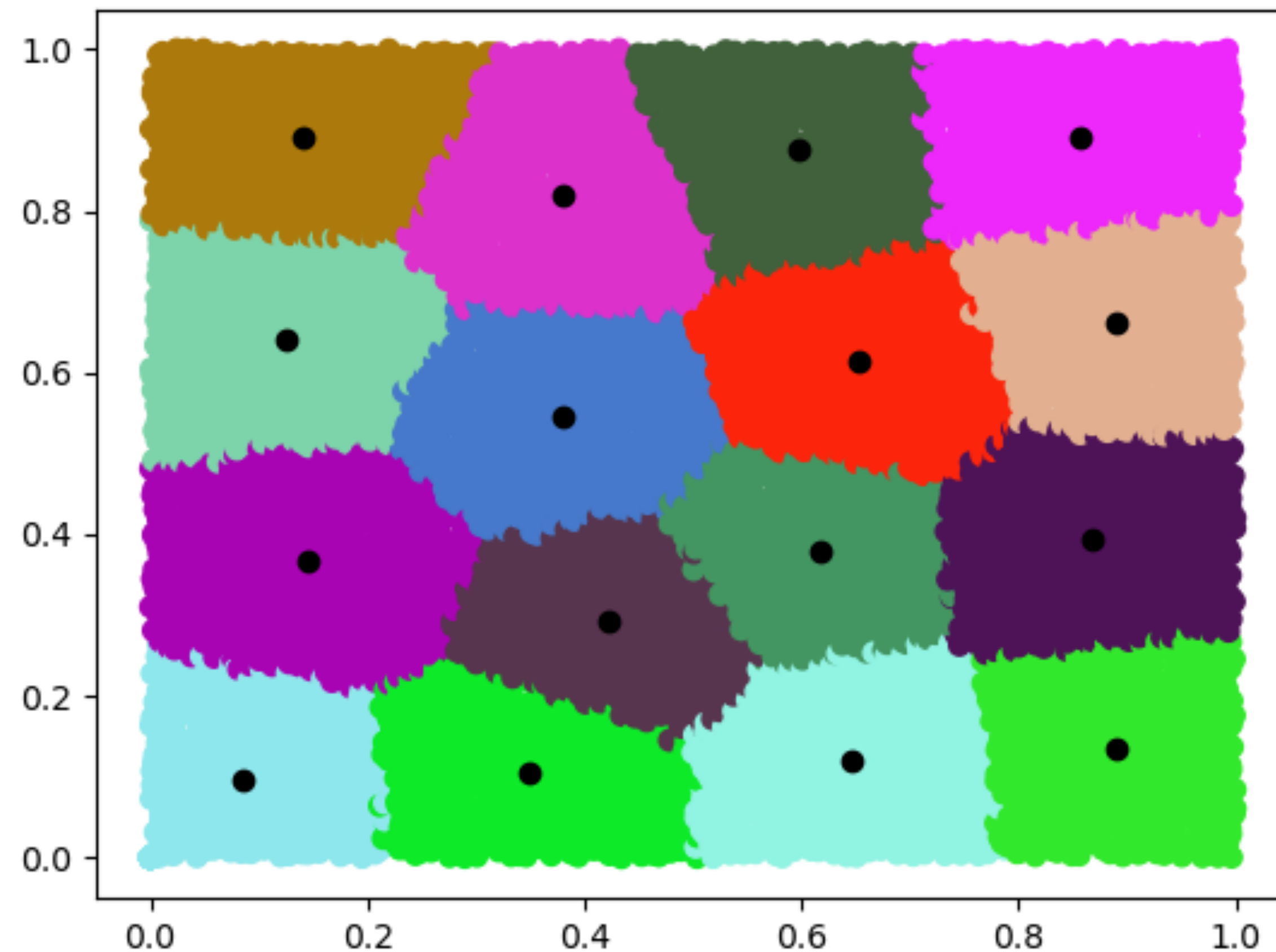
Lloyd-Relaxation Method



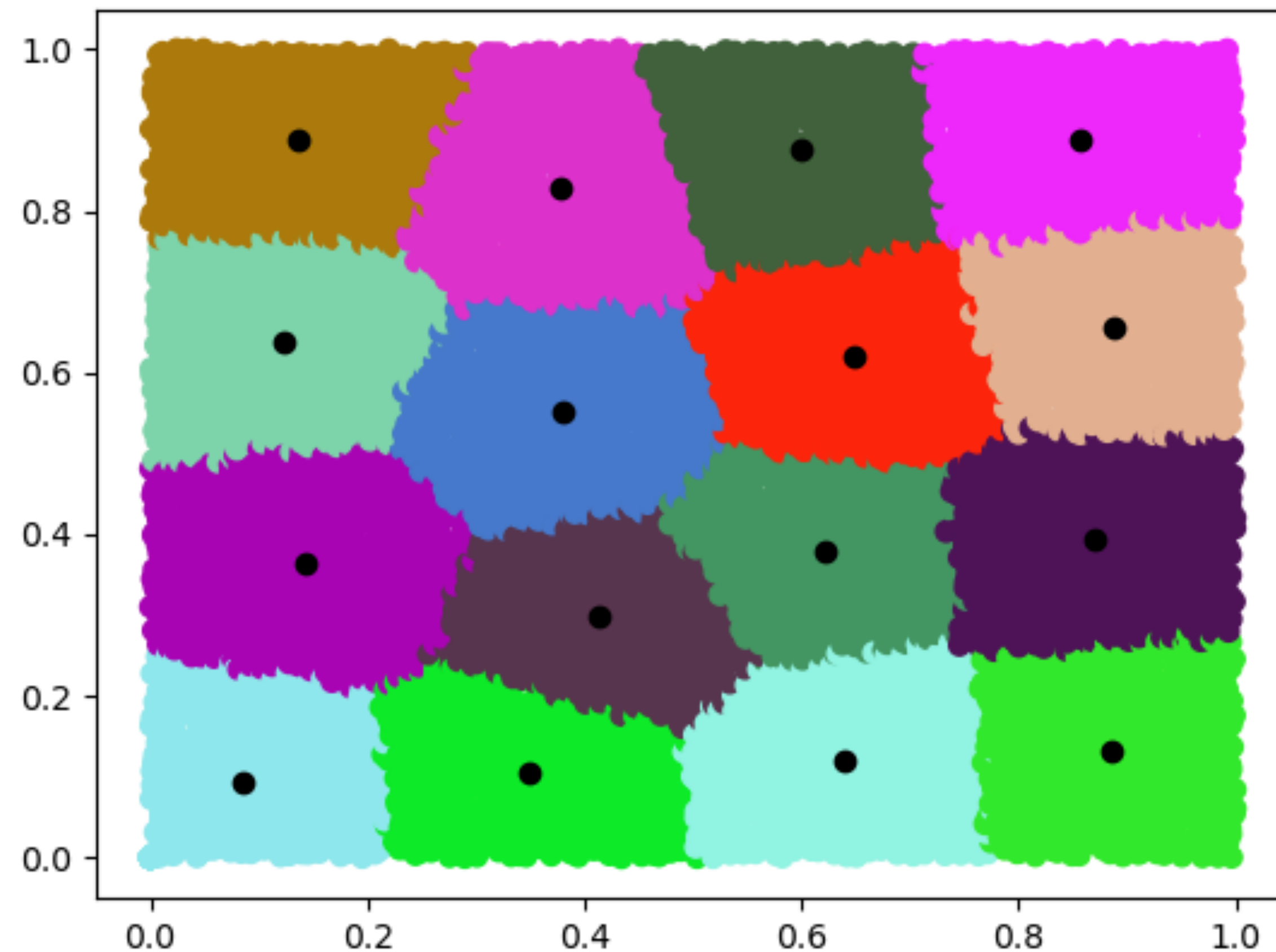
Lloyd-Relaxation Method



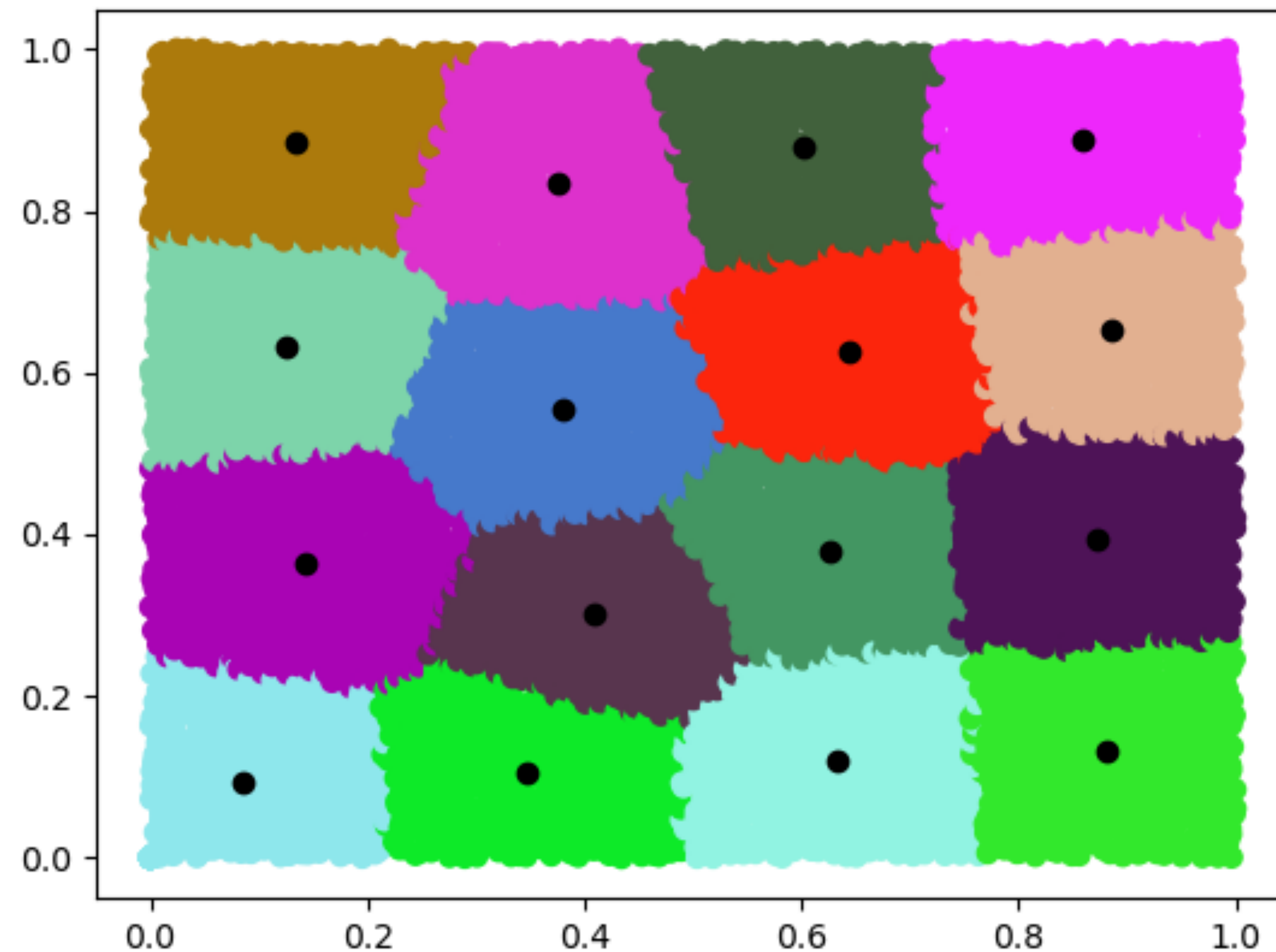
Lloyd-Relaxation Method



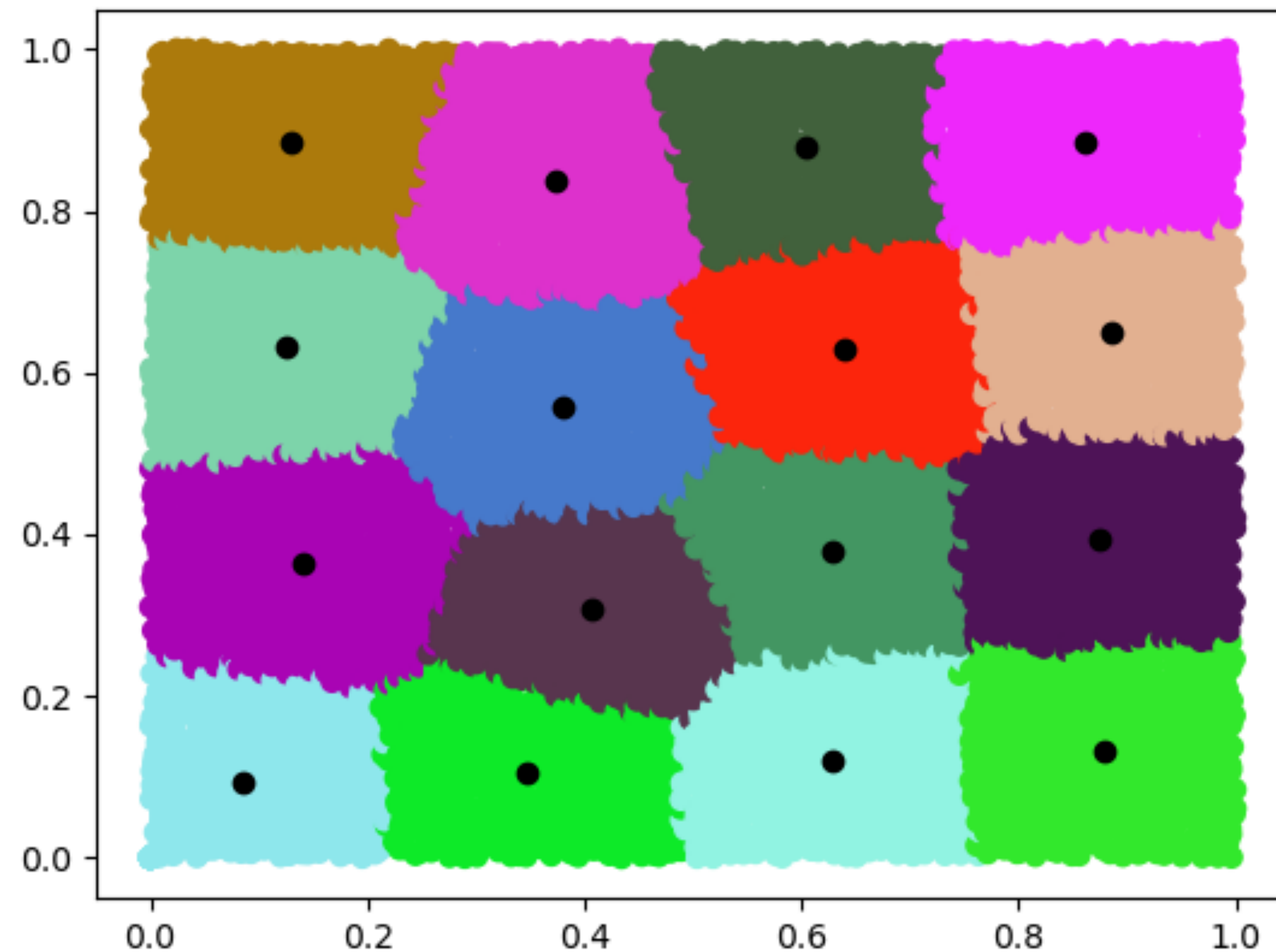
Lloyd-Relaxation Method



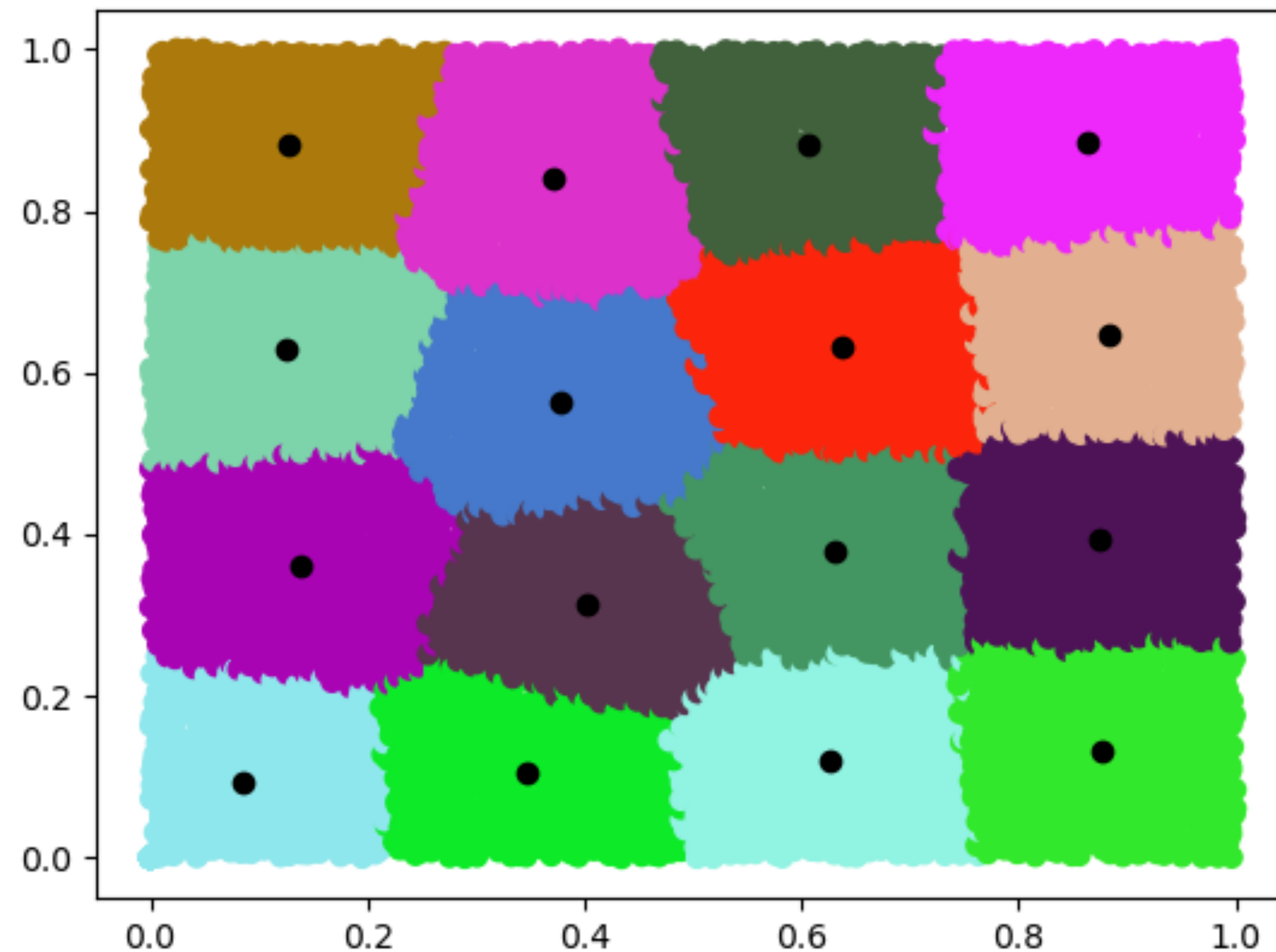
Lloyd-Relaxation Method



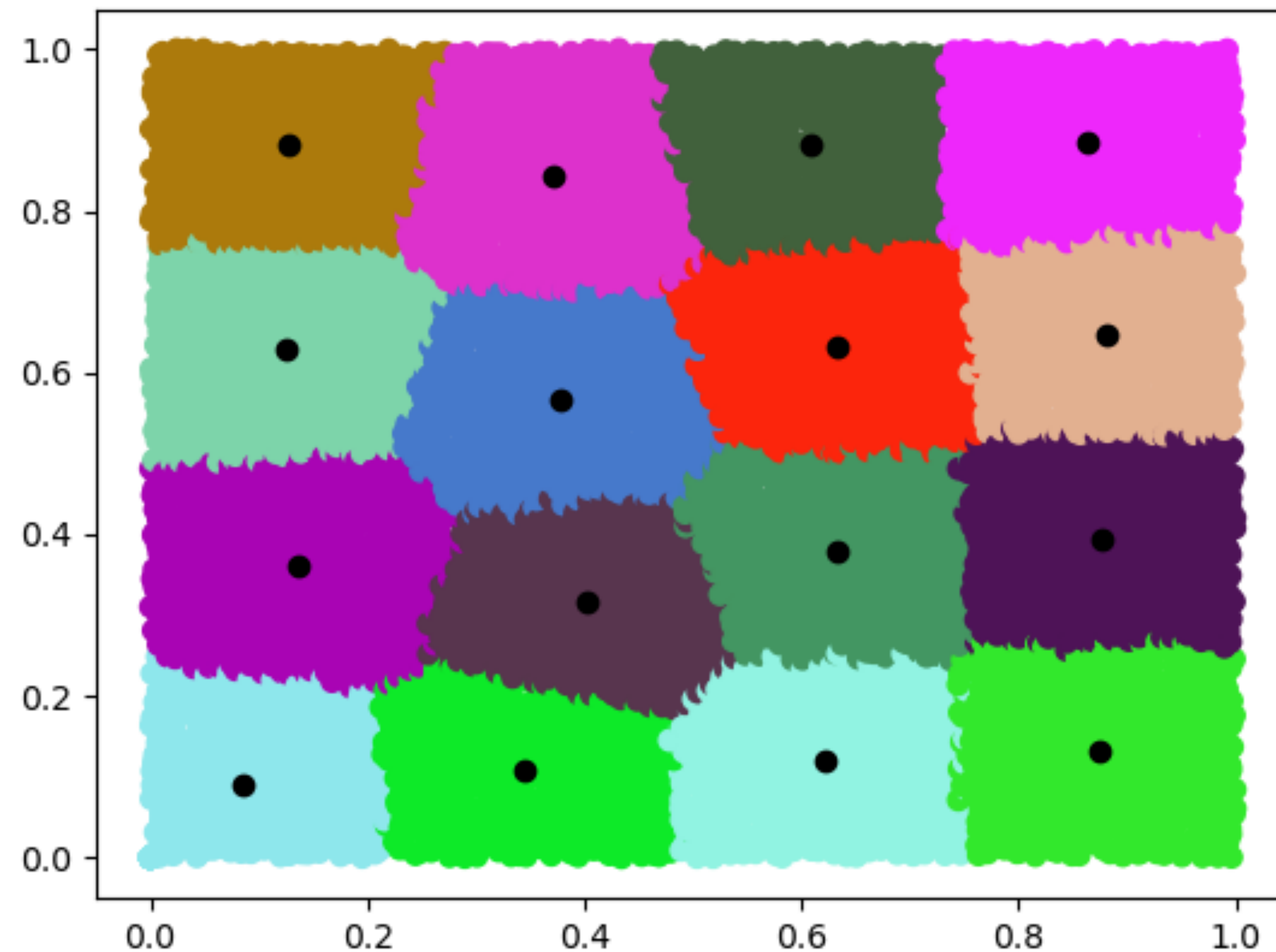
Lloyd-Relaxation Method



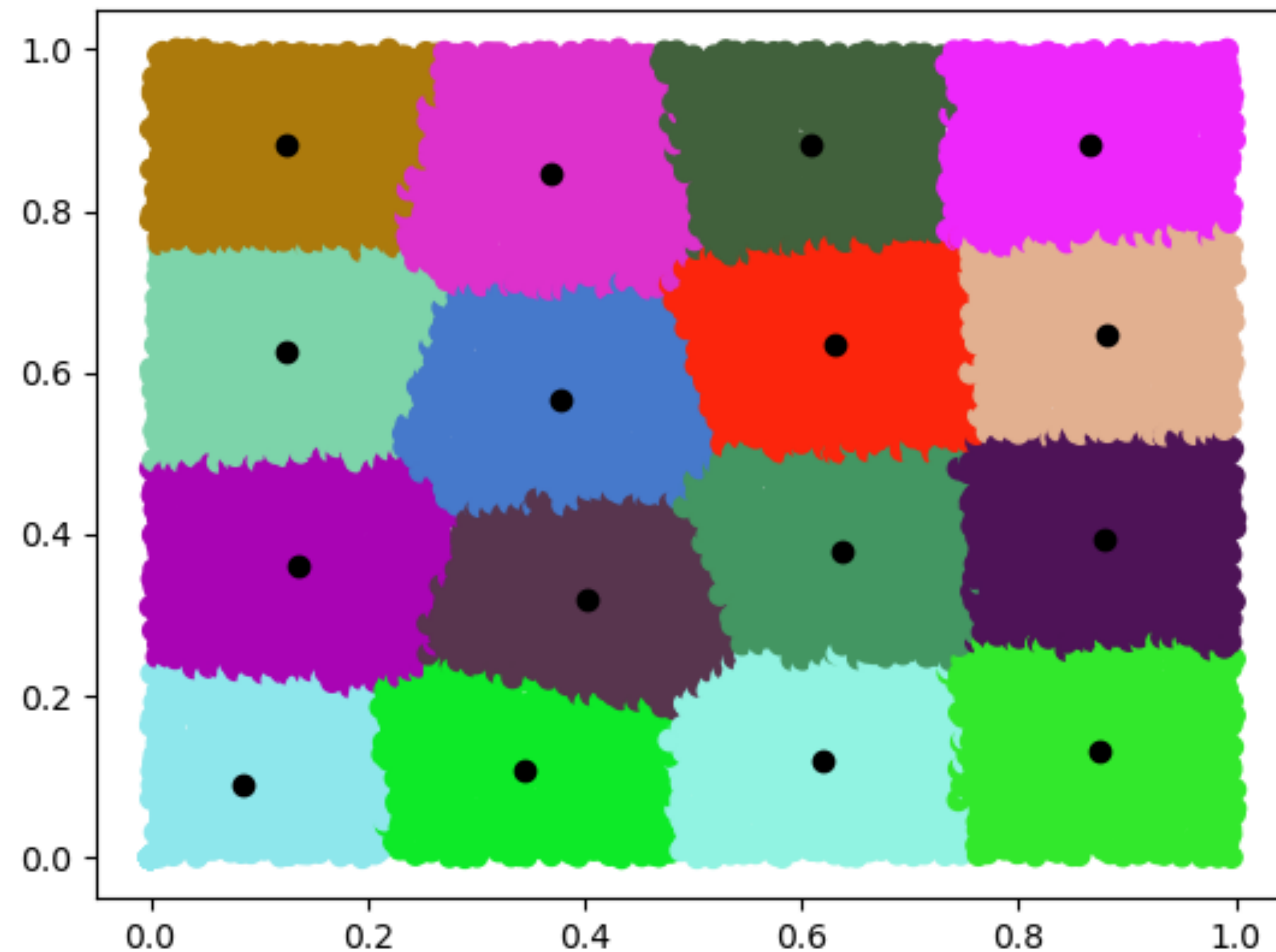
Lloyd-Relaxation Method



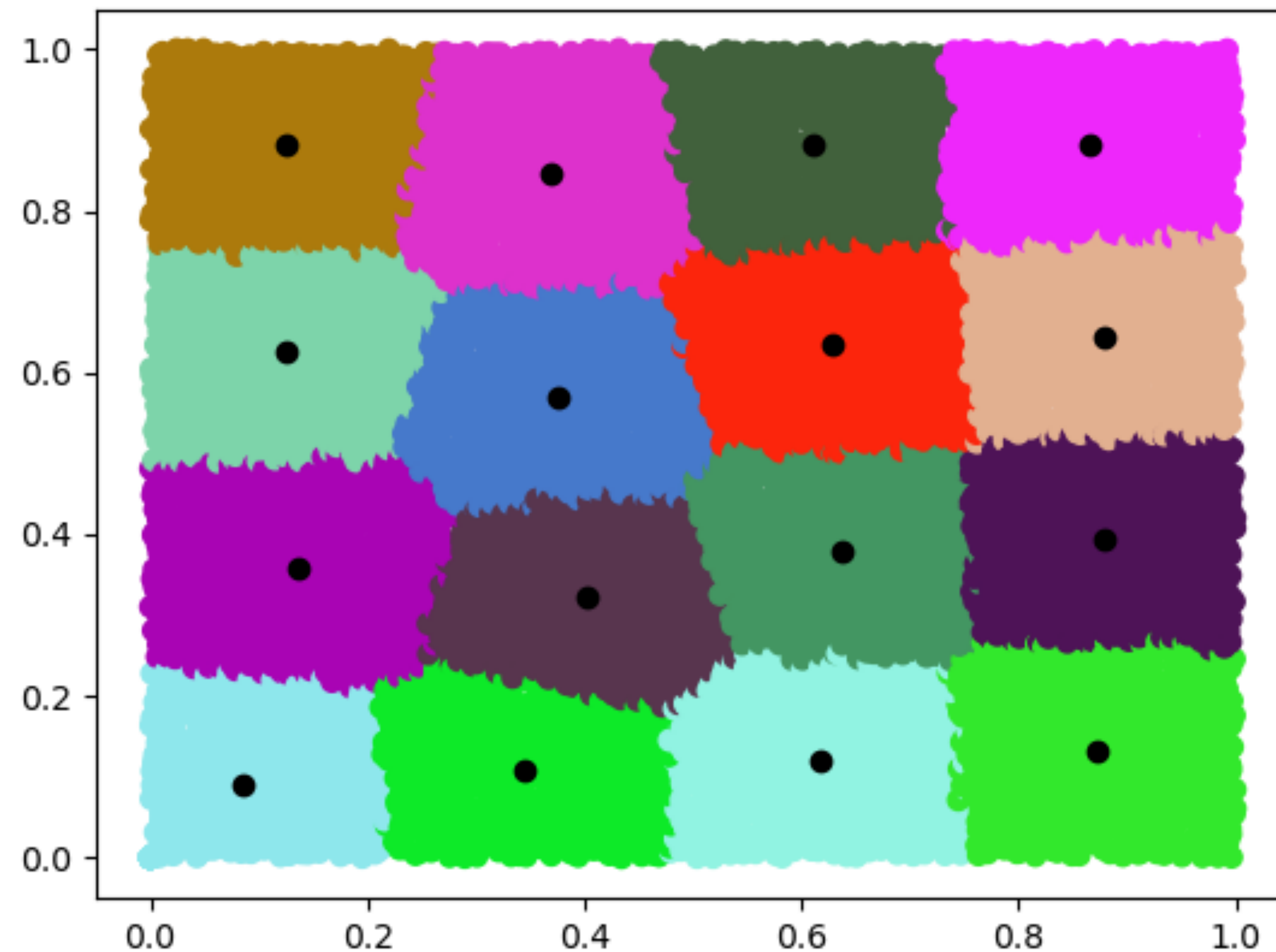
Lloyd-Relaxation Method



Lloyd-Relaxation Method



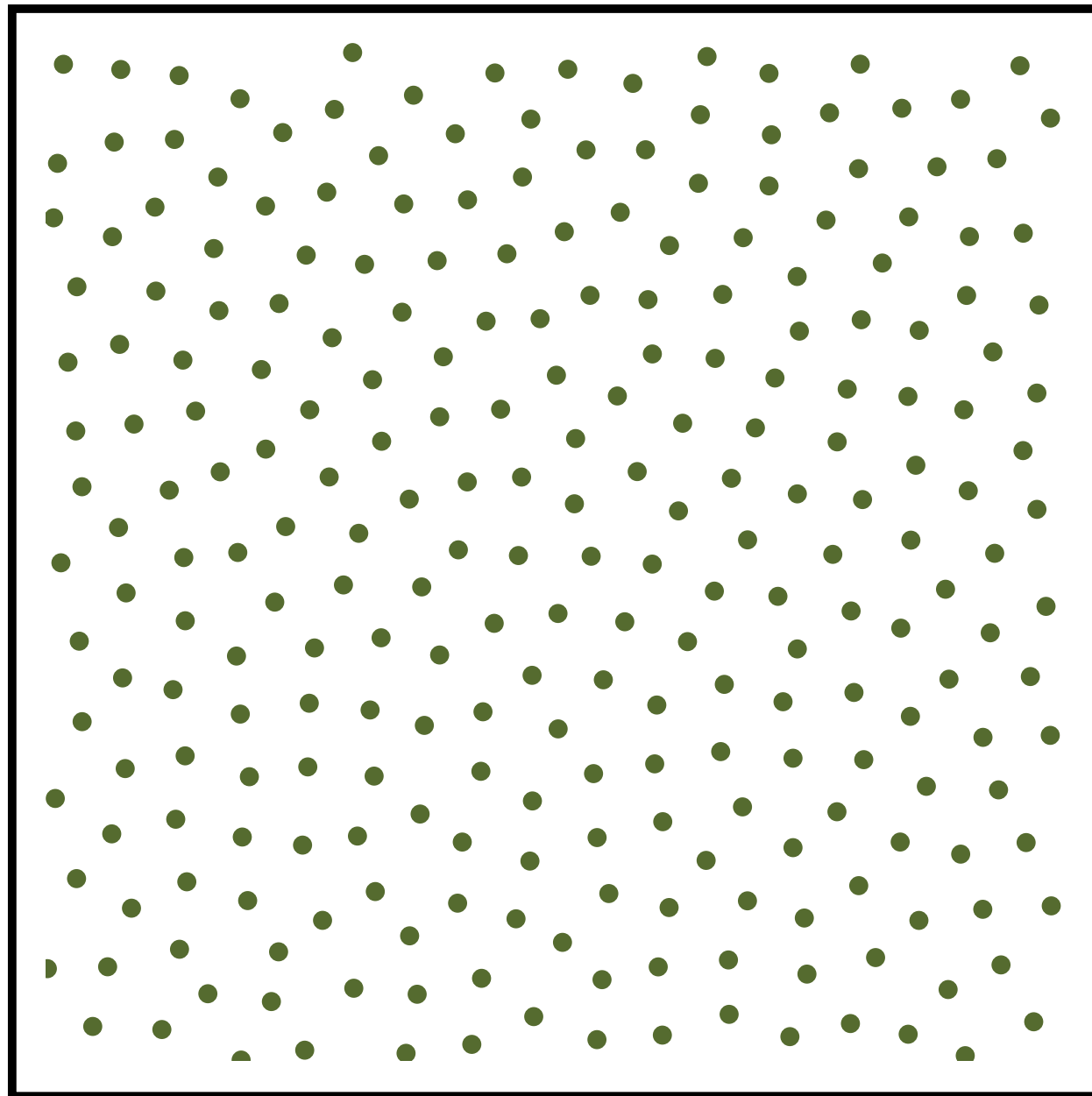
Lloyd-Relaxation Method



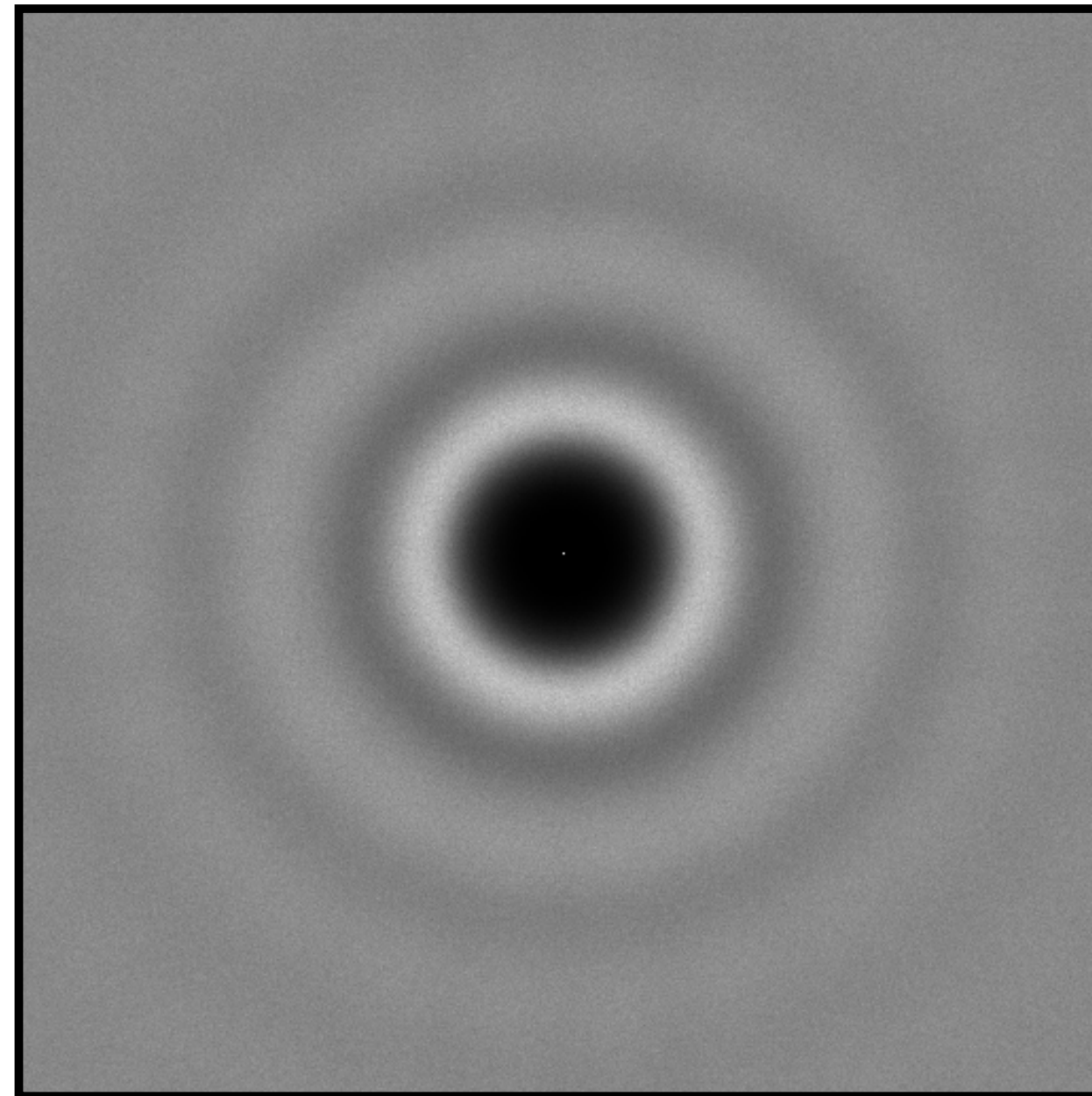
CCVT Sampling [Balzer et al. 2009]

CCVT Sampling [Balzer et al. 2009]

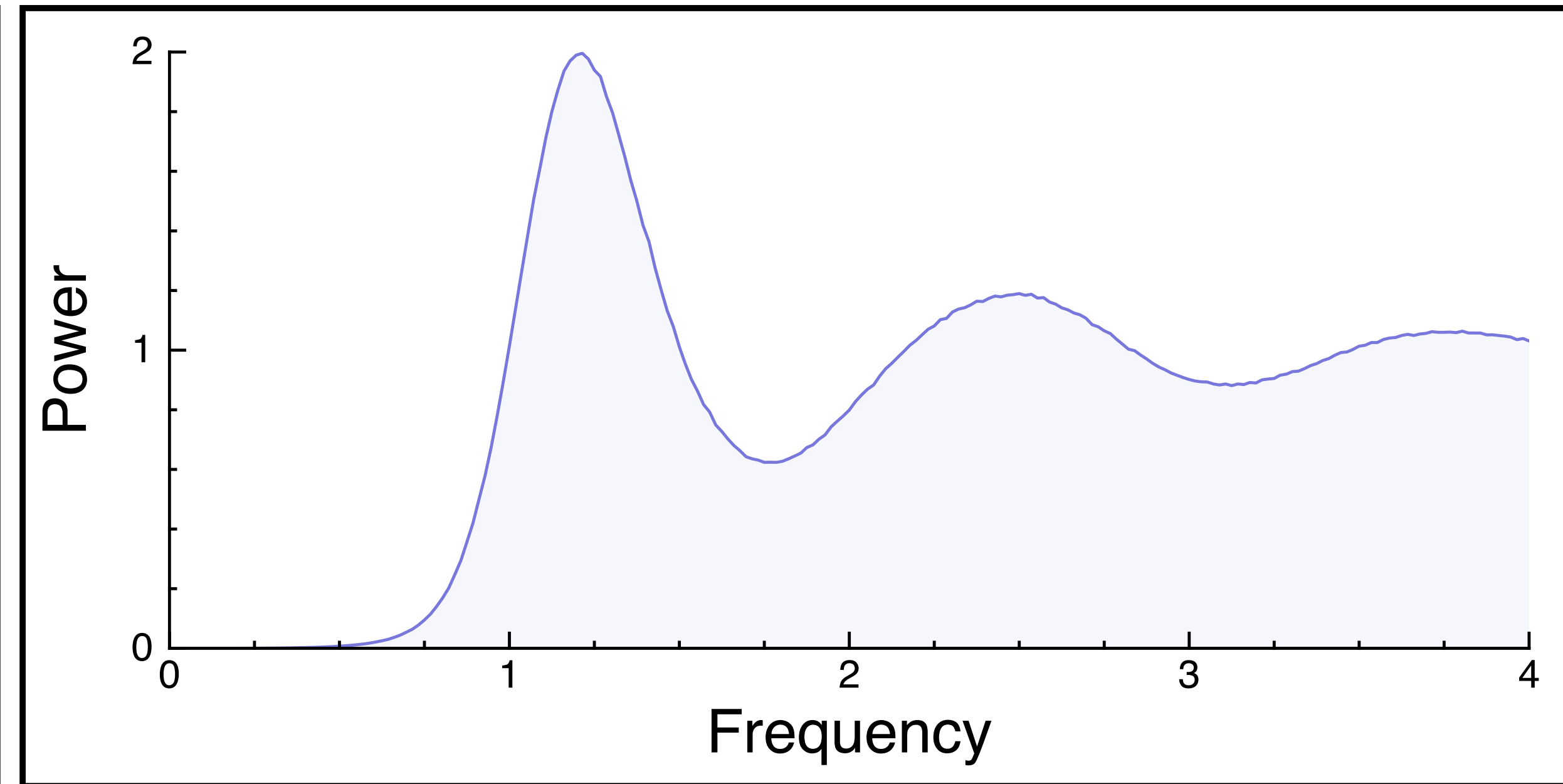
Samples



Expected power spectrum

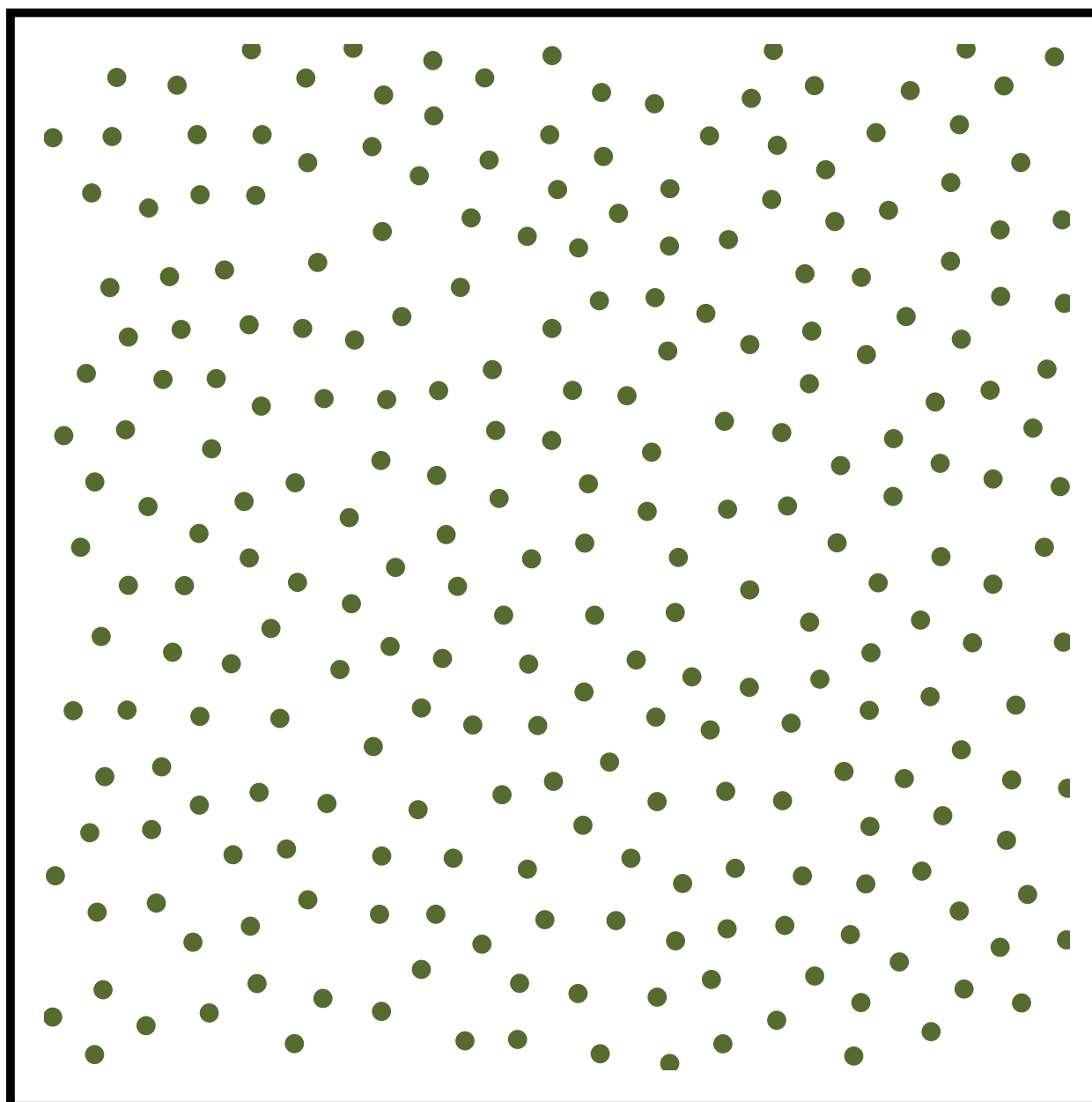


Radial mean

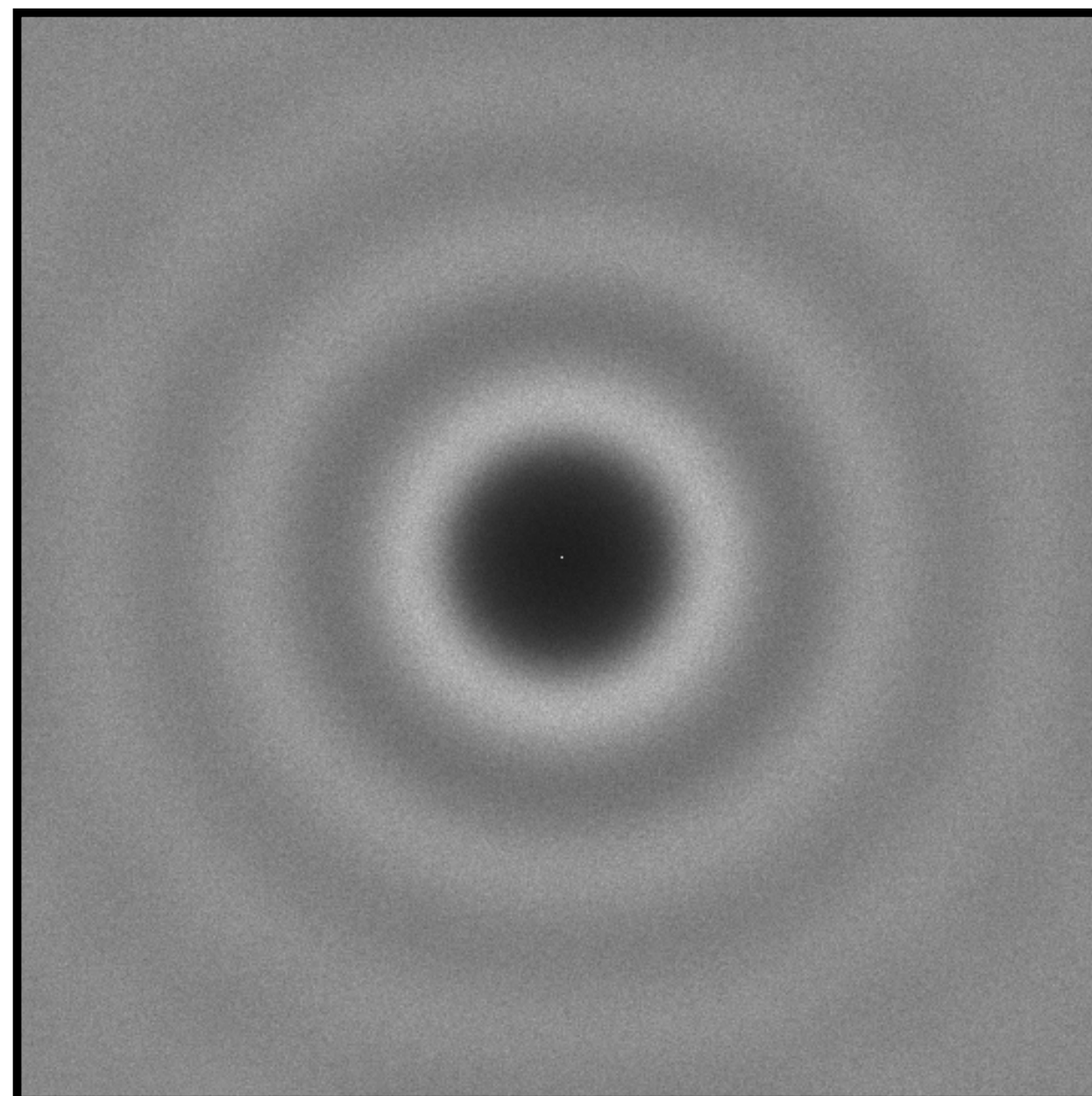


Poisson Disk Sampling

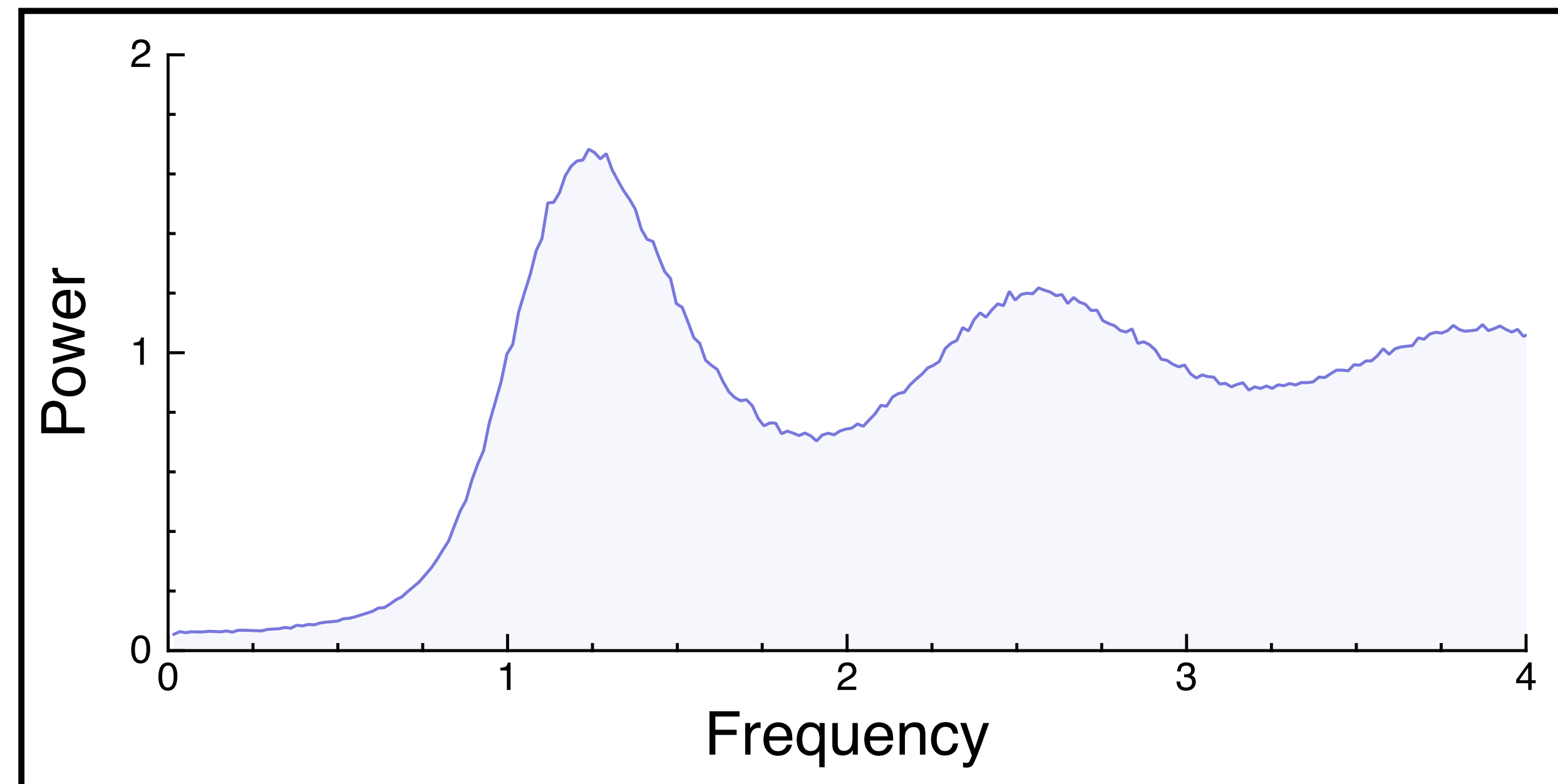
Samples



Expected power spectrum



Radial mean



Low-Discrepancy Sampling

Deterministic sets of points specially crafted to be evenly distributed (have low discrepancy).

Entire field of study called Quasi-Monte Carlo (QMC)

The Van der Corput Sequence

Radical Inverse Φ_b in base 2

k	Base 2	Φ_b
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Subsequent points “fall into
biggest holes”

The Van der Corput Sequence

Radical Inverse Φ_b in base 2

Subsequent points “fall into
biggest holes”

k	Base 2	Φ_b
1	1	.1 = 1/2

The Van der Corput Sequence

Radical Inverse Φ_b in base 2

Subsequent points “fall into
biggest holes”

k	Base 2	Φ_b
1	1	.1 = 1/2
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The Van der Corput Sequence

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3	11	.11 = 3/4



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biggest holes”

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1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4
4	100	.001 = 1/8



The Van der Corput Sequence

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3	11	.11 = 3/4
4	100	.001 = 1/8
5	101	.101 = 5/8
6	110	.011 = 3/8

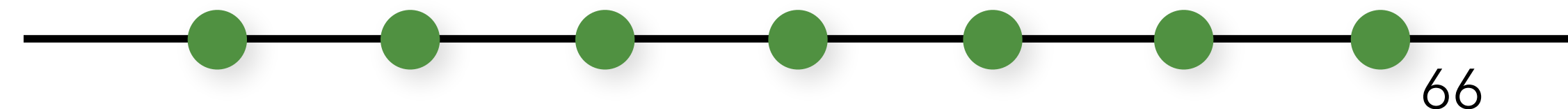


The Van der Corput Sequence

Radical Inverse Φ_b in base 2

Subsequent points “fall into biggest holes”

k	Base 2	Φ_b
1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4
4	100	.001 = 1/8
5	101	.101 = 5/8
6	110	.011 = 3/8
7	111	.111 = 7/8

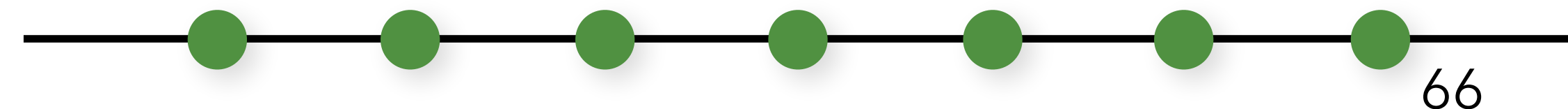


The Van der Corput Sequence

Radical Inverse Φ_b in base 2

Subsequent points “fall into
biggest holes”

k	Base 2	Φ_b
1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4
4	100	.001 = 1/8
5	101	.101 = 5/8
6	110	.011 = 3/8
7	111	.111 = 7/8
...		



Halton and Hammersley Points

Halton: Radical inverse with different base for each dimension:

$$\vec{x}_k = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$$

Halton and Hammersley Points

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- The bases should all be relatively prime.

Halton and Hammersley Points

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Hammersley: Same as Halton, but first dimension is k/N :

$$\vec{x}_k = (k/N, \Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$$

Halton and Hammersley Points

Halton: Radical inverse with different base for each dimension:

$$\vec{x}_k = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$$

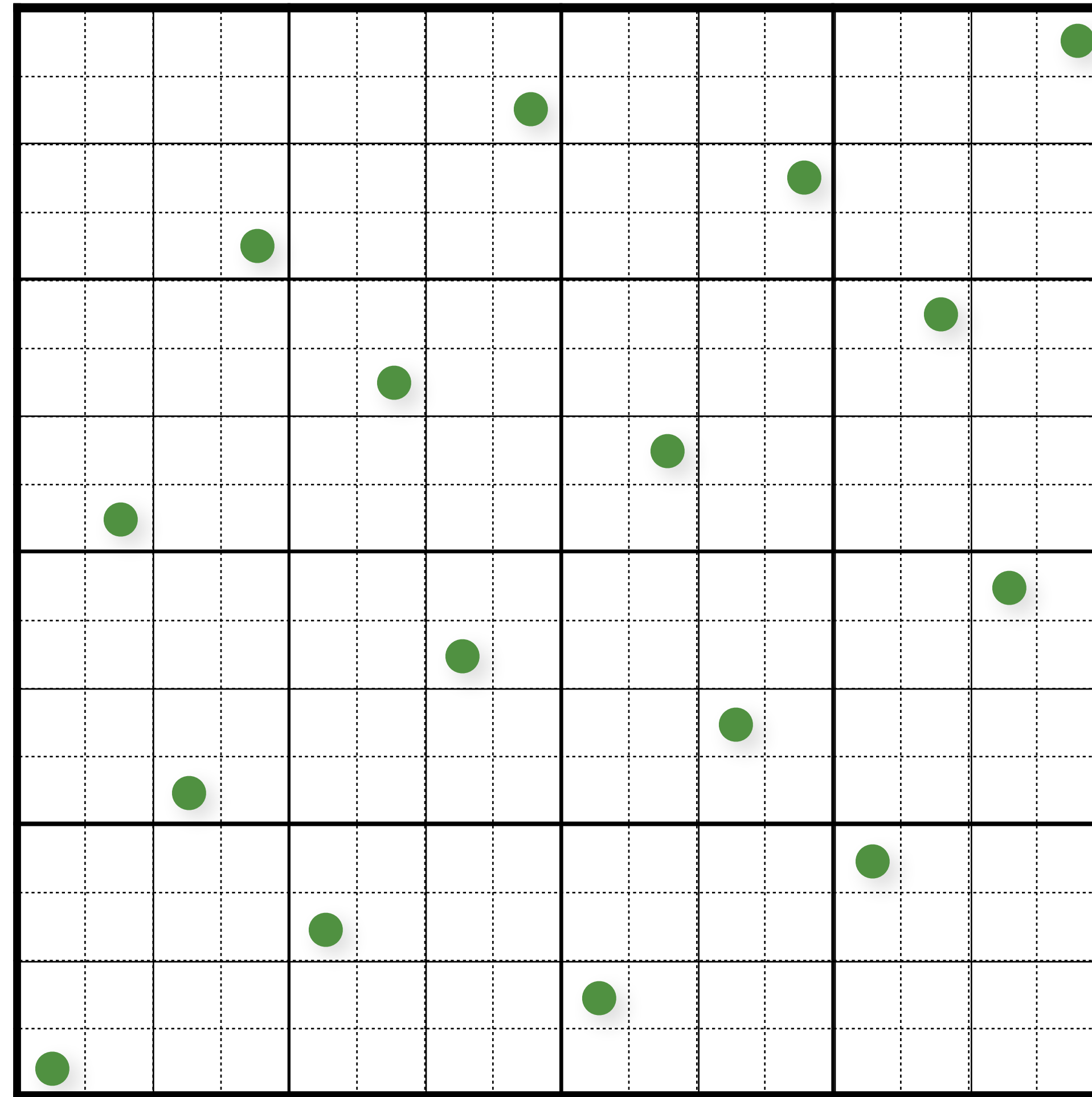
- The bases should all be relatively prime.
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Hammersley: Same as Halton, but first dimension is k/N :

$$\vec{x}_k = (k/N, \Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$$

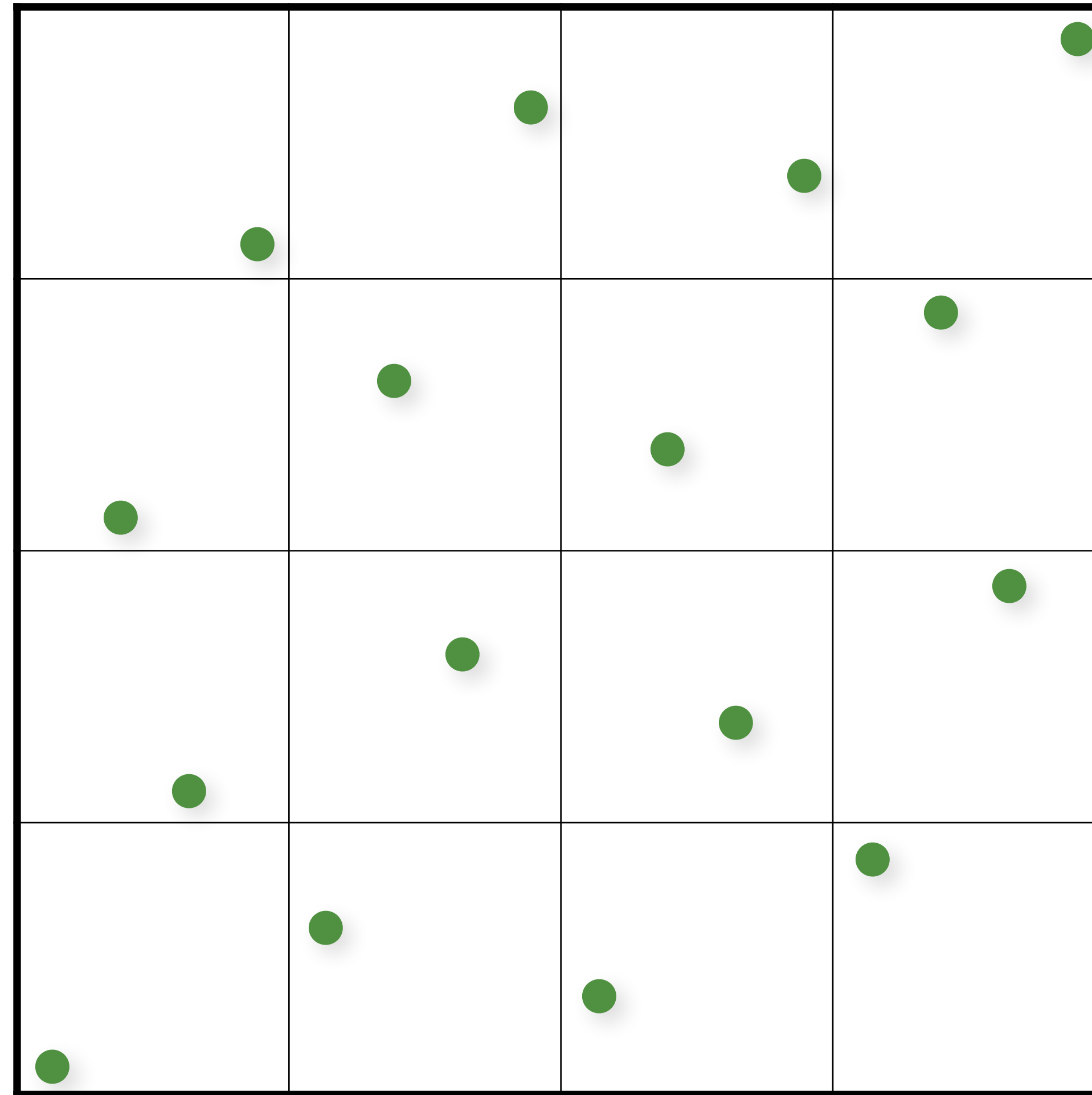
- Not incremental, need to know sample count, N , in advance

The Hammersley Sequence



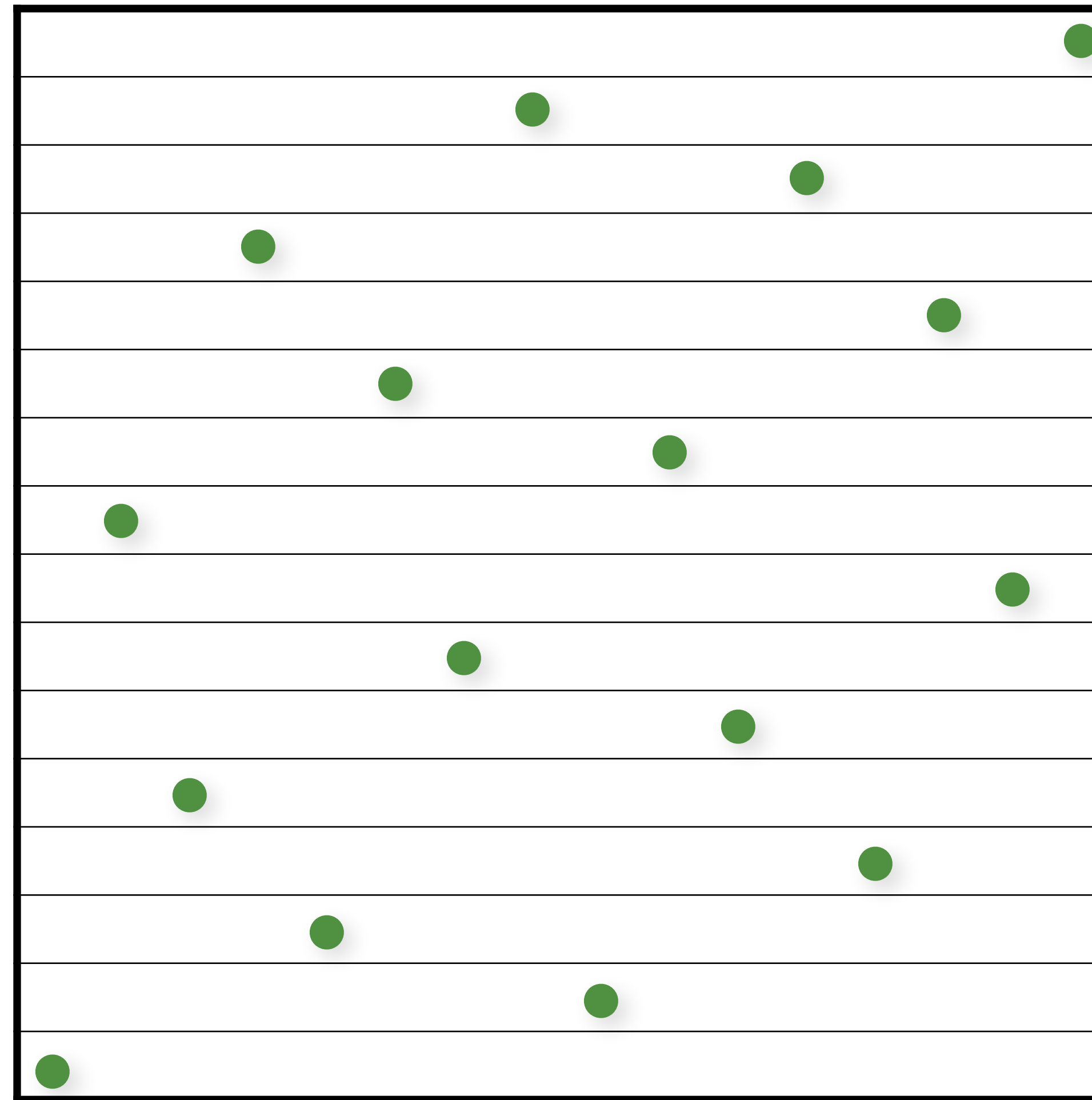
1 sample in each "elementary interval"

The Hammersley Sequence



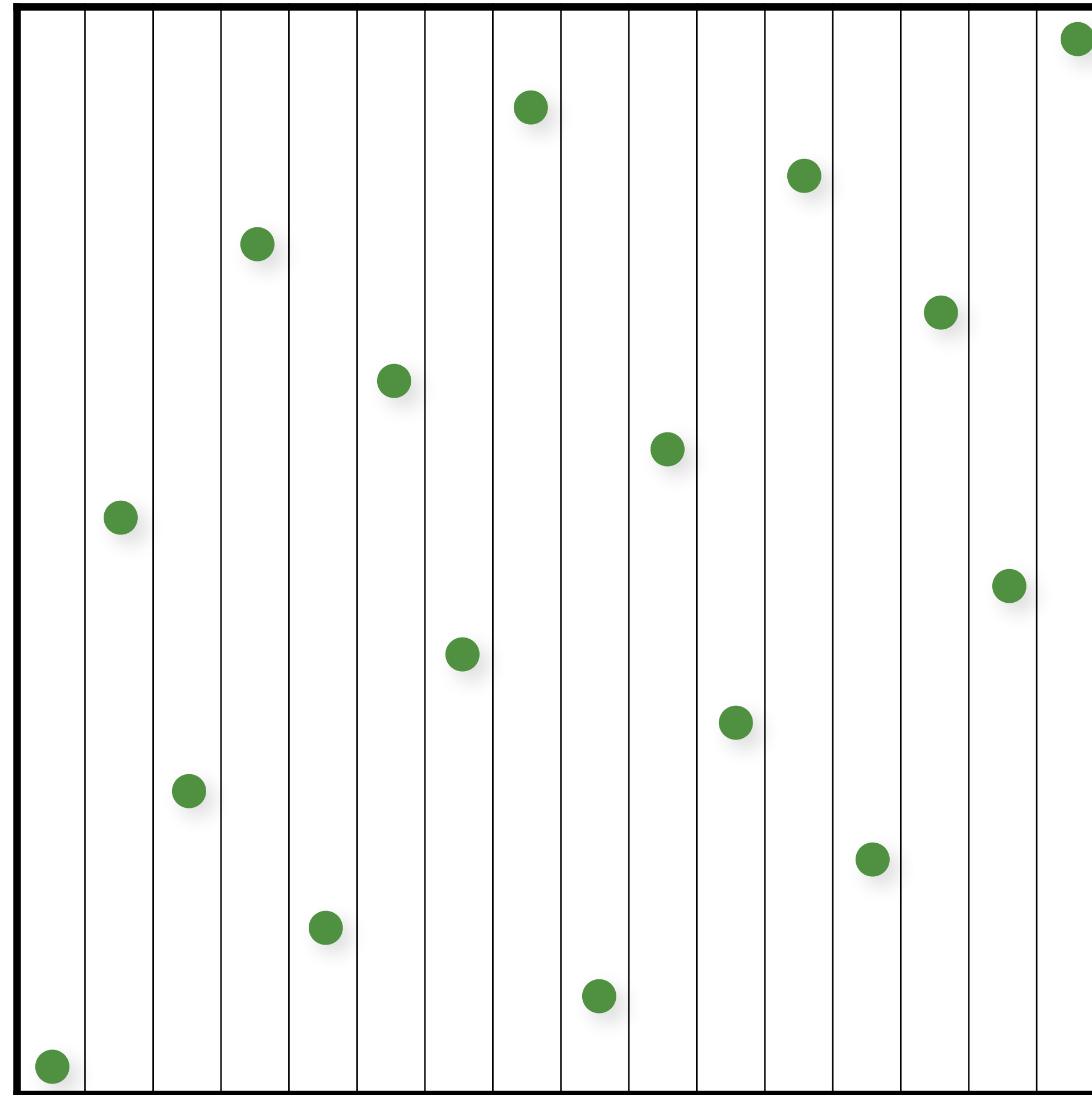
1 sample in each "elementary interval"

The Hammersley Sequence



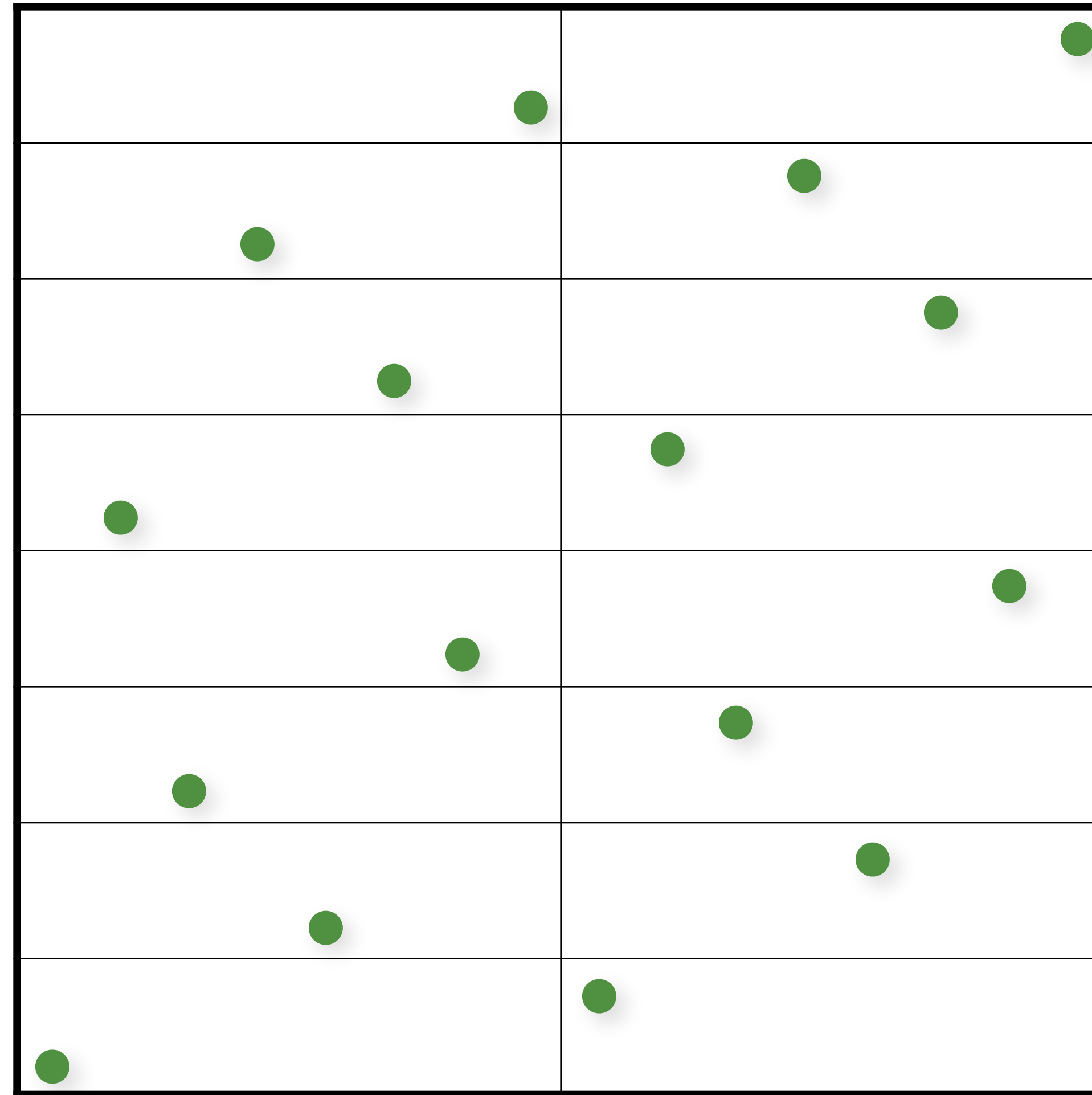
1 sample in each "elementary interval"

The Hammersley Sequence



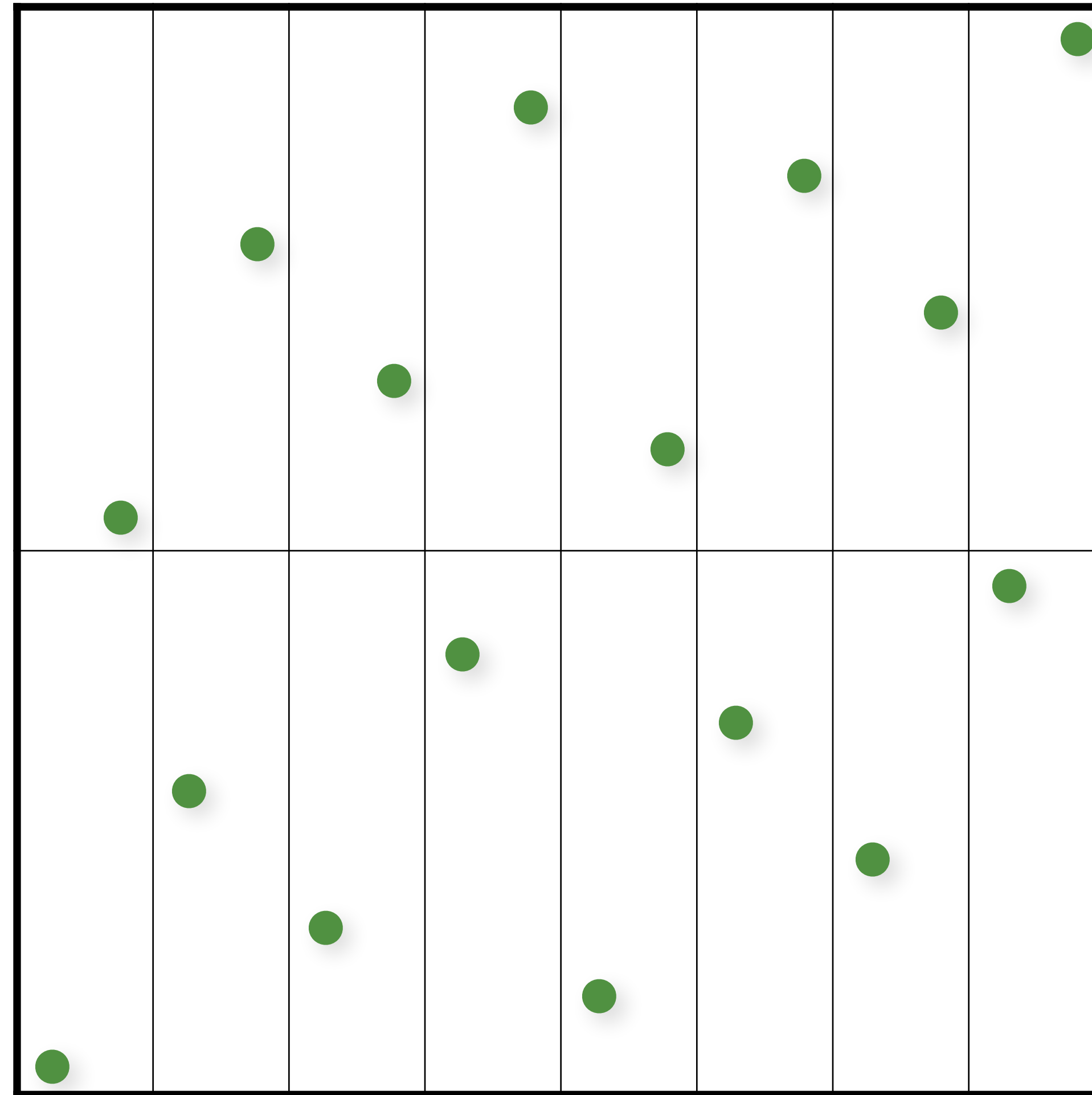
1 sample in each "elementary interval"

The Hammersley Sequence



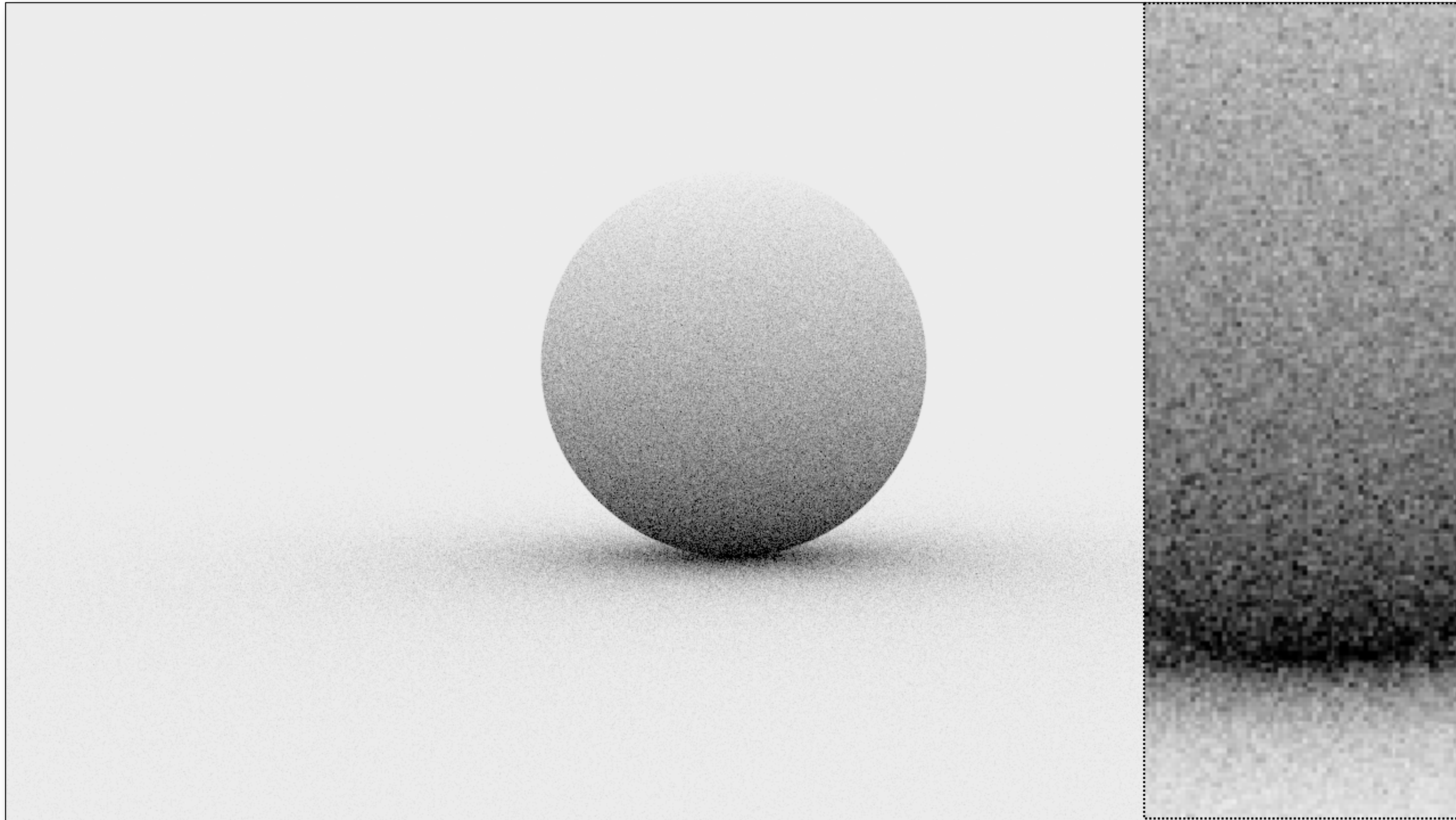
1 sample in each "elementary interval"

The Hammersley Sequence

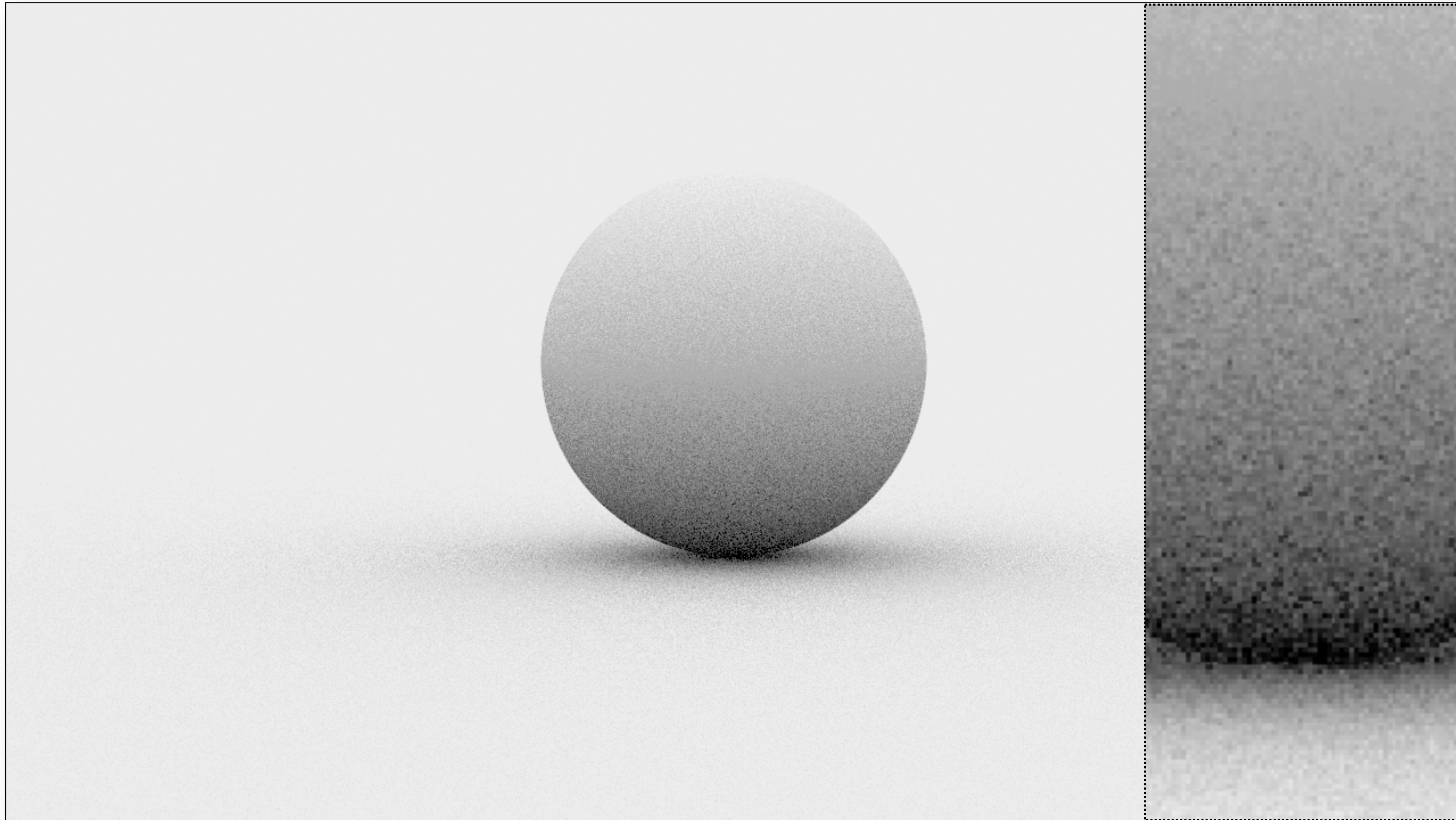


1 sample in each "elementary interval"

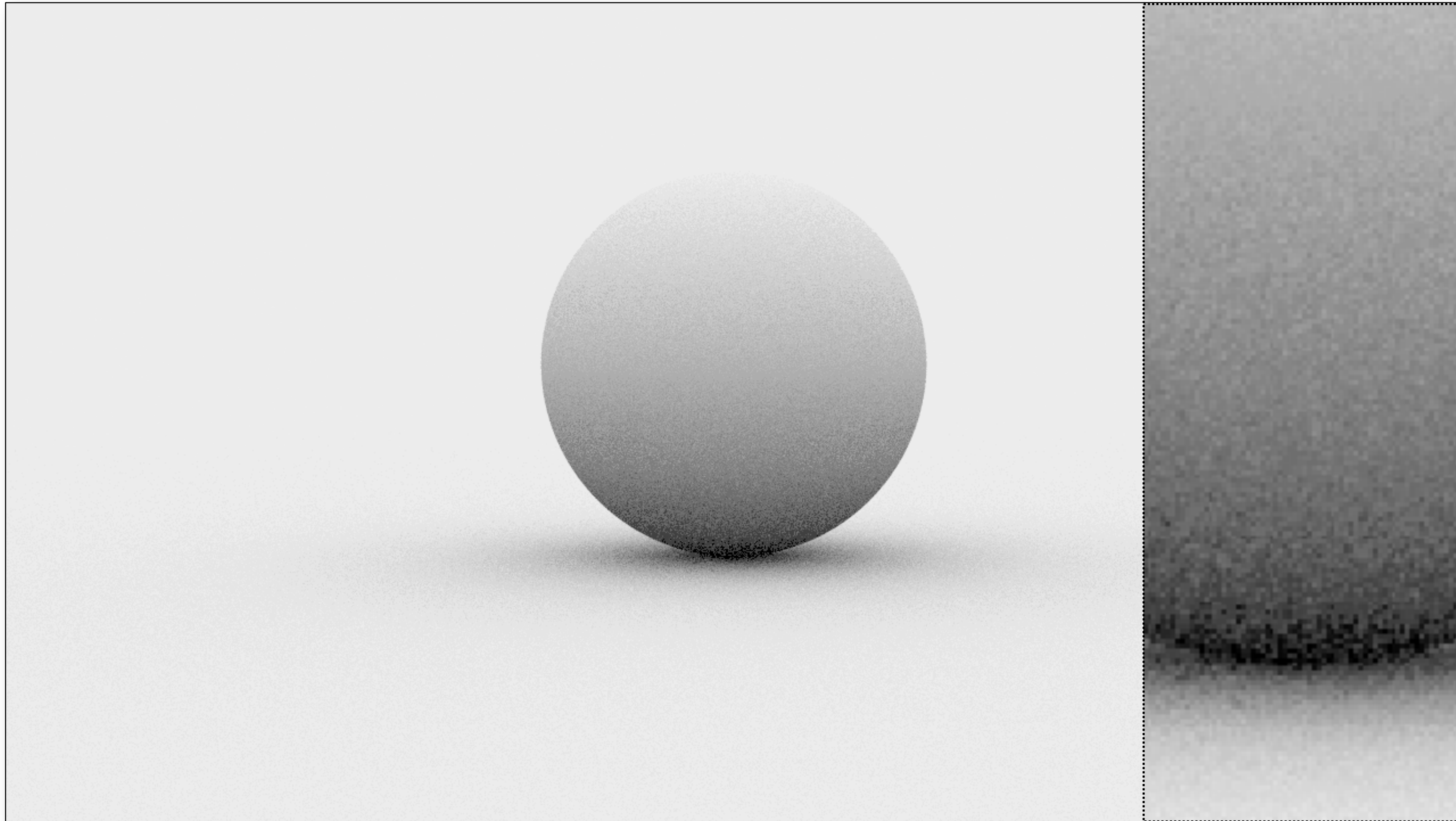
Monte Carlo (16 random samples)



Monte Carlo (16 jittered samples)



Scrambled Low-Discrepancy Sampling

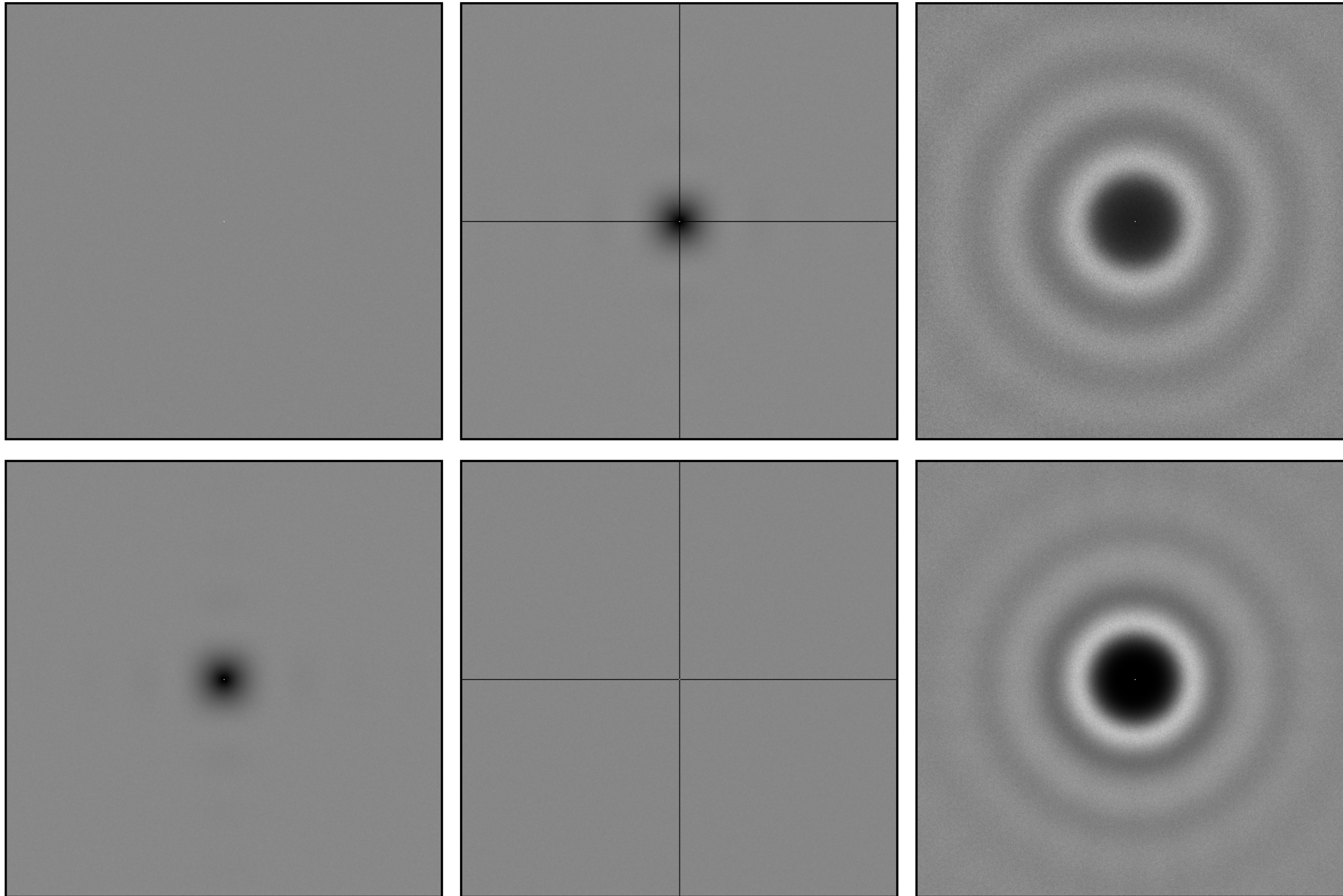


More info on QMC in Rendering

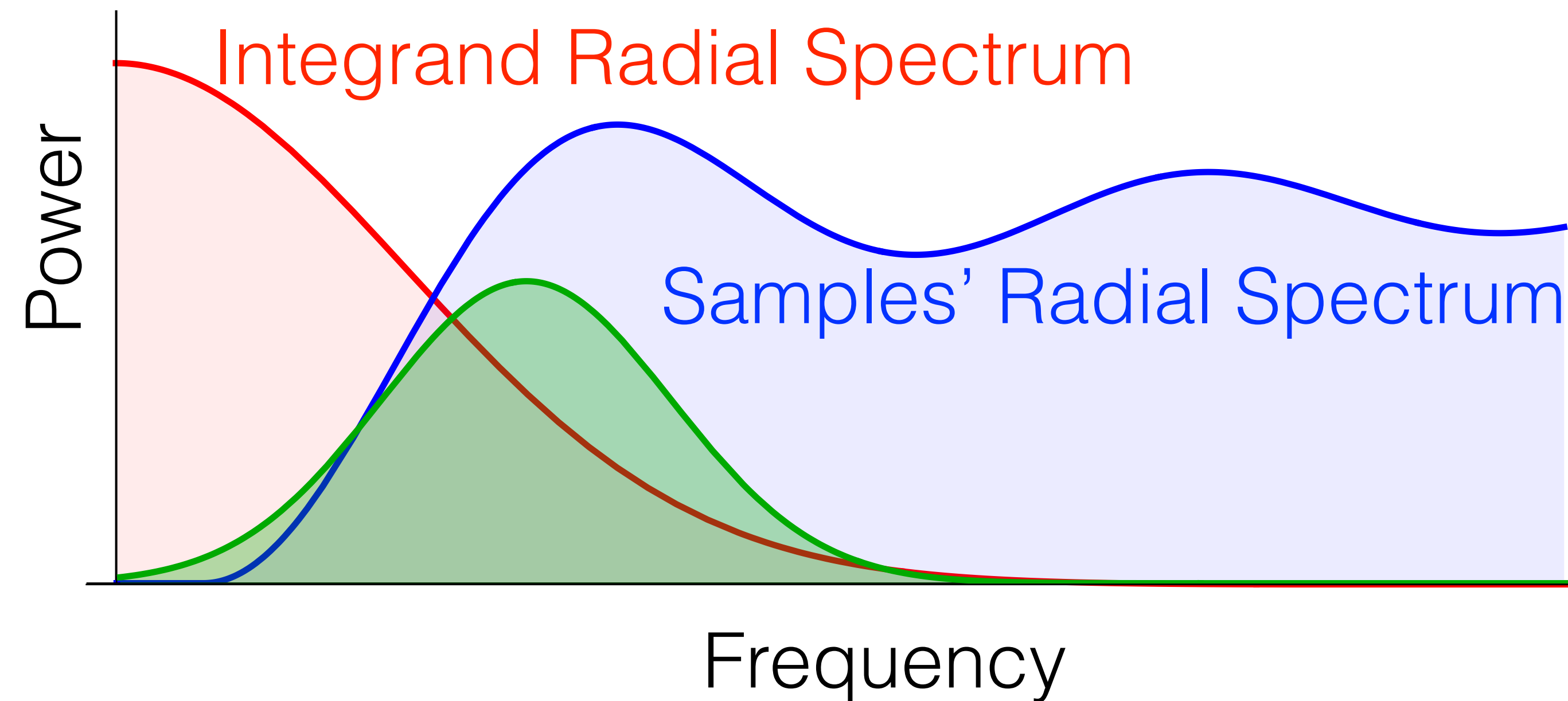
S. Premoze, A. Keller, and M. Raab.

Advanced (Quasi-) Monte Carlo Methods for Image Synthesis.
In SIGGRAPH 2012 courses.

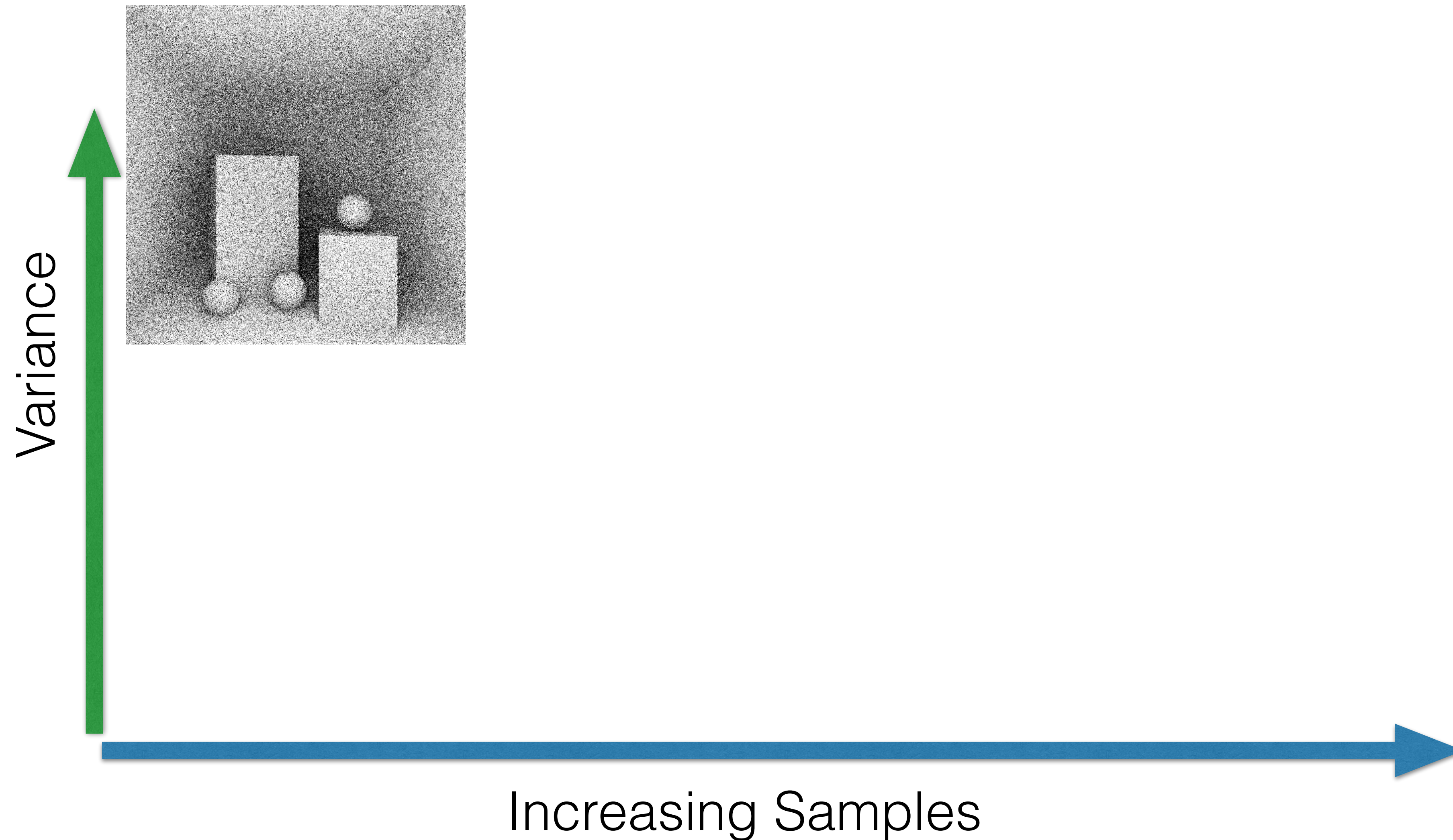
How can we predict error from these?



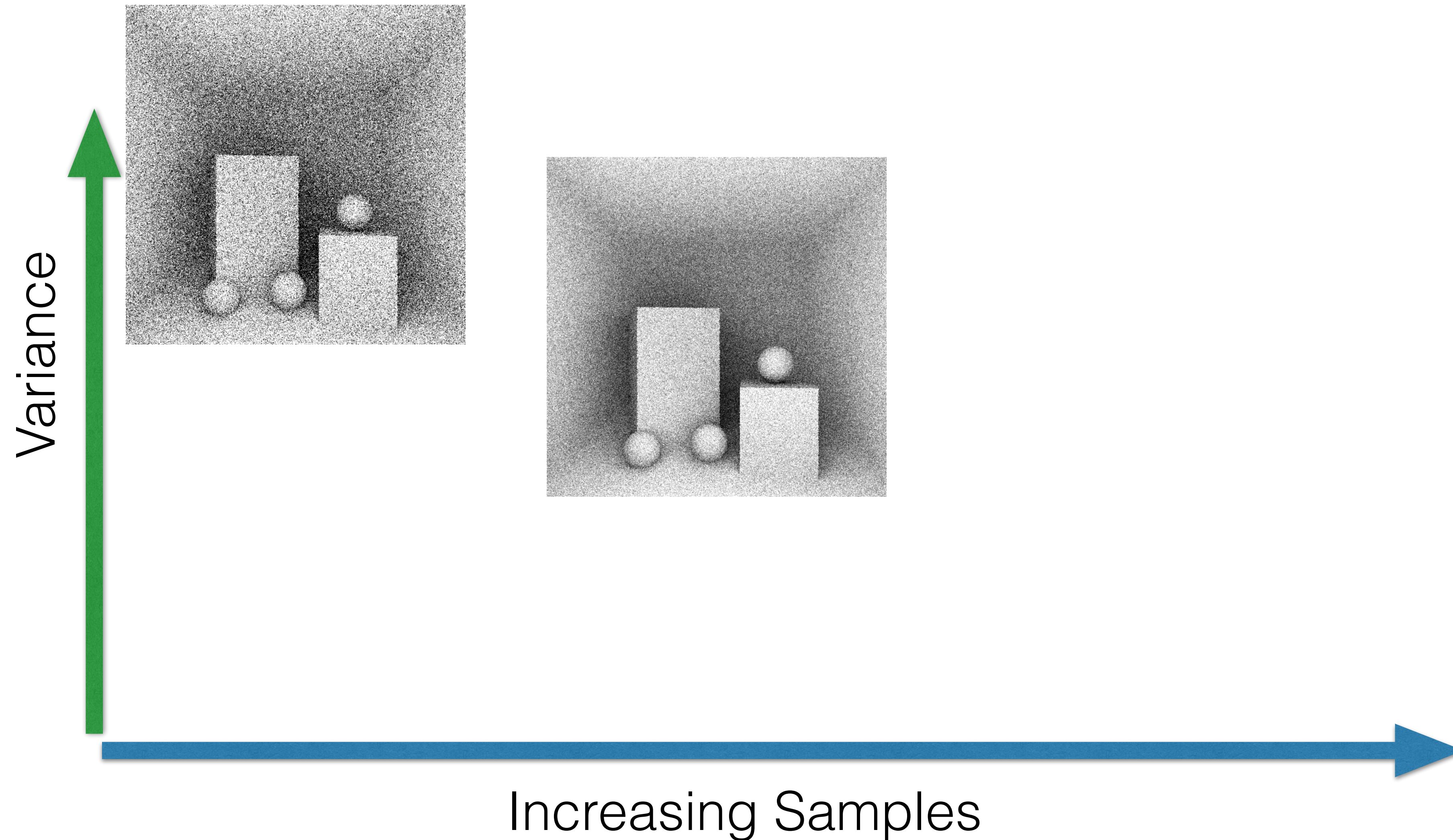
Part 2: Formal Treatment of MSE, Bias and Variance



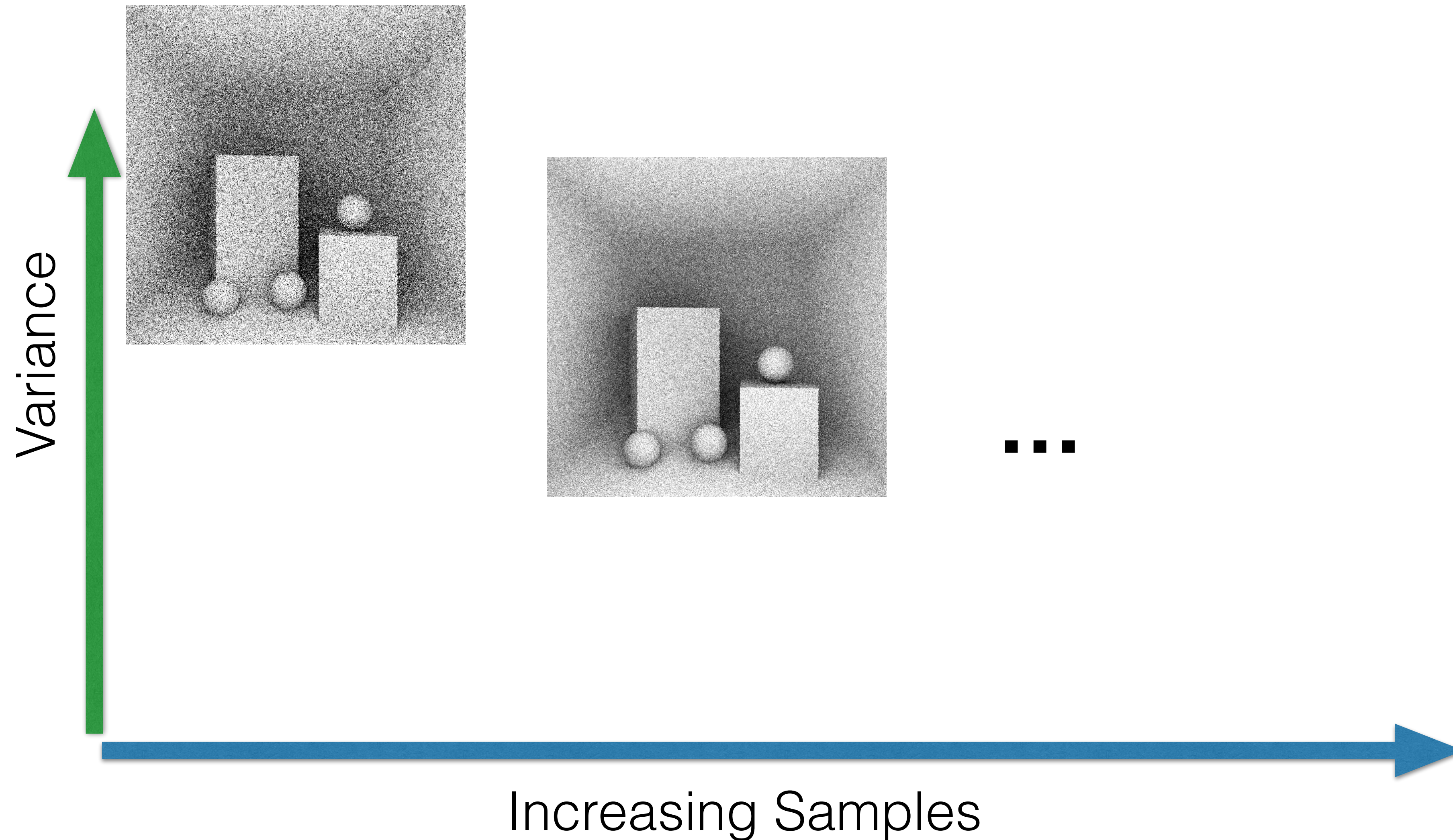
Convergence rate for Random Samples



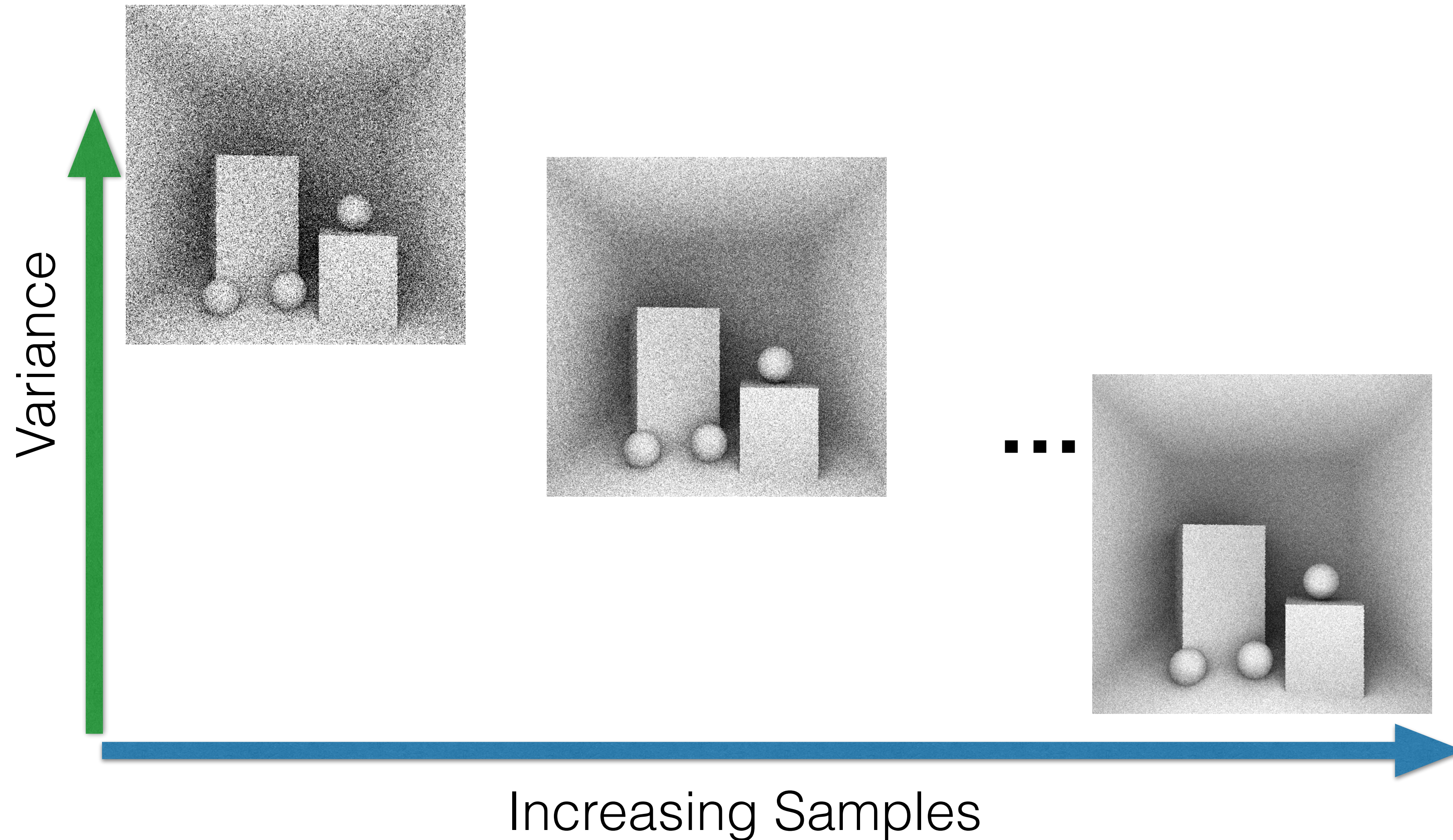
Convergence rate for Random Samples



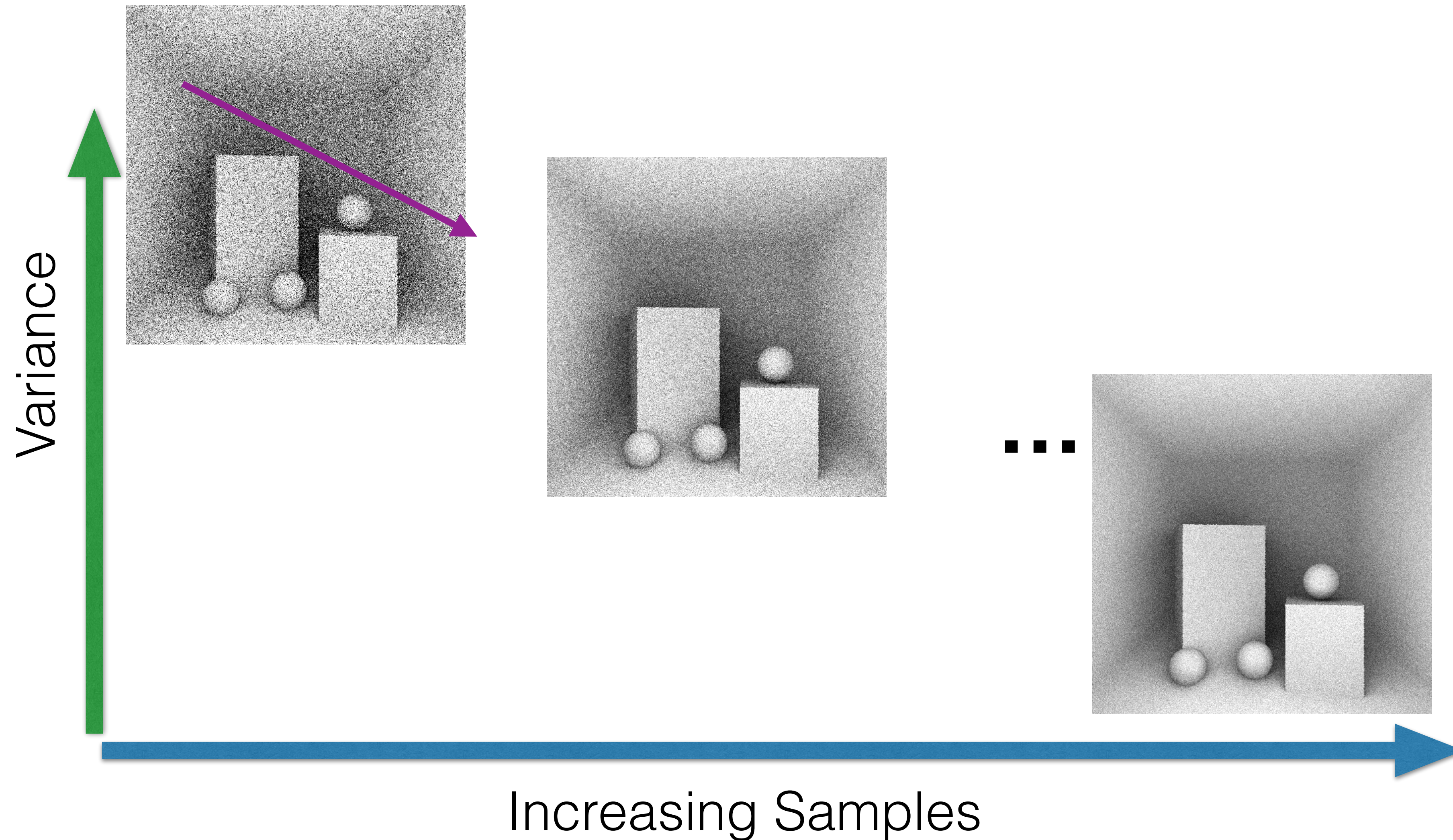
Convergence rate for Random Samples



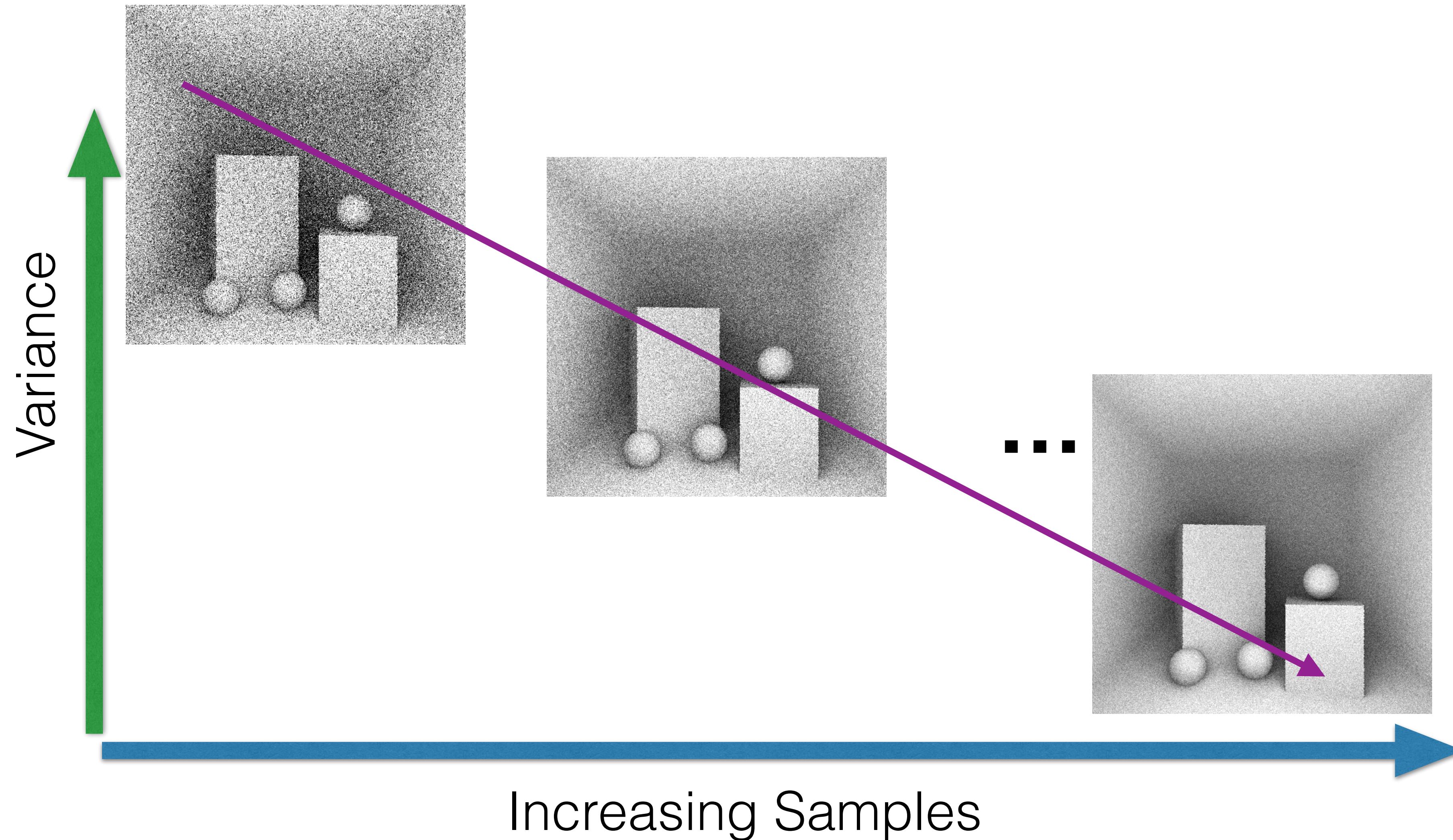
Convergence rate for Random Samples



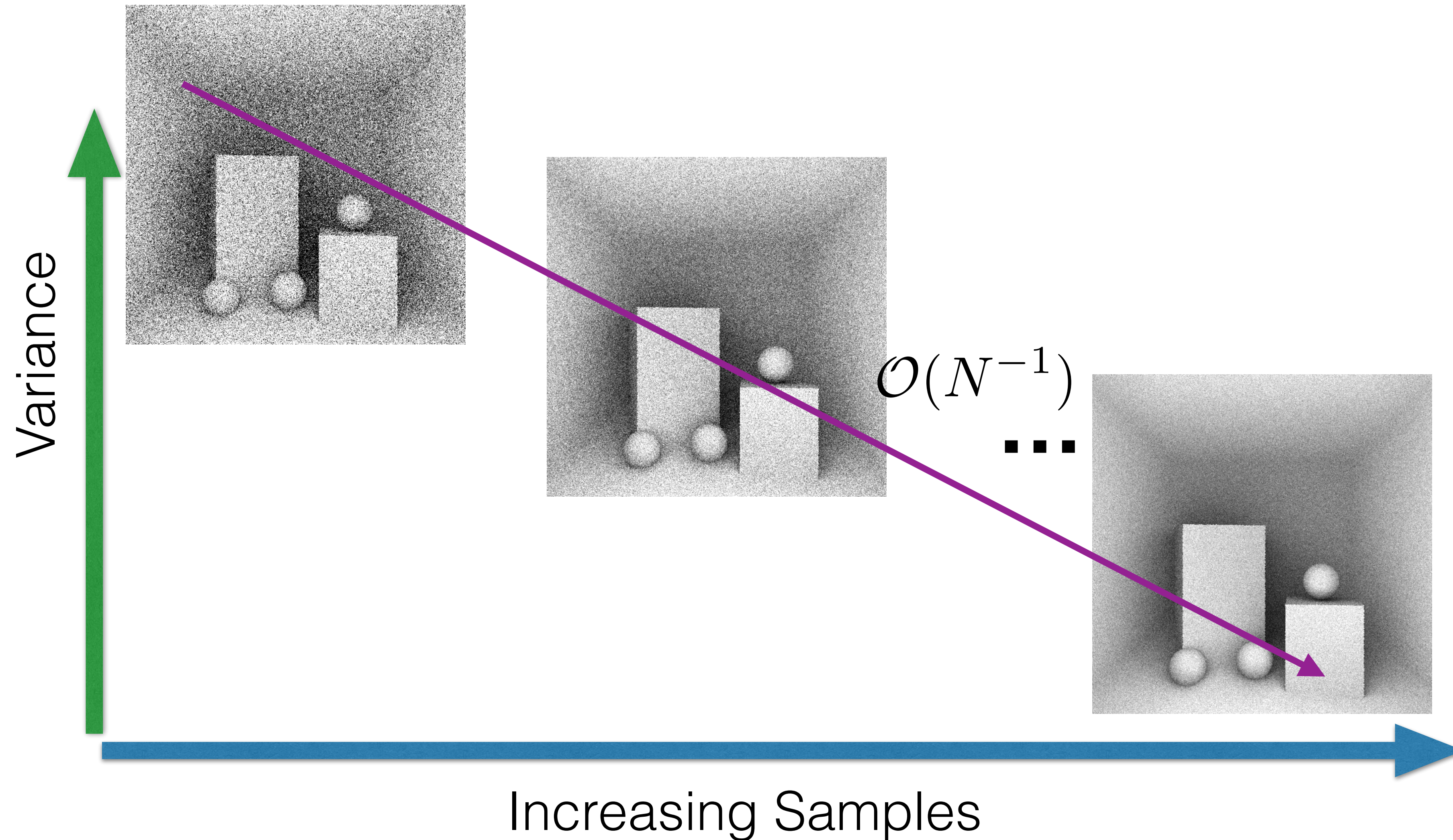
Convergence rate for Random Samples



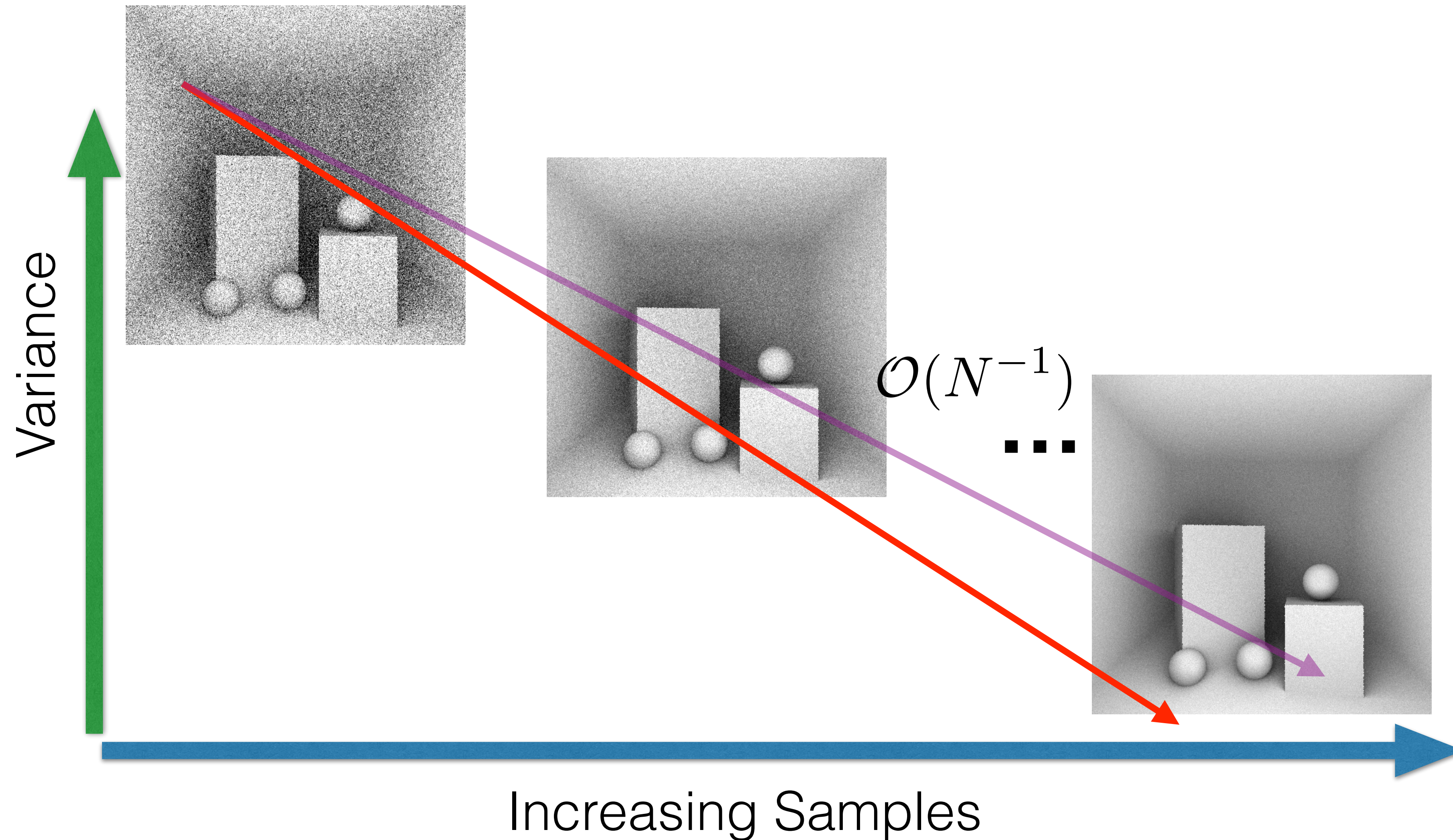
Convergence rate for Random Samples



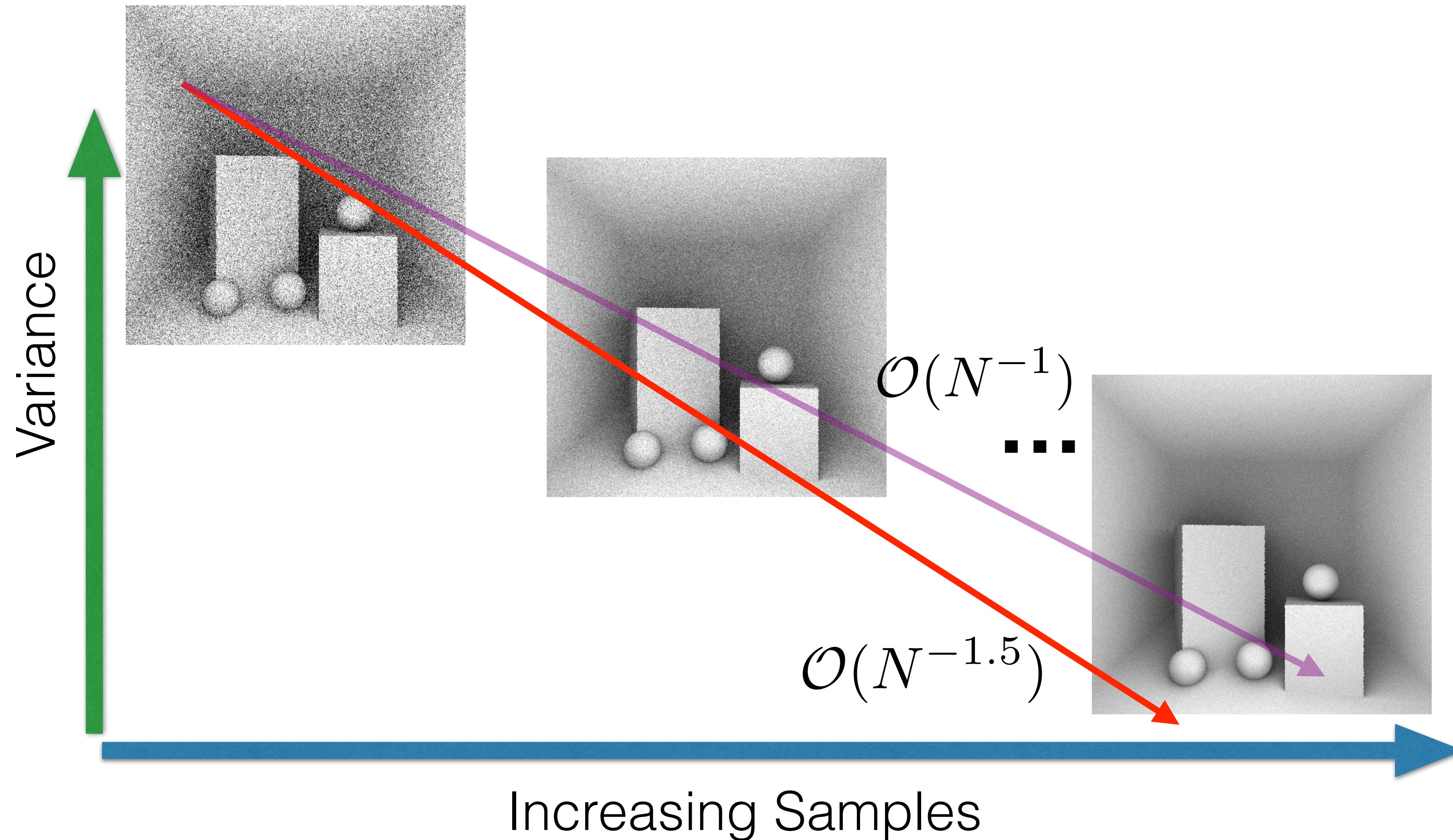
Convergence rate for Random Samples



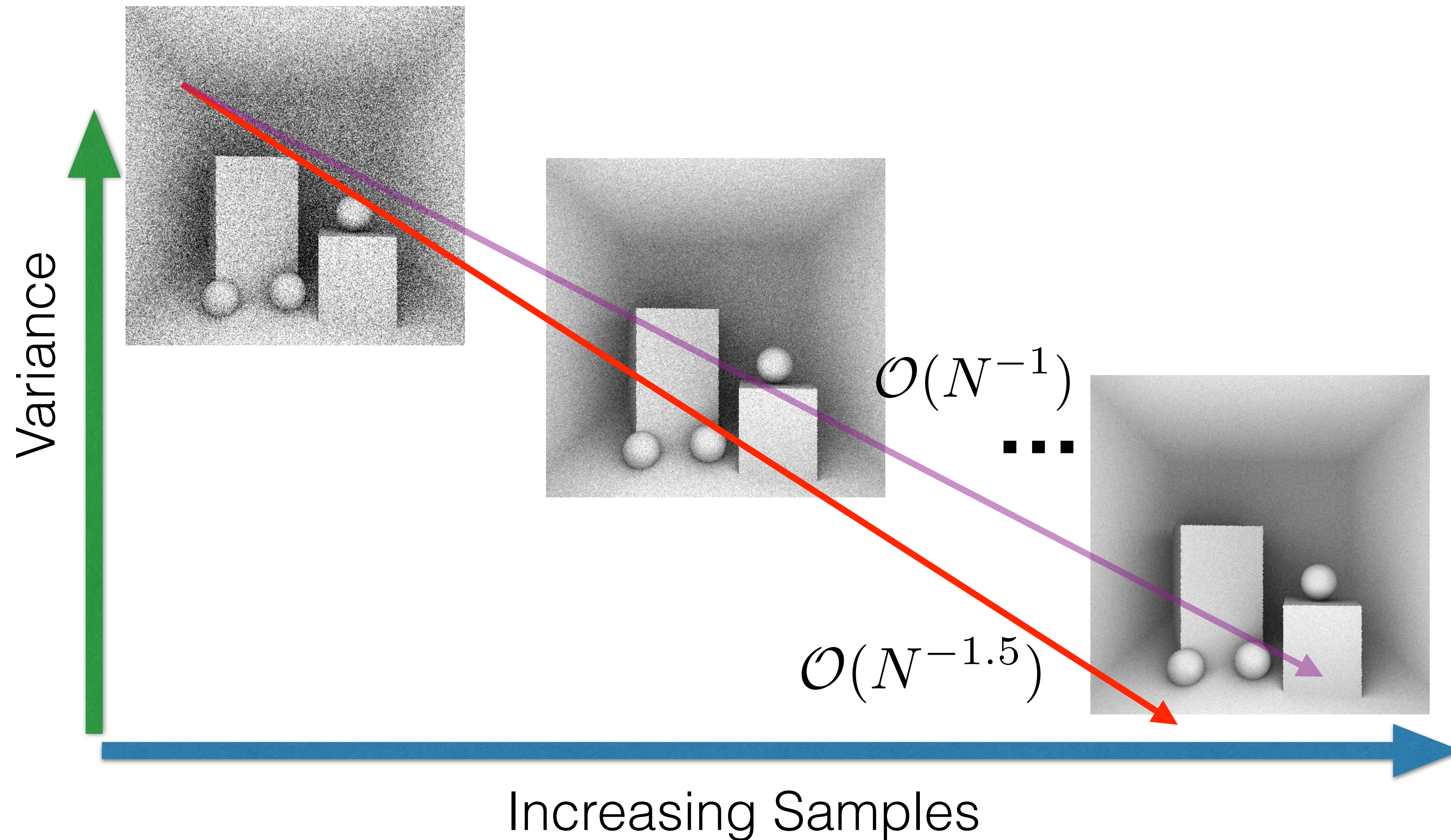
Convergence rate for Jittered Samples



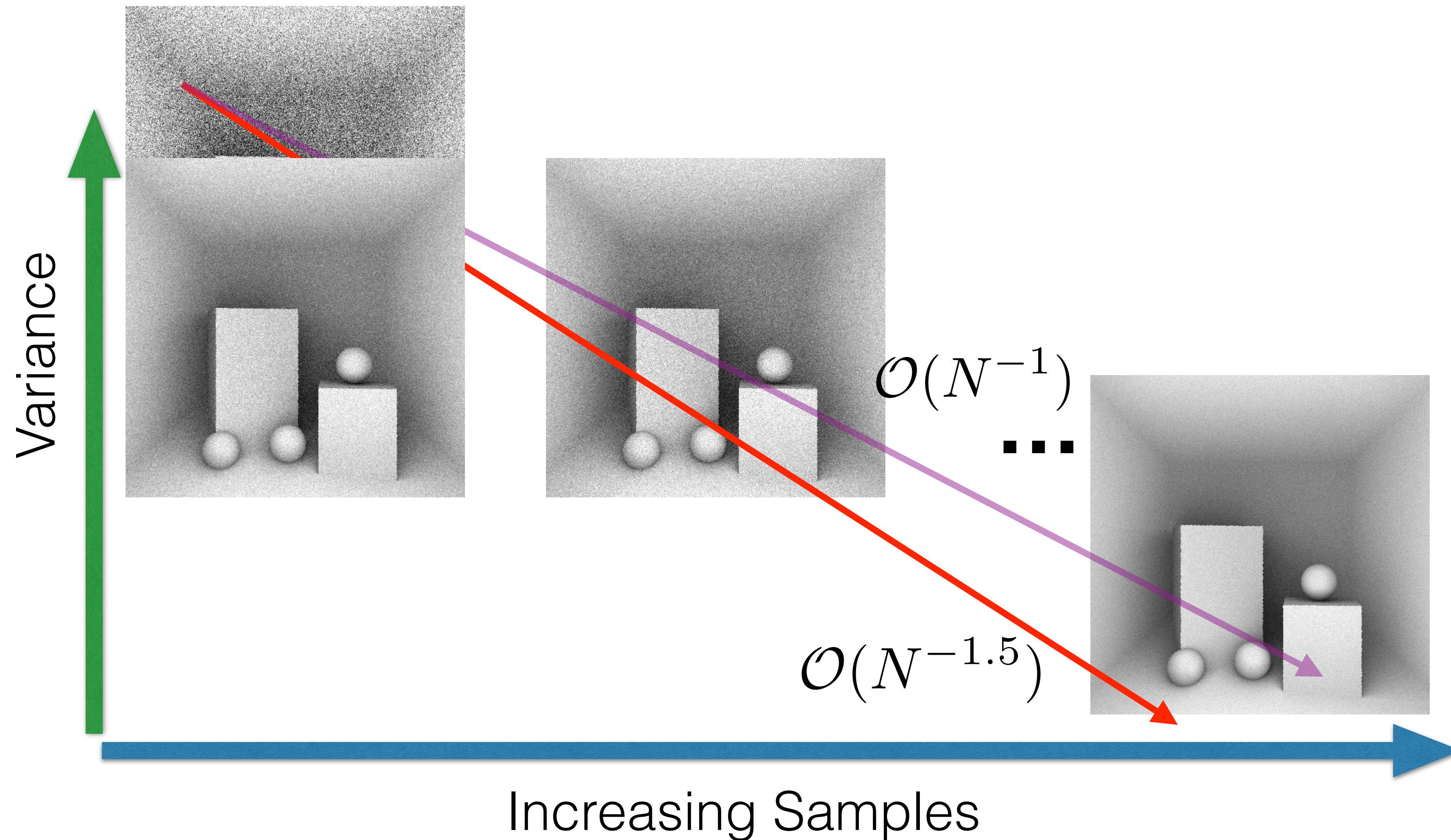
Convergence rate for Jittered Samples



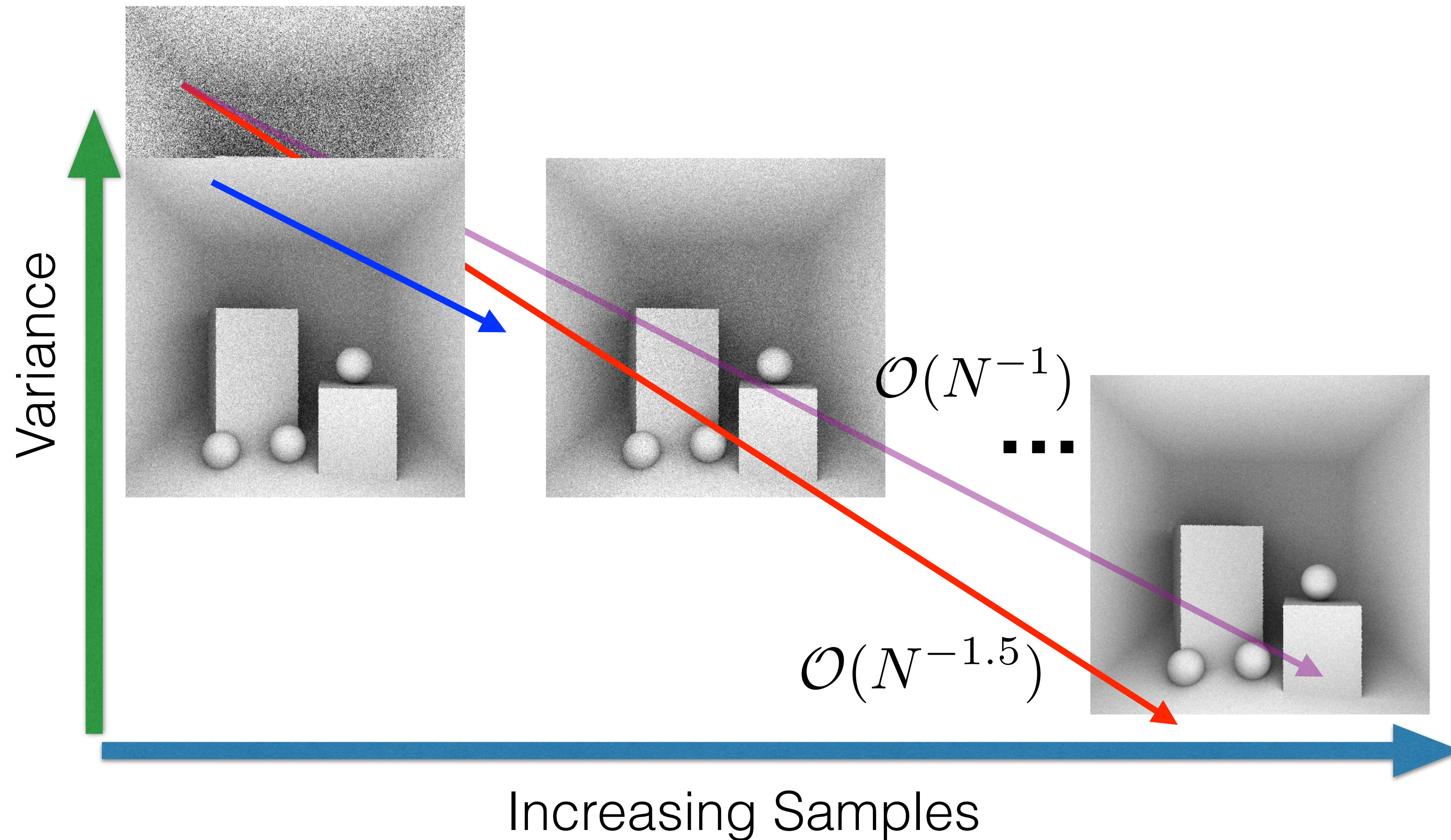
Convergence rate Jittered vs Poisson Disk



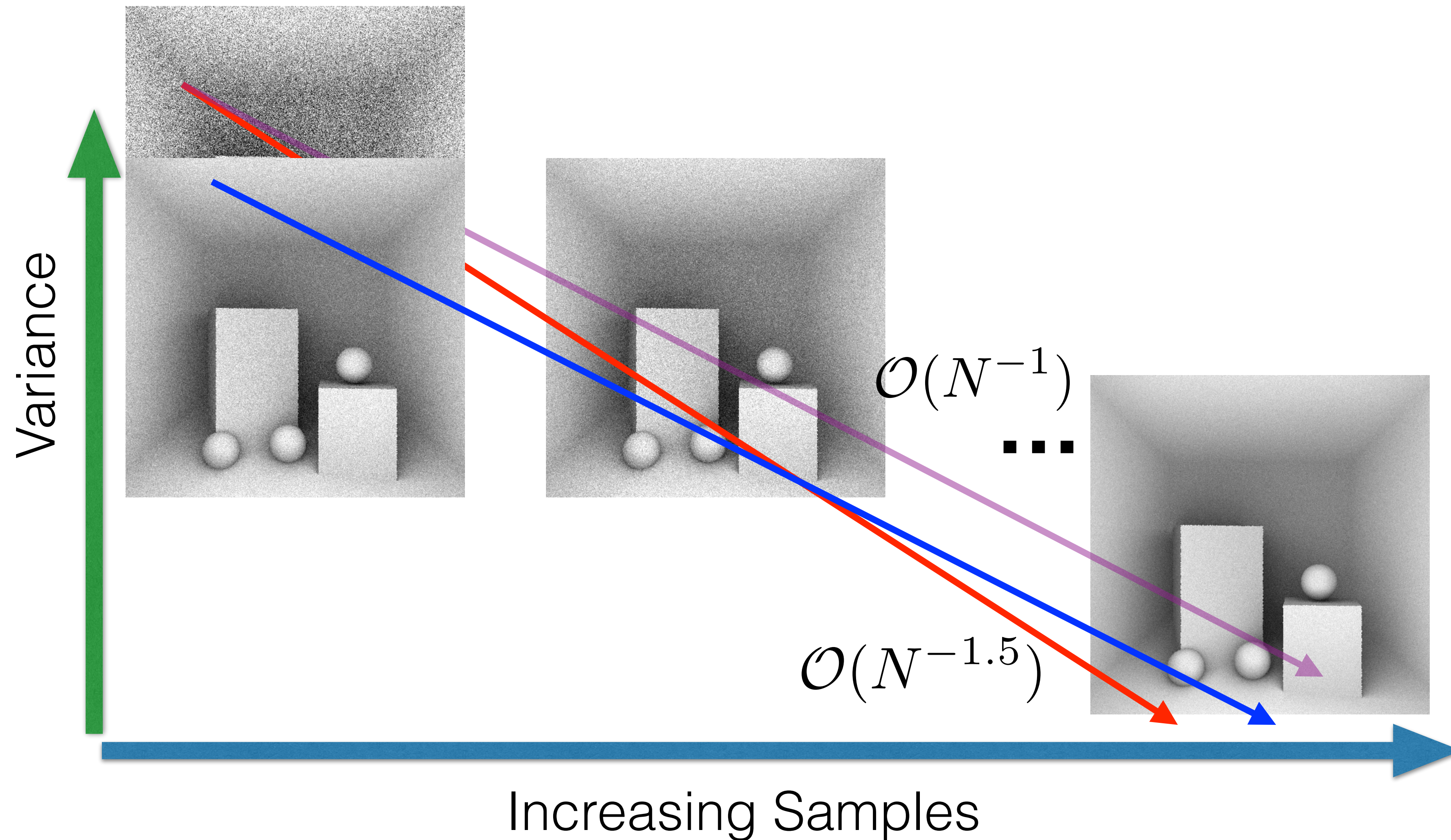
Convergence rate Jittered vs Poisson Disk



Convergence rate Jittered vs Poisson Disk

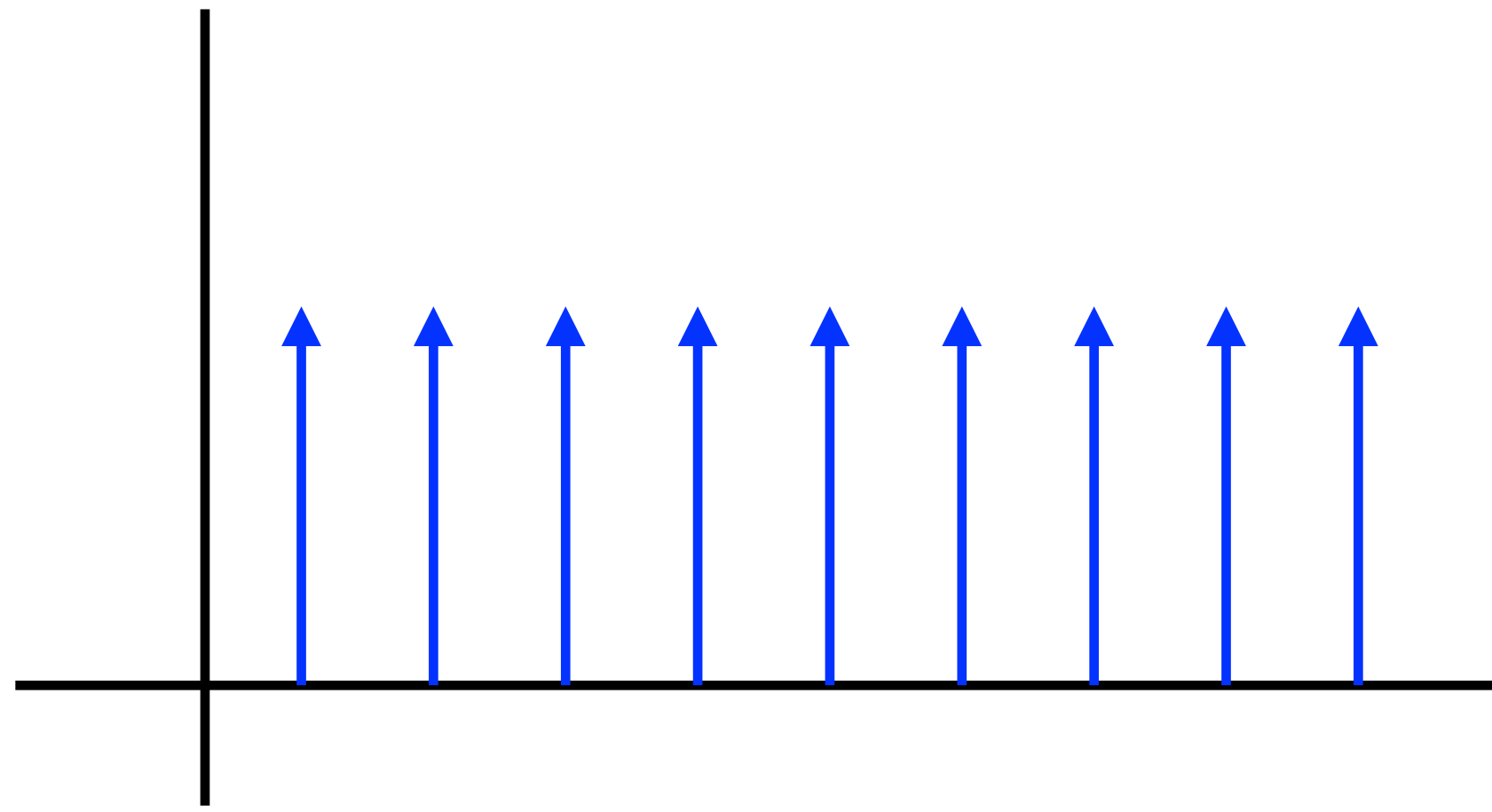


Convergence rate Jittered vs Poisson Disk



Samples and function in Fourier Domain

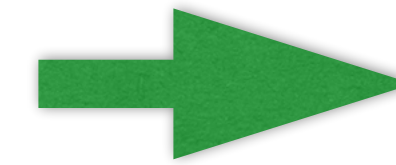
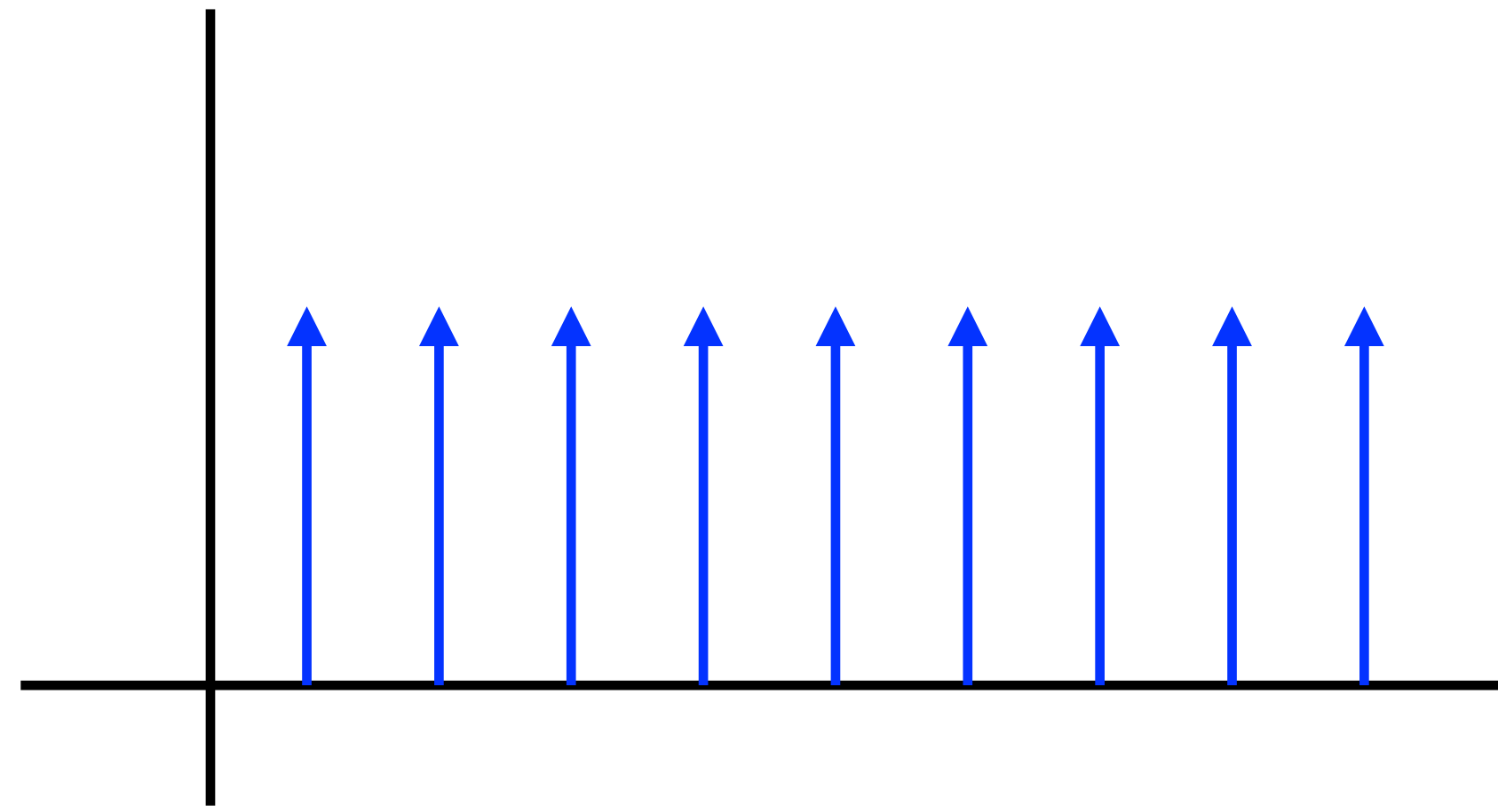
Spatial Domain



Fourier Domain

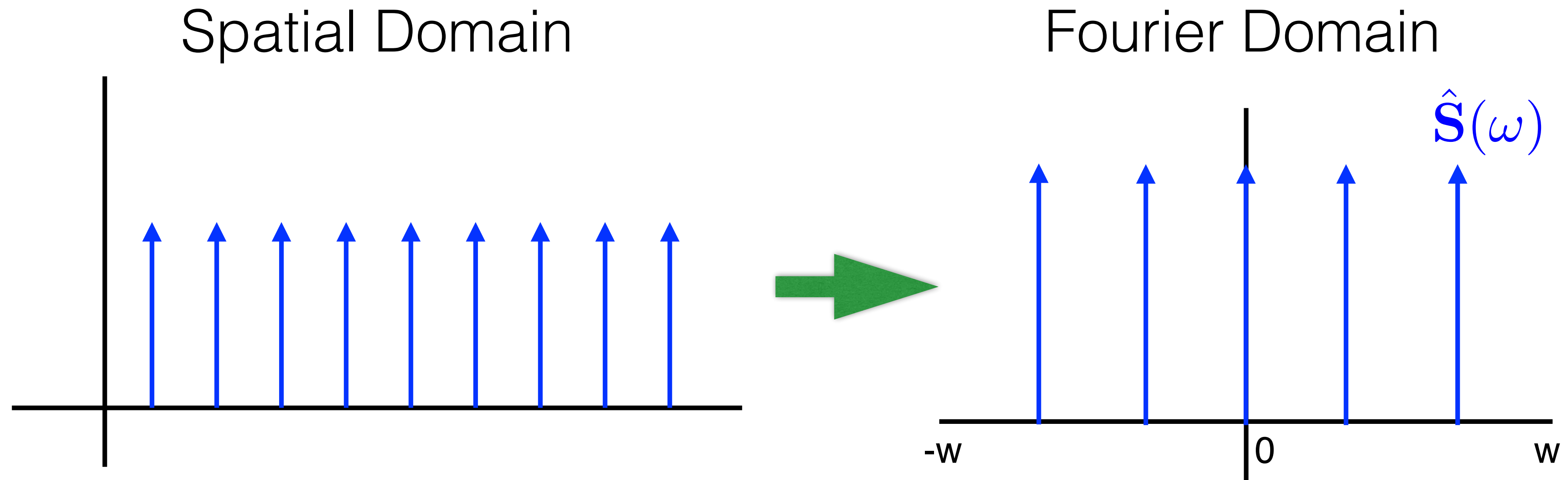
Samples and function in Fourier Domain

Spatial Domain

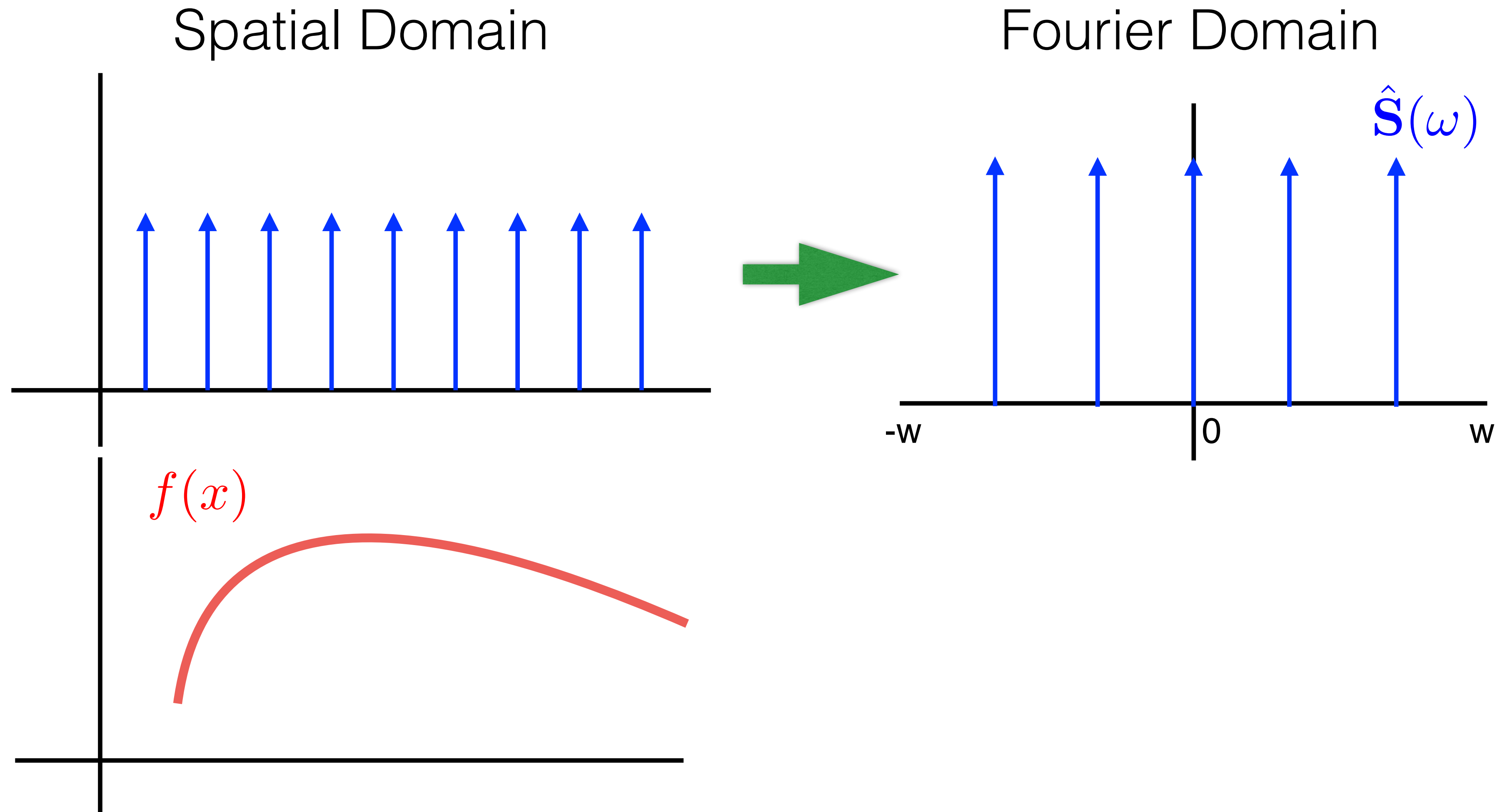


Fourier Domain

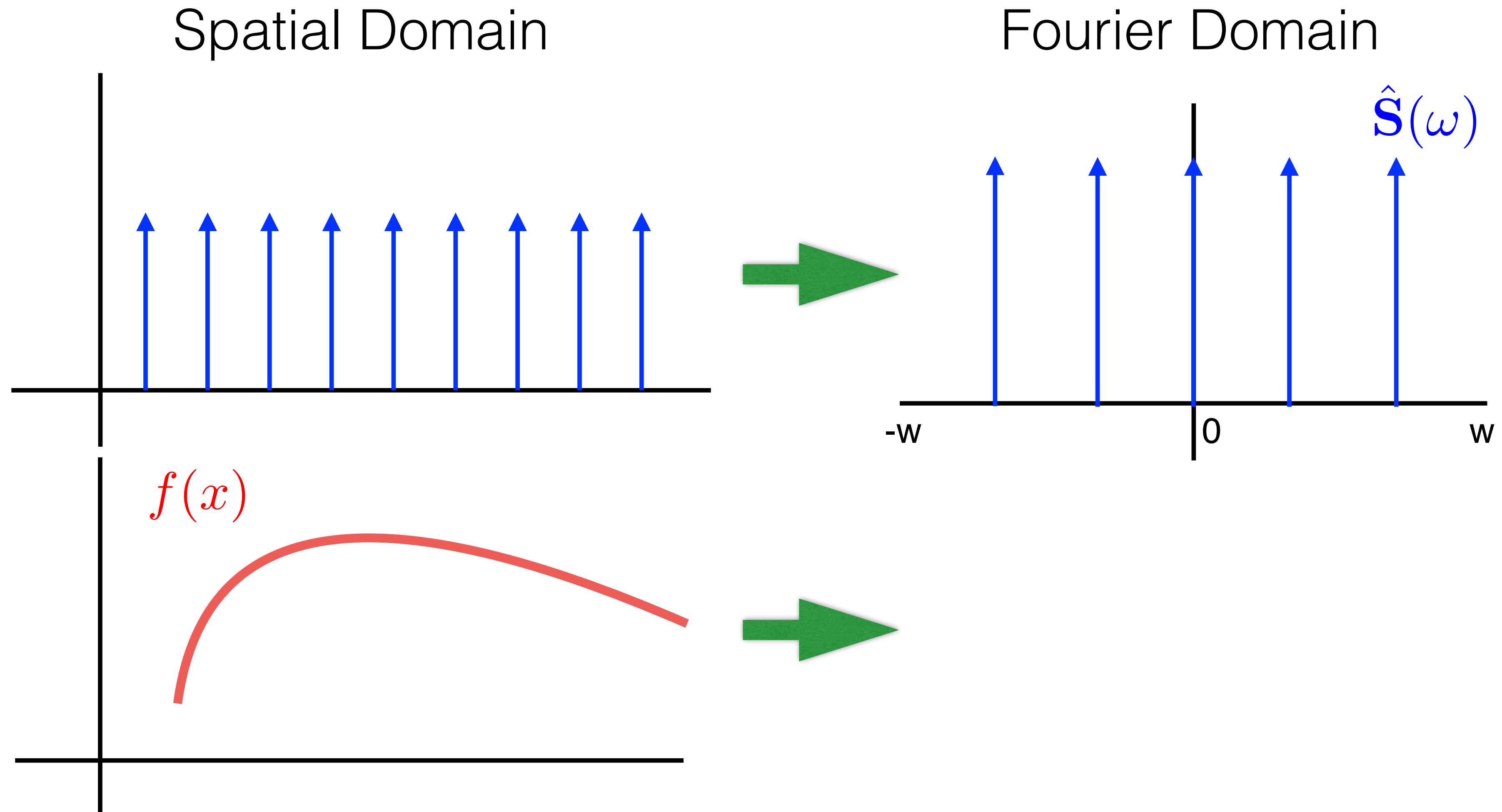
Samples and function in Fourier Domain



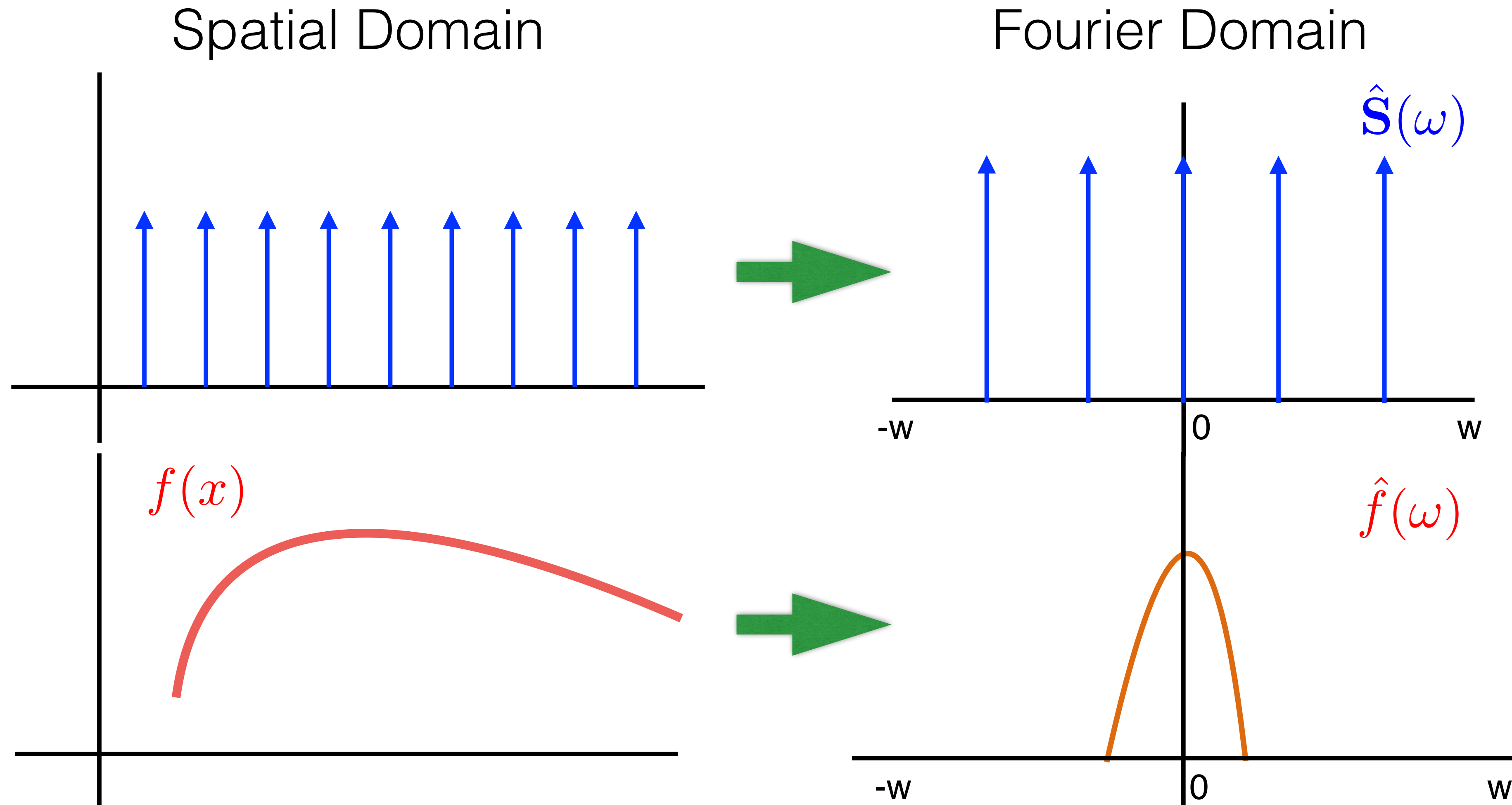
Samples and function in Fourier Domain



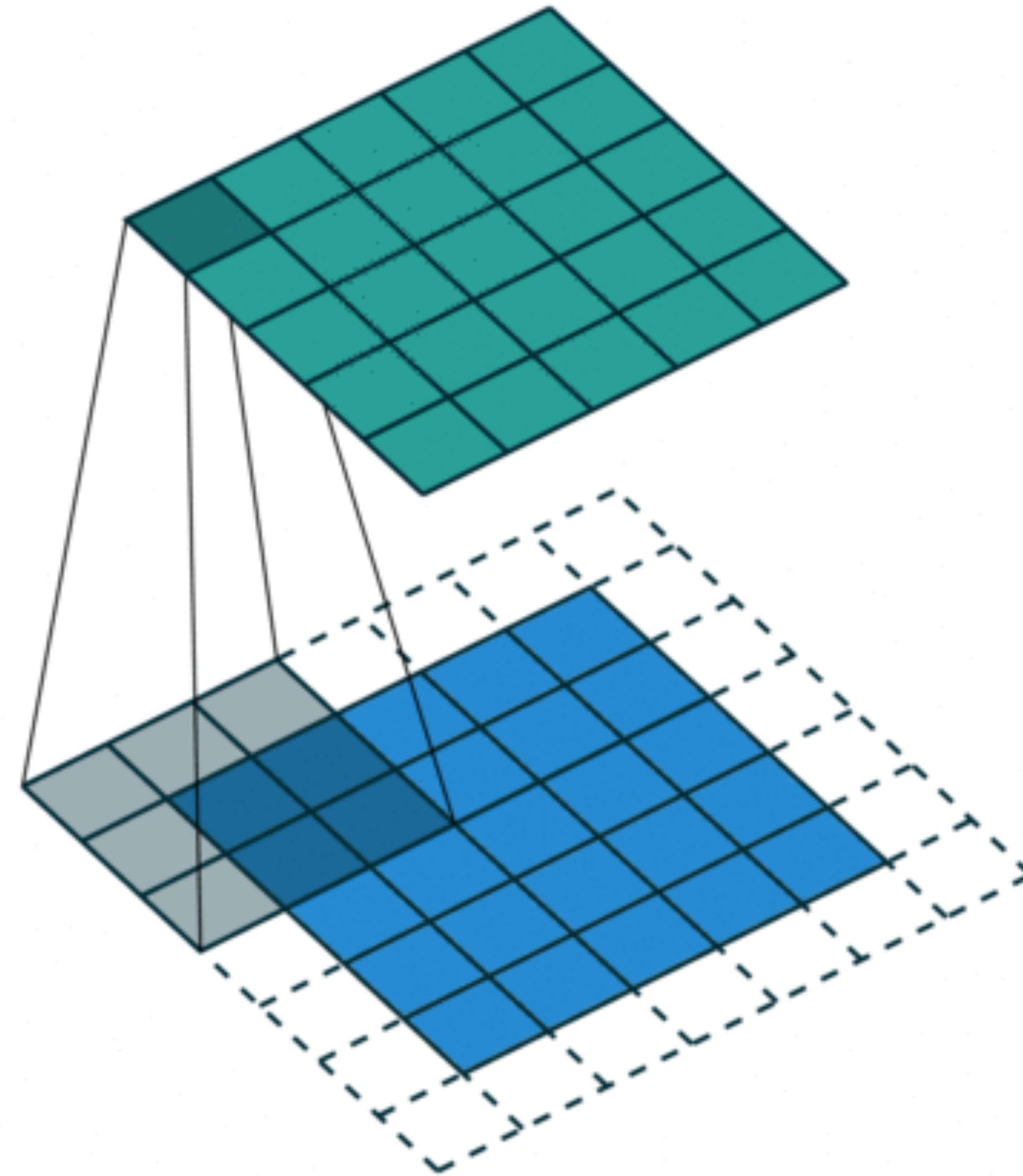
Samples and function in Fourier Domain



Samples and function in Fourier Domain

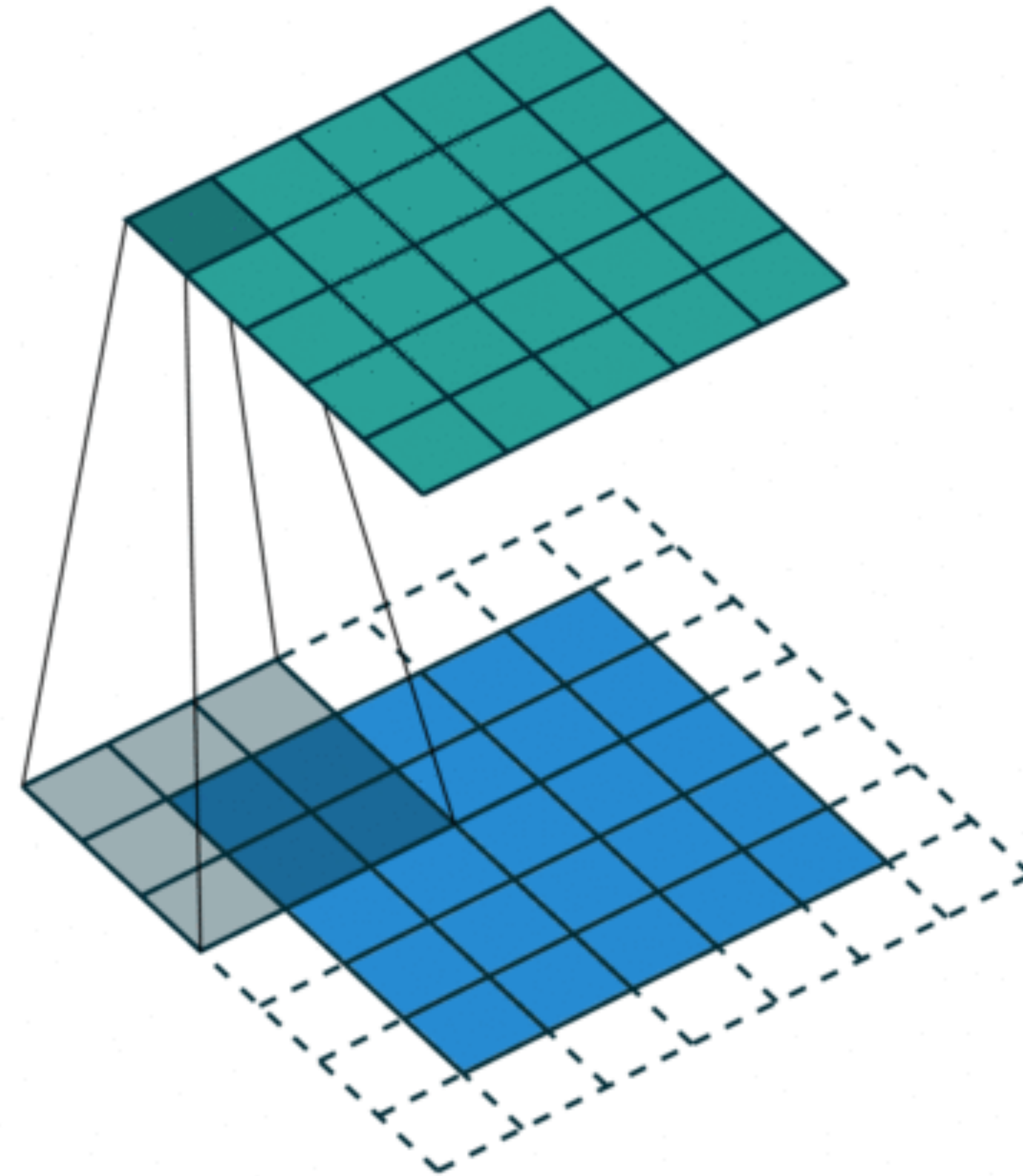


Convolution



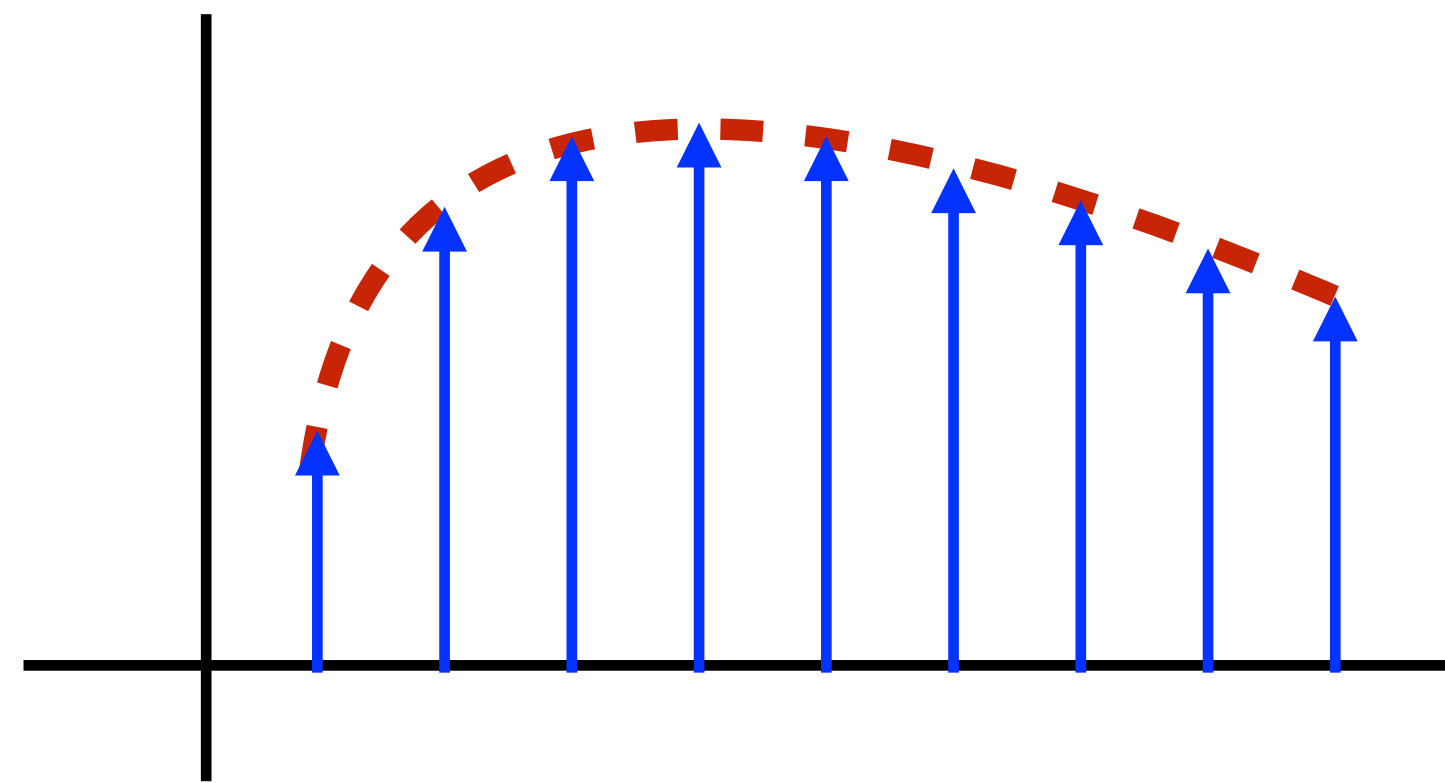
Source: [vdumoulin-github](#)

Convolution



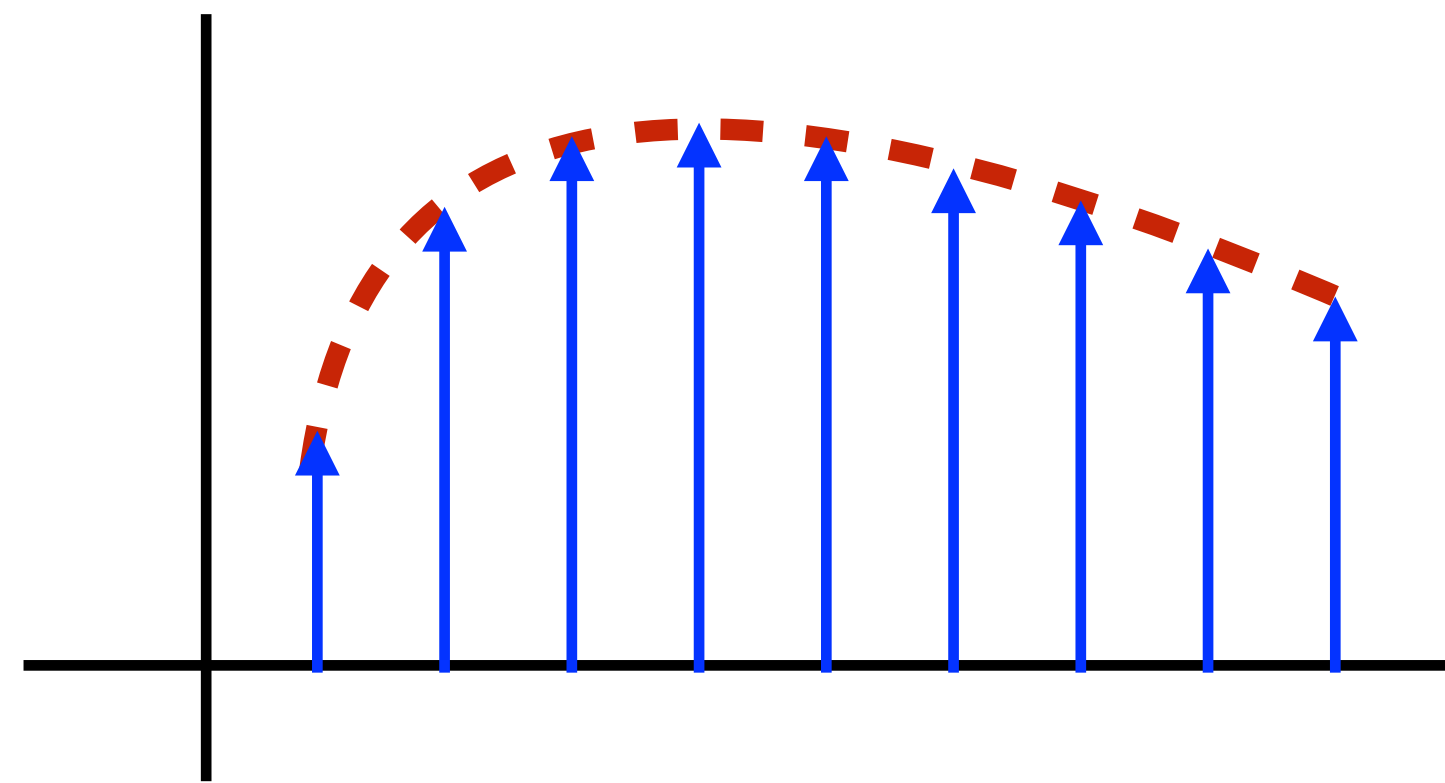
Source: vdumoulin-github

Sampling in Primal Domain is Convolution in Fourier Domain



$$f(x) \mathbf{S}(x)$$

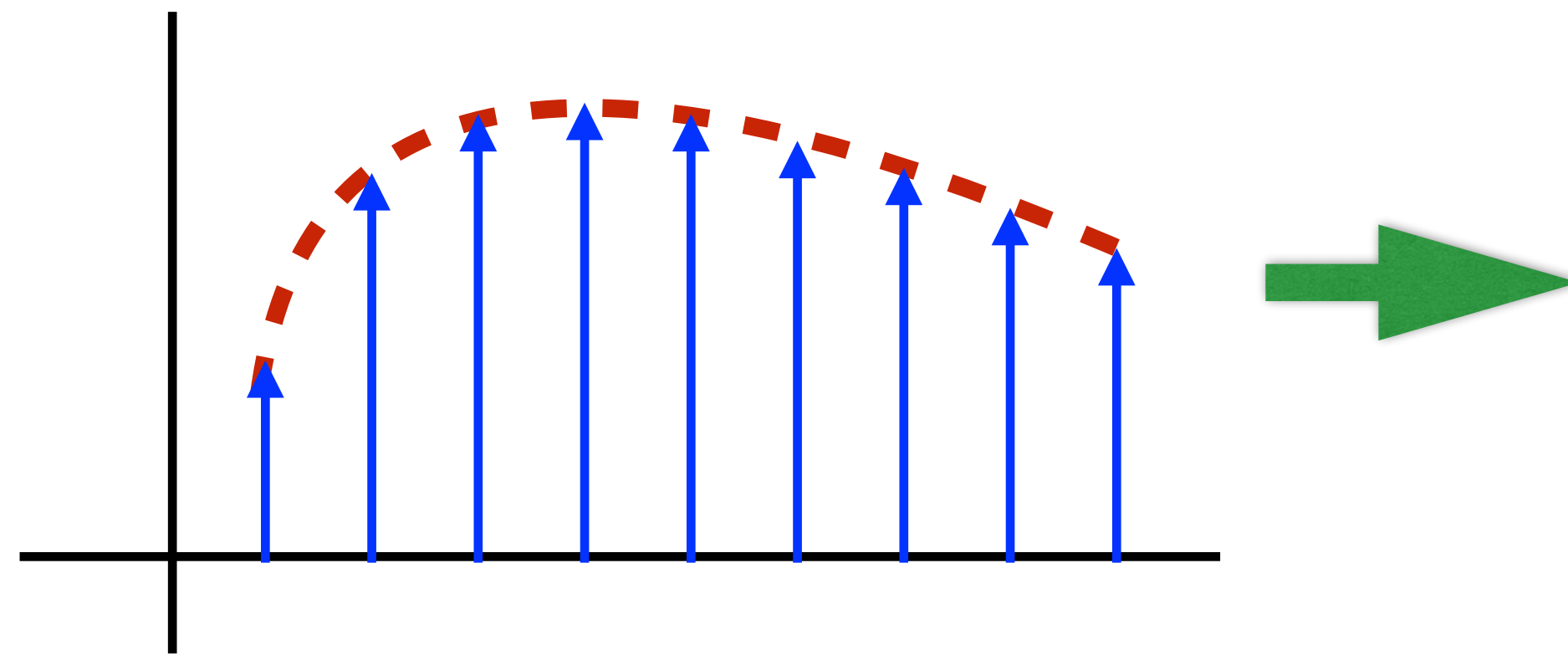
Sampling in Primal Domain is Convolution in Fourier Domain



$$f(x) \mathbf{S}(x)$$

Fredo Durand [2011]

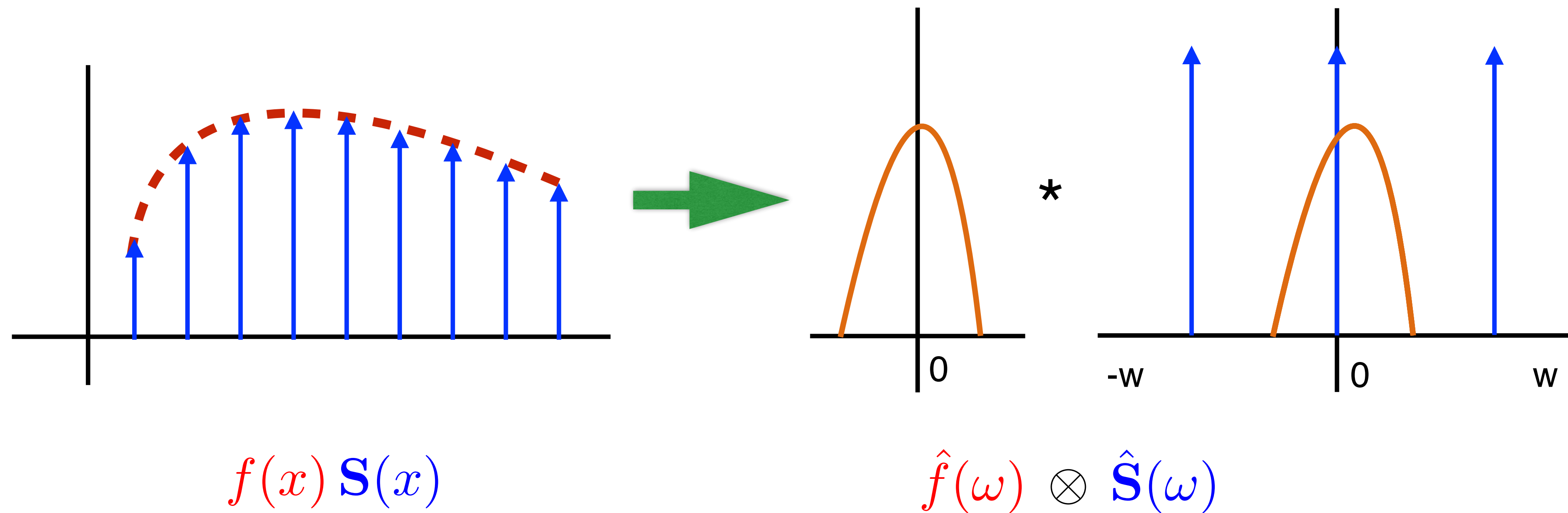
Sampling in Primal Domain is Convolution in Fourier Domain



$$f(x) \mathbf{S}(x)$$

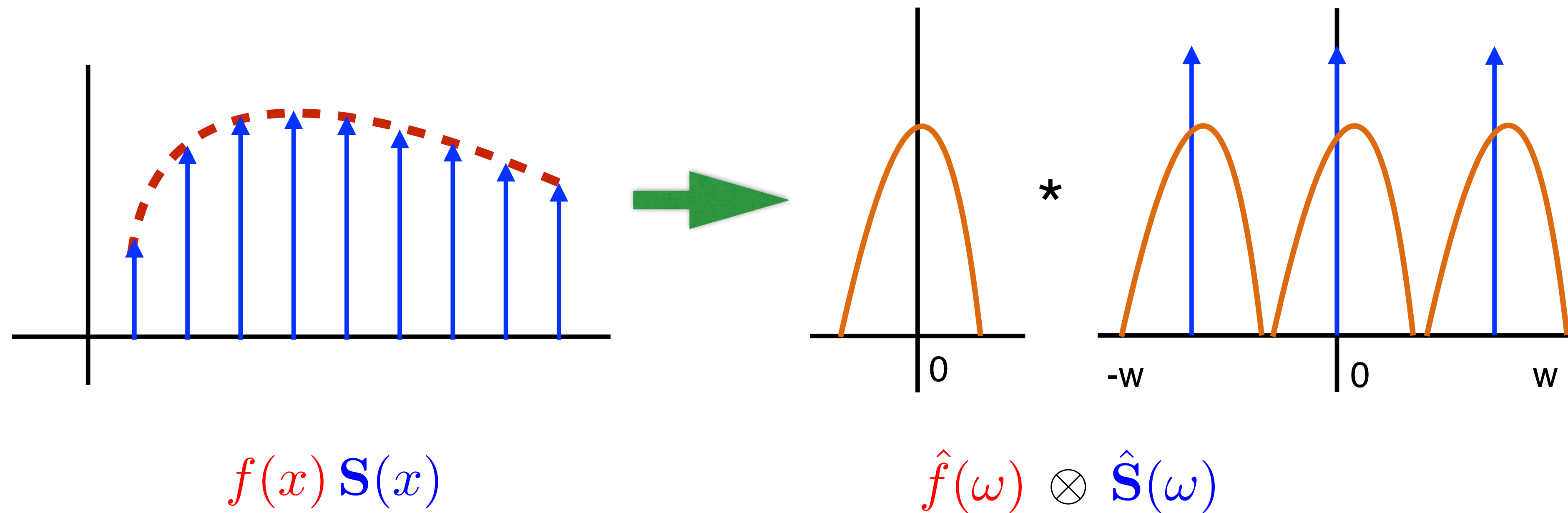
Fredo Durand [2011]

Sampling in Primal Domain is Convolution in Fourier Domain



Fredo Durand [2011]

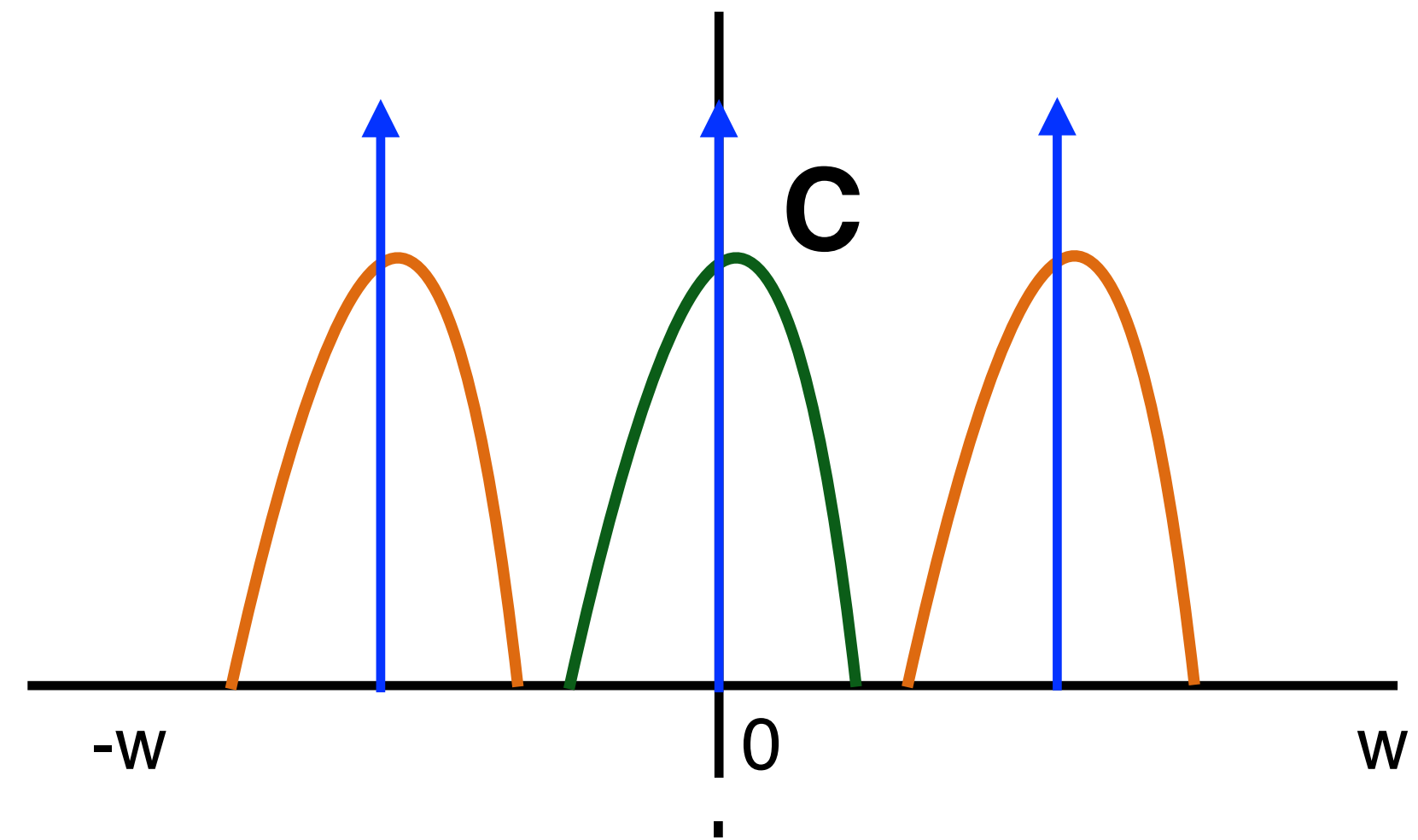
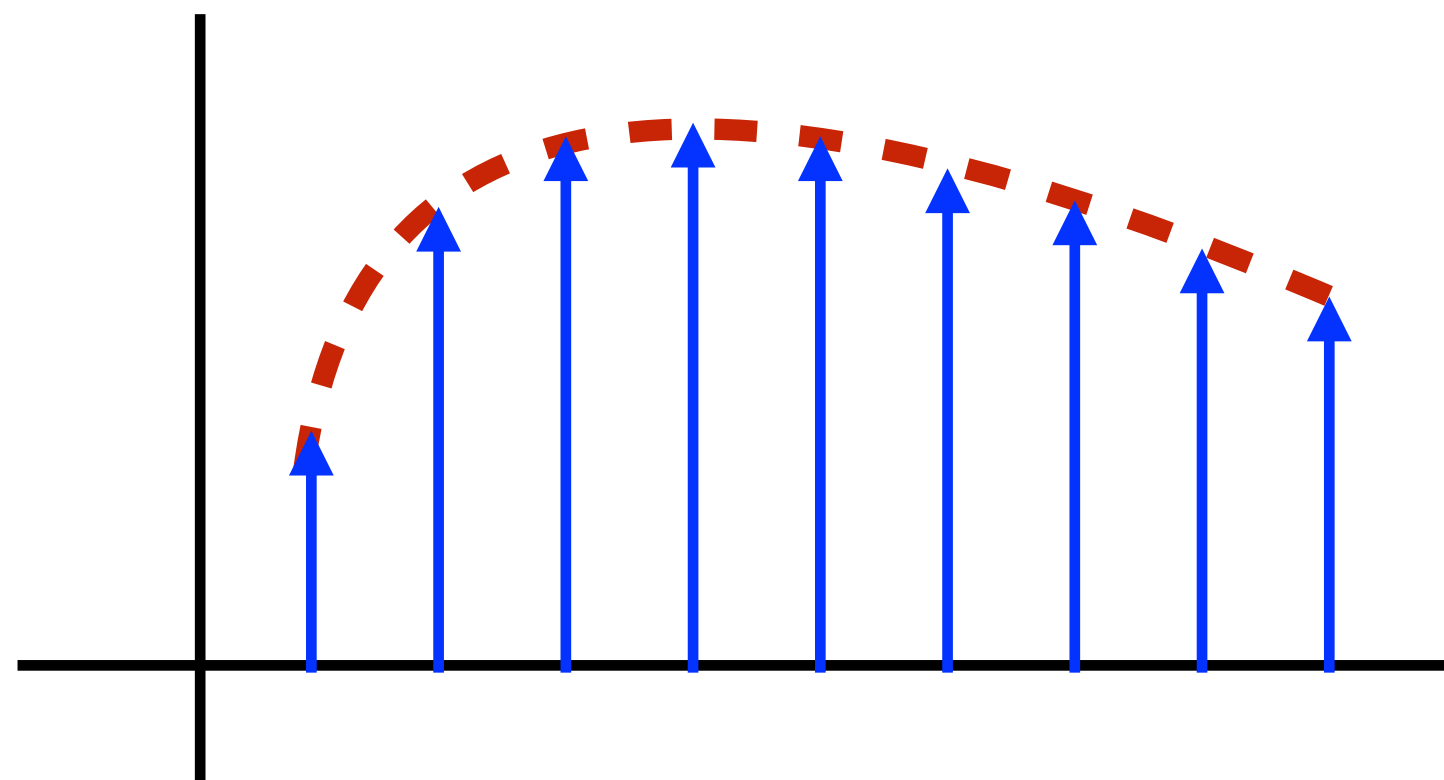
Sampling in Primal Domain is Convolution in Fourier Domain



Fredo Durand [2011]

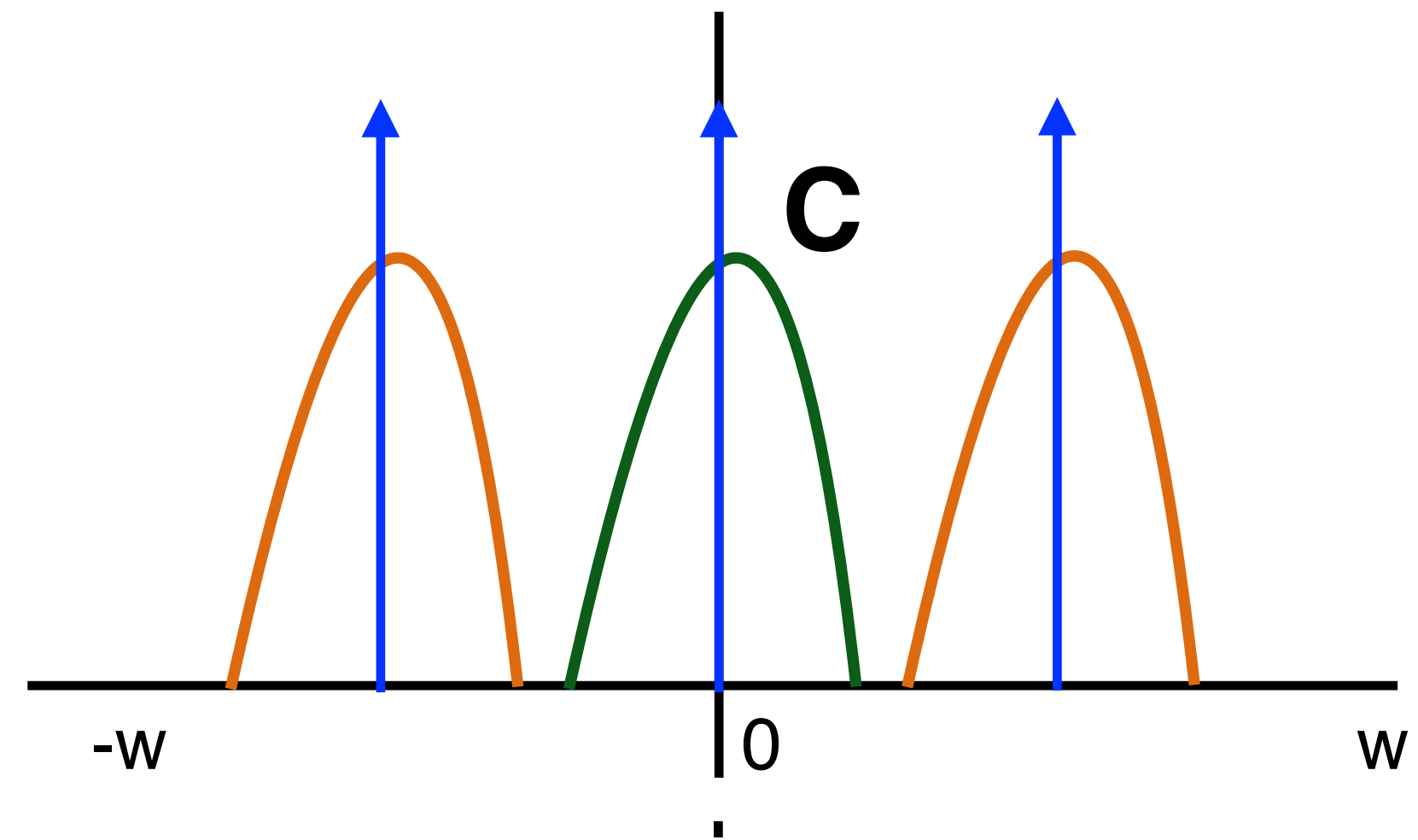
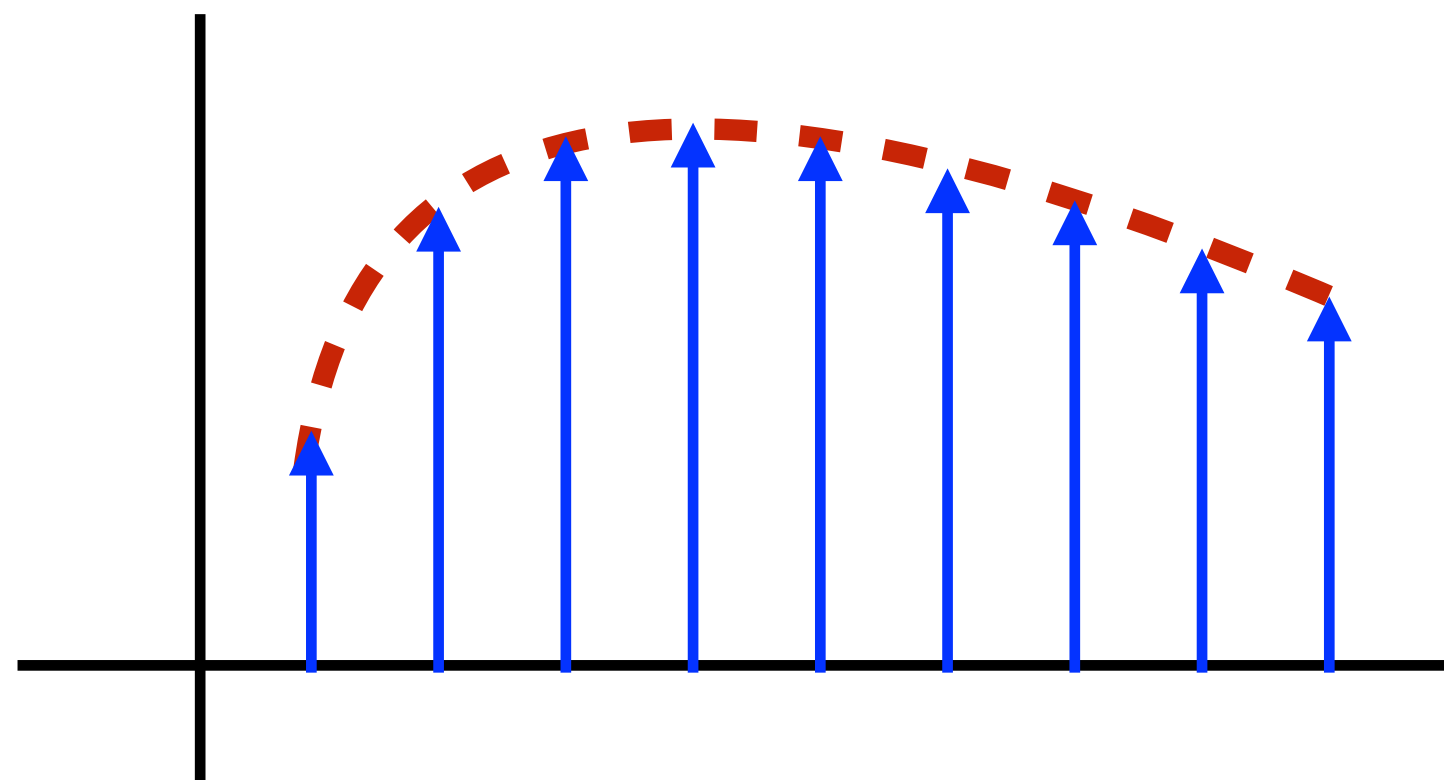
Aliasing in Reconstruction

High Sampling Rate



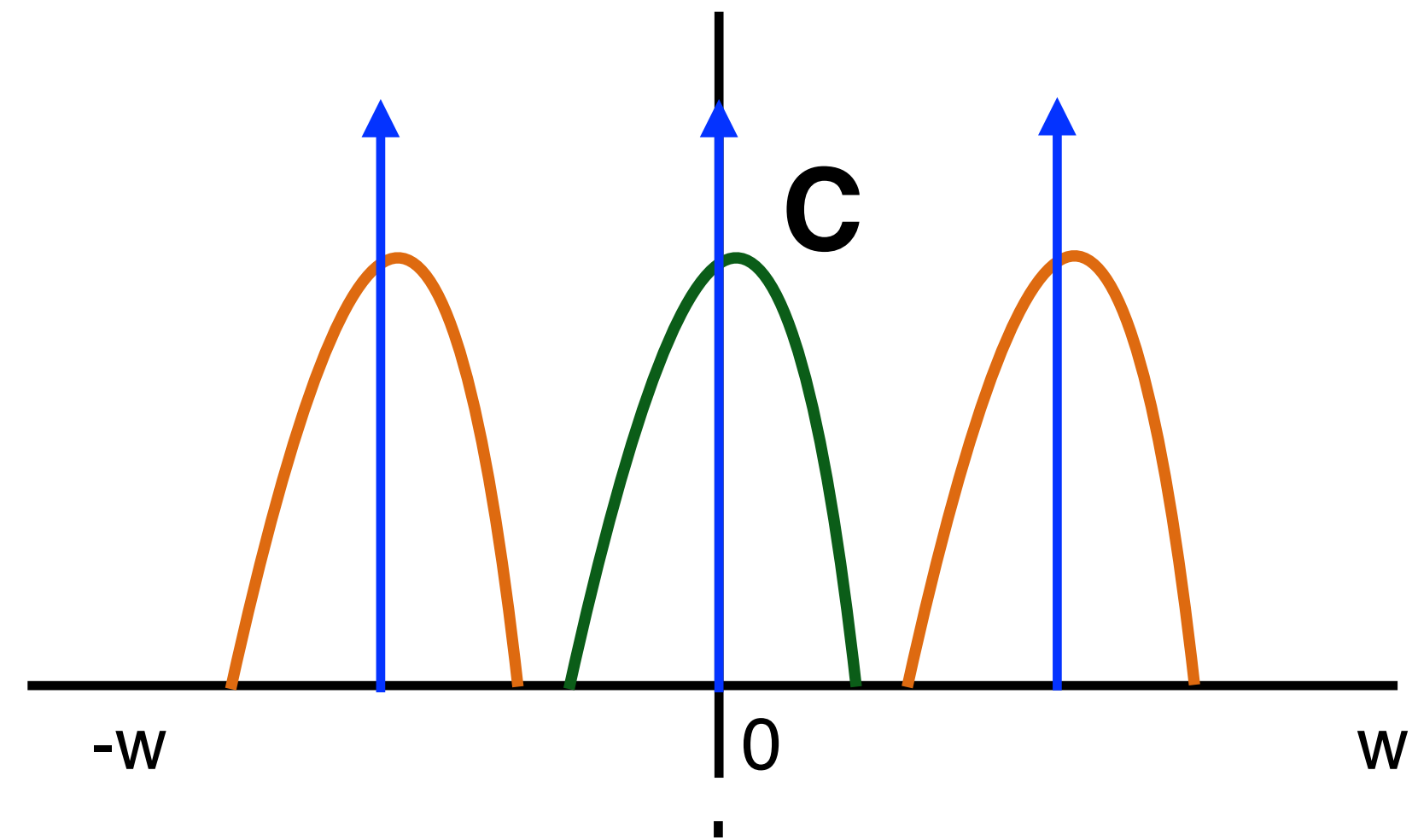
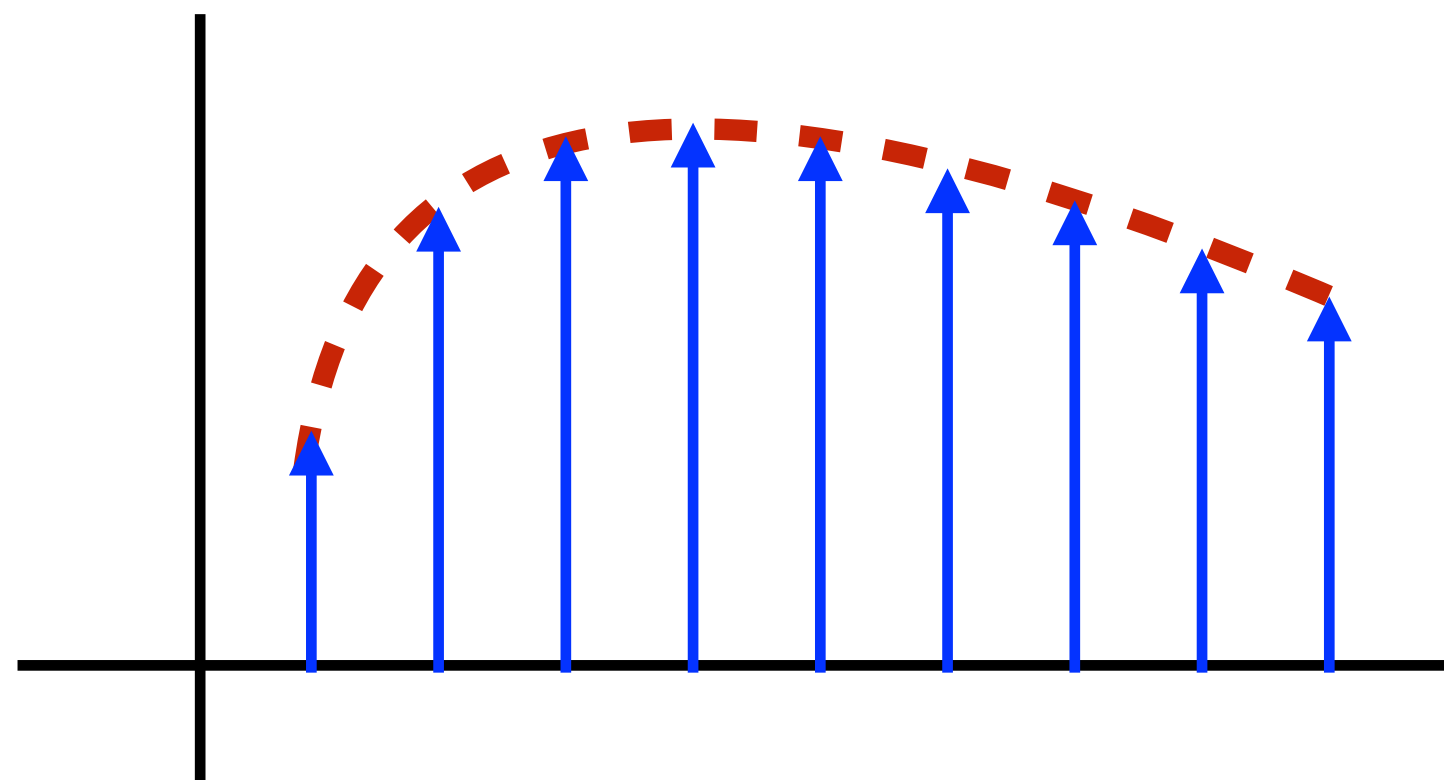
Aliasing in Reconstruction

High Sampling Rate



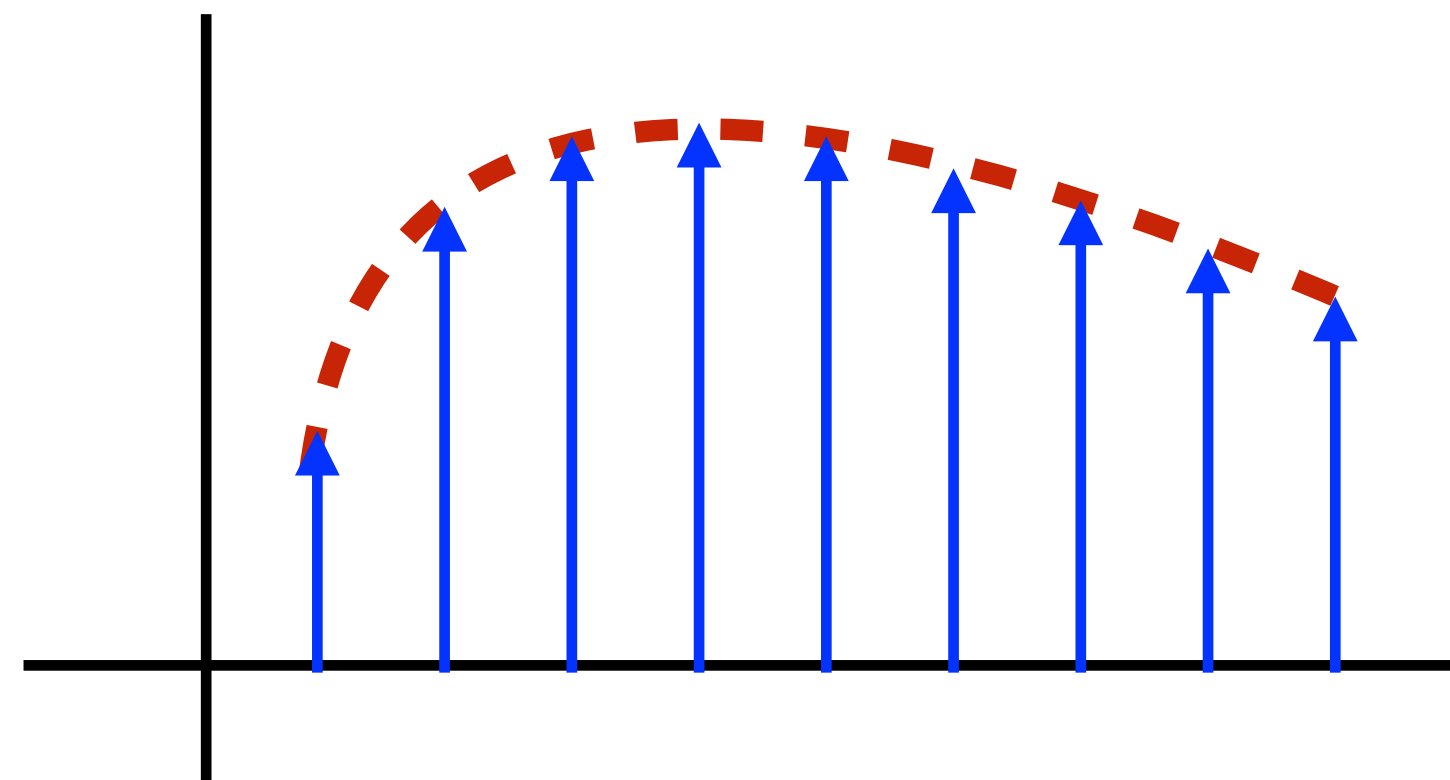
Aliasing in Reconstruction

Low Sampling Rate High Sampling Rate

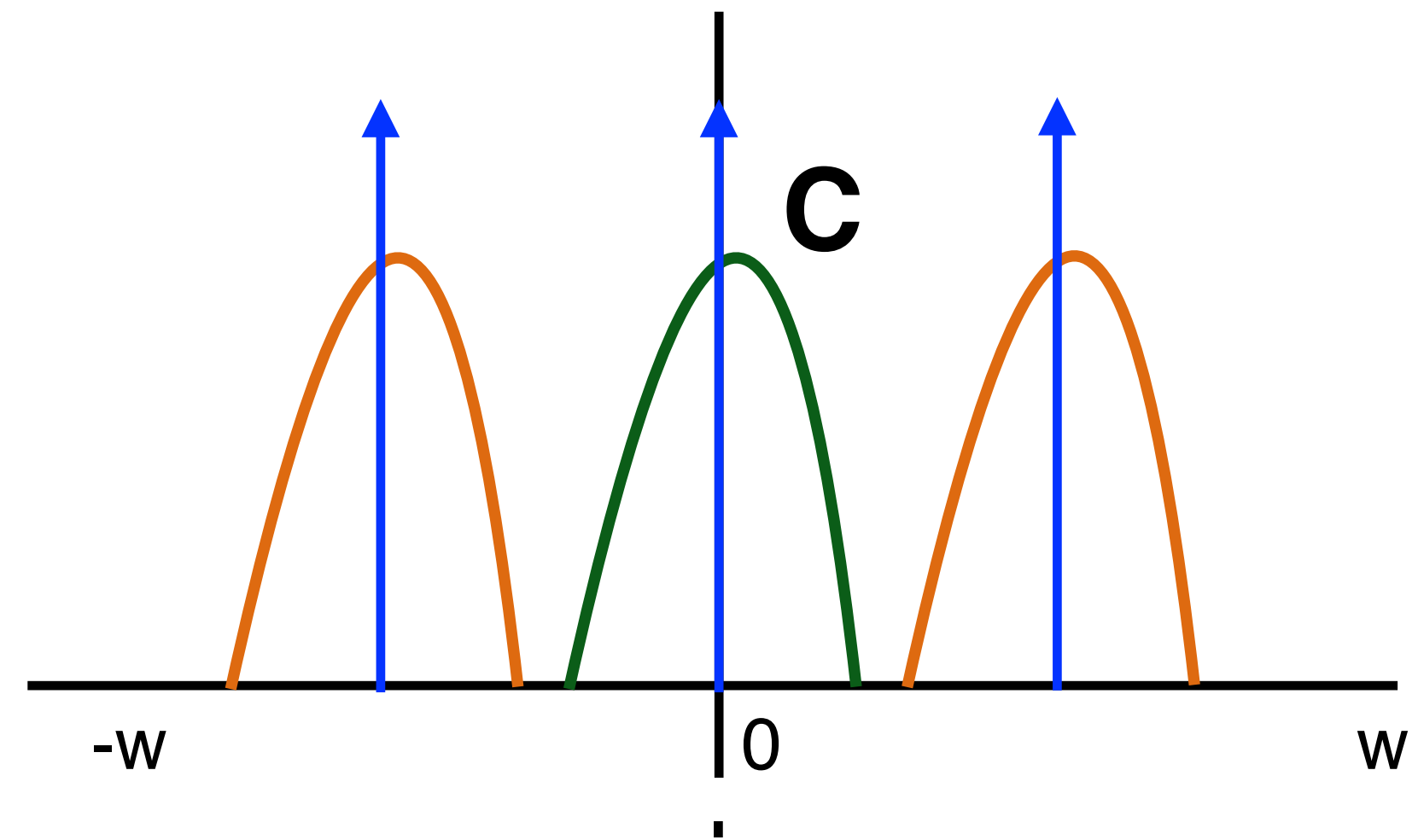
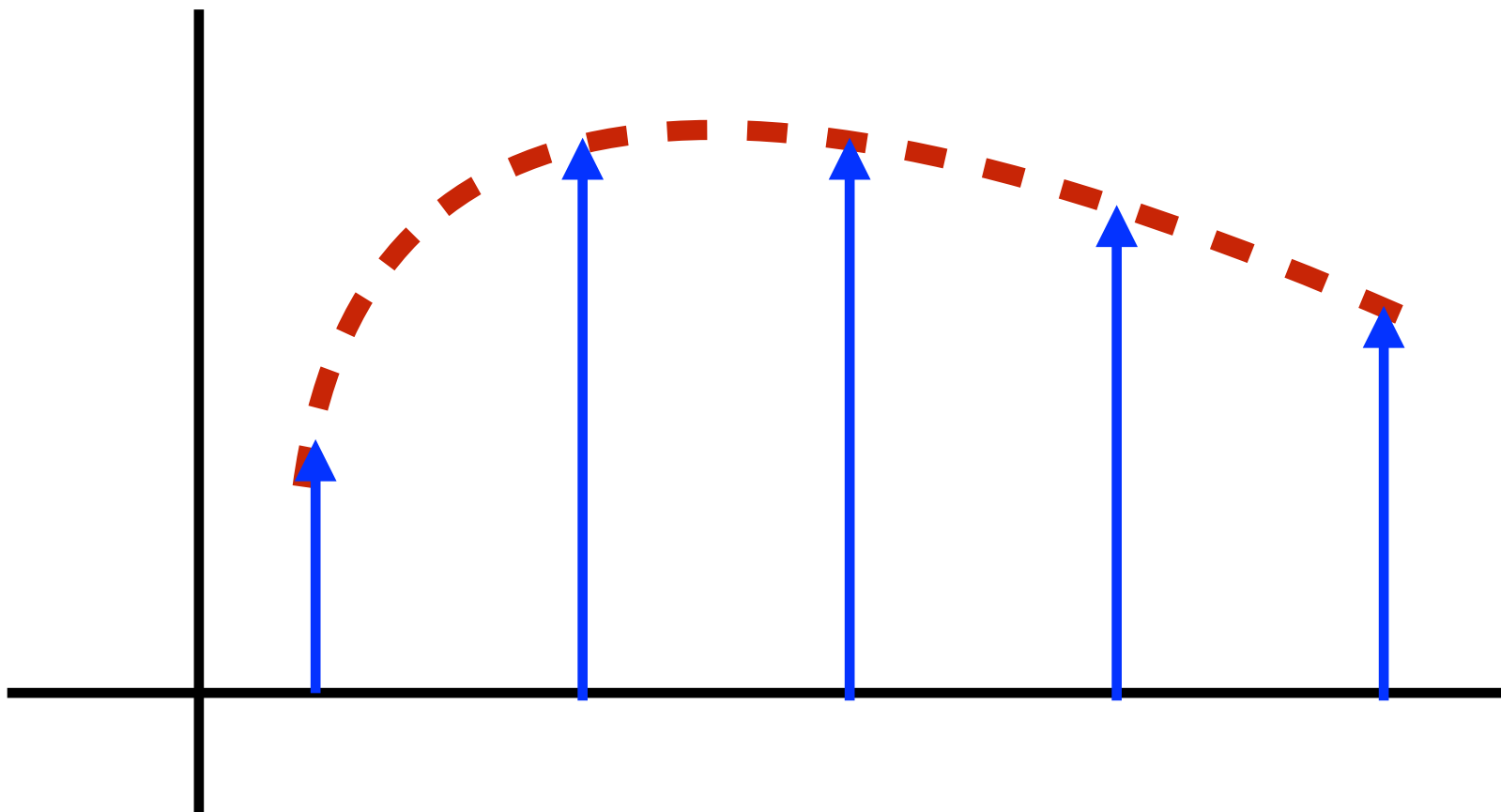


Aliasing in Reconstruction

High Sampling Rate

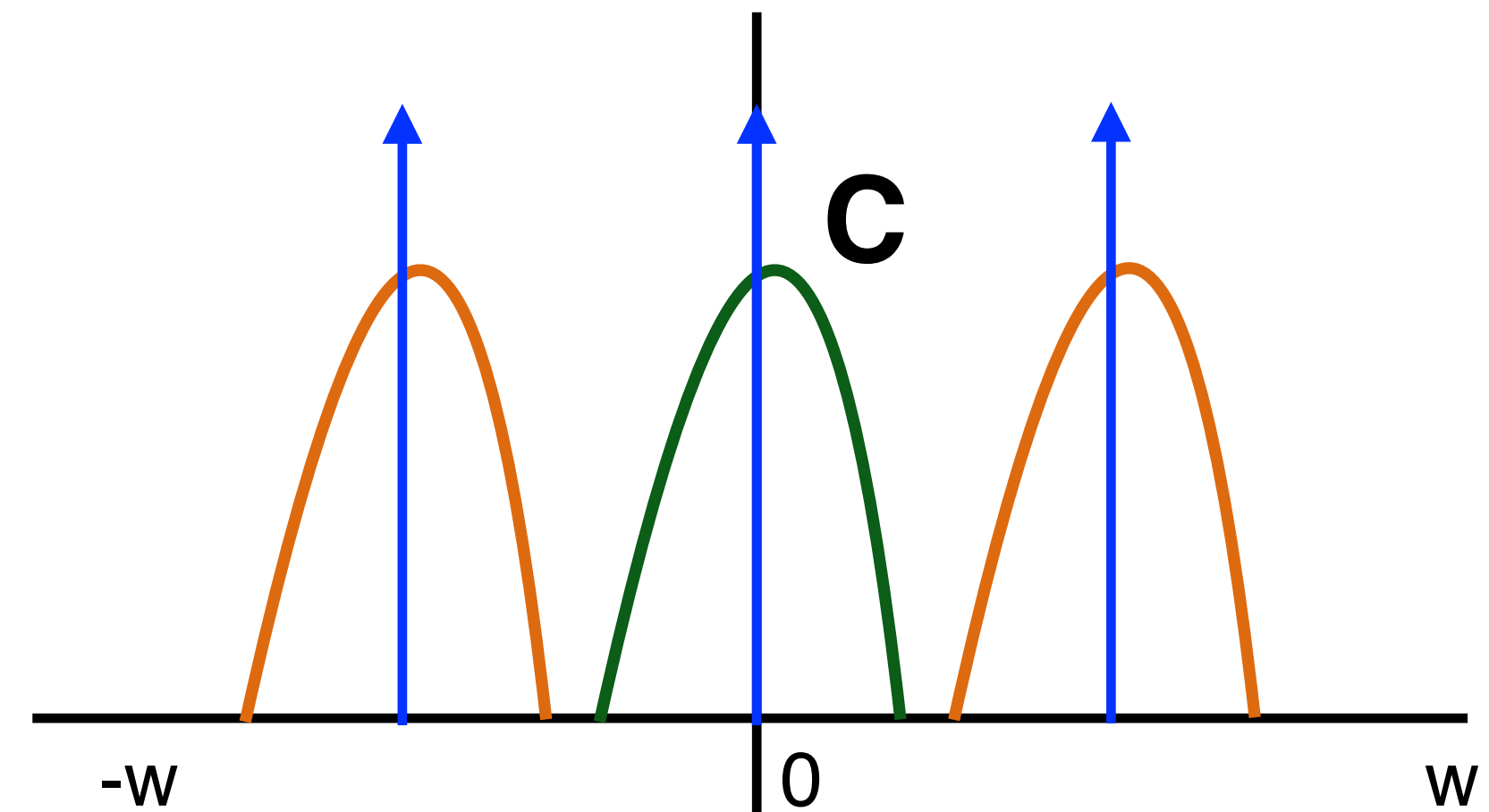
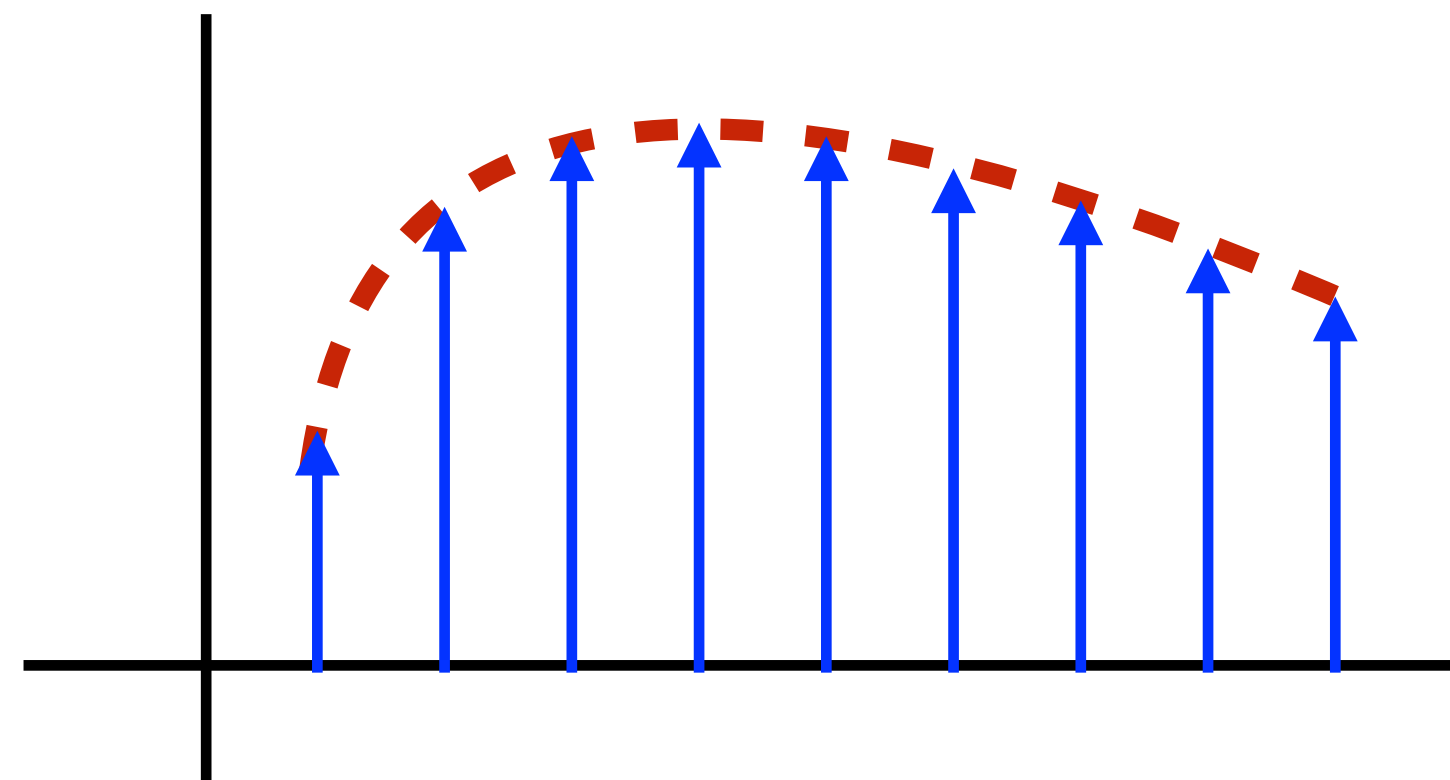


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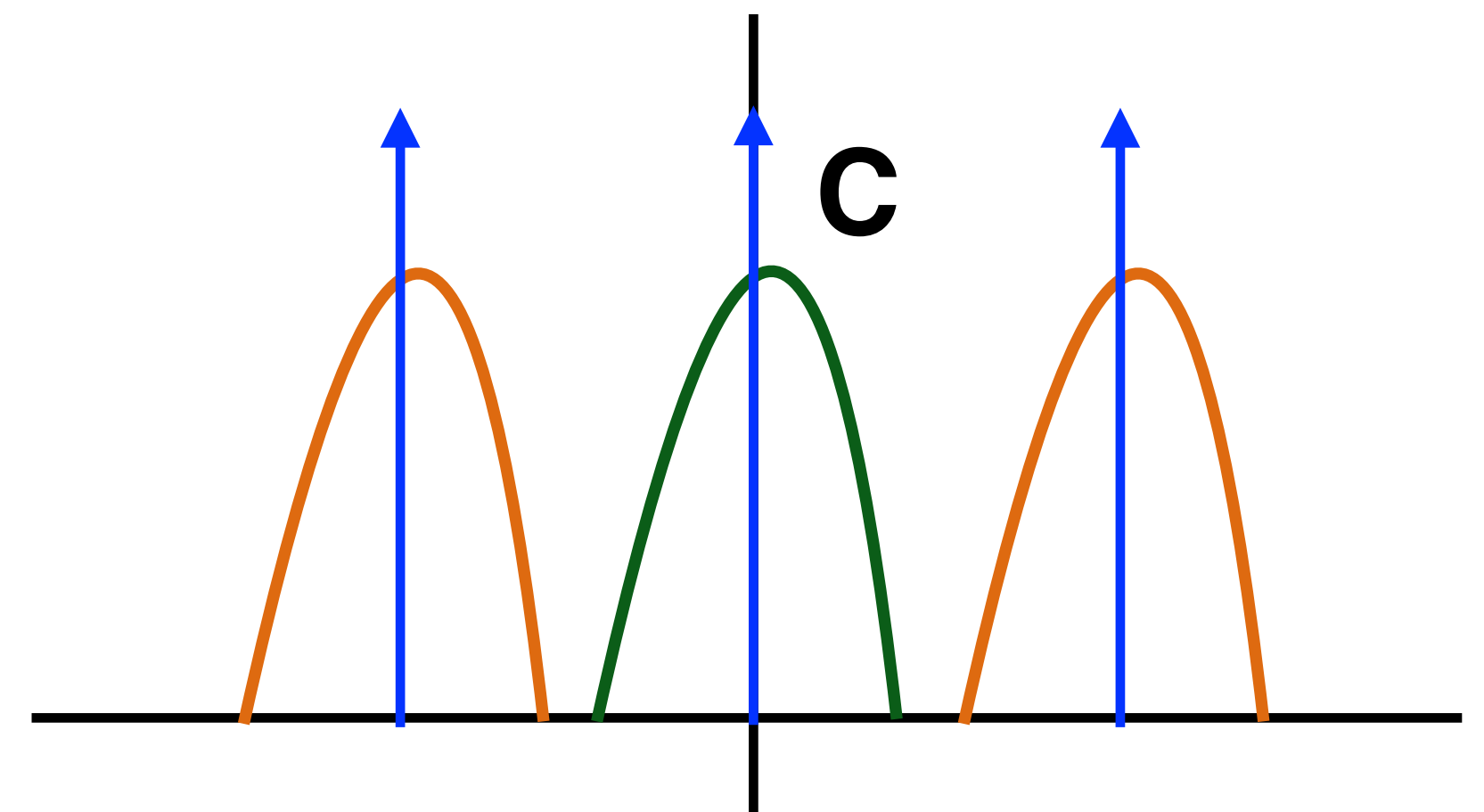
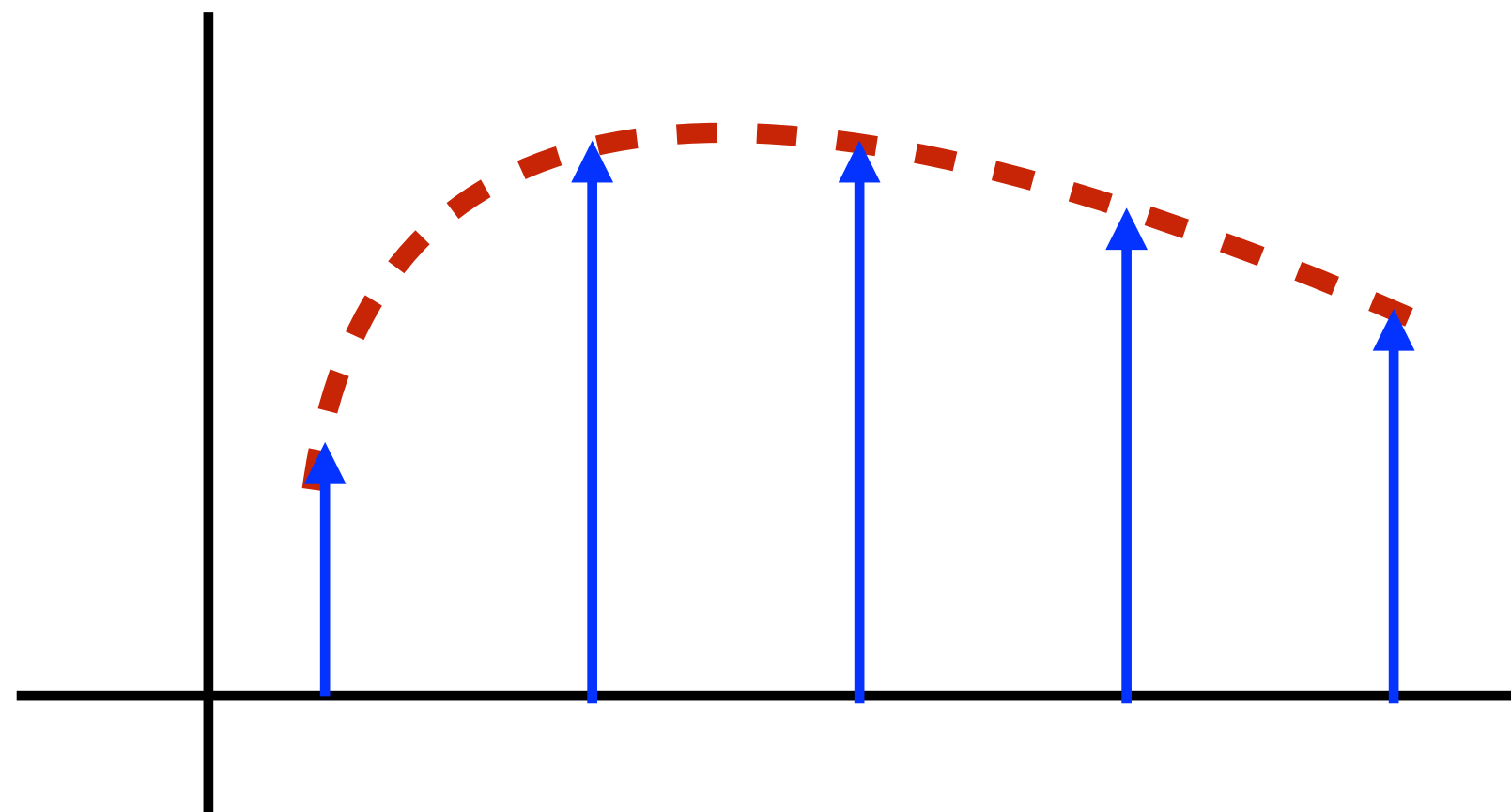


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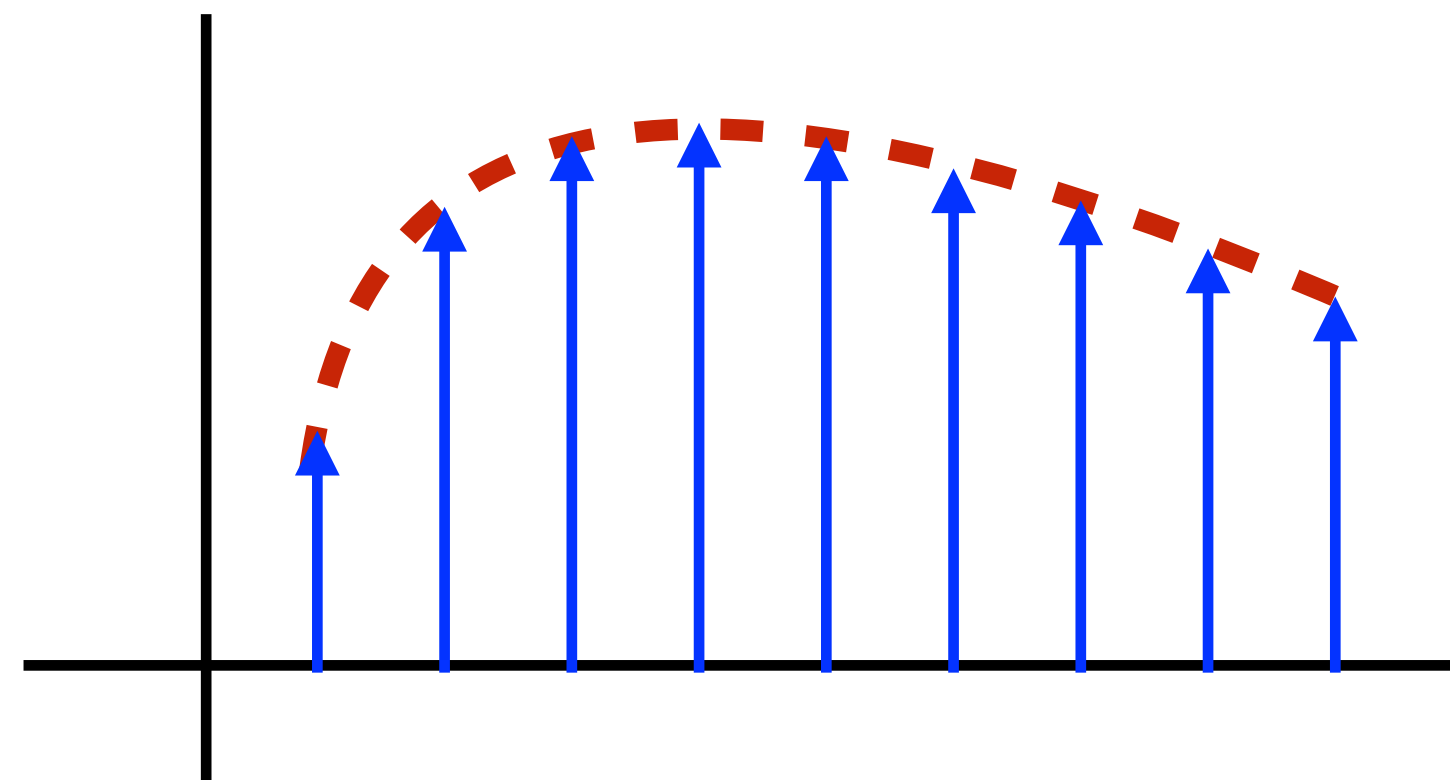


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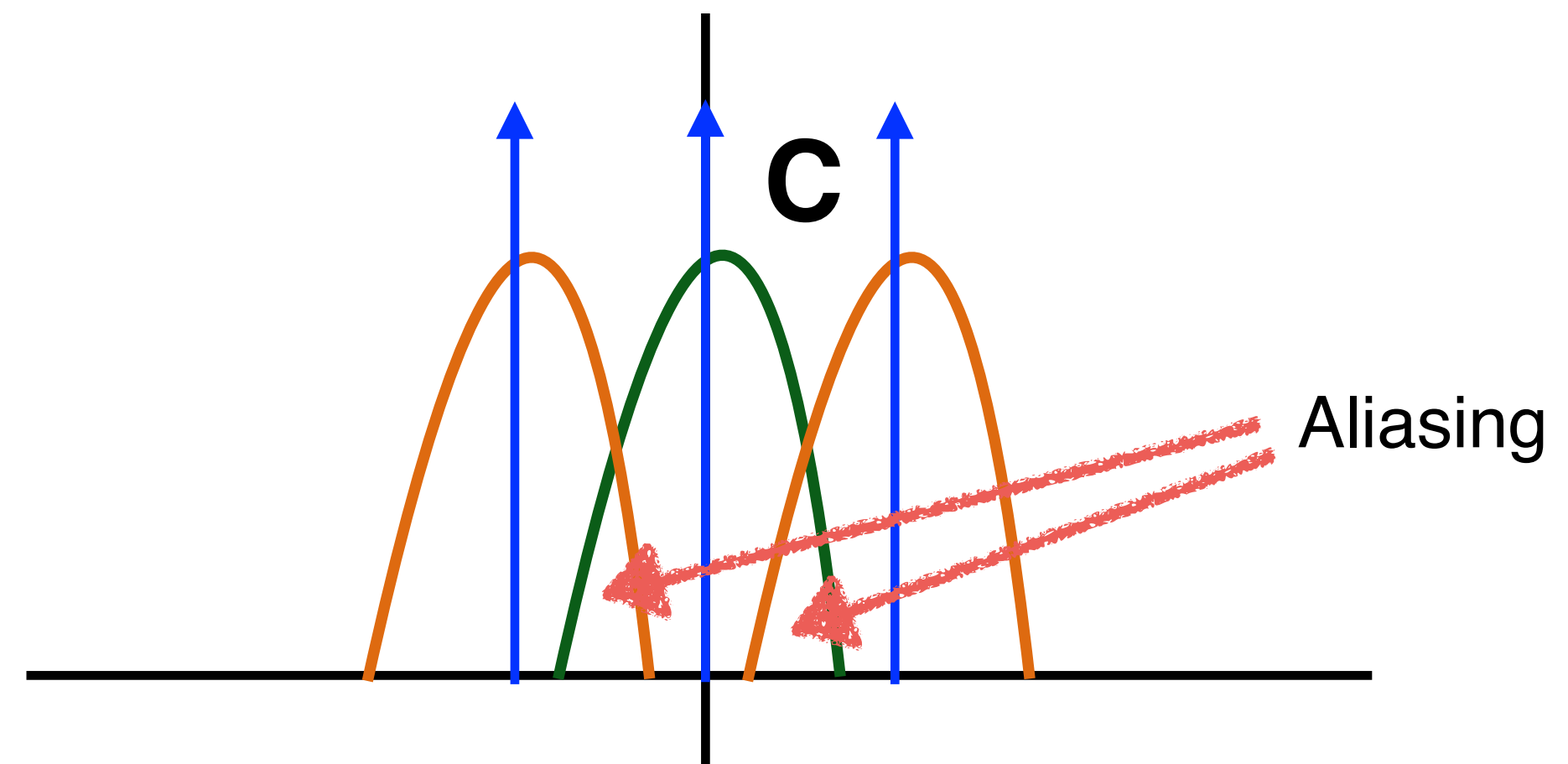
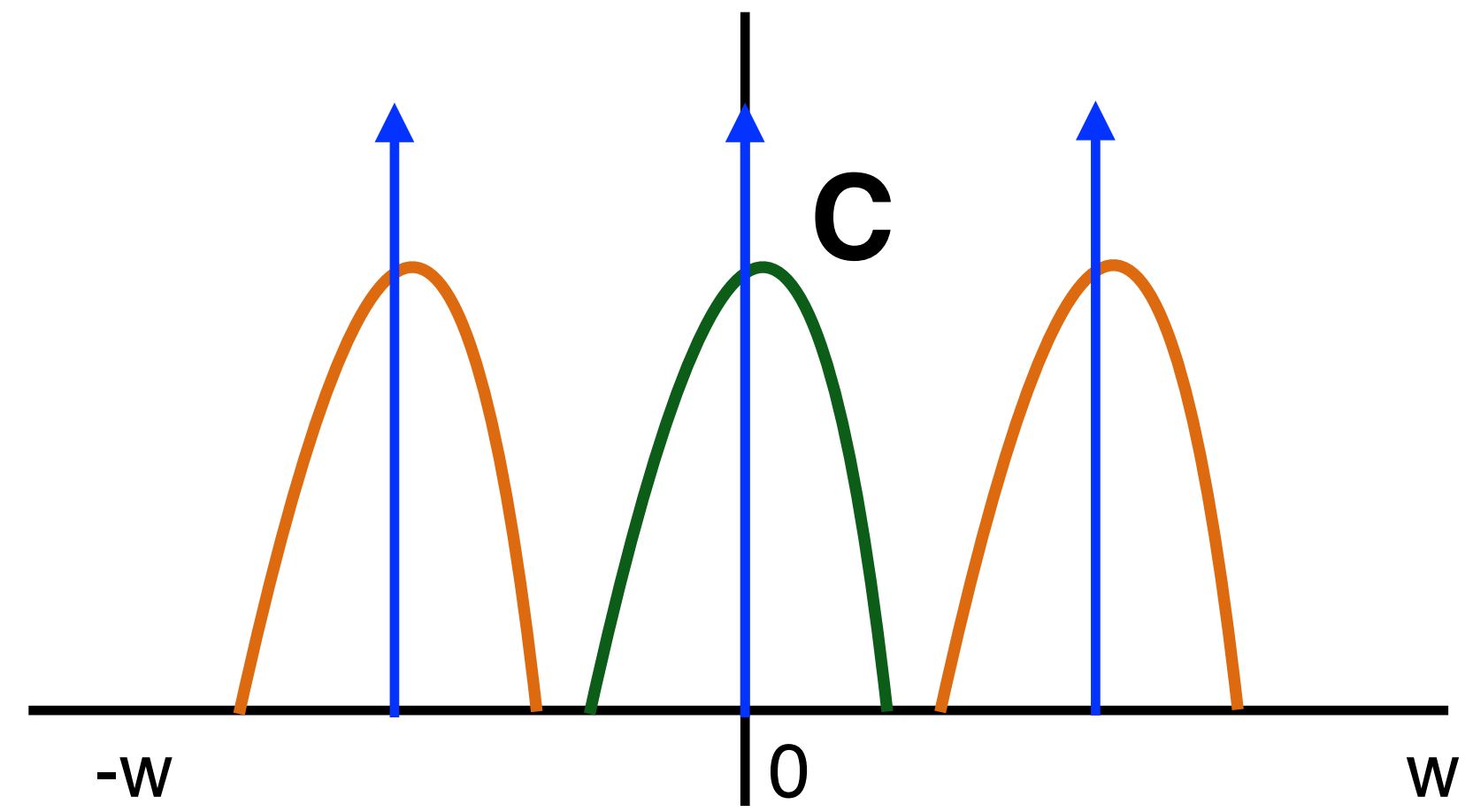
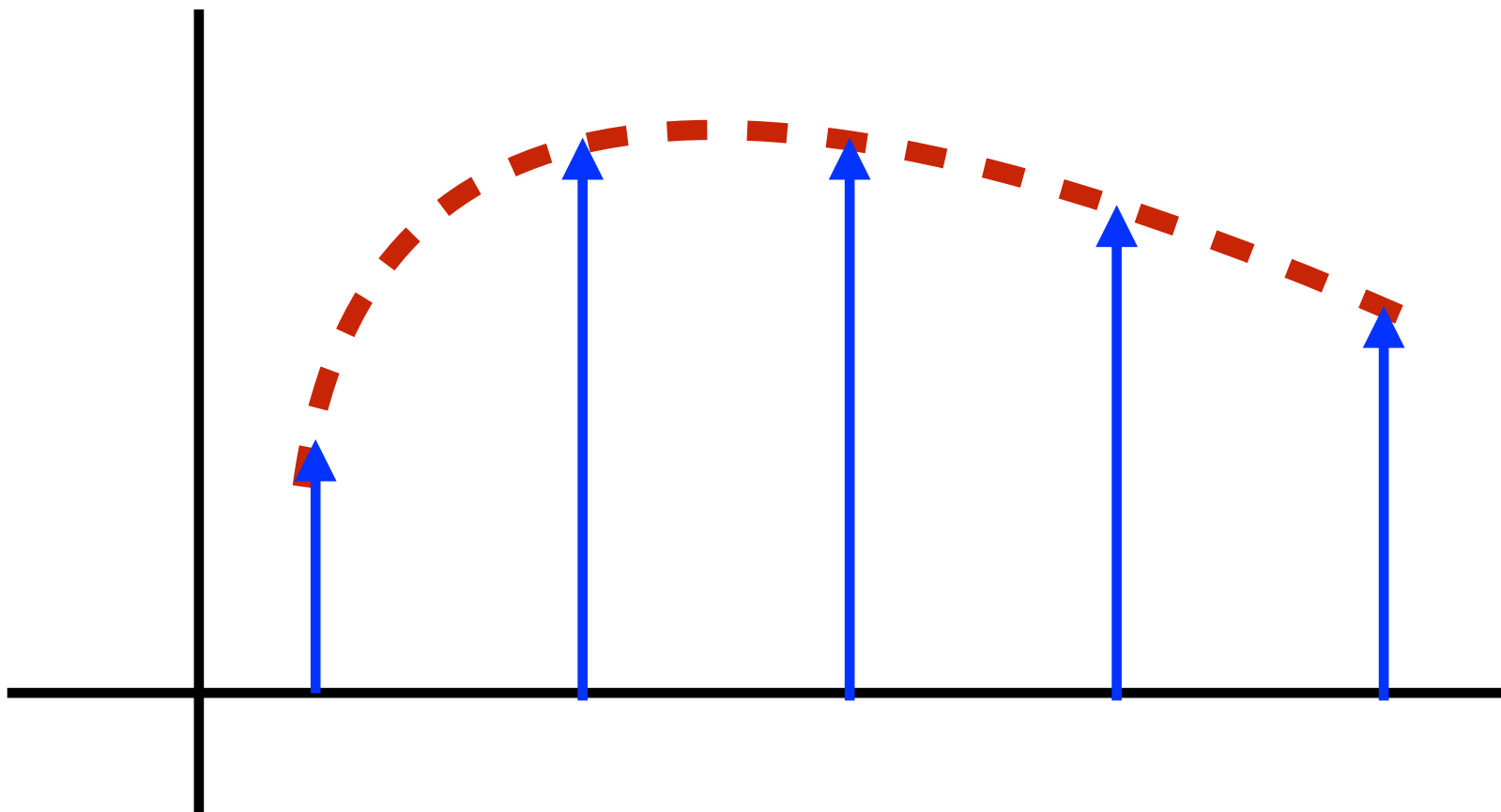


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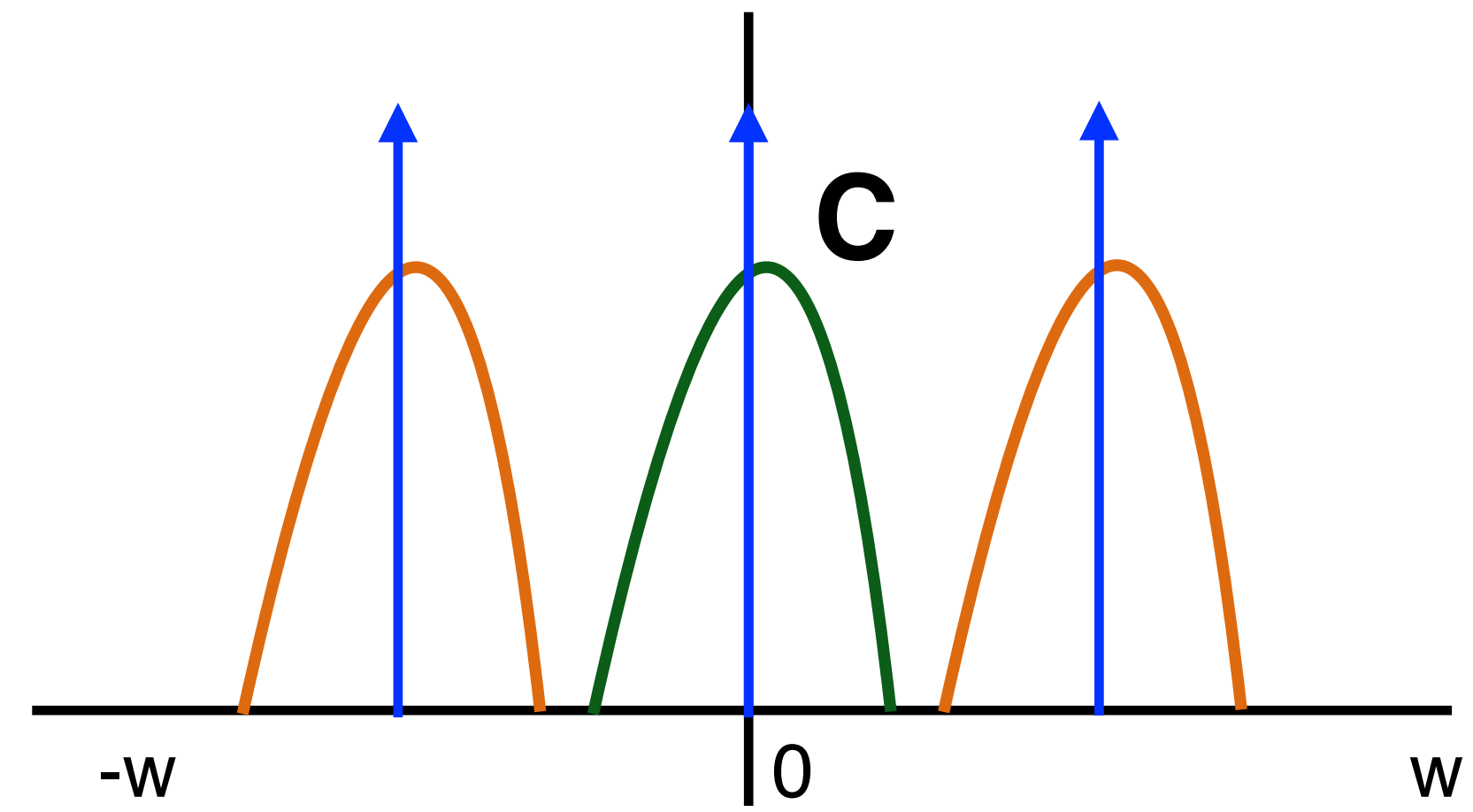
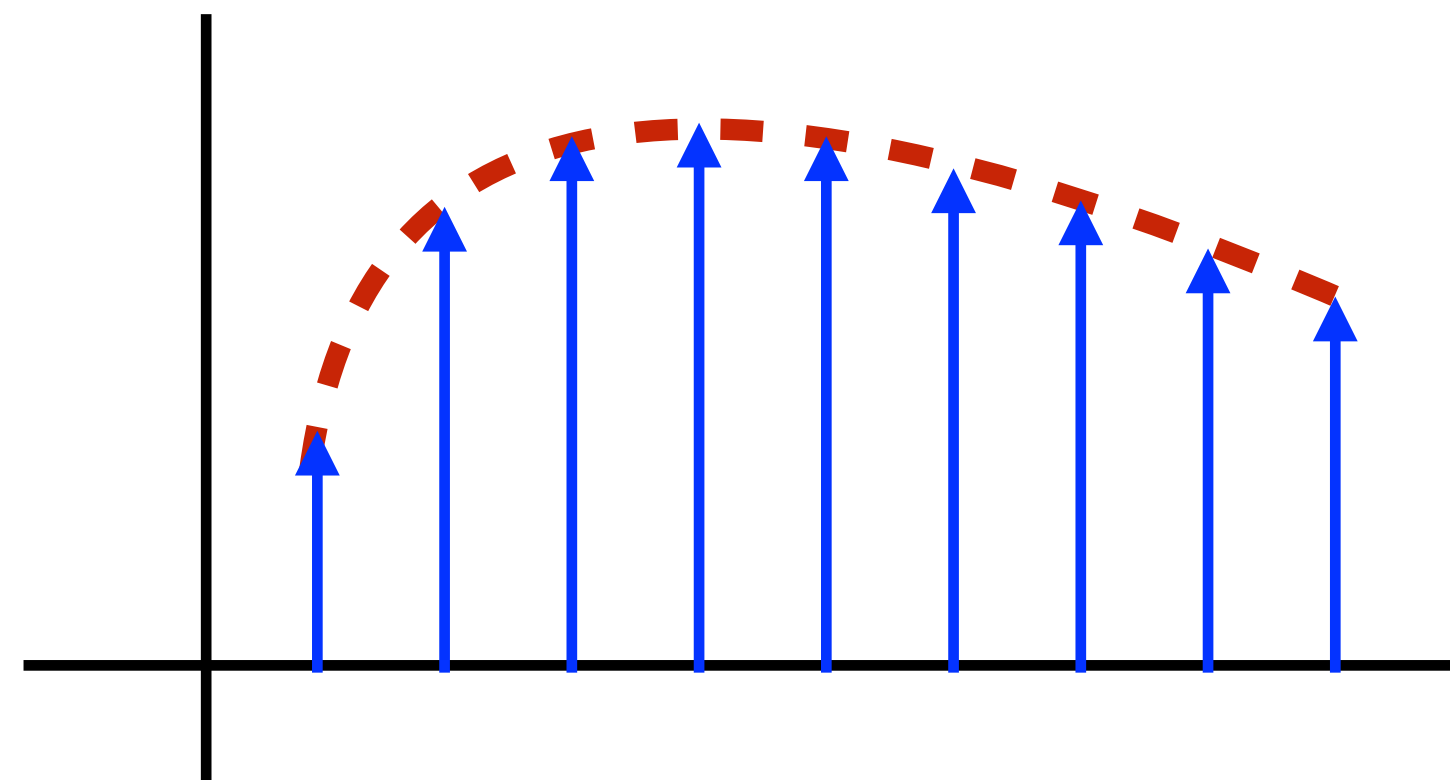


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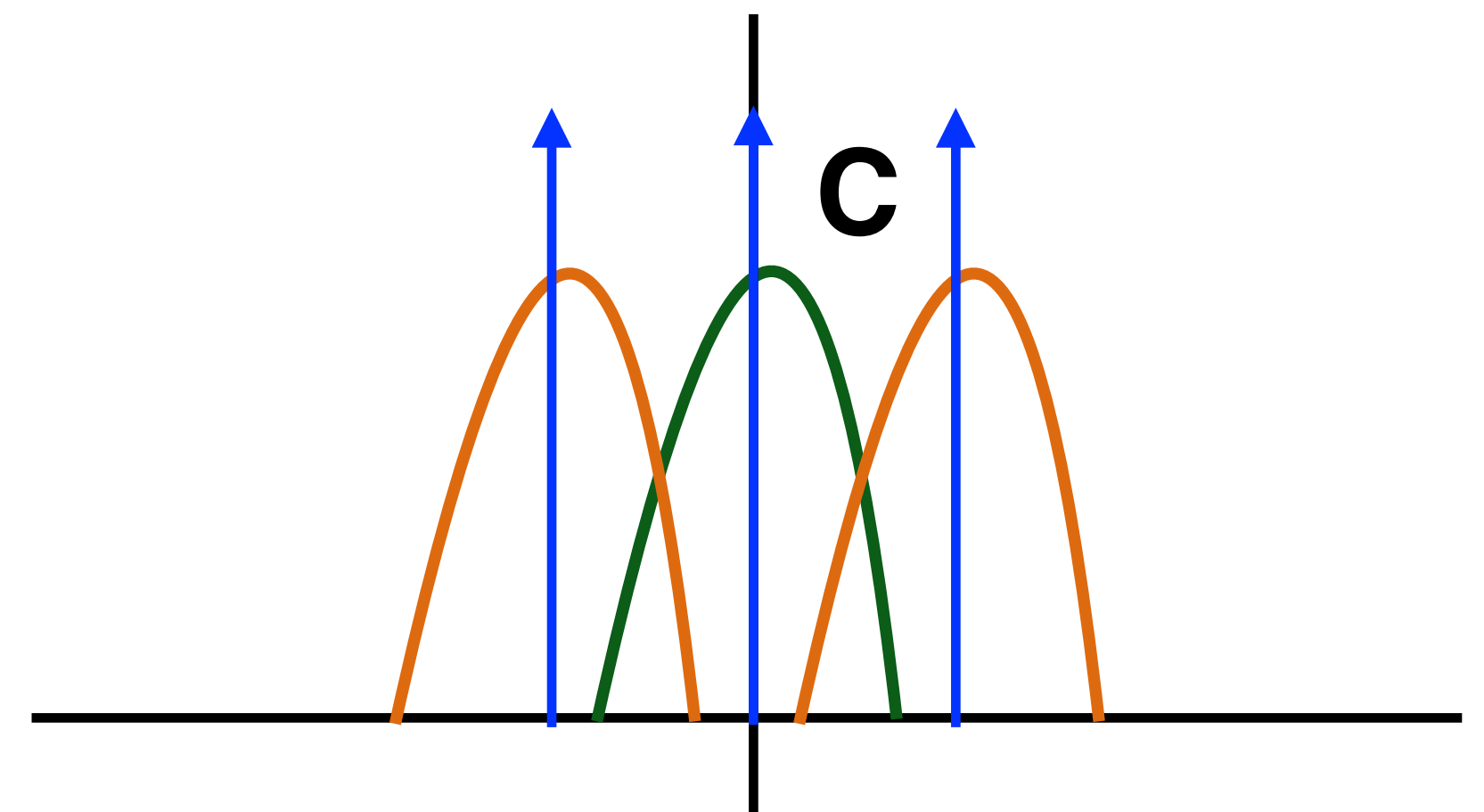
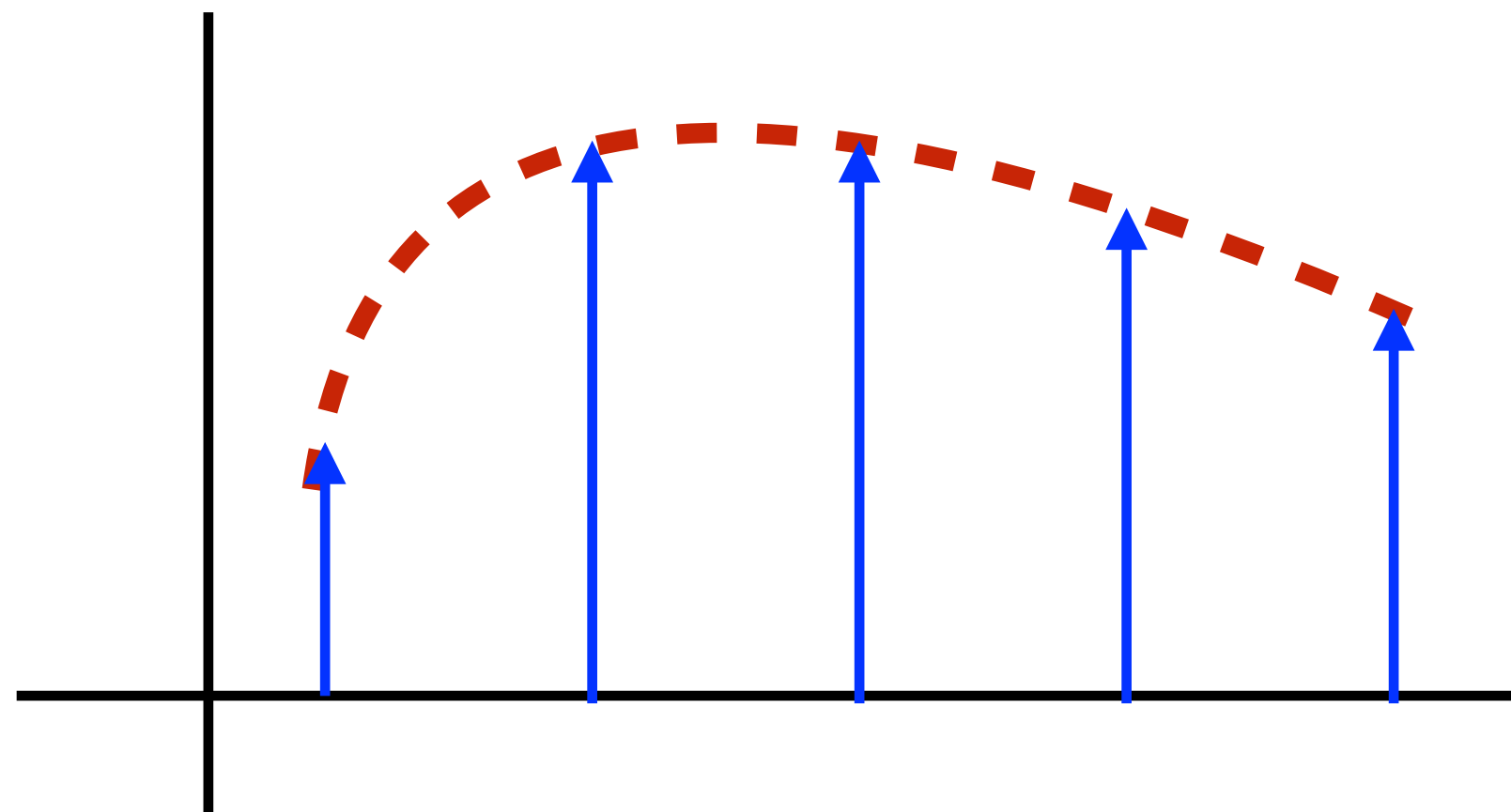


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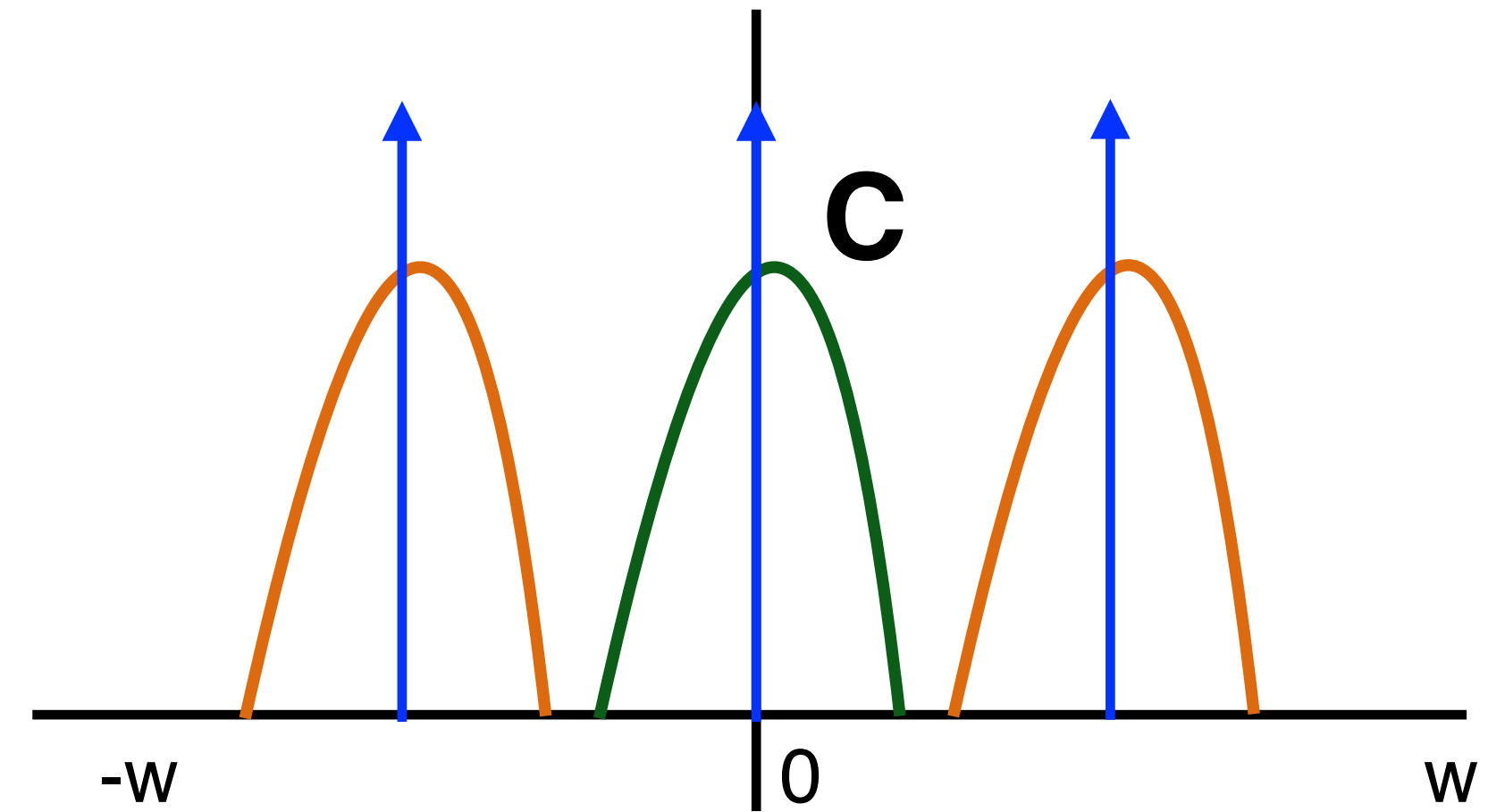
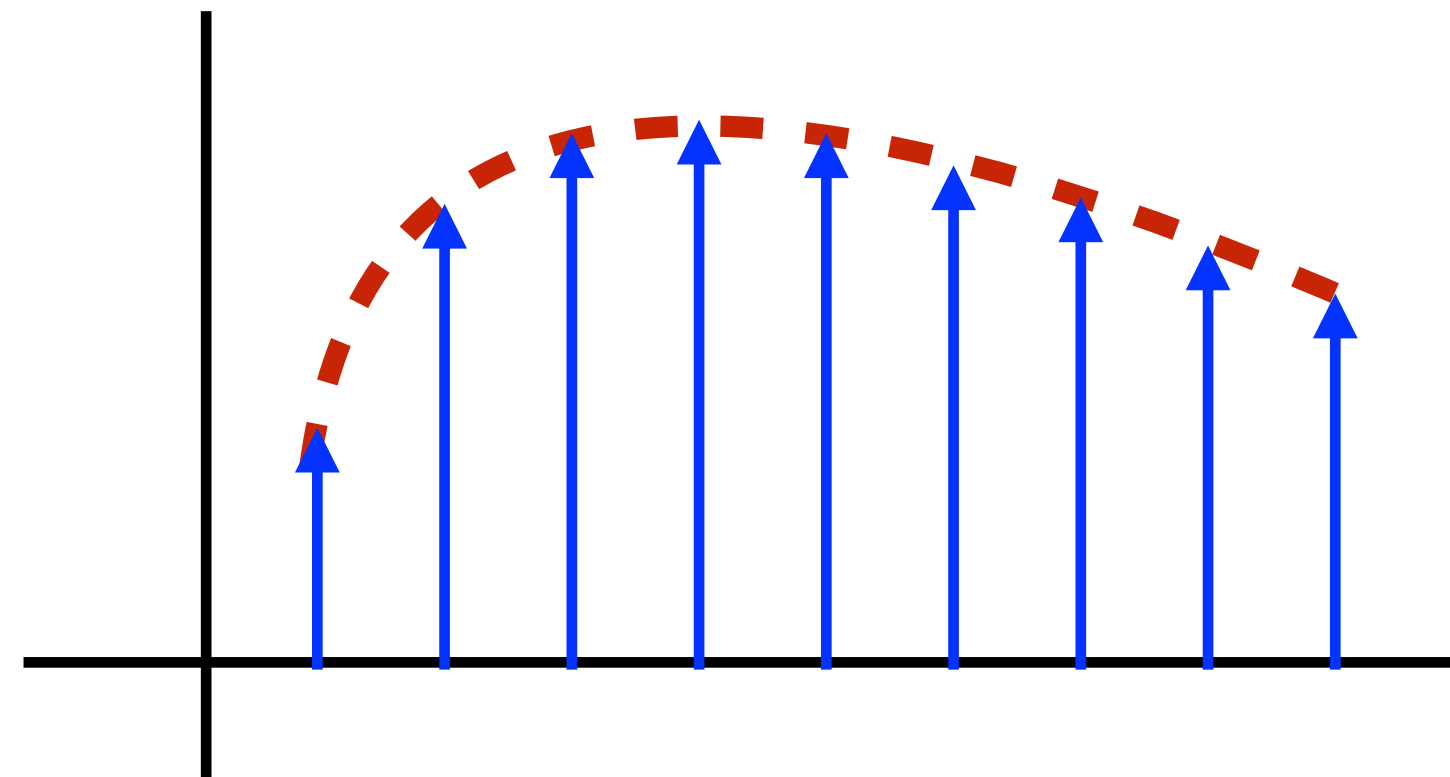


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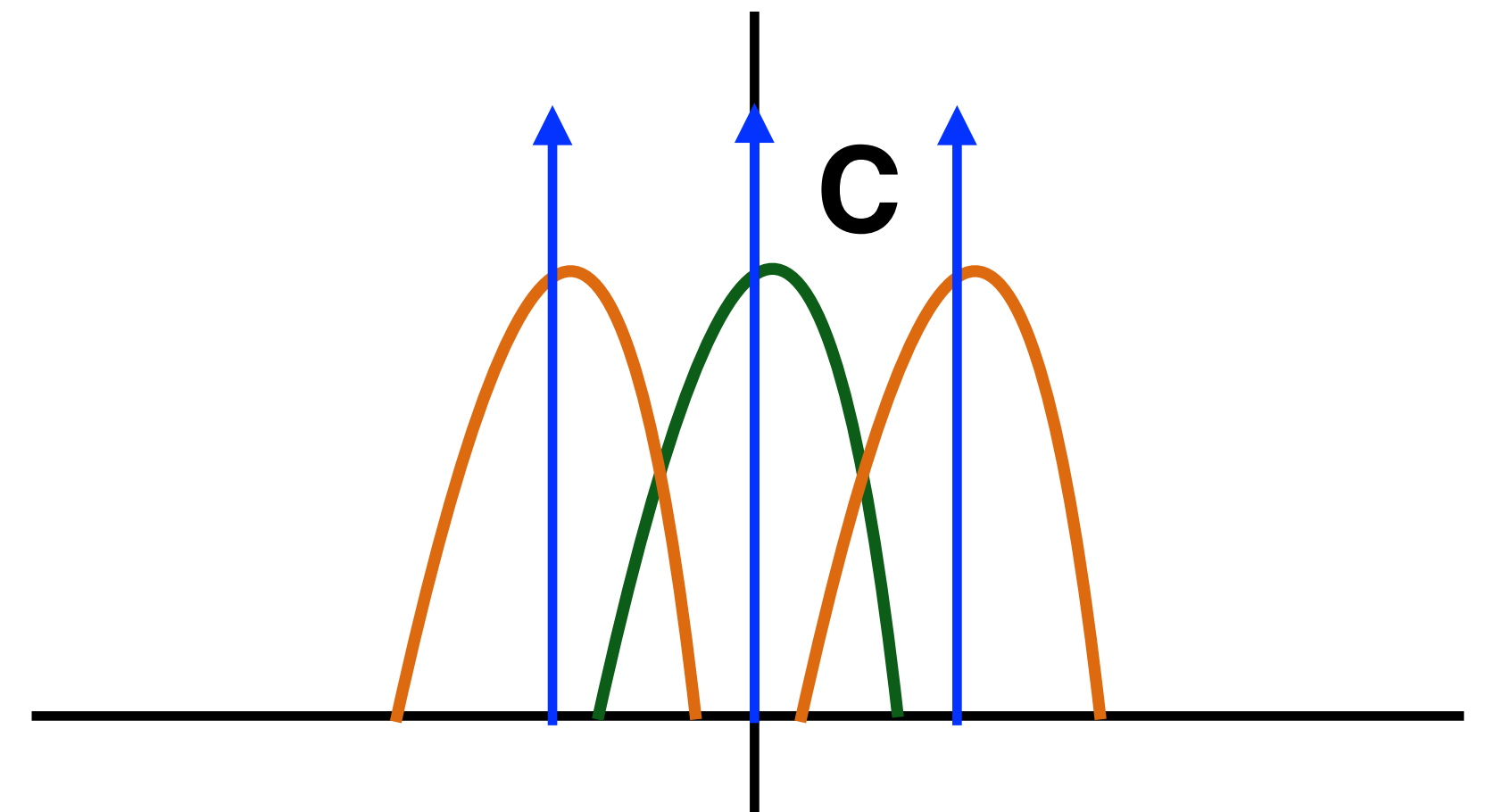
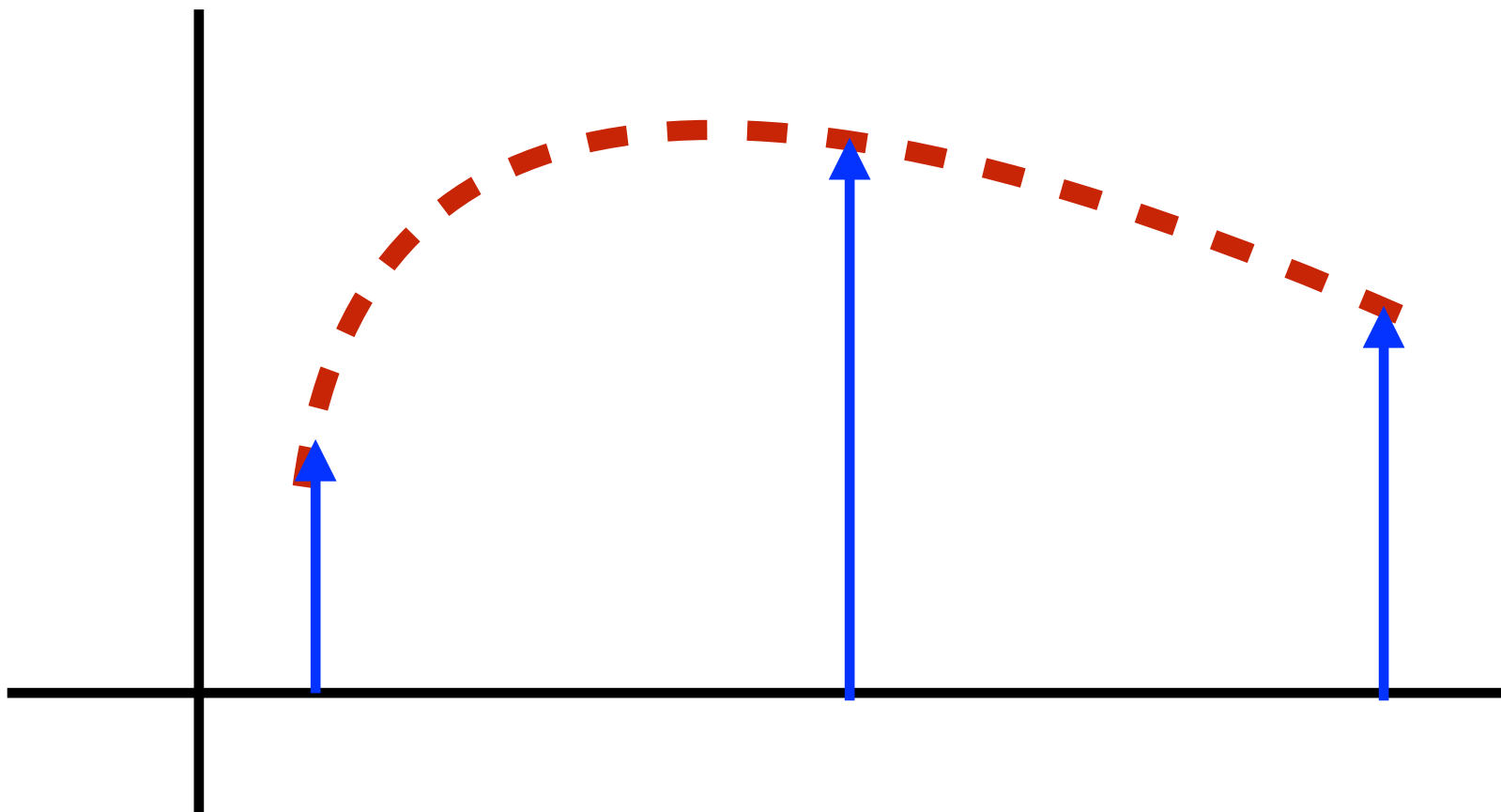


Error in Monte Carlo Integration

High Sampling Rate

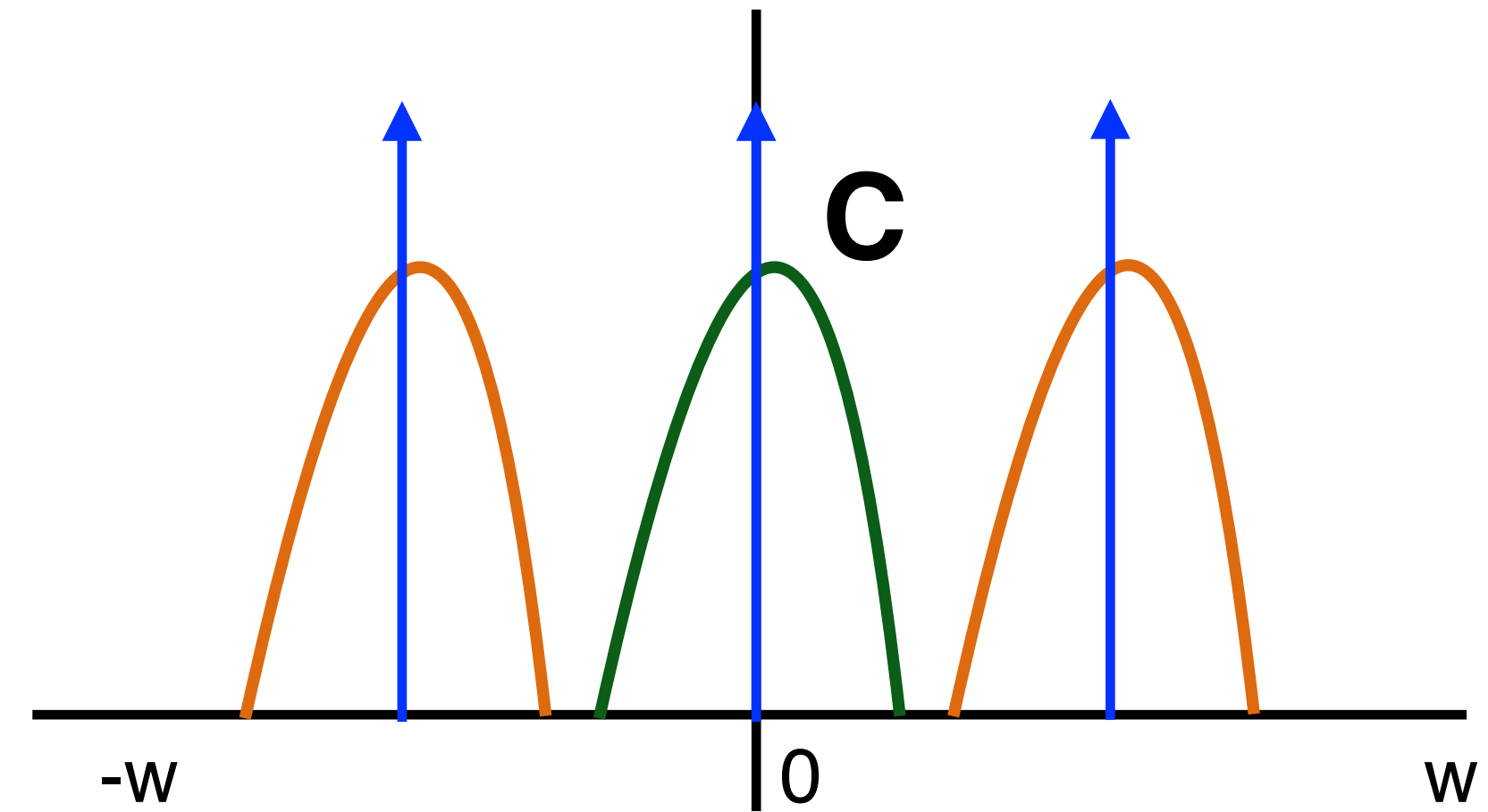
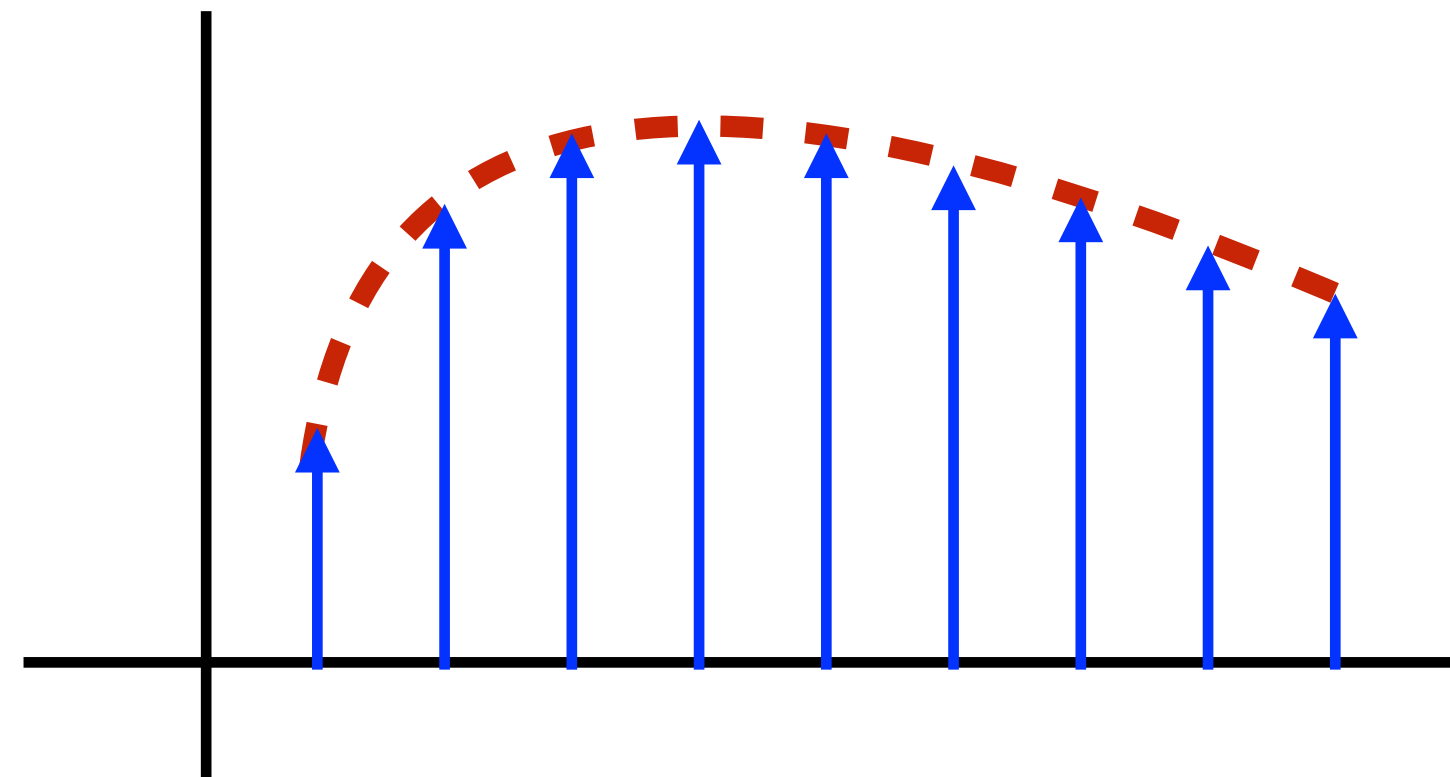


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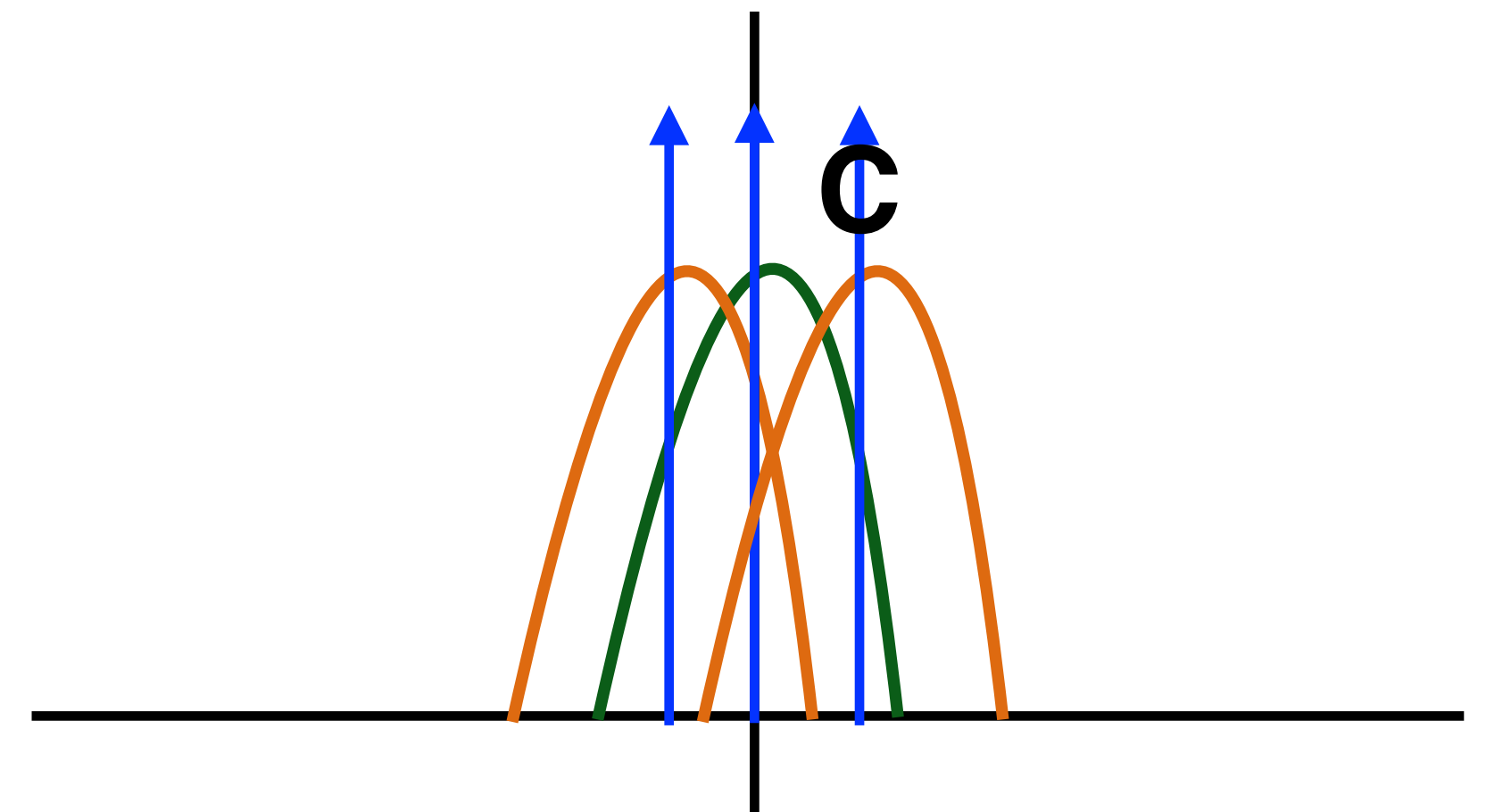
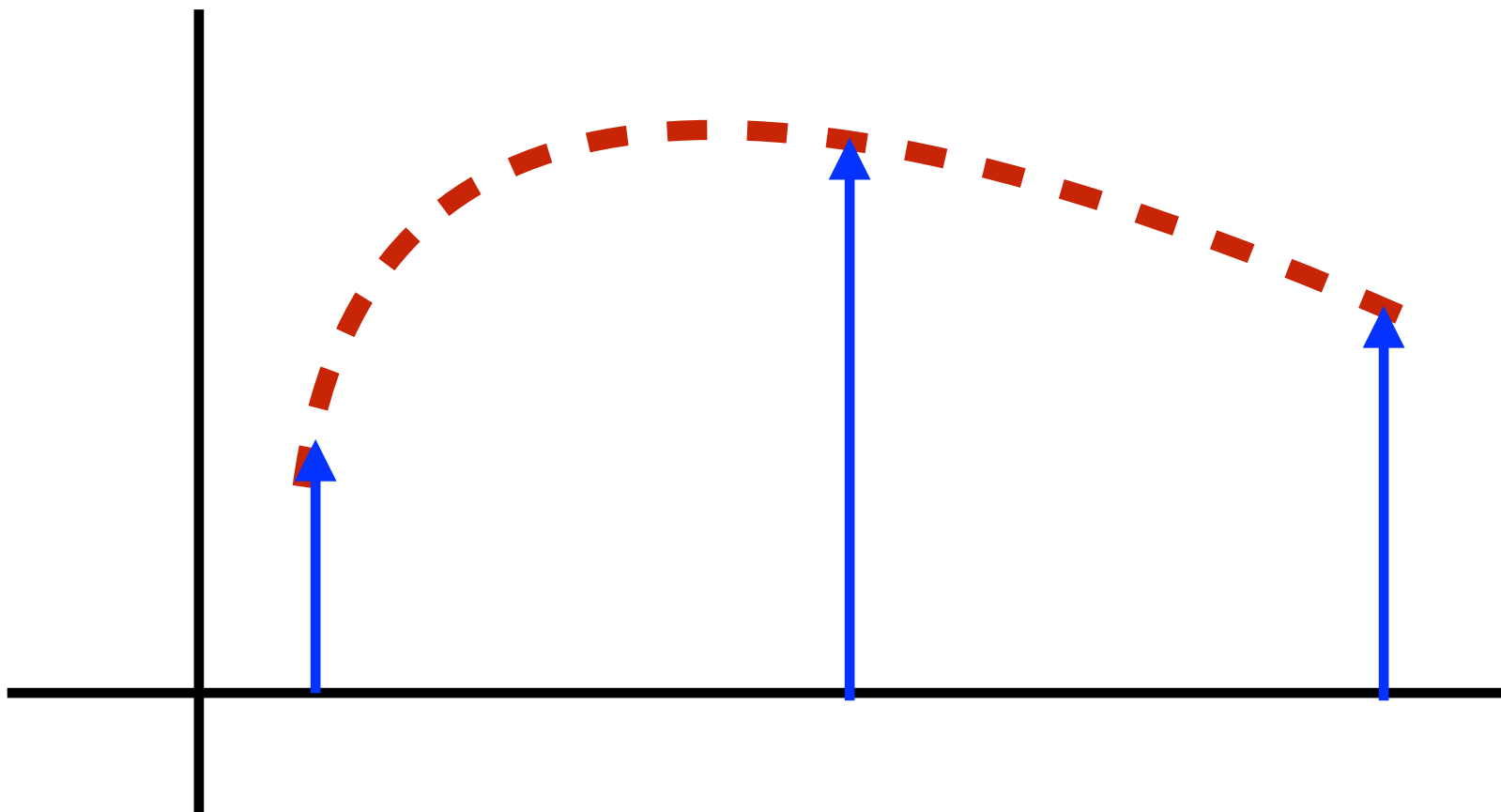


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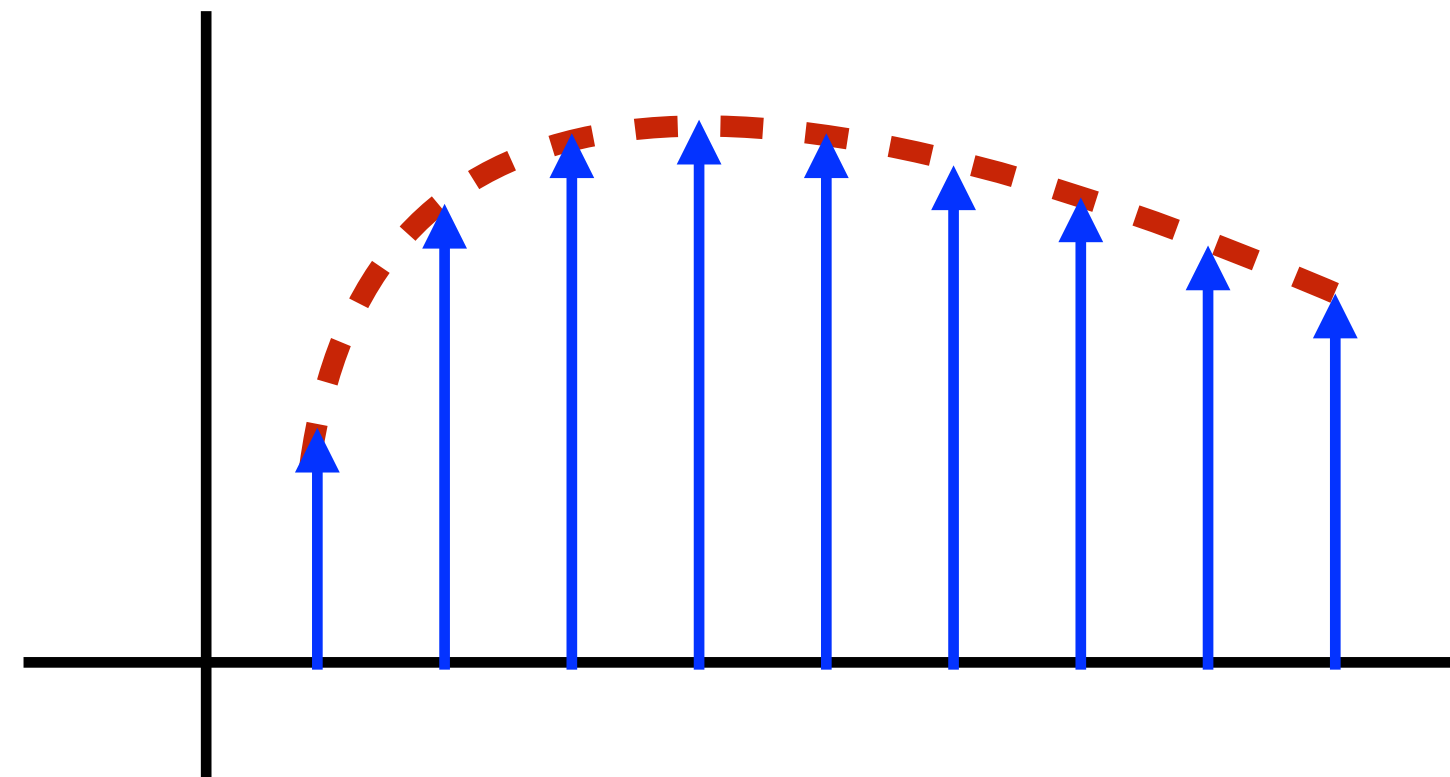


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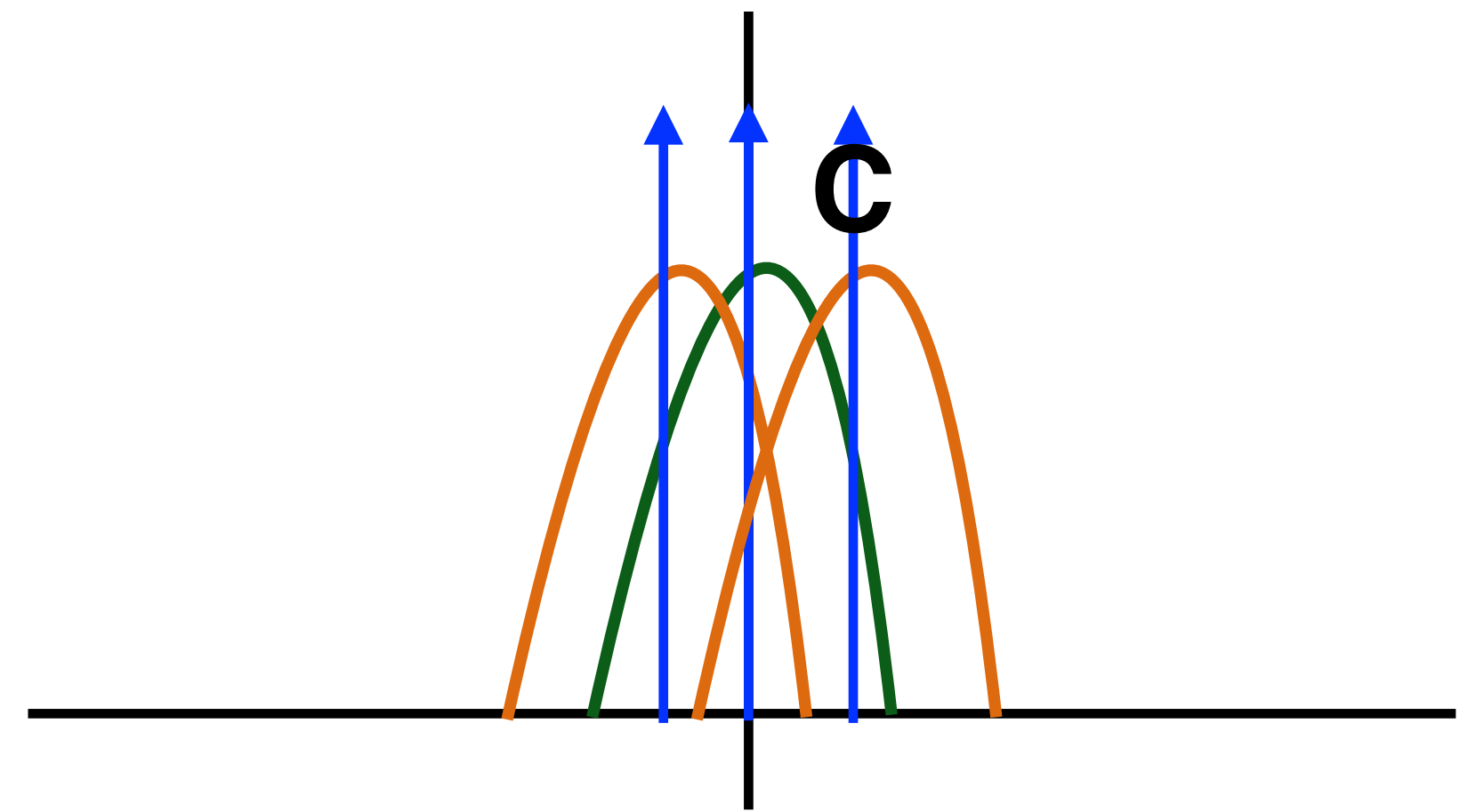
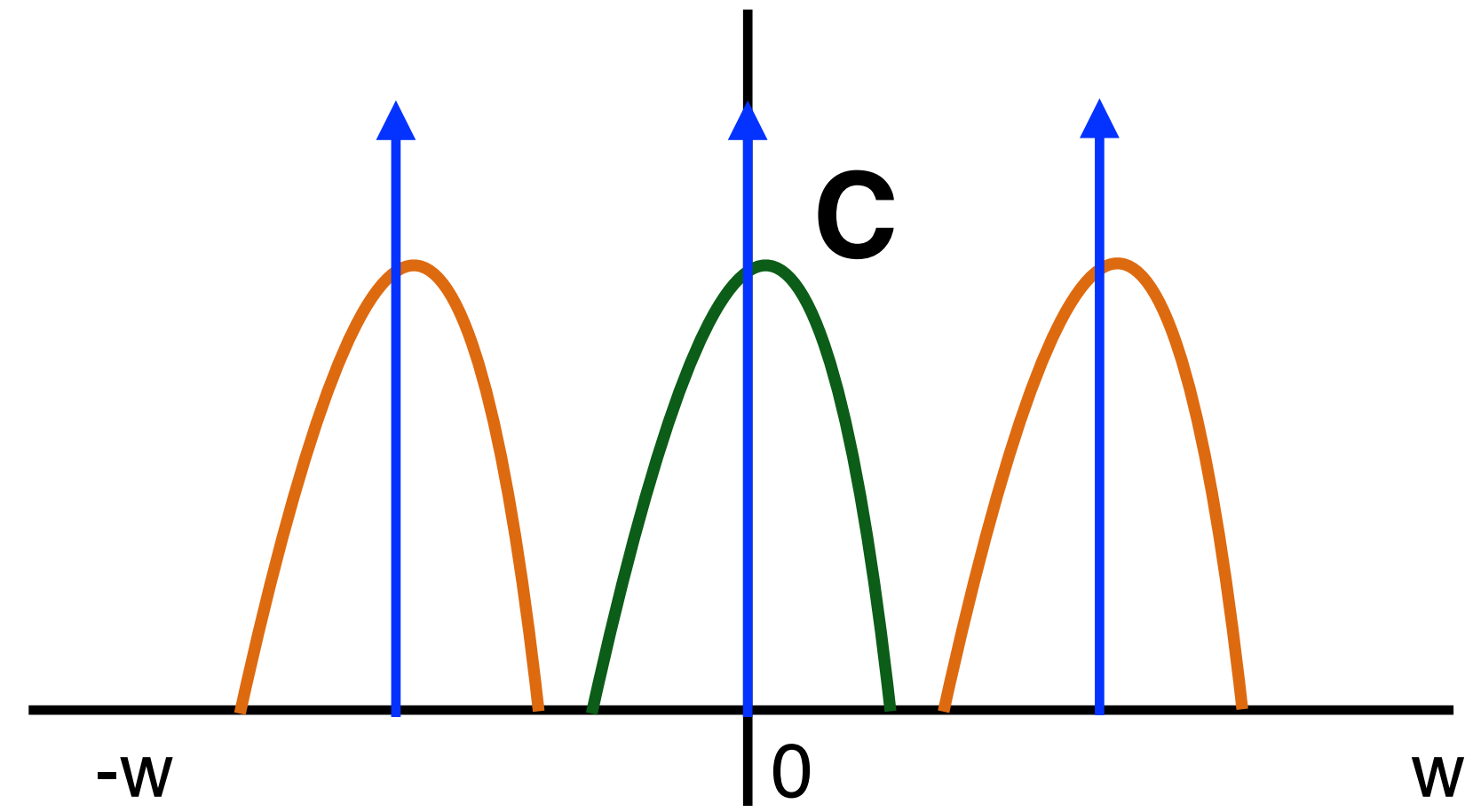
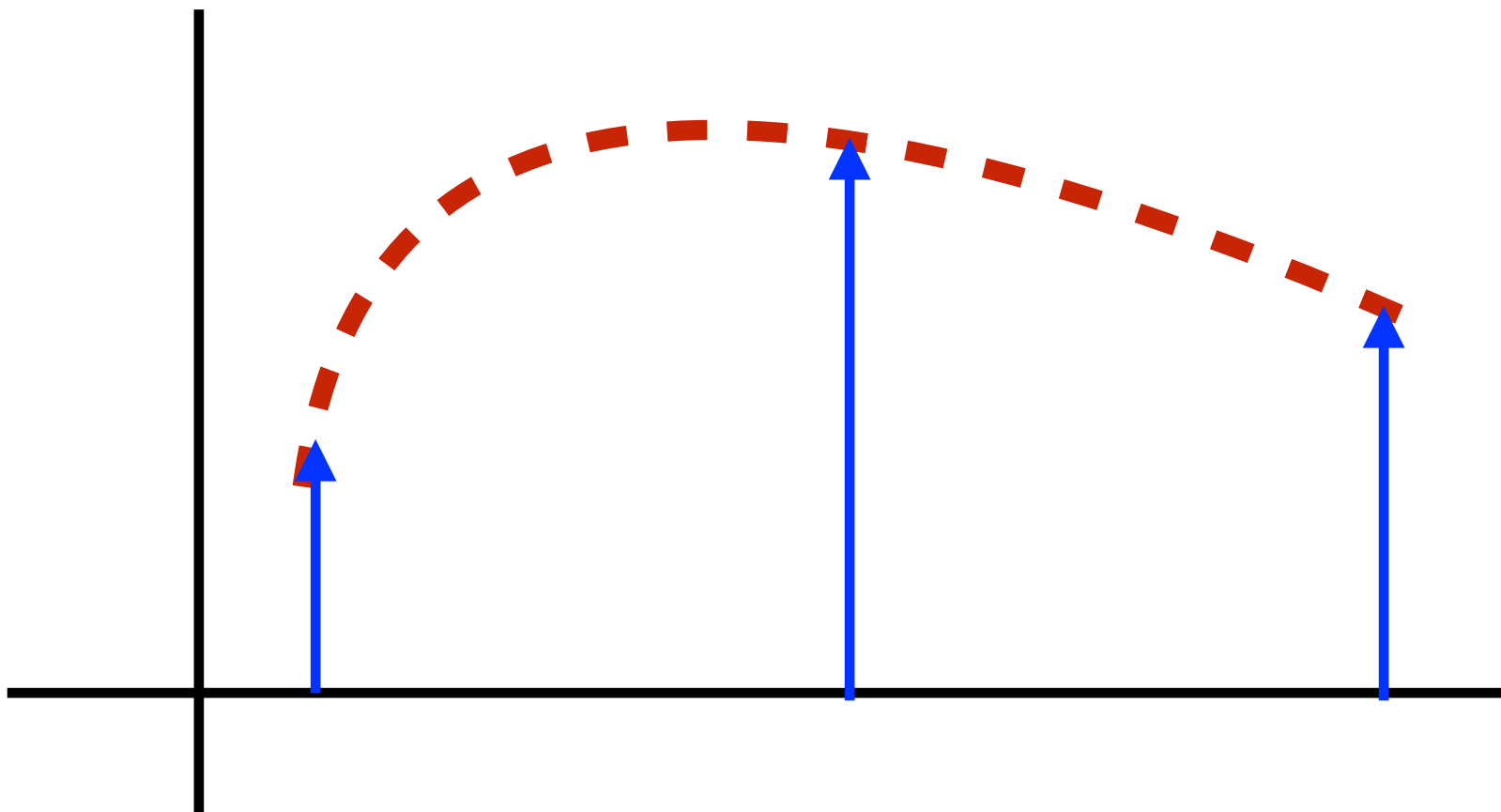


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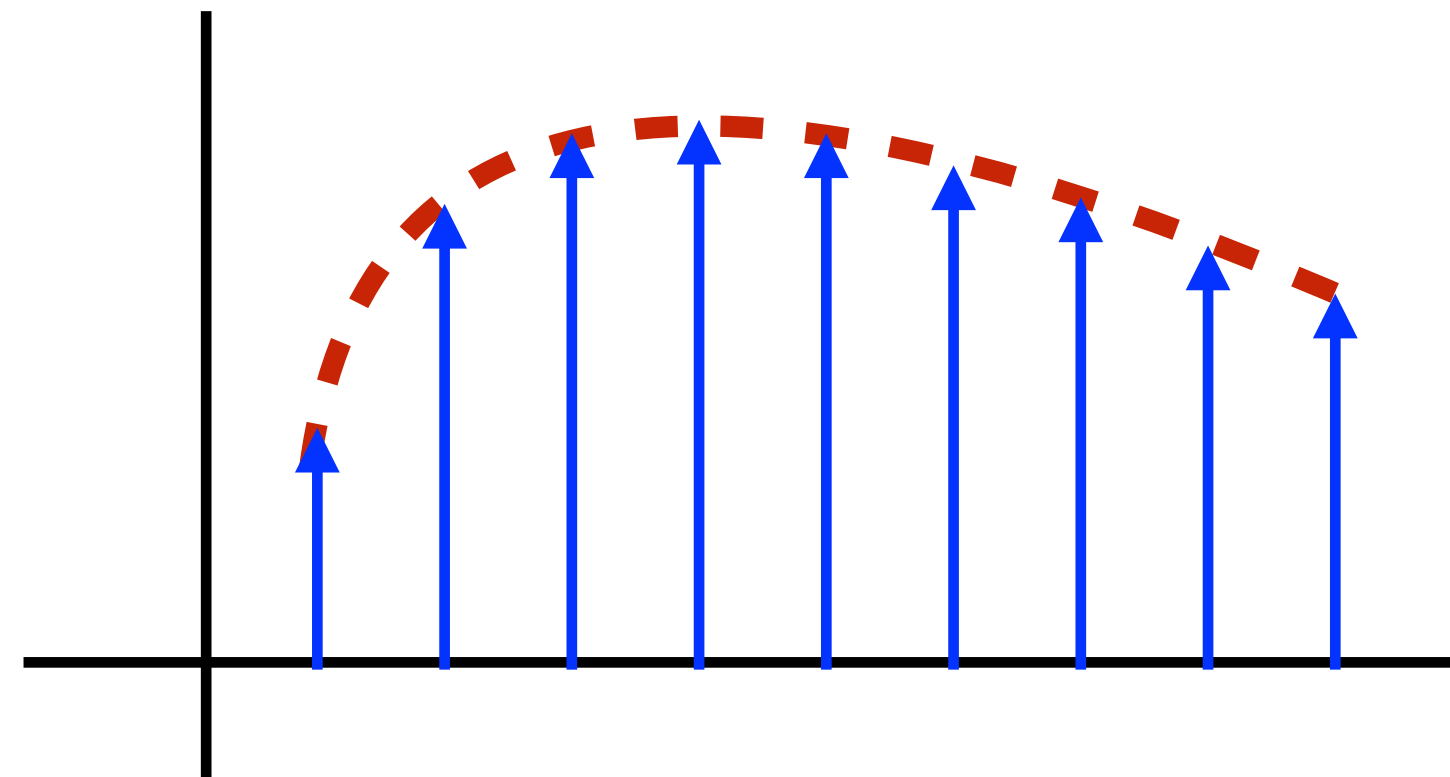


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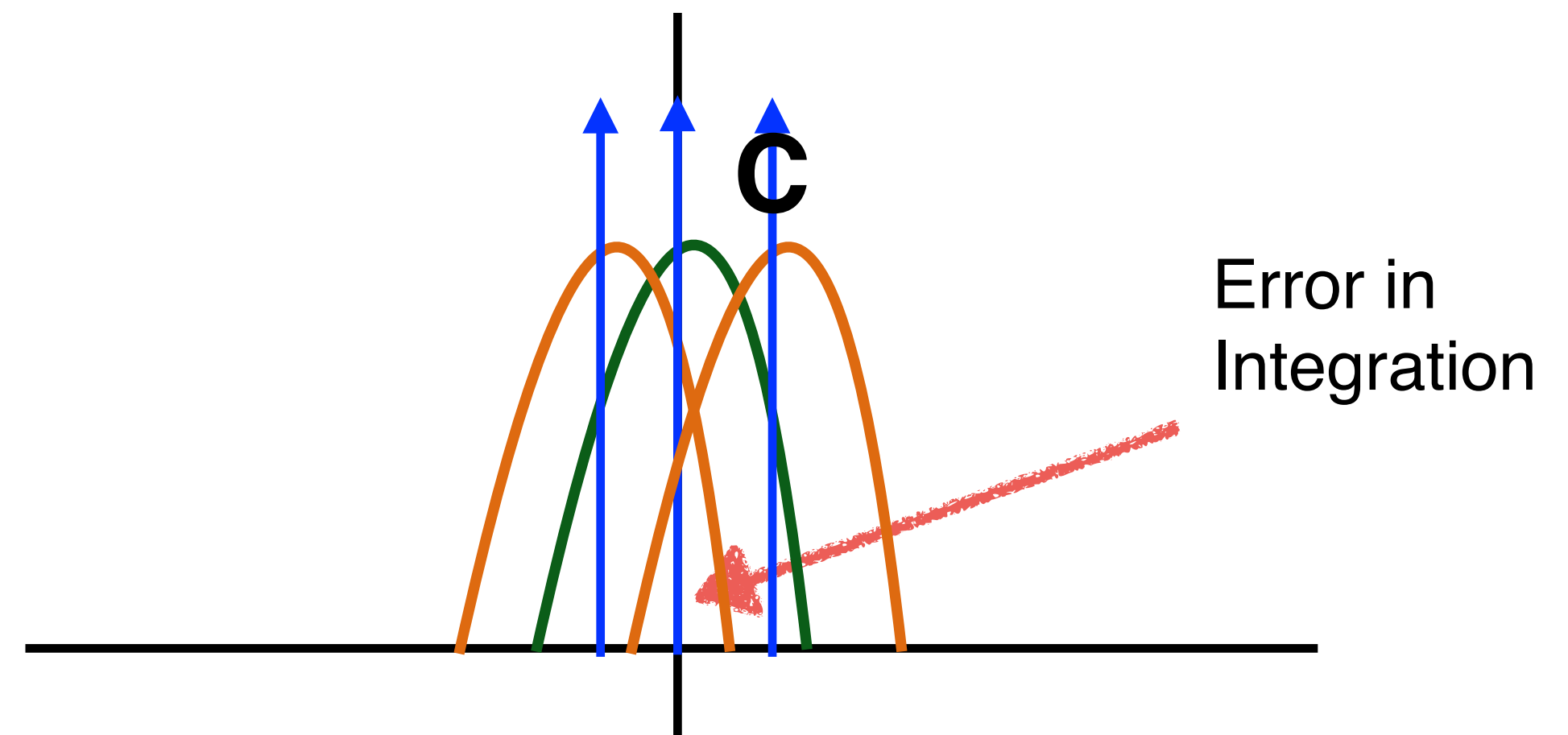
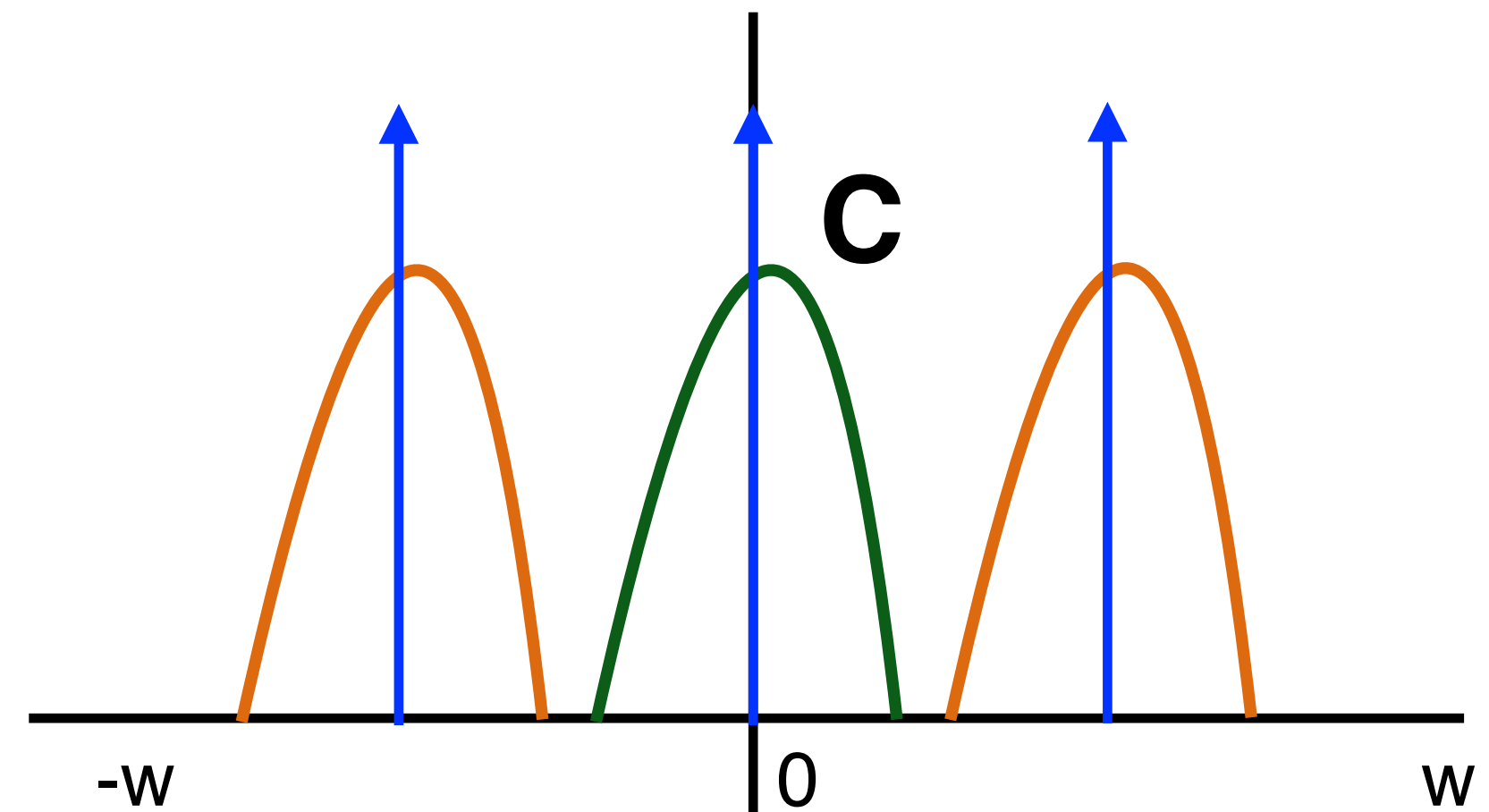
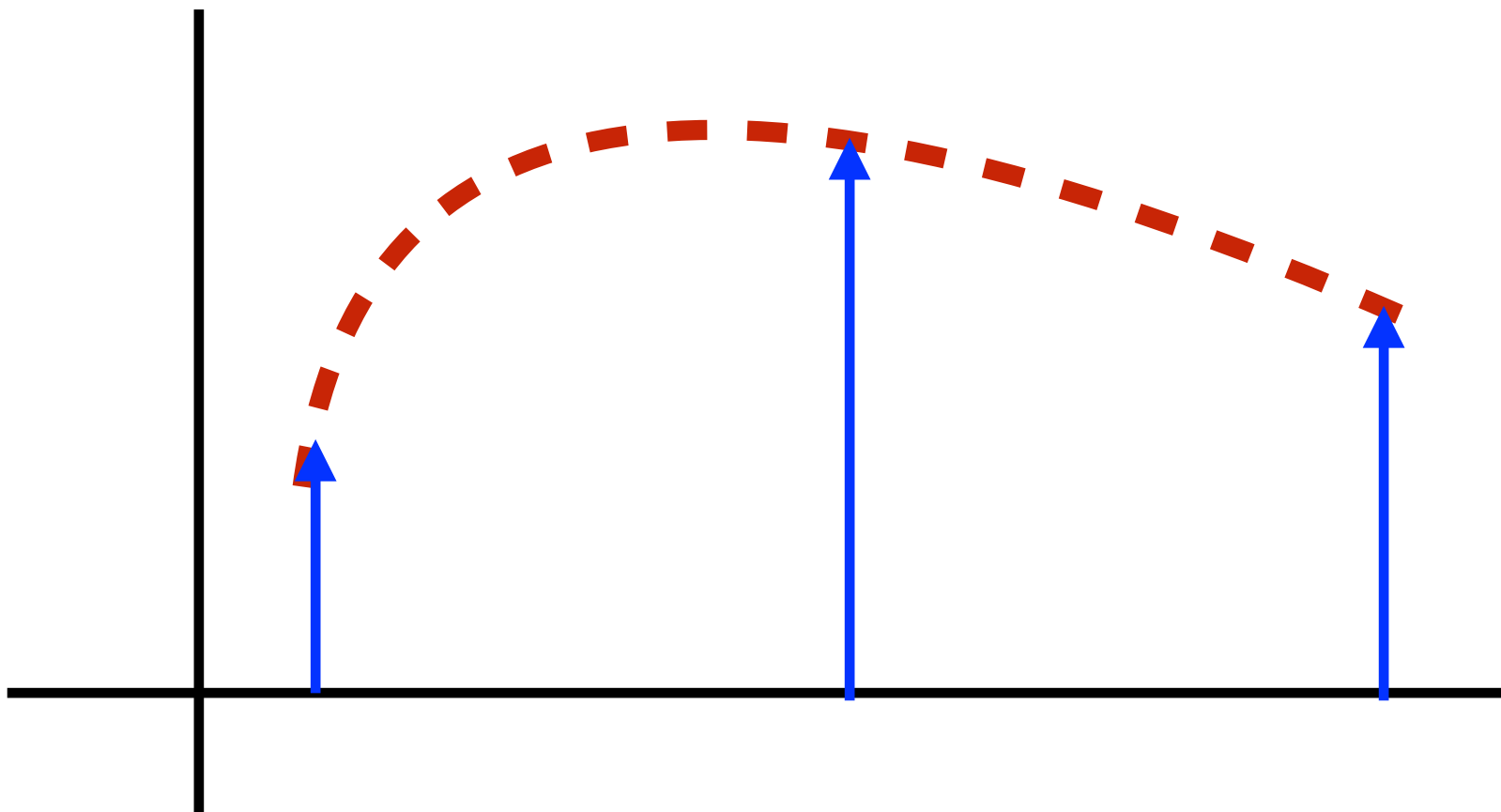


Error in Monte Carlo Integration

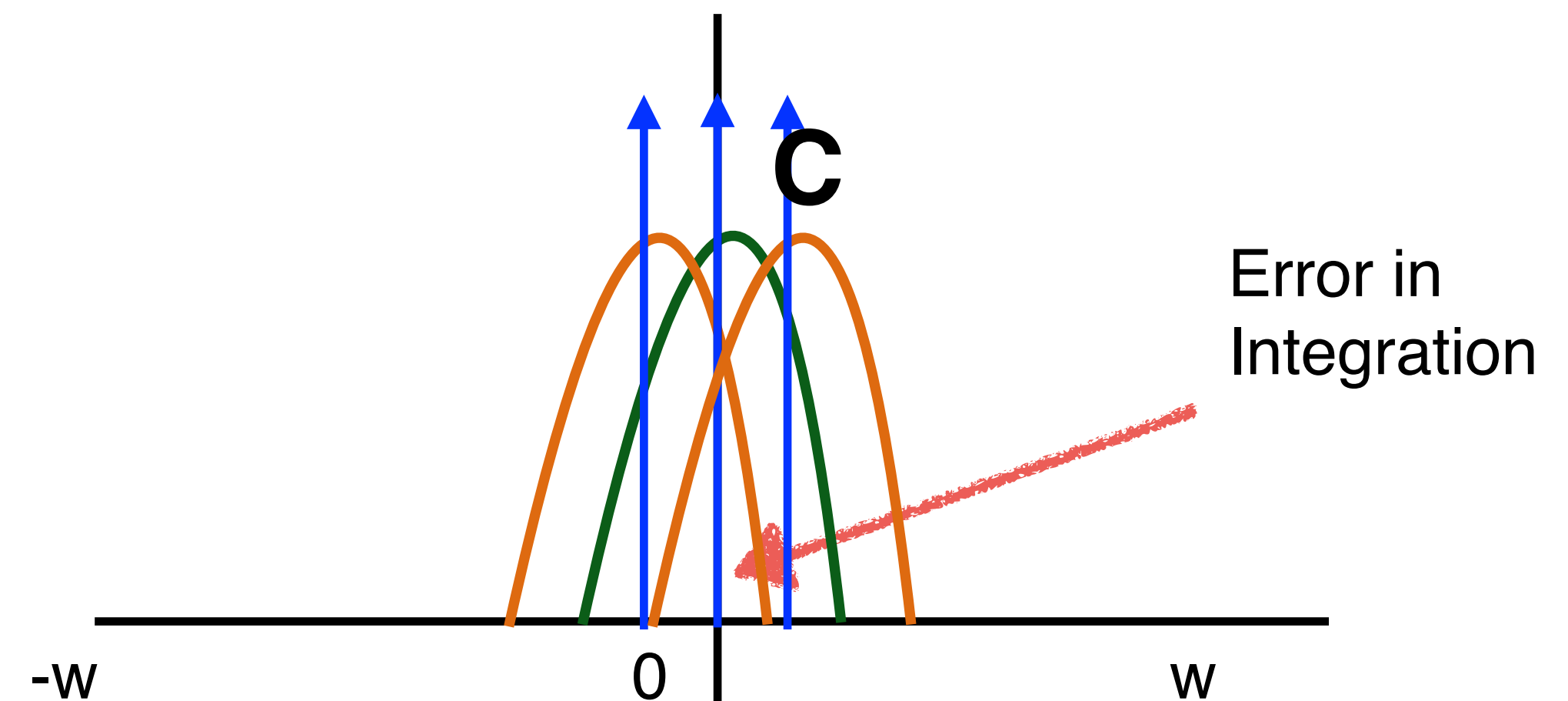
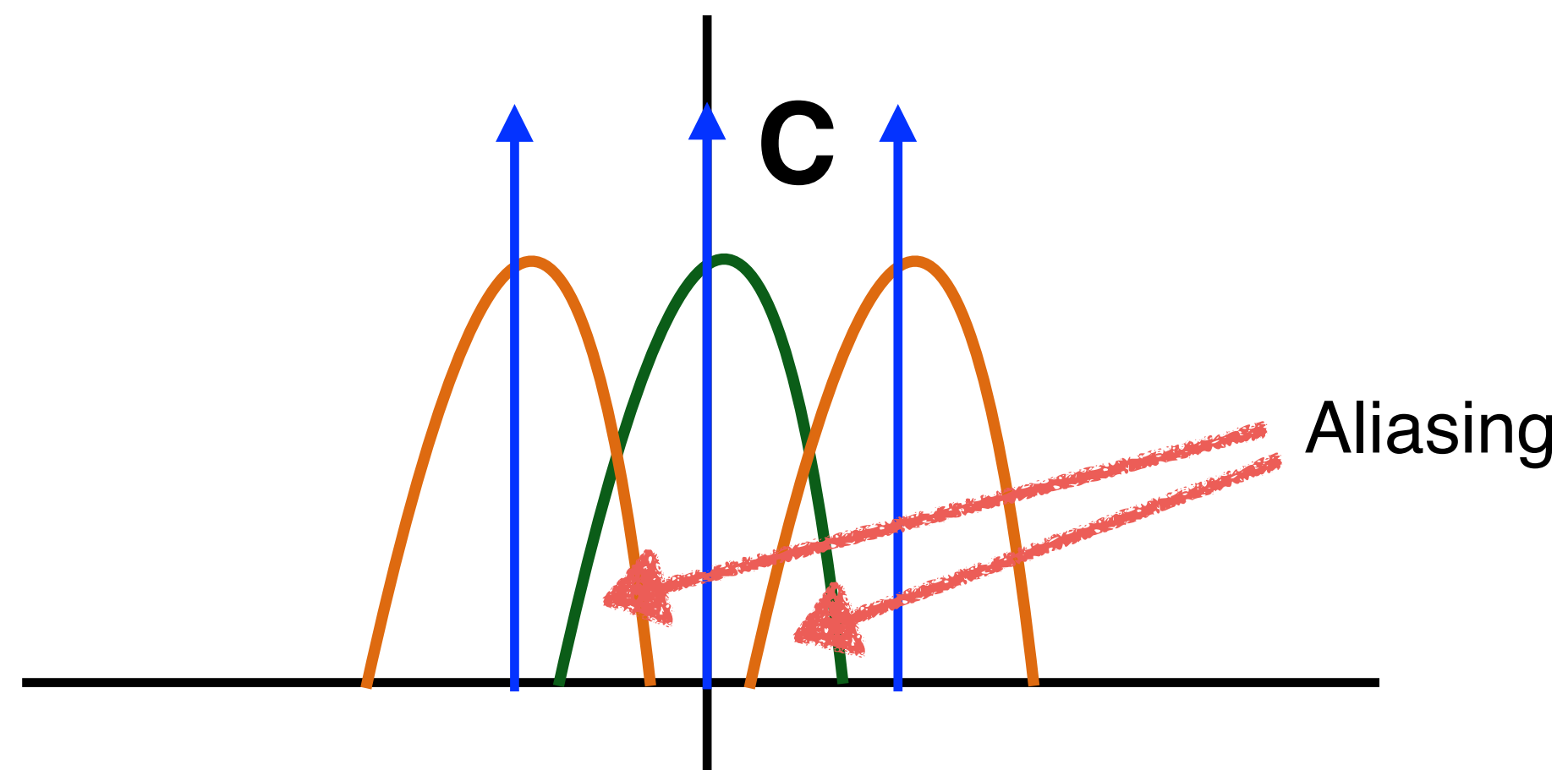
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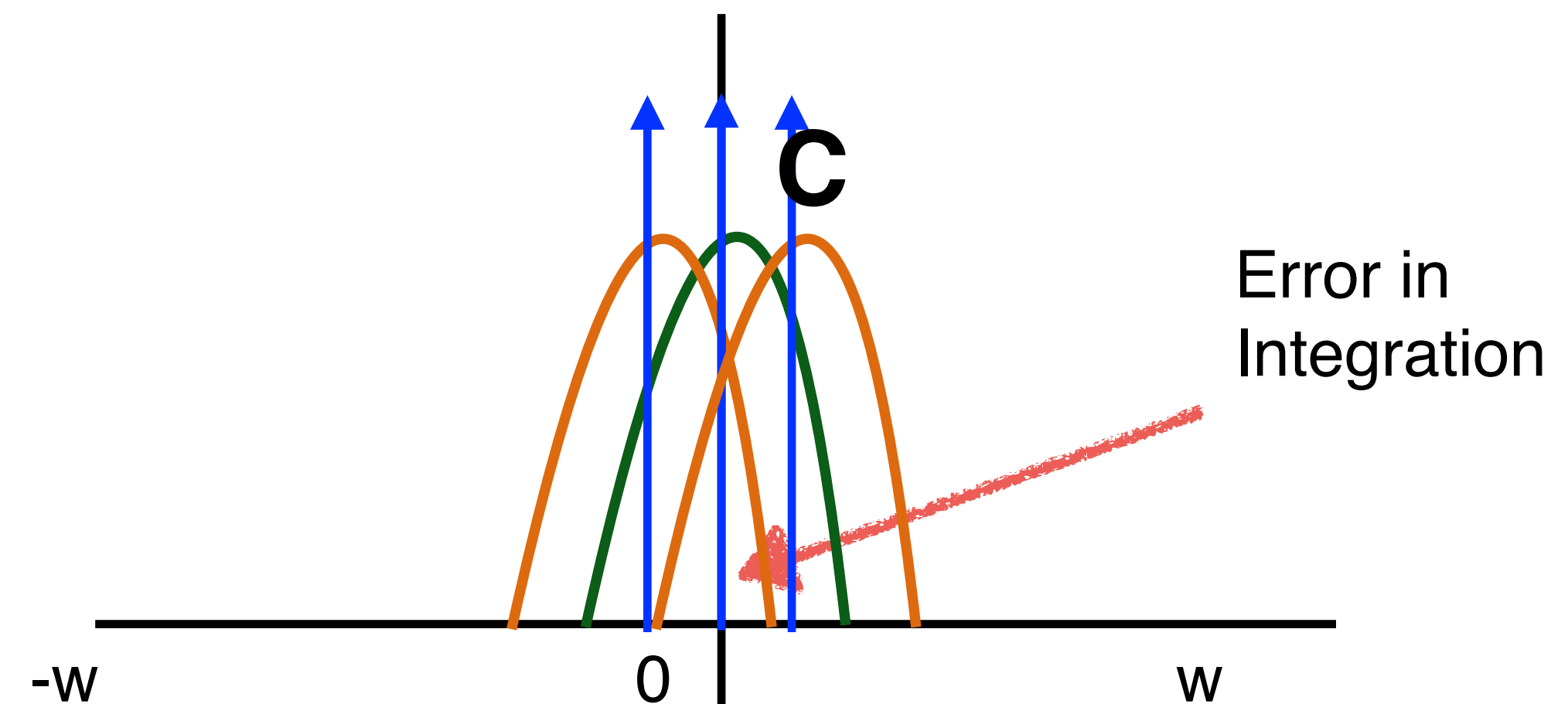
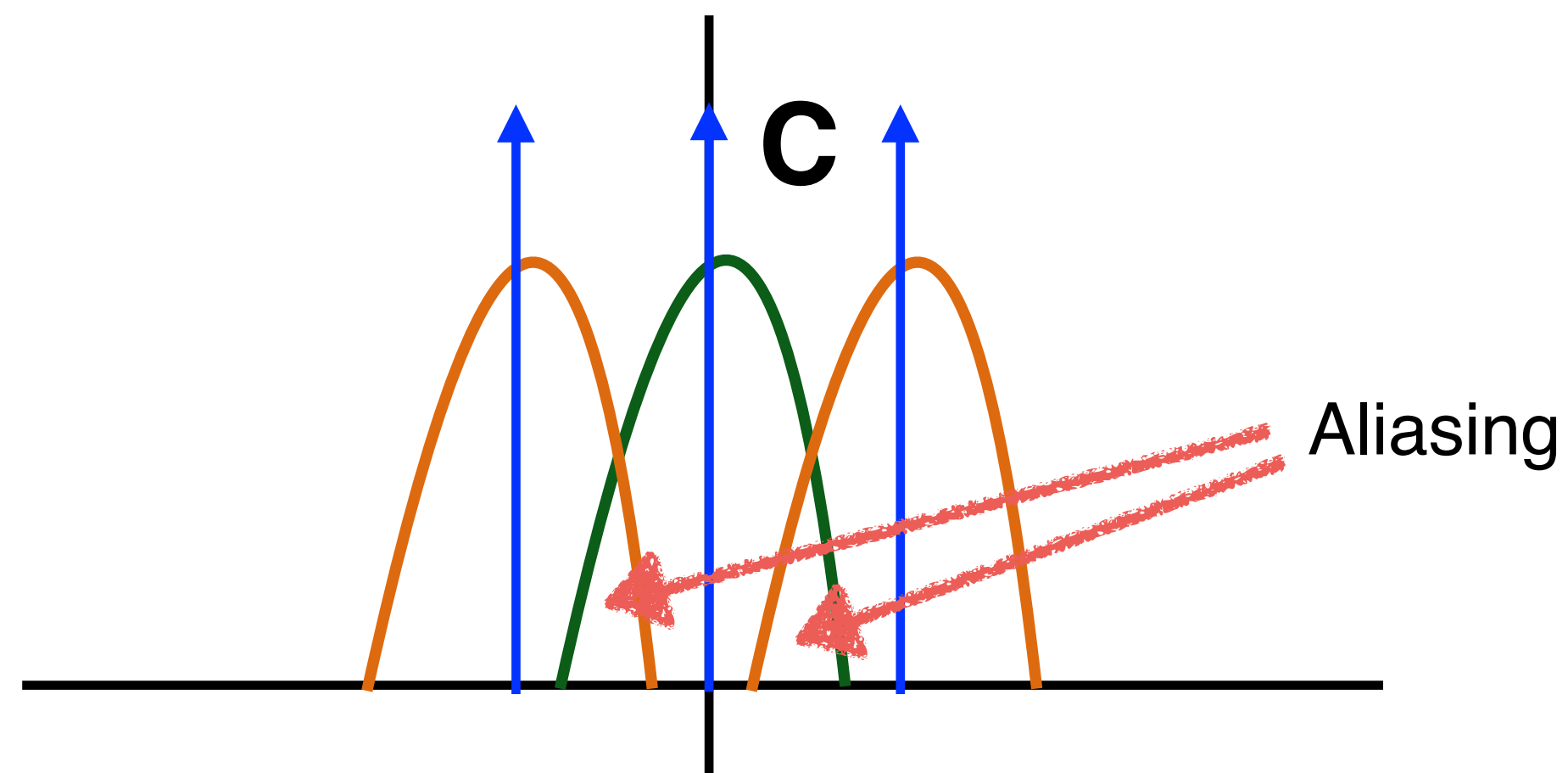


Aliasing (Reconstruction) vs. Error (Integration)



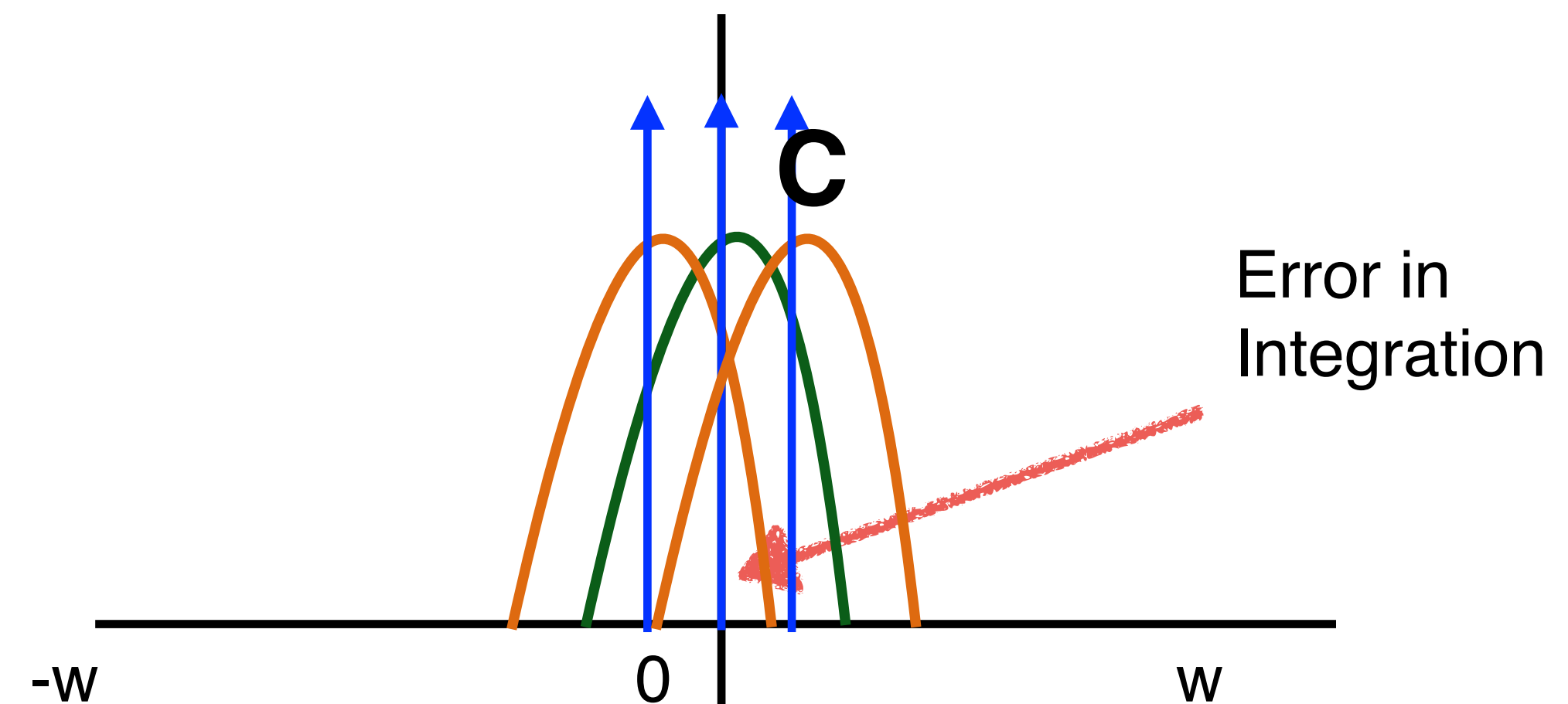
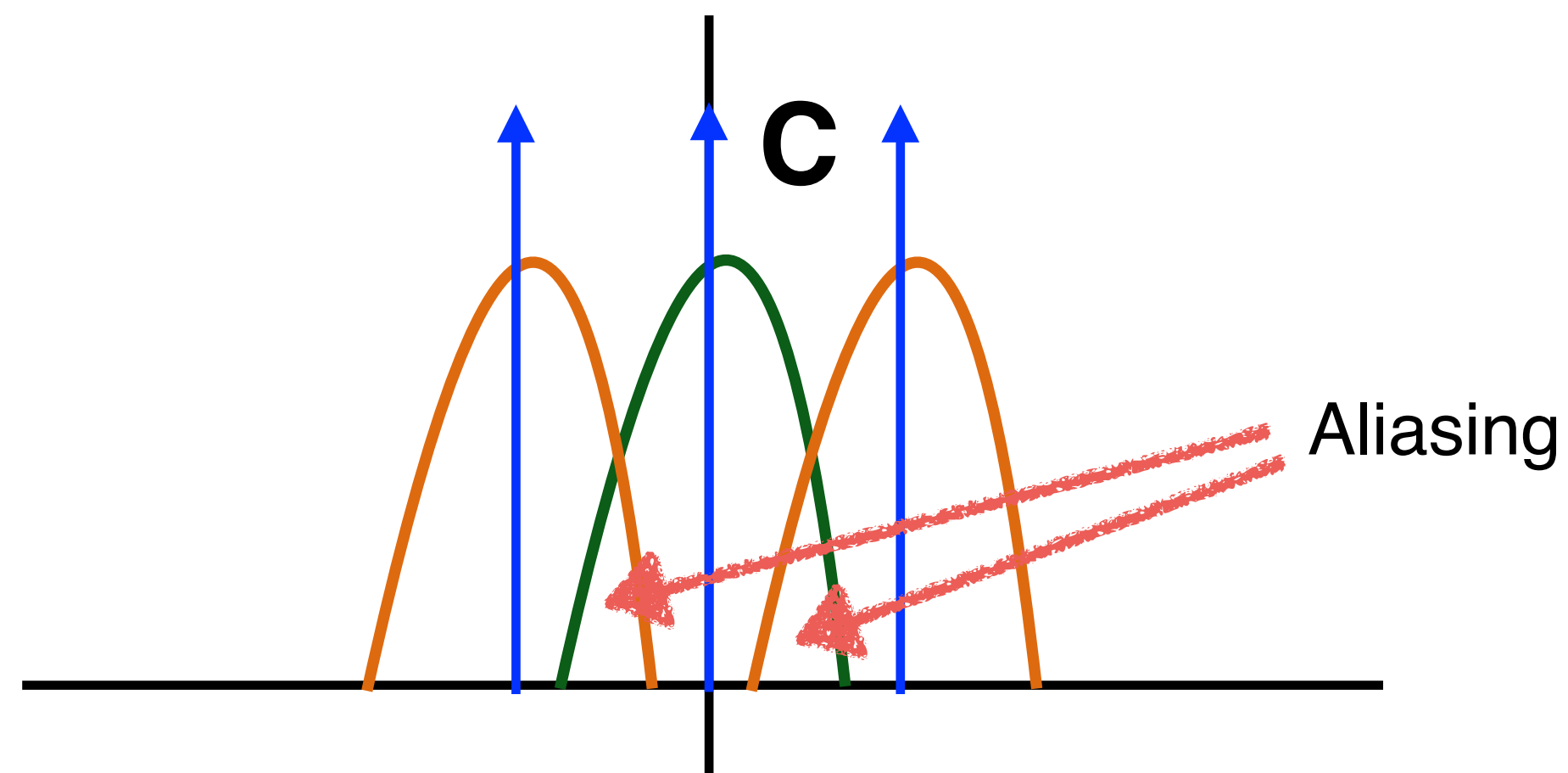
Aliasing (Reconstruction) vs. Error (Integration)

Fredo Durand [2011]
Belcour et al. [2013]



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Integration in the Fourier Domain

Integration is the DC term in the Fourier Domain

Spatial Domain:

$$I = \int_D f(x) dx$$

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Fourier Domain:

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$$\hat{f}(0)$$

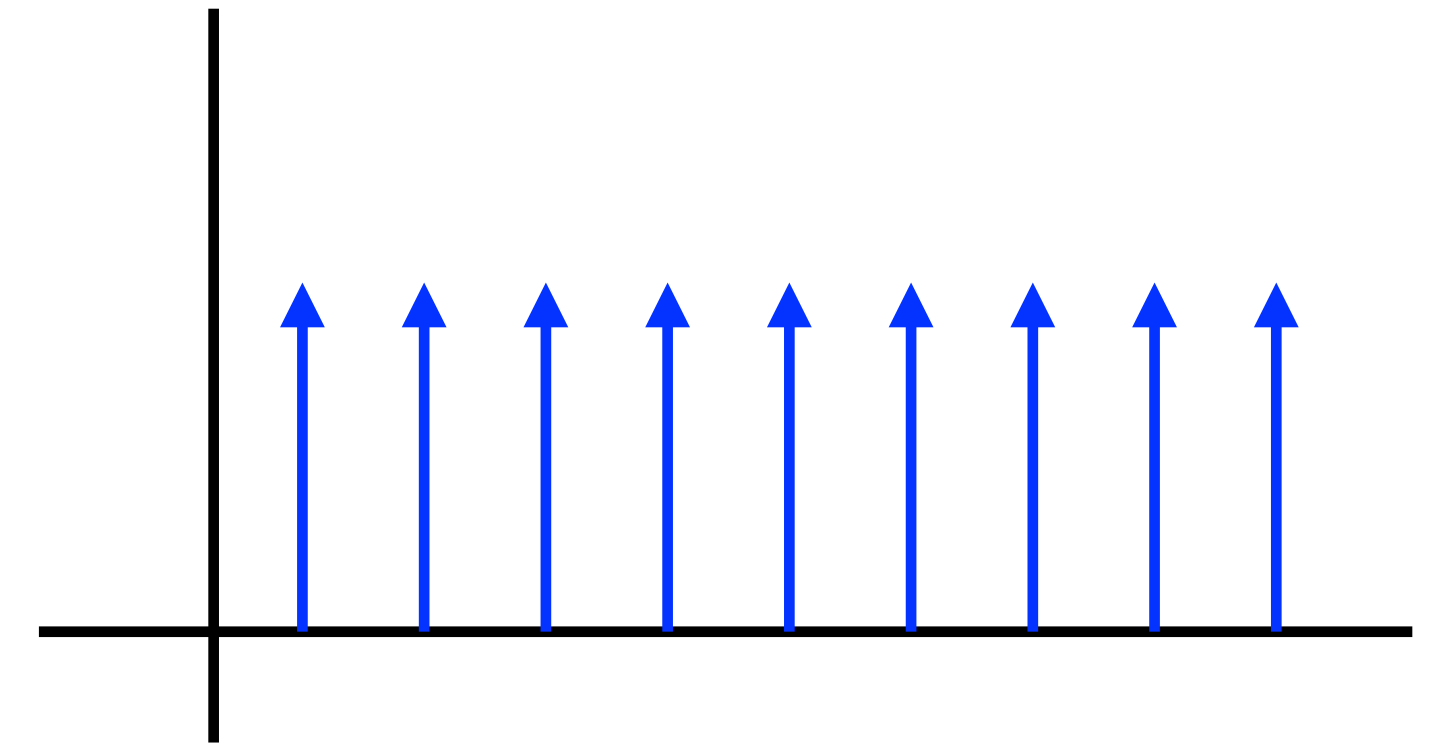
Monte Carlo Estimator in Spatial Domain

$$\tilde{\mu}_N = \int_D \textcolor{red}{f}(\textcolor{red}{x})\textcolor{blue}{S}(\textcolor{blue}{x})dx$$

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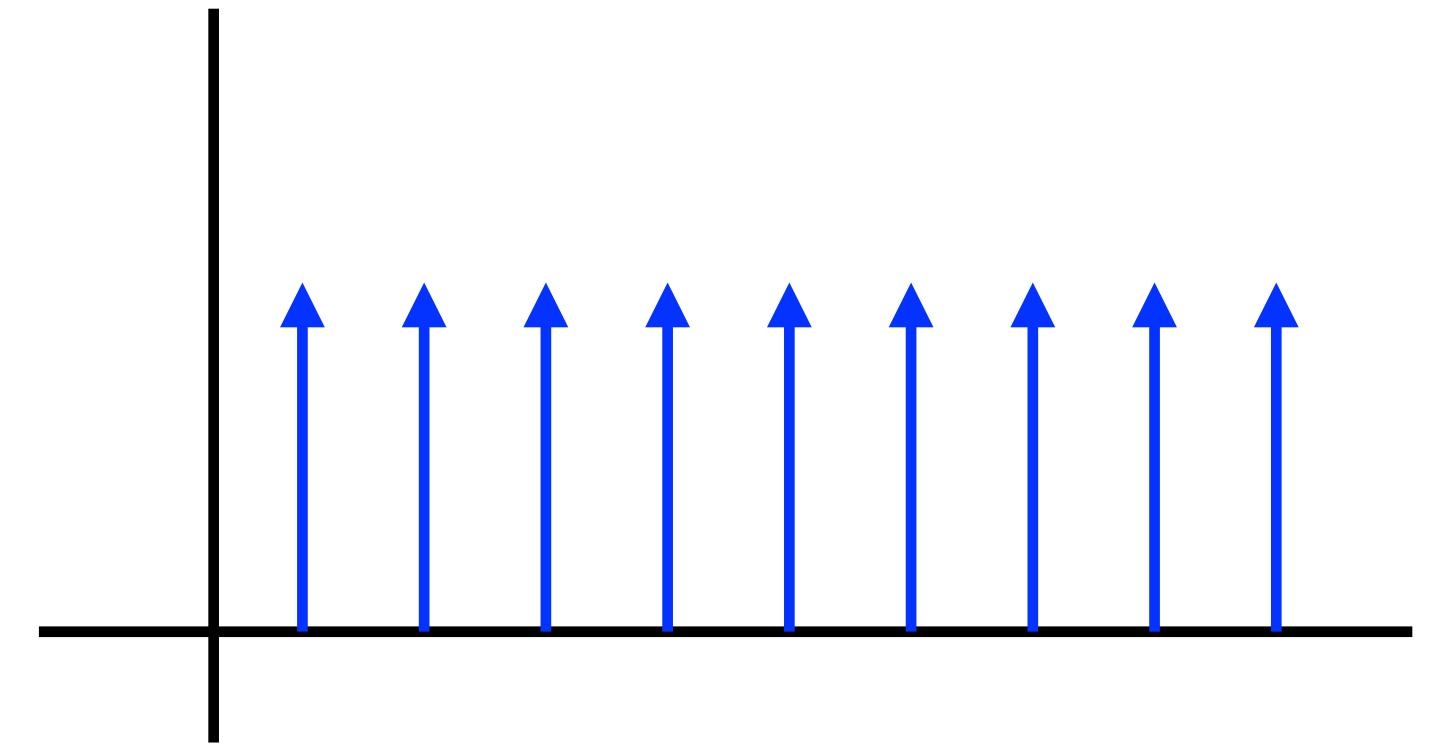
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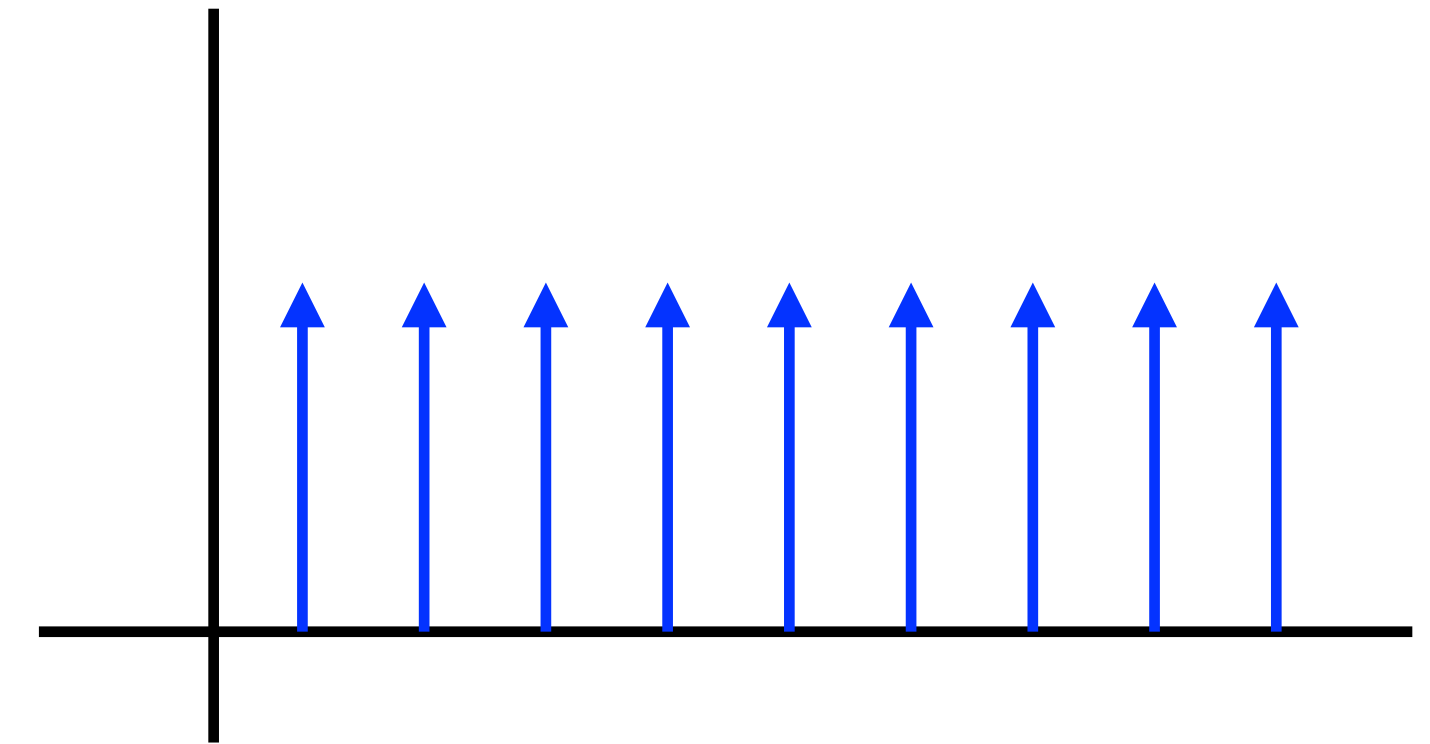
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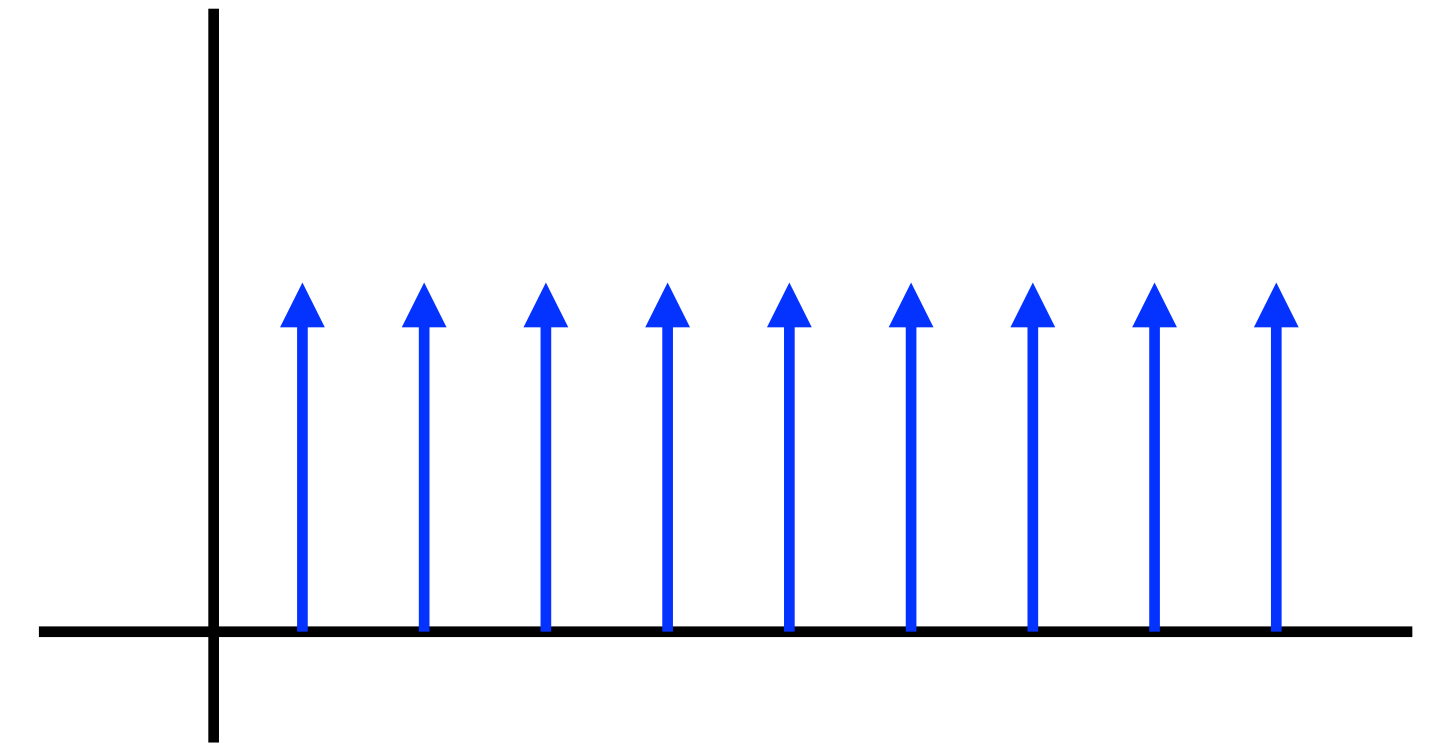
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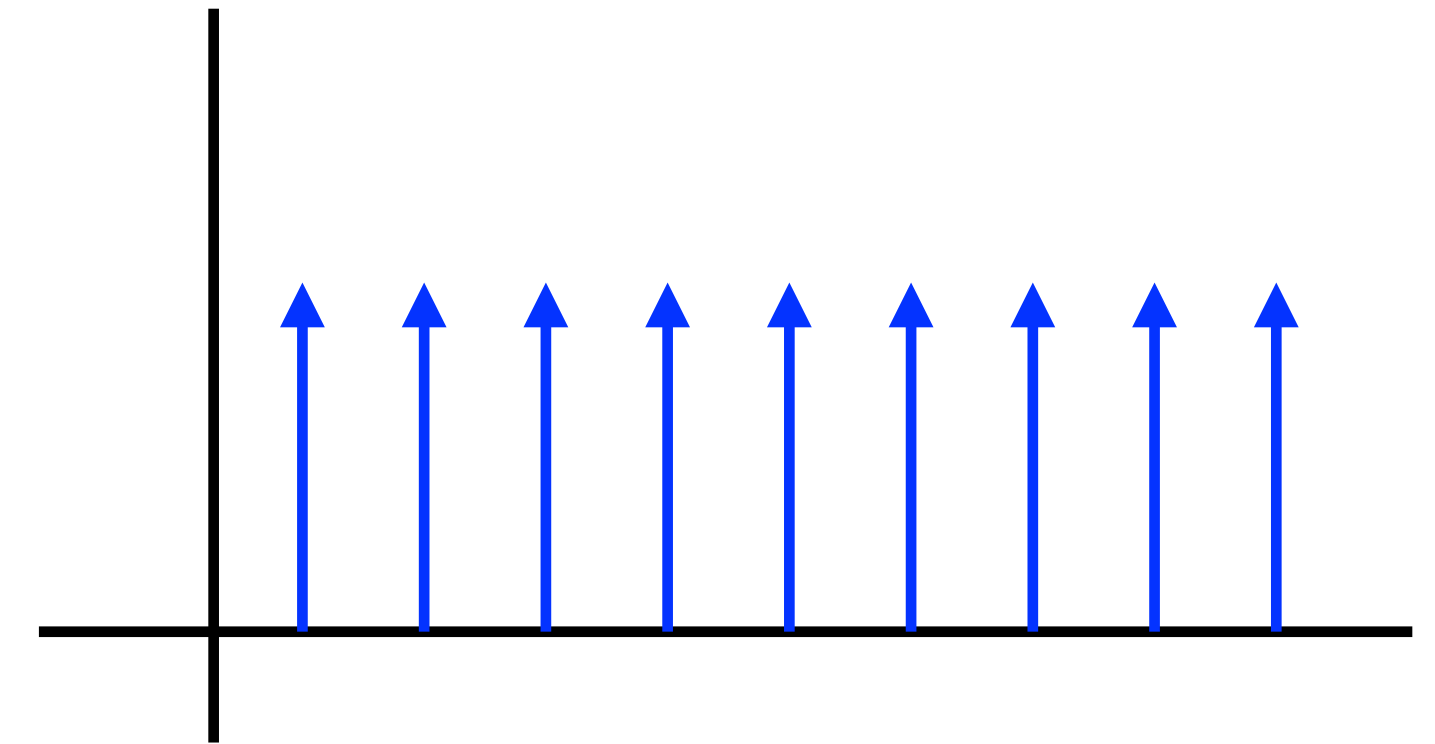
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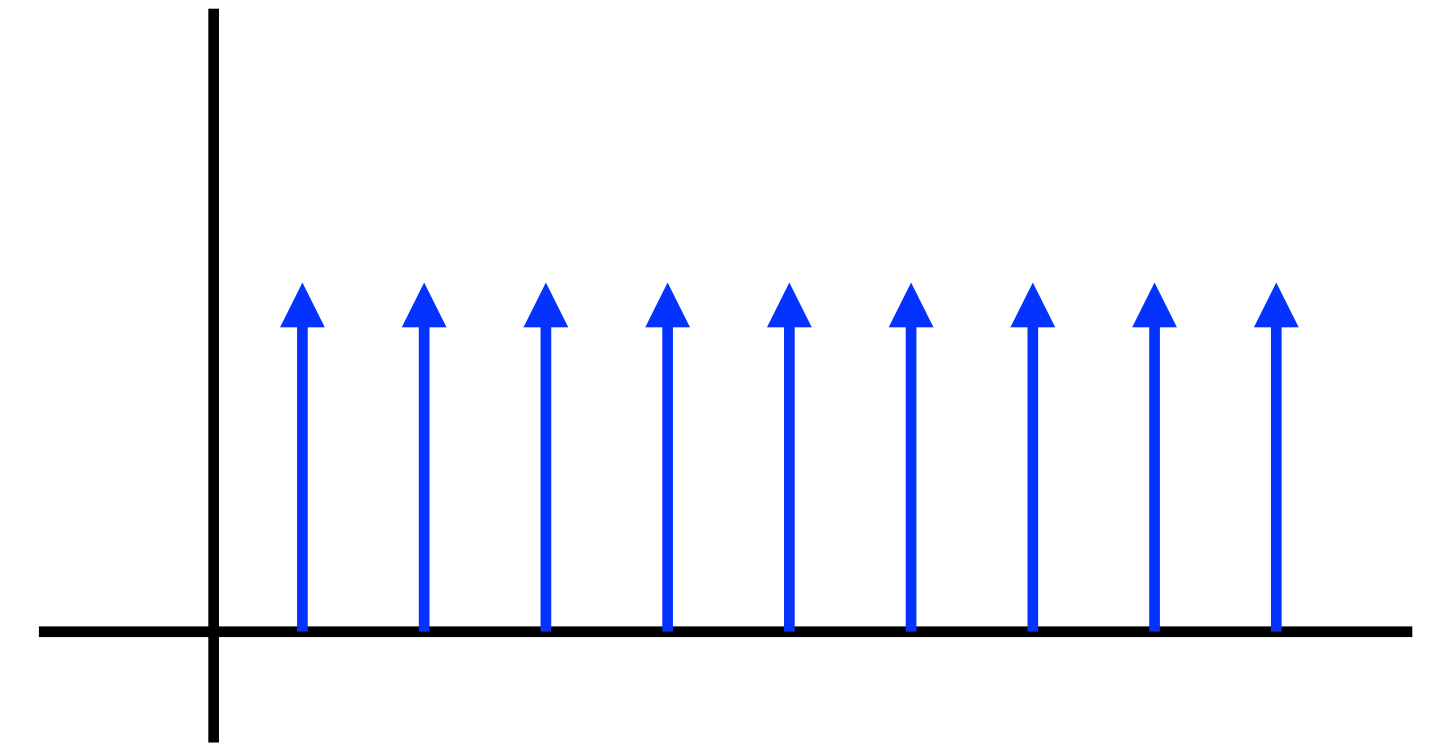
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Monte Carlo Estimator in Fourier Domain

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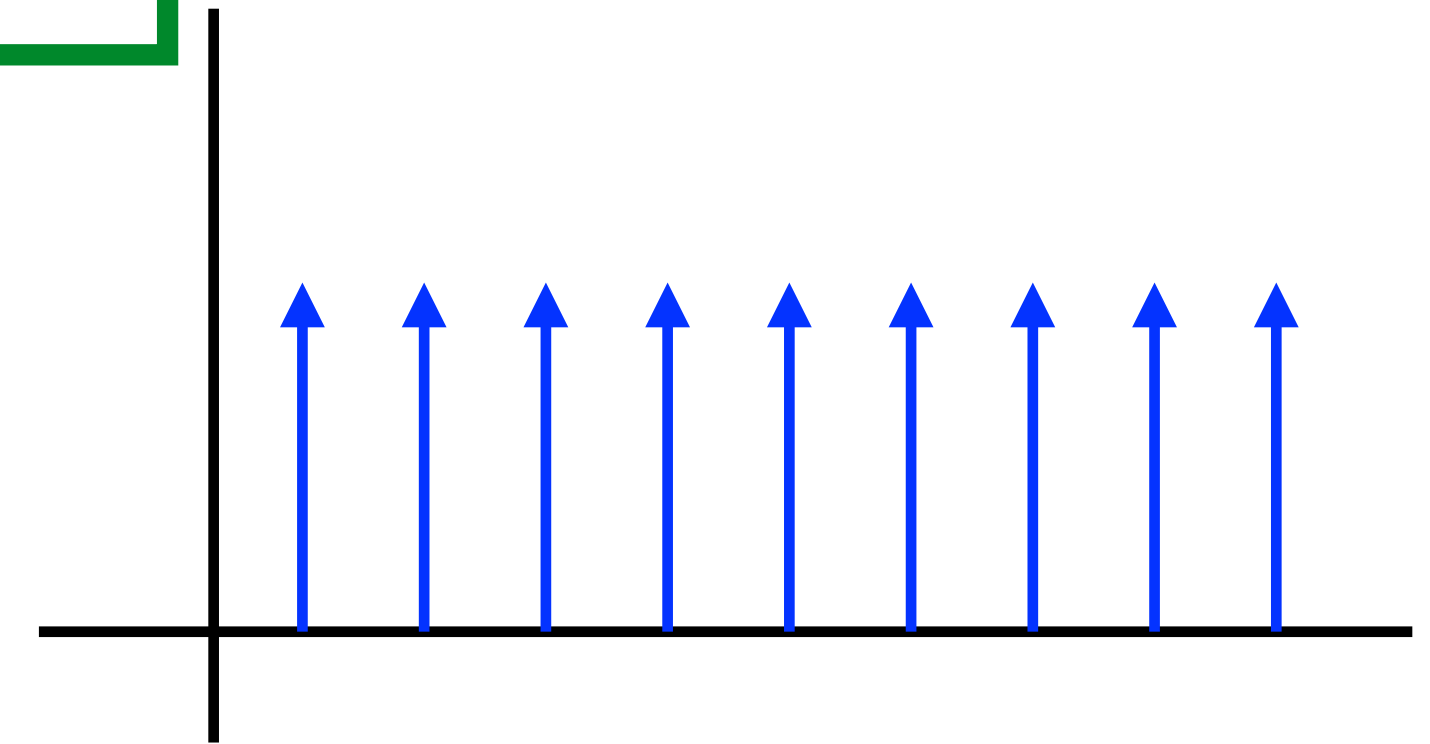
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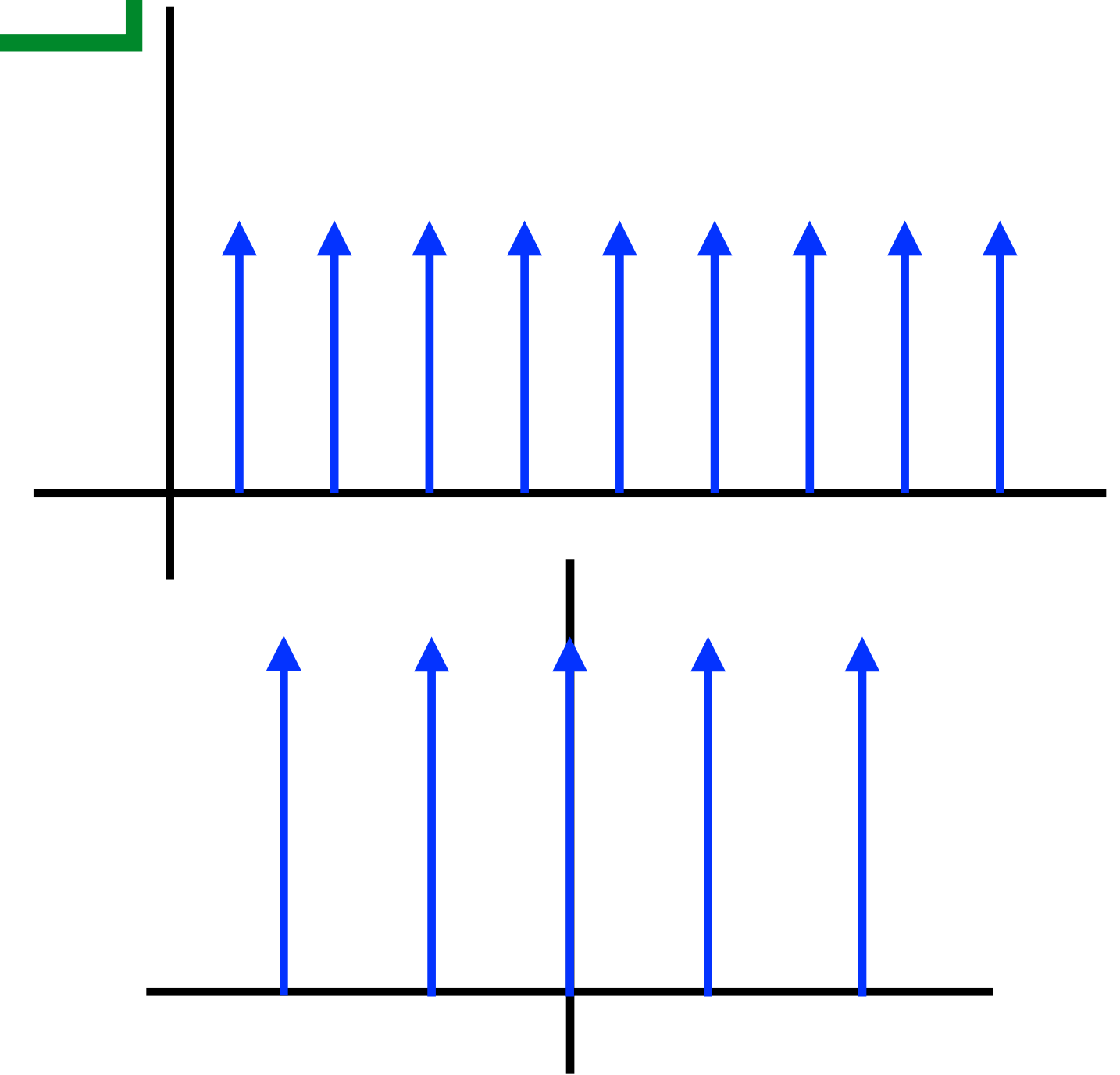


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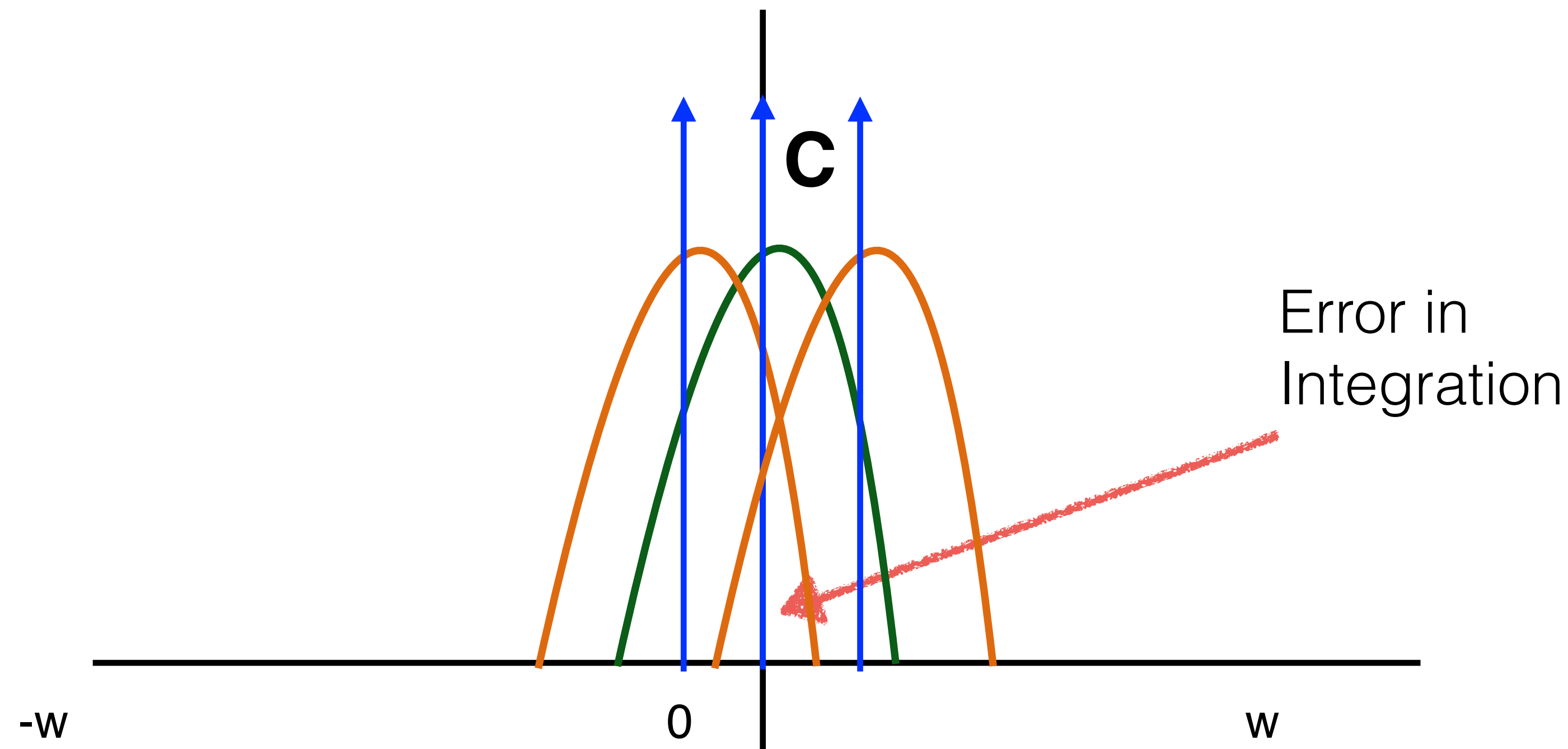
$$\textcolor{blue}{\hat{S}}(\omega) = \frac{1}{N} \sum_{k=1}^N e^{-i2\pi\omega x_k}$$



How to Formulate Error in Fourier Domain ?

$$I = \hat{f}(0)$$

$$\tilde{\mu}_N = \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$$

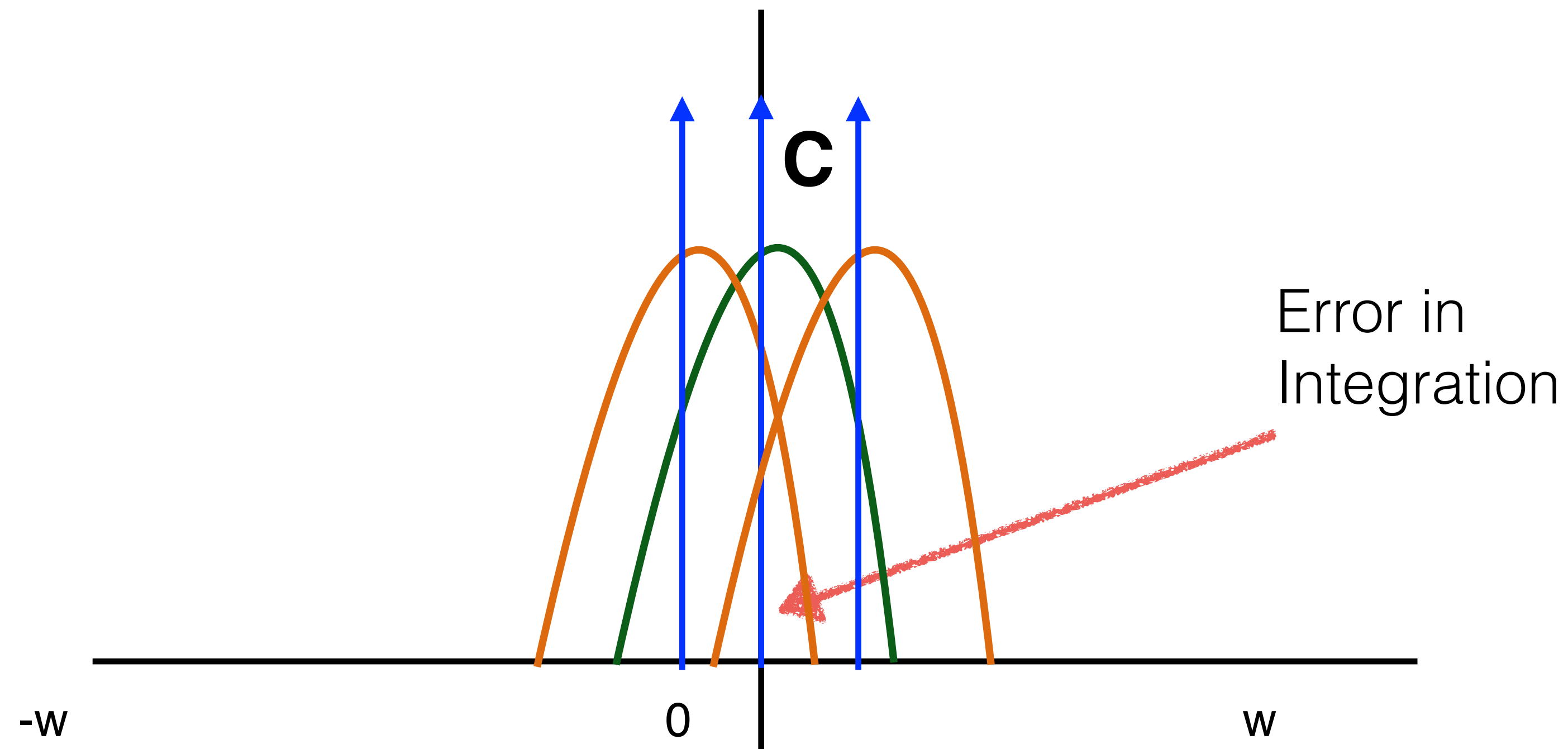


Fredo Durand [2011]

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Fredo Durand [2011]

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Monte Carlo Estimator

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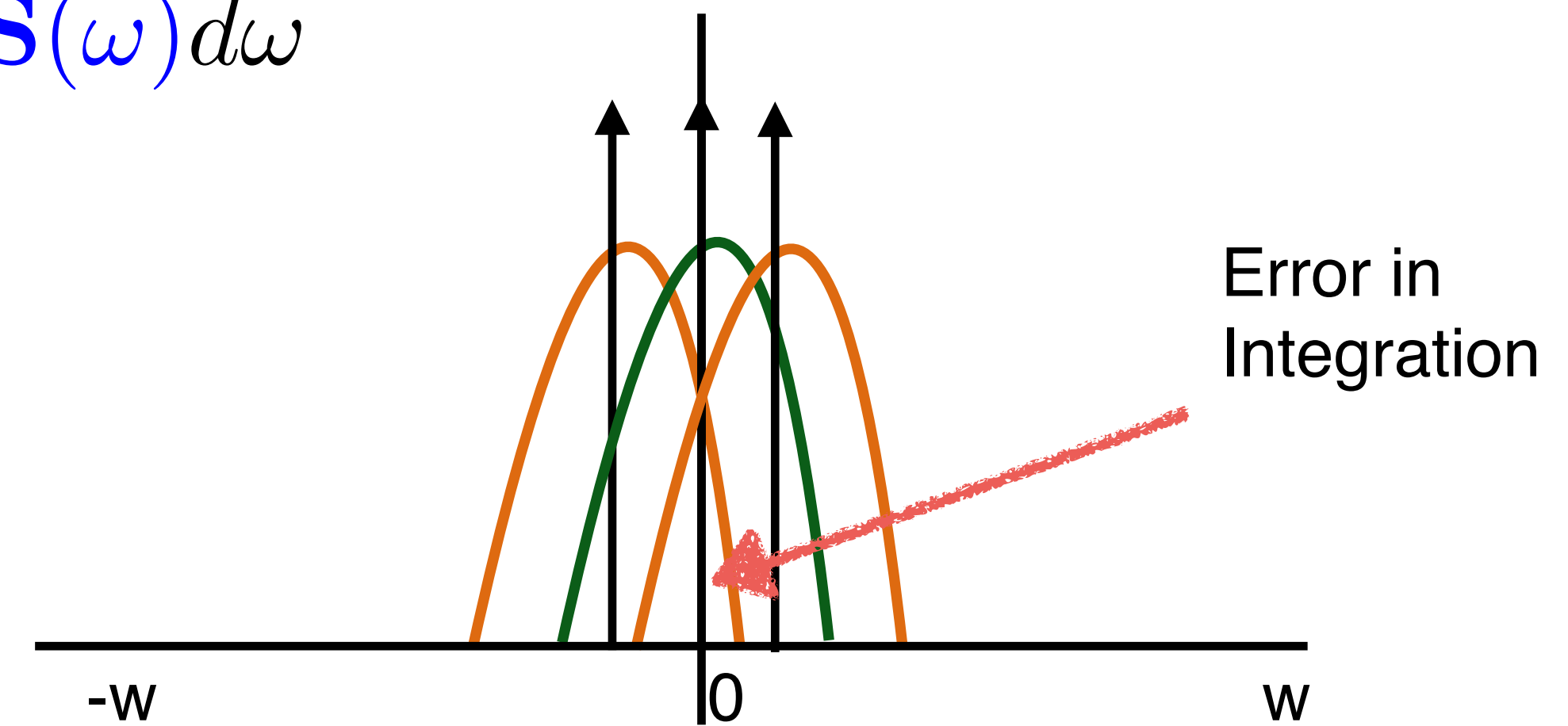
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Fredo Durand [2011]

$$\text{Error} = \text{Bias}^2 + \text{Variance}$$

Properties of Error

- Bias
- Variance

Properties of Error

- Bias: Expected value of the Error
- Variance

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- Bias: Expected value of the Error $\langle I - \tilde{\mu}_N \rangle$
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Properties of Error

- Bias: Expected value of the Error $\langle I - \tilde{\mu}_N \rangle$
- Variance: $\text{Var}(I - \mu_N)$

Subr and Kautz [2013]

Bias in the Monte Carlo Estimator

Bias in Fourier Domain

Error:

$$I - \tilde{\mu}_N = \hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$$

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$$\langle I - \tilde{\mu}_N \rangle$$

Bias in Fourier Domain

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To obtain an unbiased estimator:

Subr and Kautz [2013]

Bias in Fourier Domain

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To obtain an unbiased estimator:

Subr and Kautz [2013]

$$\langle \hat{\mathbf{S}}(\omega) \rangle = 0$$

for frequencies other than zero

How to obtain $\langle \hat{\mathbf{S}}(\omega) \rangle = 0$?

Complex form in Amplitude and Phase

$$\langle \hat{\mathbf{S}}(\omega) \rangle = |\langle \hat{\mathbf{S}}(\omega) \rangle| e^{-\Phi(\langle \hat{\mathbf{S}}(\omega) \rangle)}$$

Complex form in Amplitude and Phase

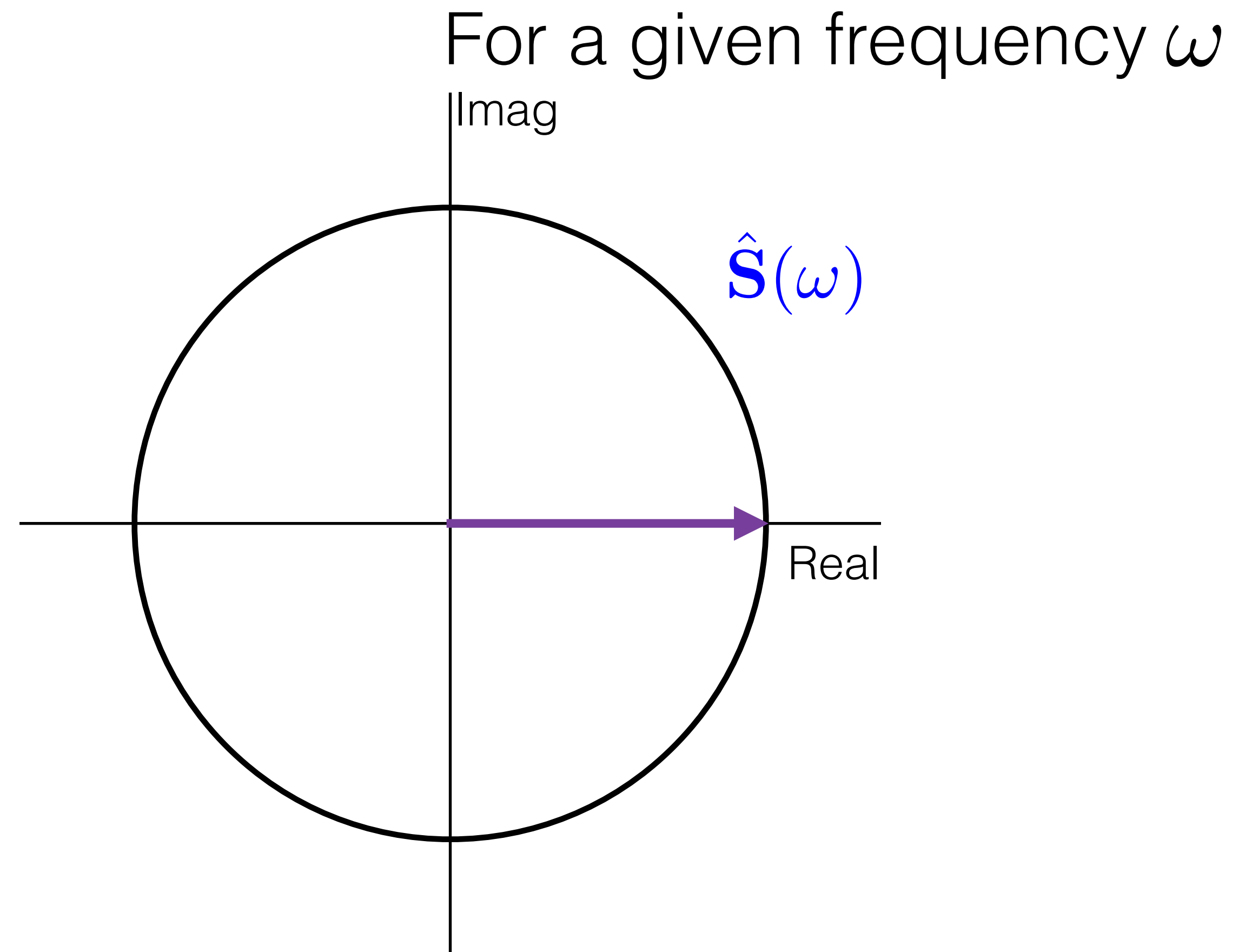
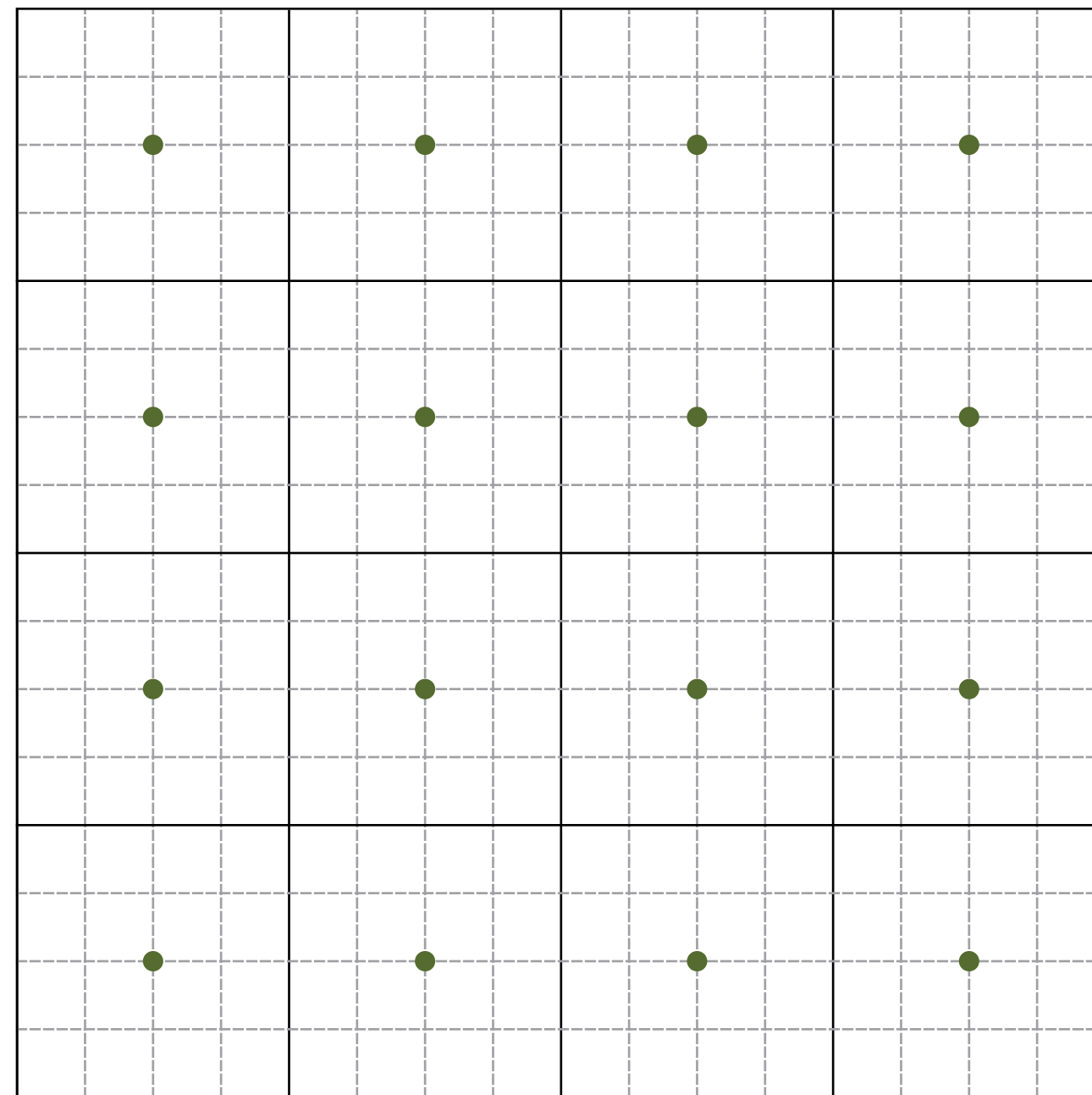
Amplitude

$$\langle \hat{\mathbf{S}}(\omega) \rangle = |\langle \hat{\mathbf{S}}(\omega) \rangle| e^{-\Phi(\langle \hat{\mathbf{S}}(\omega) \rangle)}$$

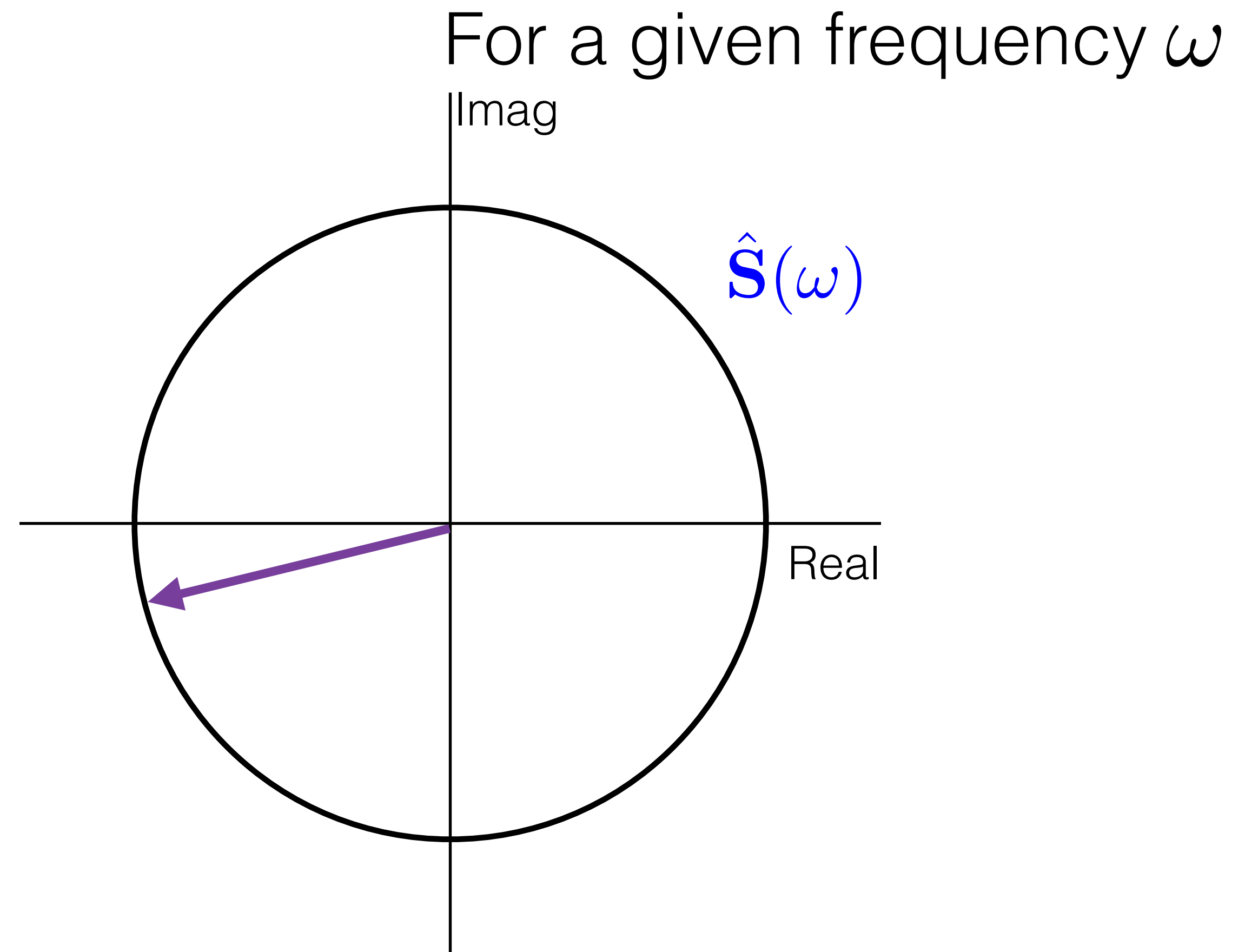
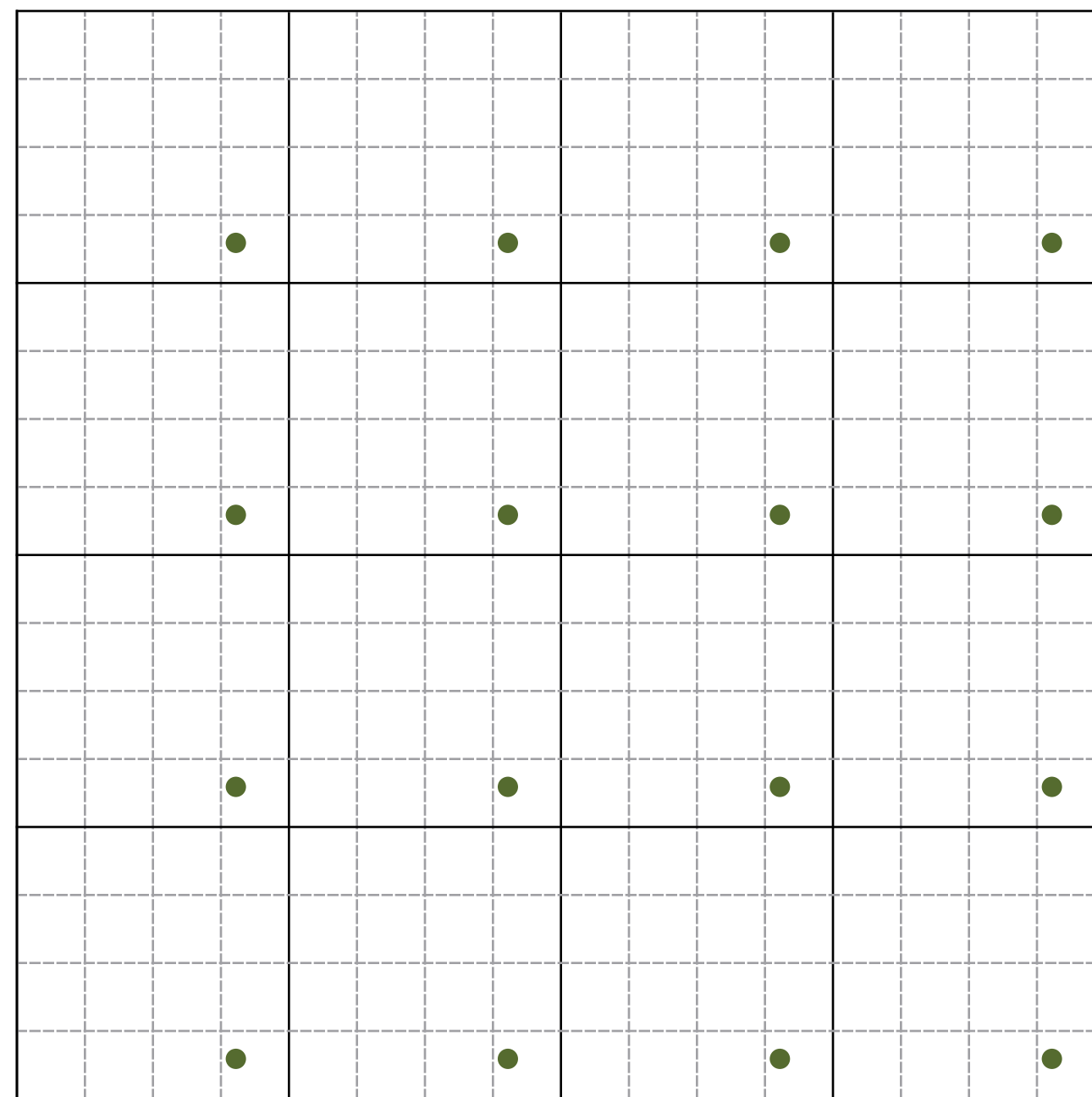
Complex form in Amplitude and Phase

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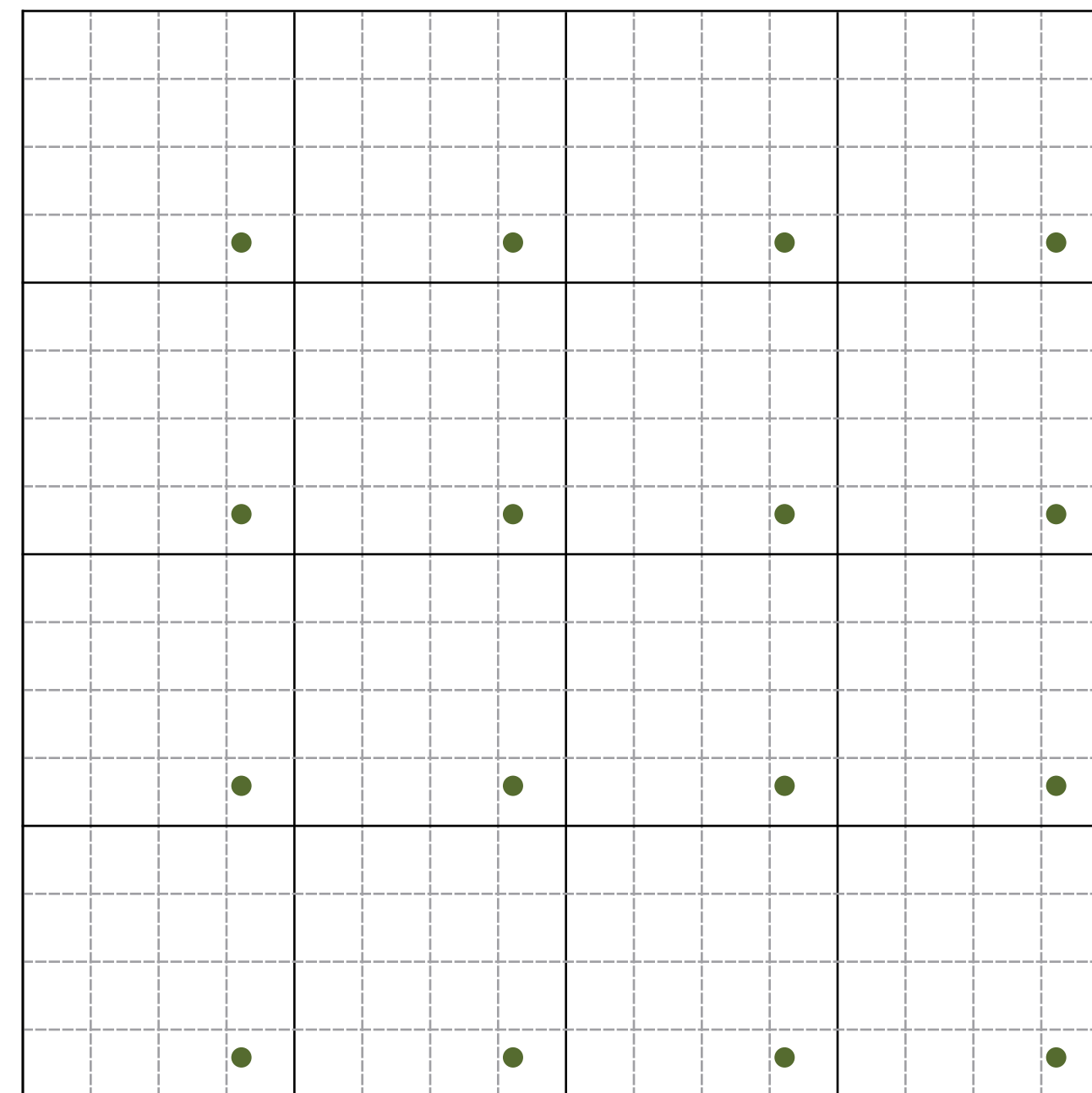
Phase change due to Random Shift



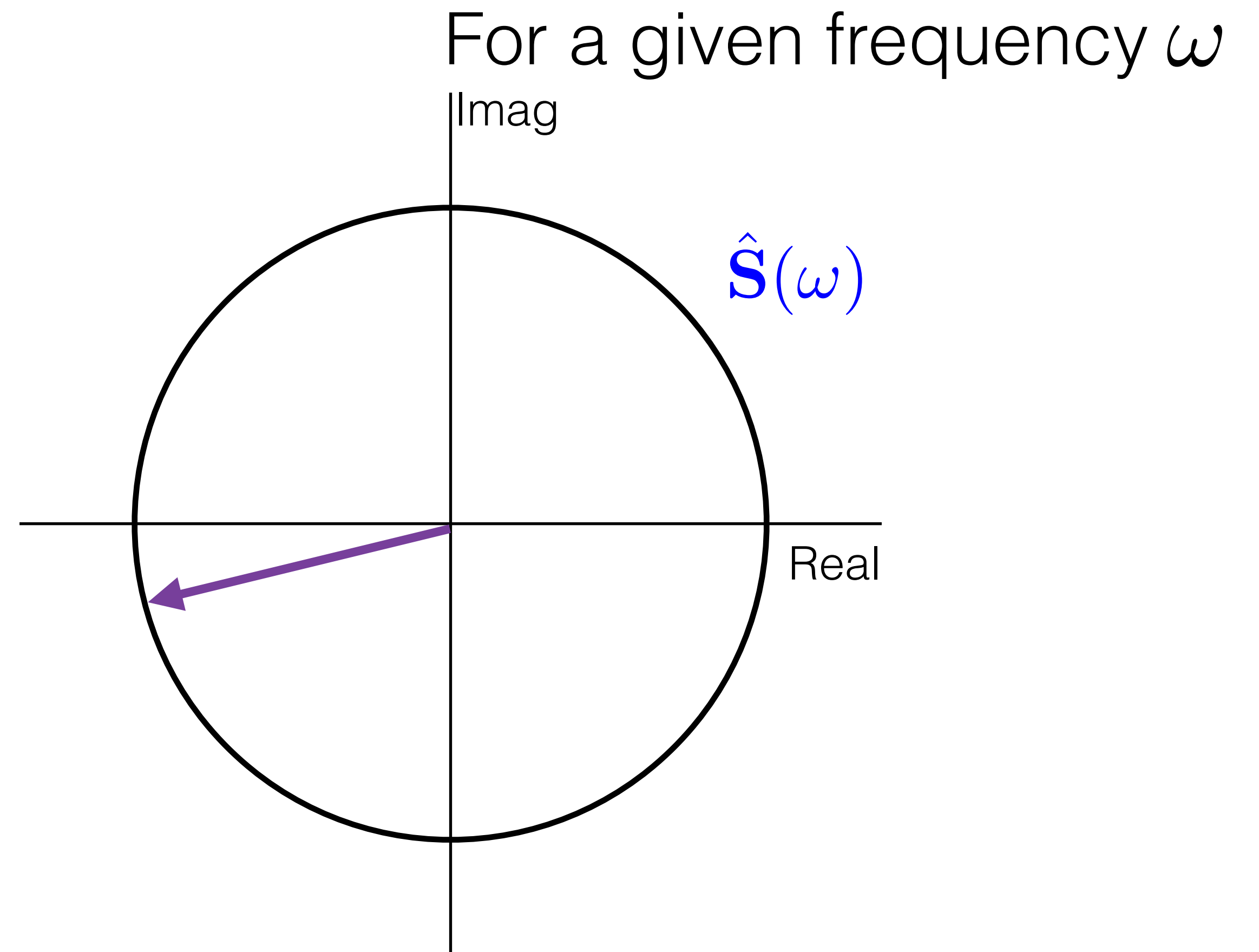
Phase change due to Random Shift



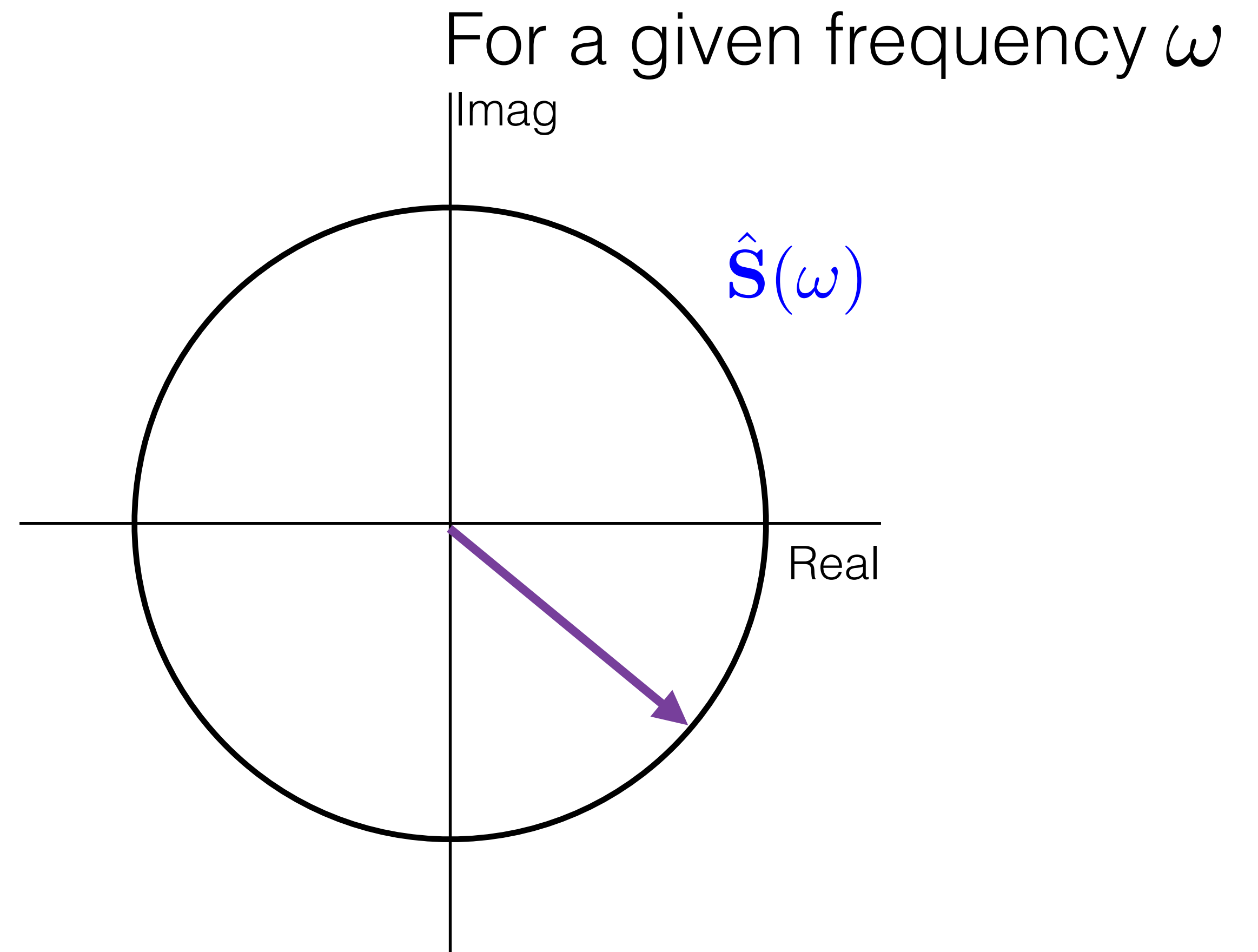
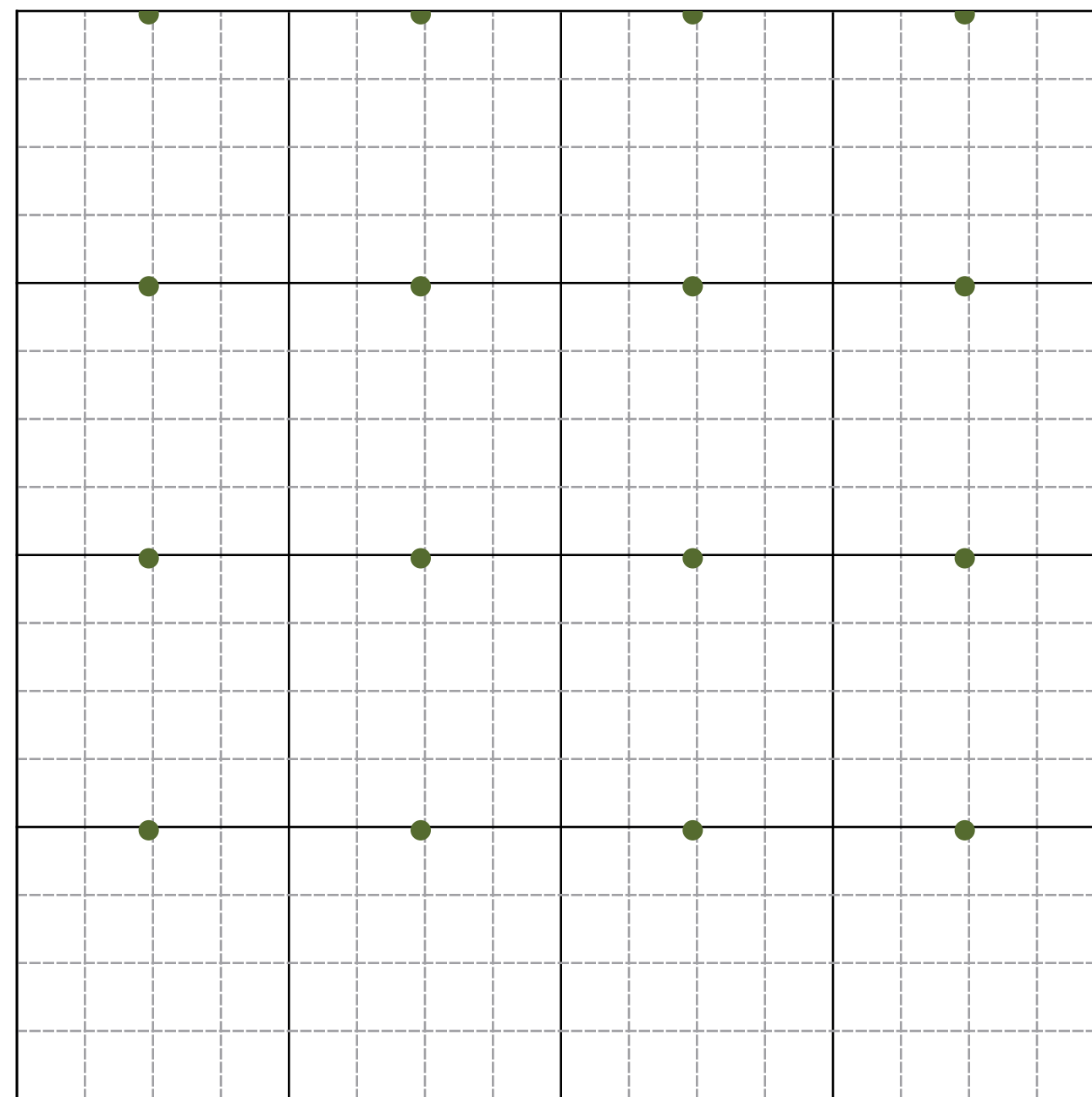
Phase change due to Random Shift



Pauly et al. [2000]
Ramamoorthi et al. [2012]



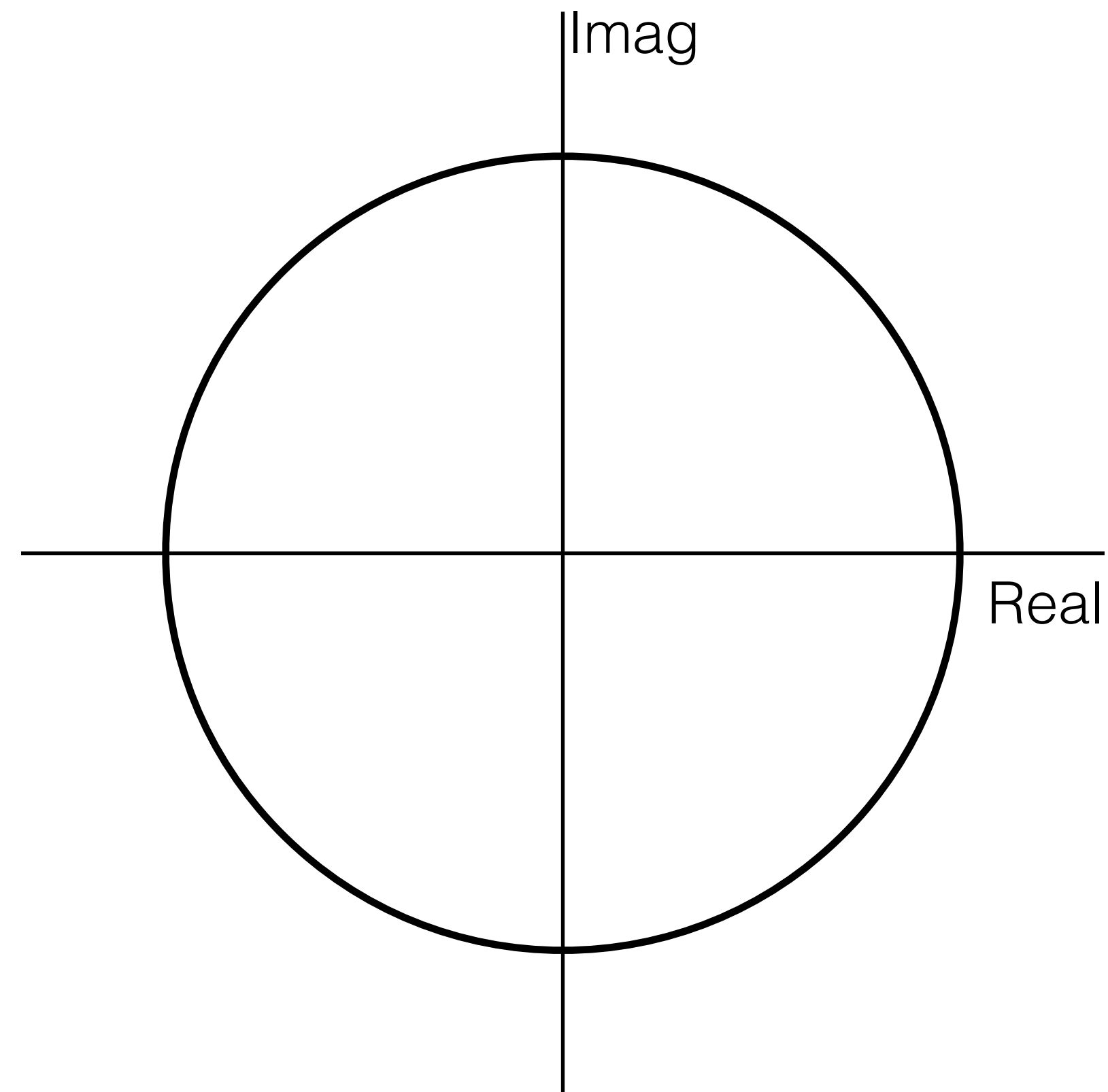
Phase change due to Random Shift



Phase change due to Random Shift

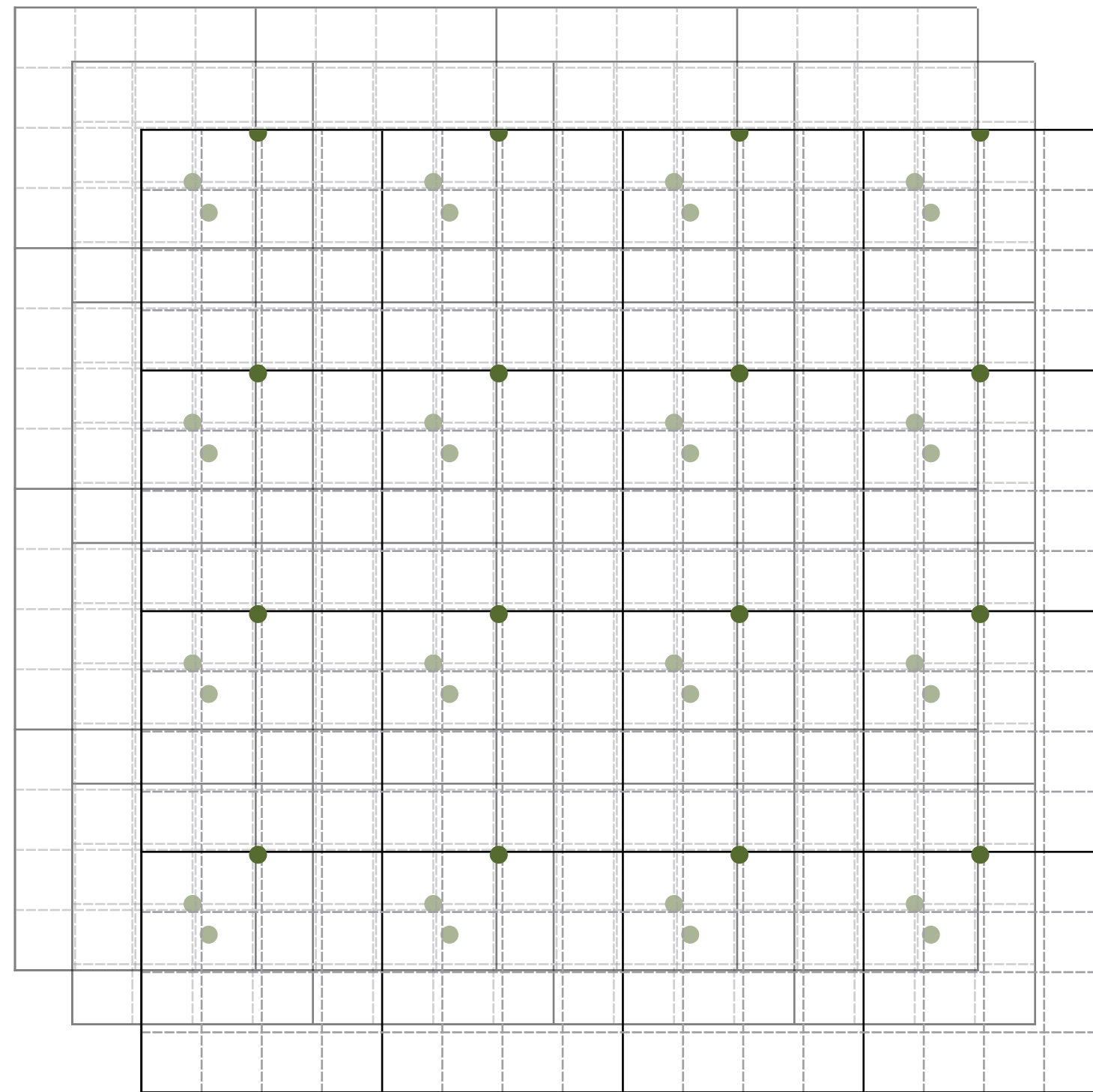
Multiple realizations

For a given frequency ω

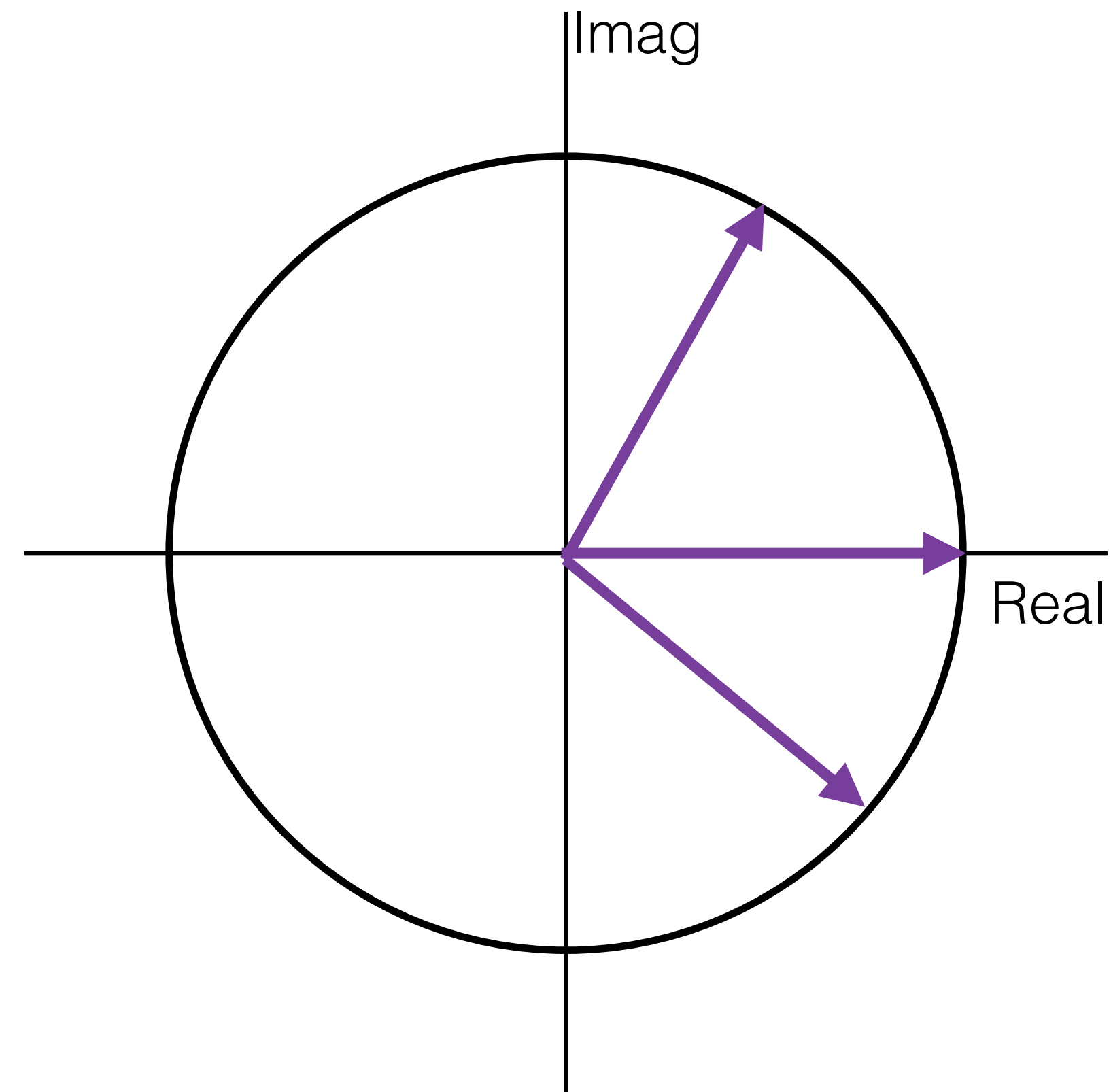


Phase change due to Random Shift

Multiple realizations

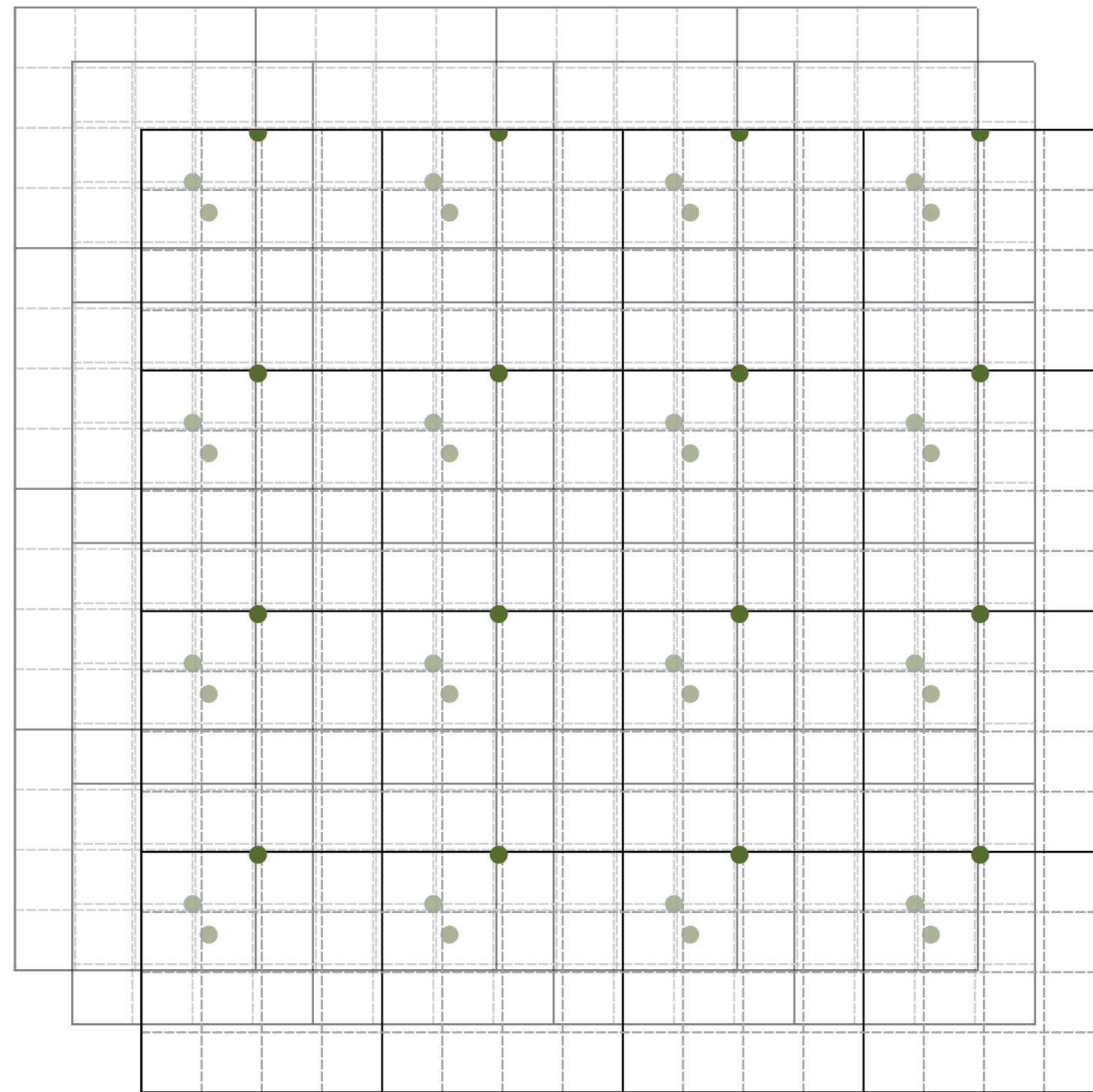


For a given frequency ω

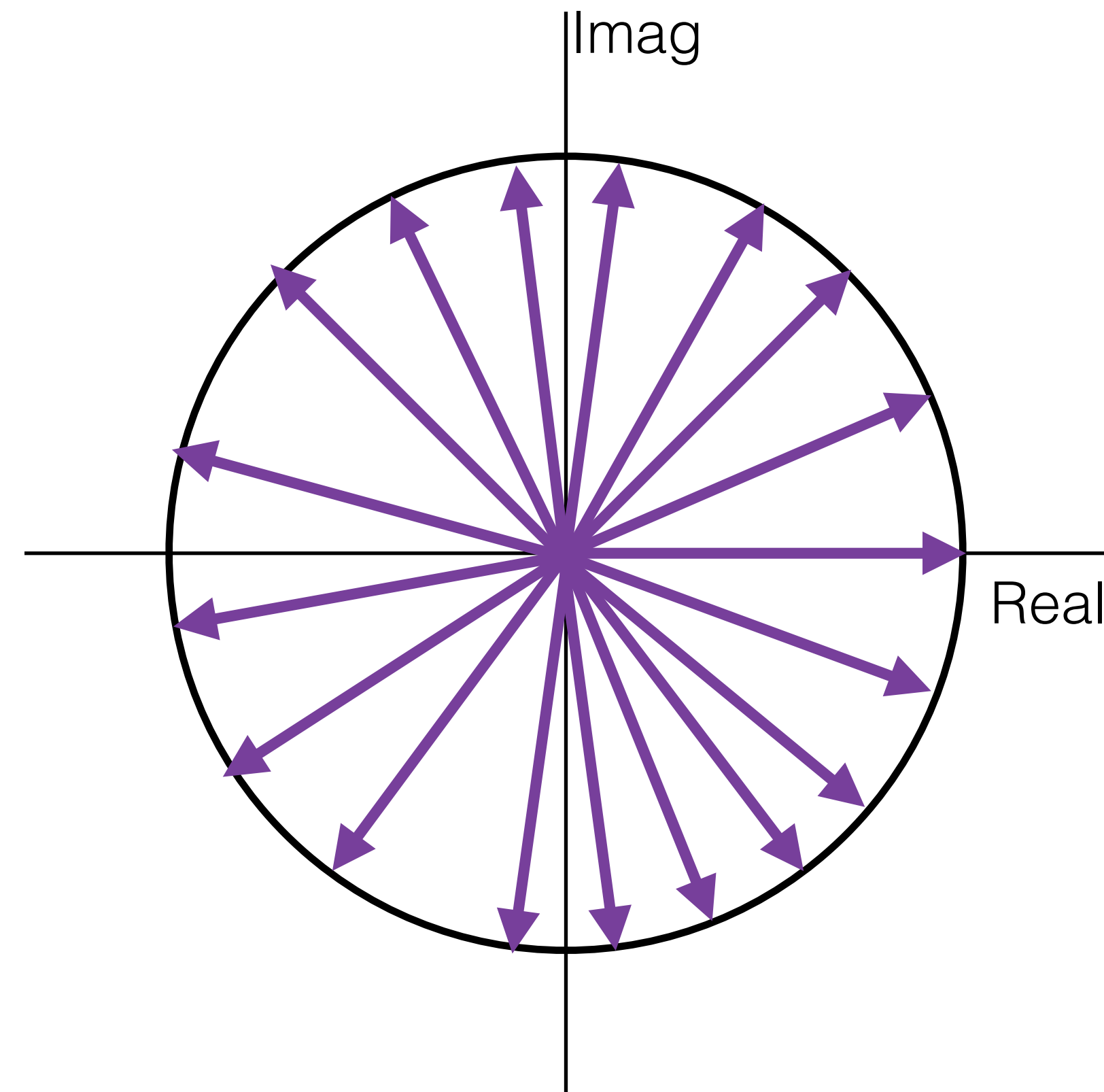


Phase change due to Random Shift

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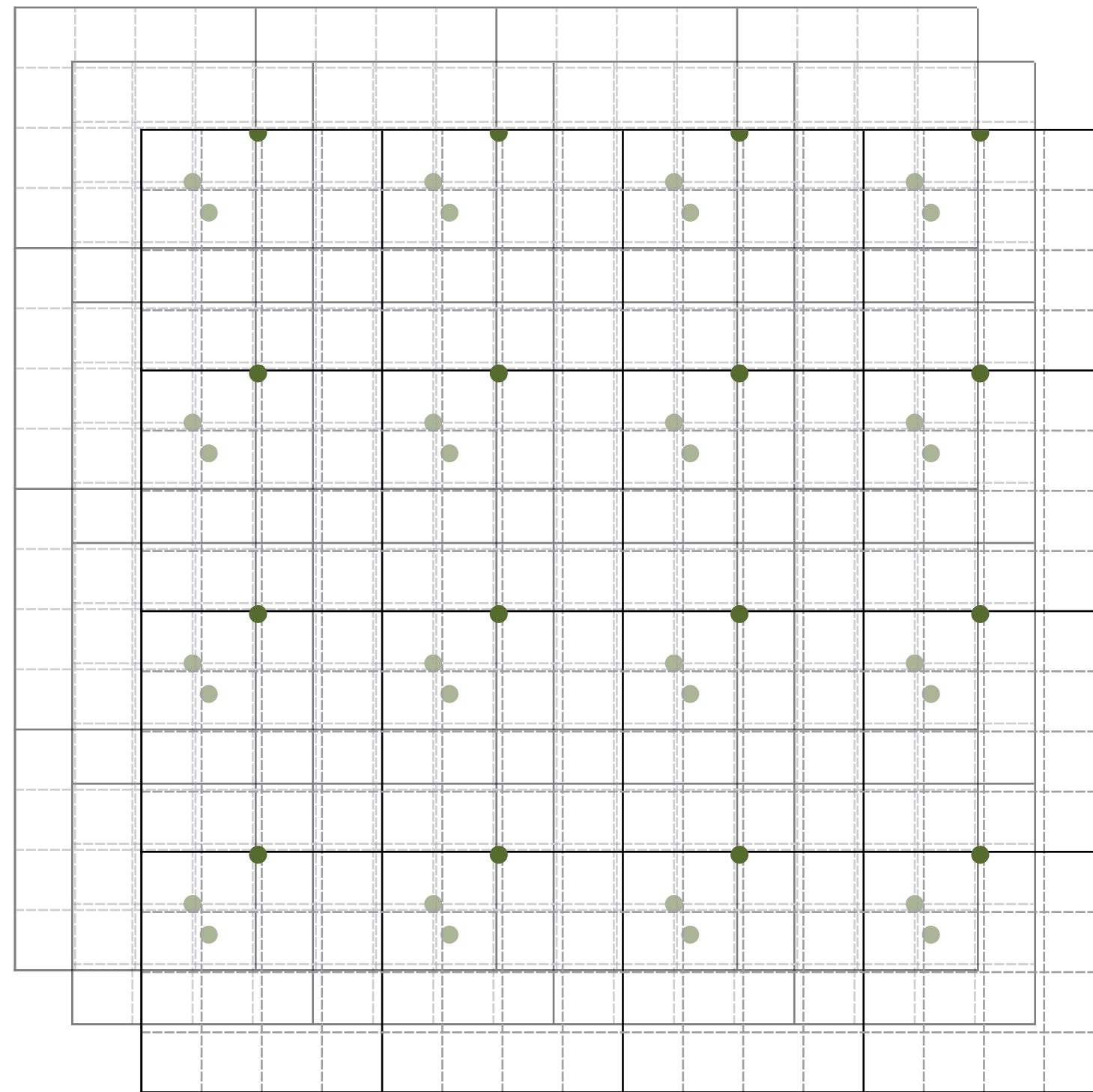


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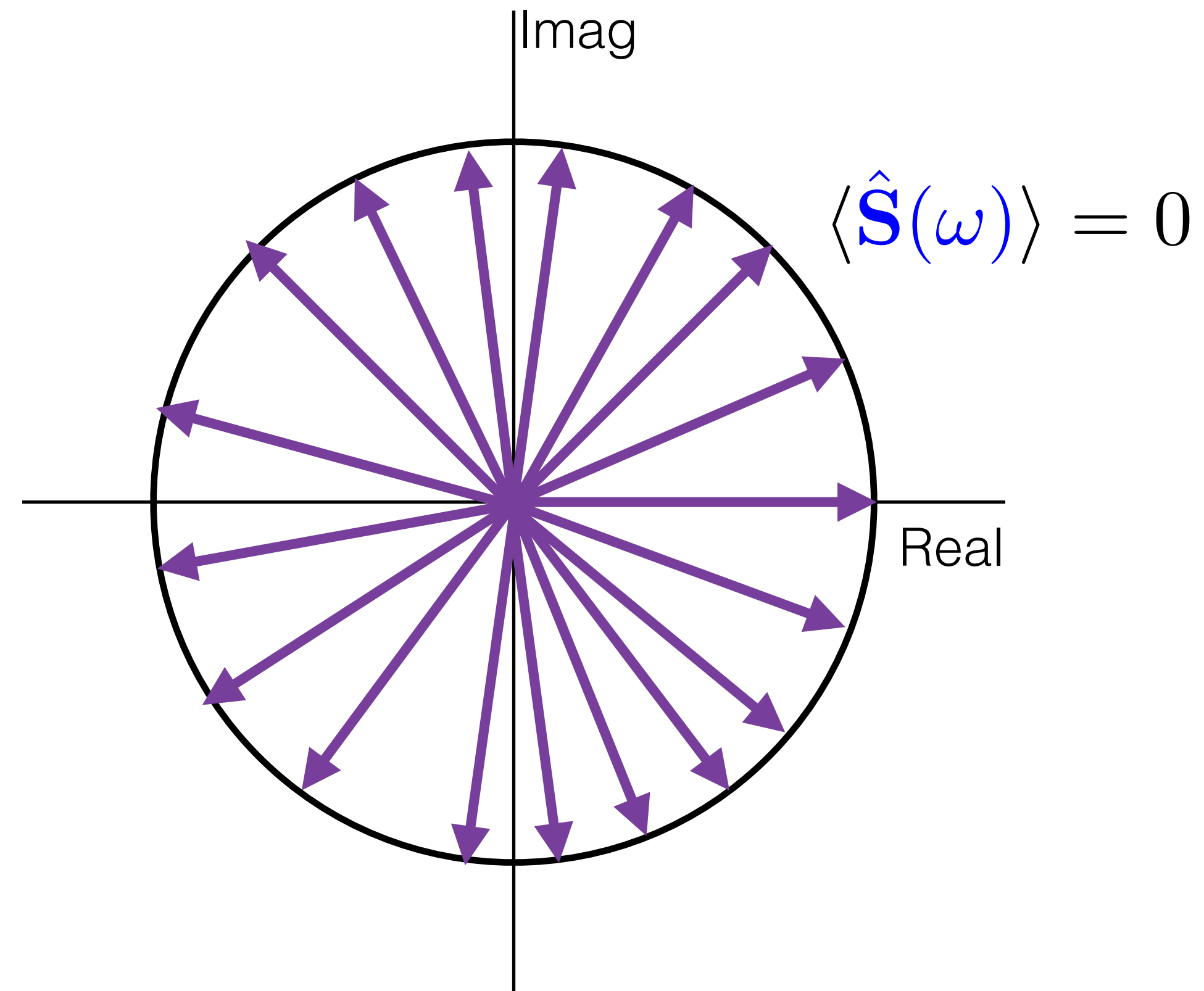


Phase change due to Random Shift

Multiple realizations

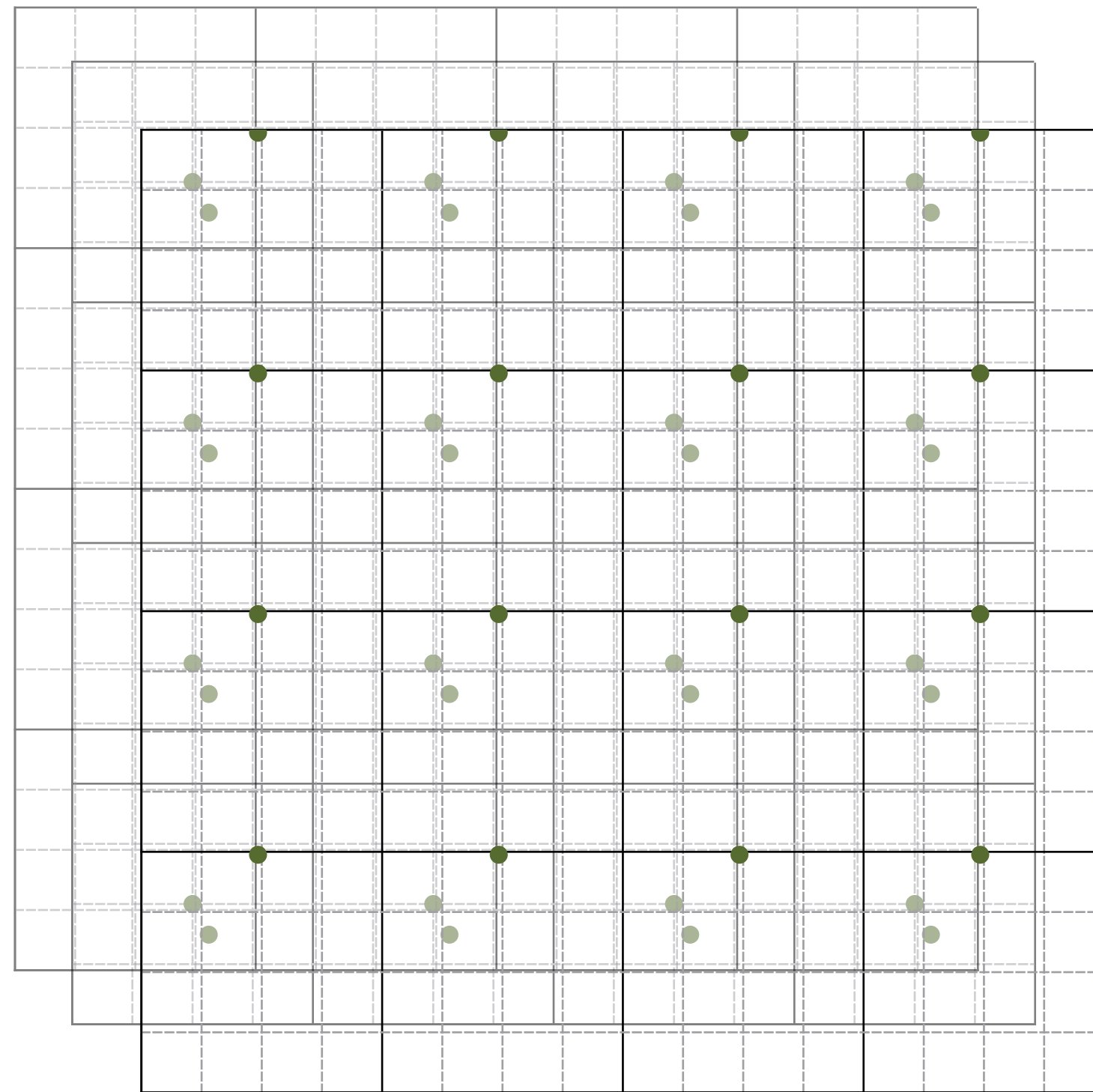


For a given frequency ω

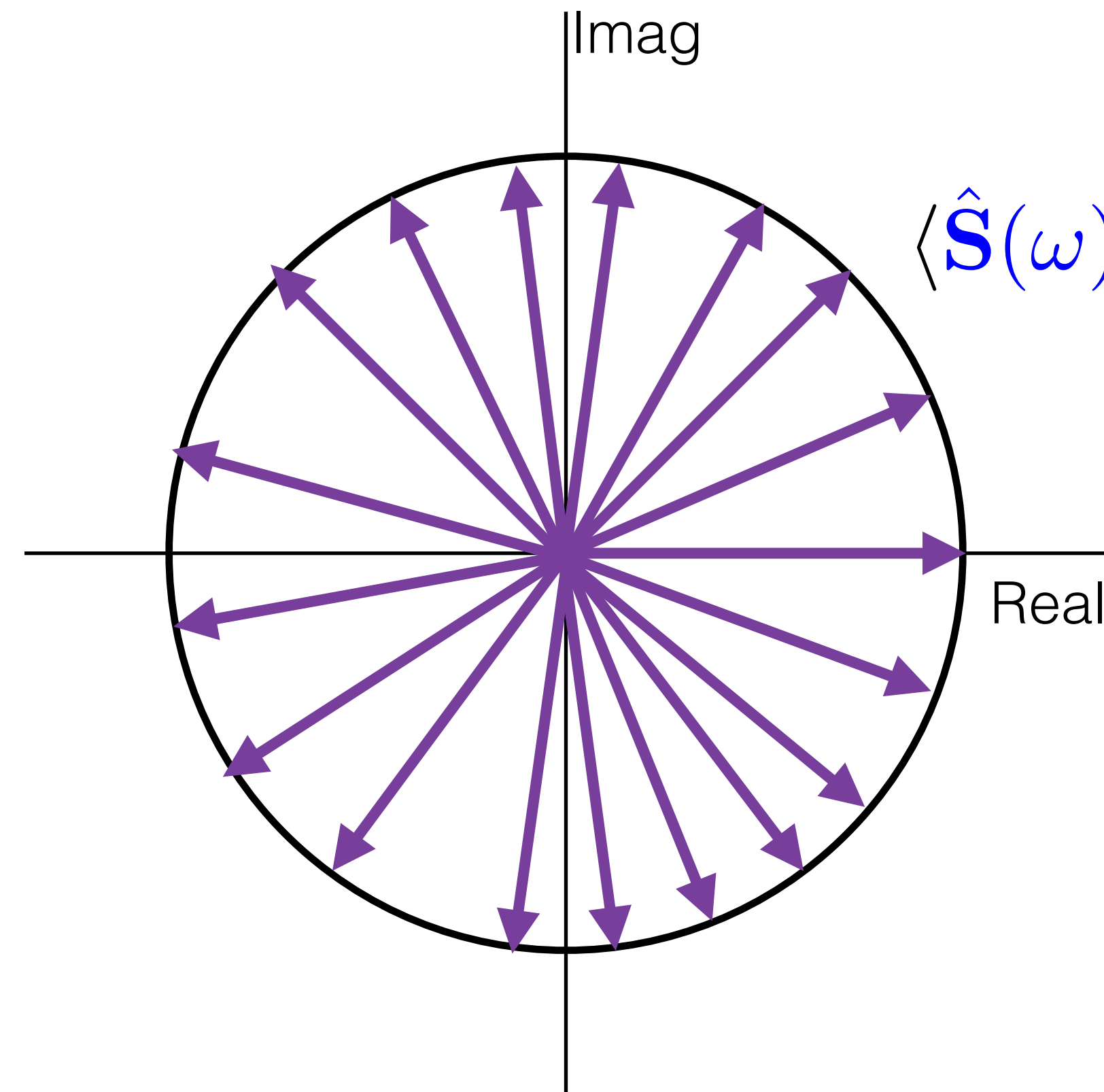


Phase change due to Random Shift

Multiple realizations



For a given frequency ω



$$\langle \hat{\mathbf{S}}(\omega) \rangle = 0 \quad \forall \omega \neq 0$$

$$\text{Error} = \text{Bias}^2 + \text{Variance}$$

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- Homogenization allows representation of error only in terms of variance
- We can take any sampling pattern and homogenize it to make the Monte Carlo estimator unbiased.

Variance in the Fourier domain

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Error:

$$I - \tilde{\mu}_N = \hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$$

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Variance in the Fourier domain

$$\text{Var}(I - \tilde{\mu}_N) = \text{Var} \left(\hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega \right)$$

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where,

$$P_f(\omega) = |\hat{f}^*(\omega)|^2 \quad \text{Power Spectrum}$$

Variance in the Fourier domain

$$\text{Var}(\tilde{\mu}_N) = \int_{\Omega} P_f(\omega) \text{Var}(\hat{\mathbf{S}}(\omega)) d\omega$$

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Subr and Kautz [2013]

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Subr and Kautz [2013]

This is a general form, both for homogenised as well as non-homogenised sampling patterns

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Fredo Durand [2011]

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Pilleboue et al. [2015]

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Variance using Homogenized Samples

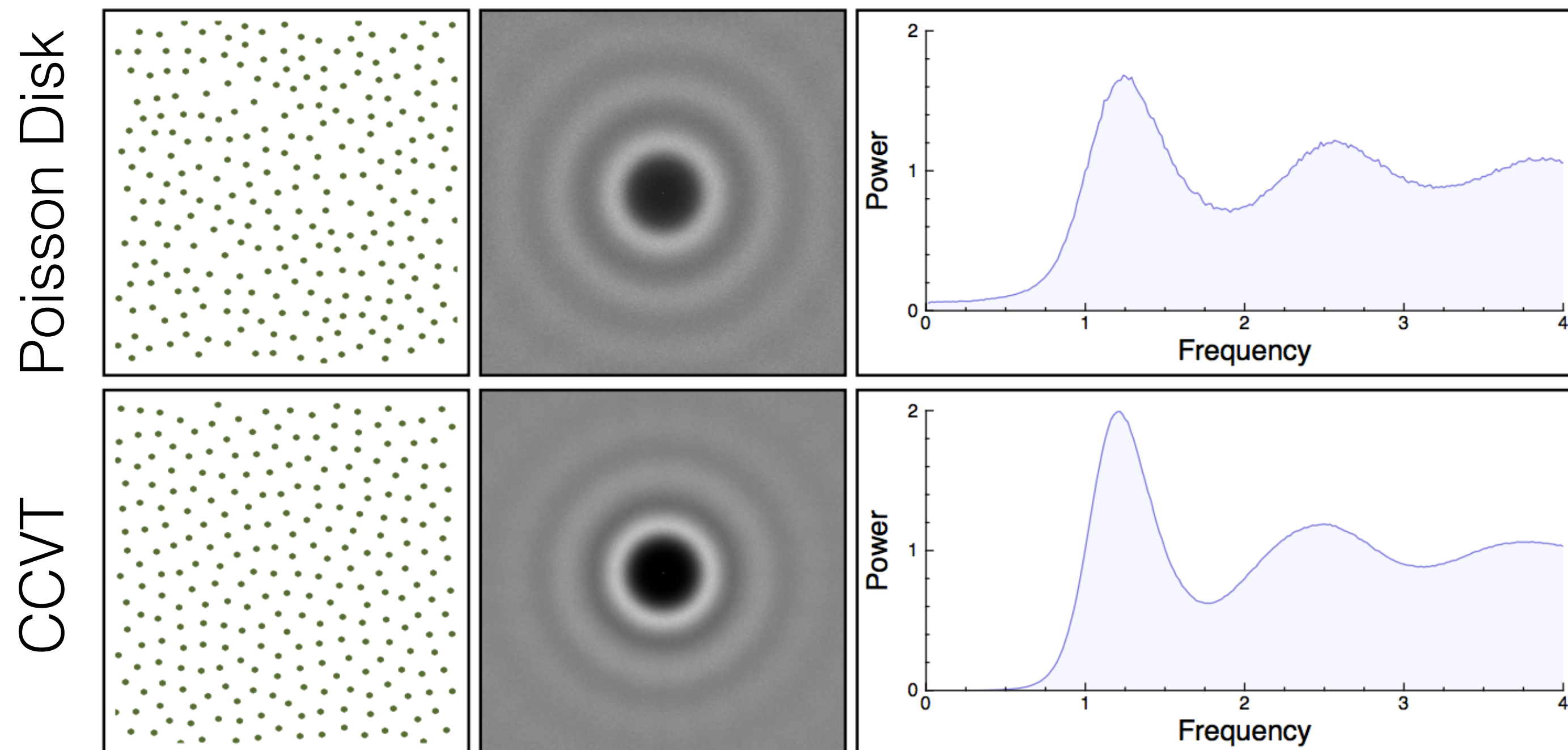
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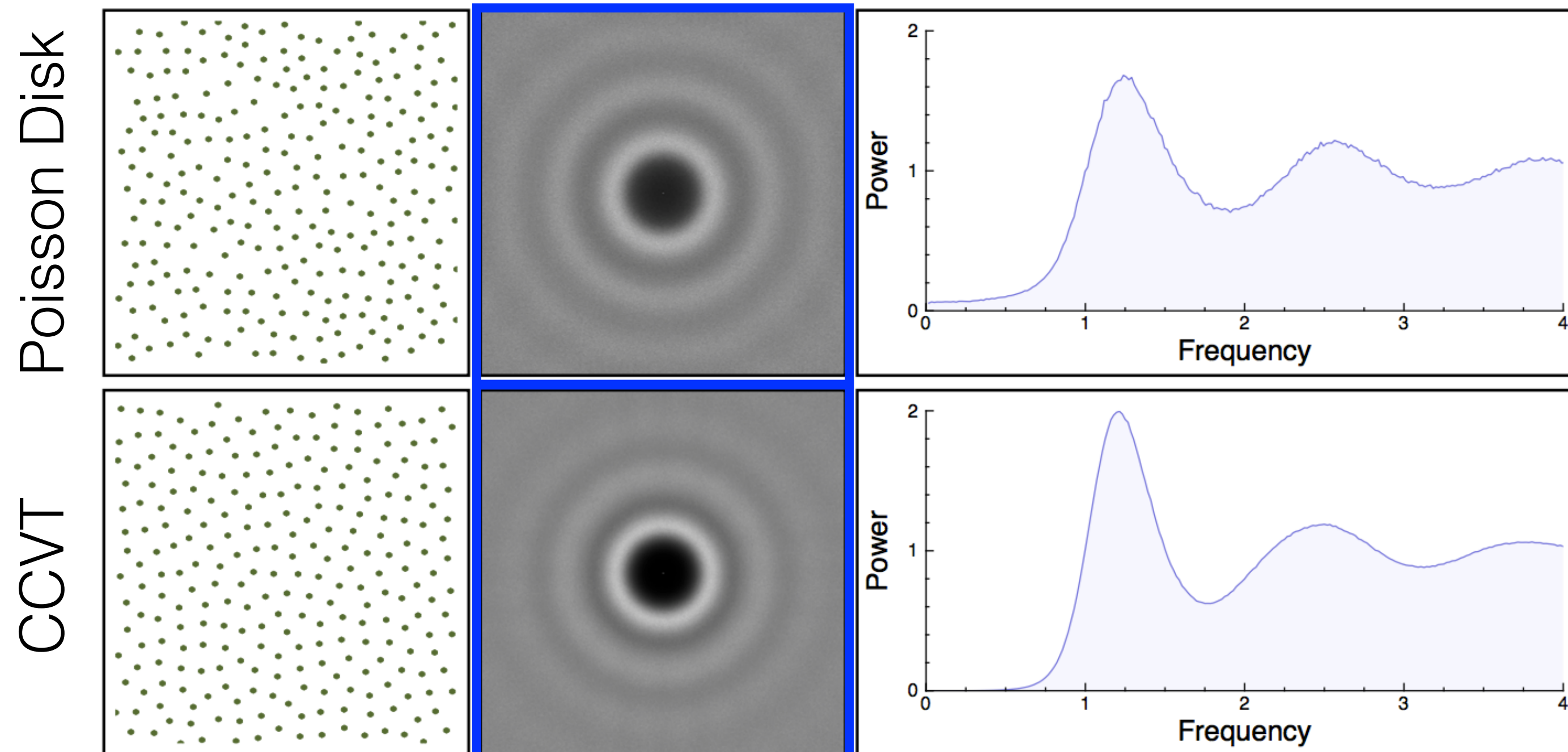
Variance in terms of n-dimensional Power Spectra

$$\text{Var}(\tilde{\mu}_N) = \int_{\Omega} P_f(\omega) \langle P_S(\omega) \rangle d\omega$$



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Variance for Isotropic Power Spectra

$$\text{Var}[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty \int_{\mathcal{S}^{d-1}} P_f(\rho \mathbf{n}) \langle P_s(\rho \mathbf{n}) \rangle d\mathbf{n} d\rho$$

Variance for Isotropic Power Spectra

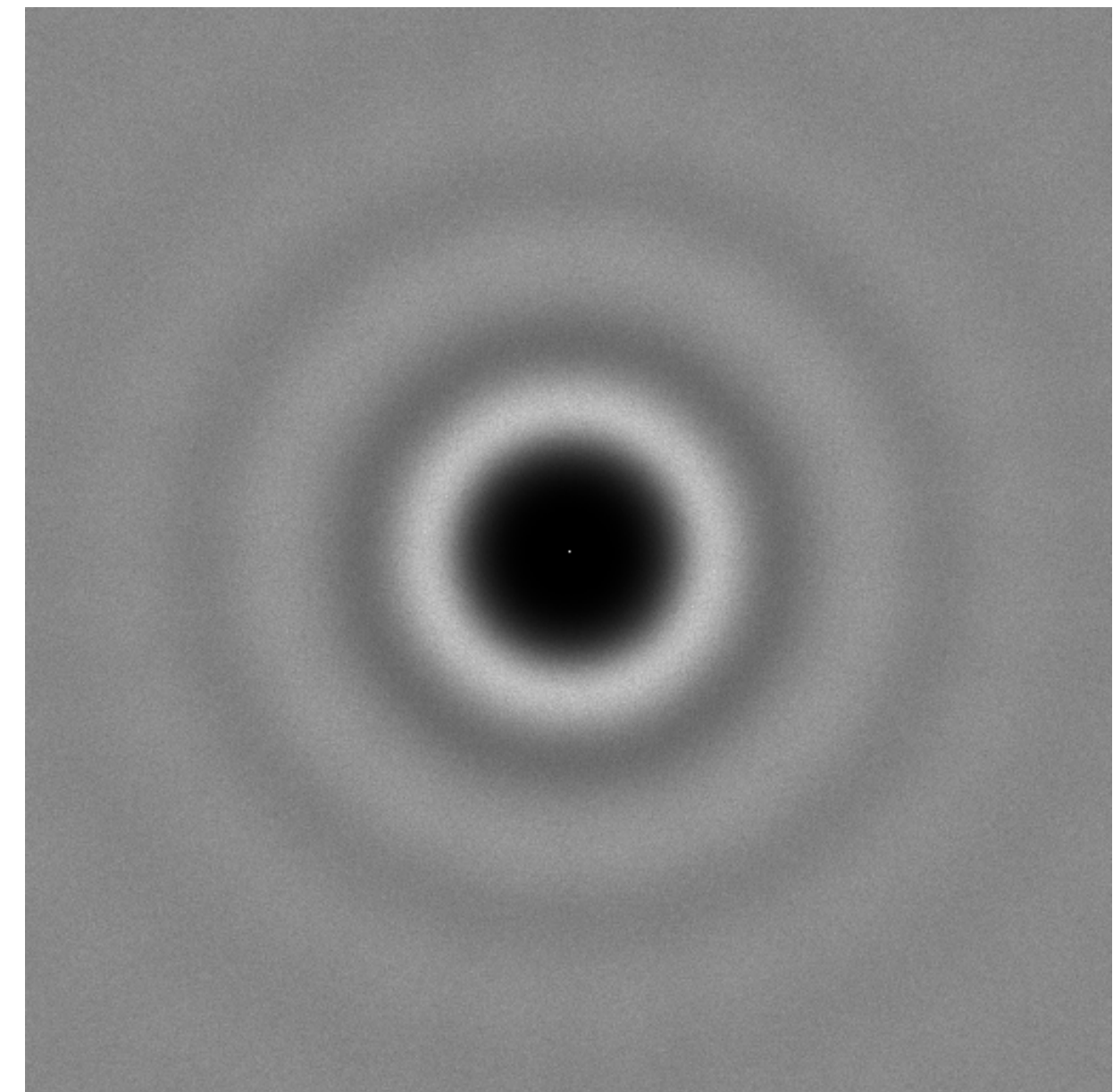
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For isotropic power spectra:

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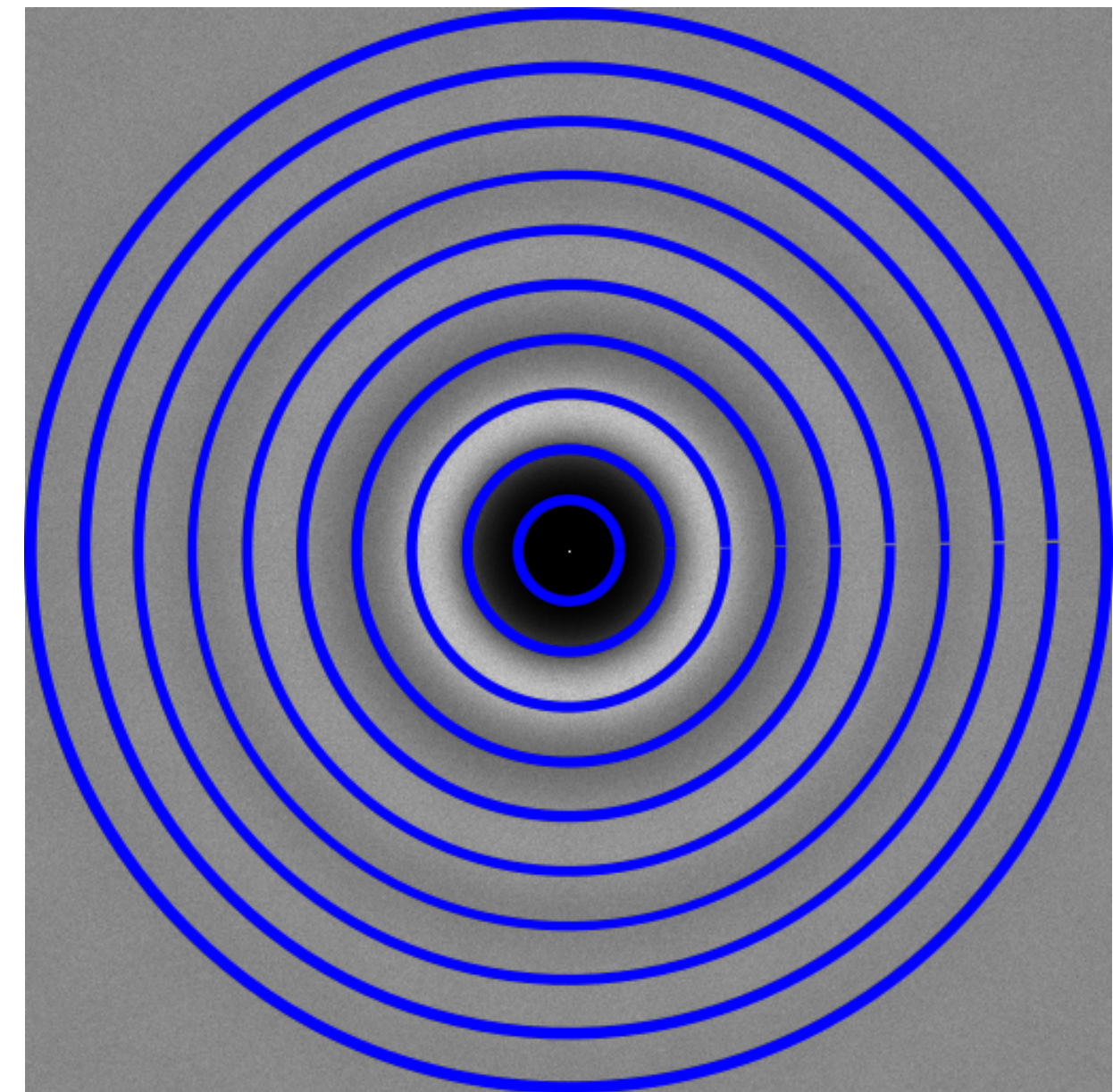
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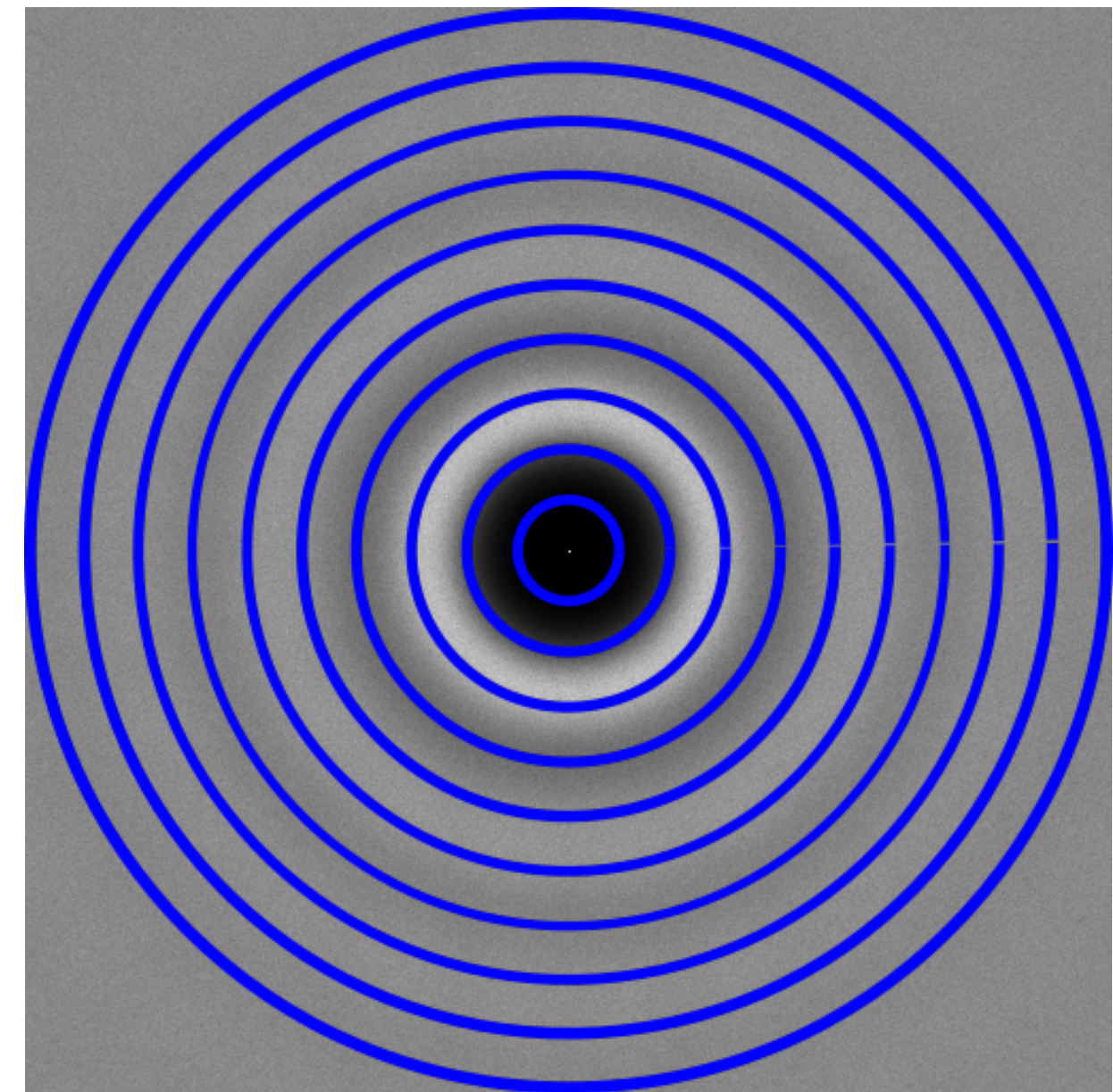


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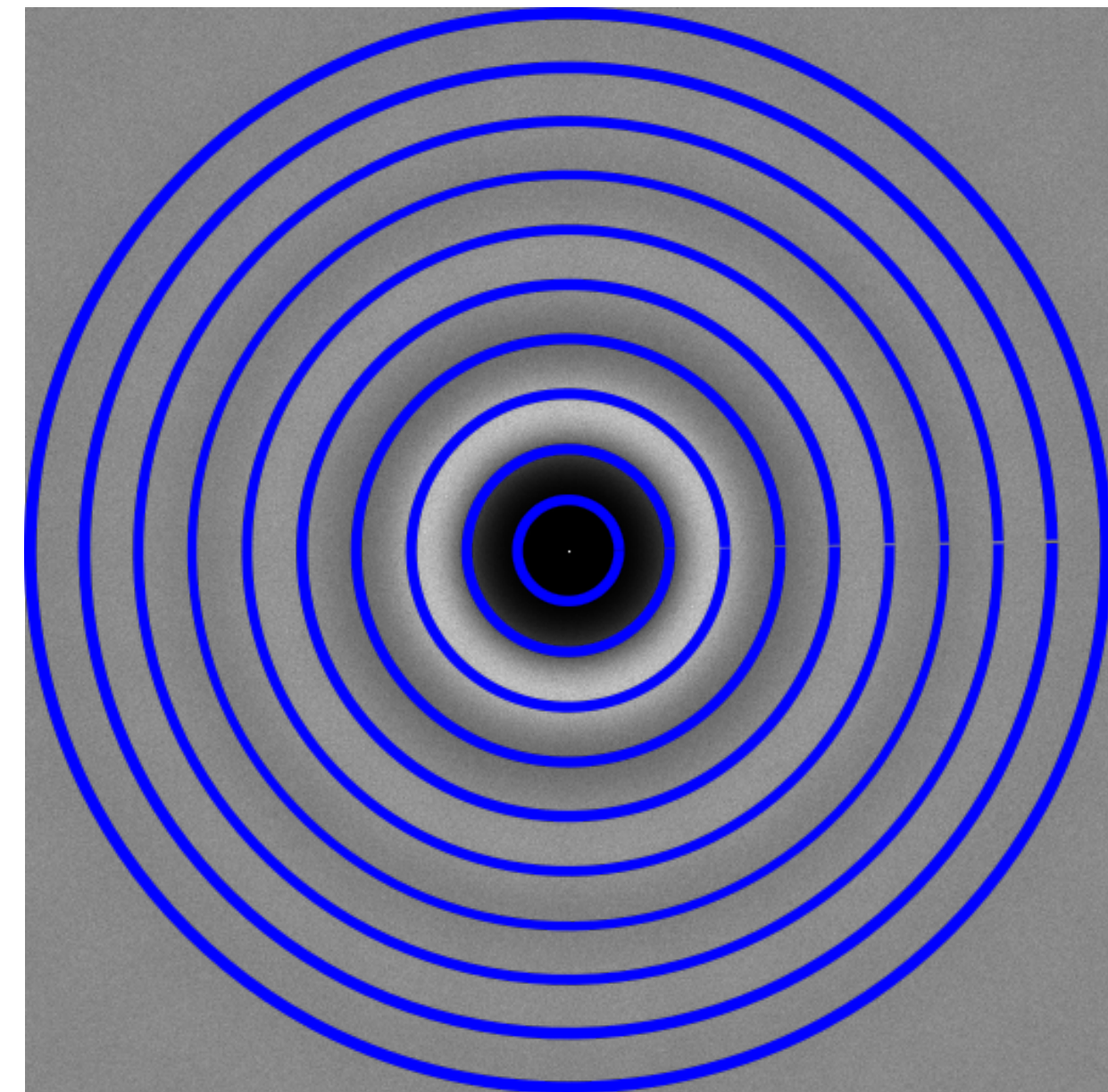


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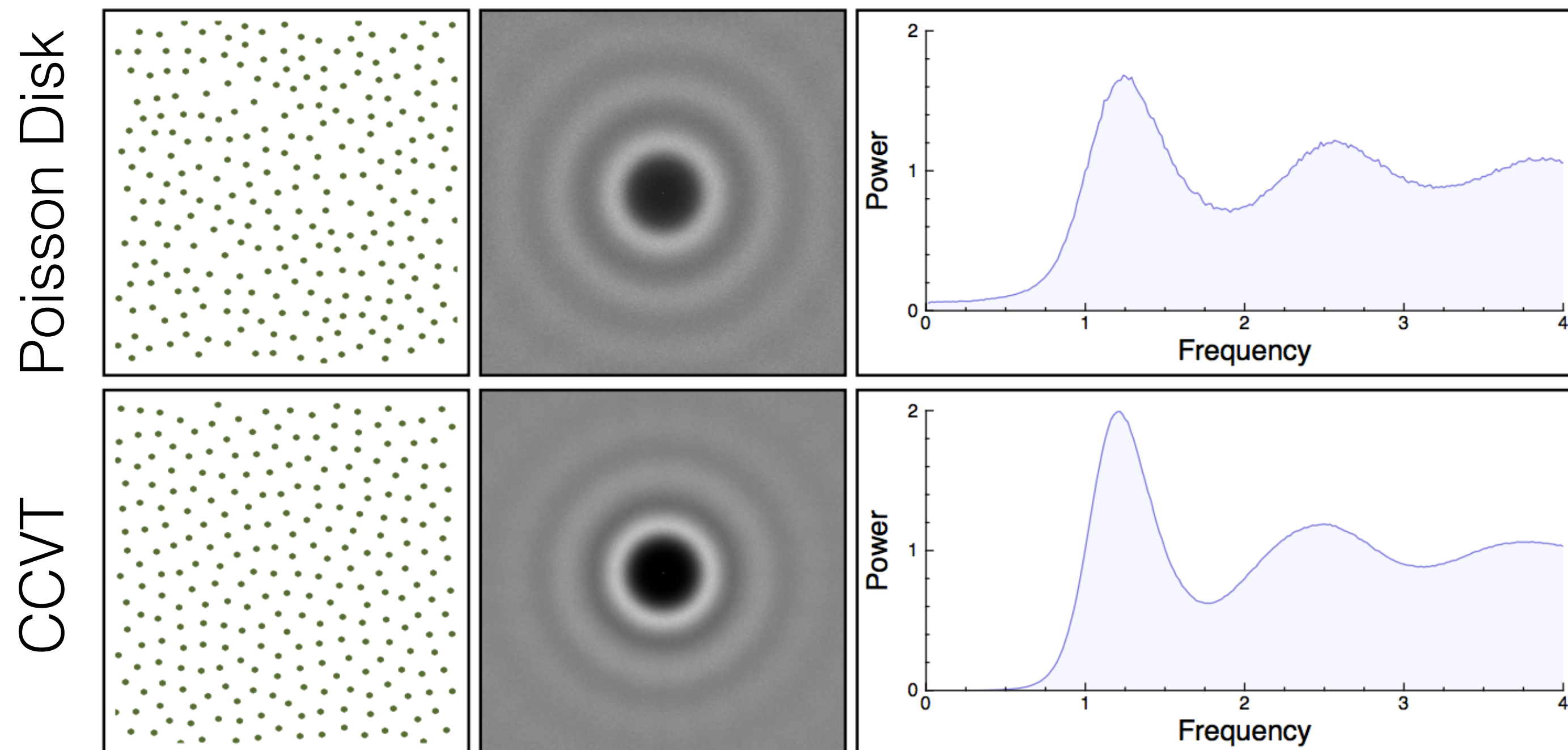
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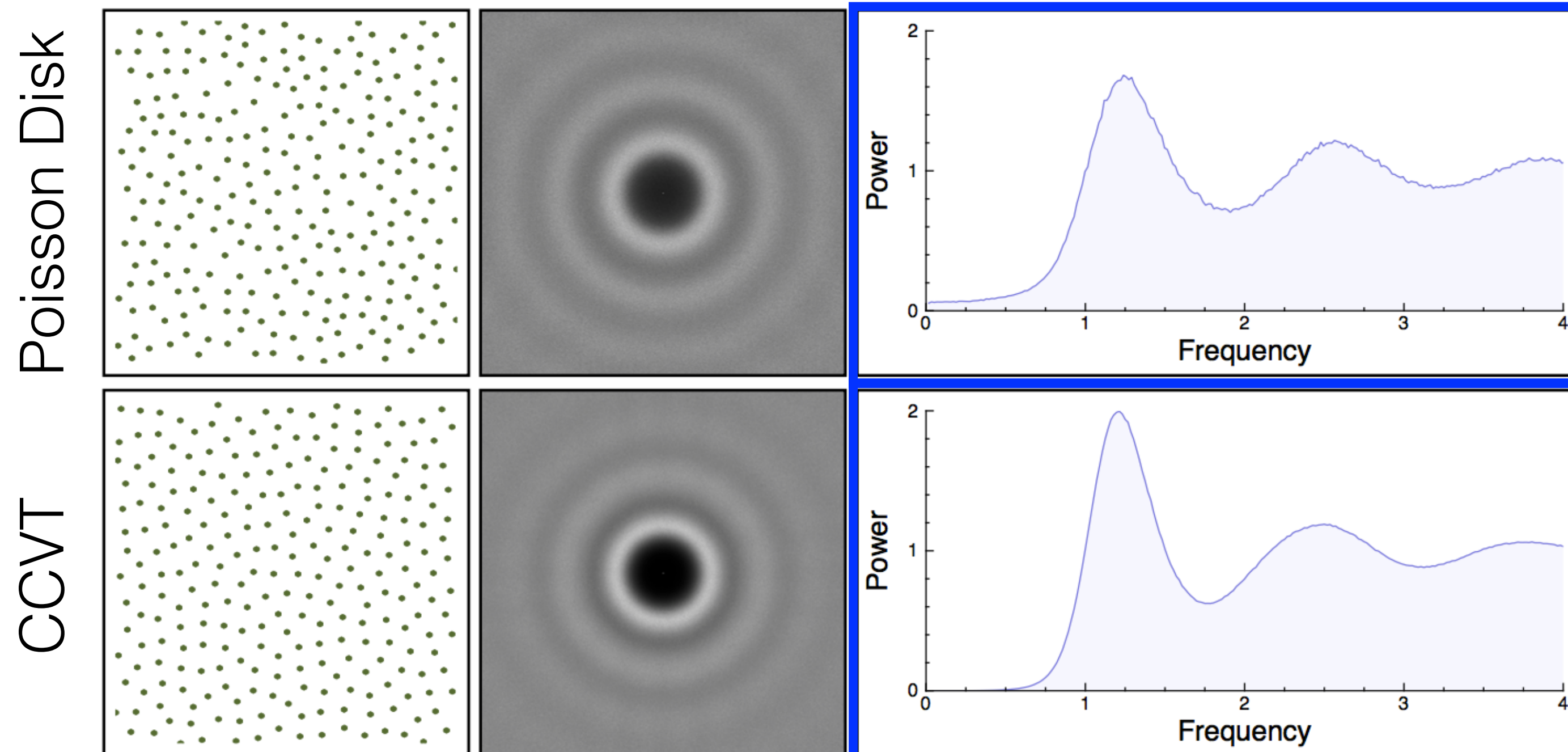
Variance in terms of 1-dimensional Power Spectra

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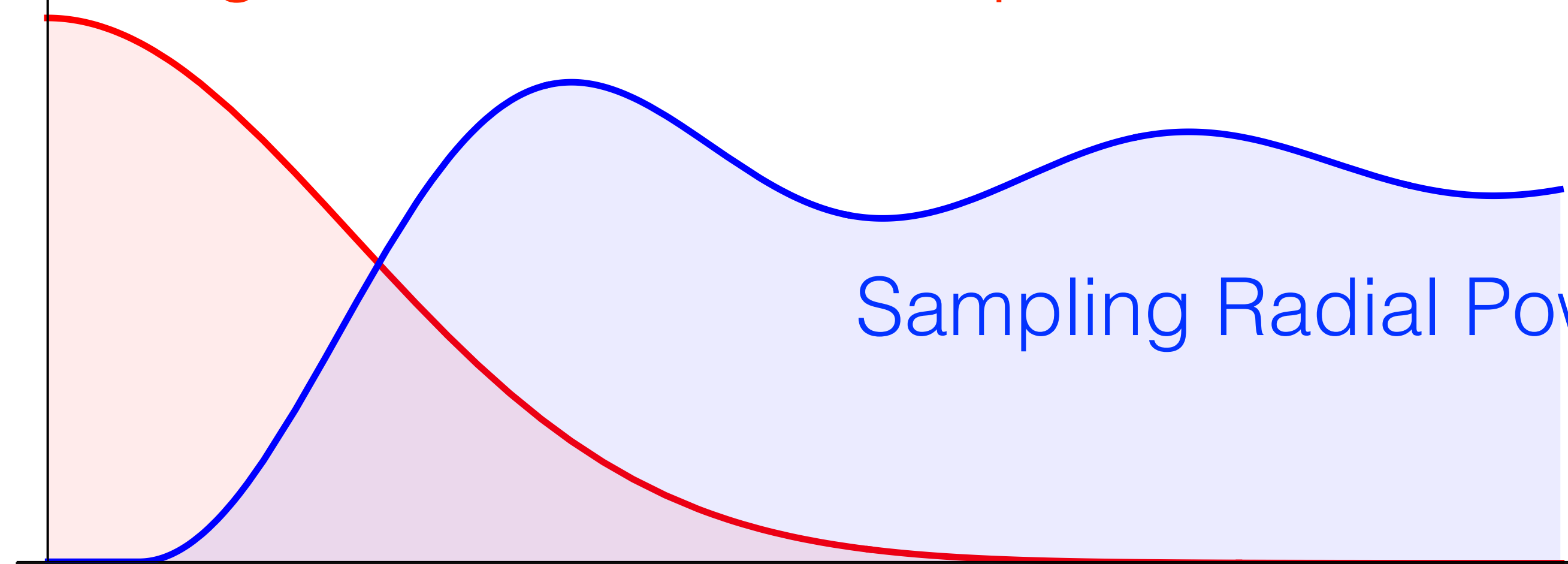
Variance: Integral over Product of Power Spectra

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Integrand Radial Power Spectrum



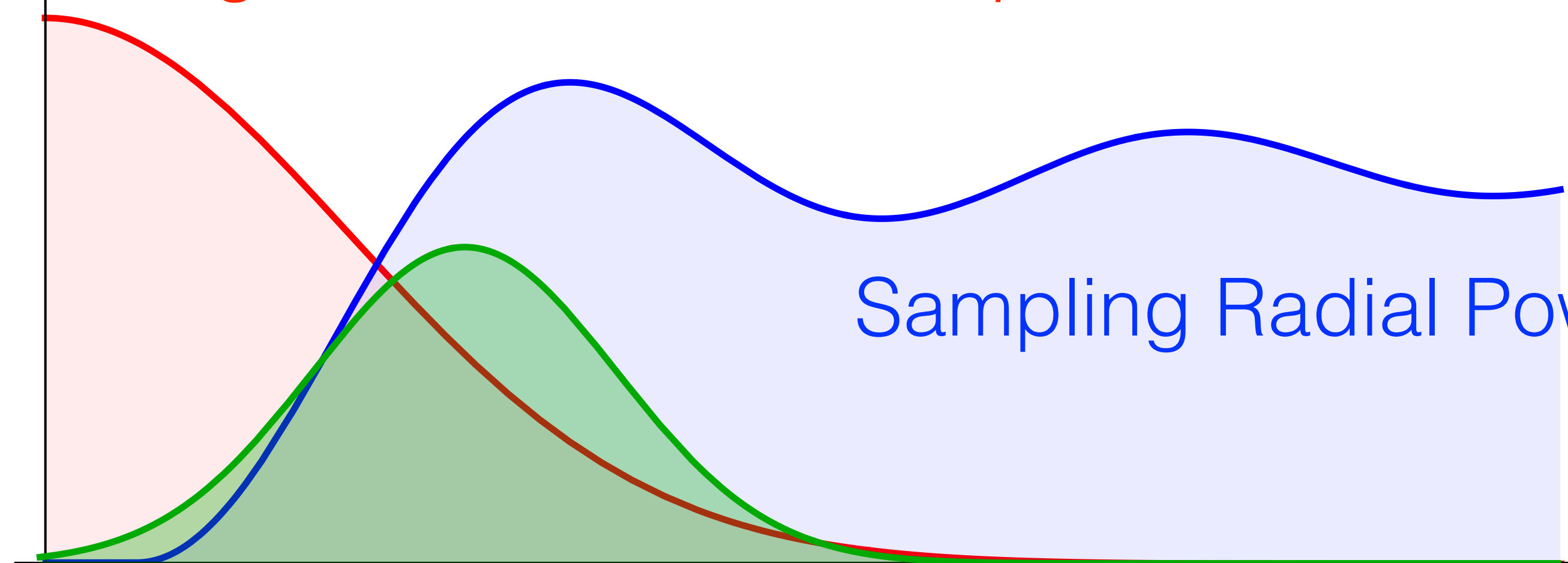
Sampling Radial Power Spectrum

For given number of Samples

Variance: Integral over Product of Power Spectra

$$\text{Var}[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty \tilde{P}_f(\rho) \langle \tilde{P}_s(\rho) \rangle d\rho$$

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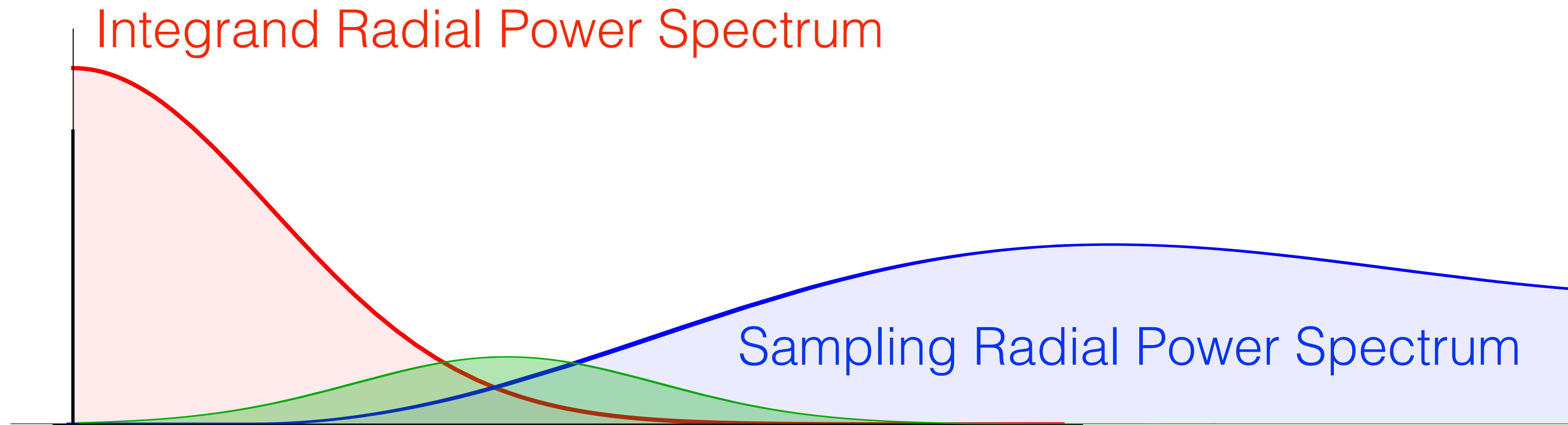


Sampling Radial Power Spectrum

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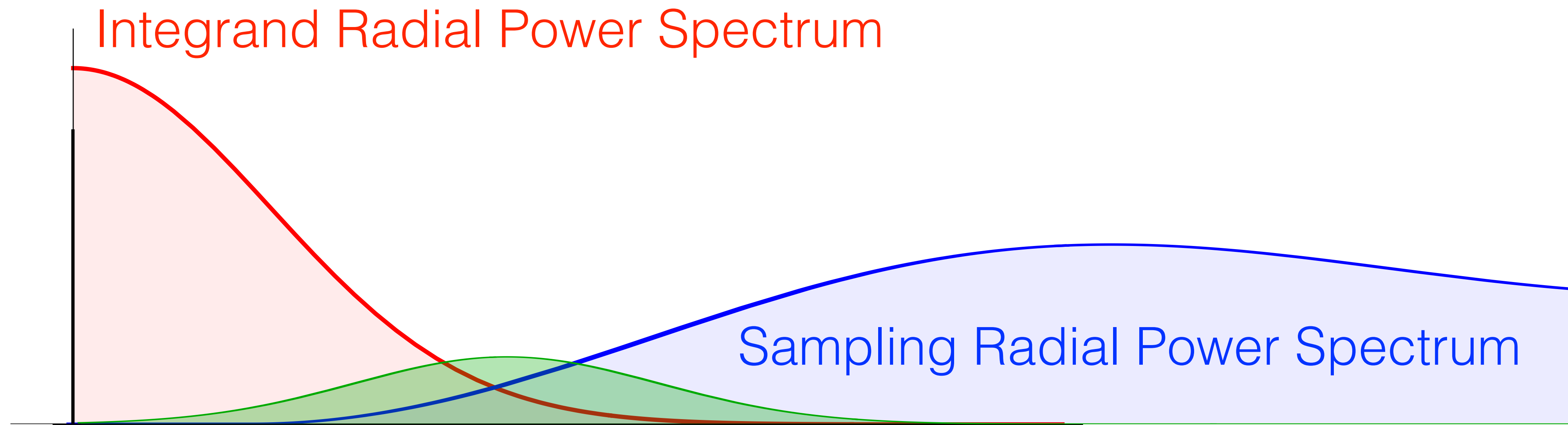
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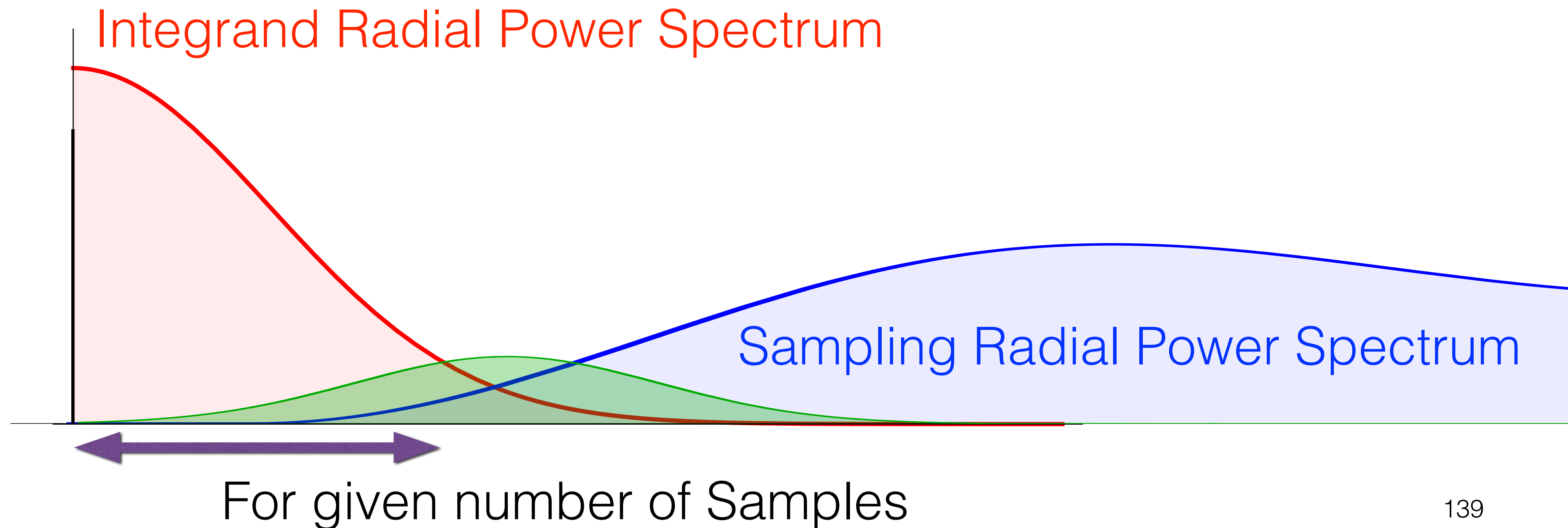
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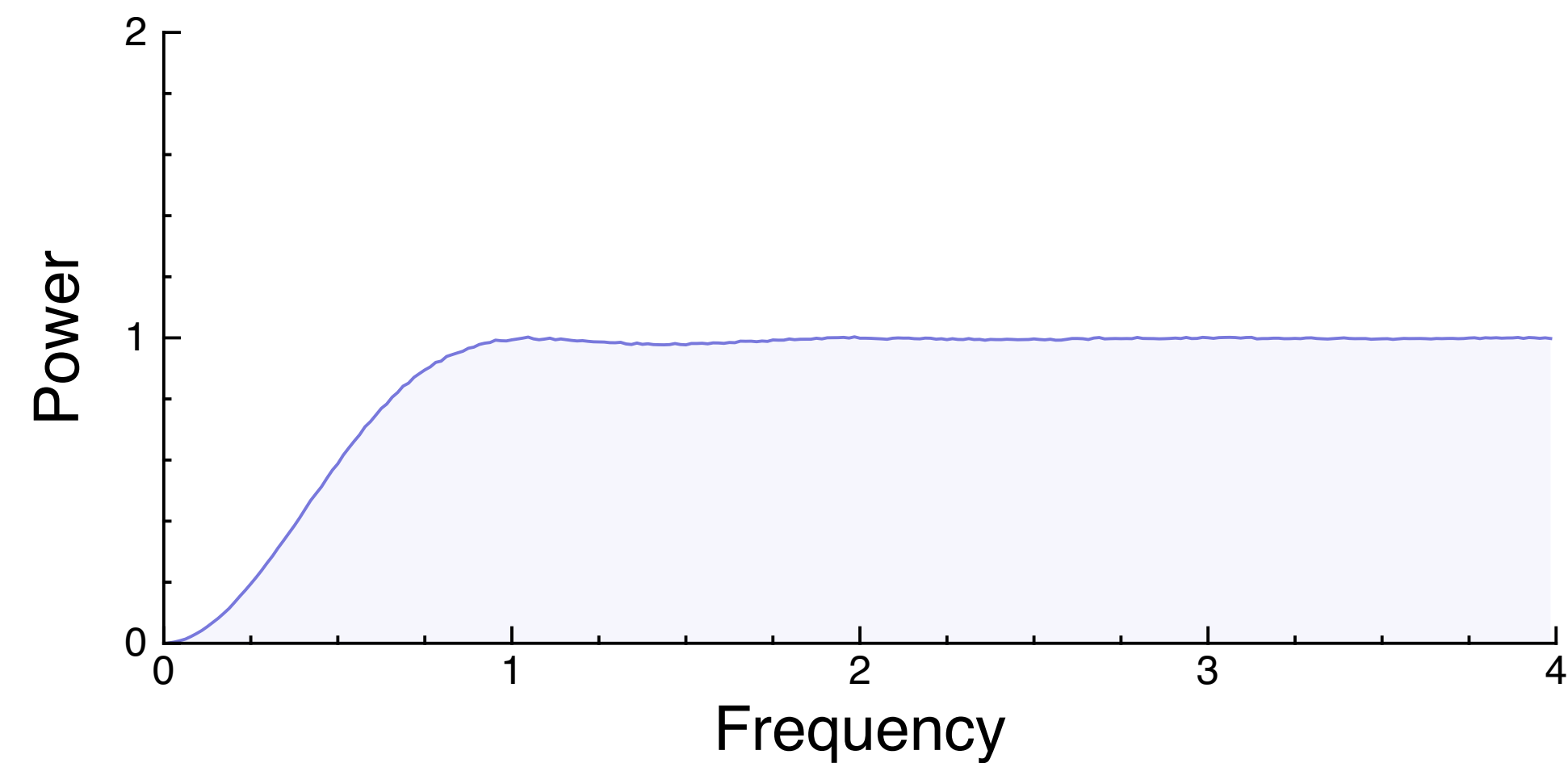
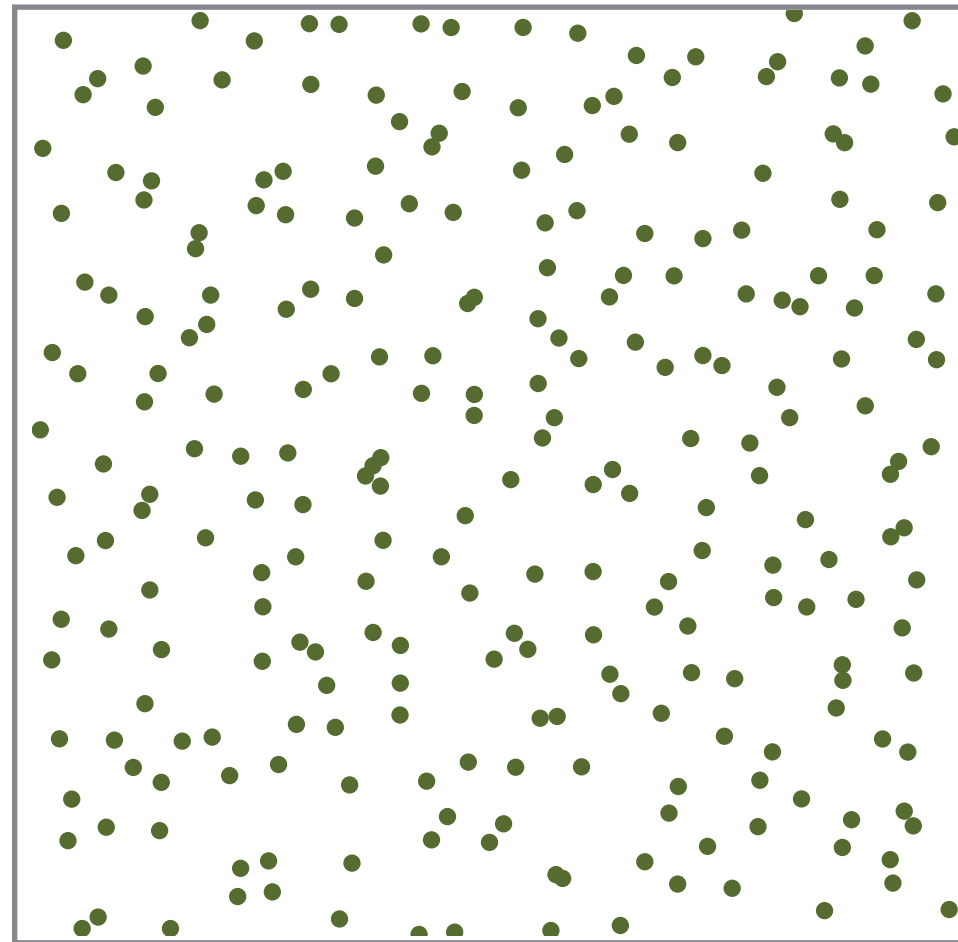
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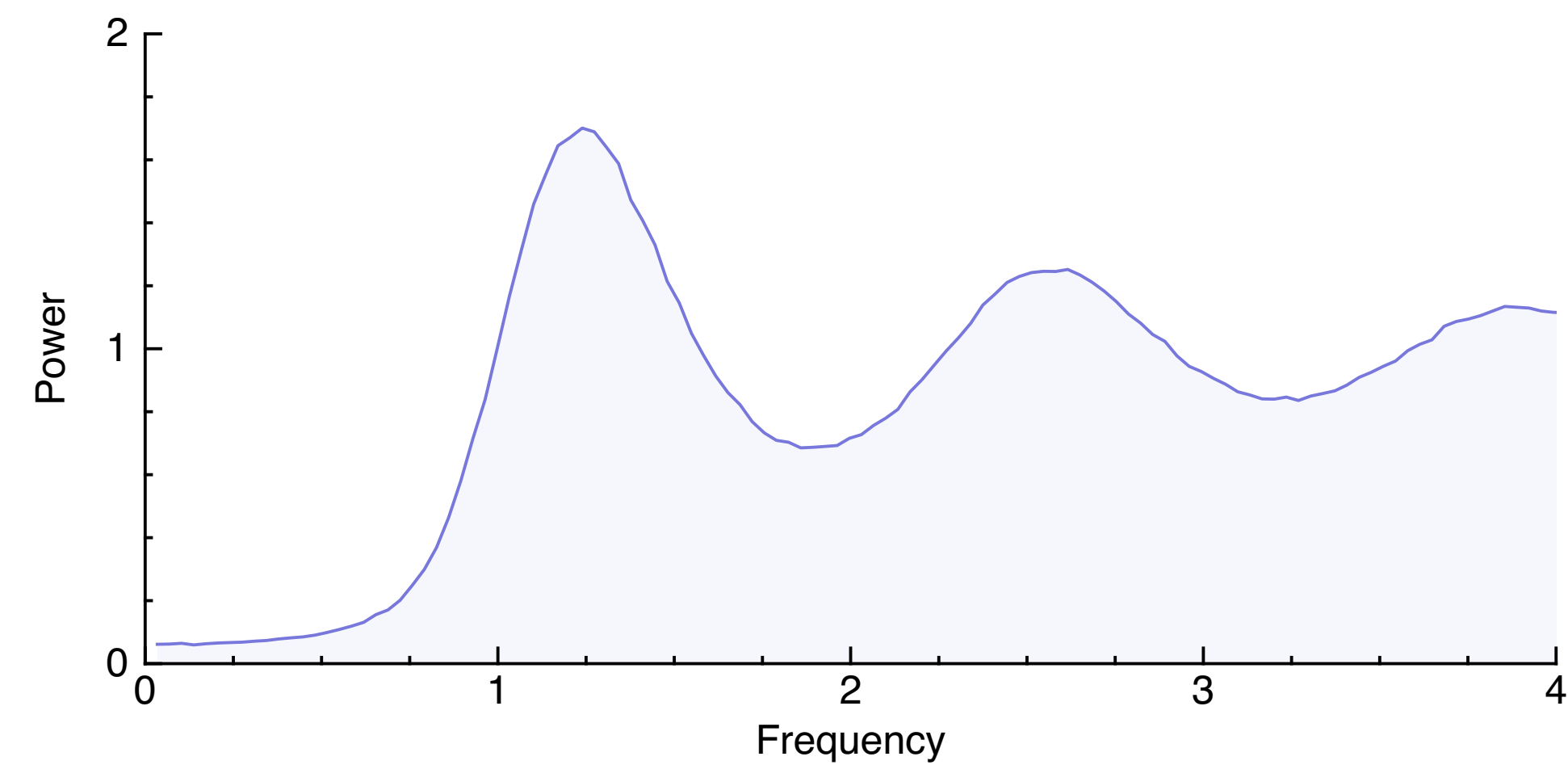
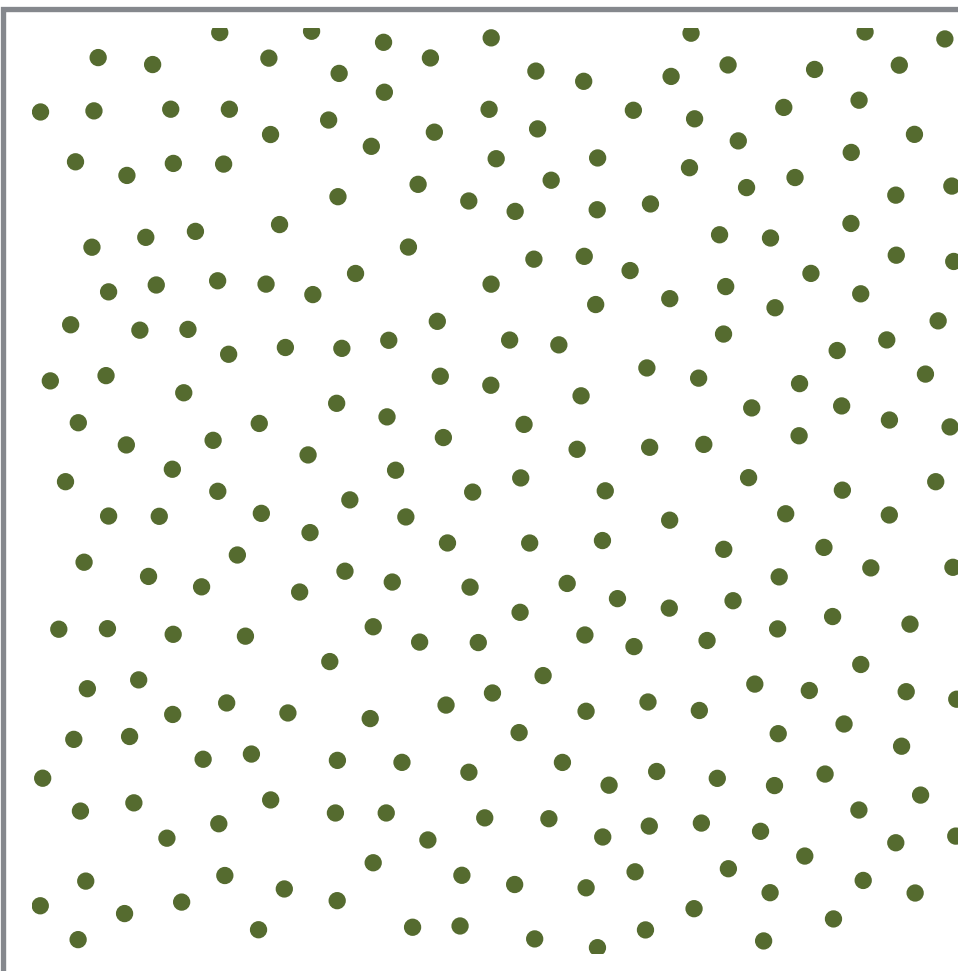


Spatial Distribution vs Radial Mean Power Spectra

Jitter



Poisson Disk



For 2-dimensions

Samplers	Worst Case	Best Case
Random		
Jitter		
Poisson Disk		
CCVT		

Pilleboue et al. [2015]

For 2-dimensions

Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	
Jitter		
Poisson Disk		
CCVT		

Pilleboue et al. [2015]

For 2-dimensions

Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter		
Poisson Disk		
CCVT		

Pilleboue et al. [2015]

For 2-dimensions

Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	
Poisson Disk		
CCVT		

Pilleboue et al. [2015]

For 2-dimensions

Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-2})$
Poisson Disk		
CCVT		

Pilleboue et al. [2015]

For 2-dimensions

Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-2})$
Poisson Disk	$\mathcal{O}(N^{-1})$	
CCVT		

Pilleboue et al. [2015]

For 2-dimensions

Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-2})$
Poisson Disk	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
CCVT		

Pilleboue et al. [2015]

For 2-dimensions

Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-2})$
Poisson Disk	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
CCVT	$\mathcal{O}(N^{-1.5})$	

Pilleboue et al. [2015]

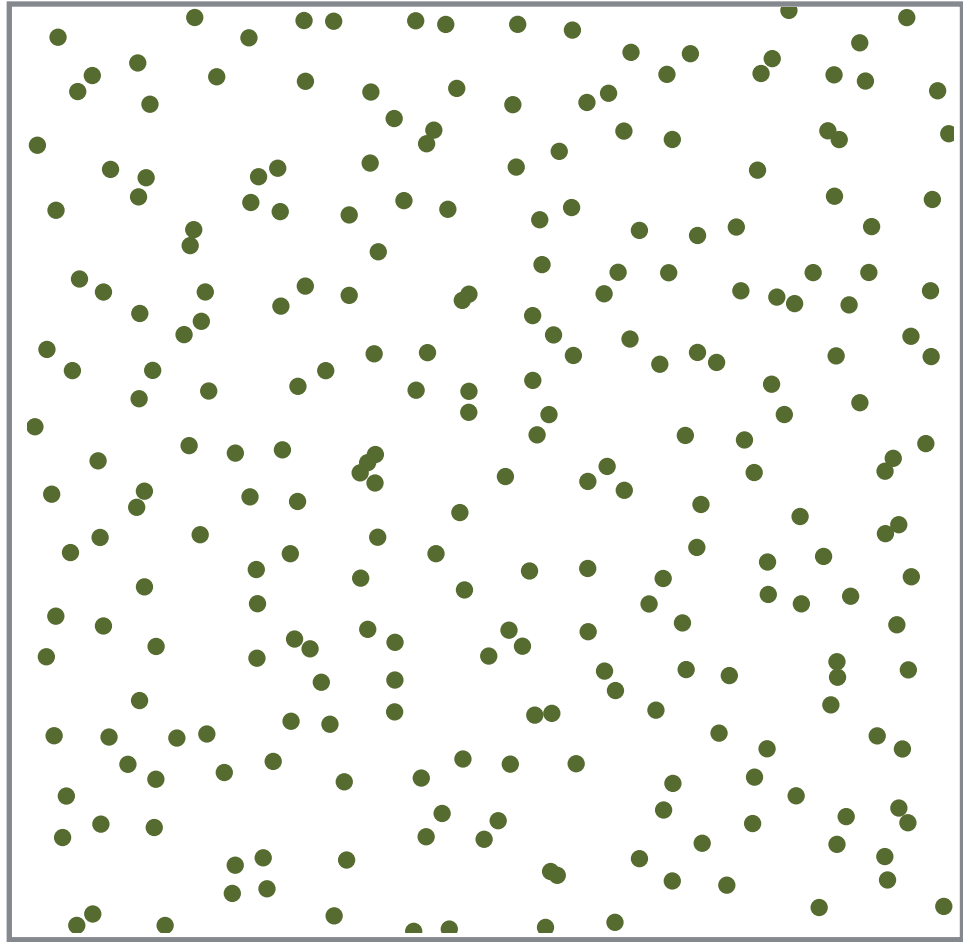
For 2-dimensions

Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-2})$
Poisson Disk	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
CCVT	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-3})$

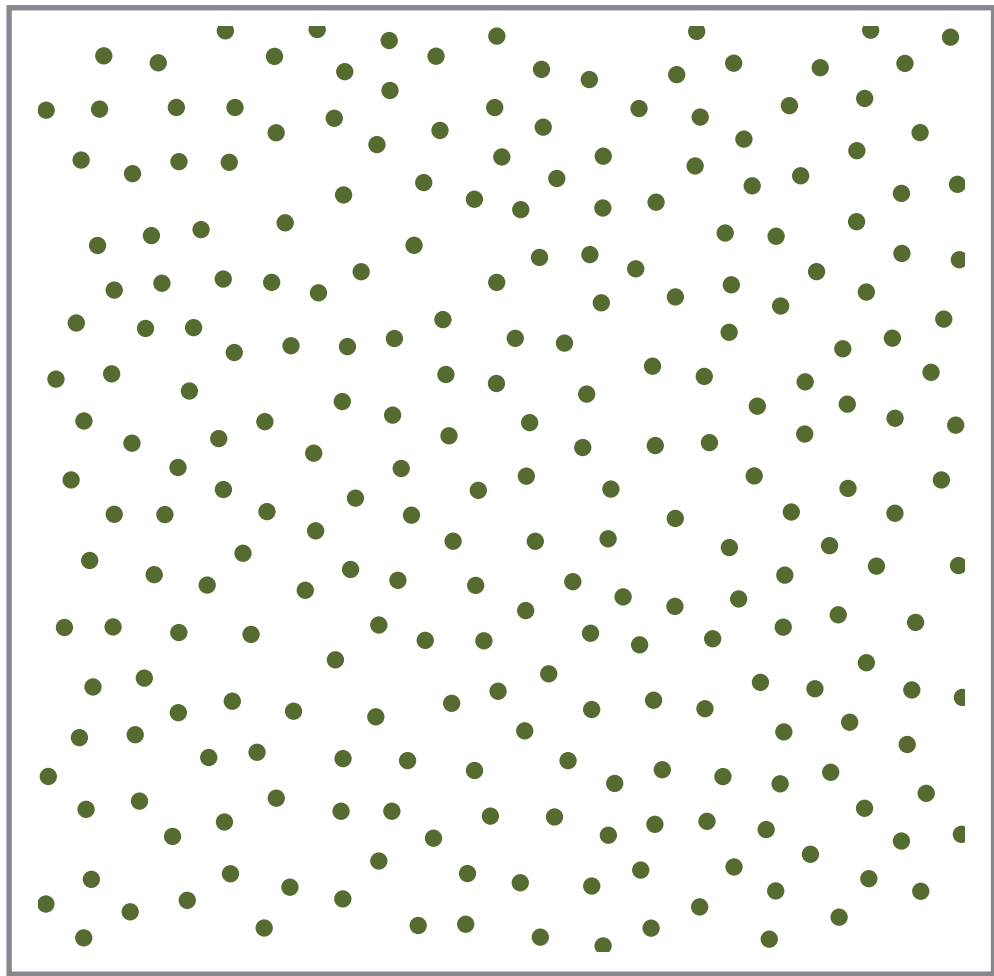
Pilleboue et al. [2015]

For 2-dimensions

Jitter



Poisson Disk

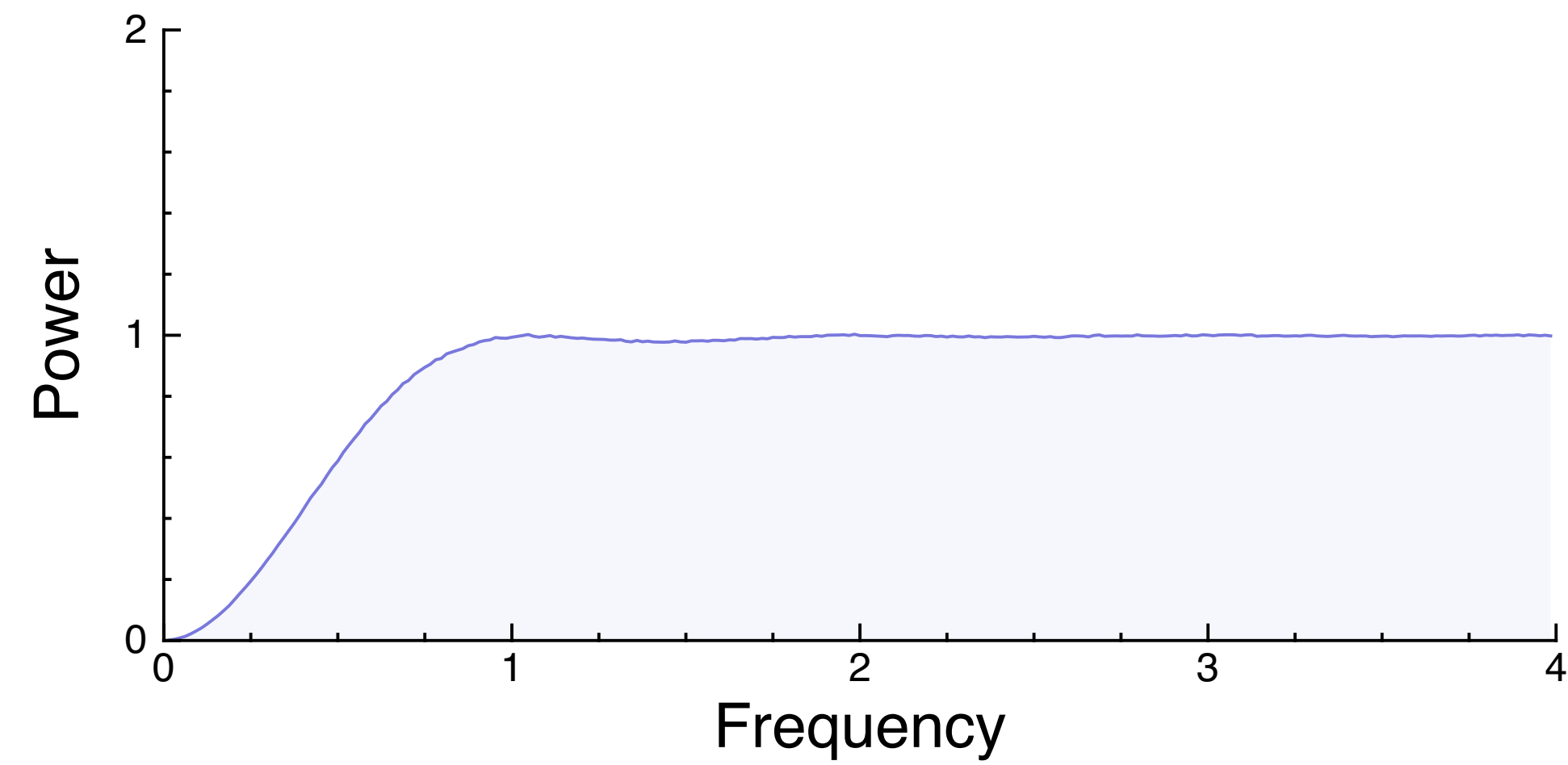


Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-2})$
Poisson Disk	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
CCVT	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-3})$

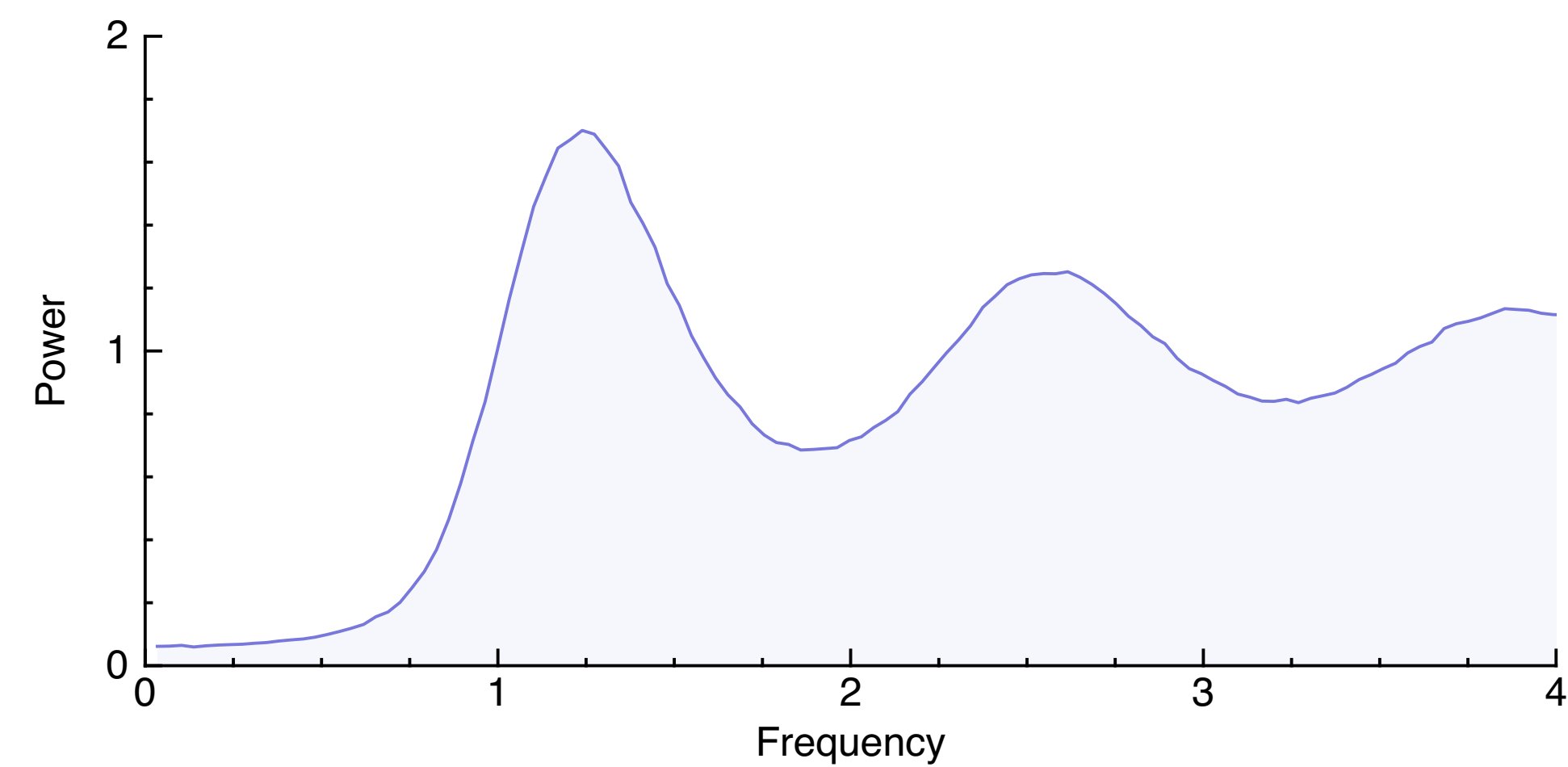
Pilleboue et al. [2015]

Low Frequency Region

Jitter

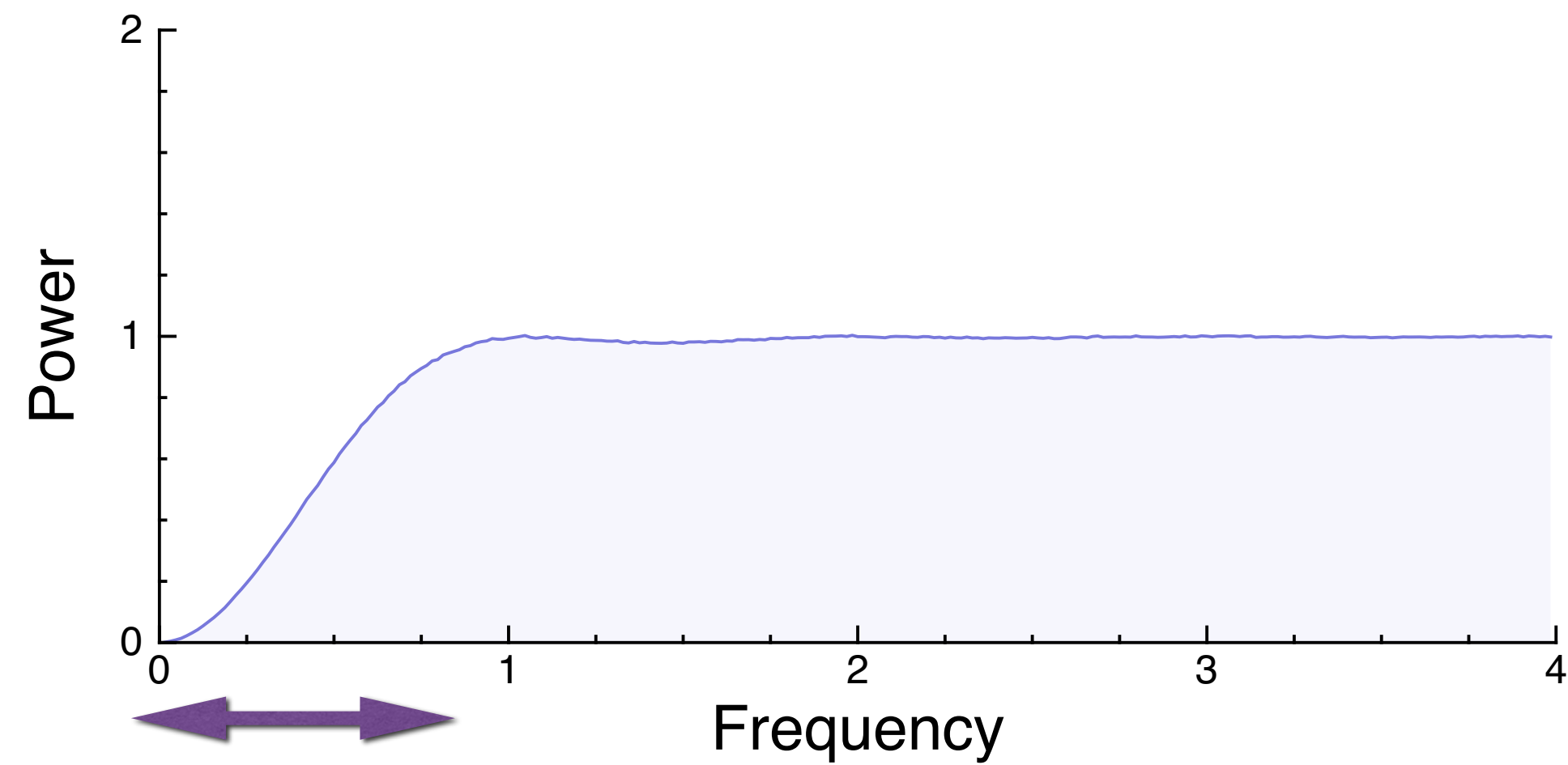


Poisson Disk

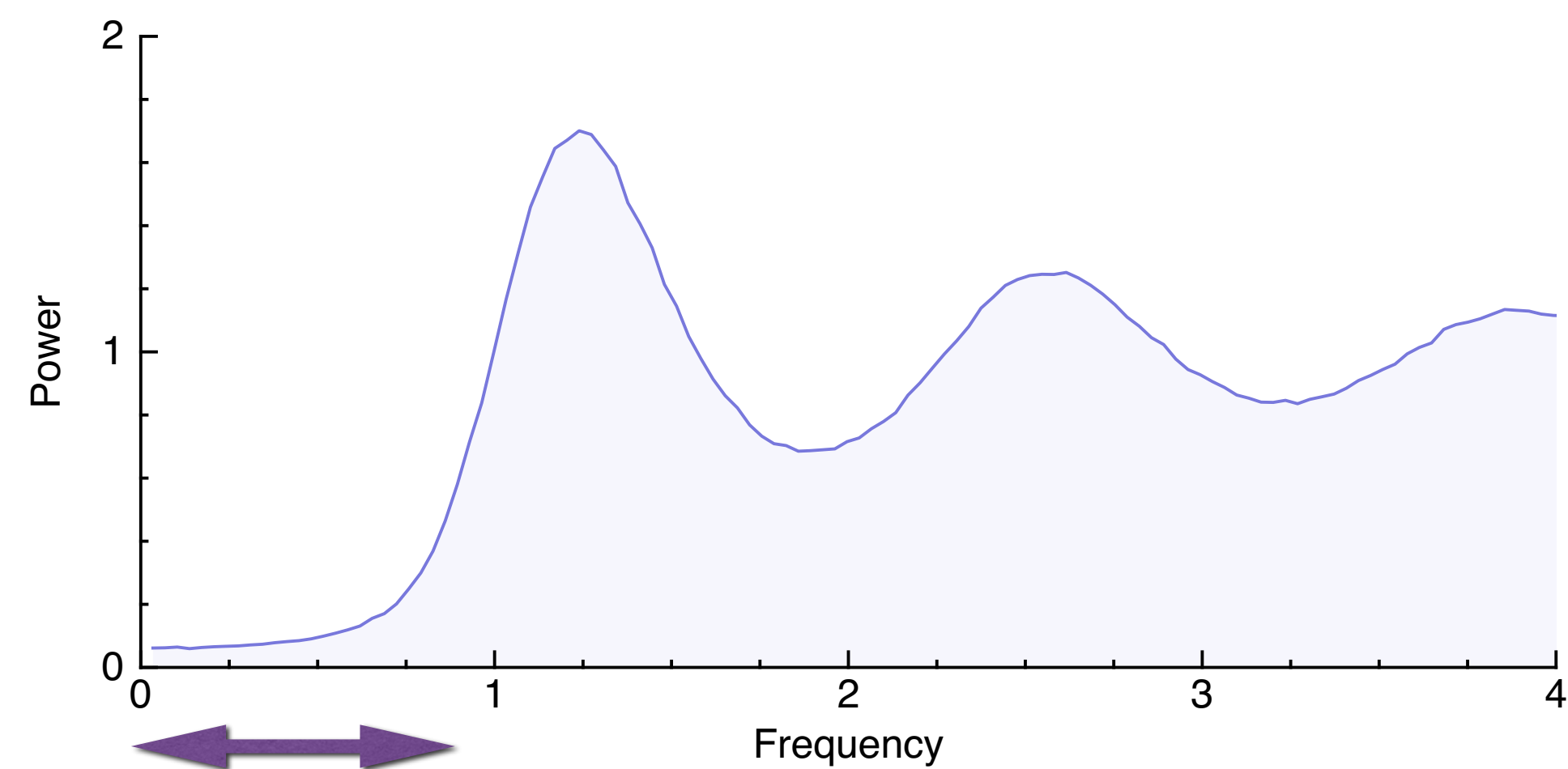


Low Frequency Region

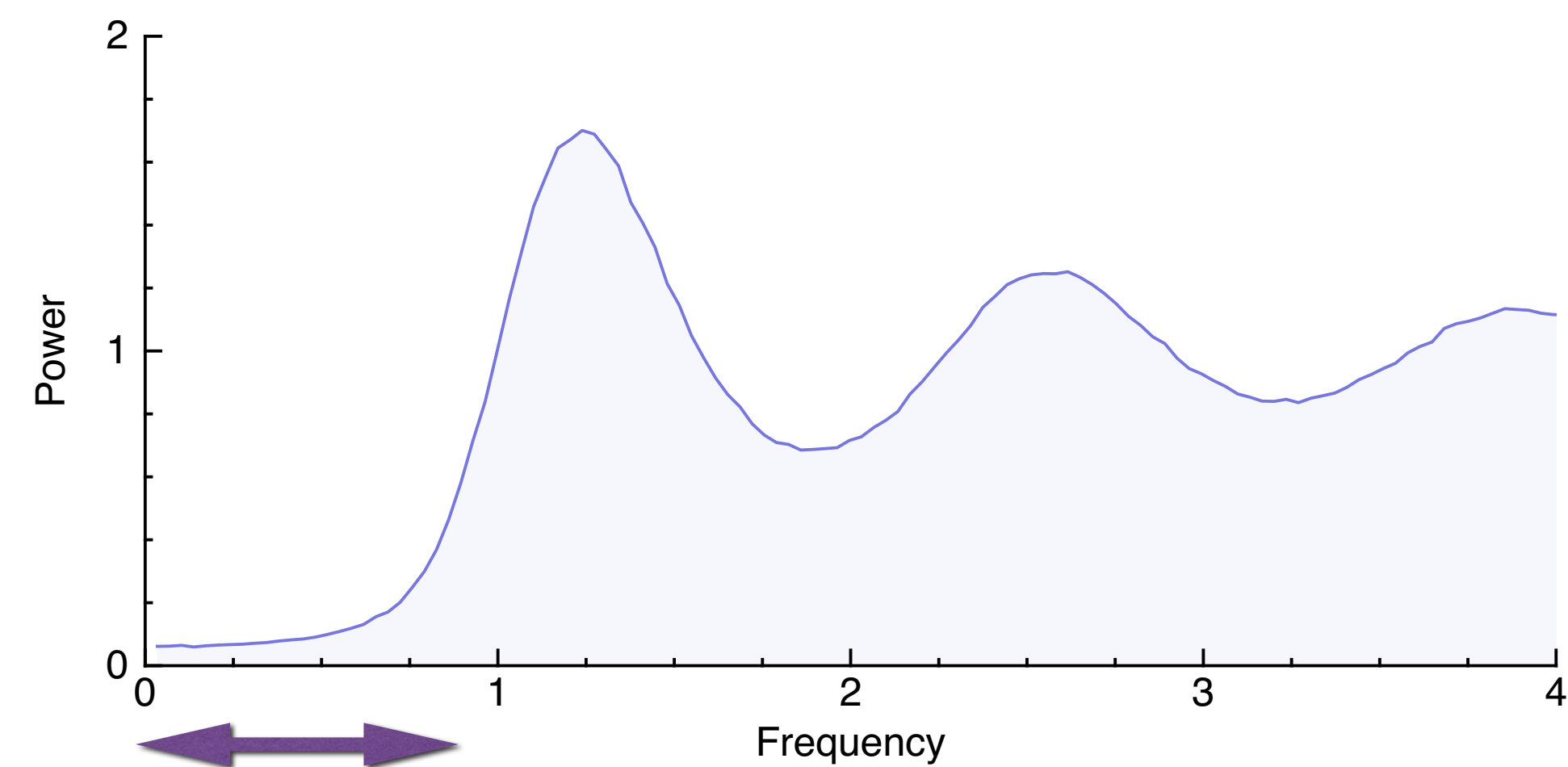
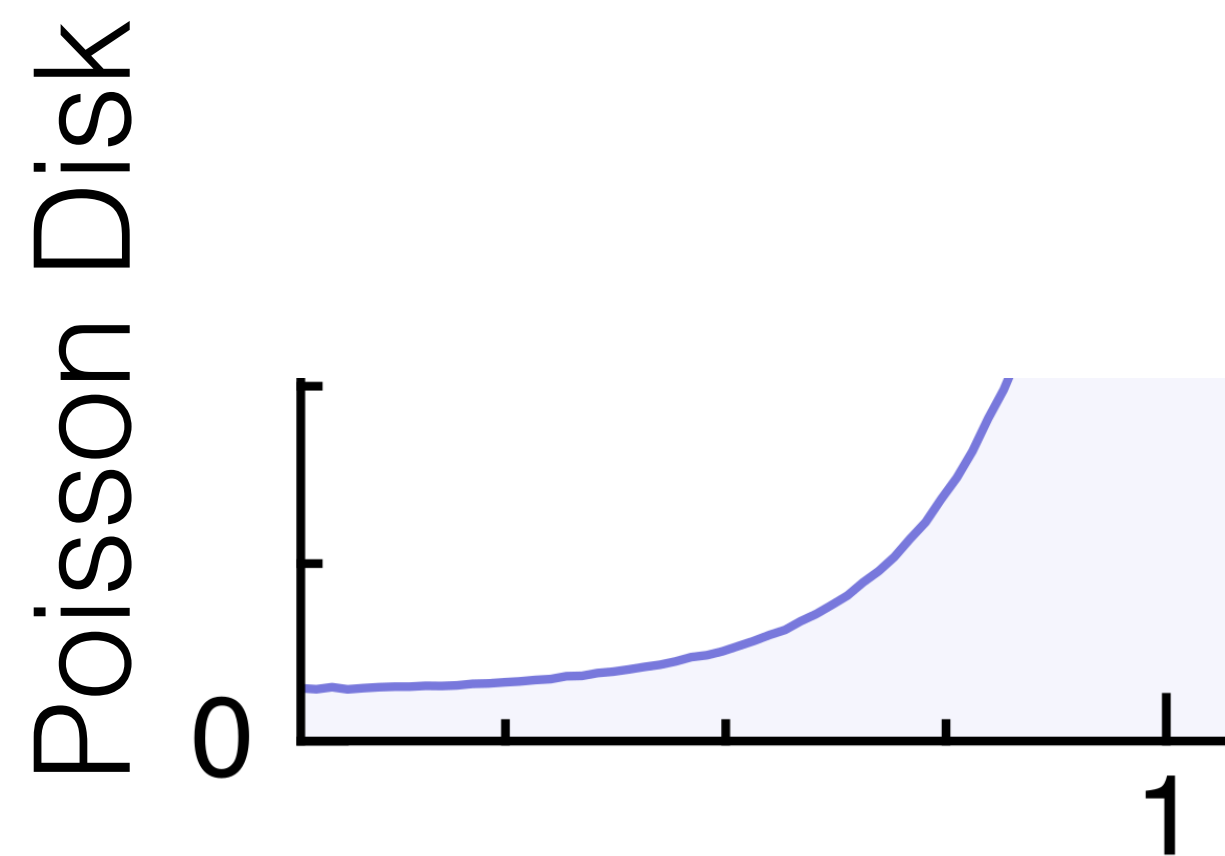
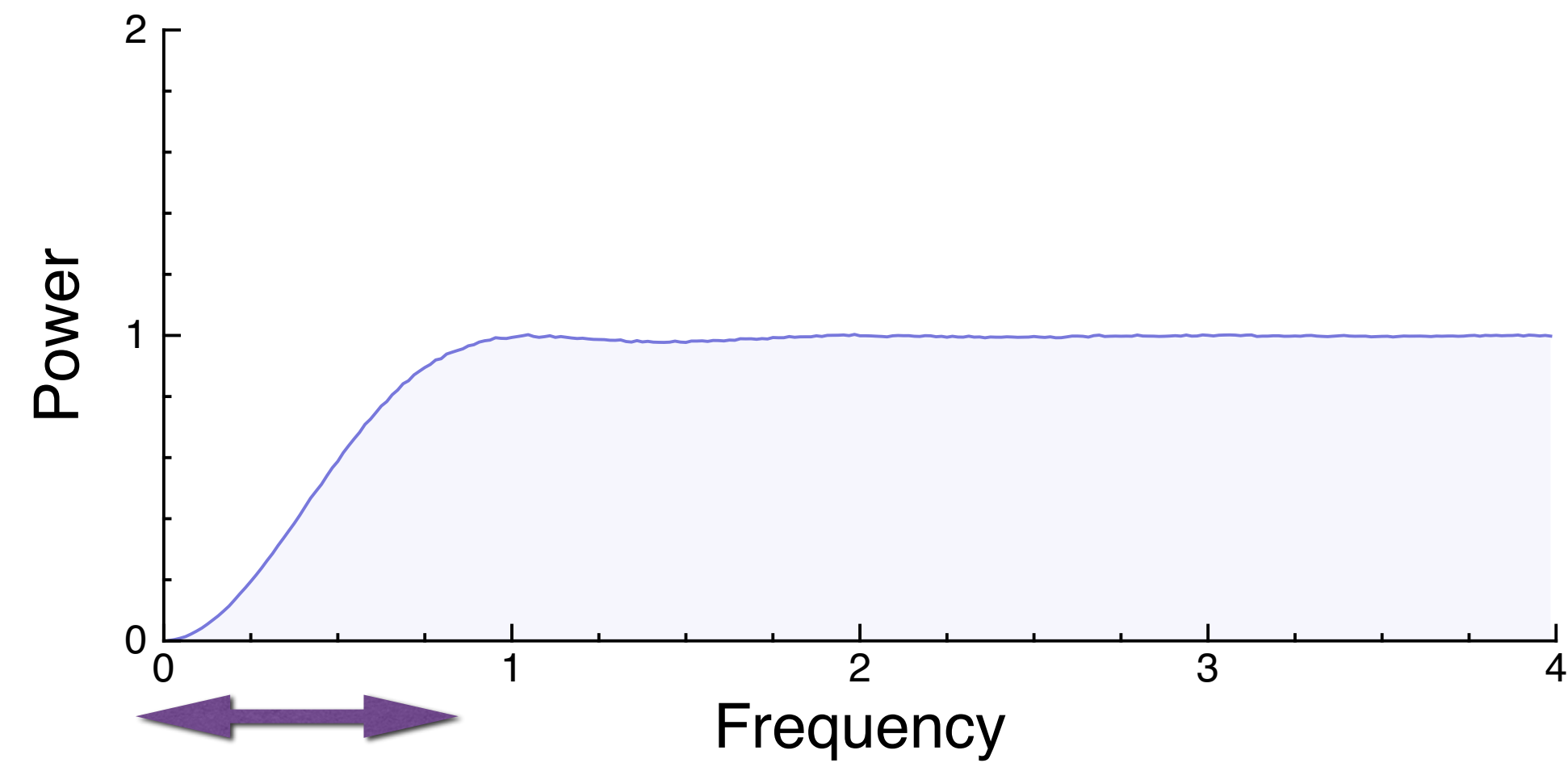
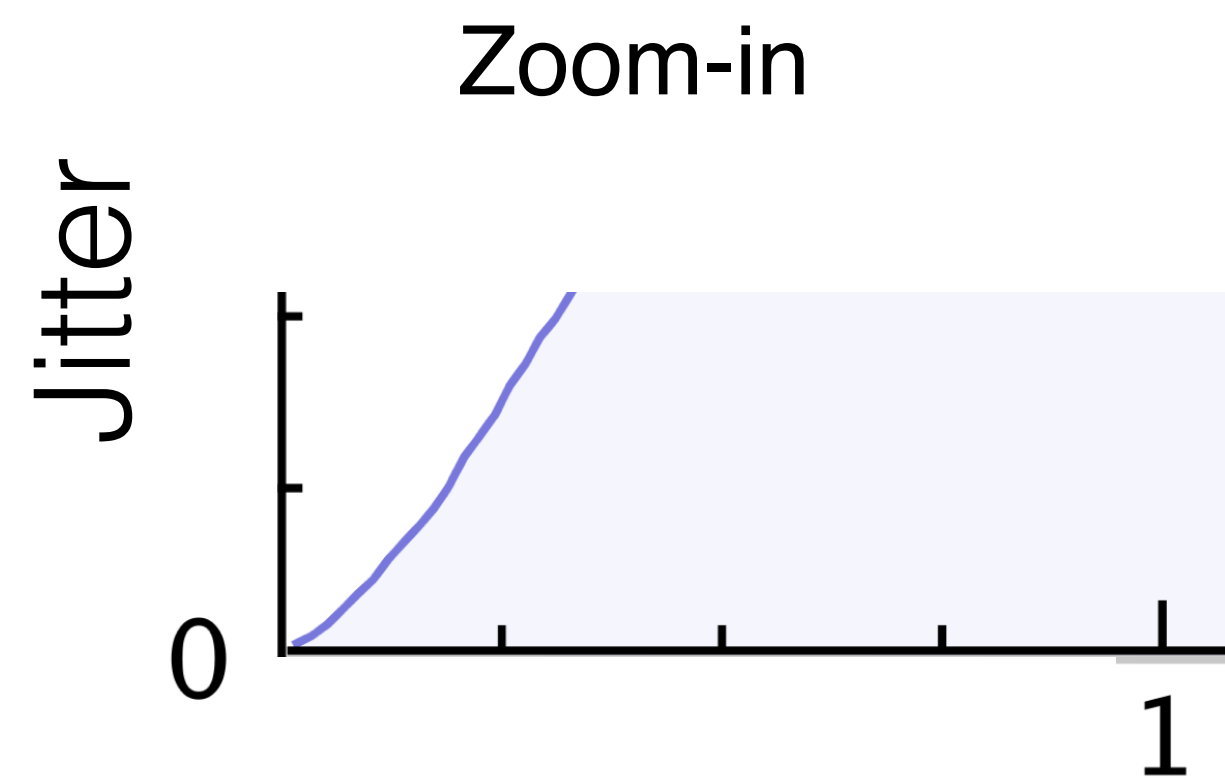
Jitter



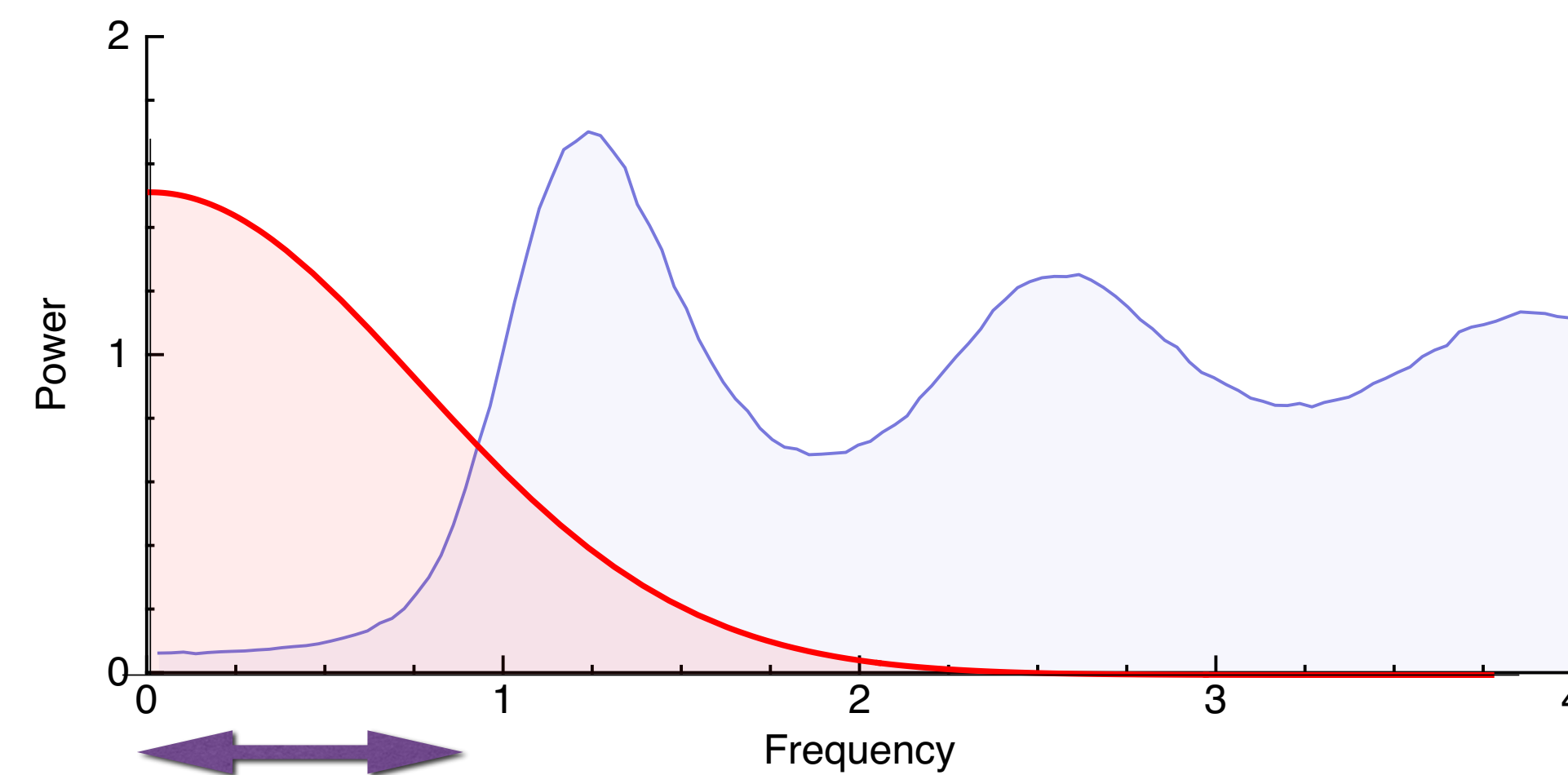
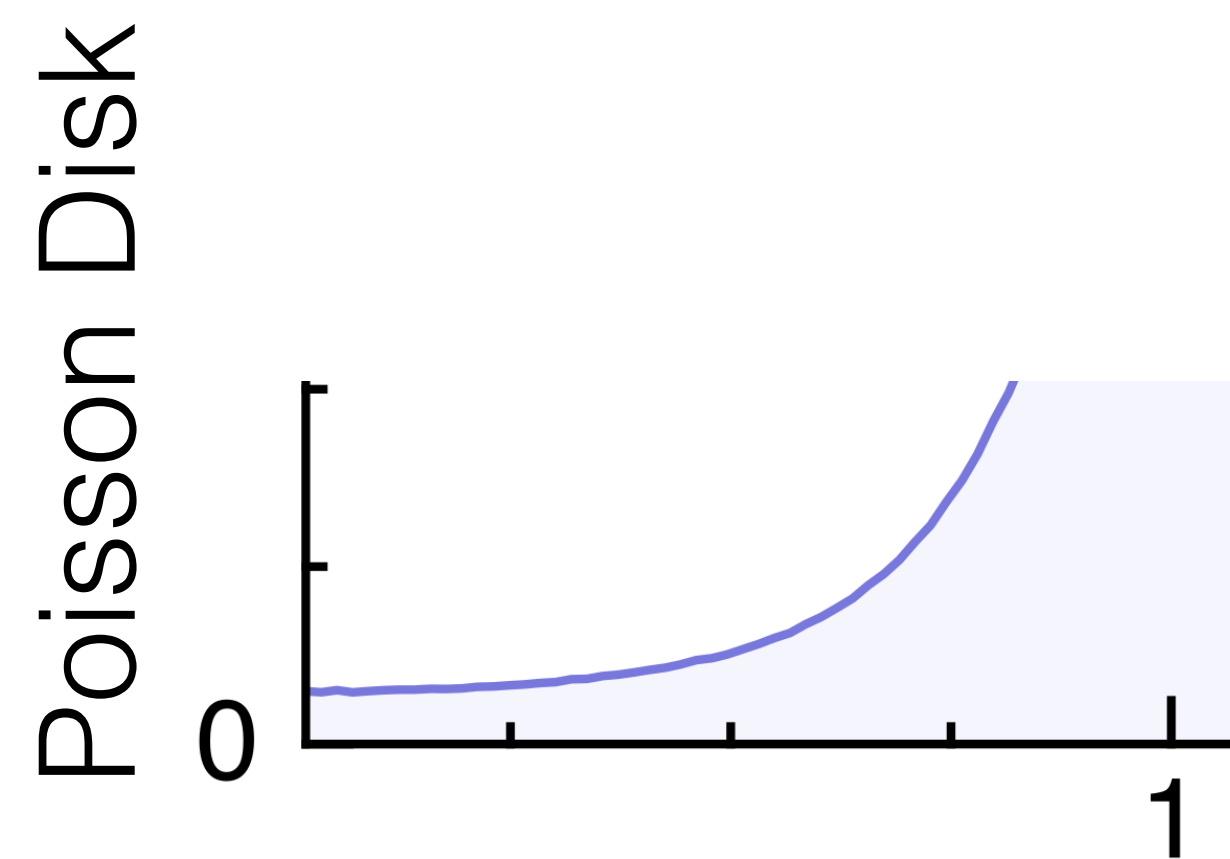
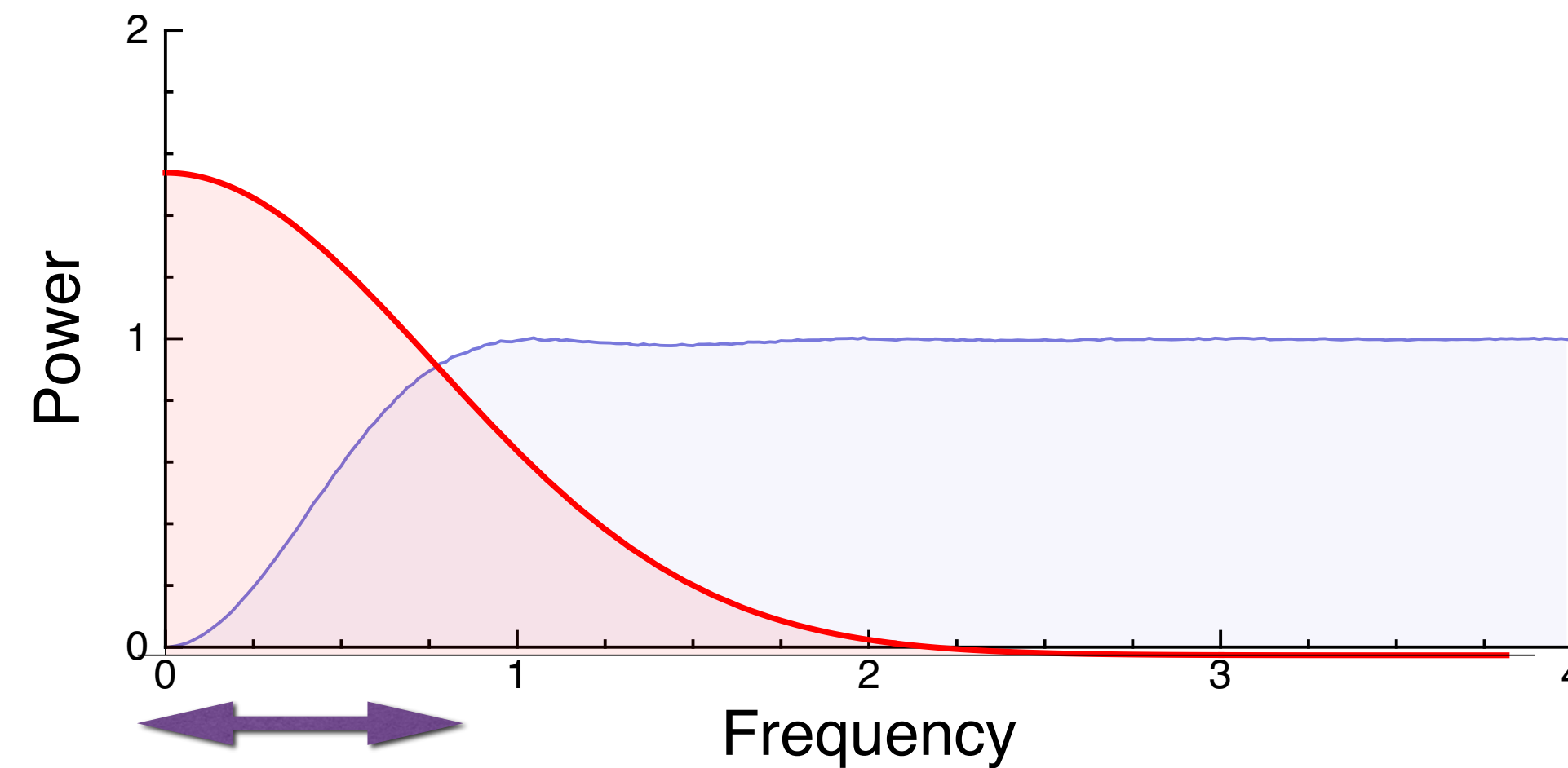
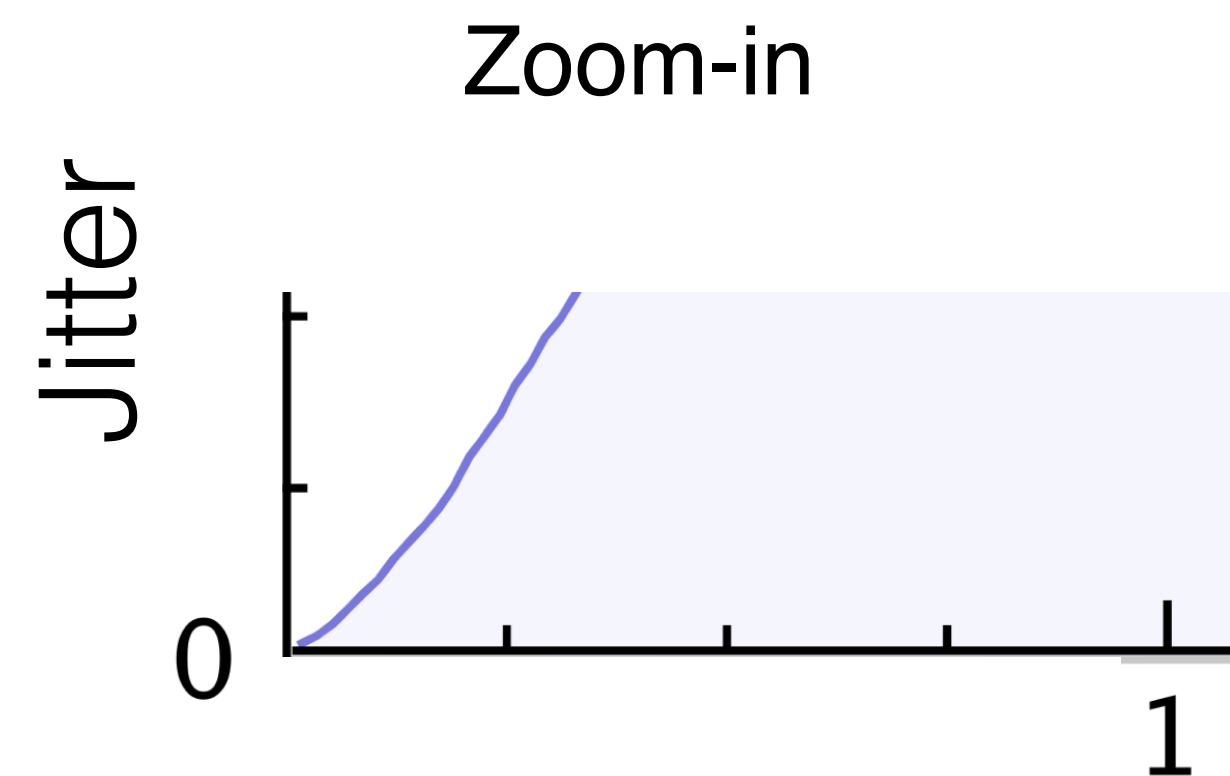
Poisson Disk



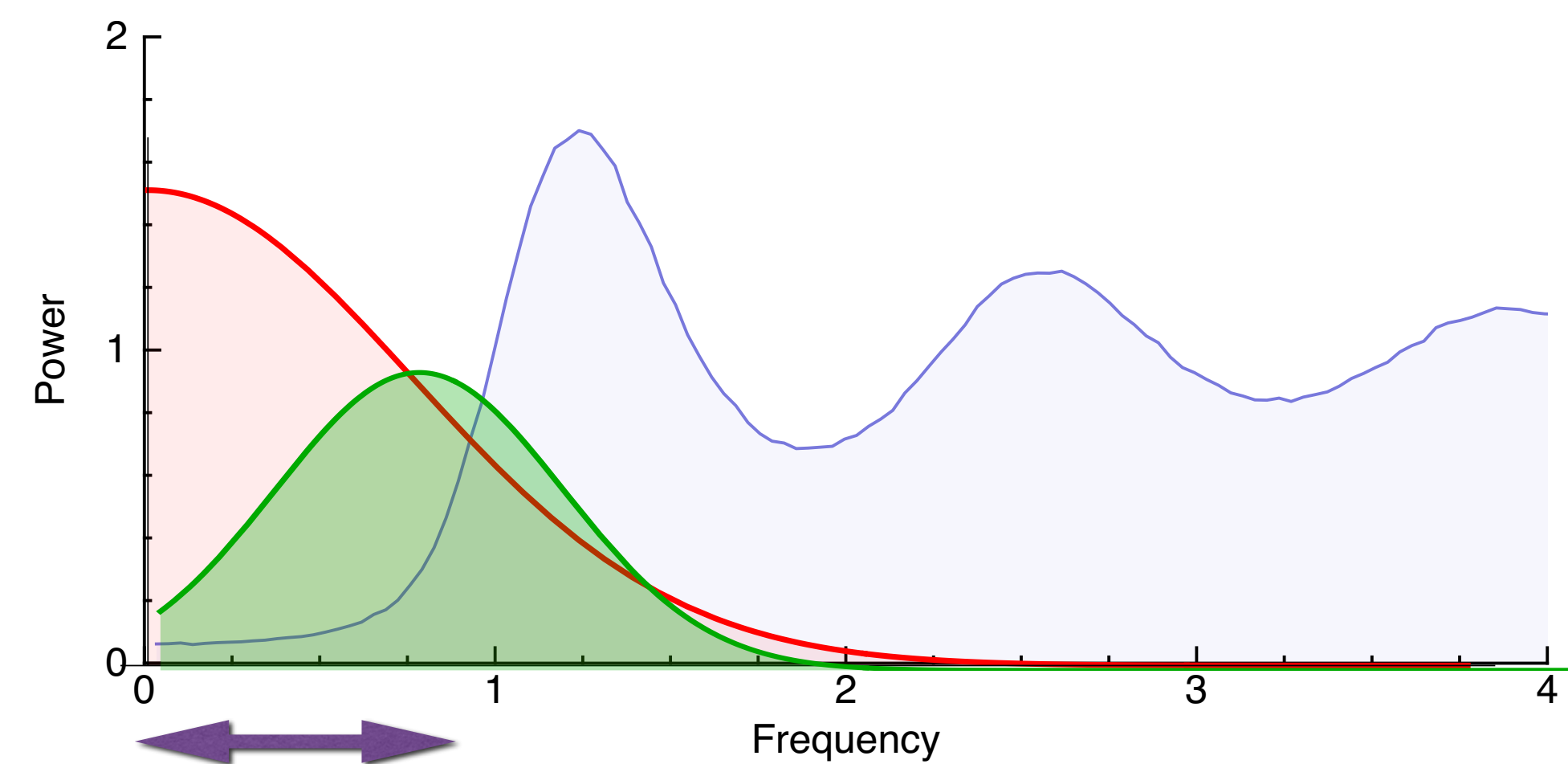
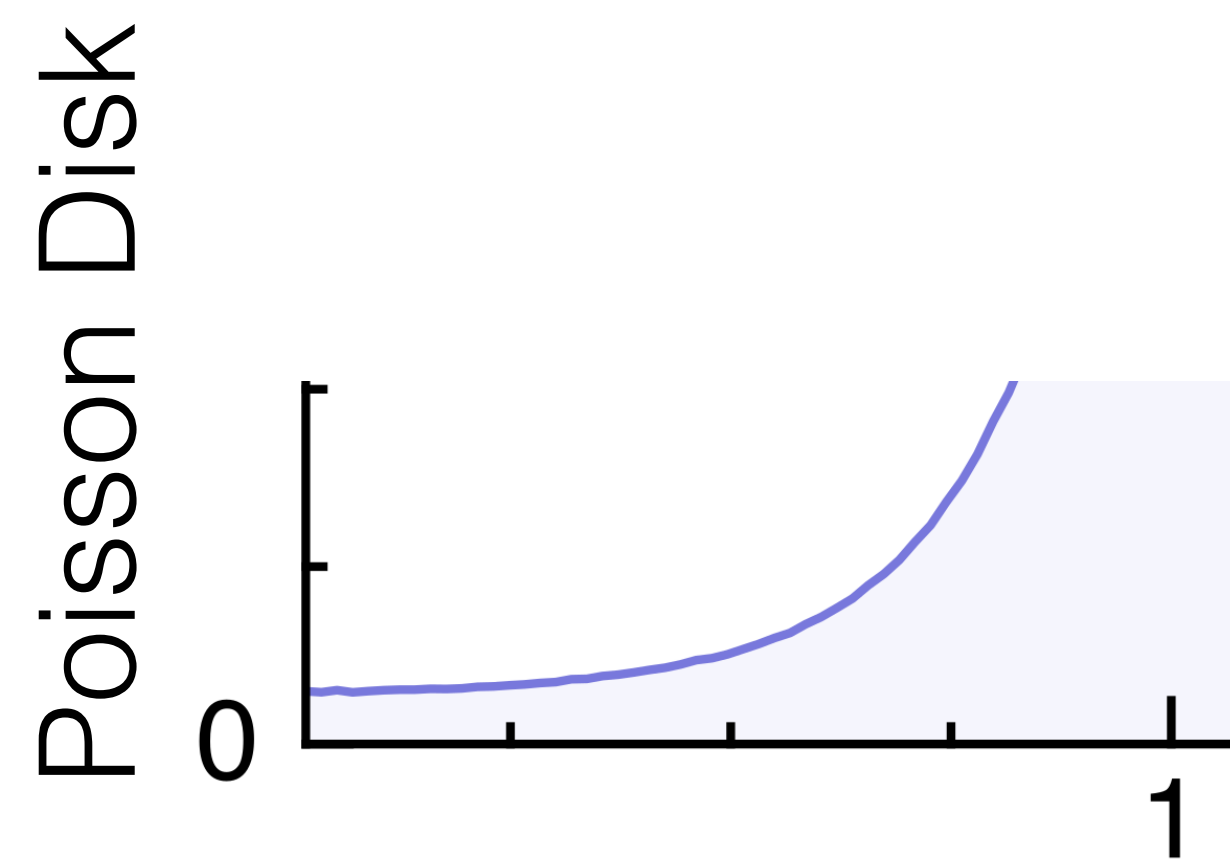
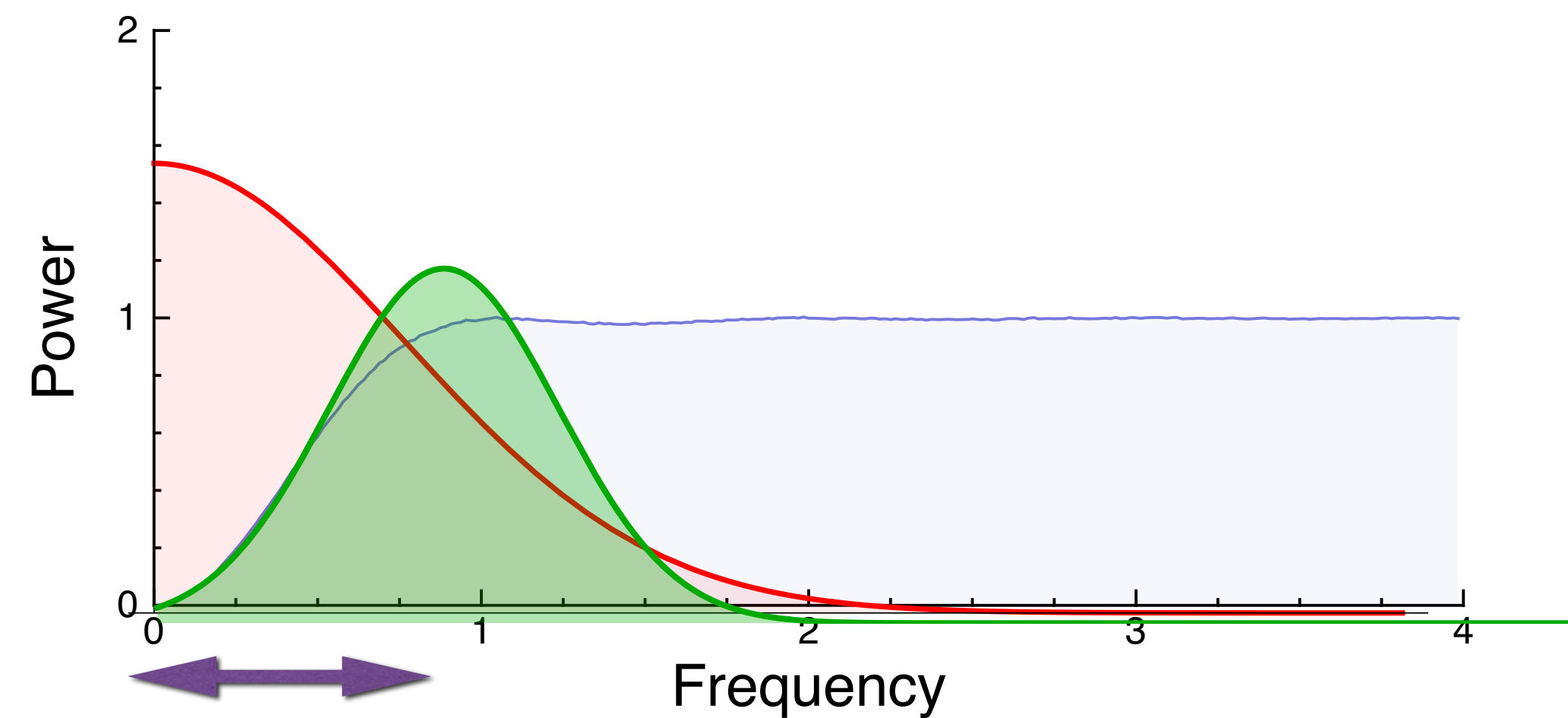
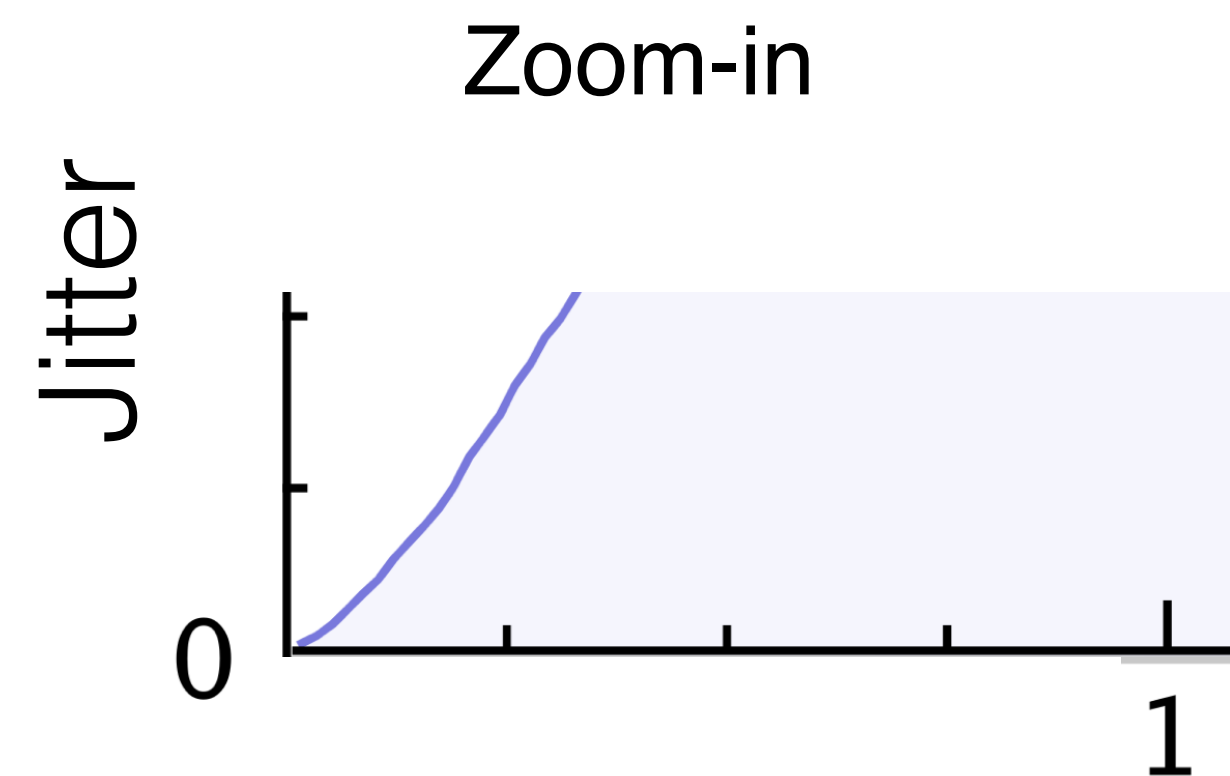
Low Frequency Region



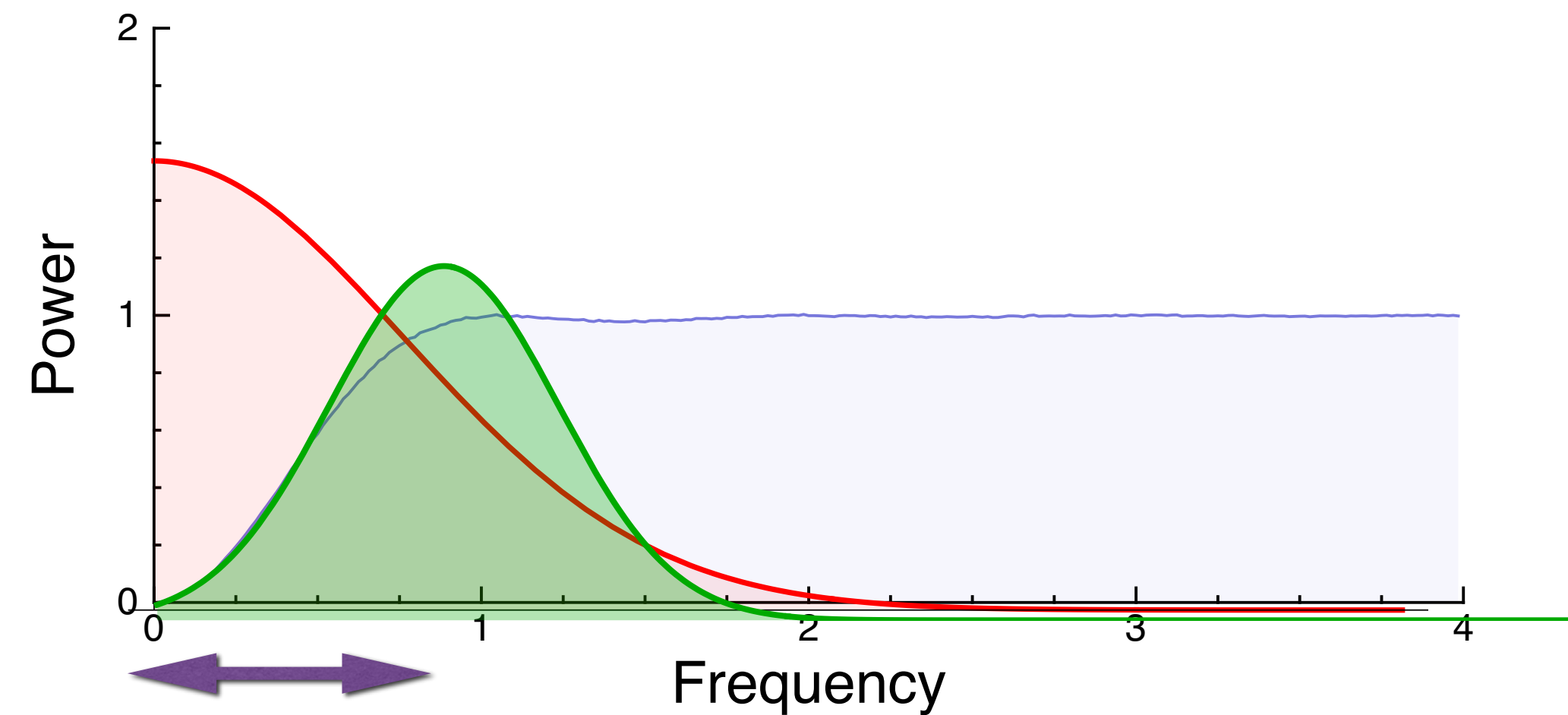
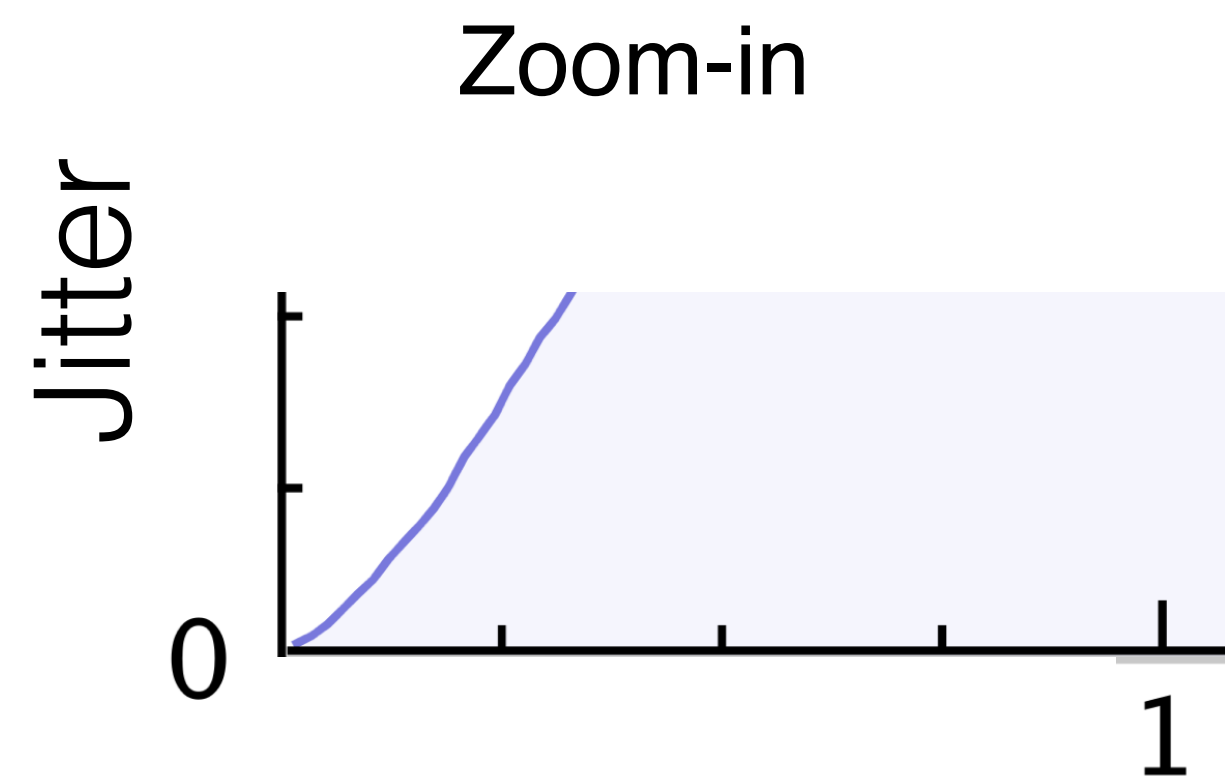
Variance for Low Sample Count



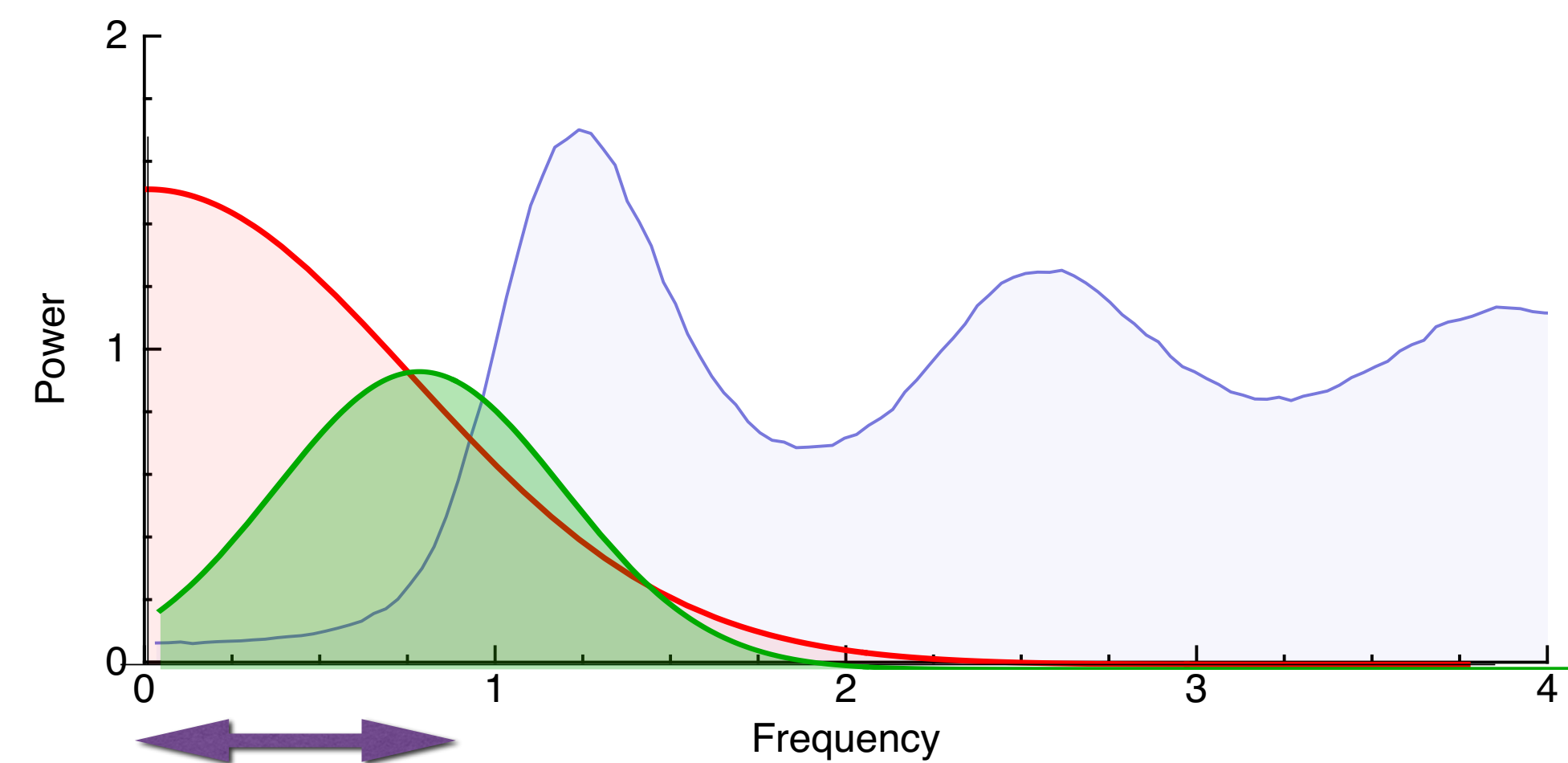
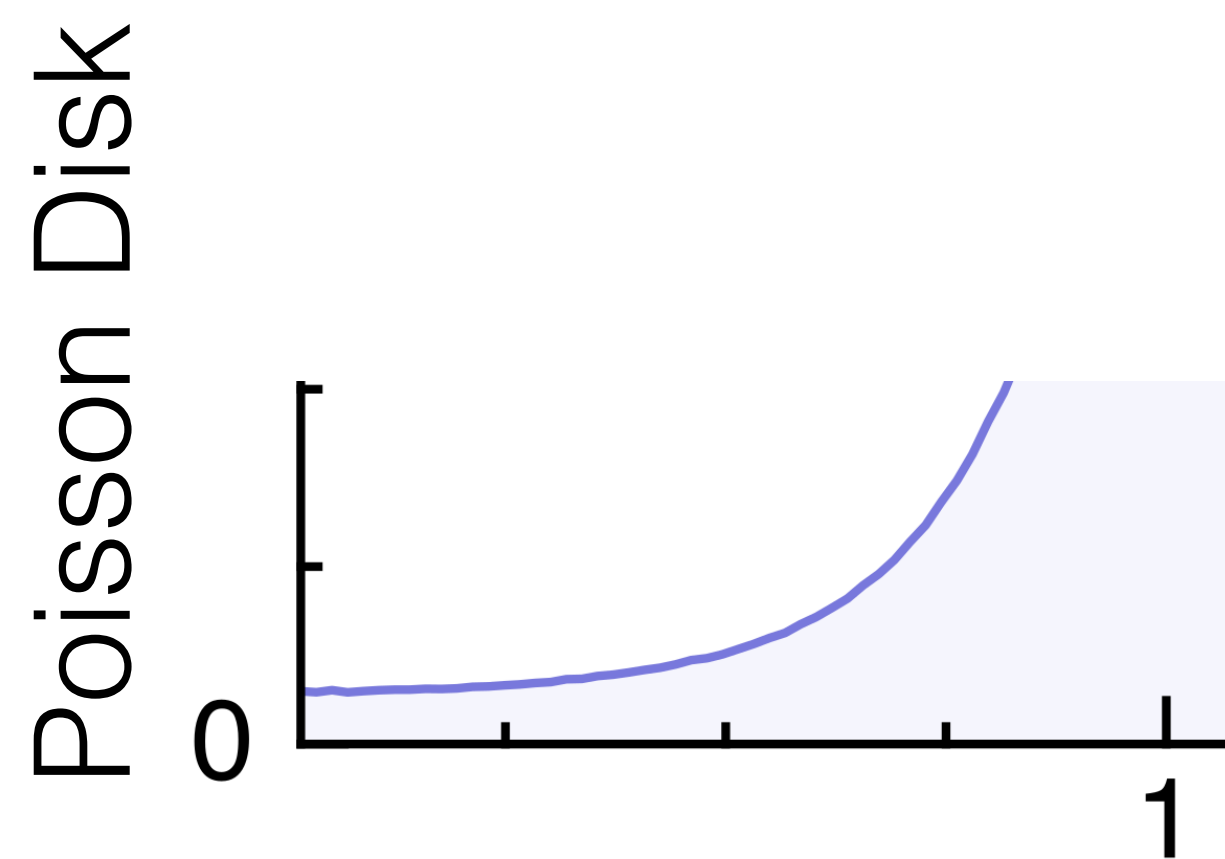
Variance for Low Sample Count



Variance for Increasing Sample Count



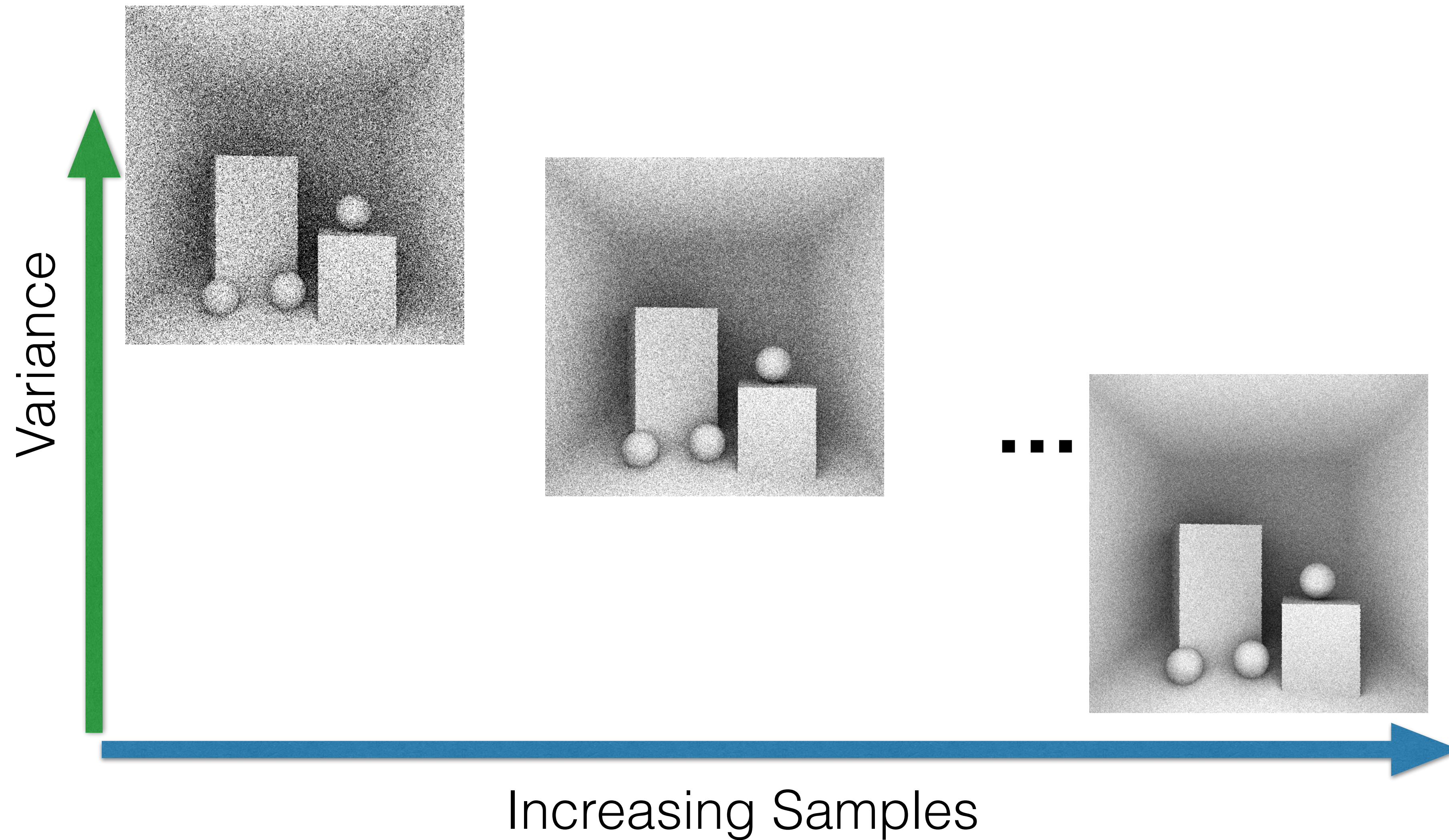
$$\mathcal{O}(N^{-2})$$



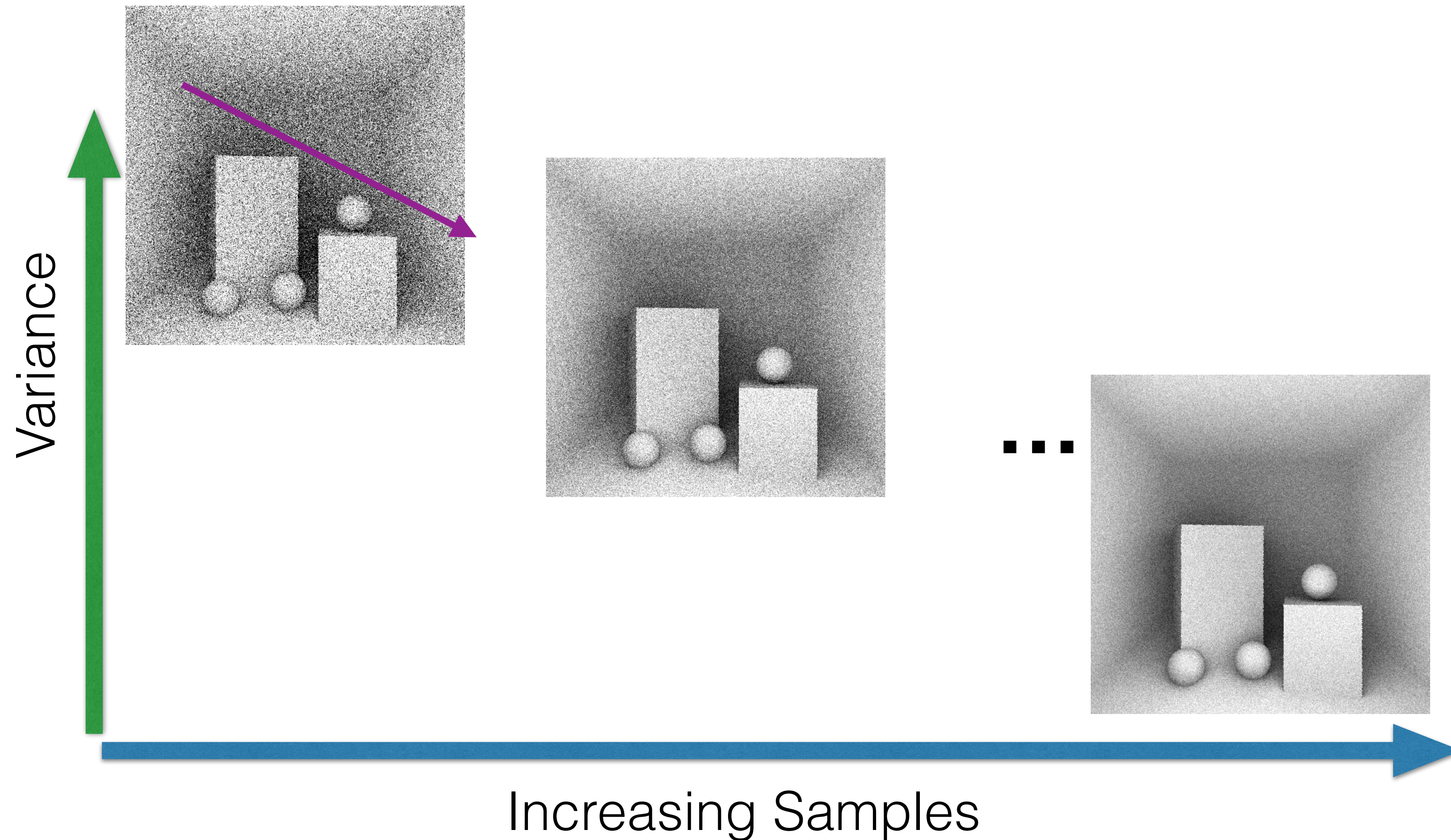
$$\mathcal{O}(N^{-1})$$

Experimental Verification

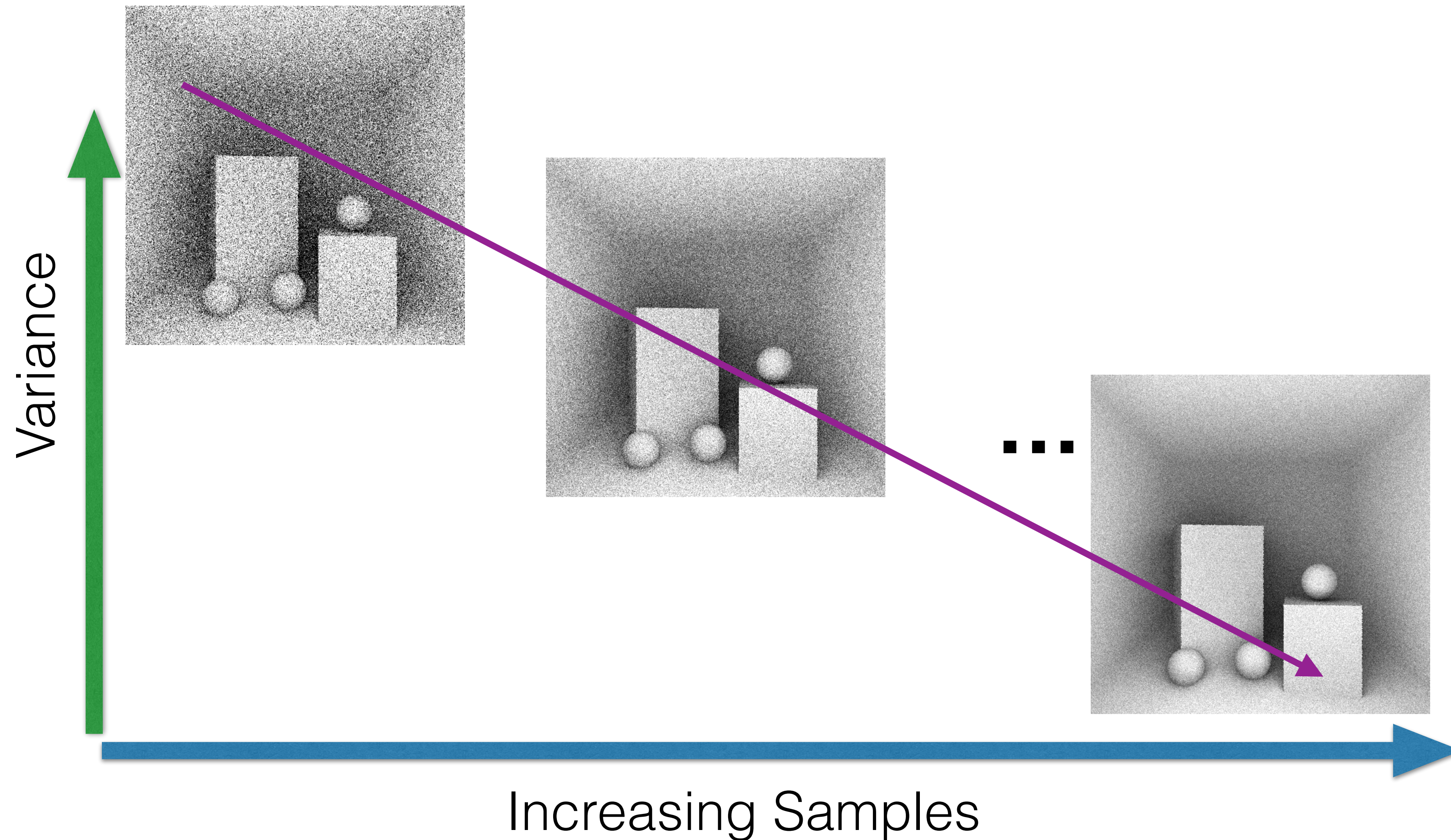
Convergence rate



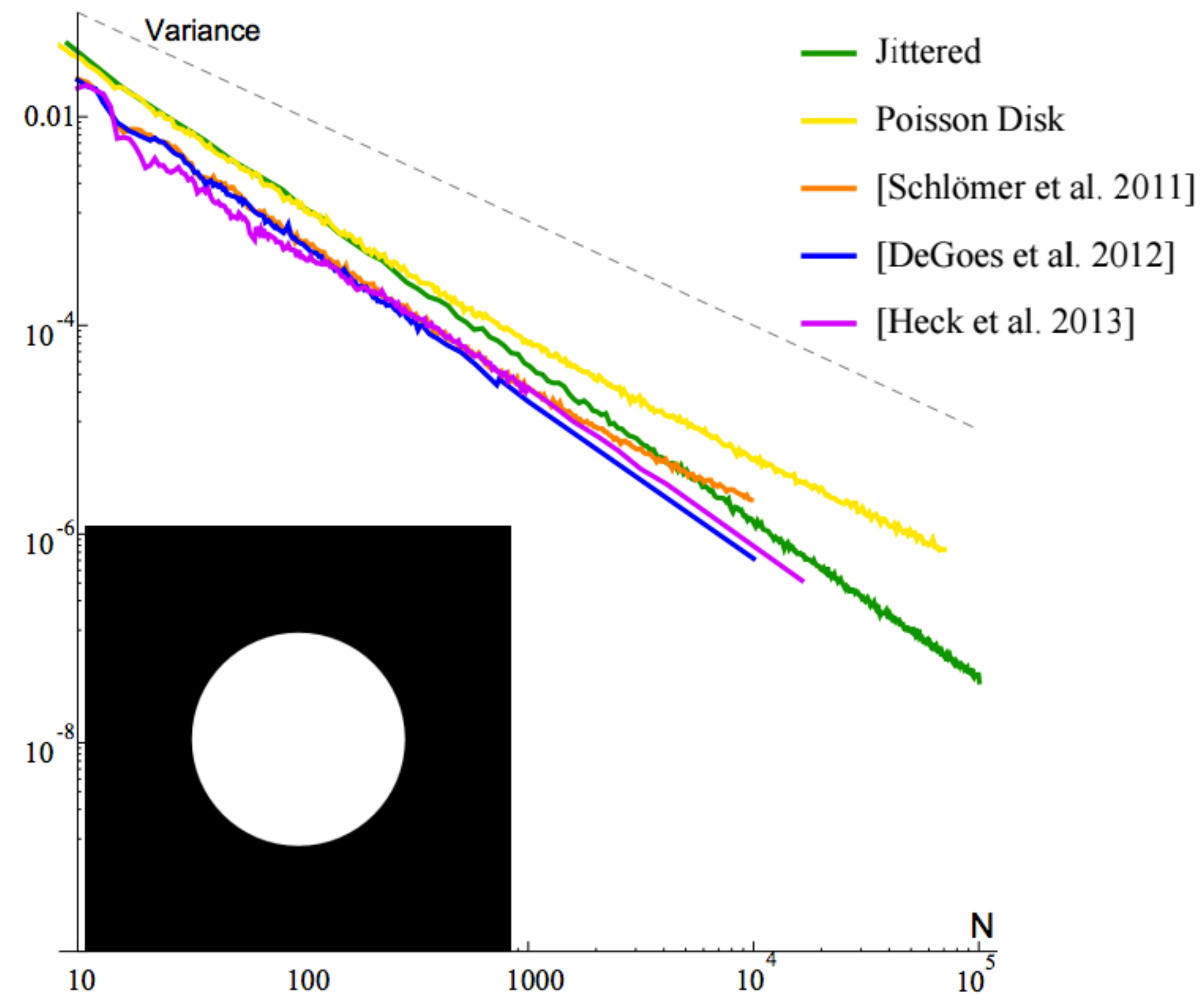
Convergence rate



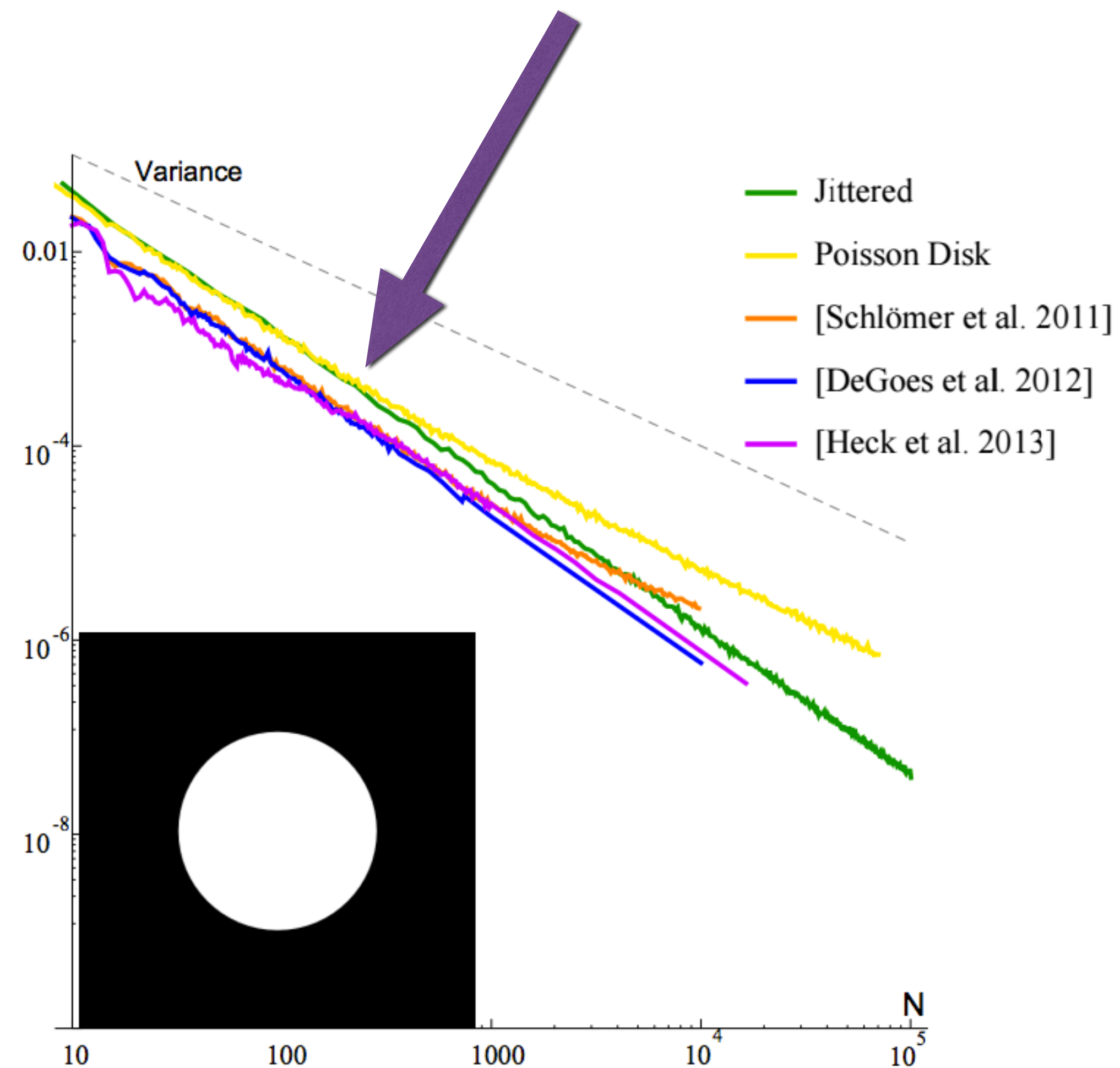
Convergence rate



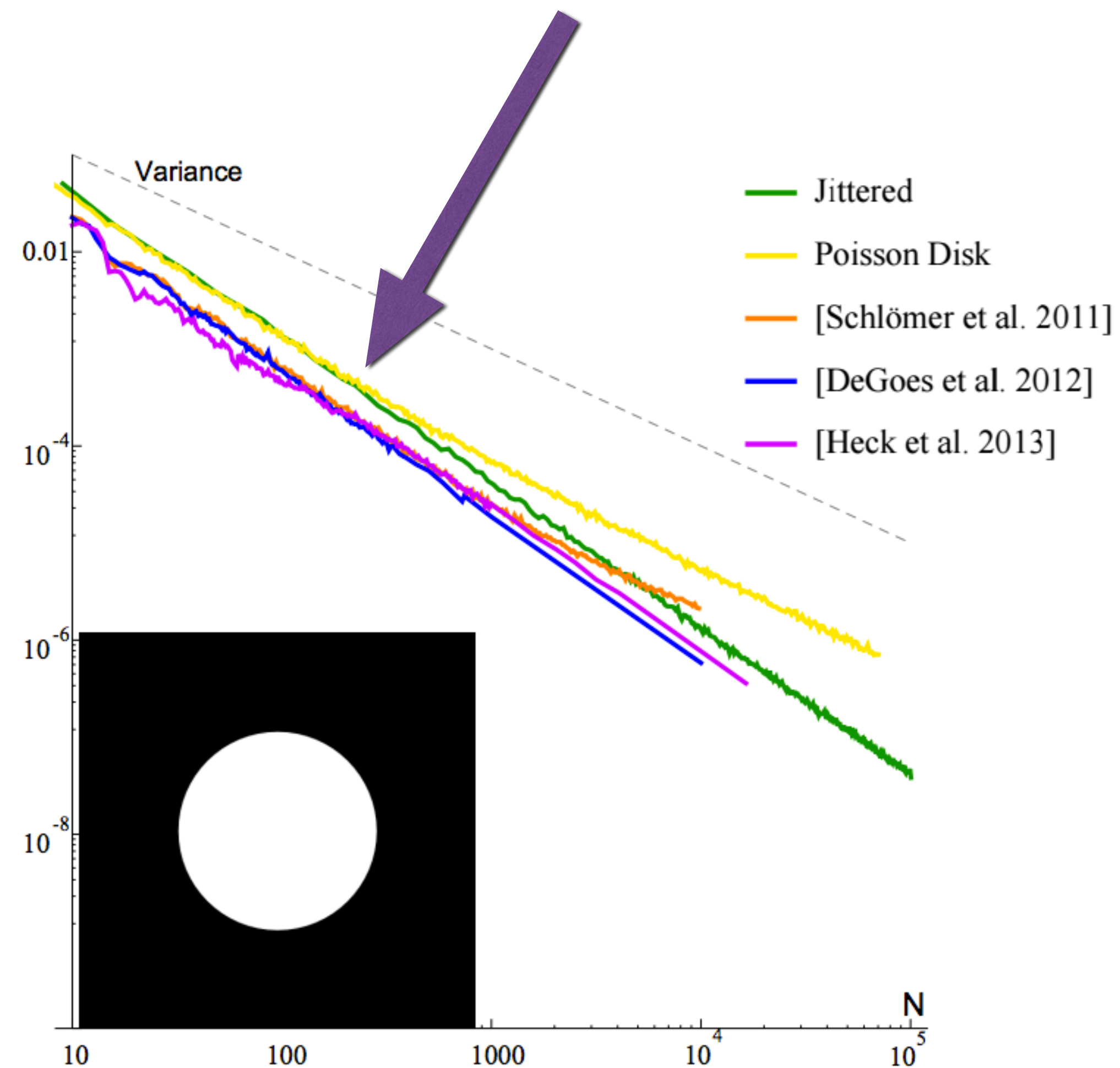
Disk Function as Worst Case



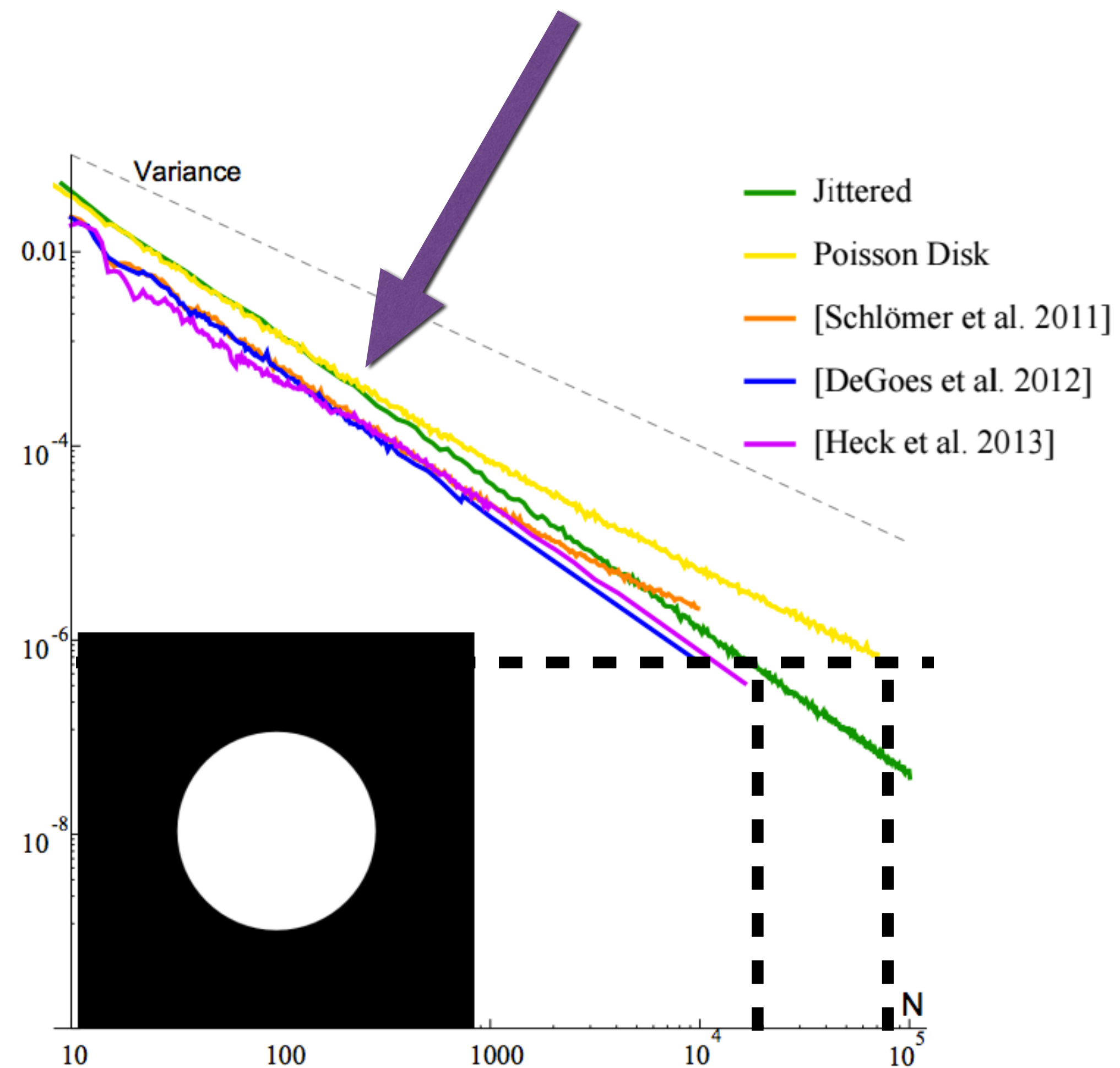
Disk Function as Worst Case



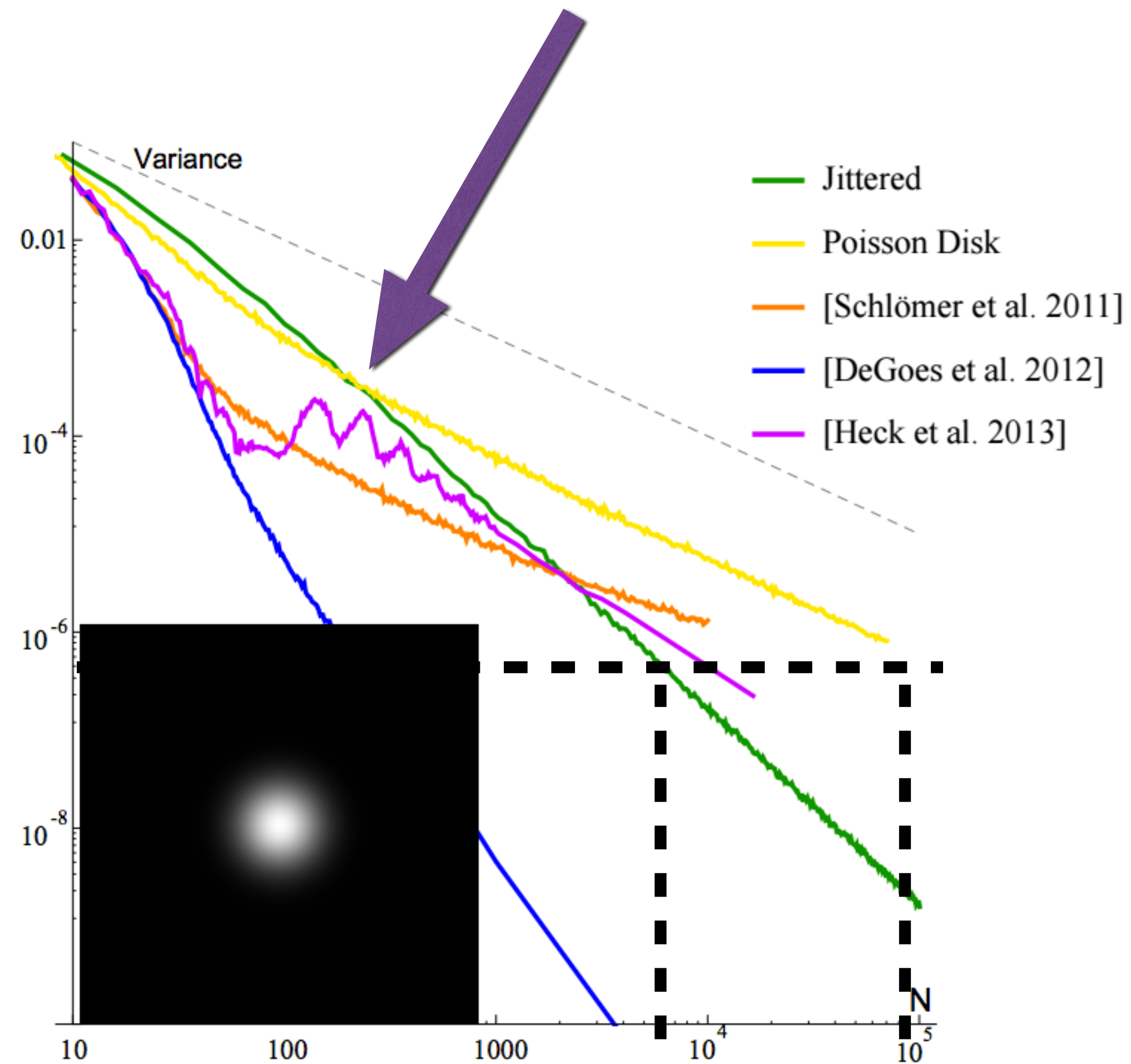
Disk Function as Worst Case



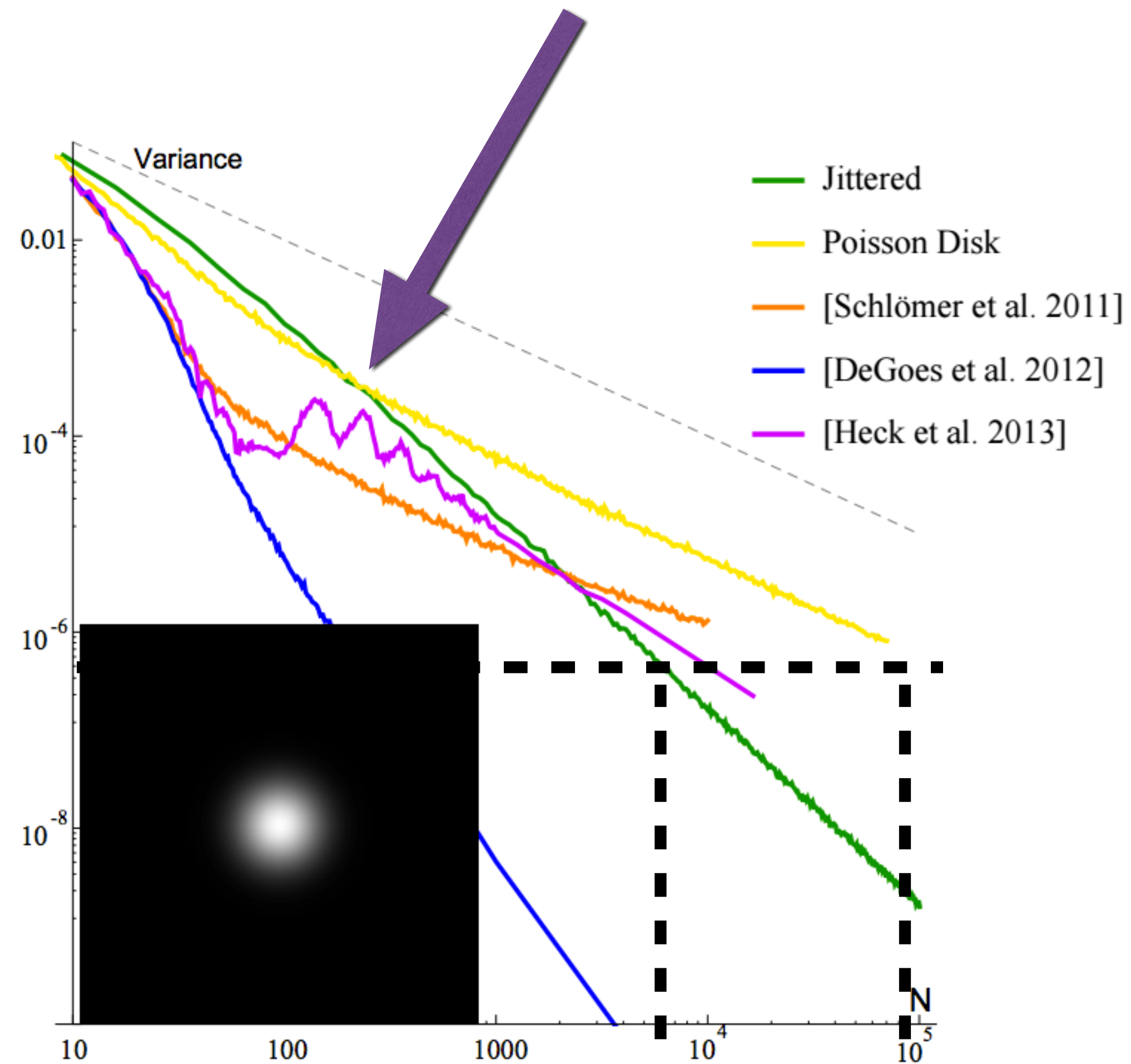
Disk Function as Worst Case



Gaussian as Best Case



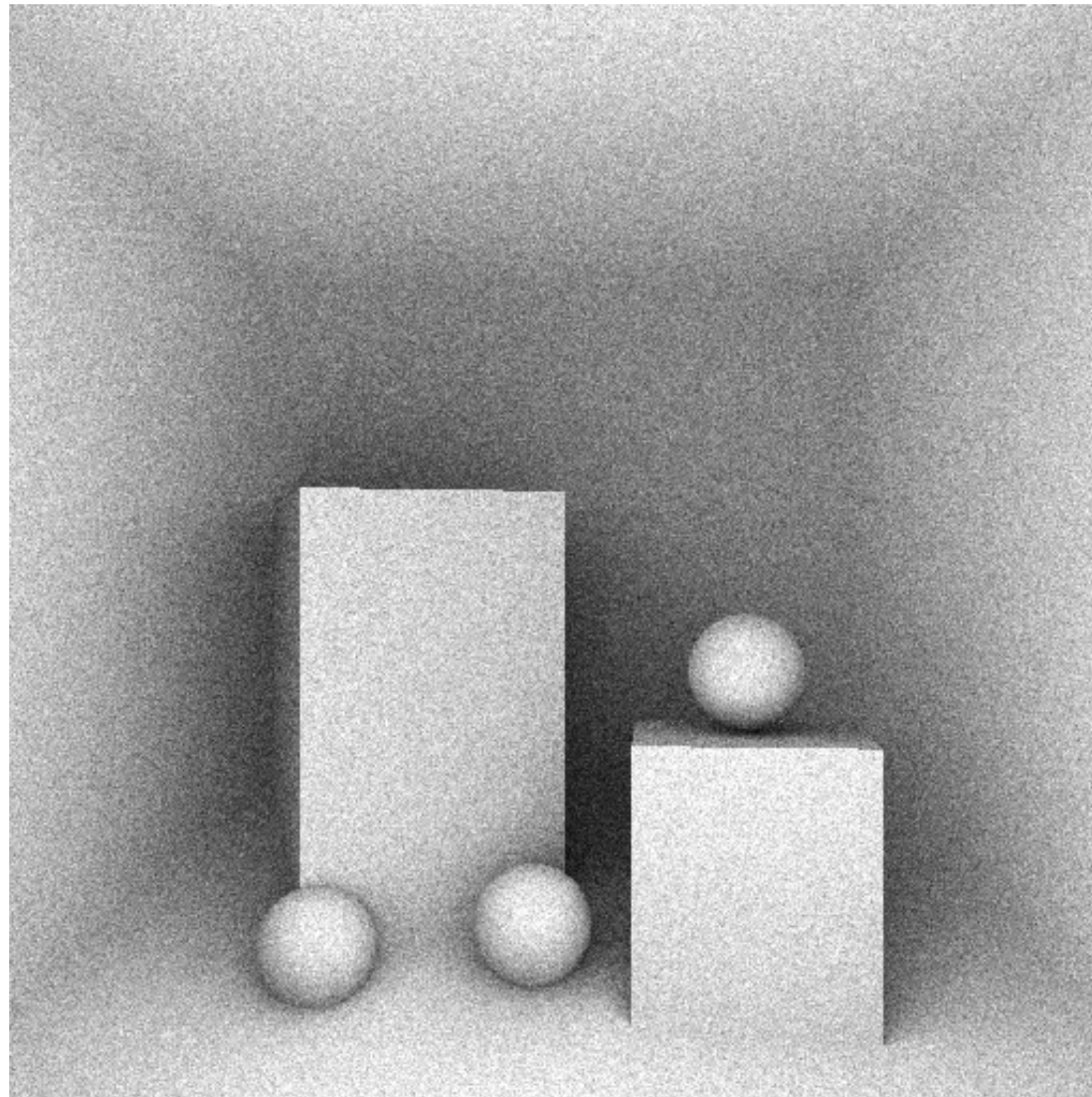
Gaussian as Best Case



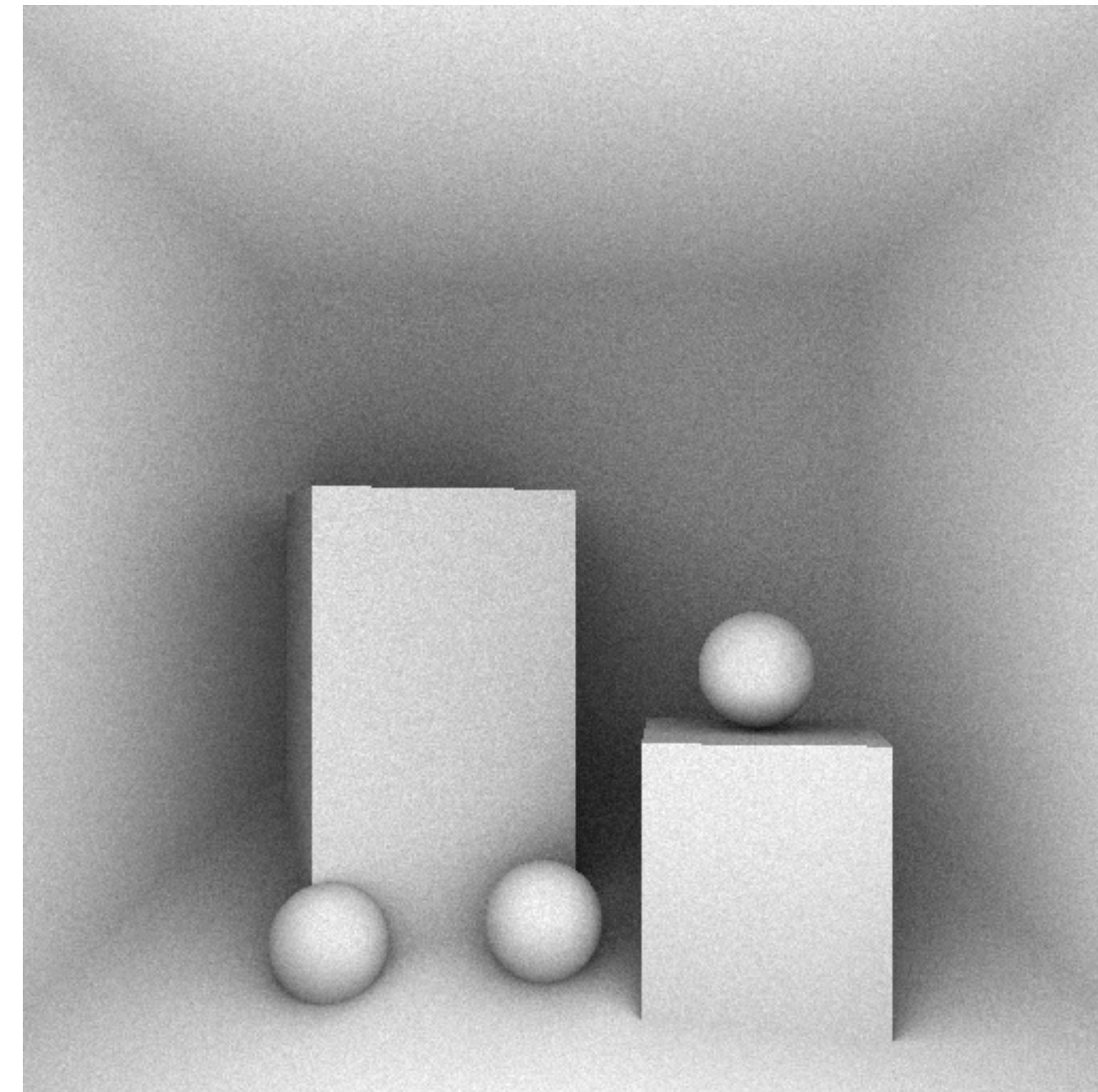
Ambient Occlusion Examples

Random vs Jittered

96 Secondary Rays



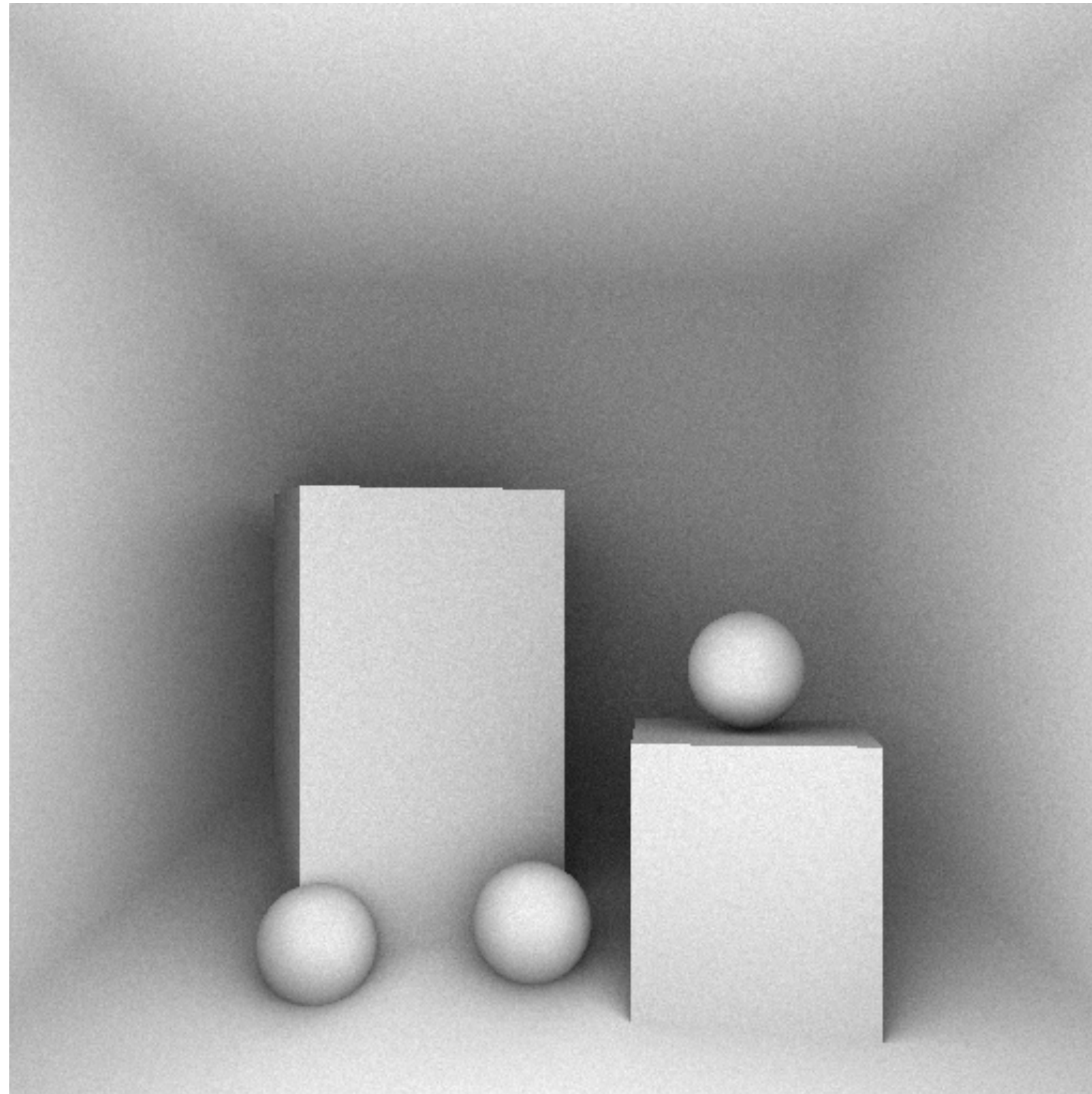
MSE: 4.74×10^{-3}



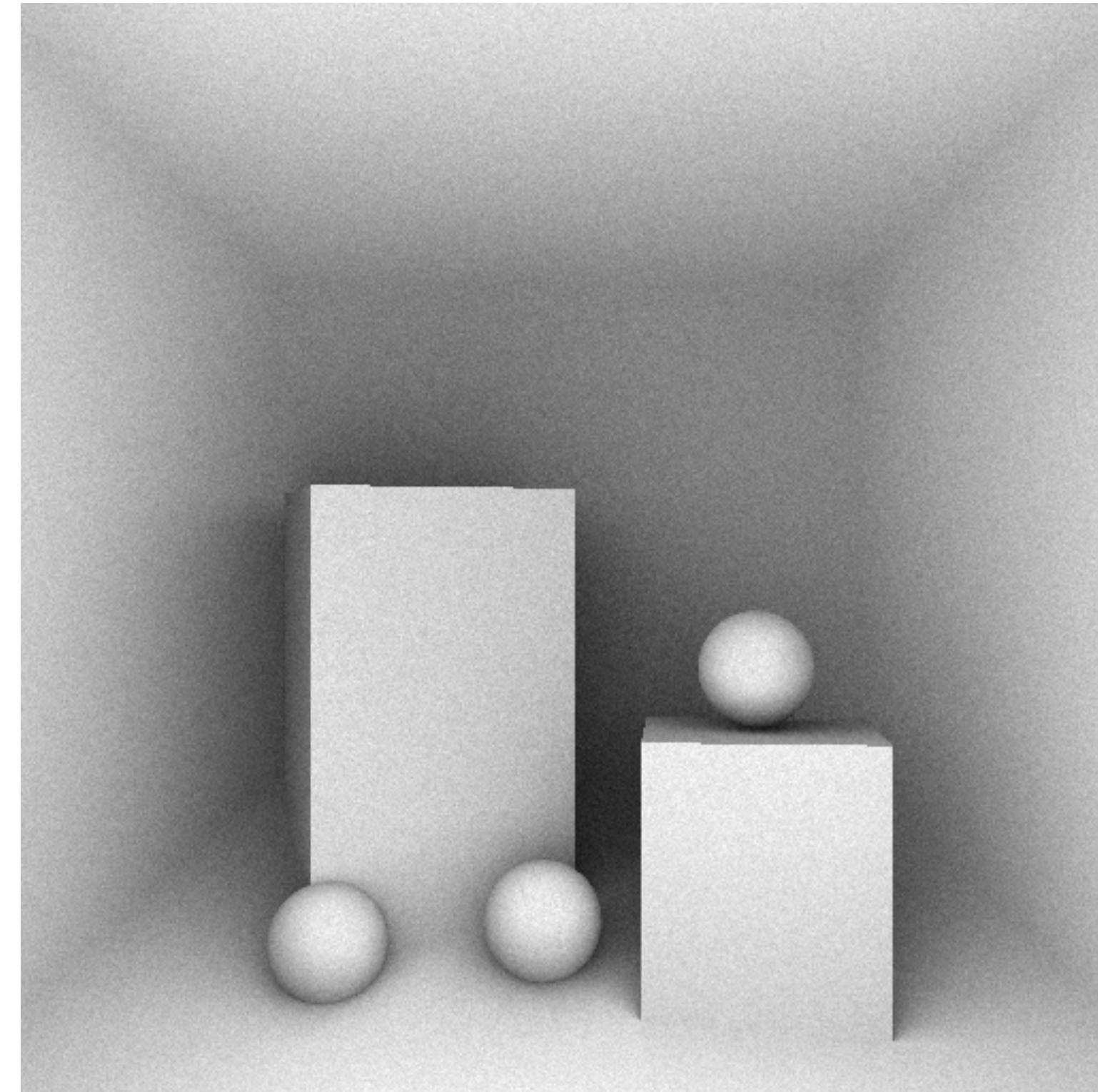
MSE: 8.56×10^{-4}

CCVT vs. Poisson Disk

96 Secondary Rays

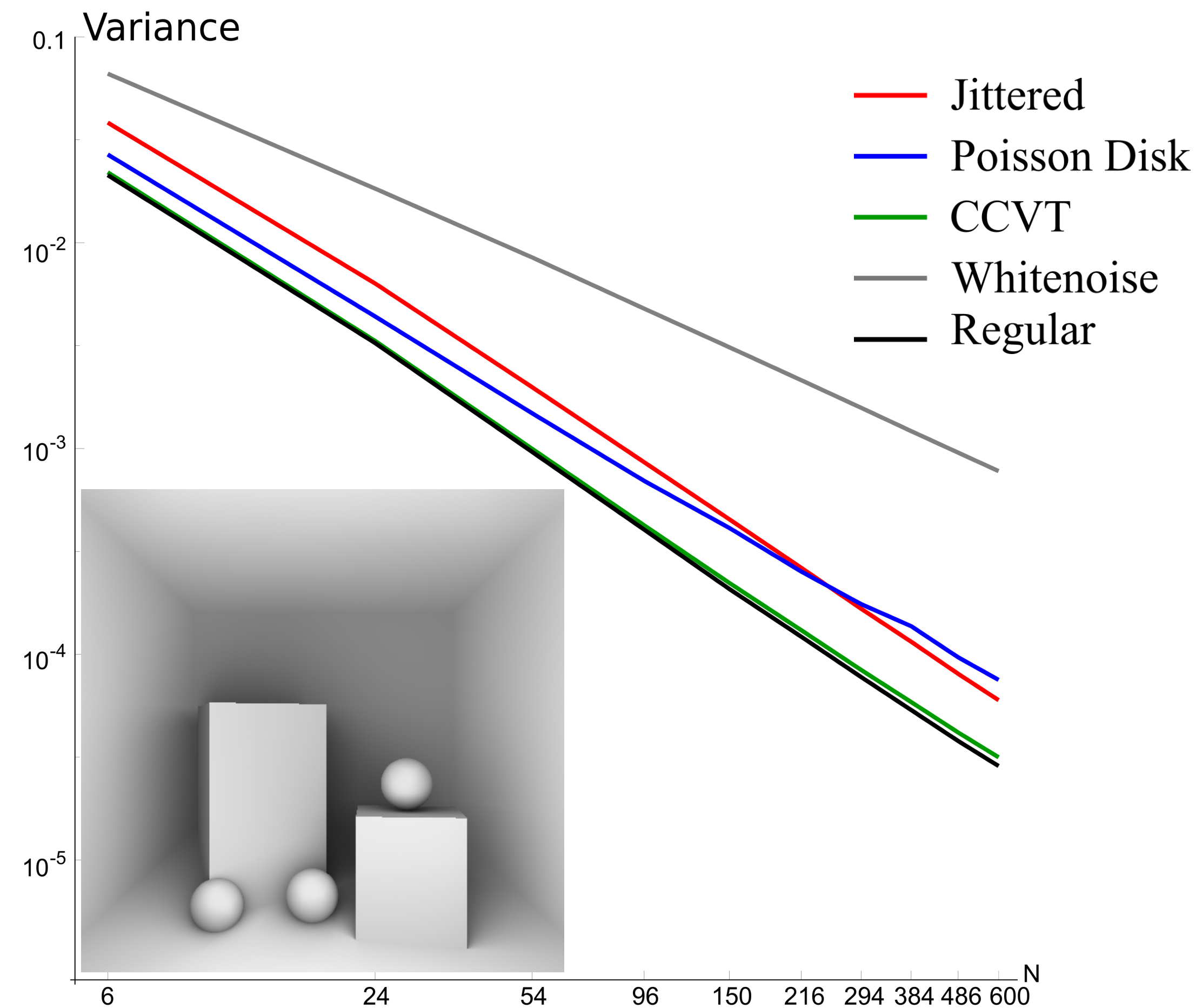


MSE: 4.24×10^{-4}

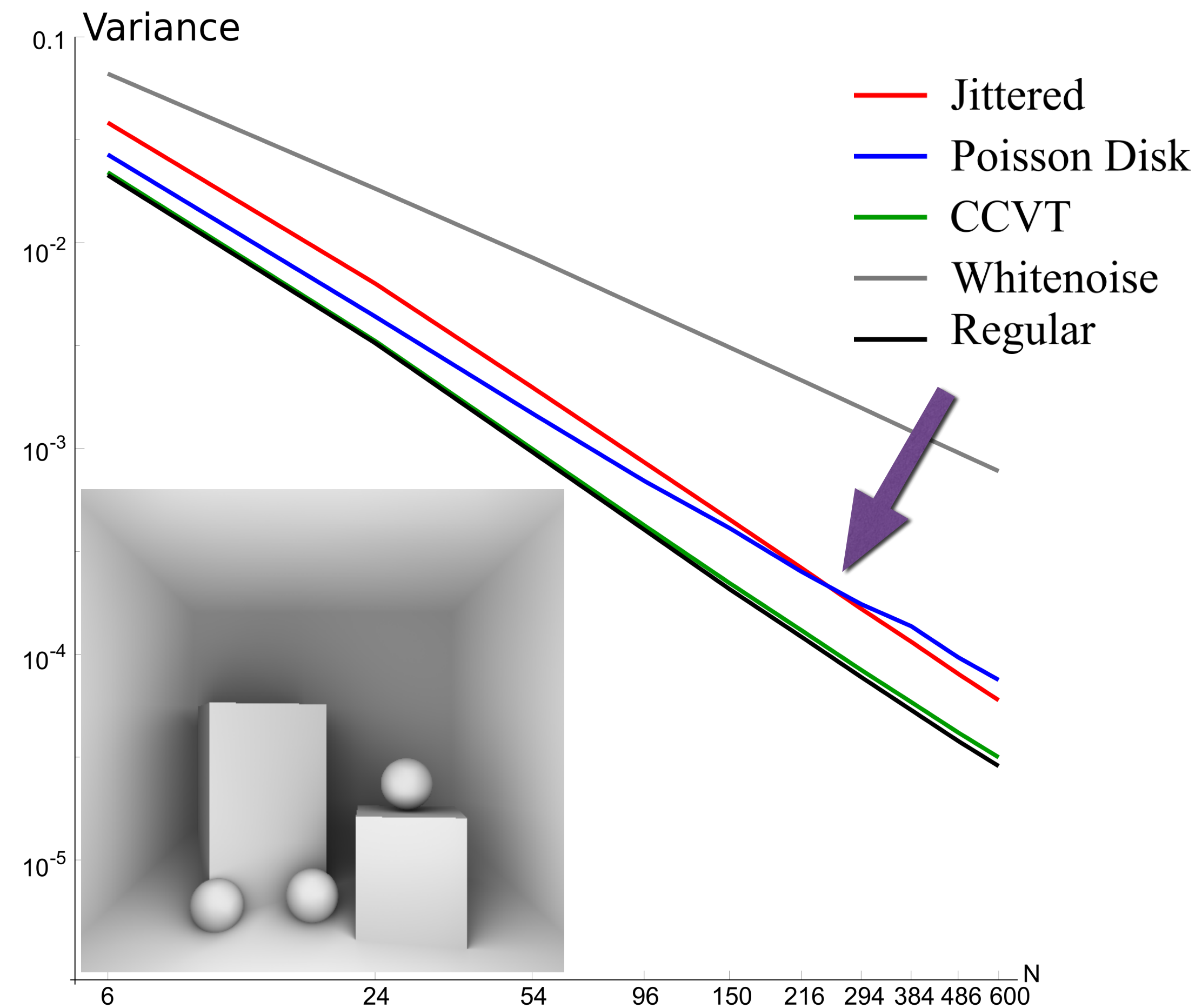


MSE: 6.95×10^{-4}

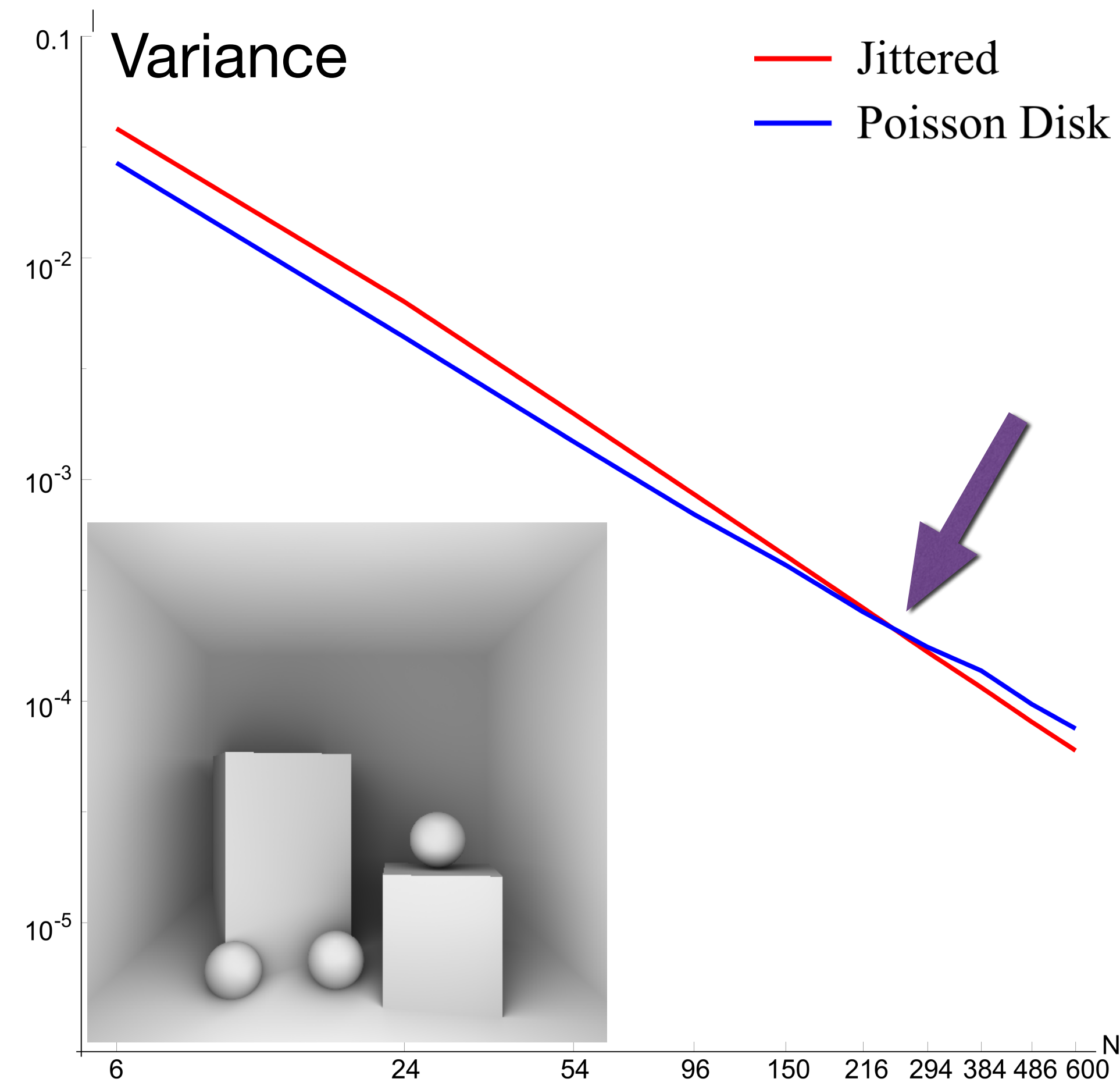
Convergence rates



Convergence rates



Jittered vs Poisson Disk



What are the benefits of this analysis ?

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- For offline rendering, analysis tells which samplers would converge faster.

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- For offline rendering, analysis tells which samplers would converge faster.
- For real time rendering, blue noise samples are more effective in reducing variance for a given number of samples

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Kartic Subr

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*Wojciech Jarosz

Render the Possibilities
SIGGRAPH2016



*First part of slides are from Wojciech Jarosz