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ADVANCED SAMPLING



Part of Siggraph 2016 Course

Fourier Analysis of Numerical Integration in Monte Carlo Rendering

Gurprit Singh *Wojciech Jarosz Kartic Subr

Render the Possibilities

*First part of slides from Wojciech Jarosz







 $I = \int_D f(x) \, \mathrm{d}x$







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 $I = \int_D f(x) \, \mathrm{d}x$







 $I = \int_D f(x) \, \mathrm{d}x$ $\approx \int f(x) \mathbf{S}(x) \, \mathrm{d}x$







$$I = \int_{D} f(x) \, dx$$
$$\approx \int_{D} f(x) \, \mathbf{S}(x) \, dx$$
$$\mathbf{S}(x) = \frac{1}{N} \sum_{k=1}^{N} \delta(x - \mathbf{x}_{k})$$







$$I = \int_{D} f(x) \, dx$$
$$\approx \int_{D} f(x) \, \mathbf{S}(x) \, dx$$
$$\mathbf{S}(x) = \frac{1}{N} \sum_{k=1}^{N} \delta(x - \mathbf{x}_{k})$$







$$I = \int_{D} f(x) \, dx$$
$$\approx \int_{D} f(x) \, \mathbf{S}(x) \, dx$$
$$\mathbf{S}(x) = \frac{1}{N} \sum_{k=1}^{N} \delta(x - \mathbf{x}_{k})$$

How to generate the locations x_k ?

k=1

 $\int \mathbf{V}$







for (int k = 0; k < num; k++)

- samples(k).x = randf();
- samples(k).y = randf();









for (int k = 0; k < num; k++)

- samples(k).x = randf();
- samples(k).y = randf();





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for (int k = 0; k < num; k++)

samples(k).x = randf();samples(k).y = randf();

Trivially extends to higher dimensions





for (int k = 0; k < num; k++)

samples(k).x = randf();
samples(k).y = randf();

Trivially extends to higher dimensions
 Trivially progressive and memory-less





for (int k = 0; k < num; k++)

samples(k).x = randf();
samples(k).y = randf();

Trivially extends to higher dimensions
 Trivially progressive and memory-less
 Big gaps





for (int k = 0; k < num; k++)

samples(k).x = randf();
samples(k).y = randf();

Trivially extends to higher dimensions
 Trivially progressive and memory-less
 Big gaps
 Clumping





Input Image





Power Spectrum



Image courtesy: Laurent Belcour





Input Image





Power Spectrum



Image courtesy: Laurent Belcour







Fourier transform: $\hat{f}(\omega) = \int_D f(x) e^{-2\pi i \omega x} dx$





Fourier transform: $\hat{f}(\vec{\omega}) = \int_D f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$







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Fourier transform: $\hat{f}(\vec{\omega}) = \int_{D} f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$

Sampling function: $\mathbf{\hat{S}}(\vec{\omega}) = \int_{D} \mathbf{S}(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$







Fourier transform: $\hat{f}(\vec{\omega}) = \int_{D} f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$ Sampling function: $\hat{\mathbf{S}}(\vec{\omega}) = \int_D \frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$







Fourier transform: $\hat{f}(\vec{\omega}) = \int_{D} f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$ Sampling function: $\hat{\mathbf{S}}(\vec{\omega}) = \int_D \frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$ $=\frac{1}{N}\sum_{k=0}^{N}e^{-2\pi i\left(\vec{\omega}\cdot\vec{x}_{k}\right)}$

















Many sample set realizations







Many sample set realizations







Samples







Samples





Radial mean





$$\left|\frac{1}{N}\sum_{k=1}^{N} e^{-2\pi i \left(\vec{\omega} \cdot \vec{x}_{k}\right)}\right|$$

for (uint i = 0; i < numX; i++) for (uint j = 0; j < numY; j++) samples(i,j).x = (i + 0.5)/numX;samples(i,j).y = (j + 0.5)/numY;







for (uint i = 0; i < numX; i++) for (uint j = 0; j < numY; j++) samples(i,j).x = (i + 0.5)/numX;samples(i,j).y = (j + 0.5)/numY;









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Extends to higher dimensions, but...





for (uint i = 0; i < numX; i++) for (uint j = 0; j < numY; j++) samples(i,j).x = (i + 0.5)/numX;samples(i,j).y = (j + 0.5)/numY;

Extends to higher dimensions, but... **X** Curse of dimensionality





for (uint i = 0; i < numX; i++) for (uint j = 0; j < numY; j++) samples(i,j).x = (i + 0.5)/numX;samples(i,j).y = (j + 0.5)/numY;

Extends to higher dimensions, but... **X** Curse of dimensionality **X** Aliasing





for (uint i = 0; i < numX; i++) for (uint j = 0; j < numY; j++) samples(i,j).x = (i + 0.5)/numX;samples(i,j).y = (j + 0.5)/numY;








```
for (uint i = 0; i < numX; i++)
     for (uint j = 0; j < numY; j++)
           samples(i,j).x = (i + randf())/numX;
           samples(i,j).y = (j + randf())/numY;
```







```
for (uint i = 0; i < numX; i++)
     for (uint j = 0; j < numY; j++)
           samples(i,j).x = (i + randf())/numX;
           samples(i,j).y = (j + randf())/numY;
```

Provably cannot increase variance







```
for (uint i = 0; i < numX; i++)
     for (uint j = 0; j < numY; j++)
           samples(i,j).x = (i + randf())/numX;
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```

Provably cannot increase variance Extends to higher dimensions, but...







```
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           samples(i,j).x = (i + randf())/numX;
           samples(i,j).y = (j + randf())/numY;
```

Provably cannot increase variance Extends to higher dimensions, but... **X** Curse of dimensionality







```
for (uint i = 0; i < numX; i++)
    for (uint j = 0; j < numY; j++)
    {
        samples(i,j).x = (i + randf())/numX;
        samples(i,j).y = (j + randf())/numY;
    }
}</pre>
```

Provably cannot increase variance

- Extends to higher dimensions, but...
- **X** Curse of dimensionality
- X Not progressive



ance s, but...









Independent Random Sampling





Monte Carlo (16 random samples)







Monte Carlo (16 jittered samples)







Stratifying in Higher Dimensions

Stratification requires O(N^d) samples - e.g. pixel (2D) + lens (2D) + time (1D) = 5D







Stratifying in Higher Dimensions

- Stratification requires O(N^d) samples
- e.g. pixel(2D) + lens(2D) + time(1D) = 5D
 - splitting 2 times in $5D = 2^5 = 32$ samples
 - splitting 3 times in $5D = 3^5 = 243$ samples!







Stratifying in Higher Dimensions

- Stratification requires O(N^d) samples
- e.g. pixel(2D) + lens(2D) + time(1D) = 5D
 - splitting 2 times in $5D = 2^5 = 32$ samples
 - splitting 3 times in $5D = 3^5 = 243$ samples!
- Inconvenient for large d
- cannot select sample count with fine granularity















Compute stratified samples in sub-dimensions







Compute stratified samples in sub-dimensions

- 2D jittered (x,y) for pixel







; ₁ ,y ₁	<i>x</i> ₂ , <i>y</i> ₂
; ₃ ,y ₃	<i>x</i> ₄ , <i>y</i> ₄





Compute stratified samples in sub-dimensions

- 2D jittered (x,y) for pixel
- 2D jittered (u,v) for lens x_1





; ₁ ,y ₁	<i>x</i> ₂ , <i>y</i> ₂
3,y ₃	<i>x</i> ₄ , <i>y</i> ₄

<i>u</i> ₁ , <i>v</i> ₁	u
<i>u</i> ₃ , <i>v</i> ₃	и







Compute stratified samples in sub-dimensions

- 2D jittered (x,y) for pixel
- 2D jittered (u,v) for lens
 1D jittered (t) for time





y ₁ ,y ₁	<i>x</i> ₂ , <i>y</i> ₂
3,y ₃	<i>x</i> ₄ , <i>y</i> ₄









Compute stratified samples in sub-dimensions

- 2D jittered (x,y) for pixel
- 2D jittered (u,v) for lens
- 1D jittered (t) for time
- combine dimensions in random order









Depth of Field (4D)

Reference



Realistic Image Synthesis SS2020 Image source: PBRTe2 [Pharr & Humphreys 2010]

Random Sampling

Uncorrelated Jitter





Stratify samples in each dimension separately







Stratify samples in each dimension separately

- for 5D: 5 separate 1D jittered point sets



ed point sets X X X1 X2 X3 X4 Y Y Y1 Y2 Y3 Y4 U U U1 U2 U3 U4 V

v2

v1

t				
	t1	t2	t3	t4

v3

v4



Stratify samples in each dimension separately

- for 5D: 5 separate 1D jittered point sets
- combine dimensions in random order



ed point sets X X X1 X2 X3 X4 Y Y Y1 Y2 Y3 Y4 U U U1 U2 U3 U4 V

v2

v1

t				
	t1	t2	t3	t4

v3

v4



Stratify samples in each dimension separately

- for 5D: 5 separate 1D jittered point sets
- combine dimensions in random order

Shuffle order





N-Rooks = 2D Latin Hypercube [Shirley 9

Stratify samples in each dimension separately

- for **2D**: **2** separate 1D jittered point sets
- combine dimensions in random order



Х				
	x1	x2	x3	x4

V				
J	y4	y2	y1	уЗ



	I	

Latin Hypercube (N-Rooks) Sampling [Shirley 91]





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Image source: Michael Maggs, CC BY-SATA.



// initialize the diagonal for (uint d = 0; d < numDimensions; d++) for (uint i = 0; i < numS; i++) samples(d,i) = (i + randf())/numS;

// shuffle each dimension independently for (uint d = 0; d < numDimensions; d++) shuffle(samples(d,:));









// initialize the diagonal for (uint d = 0; d < numDimensions; d++) for (uint i = 0; i < numS; i++) samples(d,i) = (i + randf())/numS;

// shuffle each dimension independently for (uint d = 0; d < numDimensions; d++) shuffle(samples(d,:));





Initialize





// initialize the diagonal for (uint d = 0; d < numDimensions; d++) for (uint i = 0; i < numS; i++) samples(d,i) = (i + randf())/numS;

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// shuffle each dimension independently for (unit d = 0; d < numDimensions; d++) shuffle(samples(d,:));





Shuffle rows

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Shuffle rows





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// shuffle each dimension independently for (uint d = 0; d < numDimensions; (d++)) shuffle(samples(d,:));





Shuffle columns





// initialize the diagonal for (uint d = 0; d < numDimensions; d++) for (uint i = 0; i < numS; i++) samples(d,i) = (i + randf())/numS;

// shuffle each dimension independently for (uint d = 0; d < numDimensions; (d++)) shuffle(samples(d,:));





Shuffle columns

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// initialize the diagonal for (uint d = 0; d < numDimensions; d++) for (uint i = 0; i < numS; i++) samples(d,i) = (i + randf())/numS;

// shuffle each dimension independently for (uint d = 0; d < numDimensions; d++) shuffle(samples(d,:));










































Kenneth Chiu, Peter Shirley, and Changyaw Wang. "Multi-jittered sampling." In Graphics Gems IV, pp. 370-374. Academic Press, May 1994.

combine N-Rooks and Jittered stratification constraints













```
// initialize
float cellSize = 1.0 / (resX*resY);
for (uint i = 0; i < resX; i++)
      for (uint i = 0; i < resY; i++)
              samples(i,j).x = i/resX + (j+randf()) / (resX*resY);
              samples(i,j).y = j/resY + (i+randf()) / (resX*resY);
```

// shuffle x coordinates within each column of cells for (uint i = 0; i < resX; i++) for (uint $j = resY-1; j \ge 1; j--$) swap(samples(i, j).x, samples(i, randi(0, j)).x);

// shuffle y coordinates within each row of cells for (unsigned j = 0; j < resY; j++) for (unsigned $i = resX-1; i \ge 1; i--$) swap(samples(i, j).y, samples(randi(0, i), j).y);











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Initialize











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Shuffle x-coords













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Shuffle y-coords













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Shuffle y-coords









Shuffle y-coords













































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Samples



















Poisson-Disk/Blue-Noise Sampling

- Enforce a minimum distance between points Poisson-Disk Sampling:
- Mark A. Z. Dippé and Erling Henry Wold. "Antialiasing through stochastic sampling." ACM SIGGRAPH, 1985.
- Robert L. Cook. "Stochastic sampling in computer graphics." ACM Transactions on Graphics, 1986.
- Ares Lagae and Philip Dutré. "A comparison of methods for generating Poisson disk distributions." Computer Graphics Forum, 2008.


















































Random Dart Throwing









Poisson Disk Sampling

Samples

Expected power spectrum



Radial mean

Blue-Noise Sampling (Relaxation-based)



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Blue-Noise Sampling (Relaxation-based)

1. Initialize sample positions (e.g. random)





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Blue-Noise Sampling (Relaxation-based)

- 1. Initialize sample positions (e.g. random)
- 2. Use an iterative relaxation to move samples away from each other.





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Samples









Poisson Disk Sampling

Samples

Expected power spectrum



Radial mean

Low-Discrepancy Sampling

Deterministic sets of points specially crafted to be evenly distributed (have low discrepancy).



- Entire field of study called Quasi-Monte Carlo (QMC)





Radical Inverse Φ_b in base 2

Subsequent points "fall into biggest holes"











Radical Inverse Φ_b in base 2

Subsequent points "fall into biggest holes"



k	Base 2	Φ_b
1	1	.1 = 1/2





Radical Inverse Φ_b in base

Subsequent points "fall inte biggest holes"



2	k	Base 2	Φ_b
	1	1	.1 = 1/2
.U	2	10	.01 = 1/4





Radical Inverse Φ_b in base 2

Subsequent points "fall into biggest holes"



k	Base 2	Φ_b
1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4



Radical Inverse Φ_b in base 2

Subsequent points "fall into biggest holes"



k	Base 2	Φ_b
1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4
4	100	.001 = 1/8





Radical Inverse Φ_b in base 2

Subsequent points "fall into biggest holes"



k	Base 2	Φ_b
1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4
4	100	.001 = 1/8
5	101	.101 = 5/8



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Radical Inverse Φ_b in base 2

Subsequent points "fall into biggest holes"



k	Base 2	Φ_b
1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4
4	100	.001 = 1/8
5	101	.101 = 5/8
6	110	.011 = 3/8



3		
3		
3		



Radical Inverse Φ_b in base 2

Subsequent points "fall into biggest holes"



k	Base 2	Φ_b
1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4
4	100	.001 = 1/8
5	101	.101 = 5/8
6	110	.011 = 3/8
7	111	.111 = 7/8

3		
3		
3		
3		



Radical Inverse Φ_b in base 2

Subsequent points "fall into biggest holes"



k	Base 2	Φ_b
1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4
4	100	.001 = 1/8
5	101	.101 = 5/8
6	110	.011 = 3/8
7	111	.111 = 7/8
•••		

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3		
3		
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3		

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- Halton: Radical inverse with different base for each dimension:
 - $\vec{x}_k = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$







- Halton: Radical inverse with different base for each dimension:
 - $\vec{x}_k = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$
- The bases should all be relatively prime.









- Halton: Radical inverse with different base for each dimension:
 - $\vec{x}_k = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$
- The bases should all be relatively prime.
- Incremental/progressive generation of samples









- Halton: Radical inverse with different base for each dimension: $\vec{x}_k = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$
- The bases should all be relatively prime.
- Incremental/progressive generation of samples
- **Hammersley**: Same as Halton, but first dimension is k/N: $\vec{x}_k = (k/N, \Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$









- Halton: Radical inverse with different base for each dimension: $\vec{x}_k = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$
- The bases should all be relatively prime.
- Incremental/progressive generation of samples
- **Hammersley**: Same as Halton, but first dimension is k/N: $\vec{x}_k = (k/N, \Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_m}(k))$ - Not incremental, need to know sample count, N, in advance















1 sample in each "elementary interval"









1 sample in each "elementary interval"











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Monte Carlo (16 random samples)







Monte Carlo (16 jittered samples)







Scrambled Low-Discrepancy Sampling







More info on QMC in Rendering

S. Premoze, A. Keller, and M. Raab. In SIGGRAPH 2012 courses.



- Advanced (Quasi-) Monte Carlo Methods for Image Synthesis.







How can we predict error from these?









Part 2: Formal Treatment of MSE, Bias and Variance







Frequency





Convergence rate for Random Samples



Variance

Increasing Samples











Convergence rate for Random Samples







Increasing Samples
















Increasing Samples

















Increasing Samples















Increasing Samples













Increasing Samples









Increasing Samples







Convergence rate for Jittered Samples



Increasing Samples







Convergence rate for Jittered Samples



Increasing Samples









Increasing Samples









Increasing Samples









Increasing Samples











Increasing Samples







Samples and function in Fourier Domain

Spatial Domain



Fourier Domain



Samples and function in Fourier Domain

Spatial Domain



Fourier Domain





Samples and function in Fourier Domain

Spatial Domain









Samples and function in Fourier Domain

Spatial Domain









Samples and function in Fourier Domain

Spatial Domain





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Samples and function in Fourier Domain

Spatial Domain





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Convolution





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Source: vdumoulin-github



Convolution





Realistic Image Synthesis SS2020

Source: vdumoulin-github





 $f(x) \mathbf{S}(x)$



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 $f(x) \mathbf{S}(x)$



Realistic Image Synthesis SS2020

Fredo Durand [2011]







 $f(x) \mathbf{S}(x)$



Realistic Image Synthesis SS2020

Fredo Durand [2011]







 $f(x) \mathbf{S}(x)$



Fredo Durand [2011]













Aliasing in Reconstruction





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Aliasing in Reconstruction





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Aliasing in Reconstruction

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Aliasing in Reconstruction

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Aliasing in Reconstruction

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Aliasing in Reconstruction









Aliasing in Reconstruction

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Aliasing (Reconstruction) vs. Error (Integration)








Aliasing (Reconstruction) vs. Error (Integration)







Aliasing (Reconstruction) vs. Error (Integration)







Integration in the Fourier Domain







Integration is the DC term in the Fourier Domain

Spatial Domain:



 $I = \int_D f(x) dx$







Integration is the DC term in the Fourier Domain

Spatial Domain:

Fourier Domain:



 $I = \int_{D} f(x) dx$







Integration is the DC term in the Fourier Domain

Spatial Domain:

Fourier Domain:



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 $I = \int_{D} f(x) dx$

 $\hat{f}(0)$



 $\tilde{\mu}_N = \int_D f(x) \mathbf{S}(x) dx$



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 $\tilde{\mu}_N = \int_{\mathcal{D}} f(x) \mathbf{S}(x) dx$









 $\tilde{\mu}_N = \int_{\mathcal{D}} f(x) \mathbf{S}(x) dx$







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 $\tilde{\mu}_N = \int_D f(x) \mathbf{S}(x) dx$







91

 $\tilde{\mu}_N = \int_D f(x) \mathbf{S}(x) dx$







91

 $\tilde{\mu}_N = \int_D f(x) \mathbf{S}(x)$





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$$f_{\Omega}(x) dx = \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$$

$$\frac{1}{N} \sum_{k=1}^{N} \delta(x - x_k)$$

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Monte Carlo Estimator in Fourier Domain

 $\tilde{\mu}_N = \int_D f(x) \mathbf{S}(x)$

 $\mathbf{S}(x) = \frac{1}{N}$



$$\mathbf{x} dx = \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$$

$$\frac{1}{N} \sum_{k=1}^N \delta(x - x_k)$$





Monte Carlo Estimator in Fourier Domain

 $\tilde{\mu}_N = \int_D f(x) \mathbf{S}(x)$

 $\mathbf{S}(x) = \frac{1}{N}$



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$$\mathbf{x})dx = \int_{\Omega} \hat{f}^{*}(\omega)\hat{\mathbf{S}}(\omega)d\omega$$

$$\frac{1}{N}\sum_{k=1}^{N}\delta(x-x_{k})$$



Monte Carlo Estimator in Fourier Domain

 $\tilde{\mu}_N = \int_D f(x) \mathbf{S}(x)$

 $\mathbf{S}(x) = \frac{1}{N}$

 $\hat{\mathbf{S}}(\omega) =$



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$$\begin{aligned} \mathbf{x} dx &= \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega \\ \frac{1}{N} \sum_{k=1}^N \delta(x - x_k) \\ \frac{1}{N} \sum_{k=1}^N e^{-i2\pi\omega x_k} \end{aligned}$$







































 $I = \hat{f}(0)$





 $\tilde{\mu}_N = \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$

 $I - \tilde{\mu}_N = \int_D f(x) dx - \int_D f(x) \mathbf{S}(x) dx$







 $I = \hat{f}(0)$





 $\tilde{\mu}_N = \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$







 $I = \hat{f}(0)$





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 $\tilde{\mu}_N = \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$

Monte Carlo Estimator





 $I = \hat{f}(0)$





 $\tilde{\mu}_N = \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$

 $I - \tilde{\mu}_N = \int_D f(x) dx - \int_D f(x) \mathbf{S}(x) dx$







 $I = \hat{f}(0)$





 $\tilde{\mu}_N = \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$

 $I - \tilde{\mu}_N = \int_D f(x) dx - \int_D f(x) \mathbf{S}(x) dx$







Error in Fourier Domain

 $I = \hat{f}(0)$

 $I - \tilde{\mu}_N = \int_{D} f(x) dx - \int_{D} f(x) \mathbf{S}(x) dx$



 $\tilde{\mu}_N = \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$

 $I - \tilde{\mu}_N = \hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$

Fredo Durand [2011]





Error in Fourier Domain









$Error = Bias^2 + Variance$



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• Bias

• Variance







• Bias: Expected value of the Error

• Variance



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- Bias: Expected value of the Error $\langle I - \tilde{\mu}_N angle$

• Variance





• Bias: Expected value of the Error $\langle I - \tilde{\mu}_N \rangle$

• Variance: $Var(I - \mu_N)$



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Subr and Kautz [2013]







Bias in the Monte Carlo Estimator





Error:



 $I - \tilde{\mu}_N = \hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$





Error:



 $I - \tilde{\mu}_N = \hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$





Bias:

Error:

 $\langle I - \tilde{\mu}_N \rangle$



 $I - \tilde{\mu}_N = \hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$









 $\langle I - \tilde{\mu}_N \rangle = \hat{f}(0) - \left\langle \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega \right\rangle$





 $\langle I - \tilde{\mu}_N \rangle = \hat{f}(0) - \left\langle \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega \right\rangle$





 $\langle I - \tilde{\mu}_N \rangle = \hat{f}(0) - \left\langle \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega \right\rangle$




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 $\langle I - \tilde{\mu}_N \rangle = \hat{f}(0) - \left\langle \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega \right\rangle$ $\langle I - \tilde{\mu}_N \rangle = \hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \langle \hat{\mathbf{S}}(\omega) \rangle d\omega$

Subr and Kautz [2013]





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 $\langle I - \tilde{\mu}_N \rangle = \hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \langle \hat{\mathbf{S}}(\omega) \rangle d\omega$

Subr and Kautz [2013]





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 $\langle I - \tilde{\mu}_N \rangle = \hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \langle \hat{\mathbf{S}}(\omega) \rangle \, d\omega$

Subr and Kautz [2013]





To obtain an unbiased estimator:



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 $\langle I - \tilde{\mu}_N \rangle = \hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \langle \hat{\mathbf{S}}(\omega) \rangle \, d\omega$

Subr and Kautz [2013]





$\langle I - \tilde{\mu}_N \rangle = \hat{f}(0) - \hat{f}(0)$

To obtain an unbiased estimator:



$$-\int_{\Omega} \hat{f}^*(\omega) \left< \hat{\mathbf{S}}(\omega) \right> d\omega$$

Subr and Kautz [2013]

$\langle \hat{\mathbf{S}}(\omega) \rangle = 0$ for frequencies other than zero





How to obtain $\langle \hat{\mathbf{S}}(\omega) \rangle = 0$?





Complex form in Amplitude and Phase

$\langle \hat{\mathbf{S}}(\omega) \rangle = |\langle \hat{\mathbf{S}}(\omega) \rangle| e^{-\Phi(\langle \hat{\mathbf{S}}(\omega) \rangle)}$



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Complex form in Amplitude and Phase

Amplitude $\langle \hat{\mathbf{S}}(\omega) \rangle = |\langle \hat{\mathbf{S}}(\omega) \rangle| e^{-\Phi(\langle \hat{\mathbf{S}}(\omega) \rangle)}$







Complex form in Amplitude and Phase



























Pauly et al. [2000] Ramamoorthi et al. [2012]















Multiple realizations

































$Error = Bias^2 + Variance$















in terms of variance



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Homogenization allows representation of error only





- Homogenization allows representation of error only in terms of variance
- We can take any sampling pattern and homogenize it to make the Monte Carlo estimator unbiased.















Error:



 $I - \tilde{\mu}_N = \hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$





Error:

 $I - \tilde{\mu}_N = \hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$

$\operatorname{Var}(I - \tilde{\mu}_N)$







Error:



 $I - \tilde{\mu}_N = \hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \hat{\mathbf{S}}(\omega) d\omega$ $\operatorname{Var}(I - \tilde{\mu}_N) = \operatorname{Var}\left(\hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \,\hat{\mathbf{S}}(\omega) \,d\omega\right)$





 $\operatorname{Var}(I - \tilde{\mu}_N) = \operatorname{Var}\left(\hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \,\hat{\mathbf{S}}(\omega) \,d\omega\right)$





 $\operatorname{Var}(I - \tilde{\mu}_N) = \operatorname{Var}\left(\hat{f}(0) - \int_{\Omega} \hat{f}^*(\omega) \,\hat{\mathbf{S}}(\omega) \,d\omega\right)$





 $\operatorname{Var}(I - \tilde{\mu}_N) = \operatorname{Var}\left(\hat{f}(\mathbf{0}) - \int_{\Omega} \hat{f}^*(\omega) \,\hat{\mathbf{S}}(\omega) \,d\omega\right)$





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 $\operatorname{Var}(\tilde{\mu}_N) = \operatorname{Var}\left(\int_{\Omega} \hat{f}^*(\omega) \,\hat{\mathbf{S}}(\omega) d\omega\right)$





 $\operatorname{Var}(\tilde{\mu}_N) = \operatorname{Var}\left(\int_{\Omega} \hat{f}^*(\omega) \,\hat{\mathbf{S}}(\omega) d\omega\right)$



where,

 $P_f(\omega) = |\hat{f}^*(\omega)|^2$ Power Spectrum



 $\operatorname{Var}(\tilde{\mu}_N) = \operatorname{Var}\left(\int_{\Omega} \hat{f}^*(\omega) \,\hat{\mathbf{S}}(\omega) d\omega\right)$

 $\operatorname{Var}(\tilde{\mu}_N) = \int_{\Omega} P_f(\omega) \operatorname{Var}\left(\hat{\mathbf{S}}(\omega)\right) d\omega$







 $\operatorname{Var}(\tilde{\mu}_N) = \int_{\Omega} P_f(\omega) \operatorname{Var}\left(\hat{\mathbf{S}}(\omega)\right) d\omega$





$$\operatorname{Var}(\tilde{\mu}_N) = \int_{\Omega} P_f(\omega) \operatorname{Var}\left(\hat{\mathbf{S}}(\omega)\right) d\omega$$



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Subr and Kautz [2013]






$$\operatorname{Var}(\tilde{\mu}_N) = \int_{\Omega} P_f(\omega) \operatorname{Var}\left(\hat{\mathbf{S}}(\omega)\right) d\omega$$

This is a general form, both for homogenised as well as non-homogenised sampling patterns



Subr and Kautz [2013]





$$\operatorname{Var}(\tilde{\mu}_N) = \int_{\Omega}$$



 $P_f(\omega) \operatorname{Var}\left(\hat{\mathbf{S}}(\omega)\right) d\omega$





$$\operatorname{Var}(\tilde{\mu}_N) = \int_{\Omega} P_f(\omega) \operatorname{Var}\left(\hat{\mathbf{S}}(\omega)\right) d\omega$$







$$\operatorname{Var}(\tilde{\mu}_N) = \int_{\Omega} P_f(\omega) \operatorname{Var}\left(\hat{\mathbf{S}}(\omega)\right) d\omega$$





$$\operatorname{Var}(\tilde{\mu}_N) = \int_{\Omega} P_f(\omega) \operatorname{Var}\left(\hat{\mathbf{S}}(\omega)\right) d\omega$$

For purely random samples:





$$\operatorname{Var}(\tilde{\mu}_N) = \int_{\Omega} P_f(\omega) \operatorname{Var}\left(\hat{\mathbf{S}}(\omega)\right) d\omega$$

For purely random samples:

$$\operatorname{Var}(\tilde{\mu}_N) = \int_{\Omega} P_f(\omega) \left\langle P_S(\omega) \right\rangle d\omega$$

where

$$P_S(\omega) = |\hat{\mathbf{S}}(\omega)|^2$$



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Fredo Durand [2011]





$$\operatorname{Var}(\tilde{\mu}_N) = \int_{\Omega} P_f(\omega) \operatorname{Var}\left(\hat{\mathbf{S}}(\omega)\right) d\omega$$

For purely random samples: $\langle \hat{\mathbf{S}}(\omega) \rangle = 0$

$$\operatorname{Var}(\tilde{\mu}_N) = \int_{\Sigma}$$

where

$$P_S(\omega) = |\hat{\mathbf{S}}(\omega)|^2$$



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 $\int P_f(\omega) \left\langle P_S(\omega) \right\rangle d\omega$ Ω

Fredo Durand [2011]





Homogenizing any sampling pattern makes $\langle \hat{\mathbf{S}}(\omega) \rangle = 0$





Homogenizing any sampling pattern makes $\langle \hat{\mathbf{S}}(\omega) \rangle = 0$

$$\operatorname{Var}(\tilde{\mu}_N) = \int_{\Sigma}$$

where,

 $P_S(\omega) = |\hat{\mathbf{S}}(\omega)|^2$



 $\int P_f(\omega) \left\langle P_S(\omega) \right\rangle d\omega$

Pilleboue et al. [2015]



$$\operatorname{Var}(\tilde{\mu}_N) = \int_{S}$$



 \mathbf{P} $P_f(\omega) \langle P_S(\omega) \rangle d\omega$ Ω



$$\operatorname{Var}(\tilde{\mu}_N) = \int_{S}$$



ſ $P_f(\omega) \left\langle P_S(\omega) \right\rangle d\omega$ Ω





Variance in terms of n-dimensional Power Spectra

$$\operatorname{Var}(\tilde{\mu}_N) = \int_{S}$$





1 $P_f(\omega) \langle P_S(\omega) \rangle d\omega$ \sum





Variance in terms of n-dimensional Power Spectra

$$\operatorname{Var}(\tilde{\mu}_N) = \int_{S}$$





1 $P_f(\omega) \langle P_S(\omega) \rangle d\omega$ \sum





Variance in the Polar Coordinates

$$\operatorname{Var}(\tilde{\mu}_N) = \int_{S}$$



ſ $P_f(\omega) \left\langle P_S(\omega) \right\rangle d\omega$ Ω





$$\operatorname{Var}(\tilde{\mu}_N) = \int_{\Sigma}$$

In polar coordinates:



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Variance in the Polar Coordinates

 $P_f(\omega) \left\langle P_S(\omega) \right\rangle d\omega$ Ω





$$\operatorname{Var}(\tilde{\mu}_N) = \int_{S}$$

In polar coordinates:

$$Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty \int_{\mathcal{S}^{d-1}} P_f(\rho \mathbf{n}) \langle P_{\mathbf{S}}(\rho \mathbf{n}) \rangle \, d\mathbf{n} \, d\rho$$



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Variance in the Polar Coordinates

 $P_f(\omega) \langle P_S(\omega) \rangle d\omega$ Ω





$$\operatorname{Var}(\tilde{\mu}_N) = \int_{S}$$

In polar coordinates:

$$Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty \int_{\mathcal{S}^{d-1}} P_f(\rho \mathbf{n}) \langle P_{\mathbf{S}}(\rho \mathbf{n}) \rangle \, d\mathbf{n} \, d\rho$$



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Variance in the Polar Coordinates

 $P_f(\omega) \langle P_S(\omega) \rangle d\omega$ Ω



Variance in the Polar Coordinates



 $Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty \int_{\mathcal{S}^{d-1}} \frac{P_f(\rho \mathbf{n}) \langle P_{\mathbf{S}}(\rho \mathbf{n}) \rangle \, d\mathbf{n} \, d\rho}$





Variance in the Polar Coordinates

 $Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty \int_{\mathcal{S}^{d-1}}^\infty P_f(\rho \mathbf{n}) \langle P_{\mathbf{S}}(\rho \mathbf{n}) \rangle \, d\mathbf{n} \, d\rho$









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 $Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty \int_{\mathcal{S}^{d-1}}^\infty P_f(\rho \mathbf{n}) \langle P_{\mathbf{S}}(\rho \mathbf{n}) \rangle \, d\mathbf{n} \, d\rho$





For isotropic power spectra:



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 $Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty \int_{\mathcal{S}^{d-1}}^\infty P_f(\rho \mathbf{n}) \langle P_{\mathbf{S}}(\rho \mathbf{n}) \rangle \, d\mathbf{n} \, d\rho$





For isotropic power spectra:



Realistic Image Synthesis SS2020

 $Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty \int_{\mathcal{S}^{d-1}}^\infty P_f(\rho \mathbf{n}) \langle P_{\mathbf{S}}(\rho \mathbf{n}) \rangle d\mathbf{n} d\rho$







For isotropic power spectra:



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 $Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty \int_{\mathbf{S}^{d-1}} \frac{P_f(\rho \mathbf{n}) \langle P_{\mathbf{S}}(\rho \mathbf{n}) \rangle \, d\mathbf{n} \, d\rho}$







For isotropic power spectra:



 $Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty \int_{\mathcal{S}^{d-1}} \frac{P_f(\rho \mathbf{n}) \langle P_{\mathbf{S}}(\rho \mathbf{n}) \rangle \, d\mathbf{n} \, d\rho}$

 $Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty \tilde{P}_f(\rho) \langle \tilde{P}_{\mathbf{S}}(\rho) \rangle d\rho$







$$Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty$$

For isotropic power spectra:

$$Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^d)$$



 $\int_{0}^{\infty} \int_{\mathbf{S}^{d-1}}^{\infty} \frac{P_f(\rho \mathbf{n}) \langle P_{\mathbf{S}}(\rho \mathbf{n}) \rangle \, d\mathbf{n} \, d\rho}{|\mathbf{S}^{d-1}|^2}$

 $^{d-1})\int_{0}^{\infty}\tilde{P}_{f}(\rho)\langle\tilde{P}_{\mathbf{S}}(\rho)\rangle\,d\rho$







$$Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty$$

For isotropic power spectra:

$$Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^d)$$



 $\int_{0}^{\infty} \int_{S^{d-1}}^{\infty} P_{f}(\rho \mathbf{n}) \left\langle P_{\mathbf{S}}(\rho \mathbf{n}) \right\rangle d\mathbf{n} \, d\rho$

 $^{d-1}$) $\int_{0}^{\infty} \tilde{P}_{f}(\rho) \langle \tilde{P}_{\mathbf{S}}(\rho) \rangle d\rho$





Variance in terms of 1-dimensional Power Spectra

$$Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d})$$





 $^{l-1})\int_{0}^{\infty}\tilde{P}_{f}(\rho)\langle\tilde{P}_{\mathbf{S}}(\rho)\rangle\,d
ho$





Variance in terms of 1-dimensional Power Spectra

$$Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d})$$





 $^{l-1})\int_{0}^{\infty}\tilde{P}_{f}(\rho)\langle\tilde{P}_{\mathbf{S}}(\rho)\rangle\,d\rho$





 $Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d-1}) \int_0^\infty \tilde{P}_f(\rho) \left\langle \tilde{P}_{\mathbf{S}}(\rho) \right\rangle d\rho$







$$Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d})$$

Integrand Radial Power Spectrum

For given number of Samples



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 $^{l-1})\int_{0}^{\infty}\tilde{P}_{f}(\rho)\langle\tilde{P}_{\mathbf{S}}(\rho)\rangle\,d\rho$

Sampling Radial Power Spectrum





$$Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d})$$

Integrand Radial Power Spectrum

For given number of Samples



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 $^{l-1})\int_{0}^{0}\tilde{P}_{f}(\rho)\langle\tilde{P}_{S}(\rho)\rangle\,d\rho$

Sampling Radial Power Spectrum





$$Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d})$$

Integrand Radial Power Spectrum





 $^{l-1})\int_{0}^{\infty}\tilde{P}_{f}(\rho)\langle\tilde{P}_{\mathbf{S}}(\rho)\rangle\,d\rho$



For given number of Samples







$$Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d})$$

Integrand Radial Power Spectrum





 $^{l-1})\int_{0}^{\infty}\tilde{P}_{f}(\rho)\langle\tilde{P}_{\mathbf{S}}(\rho)\rangle\,d\rho$



For given number of Samples

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$$Var[\tilde{\mu}_N] = \mathcal{M}(\mathcal{S}^{d})$$

Integrand Radial Power Spectrum





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 $^{l-1})\int_{0}^{\infty}\tilde{P}_{f}(\rho)\langle\tilde{P}_{\mathbf{S}}(\rho)\rangle\,d\rho$



For given number of Samples







Spatial Distribution vs Radial Mean Power Spectra



itter

Jisk

SSON



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For 2-dimensions

Samplers	Worst Case	Best Case
Random		
Jitter		
Poisson Disk		
CCVT		



Pilleboue et al. [2015]




Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	
Jitter		
Poisson Disk		
CCVT		



Pilleboue et al. [2015]





Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter		
Poisson Disk		
CCVT		



Pilleboue et al. [2015]





Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	
Poisson Disk		
CCVT		



Pilleboue et al. [2015]





Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-2})$
Poisson Disk		
CCVT		



Pilleboue et al. [2015]





Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-2})$
Poisson Disk	$\mathcal{O}(N^{-1})$	
CCVT		



Pilleboue et al. [2015]





Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-2})$
Poisson Disk	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
CCVT		



Pilleboue et al. [2015]





Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-2})$
Poisson Disk	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
CCVT	$\mathcal{O}(N^{-1.5})$	



Pilleboue et al. [2015]







Samplers	Worst Case	Best Case
Random	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
Jitter	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-2})$
Poisson Disk	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
CCVT	$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-3})$



Pilleboue et al. [2015]











Vorst Case	Best Case
$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-2})$
$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
$\mathcal{O}(N^{-1.5})$	$\mathcal{O}(N^{-3})$

Pilleboue et al. [2015]









Poisson Disk

Jitter

Power

Power

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Low Frequency Region







Poisson Disk

Jitter

Power

Power

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Low Frequency Region











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Low Frequency Region



Variance for Low Sample Count







Variance for Low Sample Count







Variance for Increasing Sample Count





Experimental Verification







Convergence rate



Increasing Samples











Convergence rate



Increasing Samples











Convergence rate



Increasing Samples











































Gaussian as Best Case







Gaussian as Best Case



Ambient Occlusion Examples





Random vs Jittered

96 Secondary Rays



MSE: 4.74 x 10e-3





MSE: 8.56 x 10e-4





96 Secondary Rays



MSE: 4.24 x 10e-4



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CCVT vs. Poisson Disk



MSE: 6.95 x 10e-4



Convergence rates









Convergence rates













Jittered vs Poisson Disk







What are the benefits of this analysis?





What are the benefits of this analysis ?

For offline rendering, an would converge faster.



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• For offline rendering, analysis tells which samplers





What are the benefits of this analysis?

- would converge faster.
- number of samples



• For offline rendering, analysis tells which samplers

• For real time rendering, blue noise samples are more effective in reducing variance for a given



