Realistic Image Synthesis

Perception-based Rendering &
 Advanced Displays-

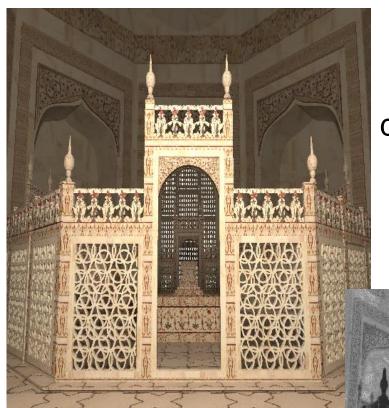
Philipp Slusallek Karol Myszkowski Gurprit Singh

Outline

- Perceptually based adaptive sampling algorithm
- Eye tracking driven rendering
- Binocular 3D displays
- Autostereoscopic (Glass-free 3D) Displays
 - Parallax Barriers
 - Integral Imaging
 - Multi-layer displays
 - Holographic displays
- Head-Mounted Displays with accommodation cues

Perceptually Based Rendering

6% effort



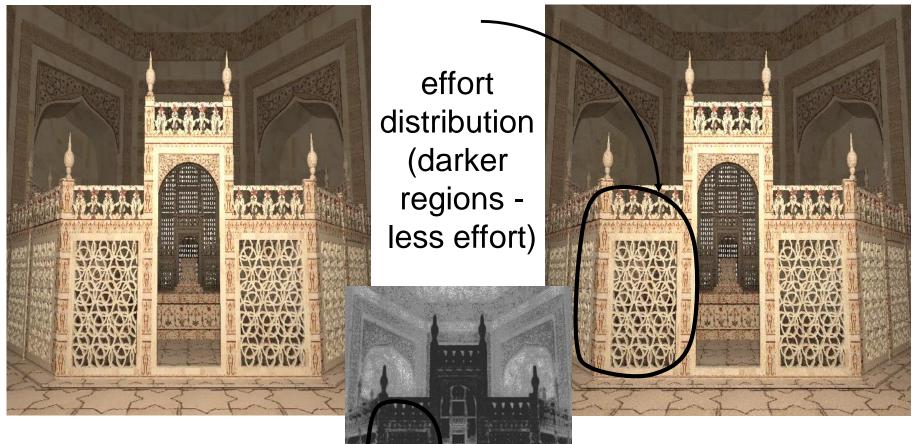
effort distribution (darker regions less effort)

physically accurate

perceptually accurate

Perceptually Based Rendering

6% effort



physically accurate

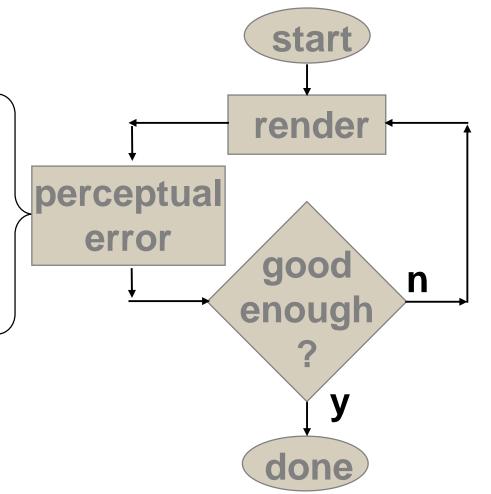
perceptually accurate

Perceptually Based Rendering

Traditional approach:

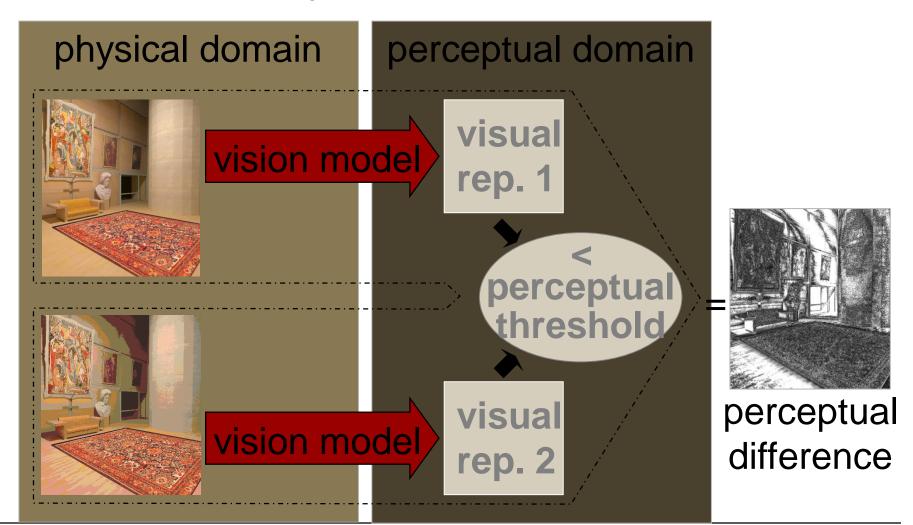
Pair of images to compare at each time step

- (a) intermediate images at consecutive time steps.
- (b) upper and lower bound images at each time step.



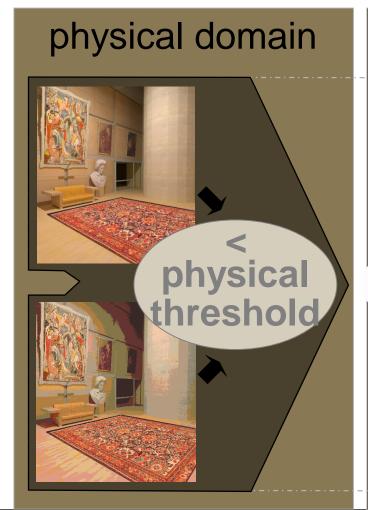
Perceptual Error Metric

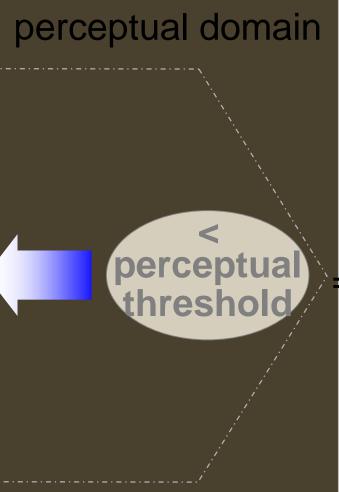
Vision model - expensive

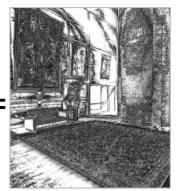


Perceptually Based

Physical Error Metric







perceptual difference

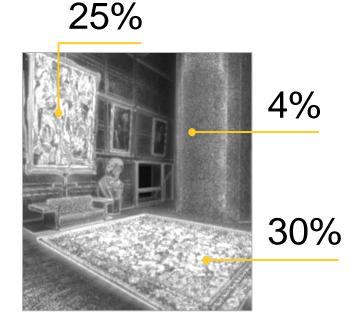
Physical Threshold Map

Predicted bounds of permissible luminance error



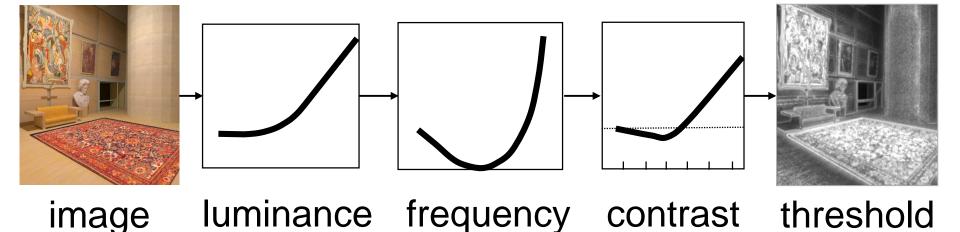
threshold model

input image



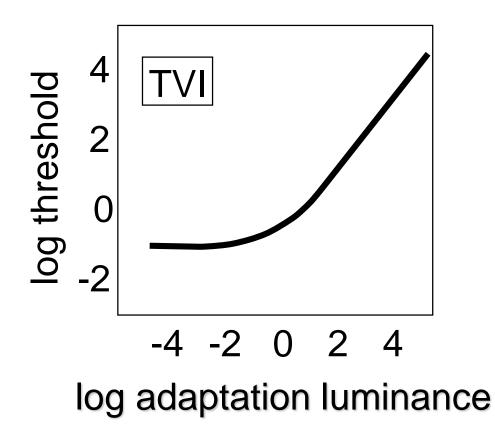
physical threshold(brighter regionshigher thresholds)

Components



component component

1. Luminance component

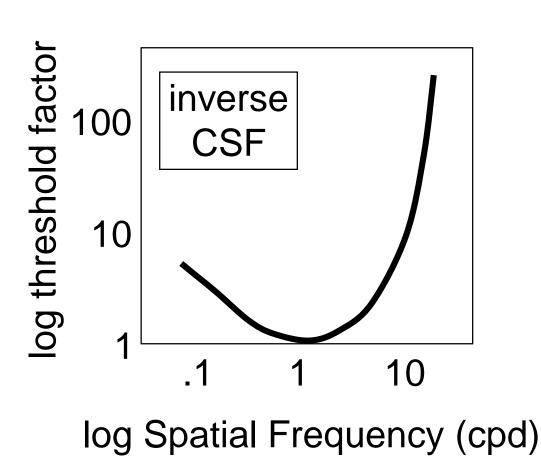


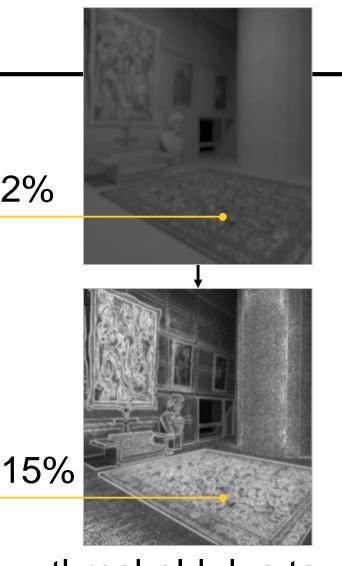


threshold due to luminance

2%

2. Frequency component



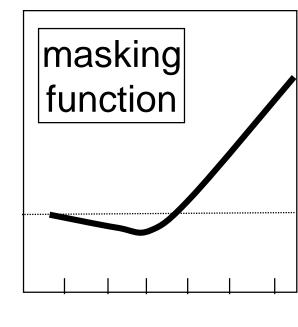


2%

threshold due to luminance + freq.

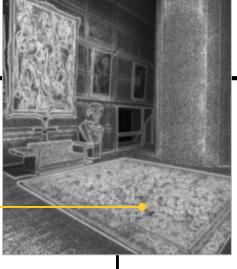
3. Contrast component (visual masking)

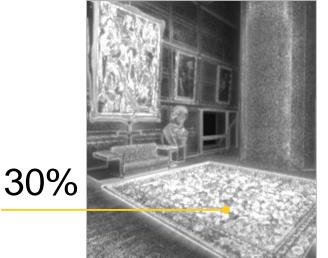
log threshold factor



log contrast

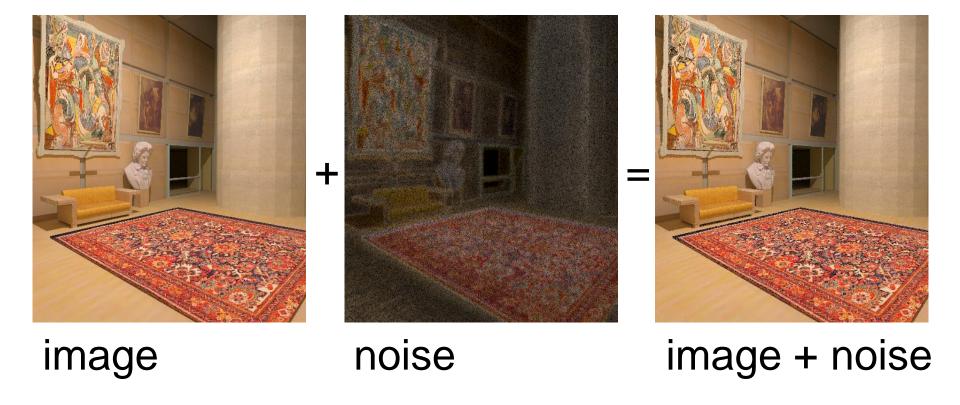
15%

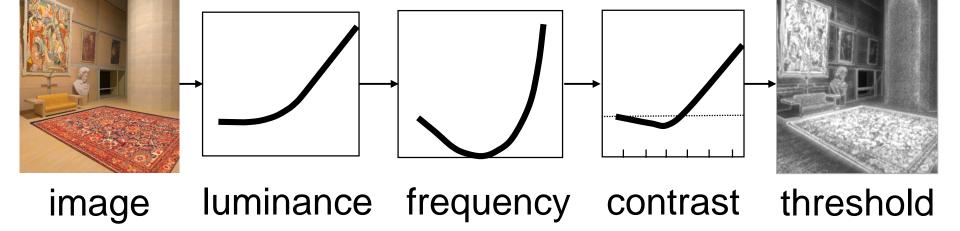




threshold due to luminance + freq. + contrast

Validation

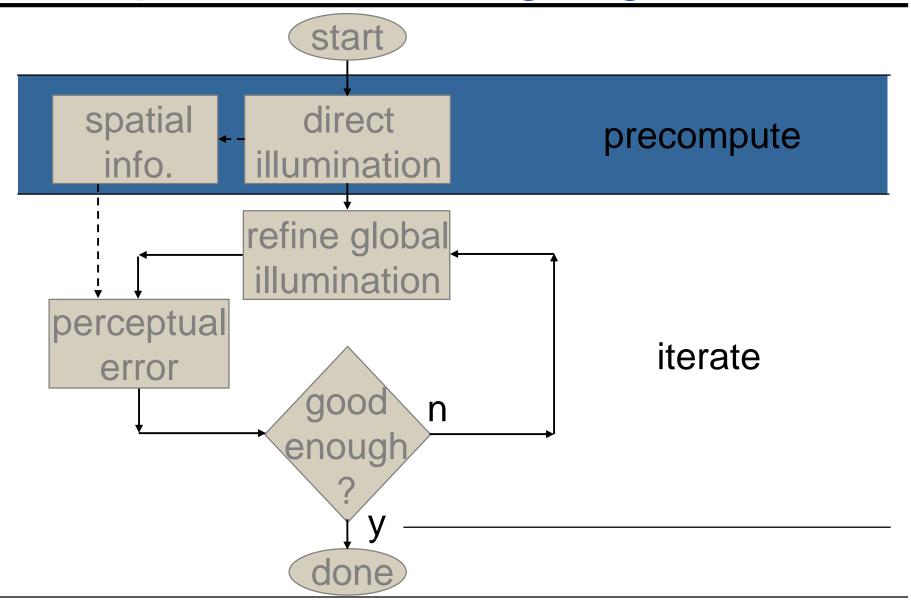




component component

Realistic Image Synthesis SS20 – Perception-based Rendering

Adaptive Rendering Algorithm



Results

5% effort

effort distribution (darker regions less effort)

adaptive solution

reference solution

Results: Masking by Textures

5% effort



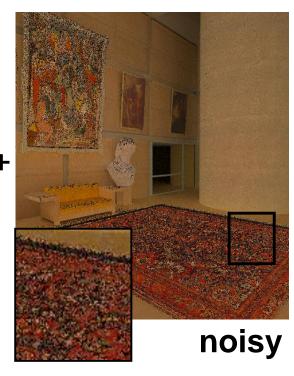
effort distribution (darker regions less effort)

reference solution

adaptive solution

Results





5% effort



direct illumination

adaptive indirect illumination

adaptive global illumination

Results: Masking by Geometry

5% effort



effort distribution (darker regions less effort)

reference solution

adaptive solution

Results: Masking by Shadows

6% effort

effort distribution (darker regions less effort)

adaptive solution

reference solution

Eye Tracking - Motivation

1. Improving computational efficiency

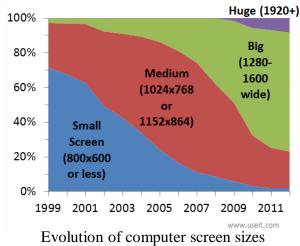
- There is a trend towards higher resolution displays
 - → Higher computational requirement for 3D rendering
- Only a fraction of pixels is consciously attended and perceived in the full-resolution

2. Improving realism

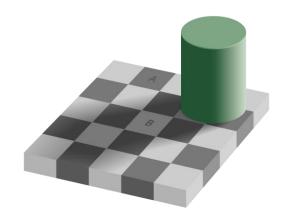
 Eye is always focused on the screen plane; nevertheless, it is possible to simulate Depth-of-Field (DoF) effect by artificially blurring out-of-focus regions according to the gaze location

3. Improve perceived quality

- Human Visual System (HVS) has local adaptation property
- Perception of luminance, contrast and color are not absolute and highly dependent on both spatial and temporal neighborhood of the gaze location



Evolution of computer screen sizes



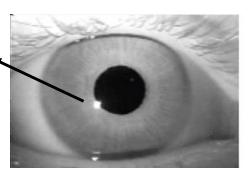
Checker shadow illusion

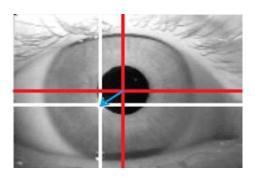
Images adapted from https://www.nngroup.com/articles/computer-screens-getting-bigger/

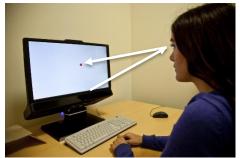
Eye Tracking

Basic Technology:

Corneal
Reflection
(also known
as "glint" or
"1st Purkinje
Reflection")

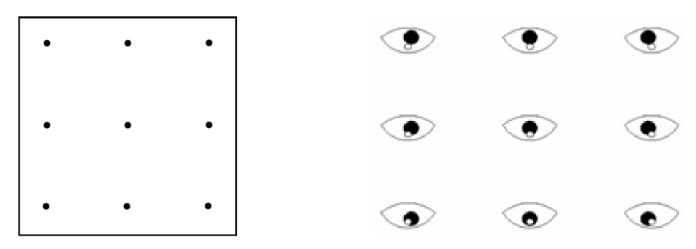






- Eye trackers mostly operate using infrared imaging technology
- Once the pupil is detected the vector between the center of the pupil and the corneal reflection of the infrared light source is translated into the gaze location on screen coordinates
- Requires calibration at the beginning

Eye Tracking



Sample 9-point calibration grid

Relative positions of the pupil and the corneal reflection

- Individual calibration is necessary for each observer
- Relative location of the corneal reflection and the pupil is different among the population due to
 - Difference in eye ball radius and shape
 - Eye-glasses

Images adapted from http://wiki.cogain.org

Eye Tracking







Chin-rest (EyeLink 1000/2000)

Glasses (SMI Eye Tracking Glasses)

Head-mounted displays (Oculus Rift)

- Some of the other types of setups are used only for specific applications since they may be highly intrusive (e.g. chin-rest eye trackers) and not comfortable for the end-users in practice
- Head-mounted displays (HMD) offer 3D stereo and augmented reality capabilities in addition to eye tracking

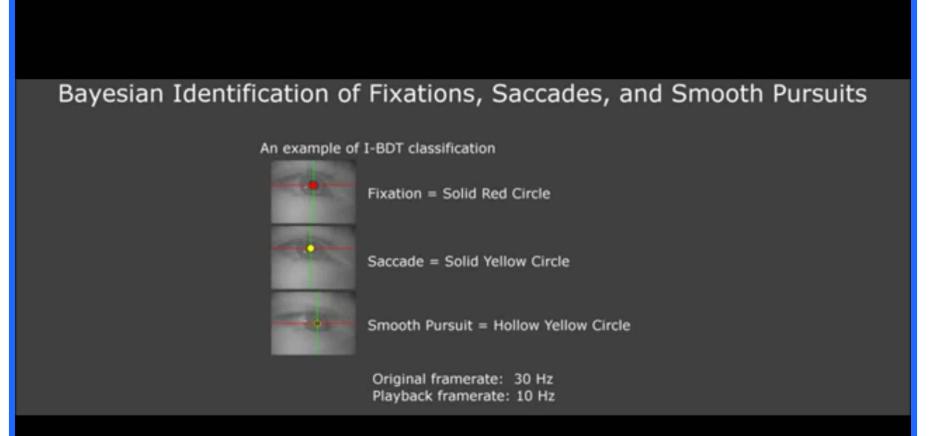
Types of Eye Motion

Туре	Duration (ms)	Amplitude (1° = 60')	Velocity
Fixation	200-300	-	-
Microsaccade	10-30	10-40'	15-50°/s
Tremor	-	<1'	20'/sec
Drift	200-1000	1-60'	6-25'/s
Saccade	30-80	4-20°	30-500°/s
Glissade	10-40	0.5-2°	20-140°/s
Smooth Pursuit	variable	variable	10-30°/s

 While the mechanisms are not exactly known, it is thought that the brain performs visual suppression and compensation during saccades and smooth pursuits against motion blur on the retina.

Reference: Holmqvist, K., Nyström, M., Andersson, R., Dewhurst, R., Jarodzka, H., & Van de Weijer, J. (2011). Eye tracking: A comprehensive guide to methods and measures. OUP Oxford.

Eye Tracking in Action

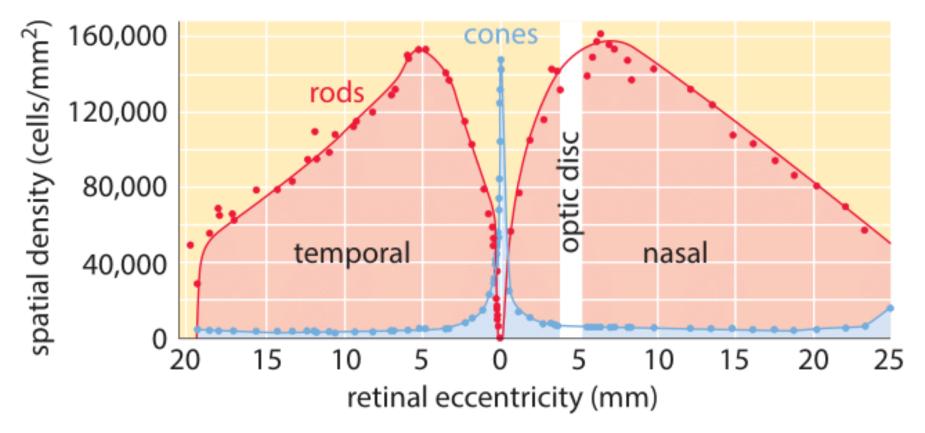


Adapted from T. Santini, W. Fuhl, T. Kübler, and E. Kasneci. Bayesian Identification of Fixations, Saccades, and Smooth Pursuits ACM Symposium on Eye Tracking Research & Applications, ETRA 2016.

Realistic Image Synthesis SS20 - Perception-based Rendering

Visual Acuity

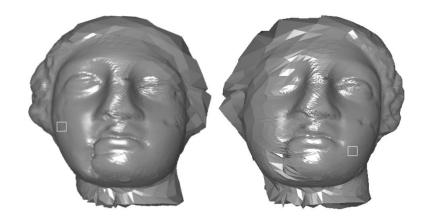
Distribution of photoreceptor cells in the retina



Adapted from R. W. Rodieck, The First Steps of Seeing, Sinauer Associates, 1998.

Level-of-Detail Rendering

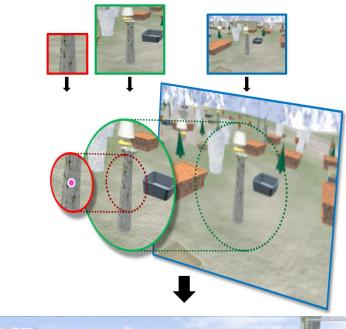
- The model resolution may be degraded according to the visual angle and the acuity of HVS at the given angle
 - Mesh structure of the model is partitioned into tiles using Voronoi diagram
 - Tiles are mapped to planar polygons
 - Remeshing into multiresolution form

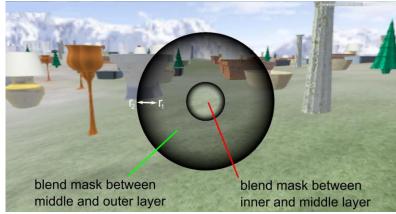


Adapted from Murphy, Hunter, and Andrew T. Duchowski. "Gaze-contingent level of detail rendering." EuroGraphics 2001 (2001).

Foveated 3D Graphics

- Screen-based (in contrast to model-based methods)
- Human eye has full acuity in around 5° foveal region
- The efficiency of image generation can be improved by maintaining high image resolution only around the gaze location
- Using 60Hz monitor and Tobii X50
 eye tracker with 50Hz sampling
 frequency and 35ms latency caused
 artifacts for the observer
- Results using 120Hz monitor and Tobii TX300 with 300Hz sampling frequency and 10ms latency were tolerable





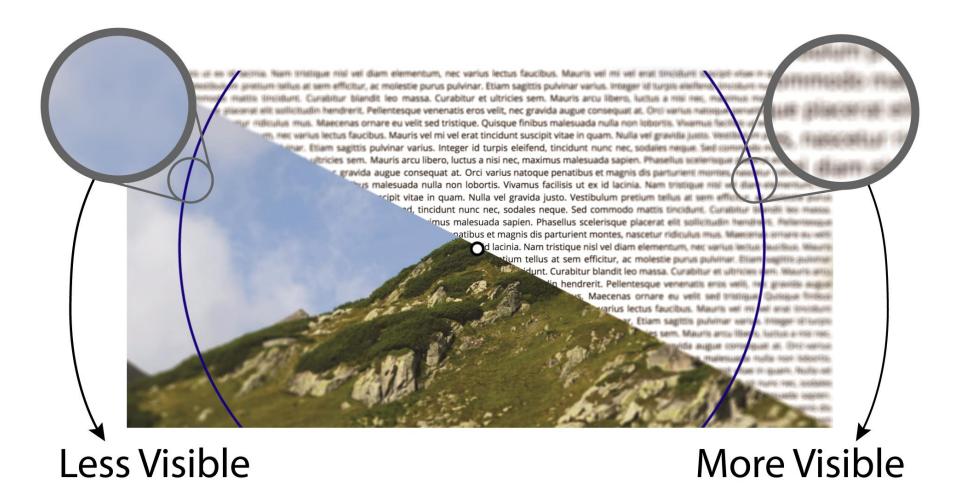
Images adapted from Guenter, B., Finch, M., Drucker, S., Tan, D., & Snyder, J. (2012). Foveated 3D graphics. ACM Transactions on Graphics (TOG), 31(6), 164.

Foveated 3D Graphics

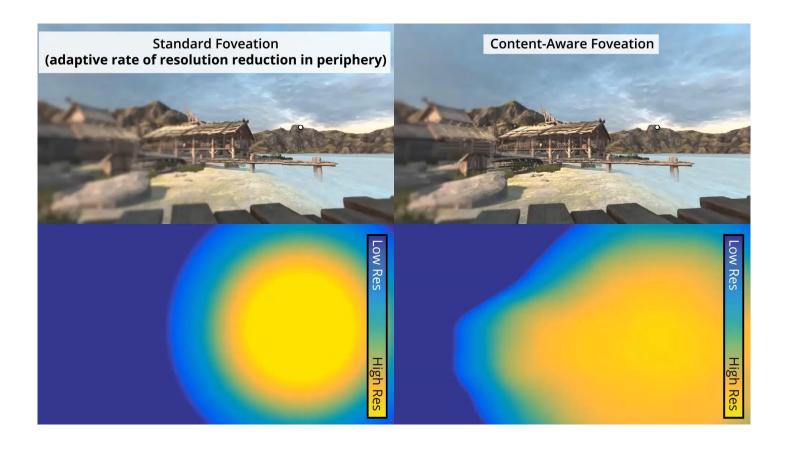


Video adapted from http://research.microsoft.com

Luminance-Contrast-Aware Foveated Rendering



Luminance-Contrast-Aware Foveated Rendering



Effect of Depth-of-Field

Improves the rendering realism and enhances the depth perception



(a) Image focused on objects at shallow depth (flower)



(b) Image focused on objects at large depth (Main Quad)



(c) Image with everything in focus



Images adapted from Gupta, Kushagr, and Suleman Kazi, "Gaze Contingent Depth of Field Display", 2016. Video adapted from Mantiuk, Radoslaw, Bartosz Bazyluk, and Rafal K. Mantiuk. "Gaze-driven Object Tracking for Real Time Rendering." Computer Graphics Forum. Vol. 32. No. 2pt2. Blackwell Publishing Ltd, 2013.

Depth-of-Field Rendering

Circle of Confusion :

$$CoC = a \cdot \left| \frac{f}{d_0 - f} \right| \cdot \left| 1 - \frac{d_0}{d_p} \right|$$

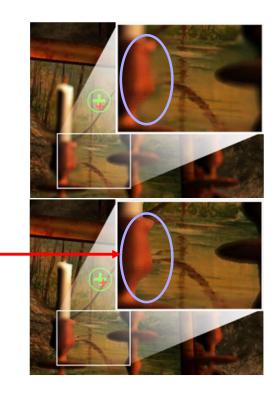
a - diameter of the lens aperture

f - focal length of the lens

 d_0 - distance between the focal plane and lens

 d_p - distance from an object to the lens

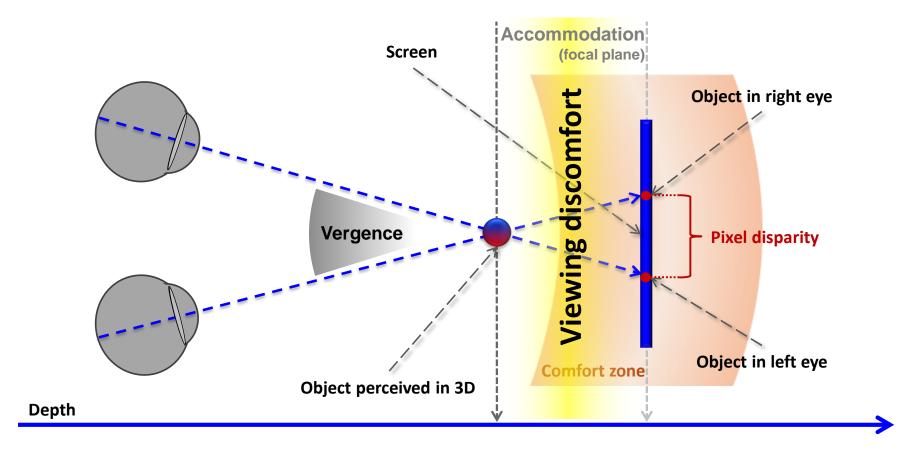
- d_p is obtained from reverse mapping of the z-buffer
- Addresses the artifacts due to the depth discontinuity near object boundaries by spreading the blur outside the object boundary



Images adapted from Mantiuk, R., Bazyluk, B., & Tomaszewska, A. (2011). Gaze-dependent depth-of-field effect rendering in virtual environments. In Serious Games Development and Applications (pp. 1-12). Springer Berlin Heidelberg.

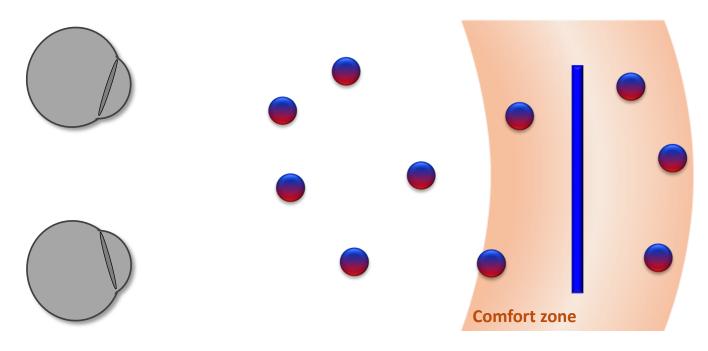
Vergence-accommodation Conflict

Stereo 3D: Binocular Disparity



Vergence-accommodation Conflict

Depth Manipulation

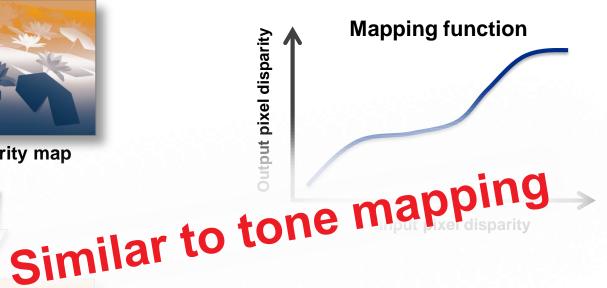


Viewing and Viewing comfort

Depth Manipulation



Pixel disparity map



Function:

- Linear
- Logarithmic
- Content dependent

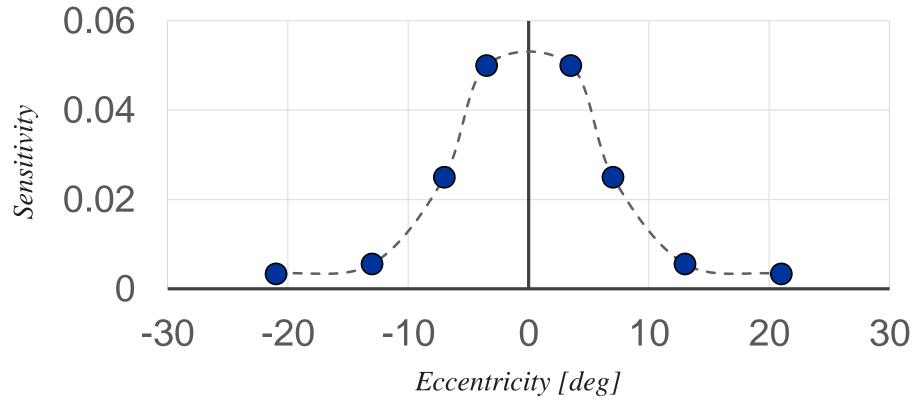
Other possibilities:

- Gradient domain
- Local operators

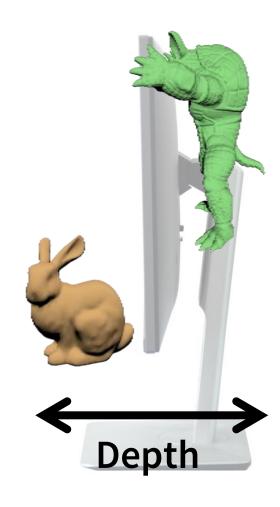
"Nonlinear Disparity Mapping for Stereoscopic 3D" [Lang et al. 2010]

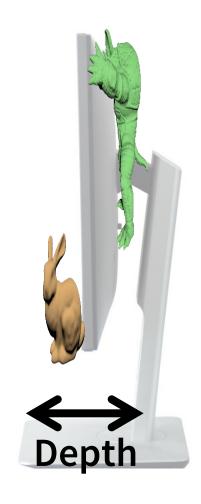
Modified pixel disparity

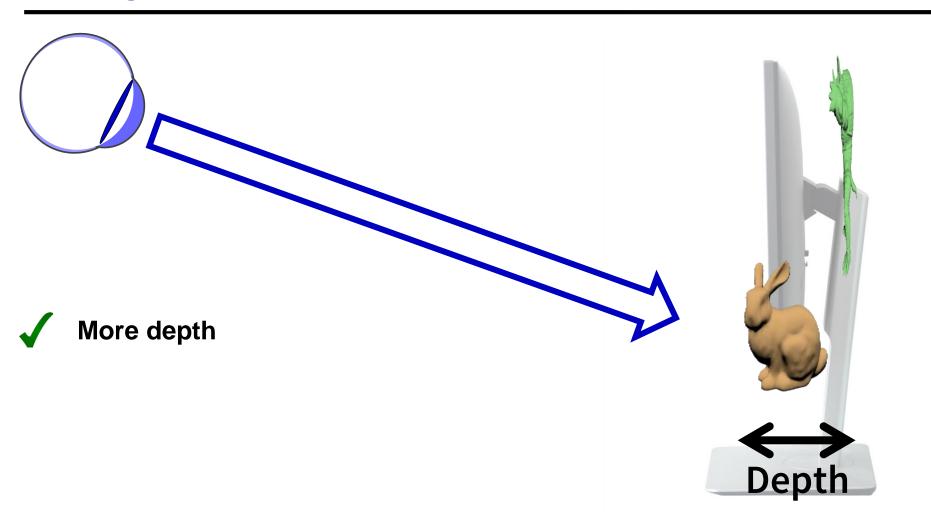
Disparity Perception (Stereo 3D)

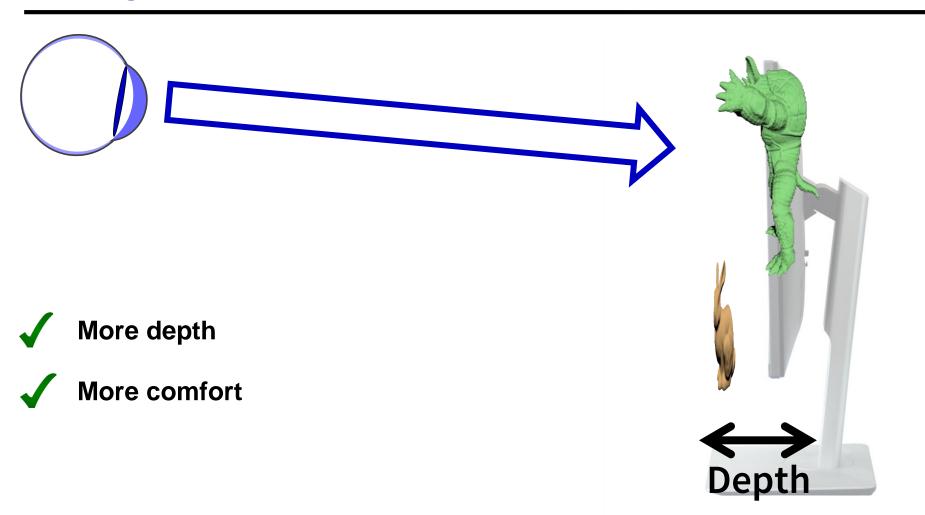


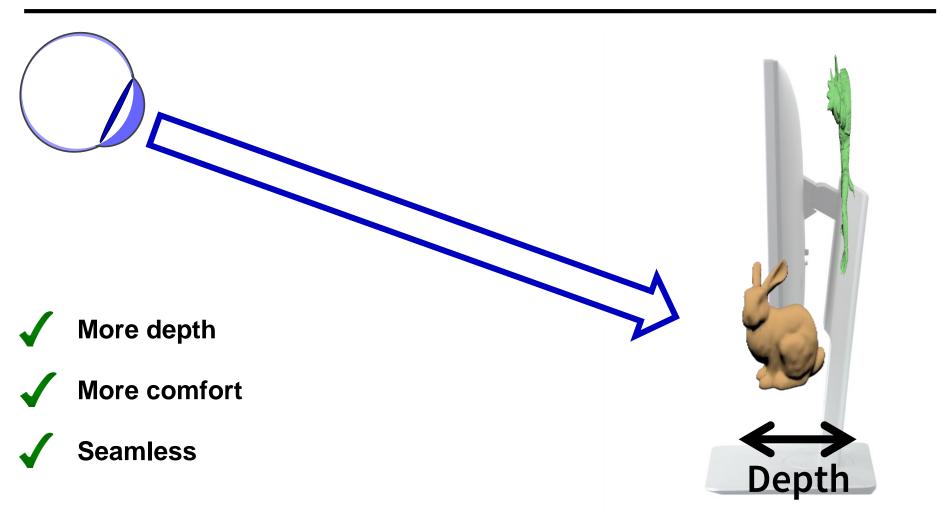
Replotted from Figure 3 of Simon J.D Prince, Brian J Rogers
Sensitivity to disparity corrugations in peripheral vision, Vision Research, Volume 38, Issue 17, September 1998

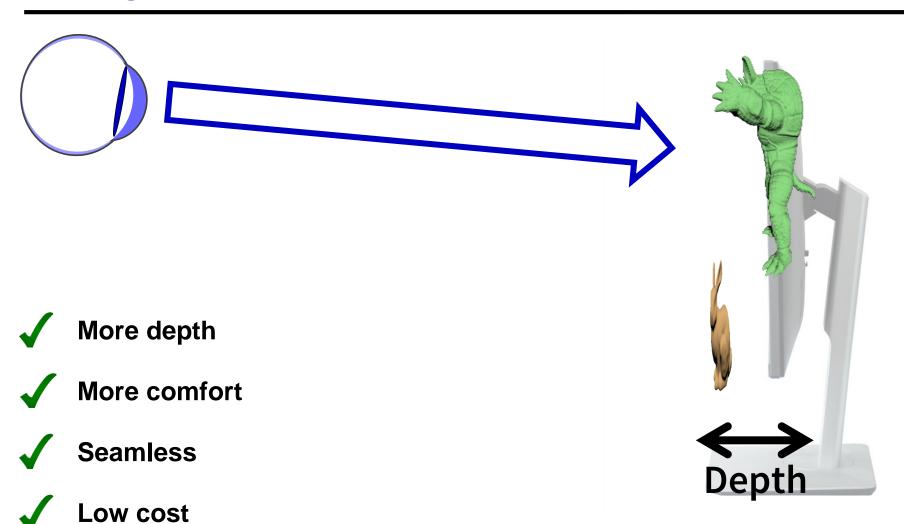












Gaze-contingent Stereo

- The region of attention may be predicted to manipulate disparity for comfortable viewing
- The online predictor uses Decision Forests (DF) to predict the object category that the viewer looks at
- A total of 13 game variables are used for prediction (e.g. Health, Hunger, Thirst, Ammo, Distance to the closest robot, ...) which are selected among 300 as the most "informative" ones (ignoring variables with little or no variability)
- The predicted objects in the current scene are placed as close to the plane of zero-disparity as possible

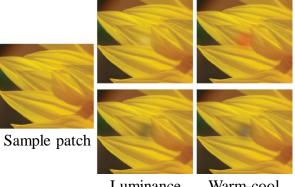


Images adapted from Koulieris, George Alex, et al. "Gaze Prediction using Machine Learning for Dynamic Stereo Manipulation in Games." IEEE Virtual Reality. 2016.

Subtle Gaze Direction

- When viewing an image lowacuity peripheral vision detects areas of interest, then HVS directs gaze to those locations
- HVS is very sensitive to changes in luminance (Spillmann et al. 1990) and opponent color channels (Hurvich and Jameson 1957)
- Introduces subtle image modulation to control the gaze direction of the observer
- Luminance and warm-cool modulations are studied and both are found successful



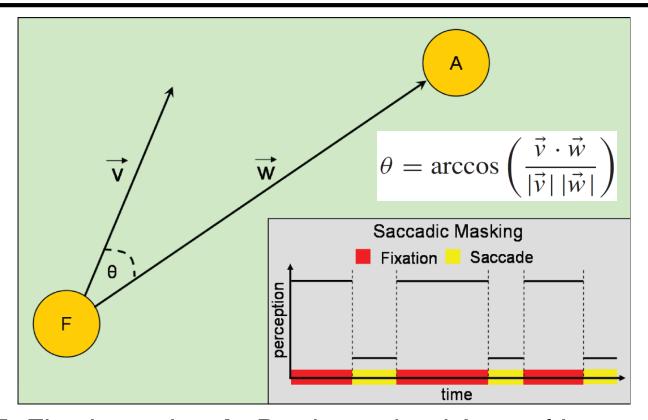


Luminance modulation

Warm-cool modulation

Images adapted from Bailey, R., McNamara, A., Sudarsanam, N., & Grimm, C. (2009). Subtle gaze direction. ACM Transactions on Graphics (TOG), 28(4), 100.

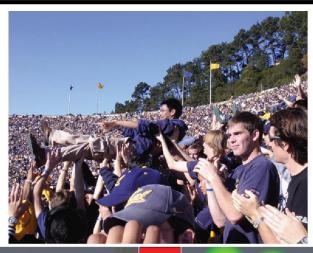
Subtle Gaze Direction

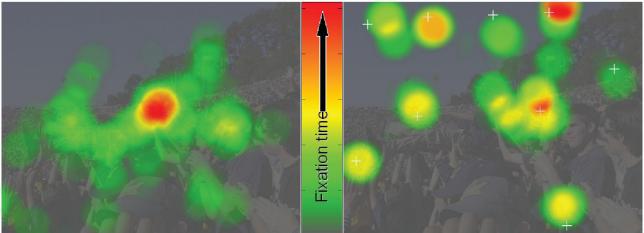


F: Fixation point, **A**: Predetermined Area of Interest **Goal**: To direct the user attention to from **F** to **A** Modulation is applied to A and θ is monitored real-time. When $\theta \le 10^{\circ}$, the modulation is terminated immediately.

Images adapted from Bailey, R., McNamara, A., Sudarsanam, N., & Grimm, C. (2009). Subtle gaze direction. ACM Transactions on Graphics (TOG), 28(4), 100.

Subtle Gaze Direction





Top: Input image, **Left:** No modulation, **Right:** Modulation at white crosses

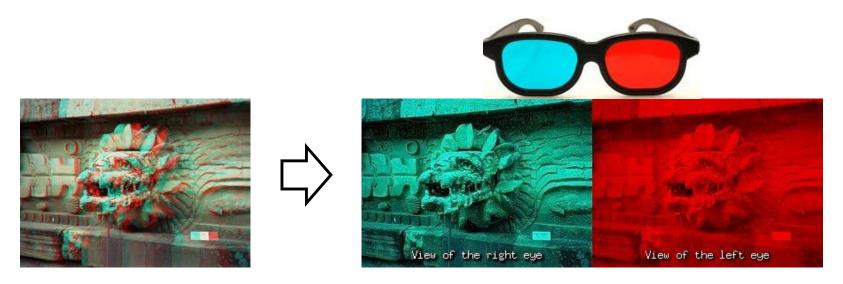
Images adapted from Bailey, R., McNamara, A., Sudarsanam, N., & Grimm, C. (2009). Subtle gaze direction. ACM Transactions on Graphics (TOG), 28(4), 100.

Binocular 3D Displays

- Capable of providing sense of 3D by simulating binocular disparity
 - Color Anaglyphs
 - Polarization
 - Shutter Glasses
 - Head-Mounted Displays
- They mostly do not provide accommodation depth cue

Color Anaglyphs

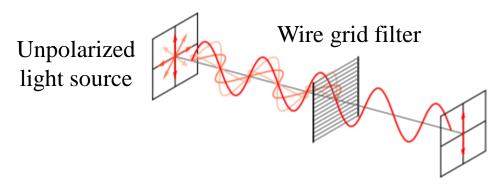
- Left and right images are filtered using different colors (usually complementary):
 - Red Green, Red Cyan, Green Magenta
 - Amber Blue (ColorCode 3D, patented [Sorensen et al. 2004])
- Limited color perception (since each eye sees only a subset of whole colorspace)



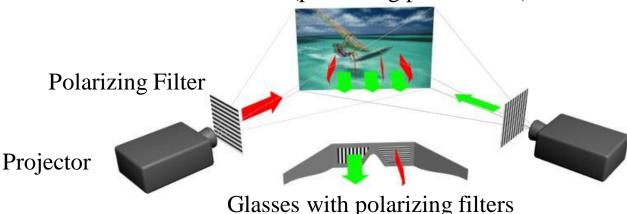
Images adapted from http://axon.physik.uni-bremen.de/research/stereo/color_anaglyph/

Polarization

 Usually a wire grid filter converts the unpolarized light beam to a polarized one



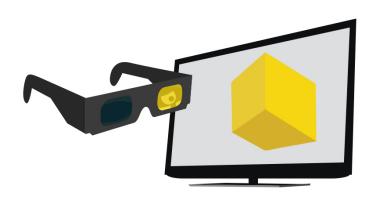
Screen (preserving polarization)



Images adapted from https://cpinettes.u-cergy.fr/S6-Electromag files/fig1.pdf

Shutter Glasses

- Exploits the "memory effect" of the Human Visual System [Coltheart
 1980]
- Glasses have shutters which operate in synchronization with the display system
- Left and right eye images are shown in alternation
- Color neutral; however, temporal resolution is reduced





IR receiver for synchronization

Images adapted from https://en.wikipedia.org/wiki/Active shutter 3D system

Head-Mounted Displays

- Separate displays for the left and right eye
- May provide current orientation of the head (and update the stimuli accordingly to provide a VR)





Images adapted from http://www.oculus.com

Autostereoscopic Displays

- Stereo displays which are viewable without special glasses or head-wear equipment
- Simulate an approximate lightfield with a finite number of views
 - Parallax Barriers
 - Integral Imaging
 - Multi-layer Displays

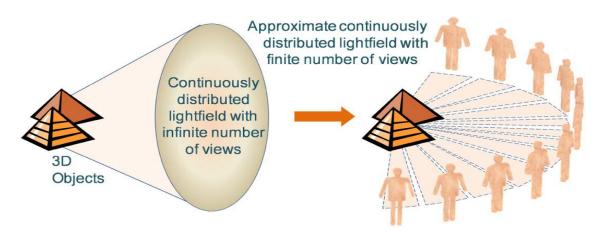
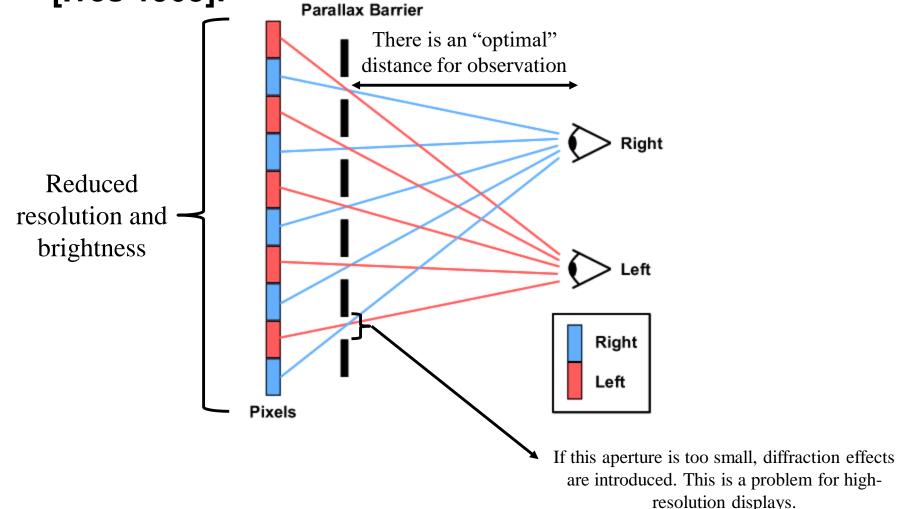


Image adapted from Geng, Jason. "Three-dimensional display technologies." Advances in optics and photonics 5.4 (2013): 456-535.

Parallax Barriers

 Occlusion-based working principle and key features [Ives 1903]:



Parallax Barriers

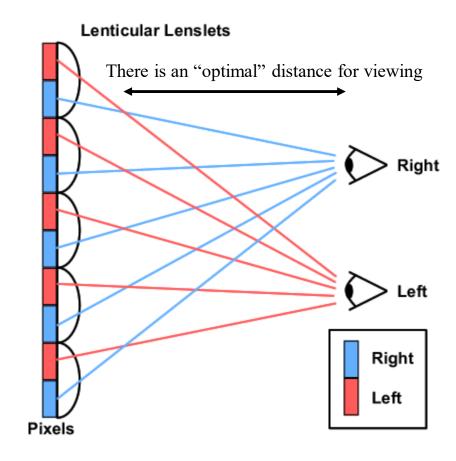


Video adapted from: http://www.youtube.com/watch?v=sxF9PGRiabw "Glasses-Free 3D Gaming for \$5 (Parallax Barrier)"

Integral Imaging

Refraction-based working principle [Lippmann 1908]:

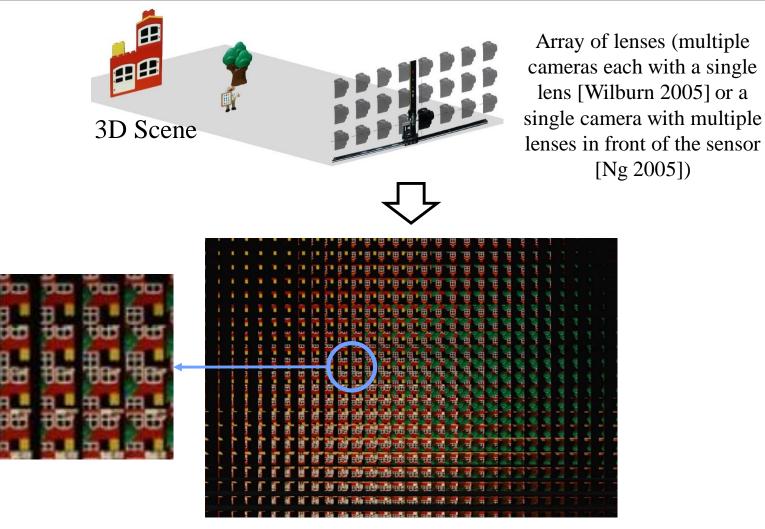
Reduction in resolution and brightness is still a problem.



It is possible to reproduce parallax, perspective shift and accommodation depth cues.

Images adapted from http://www.3d-forums.com/threads/autostereoscopic-displays.1/

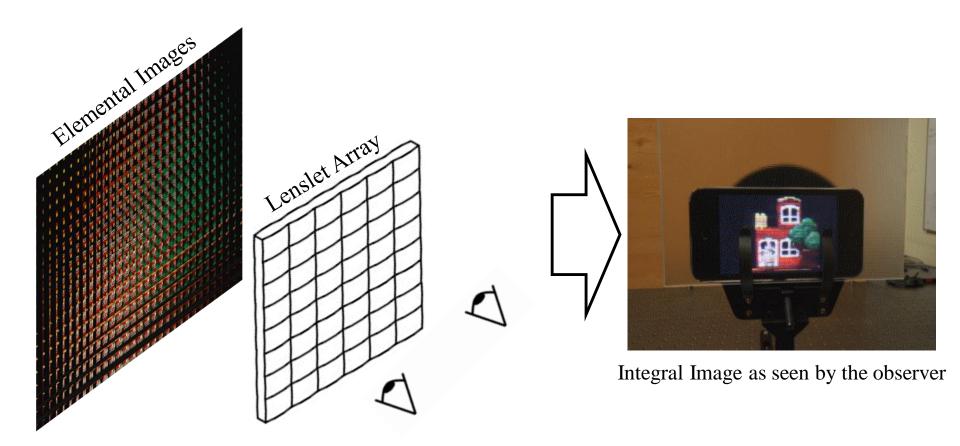
Integral Imaging



Elemental Images

Images adapted from Martinez-Corral, Manuel, et al. "3D integral imaging monitors with fully programmable display parameters."

Integral Imaging



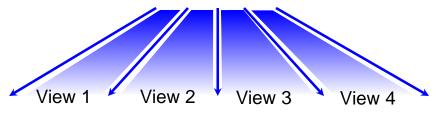
Images adapted from Martinez-Corral, Manuel, et al. "3D integral imaging monitors with fully programmable display parameters."

Multi-view Autostereoscopic Display

Smooth transitions

Multi-view autostereoscopic display





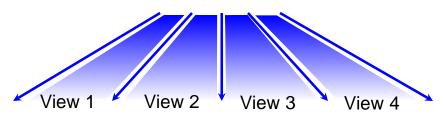
"Antialiasing for automultiscopic 3D displays" [Zwicker et al. 2006]

Multi-view Autostereoscopic Display

- Smooth transitions
- Blur increases with depth

Multi-view autostereoscopic display





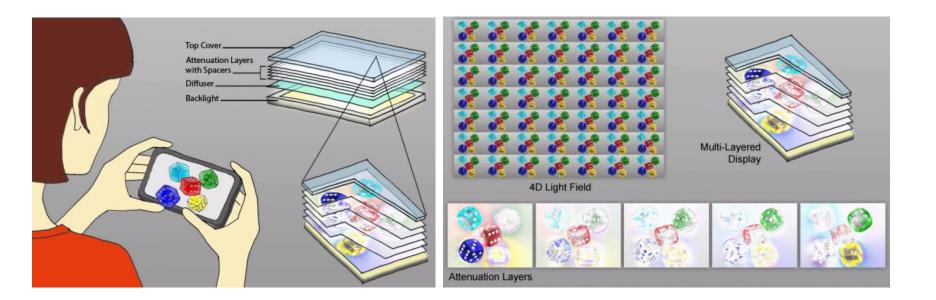


Weaker depth percept

"Antialiasing for automultiscopic 3D displays" [Zwicker et al. 2006]

Multi-layer Displays

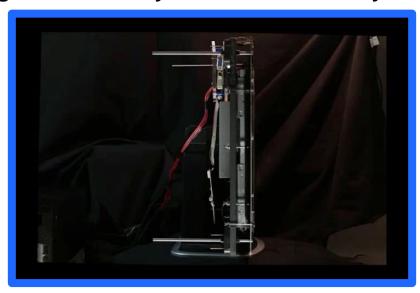
- Improved resolution over parallax barriers and lenslet arrays
- Provides a solution to accommodation-vergence conflict



Images adapted from Wetzstein, Gordon, et al. "Layered 3D: tomographic image synthesis for attenuation-based light field and high dynamic range displays." ACM Transactions on Graphics (ToG). Vol. 30. No. 4. ACM, 2011.

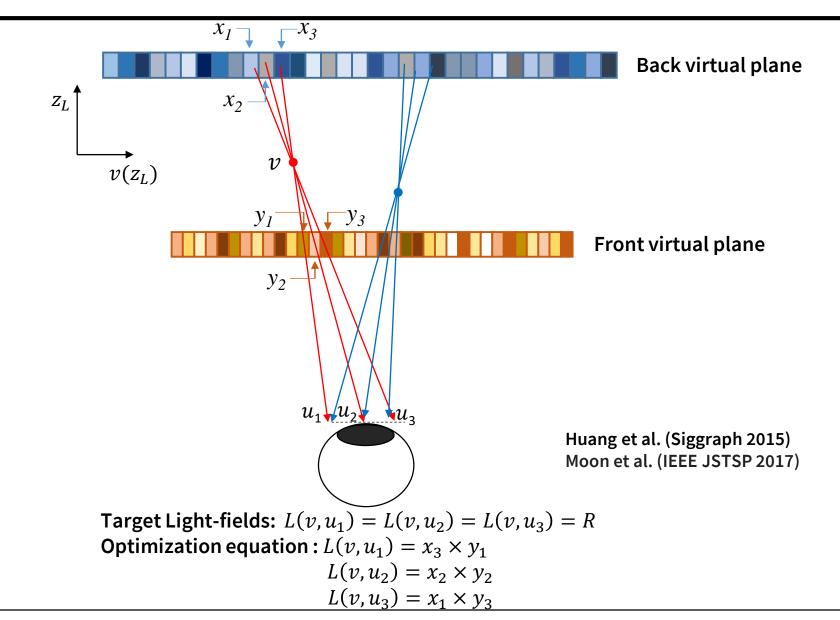
Tensor Displays

- Lightfield emitted by a multi-layer display is represented by a tensor where rays span a 2D plane in 3D tensor space
- Target lightfield is decomposed into Rank-1 tensors using Nonnegative Tensor
 Factorization
- Rank-1 tensors are shown in quick succession with a high refresh rate, which are perceptually averaged over time by the Human Visual System



Video adapted from Wetzstein, Gordon, et al. "Tensor displays: compressive light field synthesis using multilayer displays with directional backlighting." (2012).

Rendering images in Tensor Displays

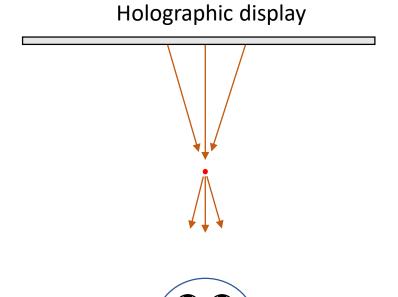


Lightfield Displays



Holographic display

Holographic display: generating 3D images in the air without any scatterer

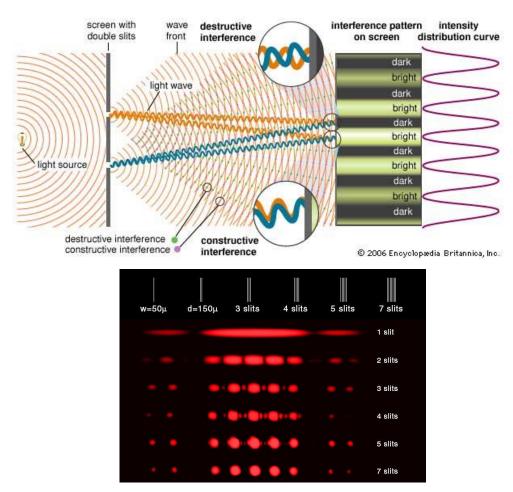






What is the meaning of "focusing the light"?

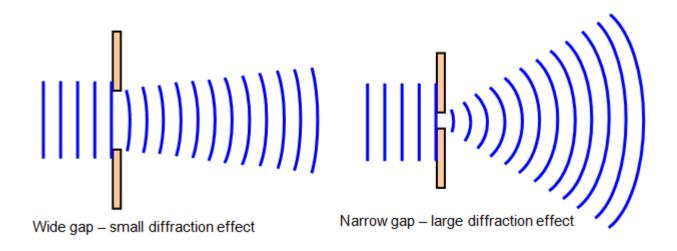
Focusing == interference



http://labman.phys.utk.edu/phys136

Focusing = constructive interference of multiple pixels (but it requires coherent light sources such as laser)

Smaller pixel size == Large diffraction angle

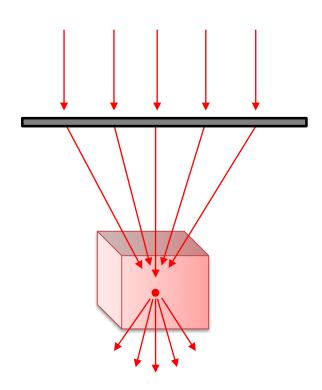


	Pixel size	Viewing angle	
LCD monitor	$200~\mu m$	0.1°	
LCoS Spatial light modulator	16 μm	2°	
Ideal pixel size	1 μm	30°	

http://www.schoolphysics.co.uk/age14-16/Wave%20properties/text/Diffraction /index.html

Ultimate 3D display: Holographic display

Ideal holographic monitor



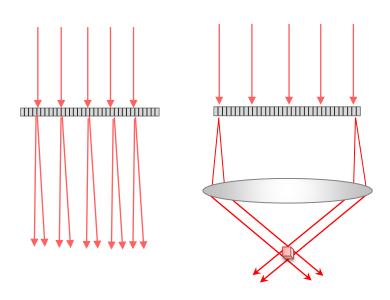
Pixel size : 1 μm

Screen size: 30 cm x 30 cm Resolution: 300000 x 300000

Viewing angle: 30°

Image size: 30 cm x 30 cm

Current holographic monitor



Pixel size : 16 μm

Screen size: 1 cm x 1 cm Resolution: 1024 x 768

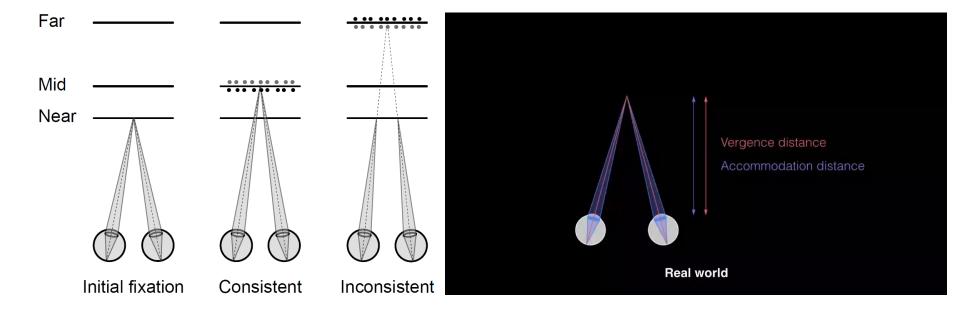
Viewing angle: 2°

Image size: 1 cm x 1 cm

Displays Comparison

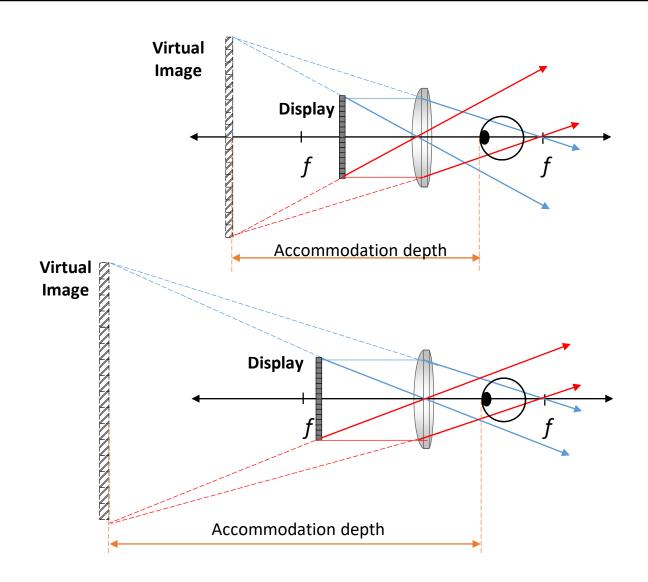
	Pictorial Cues	Disparity	Motion Parallax	Glasses-free	Accommodation
2D Display	V	X	X	V	X
Stereoscopic Display		V	X	X	X
Head-mounted Display	V	V	V	X	X
Autostereoscopic Display	V	V	V	V	X
Light field Display	V	V	V	V	V
Holographic Display	V	V	V	V	V

Accomodation-Vergence Conflict

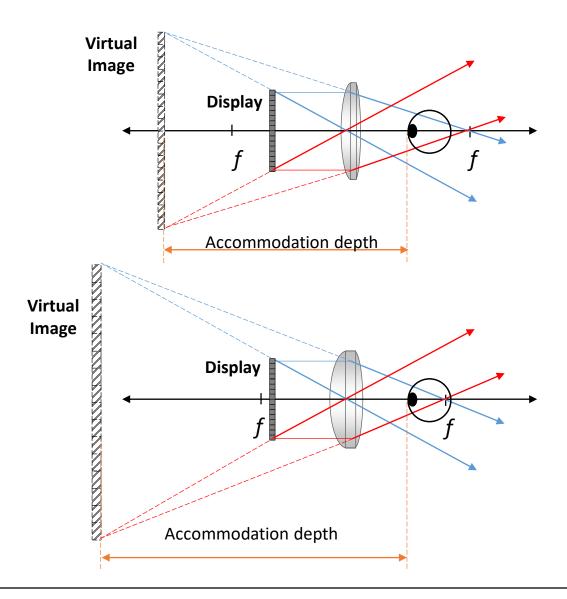


Visuals adapted from Akeley, Kurt, et al. "A stereo display prototype with multiple focal distances." ACM transactions on graphics (TOG). Vol. 23. No. 3. ACM, 2004. and Narain, Rahul, et al. "Optimal presentation of imagery with focus cues on multi-plane displays." ACM Transactions on Graphics (TOG) 34.4 (2015): 59.

How to change accommodation? : (1) the display position

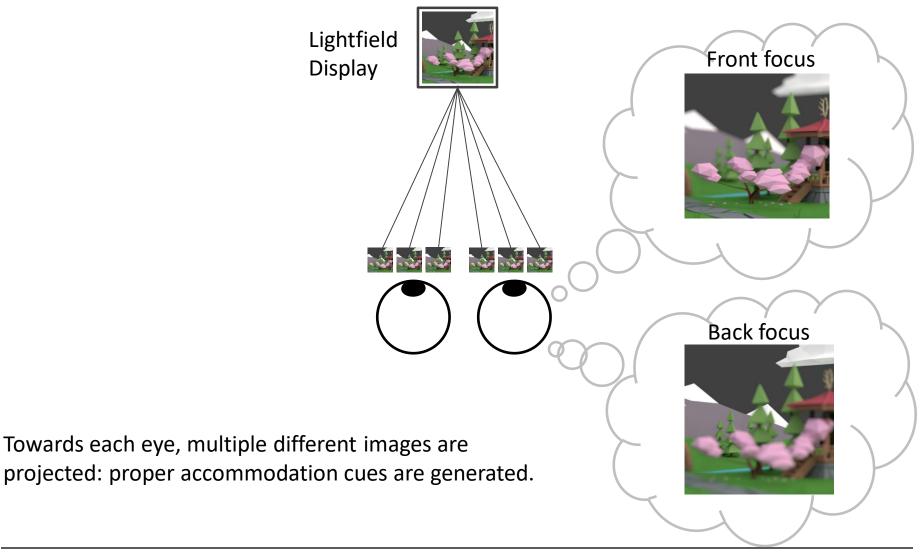


How to change accommodation? : (2) the lens focal length



Requirement for supporting accommodation

High angular resolution or dense light fields: Accommodation

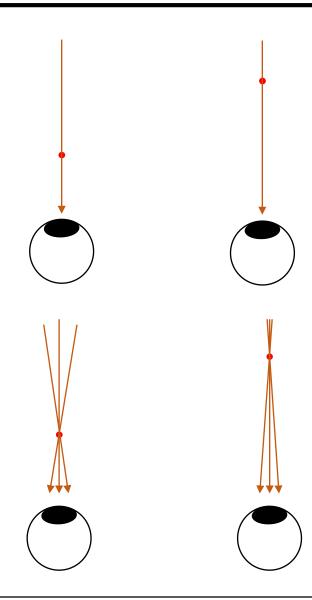


Requirement for supporting accommodation

Single ray is not enough (depth ambiguity)

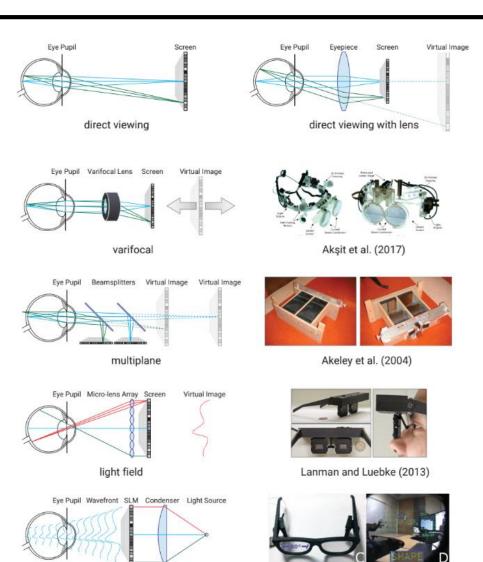
Mathematically, minimum two rays should be projected inside the pupil In practice,

3 rays for 1-D 3 x 3 rays for 2-D



HMD with accommodation cues

- Varifocal display
- Multi-focal displays
- Light field displays
- Holographic displays



holographic

Maimone et al. (2017)

Varifocal display: Deformable Beamsplitter



See-through

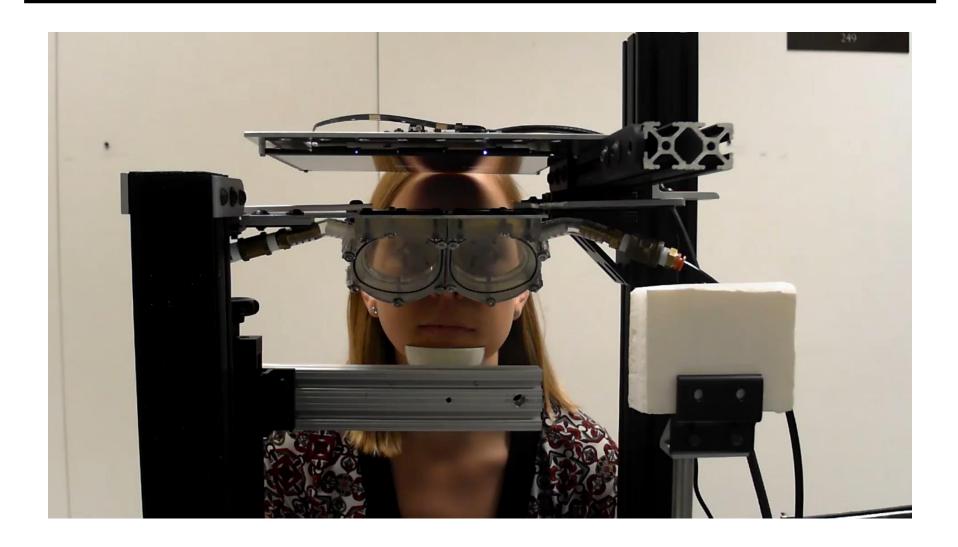
Dynamic focal depth: objects at any depth

Wide field of view

Optics are simple



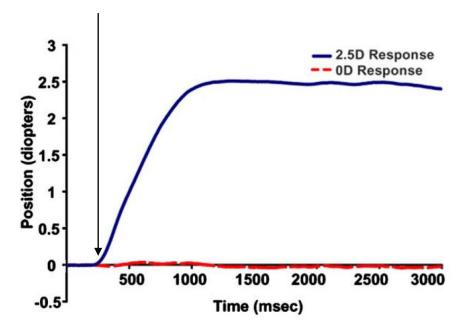
Varifocal display: Deformable Beamsplitter





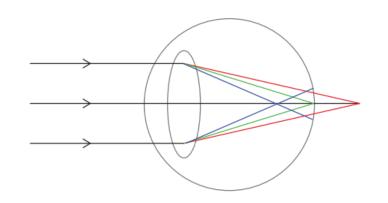
Accommodation Response

- Step change of fixated object depth
 - Smooth and steady accommodation increase
 - up to 1 second to achieve the full accommodation state
 - ~300 ms latency



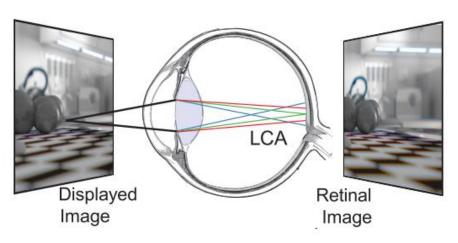
Bharadwaj and Schor, Vision Research 2004

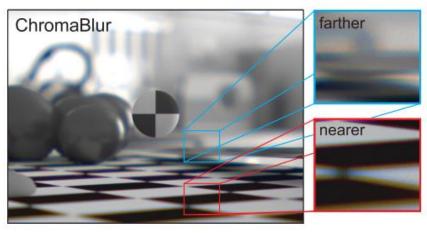
Rendering Chromatic Eye Aberration



$$D(\lambda) = 1.731 - \frac{633.46}{\lambda - 214.10}$$

Short wavelengths (blue) are refracted more than long (red). Medium wavelengths are generally in best focus for broadband lights.



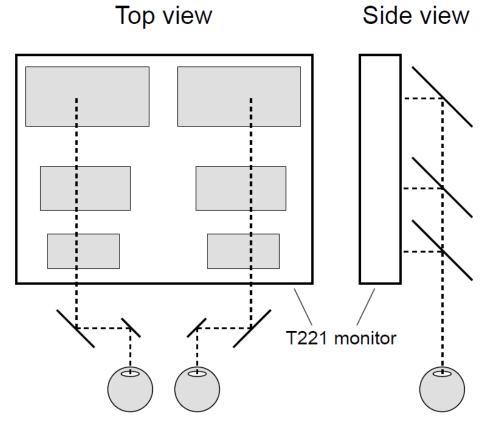


Rendering chromatic blur can provide accommodation effect (but not fully) and improve the realism

CHOLEWIAK ET AL, 2017. ChromaBlur: Rendering Chromatic Eye Aberration Improves Accommodation and Realism in HMDs. Siggraph

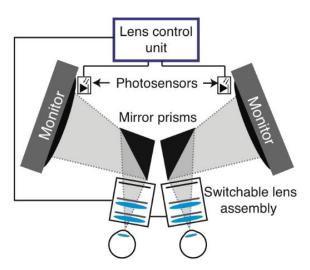
Multi-focal Plane Displays

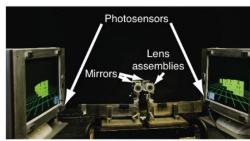
 A display prototype with multiple focal distances using beam-splitters



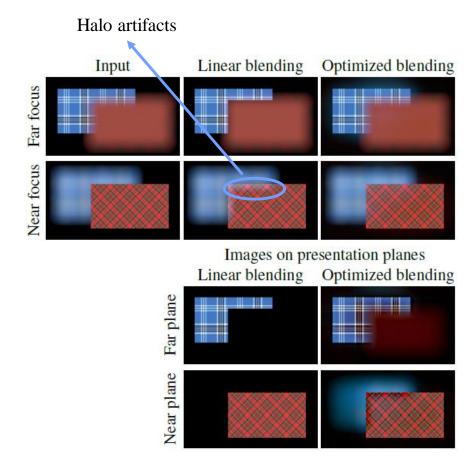
Images adapted from Akeley, Kurt, et al. "A stereo display prototype with multiple focal distances." ACM transactions on graphics (TOG). Vol. 23. No. 3. ACM, 2004.

Multi-focal Plane Displays





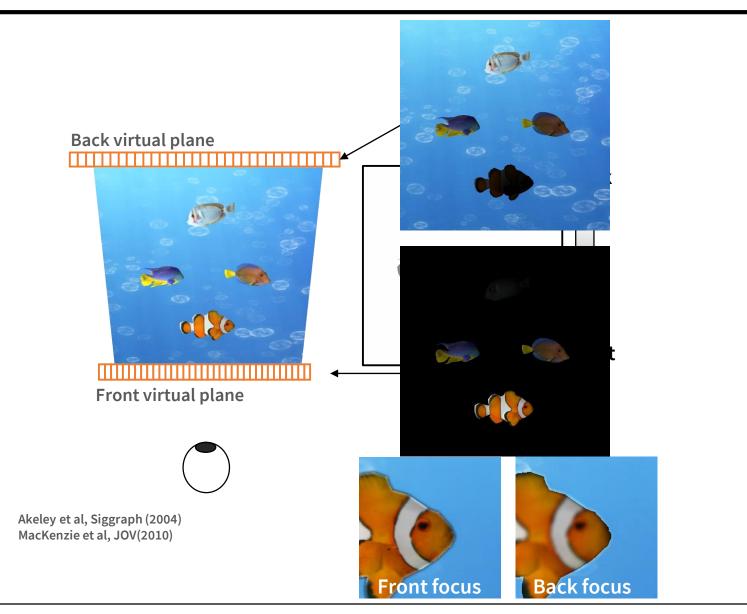
Prototype introduced by Love et al [2009]



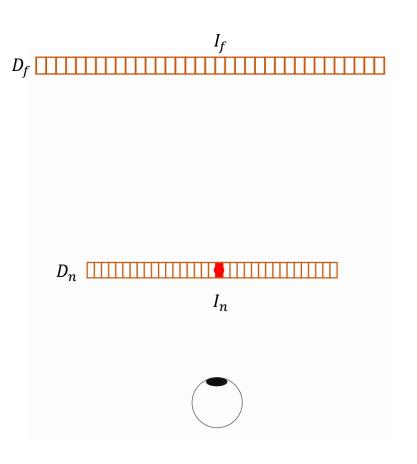
Narain et al. [2015] optimize the focus cues for improved realism.

Images adapted from Narain, Rahul, et al. "Optimal presentation of imagery with focus cues on multi-plane displays." ACM Transactions on Graphics (TOG) 34.4 (2015): 59.

Rendering for multi plane displays: (1) linear Blending Rule



Rendering for multi plane displays: (1) linear Blending Rule

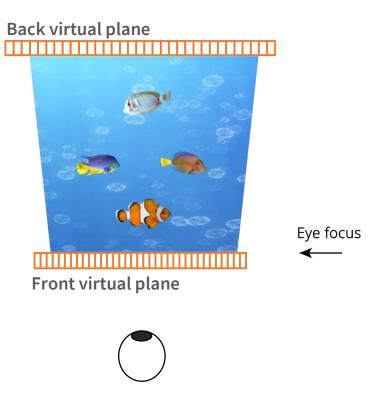


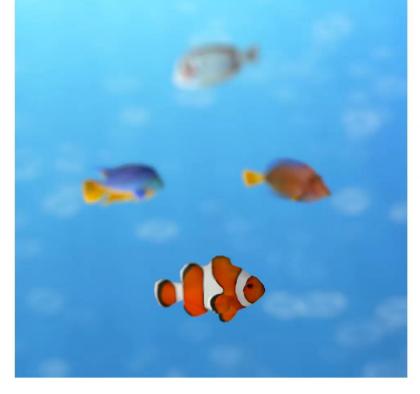
$$I_n = \left[1 - \frac{(D_n - D_s)}{(D_n - D_f)}\right] I_s \qquad I_f = \left[\frac{(D_n - D_s)}{(D_n - D_f)}\right] I_s.$$

Akeley et al, Siggraph (2004) MacKenzie et al, JOV(2010)

Rendering for multi plane displays: (2) Retinal Optimization

Optimization objective





Narain et al (Siggraph 2015) Mercier et al (Siggraph Asia 2017

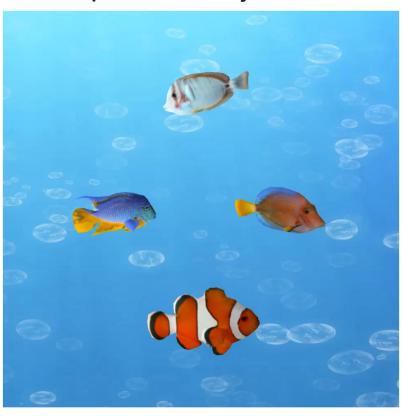
A focal stack

Rendering for multi plane displays: (3) Light field synthesis

Back virtual plane Front virtual plane Viewpoint

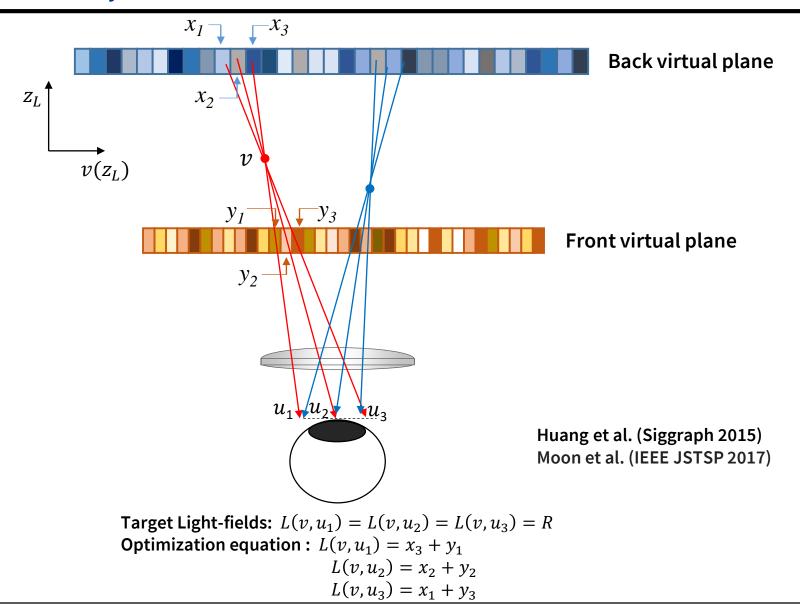
Huang et al. (Siggraph2015) Moon et al. (IEEE JSTSP 2017)

Optimization objective



Light field

Rendering for multi plane displays (3) Light field synthesis



Comparison

	Initial input	Optimization Algorithm	Occlusion & Non-Lambertian surfaces
Linear Blending [1]	Single image + depth map	Fast	Incorrect
Retinal Optimization [2,3]	Focal stack	Slow	Correct
Light-field synthesis [4]	Light field	Slow	Correct
Ours	Sparse light field	Fast	Correct

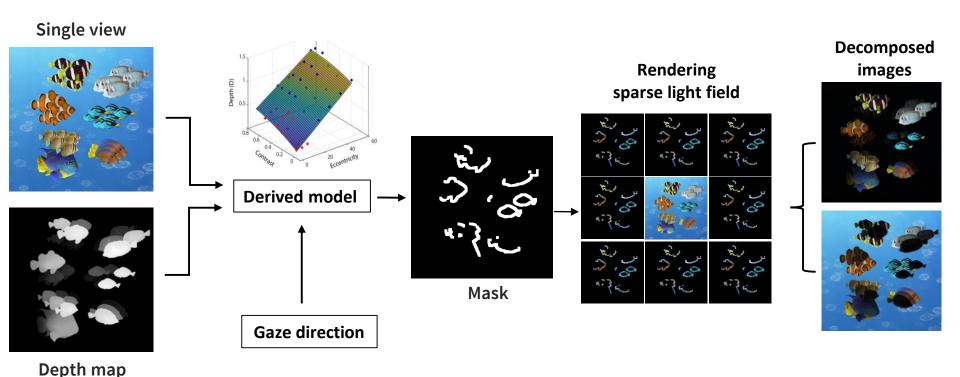
^[1] Akeley et al, Siggraph (2014)

^[2] Narain et al (Siggraph 2015)

^[3] Mercier et al, Siggraph Asia (2017)

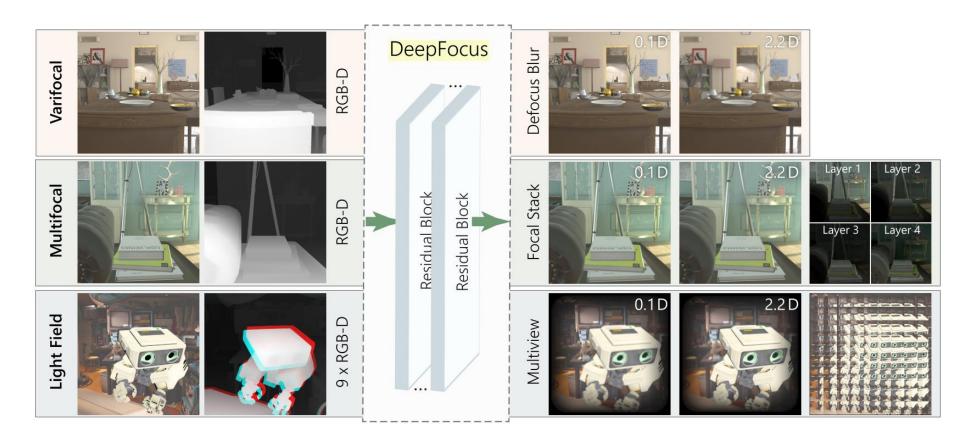
^[4] Moon et al, IEEE JSTSP (2017)

Hybrid optimization



Yu et al, "A Perception-driven Hybrid Decomposition for Multi-layer Accommodative Displays" IEEE Transactions on Visualization and Computer Graphics (2019)

Deep learning solution for various displays



XIAO ET AL, 2018. DeepFocus: Learned Image Synthesis for Accommodation-Supporting Displays. *Siggraph Asia*

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- Yu et al, "A Perception-driven Hybrid Decomposition for Multi-layer Accommodative Displays" IEEE Transactions on Visualization and Computer Graphics (2019)