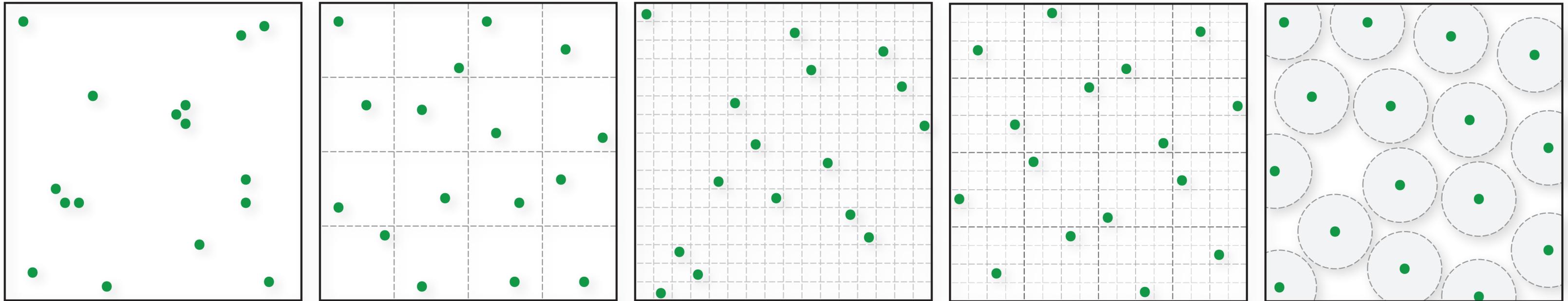


# ADVANCED SAMPLING



*Philipp Slusallek*   *Karol Myszkowski*  
Gurprit Singh

# Part of Siggraph 2016 Course

Fourier Analysis of Numerical Integration in Monte Carlo Rendering

Kartic Subr

Gurprit Singh

\*Wojciech Jarosz

Render the Possibilities  
**SIGGRAPH**2016



\*First part slides are from Wojciech Jarosz

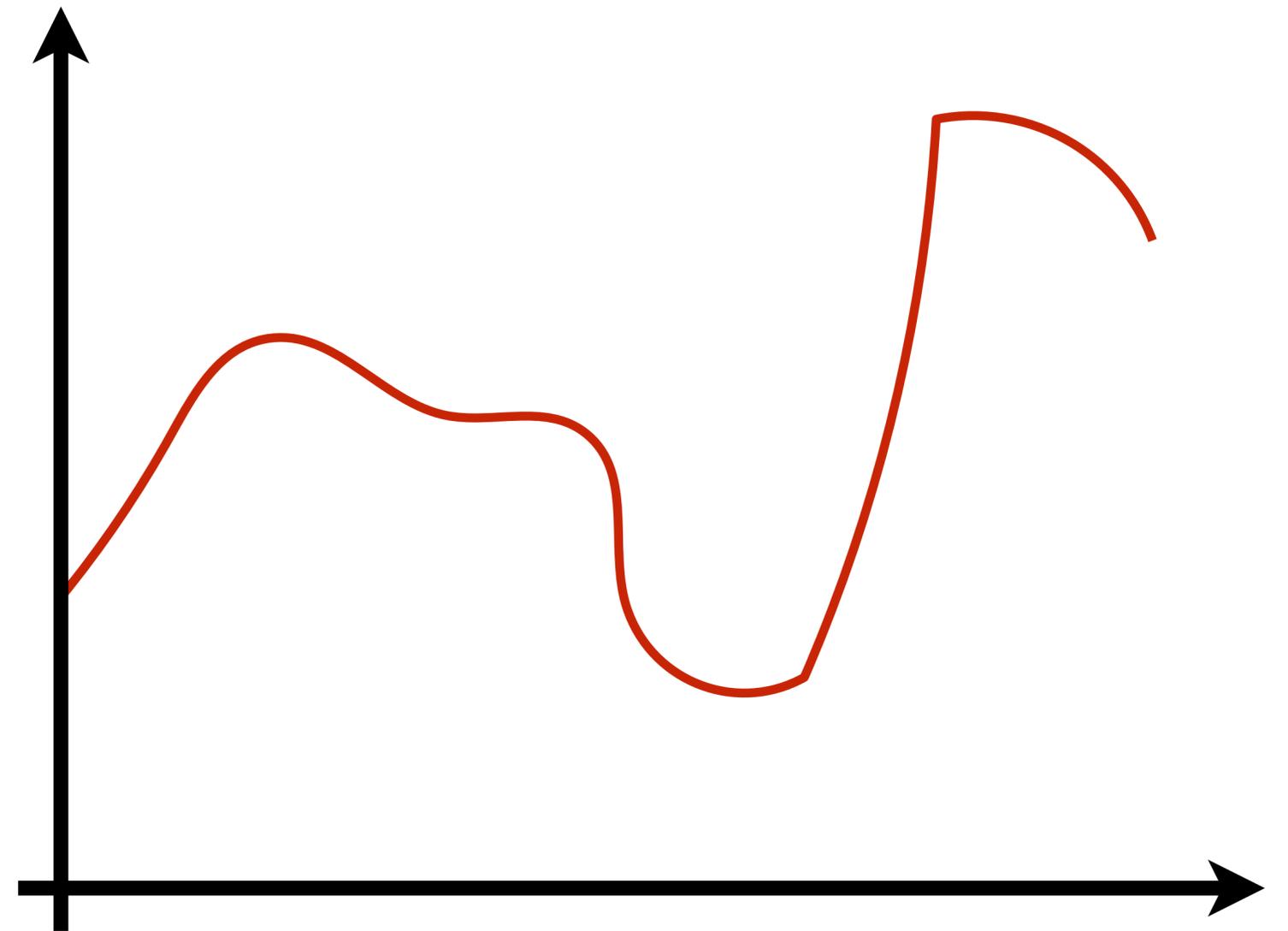
# Recall: Monte Carlo Integration

$$I = \int_D f(x) dx$$



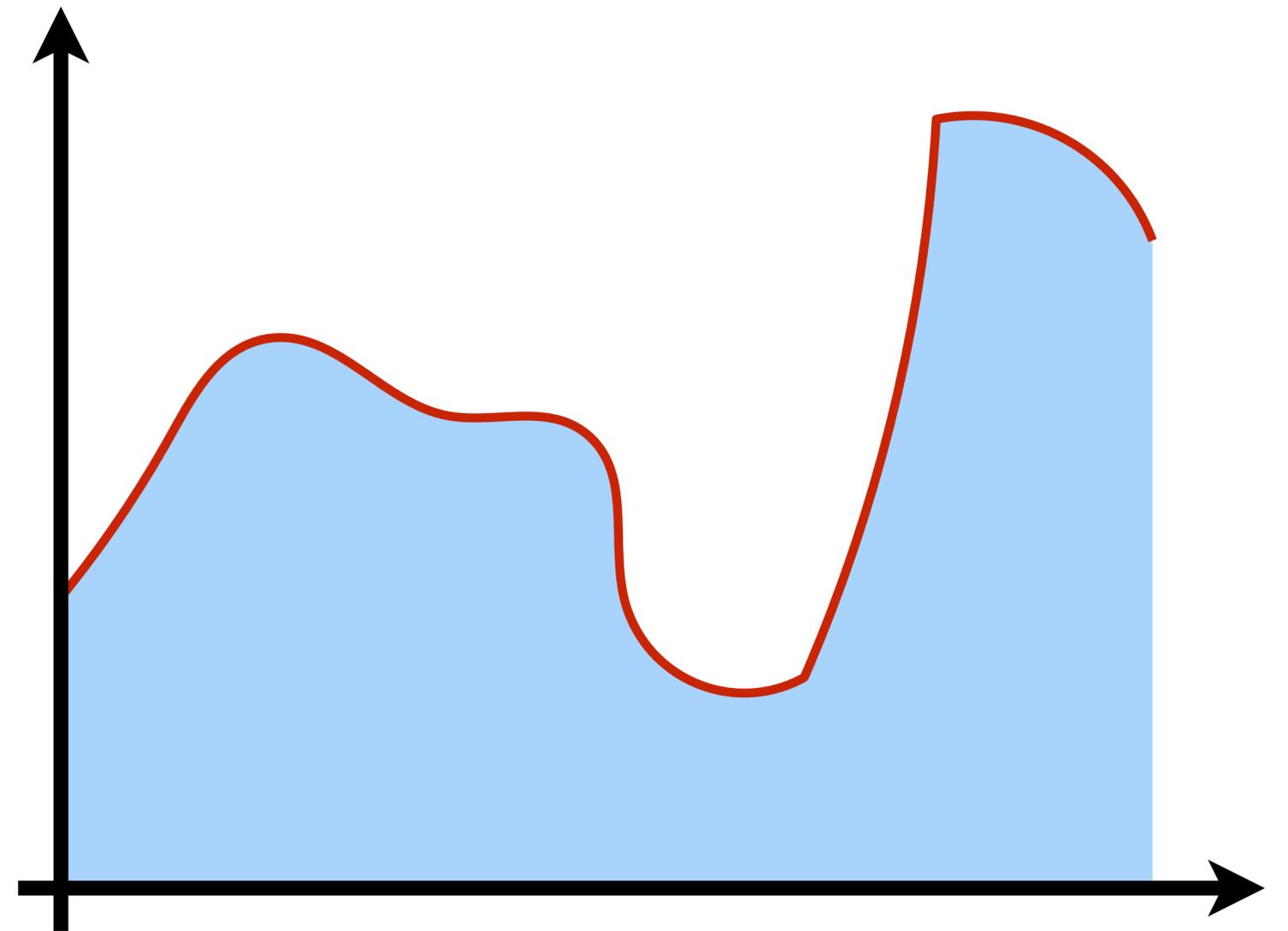
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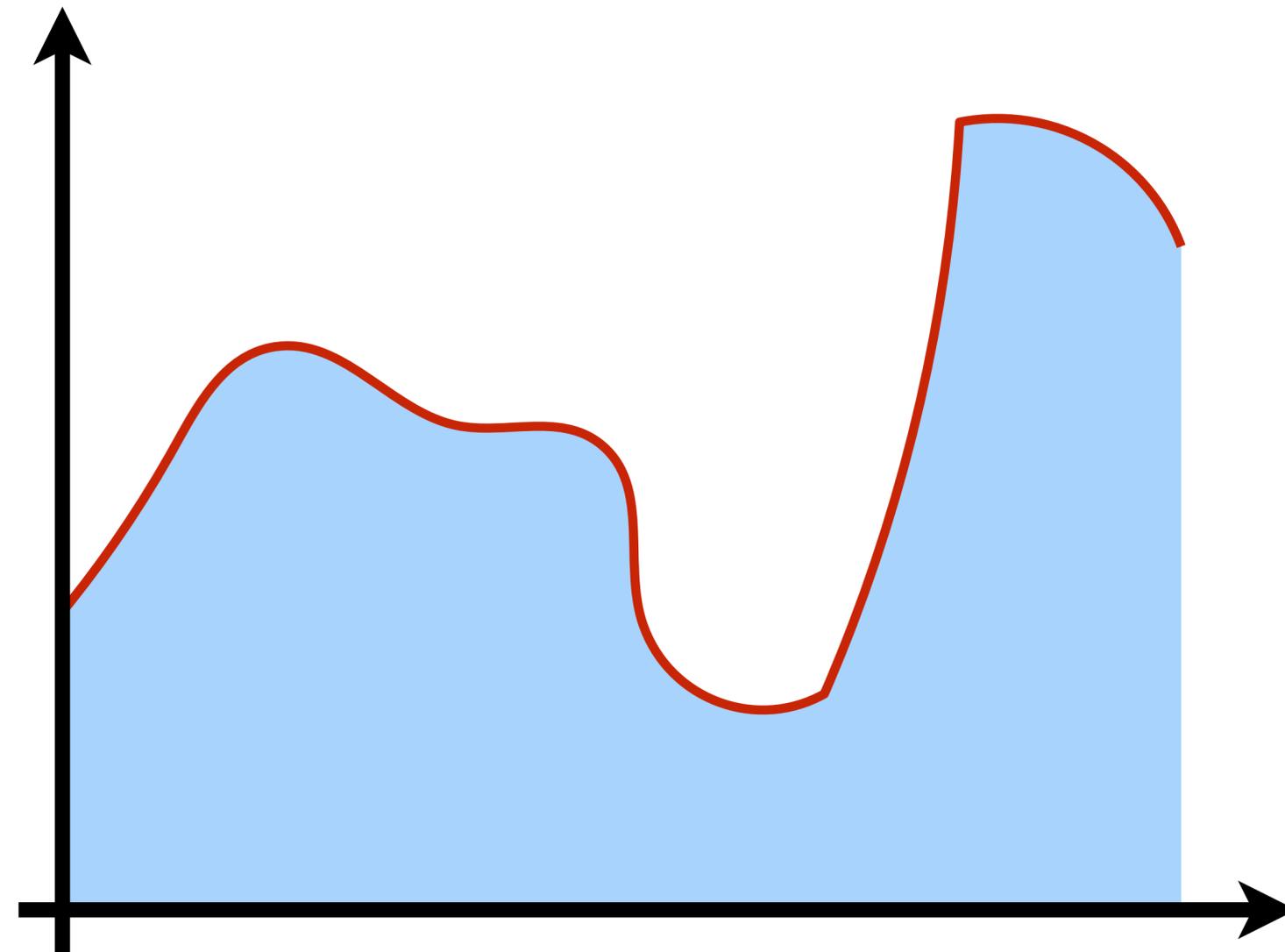
# Recall: Monte Carlo Integration

$$I = \int_D f(x) dx$$



# Recall: Monte Carlo Integration

$$I = \int_D f(x) dx$$
$$\approx \int_D f(x) \mathbf{S}(x) dx$$

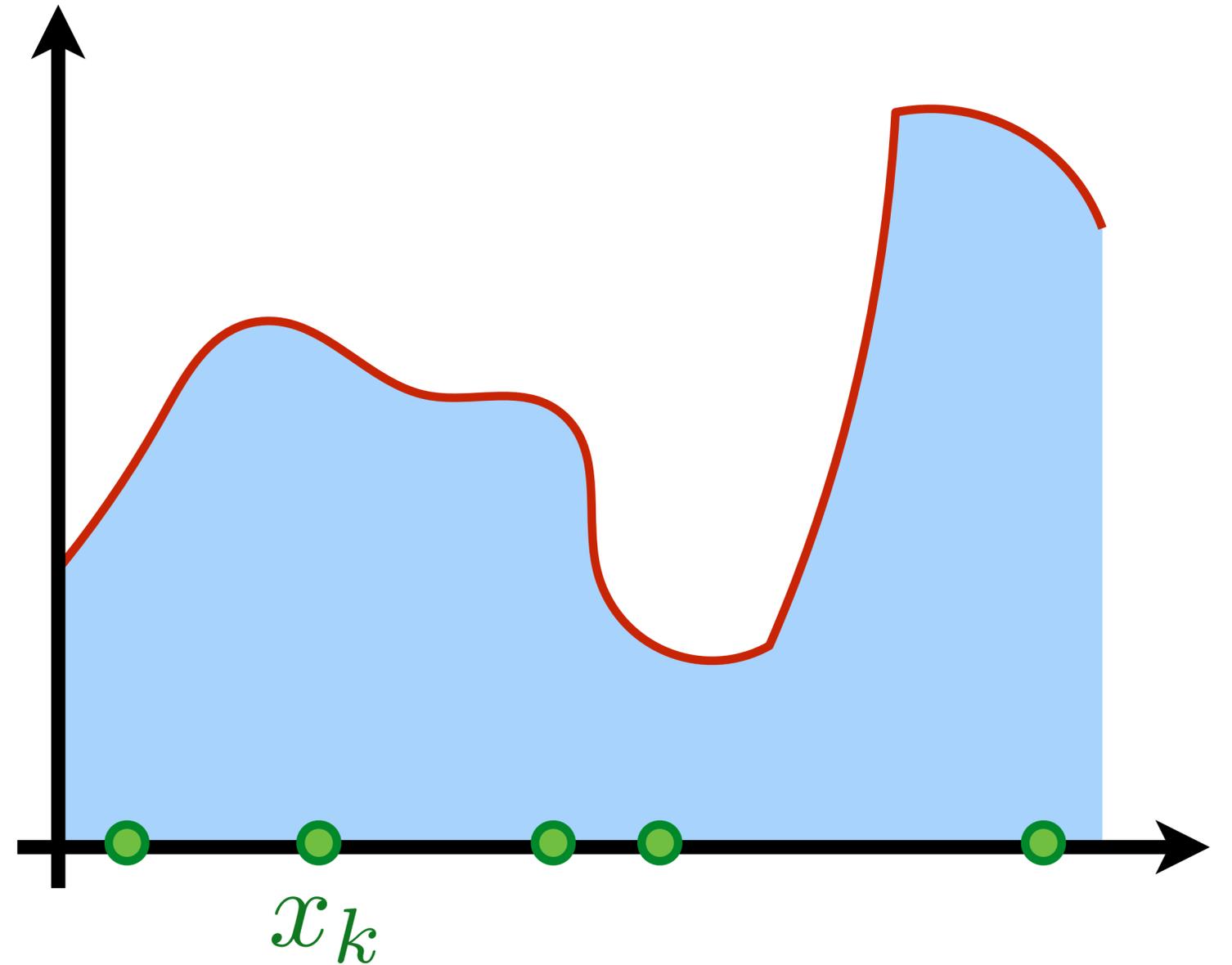


# Recall: Monte Carlo Integration

$$I = \int_D f(x) dx$$

$$\approx \int_D f(x) \mathbf{S}(x) dx$$

$$\mathbf{S}(x) = \frac{1}{N} \sum_{k=1}^N \delta(x - x_k)$$

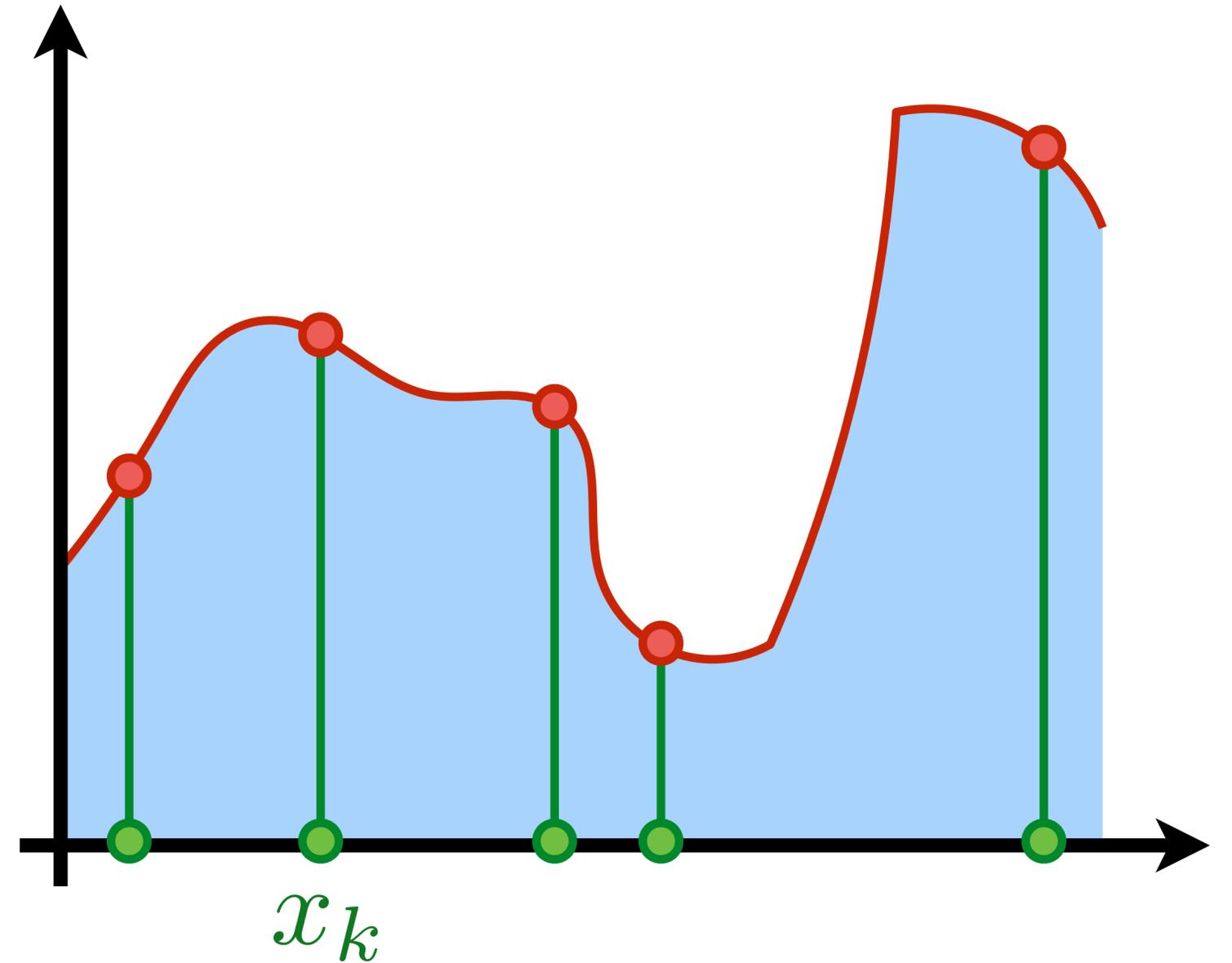


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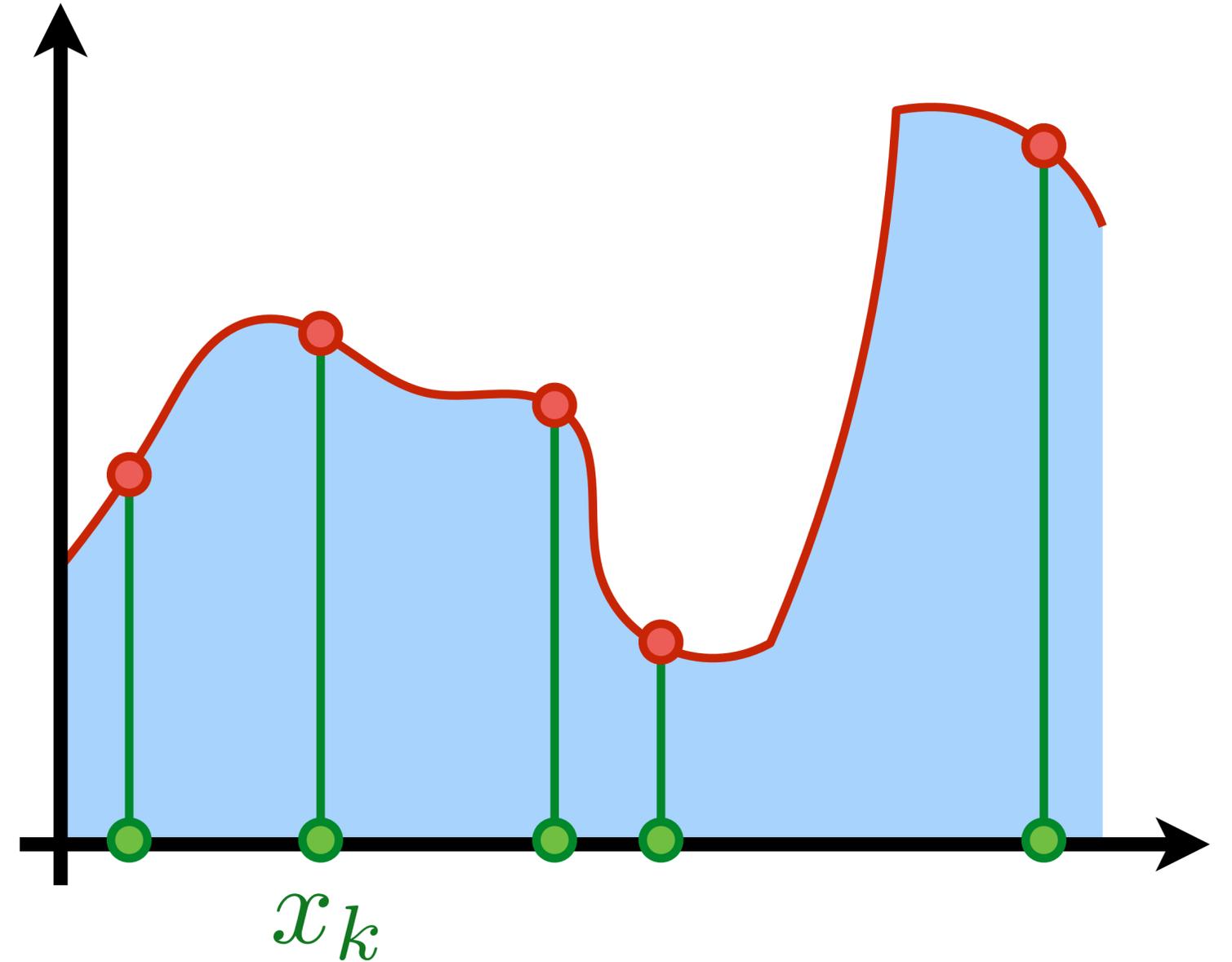
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$$\approx \int_D f(x) \mathbf{S}(x) dx$$

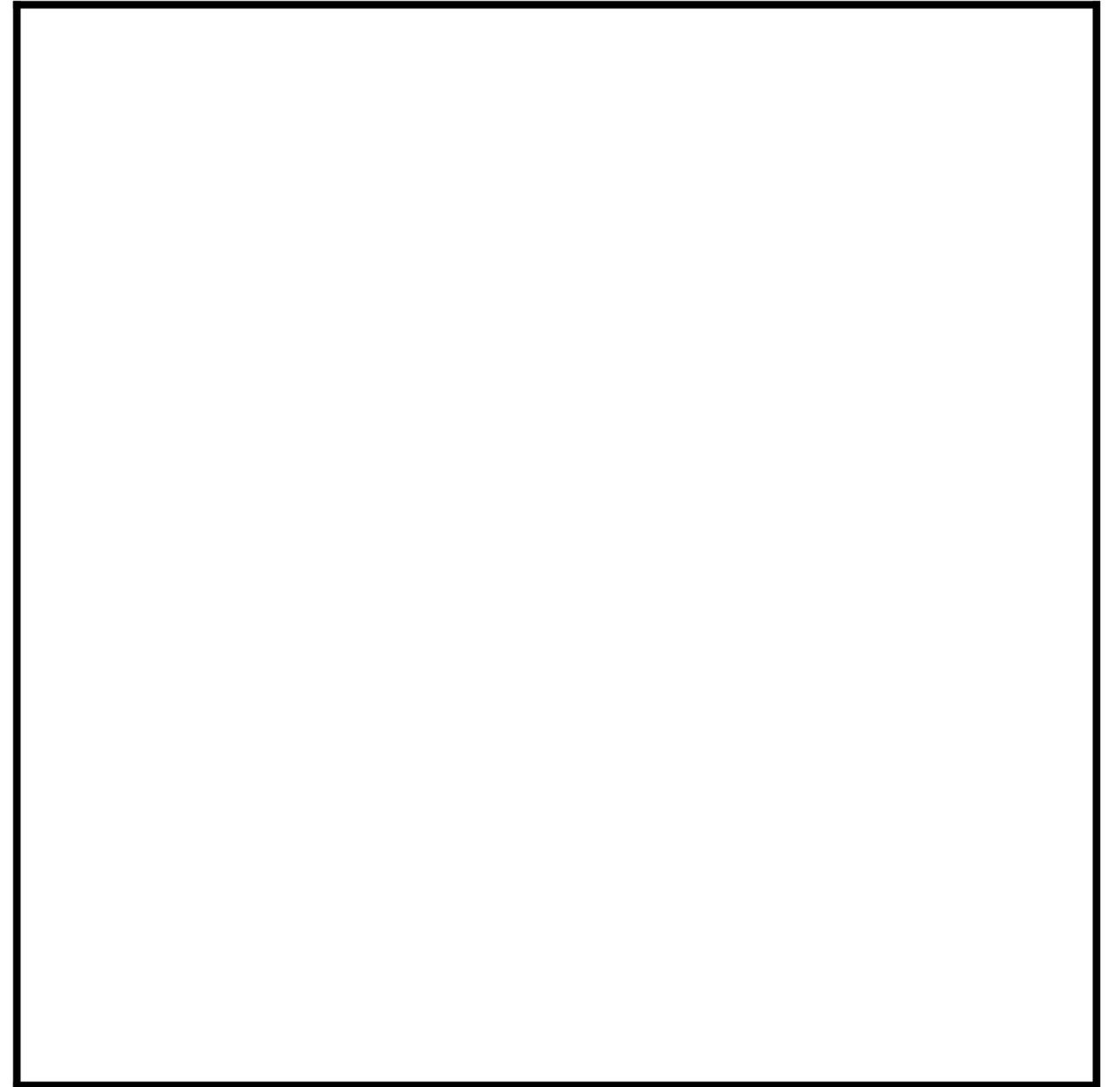
$$\mathbf{S}(x) = \frac{1}{N} \sum_{k=1}^N \delta(x - x_k)$$

How to generate the locations  $x_k$ ?



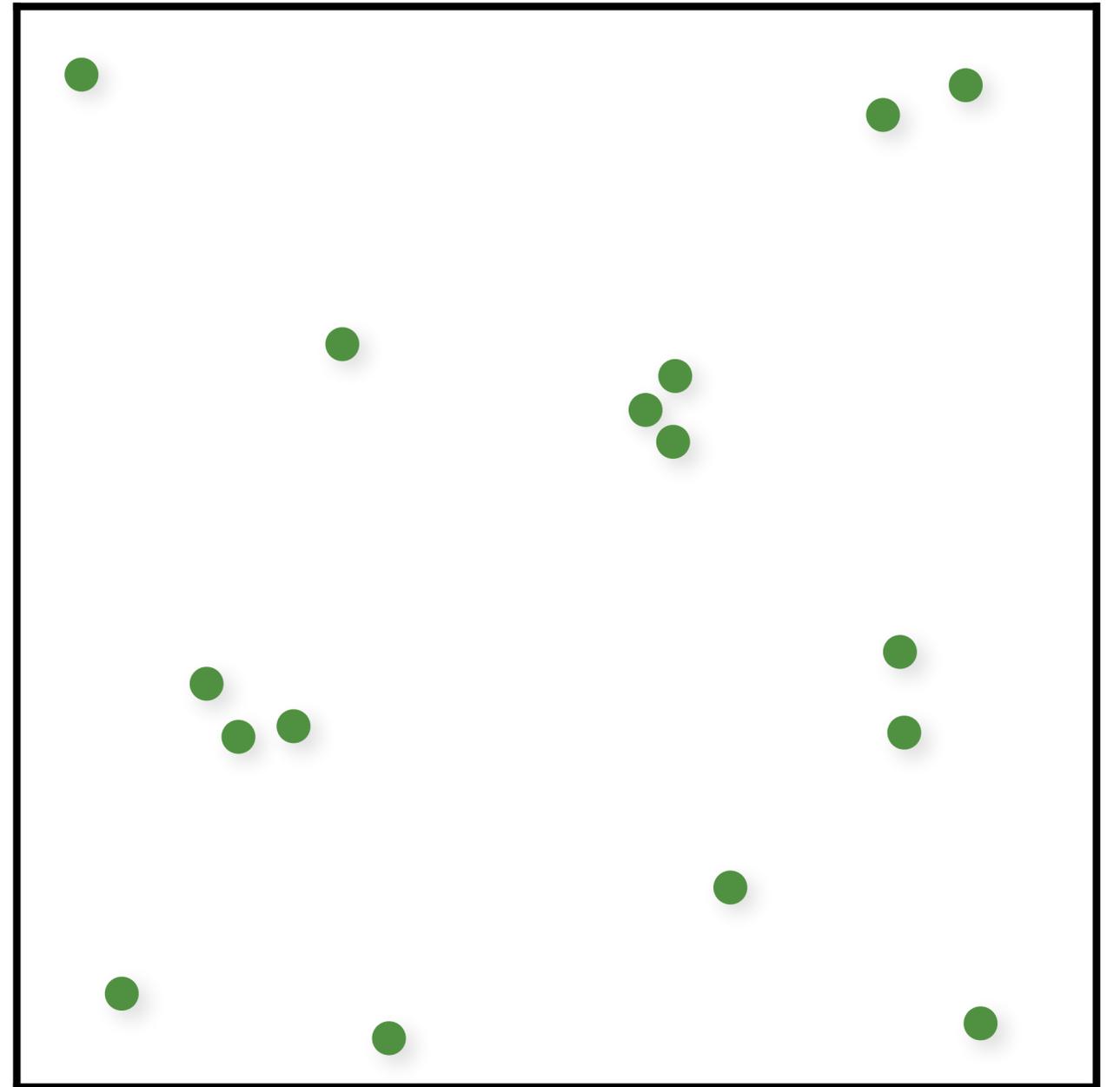
# Independent Random Sampling

```
for (int k = 0; k < num; k++)  
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    samples(k).x = randf();  
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# Independent Random Sampling

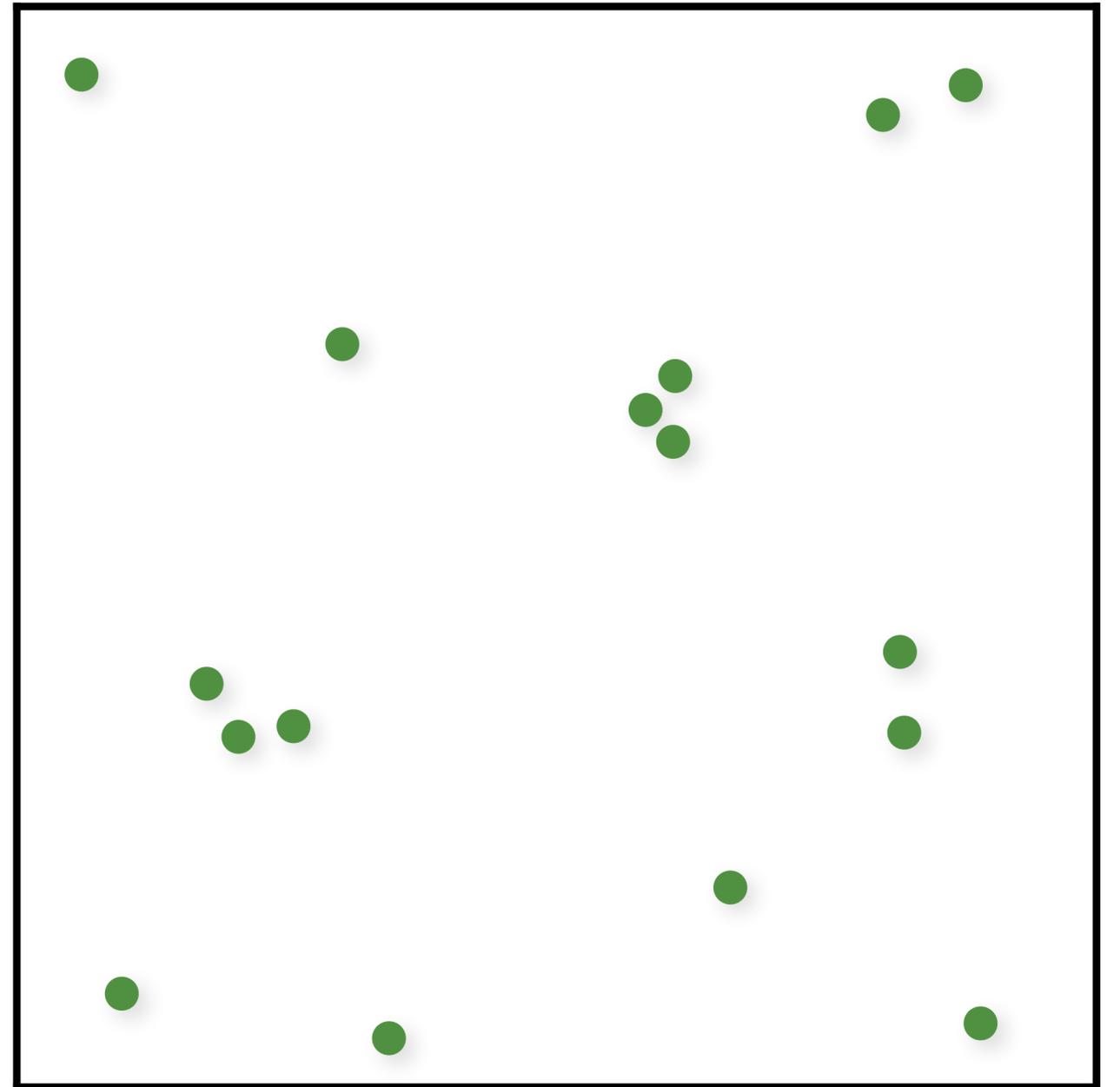
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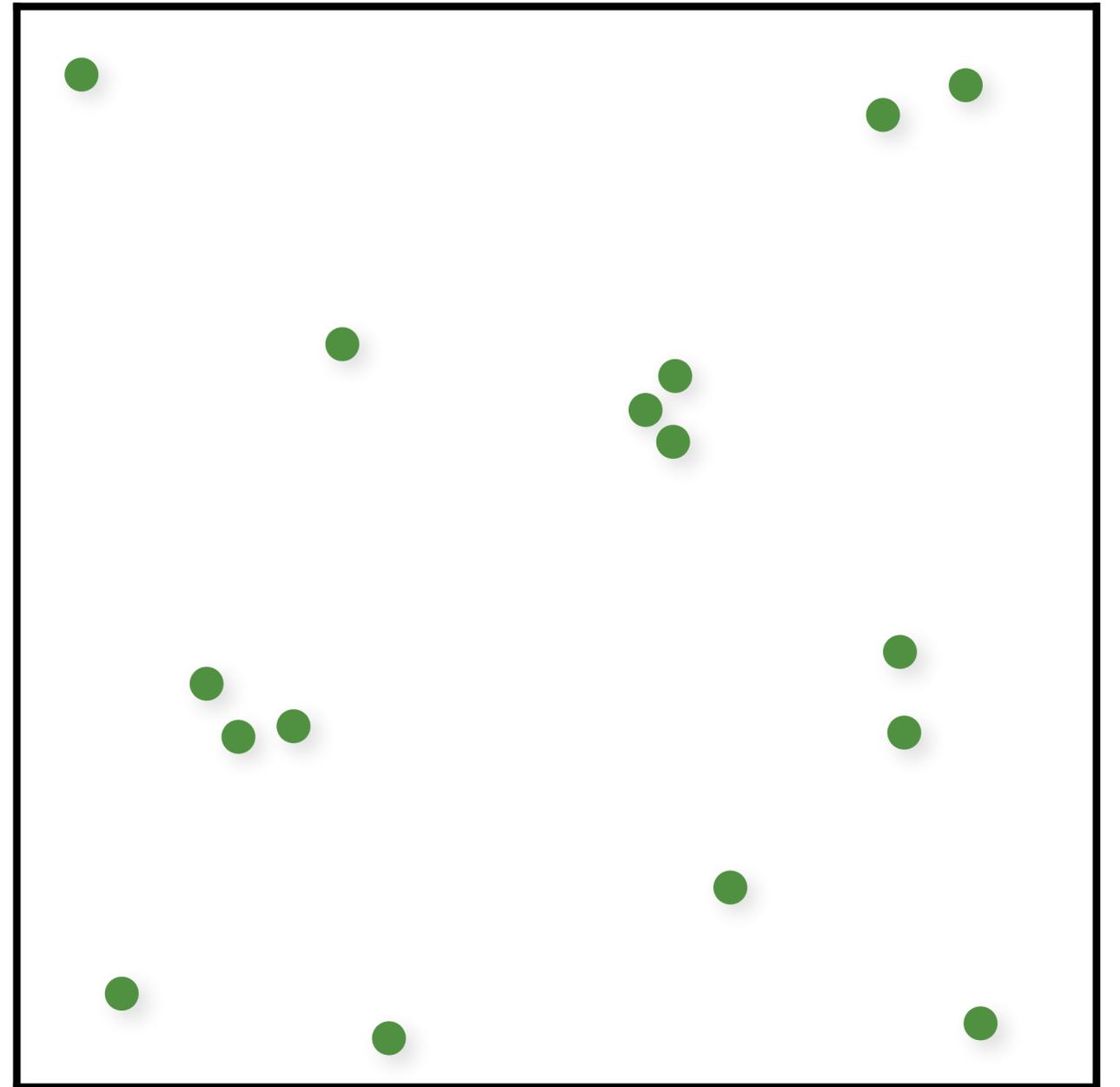
✓ Trivially extends to higher dimensions



# Independent Random Sampling

```
for (int k = 0; k < num; k++)  
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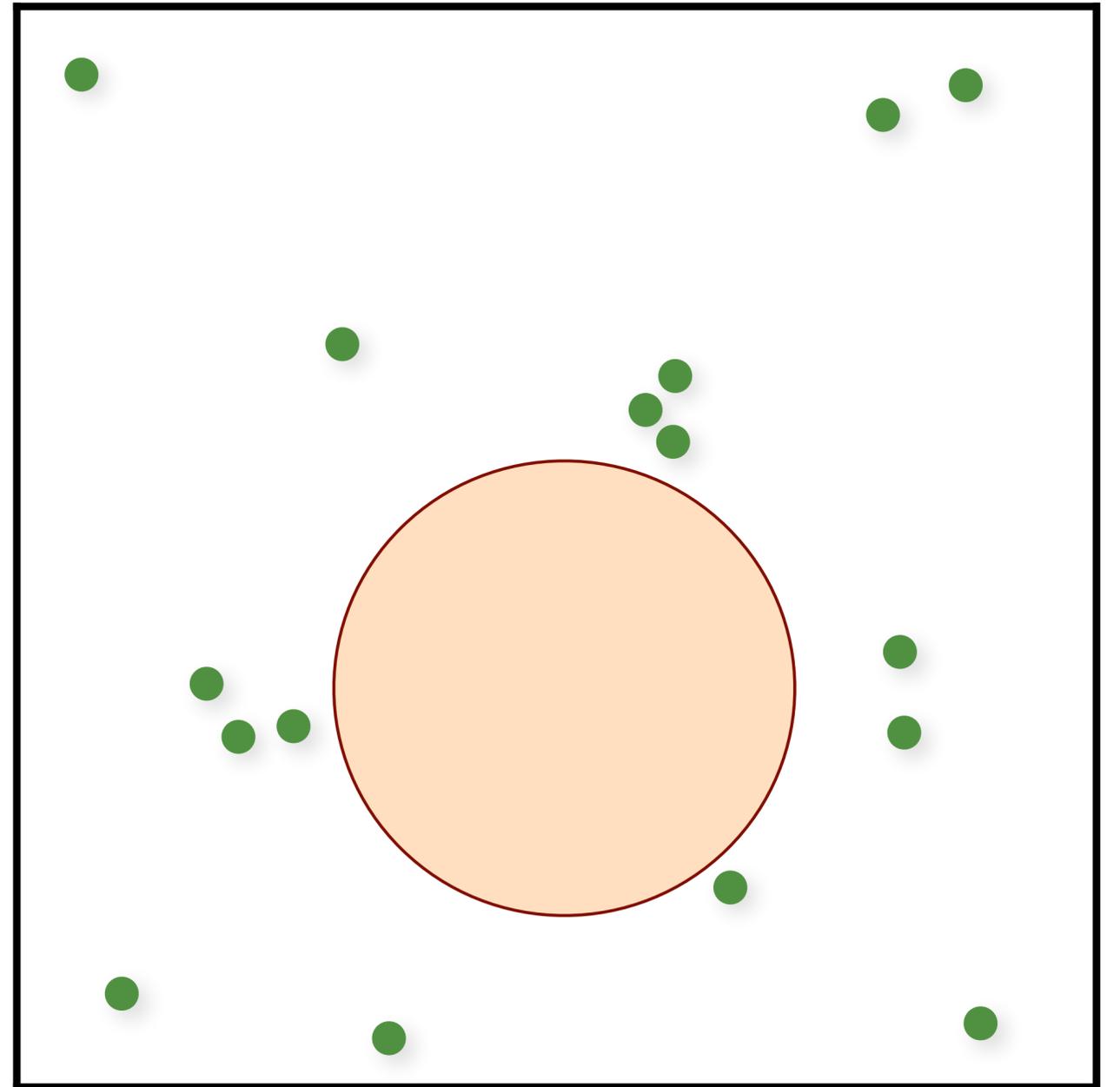
- ✓ Trivially extends to higher dimensions
- ✓ Trivially progressive and memory-less



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- ✓ Trivially progressive and memory-less
- ✗ Big gaps



# Independent Random Sampling

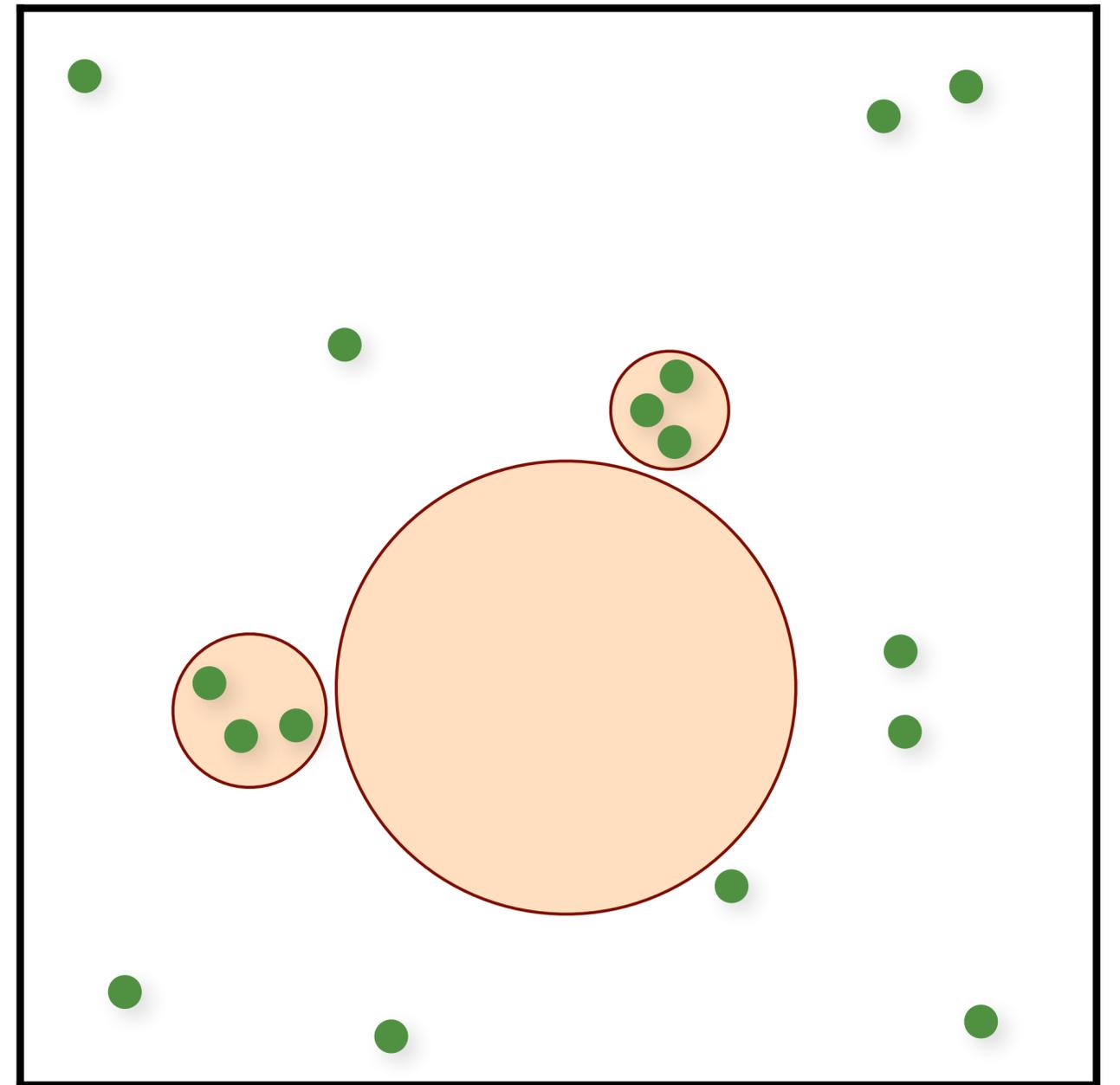
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}
```

✓ Trivially extends to higher dimensions

✓ Trivially progressive and memory-less

✗ Big gaps

✗ Clumping



# Recall: Fourier theory

---

Fourier transform:  $\hat{f}(\omega) = \int_D f(x) e^{-2\pi i \omega x} dx$

# Recall: Fourier theory

---

Fourier transform:  $\hat{f}(\vec{\omega}) = \int_D f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$

# Recall: Fourier theory

Fourier transform:  $\hat{f}(\vec{\omega}) = \int_D f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$

Sampling function:  $\hat{\mathbf{S}}(\vec{\omega}) = \int_D \mathbf{S}(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$

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Fourier transform:  $\hat{f}(\vec{\omega}) = \int_D f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$

Sampling function:  $\hat{S}(\vec{\omega}) = \int_D \frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$

# Recall: Fourier theory

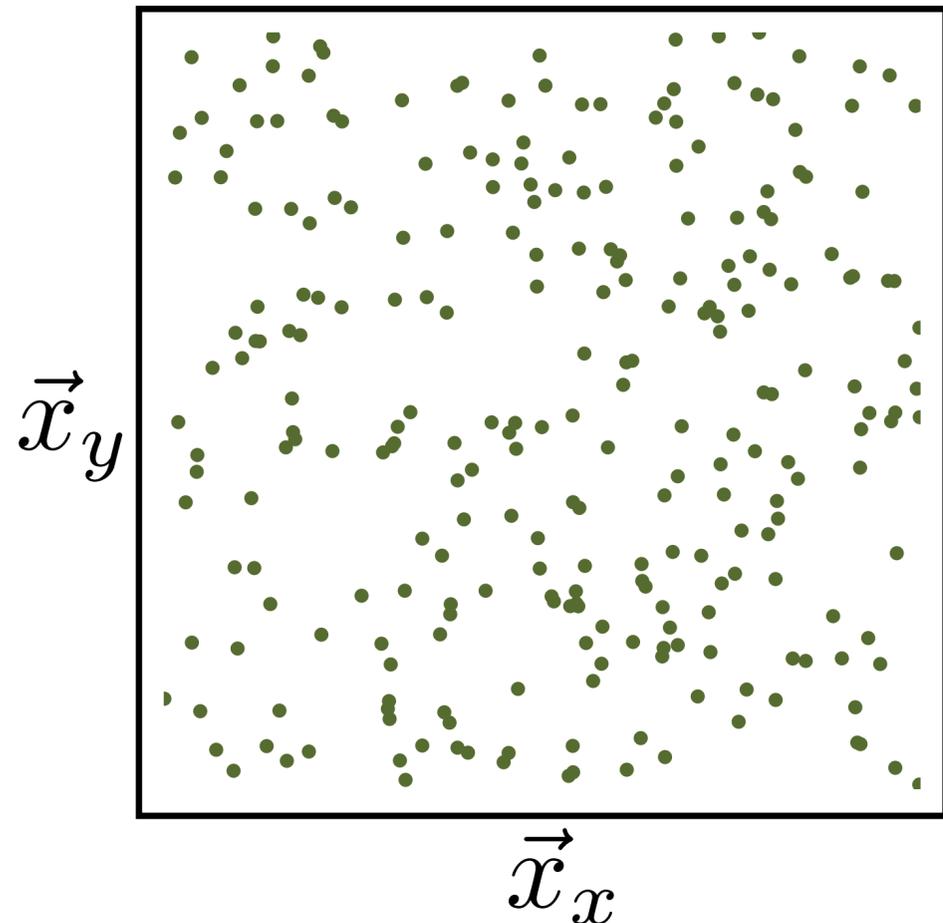
Fourier transform:  $\hat{f}(\vec{\omega}) = \int_D f(\vec{x}) e^{-2\pi i (\vec{\omega} \cdot \vec{x})} d\vec{x}$

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$$= \frac{1}{N} \sum_{k=1}^N e^{-2\pi i (\vec{\omega} \cdot \vec{x}_k)}$$

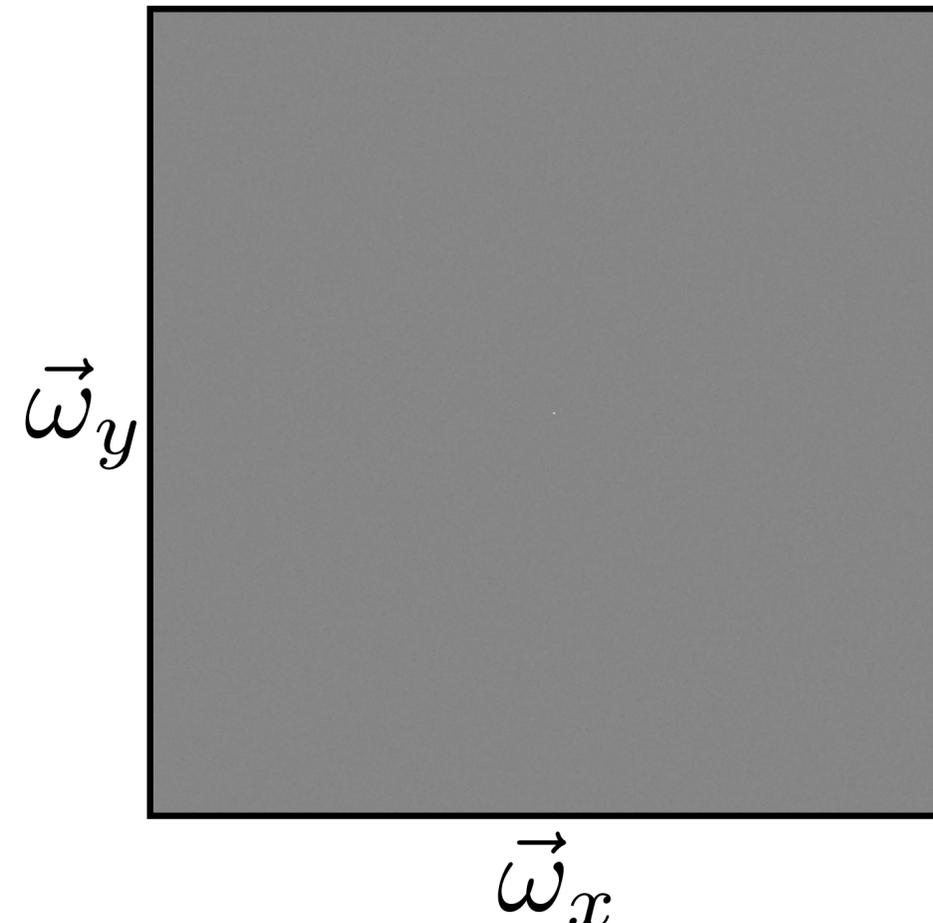
# Independent Random Sampling

Samples



$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|)$$

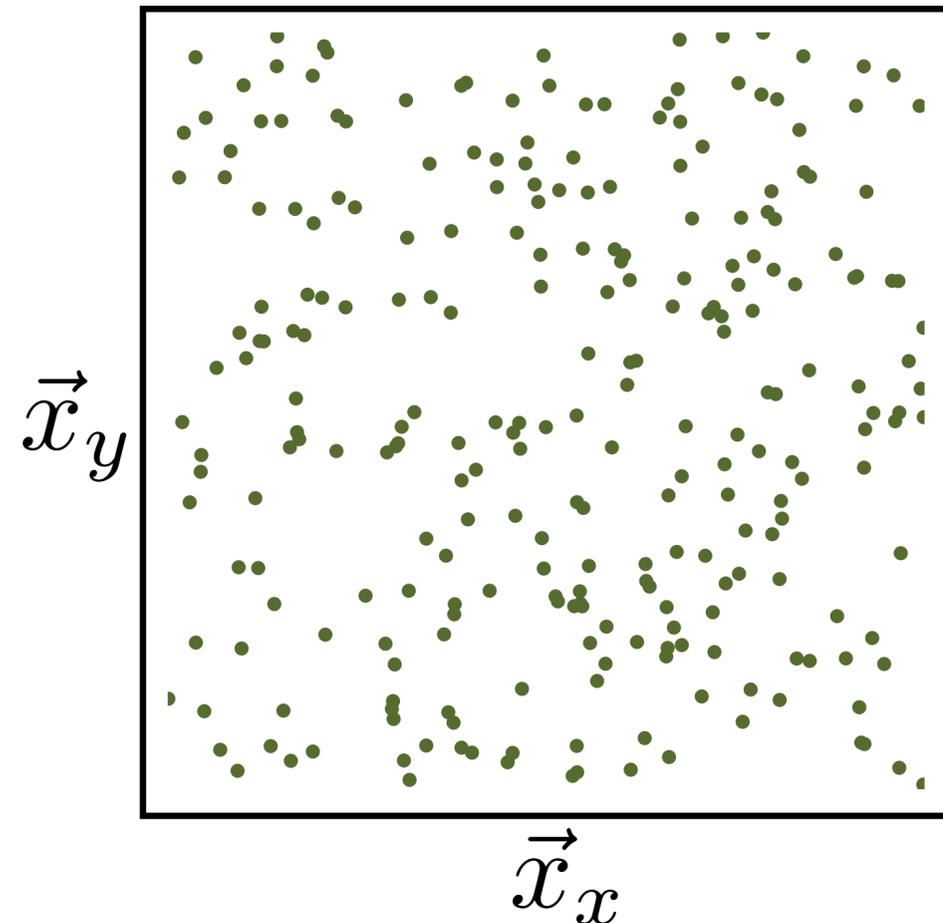
Power spectrum



$$\left| \frac{1}{N} \sum_{k=1}^N e^{-2 \pi i (\vec{w} \cdot \vec{x}_k)} \right|^2$$

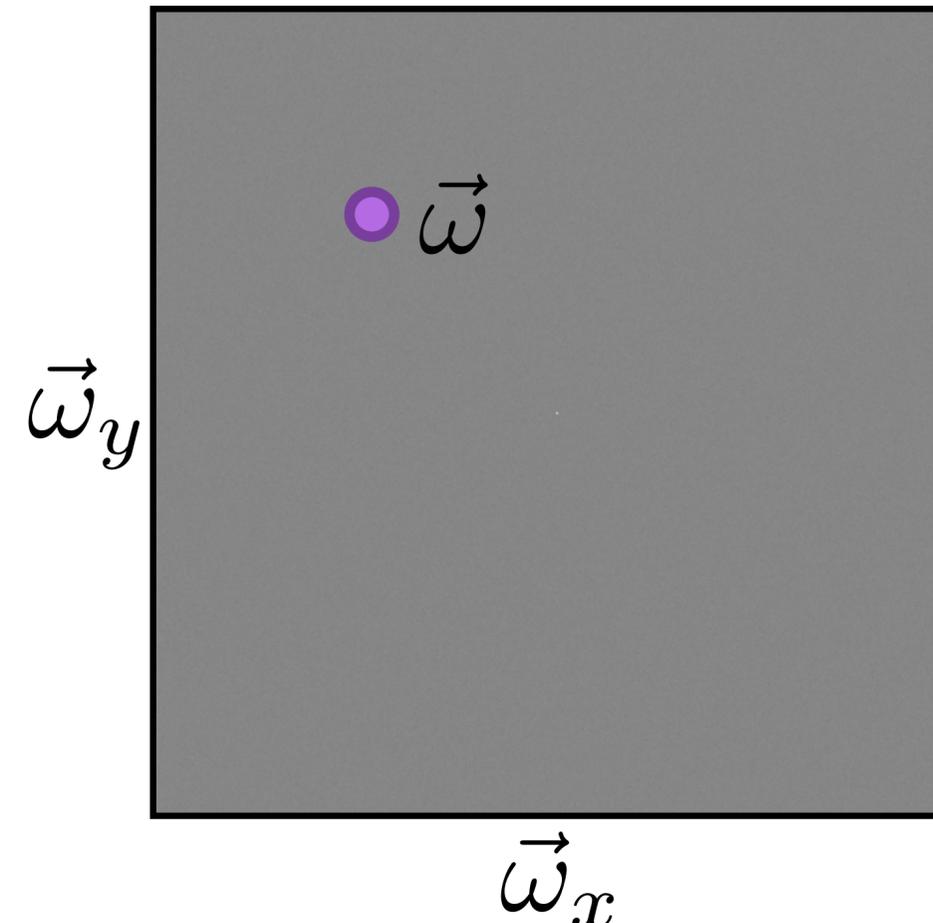
# Independent Random Sampling

Samples



$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|)$$

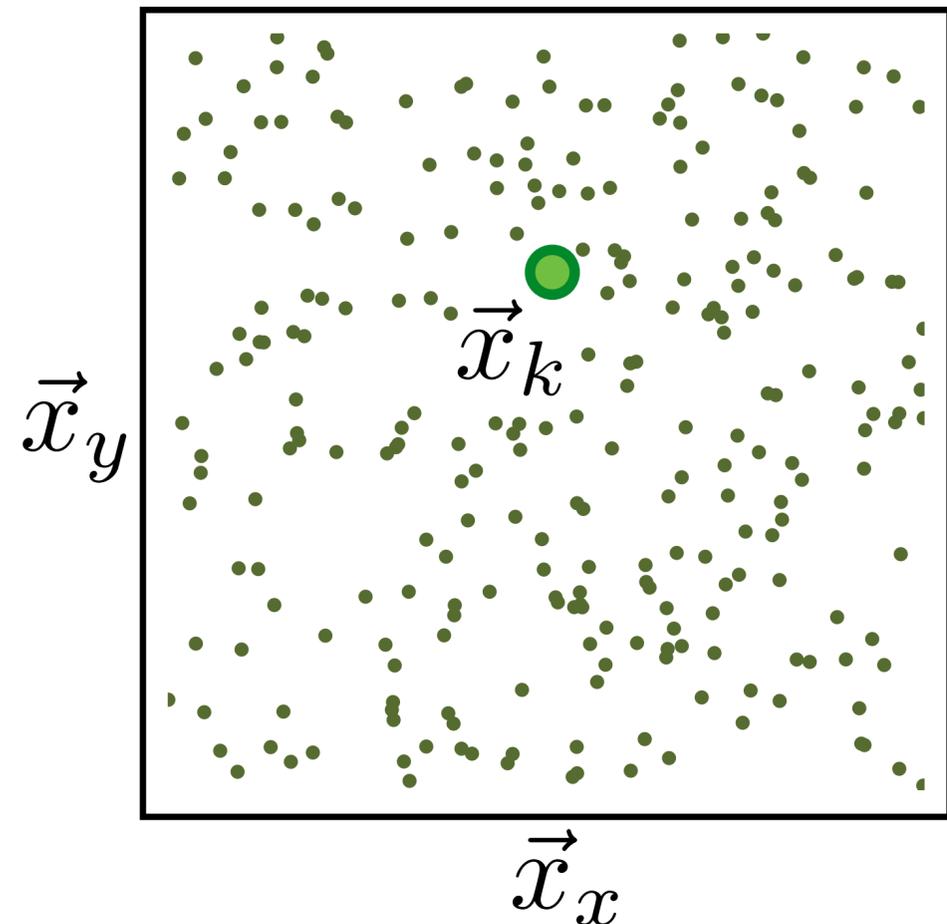
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$$\left| \frac{1}{N} \sum_{k=1}^N e^{-2\pi i (\vec{w} \cdot \vec{x}_k)} \right|^2$$

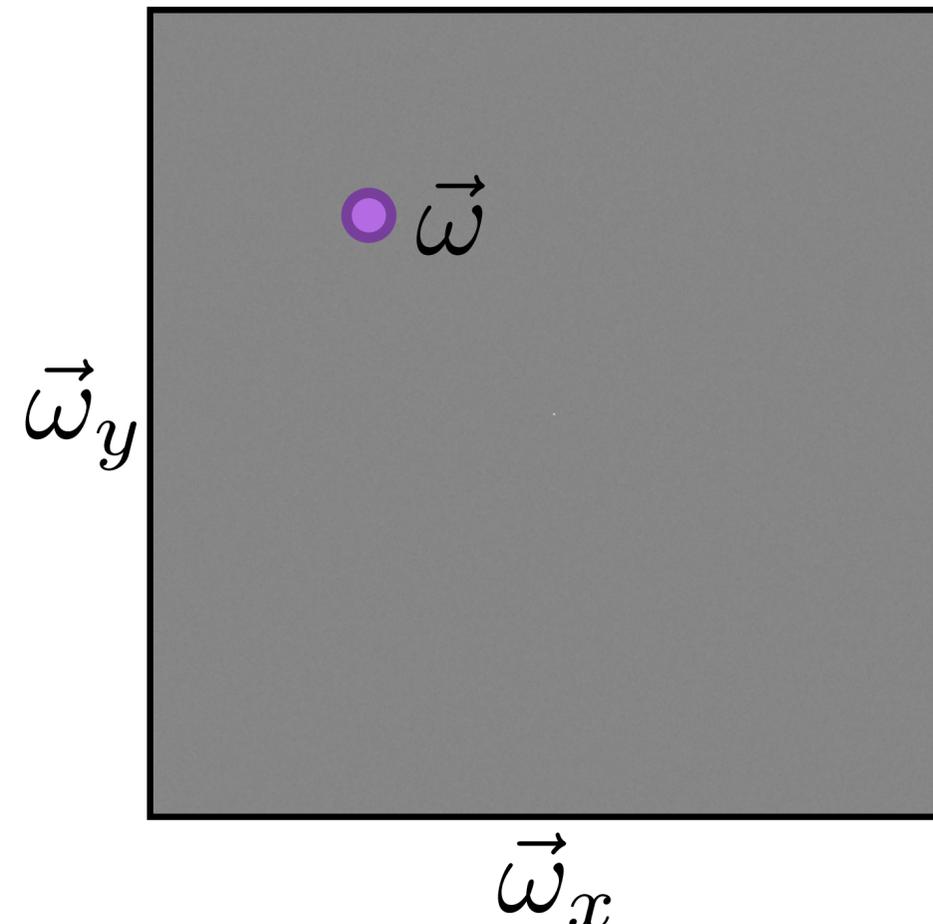
# Independent Random Sampling

Samples



$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|)$$

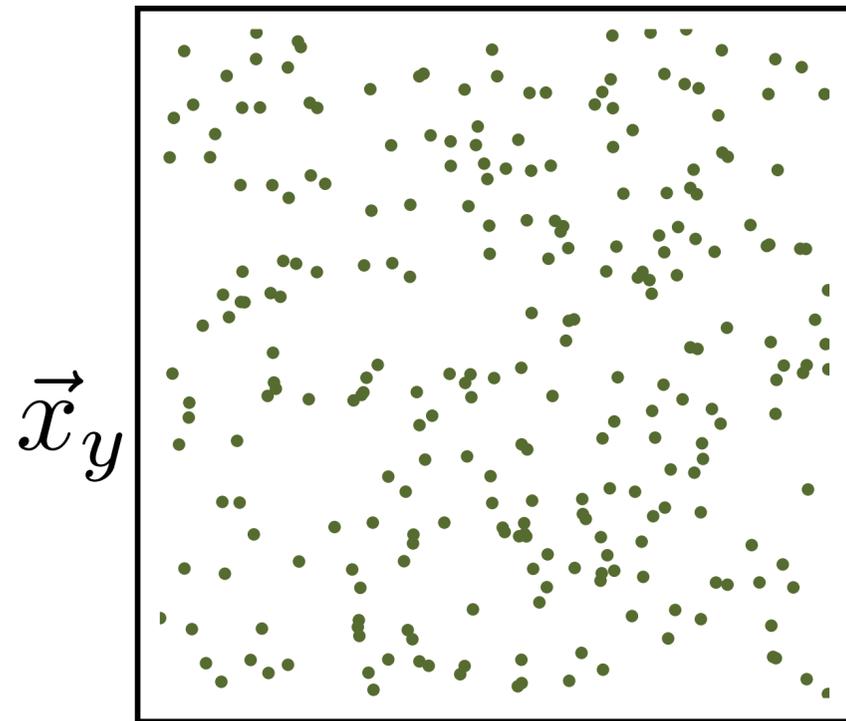
Power spectrum



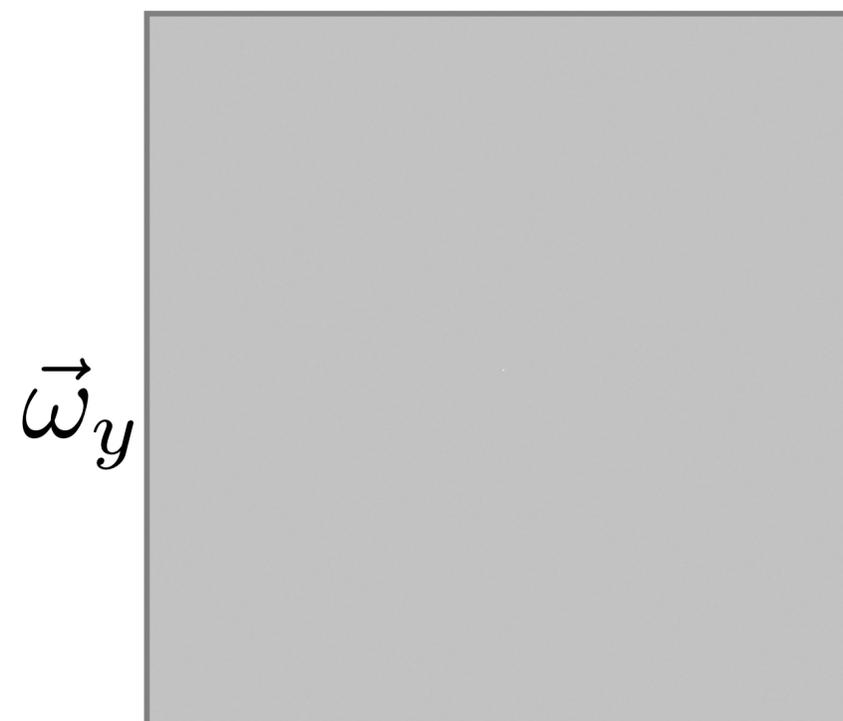
$$\left| \frac{1}{N} \sum_{k=1}^N e^{-2\pi i (\vec{w} \cdot \vec{x}_k)} \right|^2$$

# Independent Random Sampling

Many sample set realizations



**Expected** power spectrum

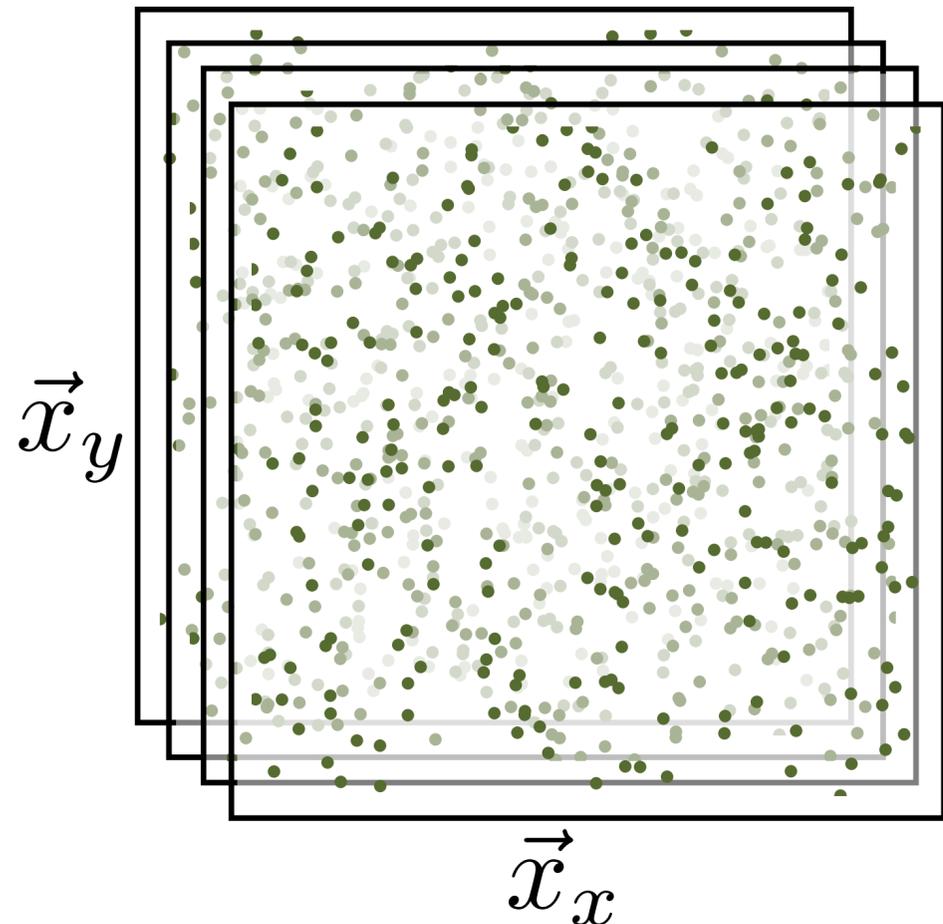


$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|)$$

$$\left| \frac{1}{N} \sum_{k=1}^N e^{-2 \pi i (\vec{\omega} \cdot \vec{x}_k)} \right|^2$$

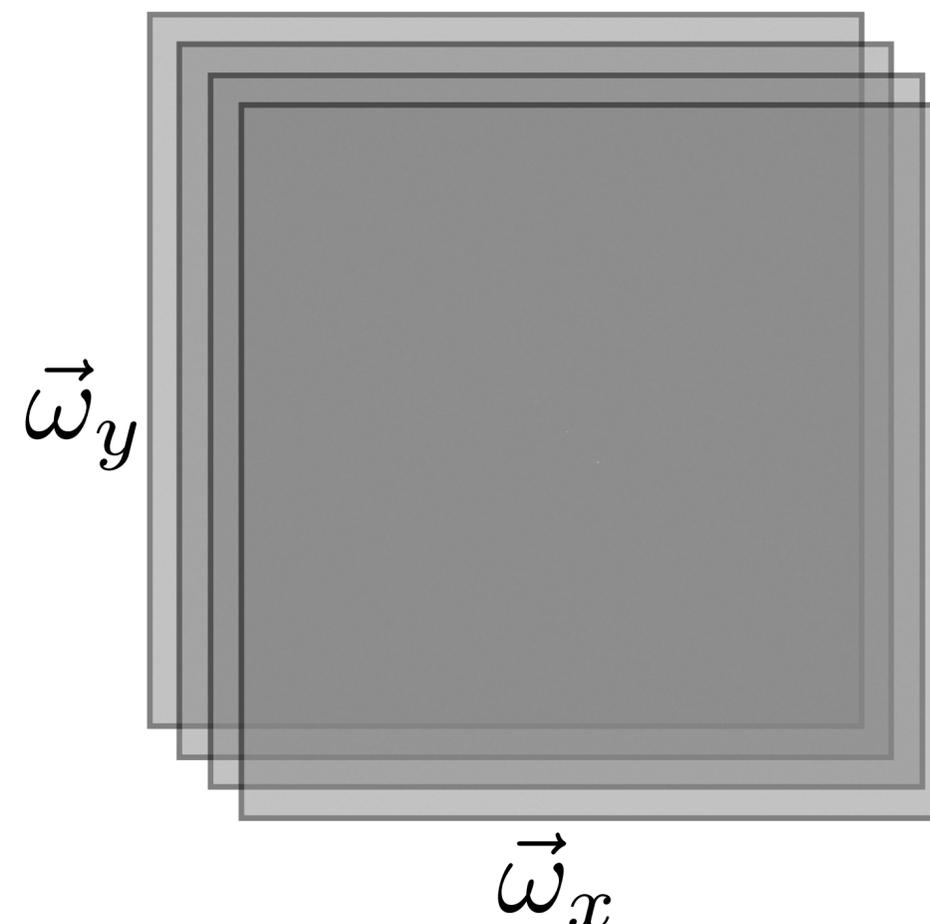
# Independent Random Sampling

Many sample set realizations



$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|)$$

**Expected** power spectrum

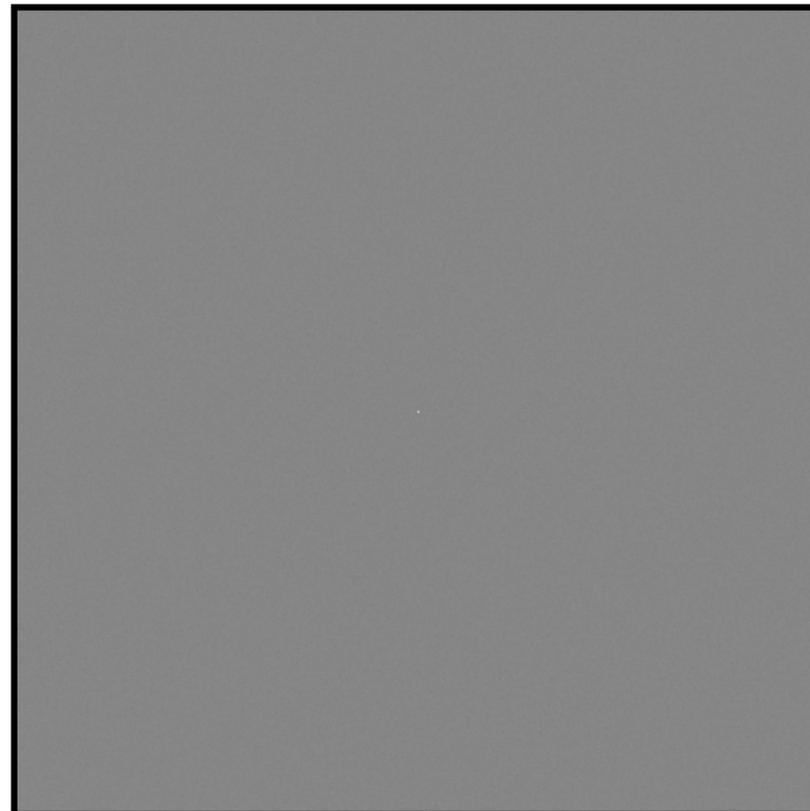
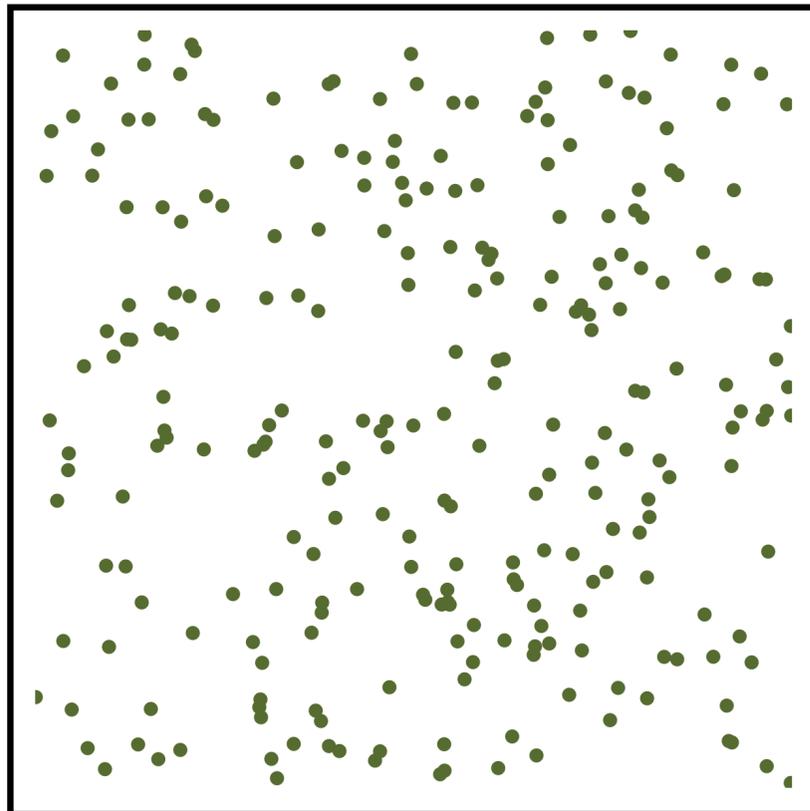


$$\mathbb{E} \left[ \left| \frac{1}{N} \sum_{k=1}^N e^{-2 \pi i (\vec{w} \cdot \vec{x}_k)} \right|^2 \right]$$

# Independent Random Sampling

Samples

Expected power spectrum



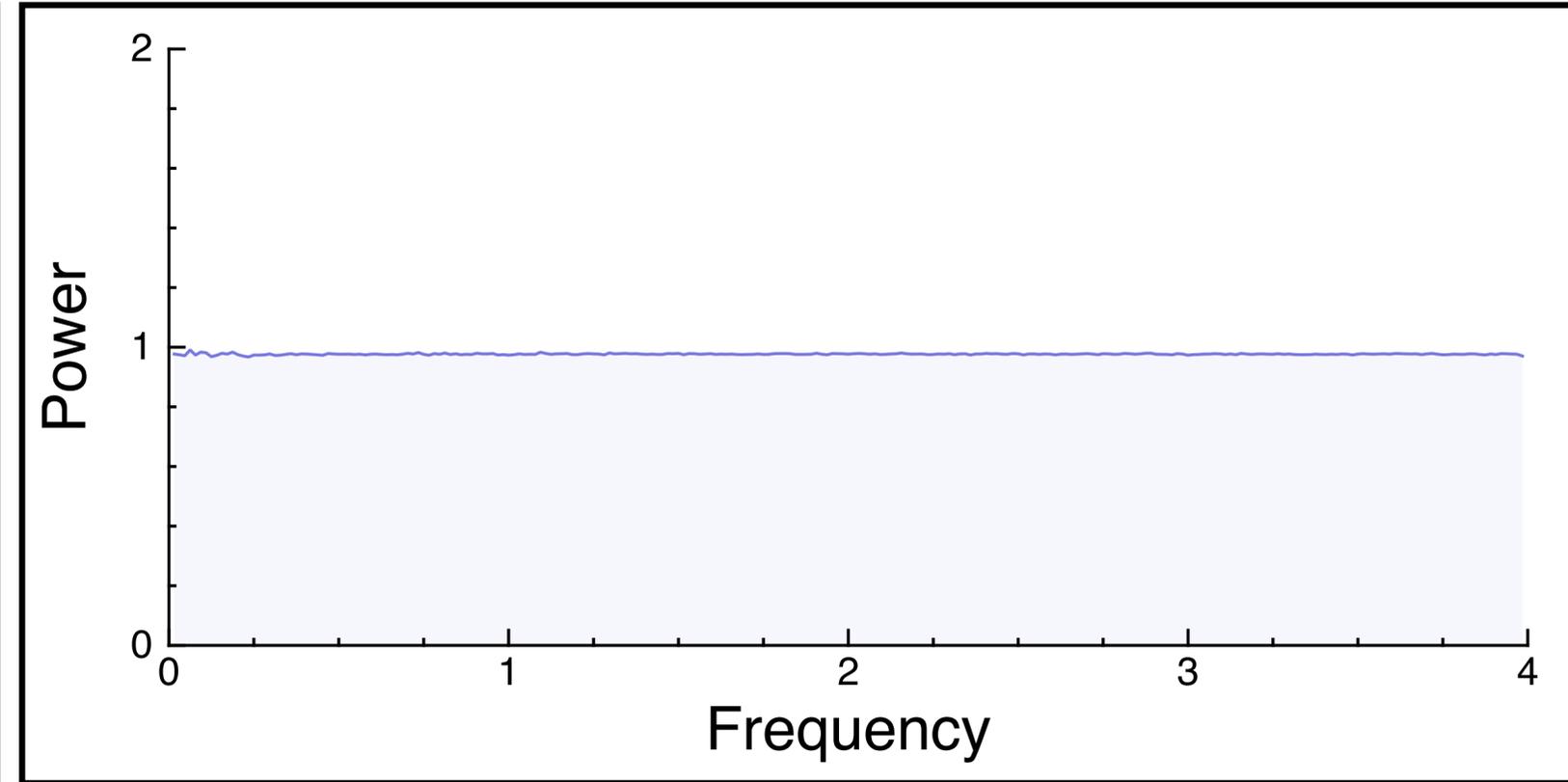
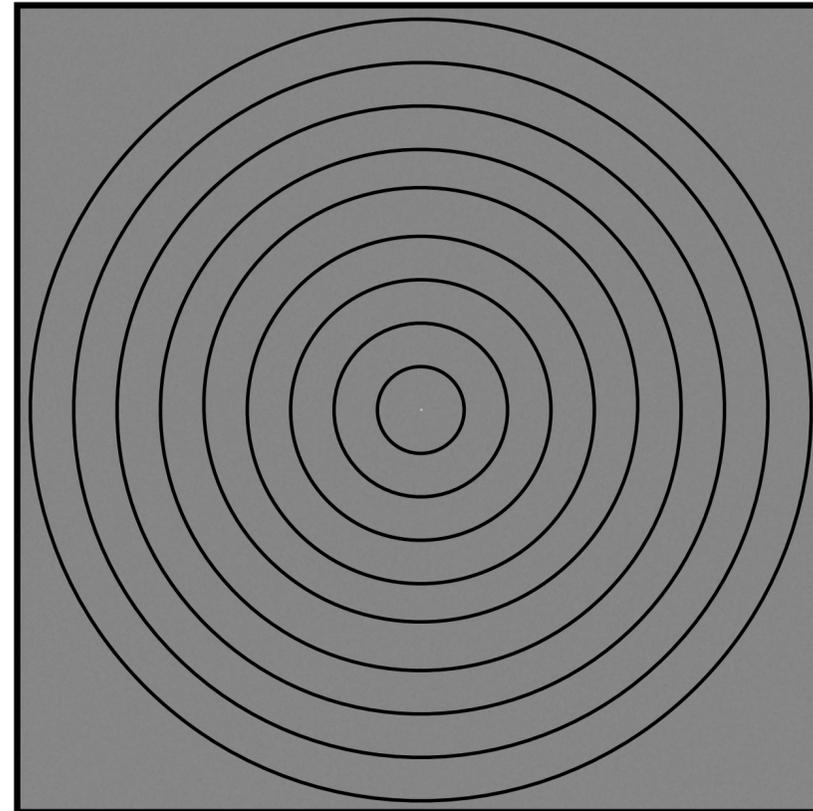
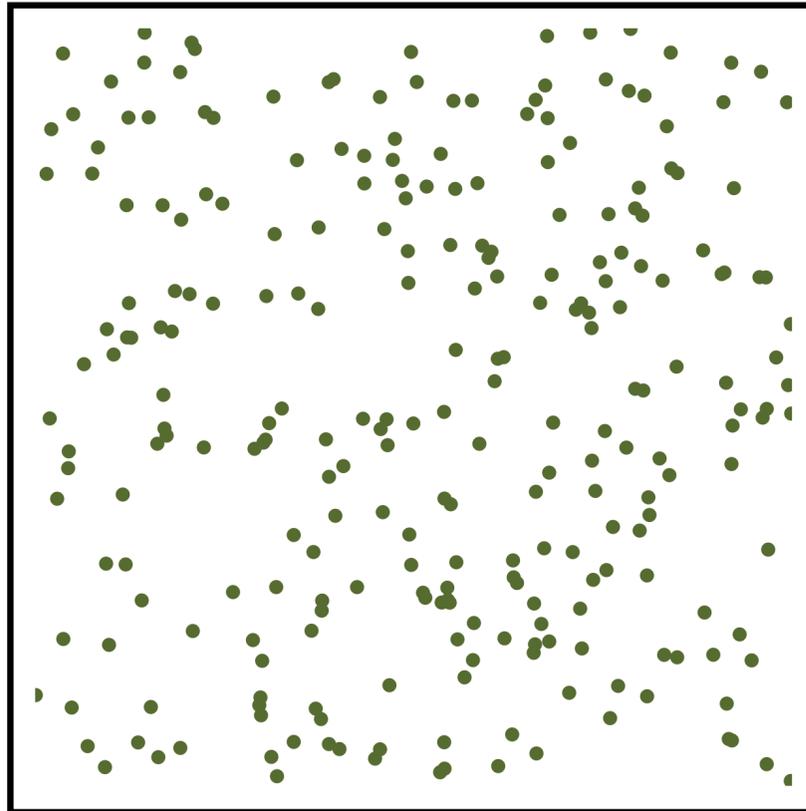
$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|) \quad \mathbb{E} \left[ \left| \frac{1}{N} \sum_{k=1}^N e^{-2\pi i (\vec{\omega} \cdot \vec{x}_k)} \right|^2 \right]$$

# Independent Random Sampling

Samples

Expected power spectrum

Radial mean



$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|) \quad \mathbb{E} \left[ \left| \frac{1}{N} \sum_{k=1}^N e^{-2\pi i (\vec{\omega} \cdot \vec{x}_k)} \right|^2 \right]$$

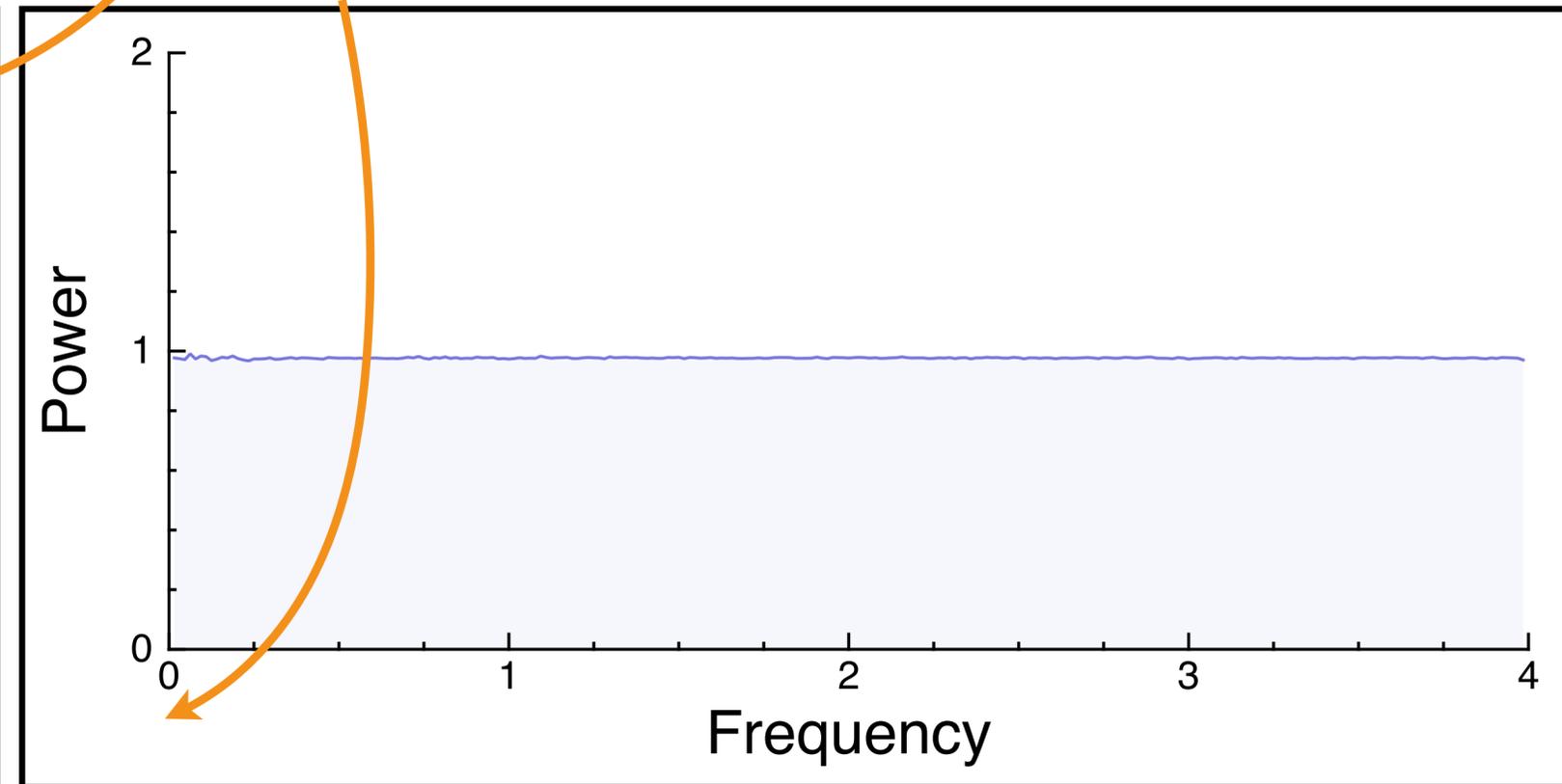
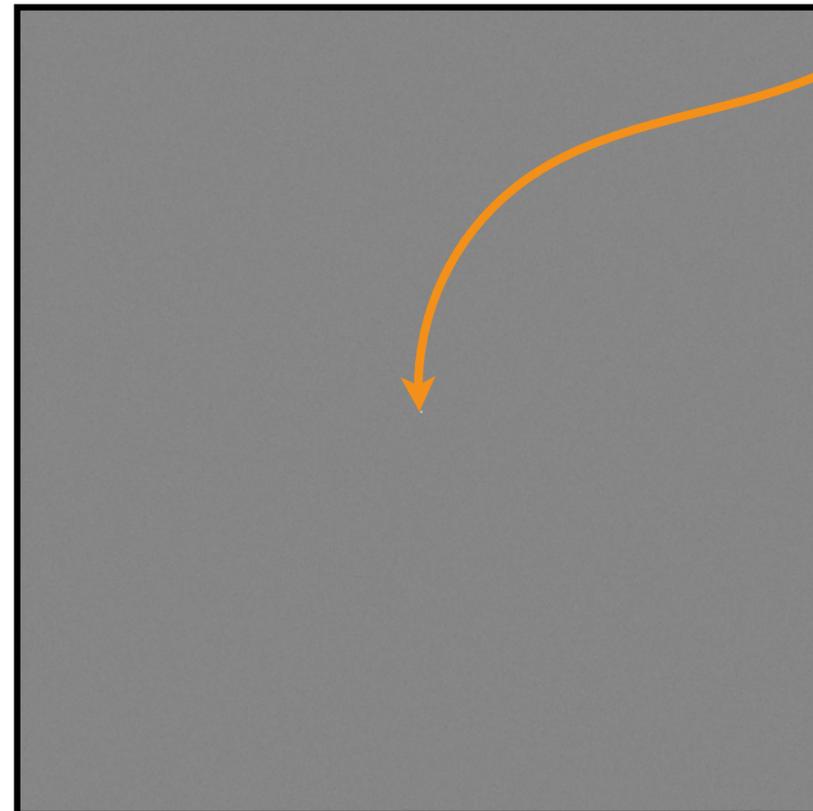
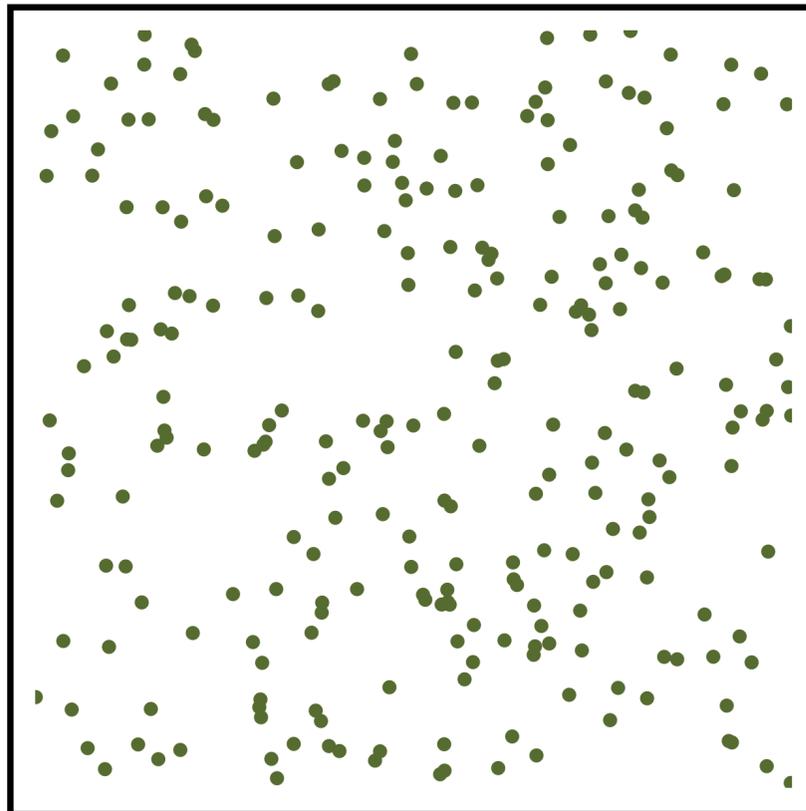
# Independent Random Sampling

Samples

Expected power spectrum

DC Peak

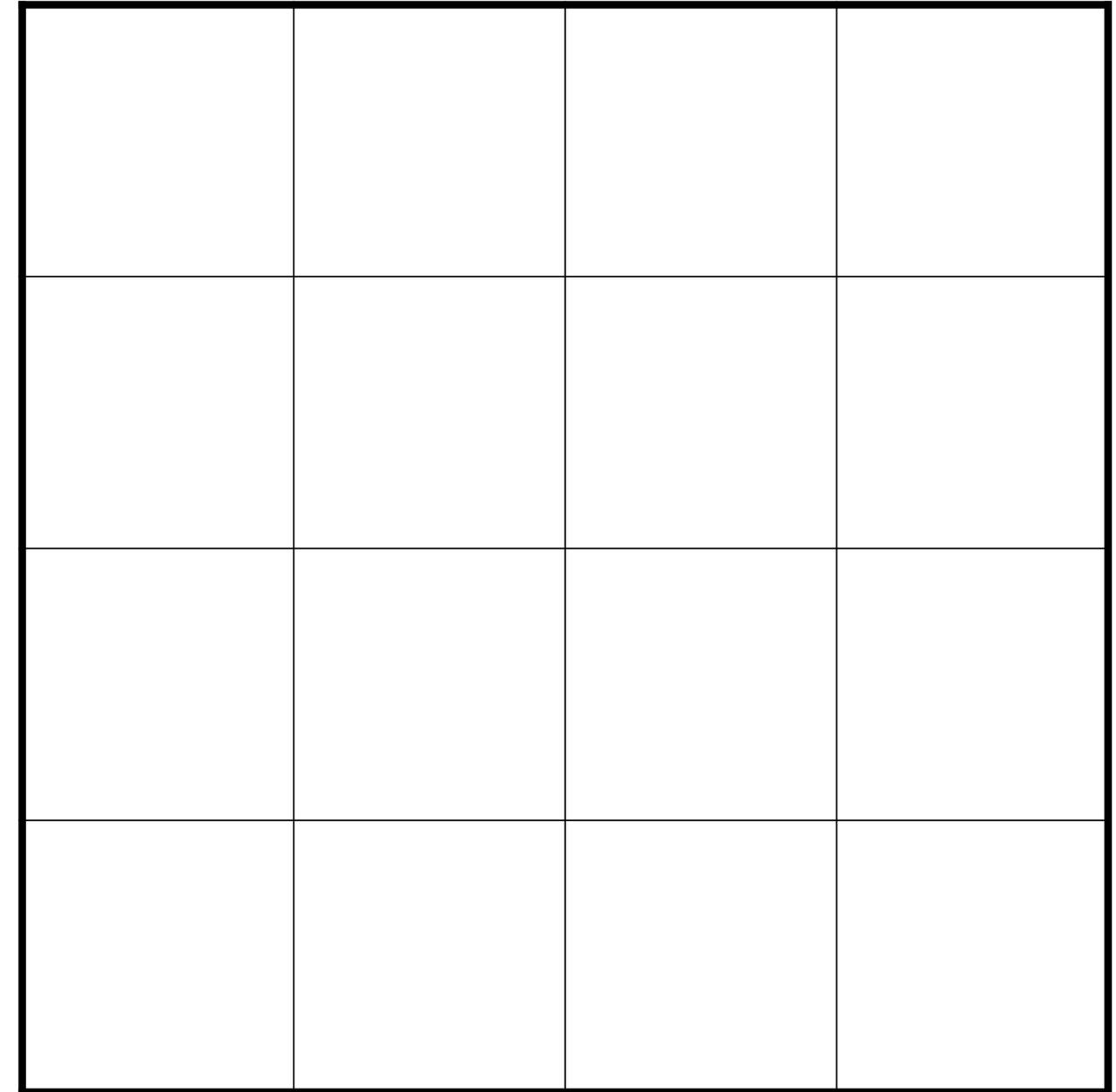
Radial mean



$$\frac{1}{N} \sum_{k=1}^N \delta(|\vec{x} - \vec{x}_k|) \quad \mathbb{E} \left[ \left| \frac{1}{N} \sum_{k=1}^N e^{-2\pi i (\vec{\omega} \cdot \vec{x}_k)} \right|^2 \right]$$

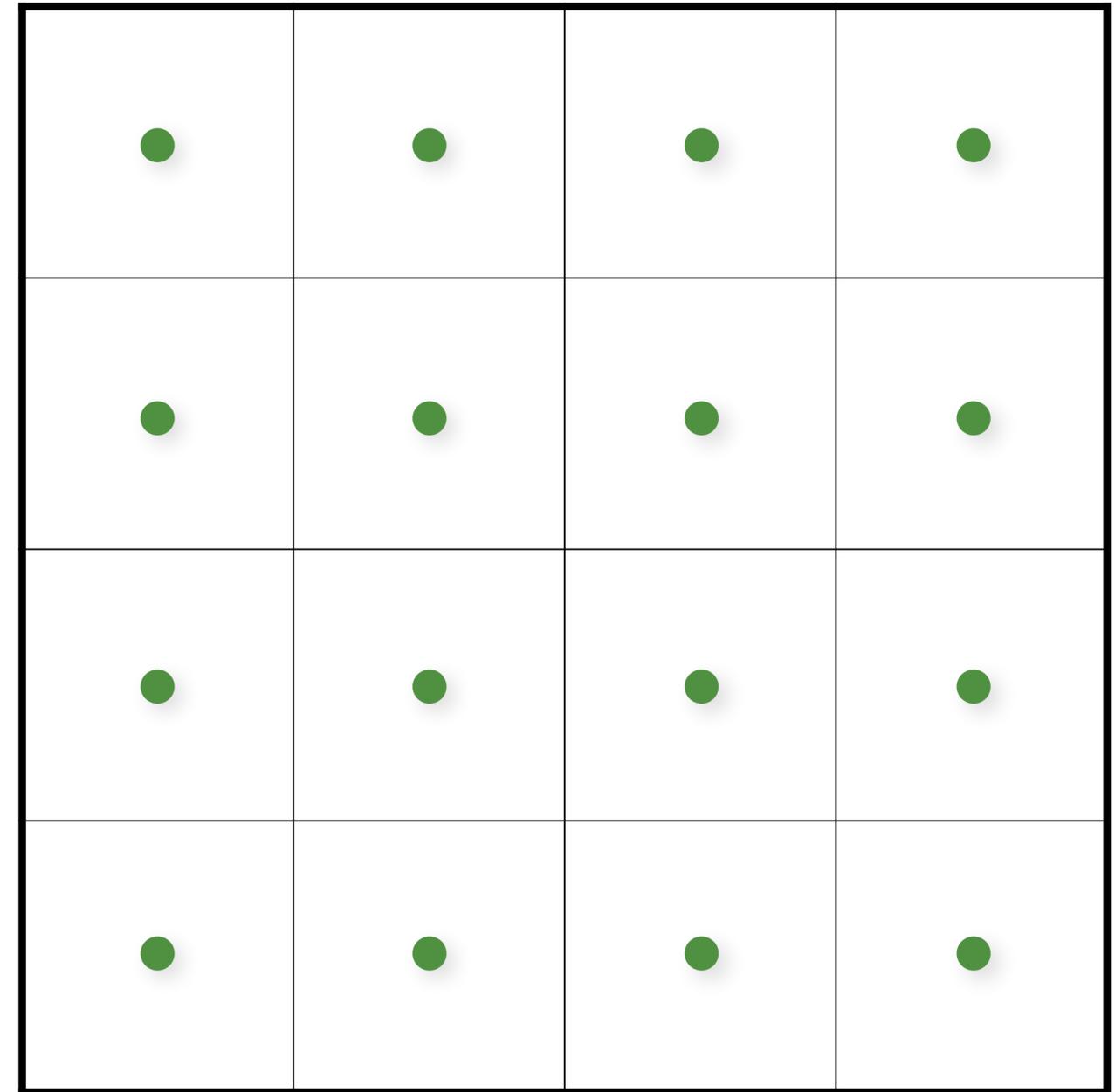
# Regular Sampling

```
for (uint i = 0; i < numX; i++)  
  for (uint j = 0; j < numY; j++)  
  {  
    samples(i,j).x = (i + 0.5)/numX;  
    samples(i,j).y = (j + 0.5)/numY;  
  }
```



# Regular Sampling

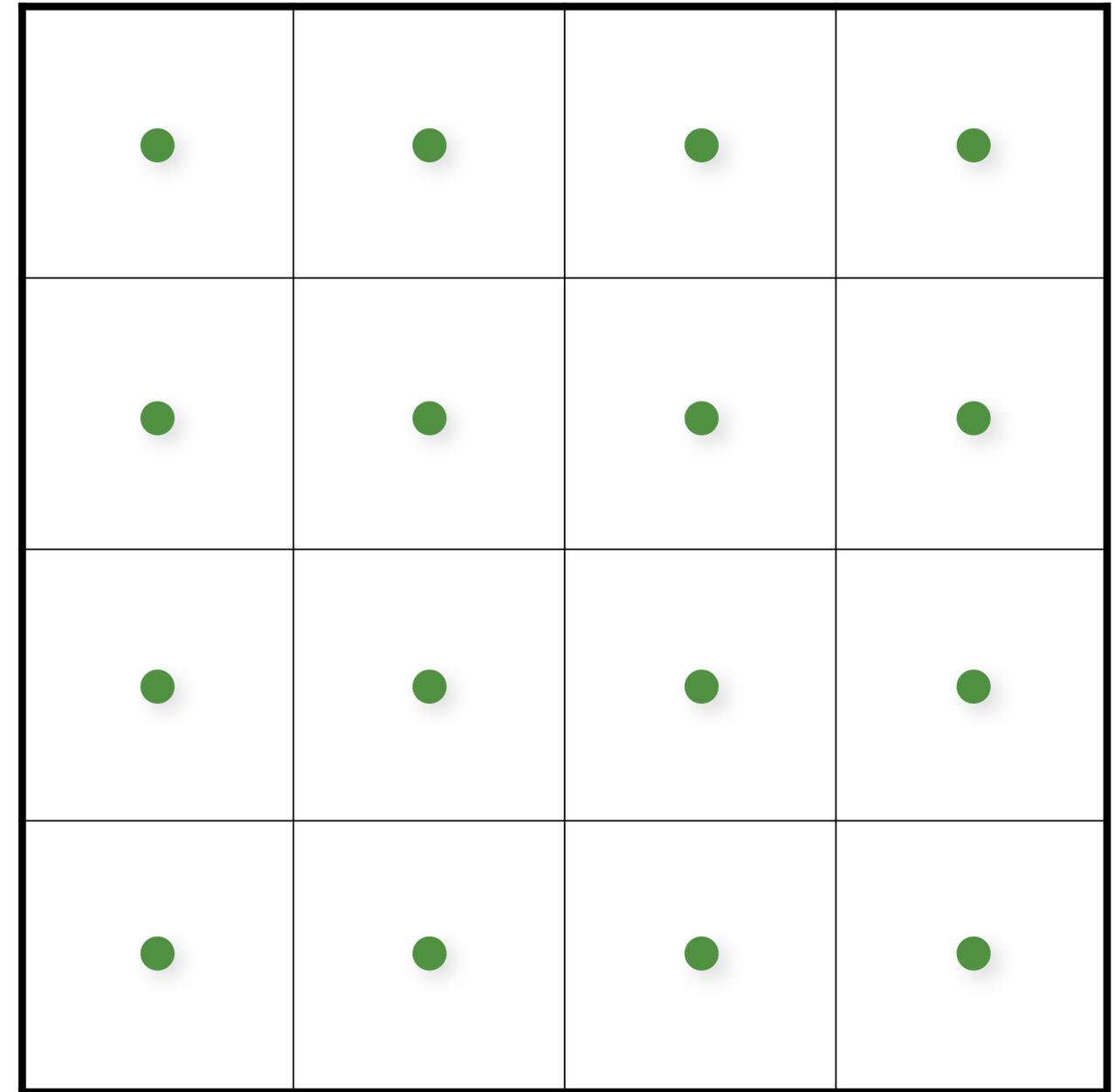
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✓ Extends to higher dimensions, but...

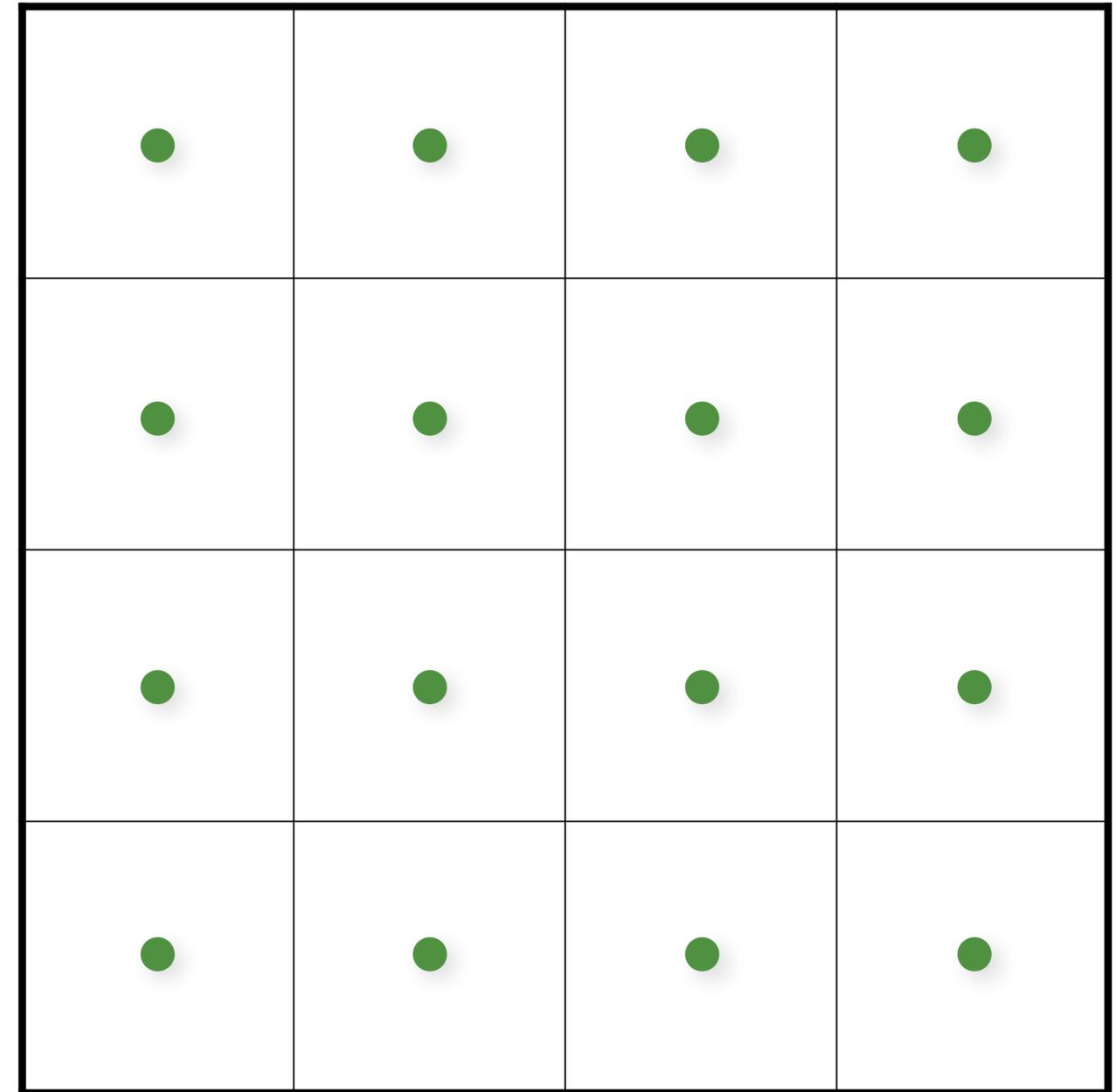


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  }
```

✓ Extends to higher dimensions, but...

✗ Curse of dimensionality



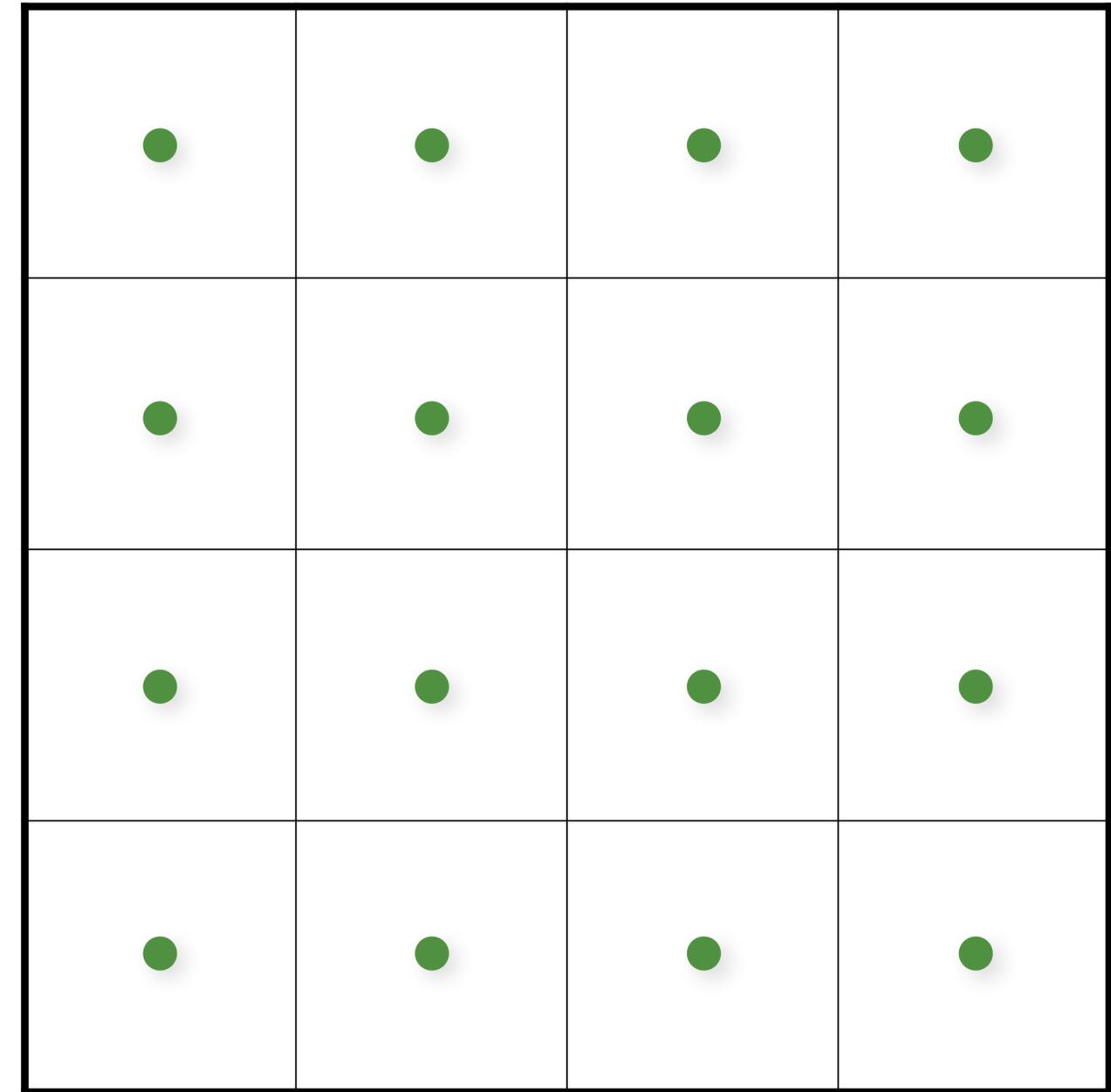
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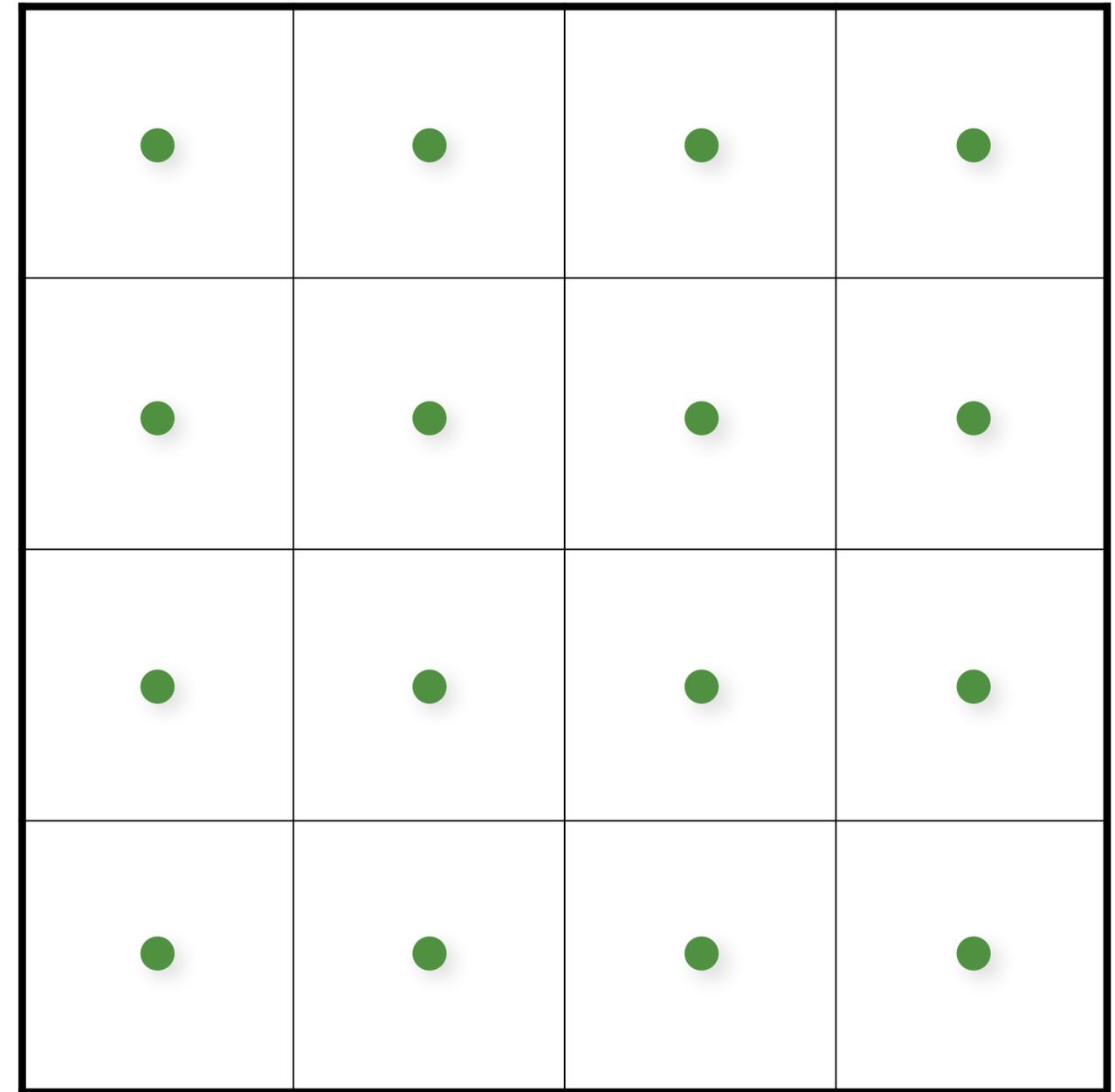
✗ Curse of dimensionality

✗ Aliasing



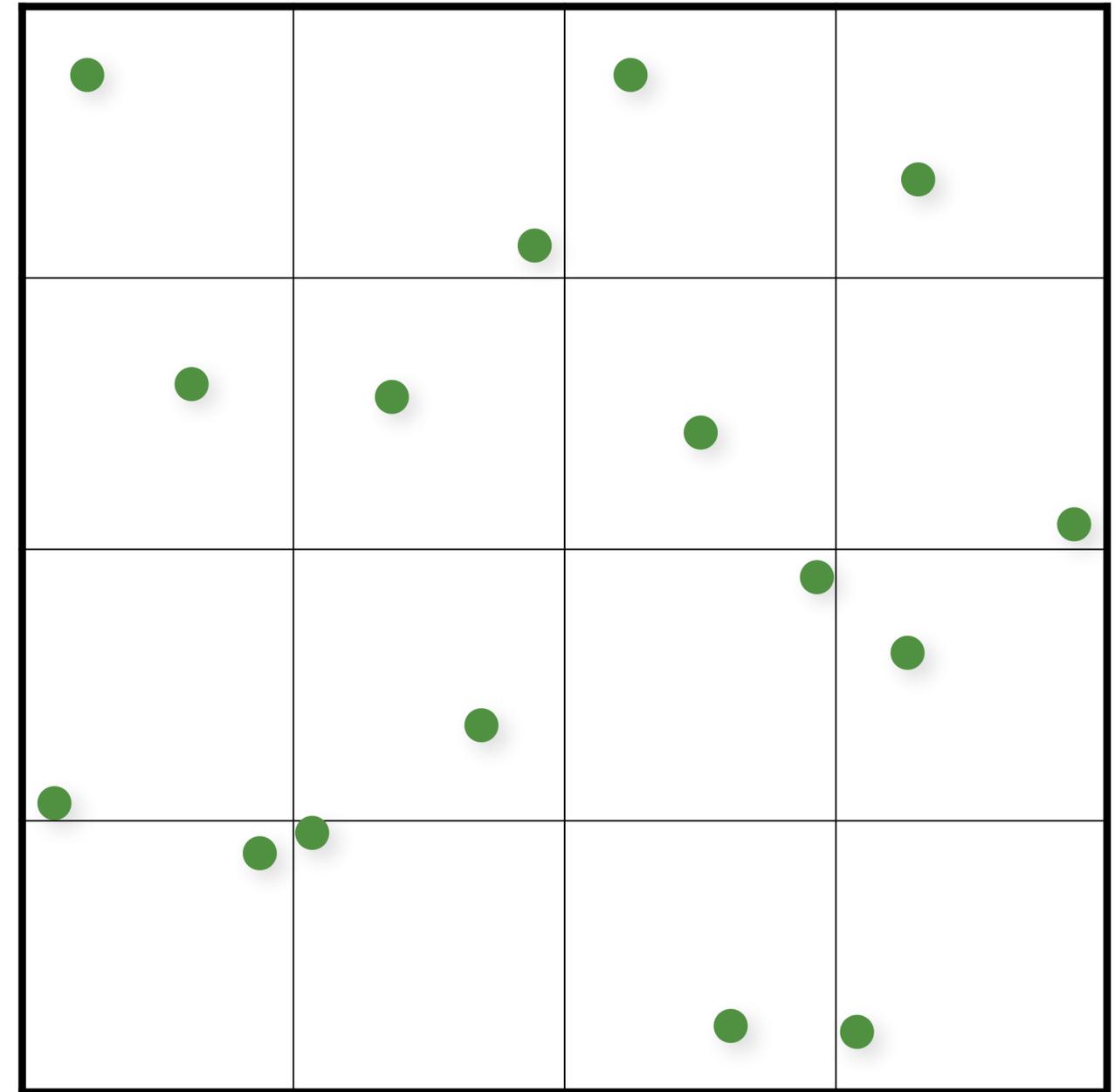
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  {  
    samples(i,j).x = (i + 0.5)/numX;  
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# Jittered/Stratified Sampling

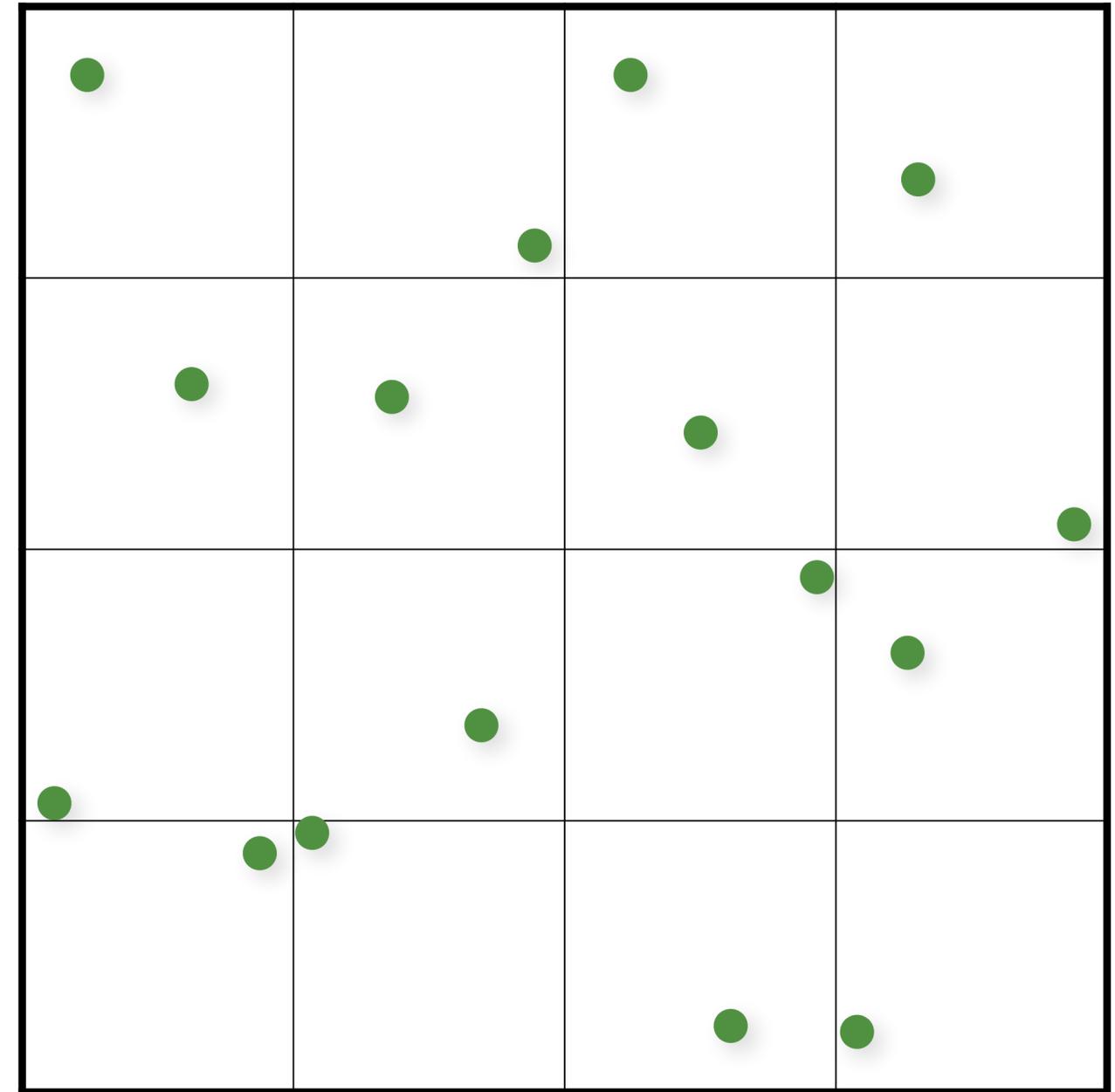
```
for (uint i = 0; i < numX; i++)  
  for (uint j = 0; j < numY; j++)  
  {  
    samples(i,j).x = (i + randf())/numX;  
    samples(i,j).y = (j + randf())/numY;  
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```



# Jittered/Stratified Sampling

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```

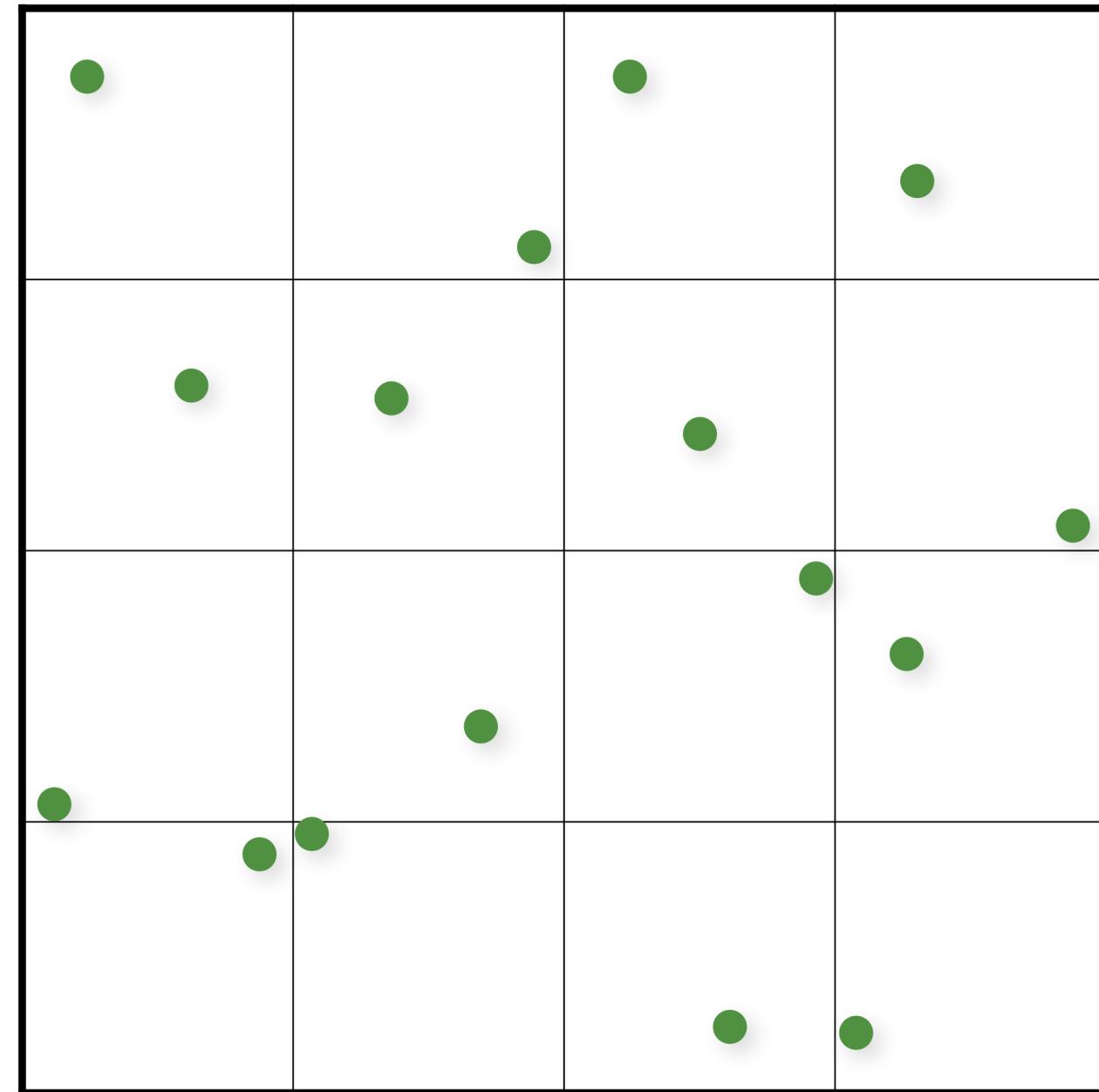
✓ Provably cannot increase variance



# Jittered/Stratified Sampling

```
for (uint i = 0; i < numX; i++)  
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  {  
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    samples(i,j).y = (j + randf())/numY;  
  }
```

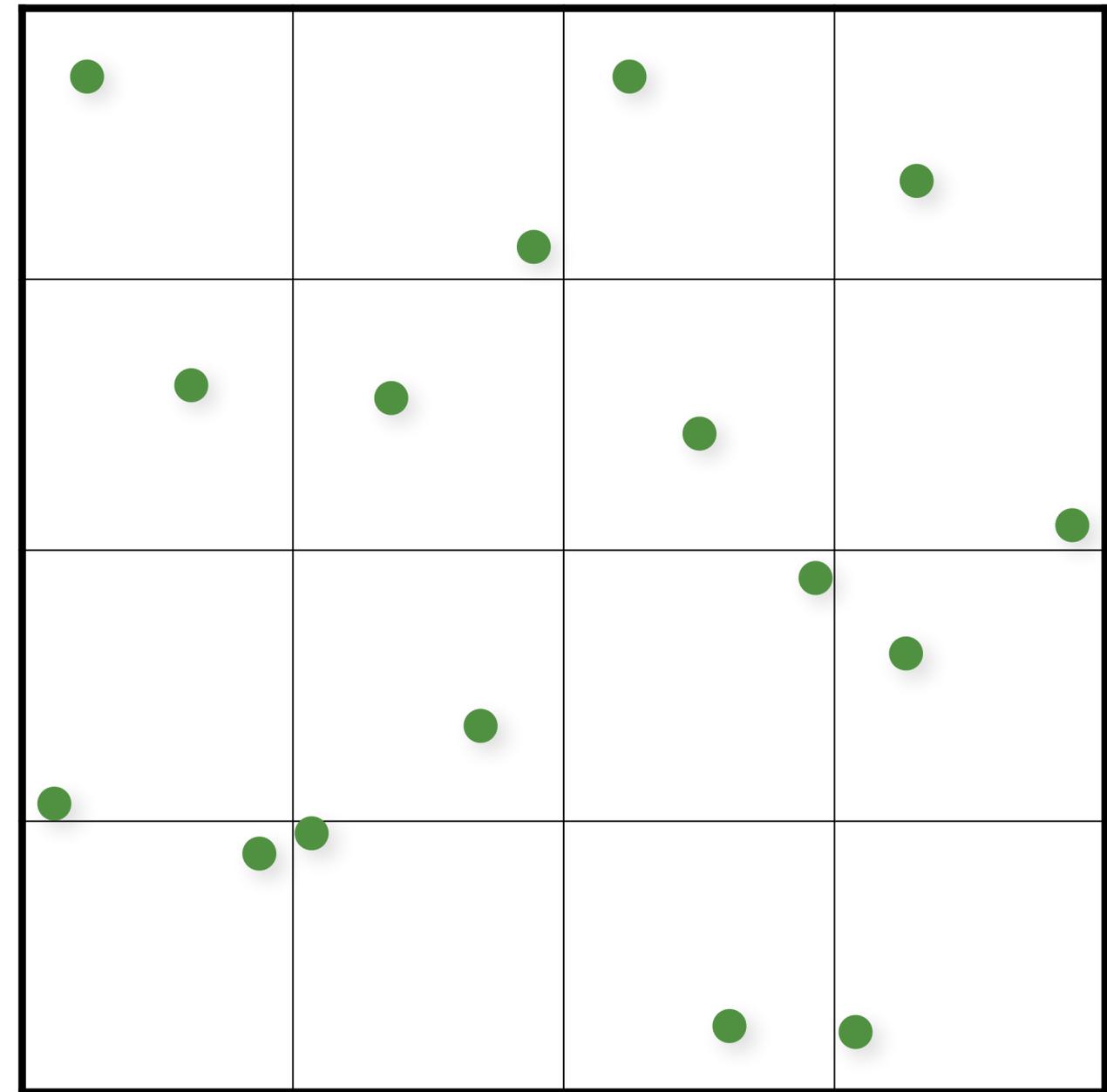
- ✓ Provably cannot increase variance
- ✓ Extends to higher dimensions, but...



# Jittered/Stratified Sampling

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  }
```

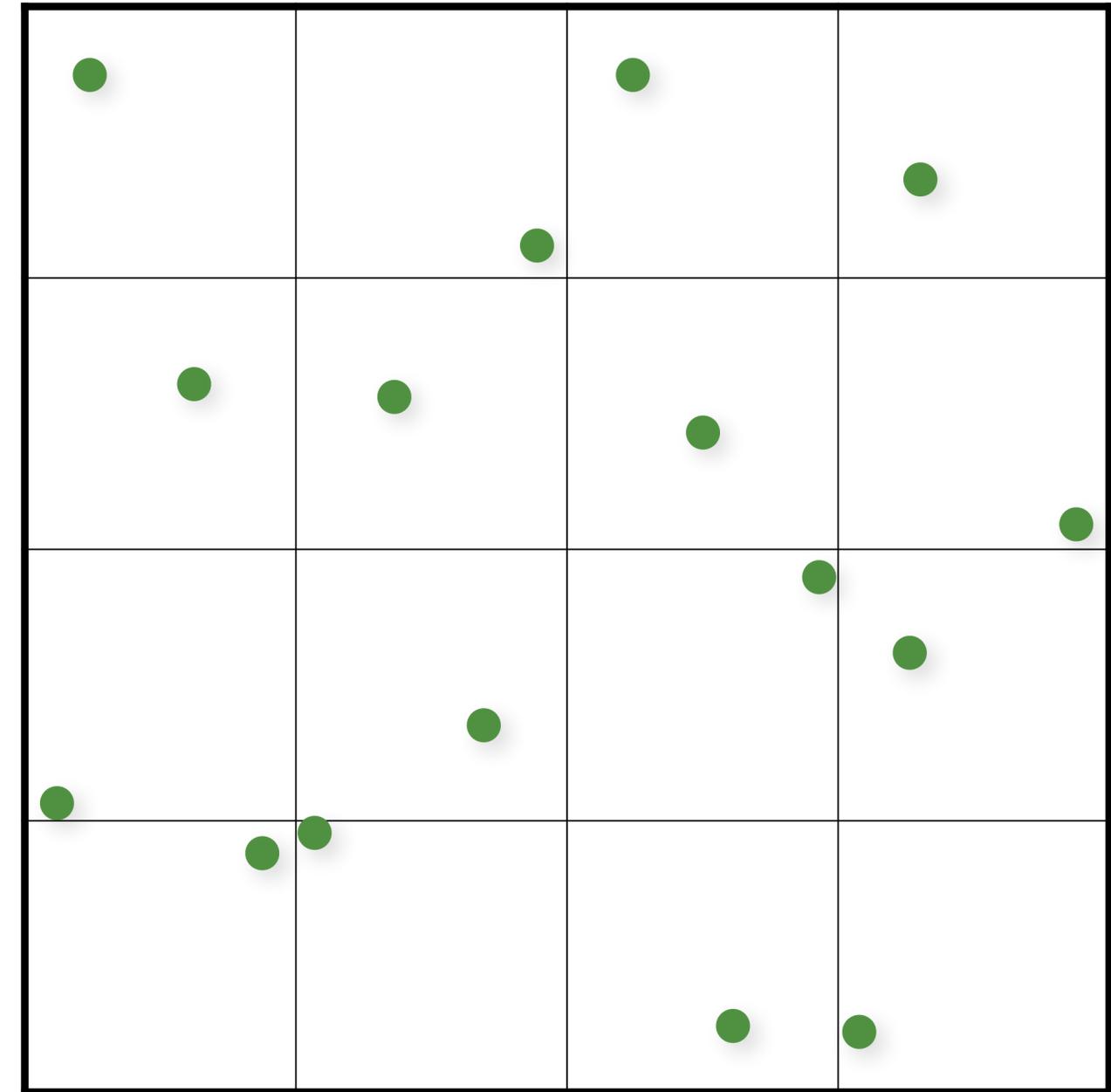
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# Jittered/Stratified Sampling

```
for (uint i = 0; i < numX; i++)  
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  {  
    samples(i,j).x = (i + randf())/numX;  
    samples(i,j).y = (j + randf())/numY;  
  }
```

- ✓ Provably cannot increase variance
- ✓ Extends to higher dimensions, but...
- ✗ Curse of dimensionality
- ✗ Not progressive

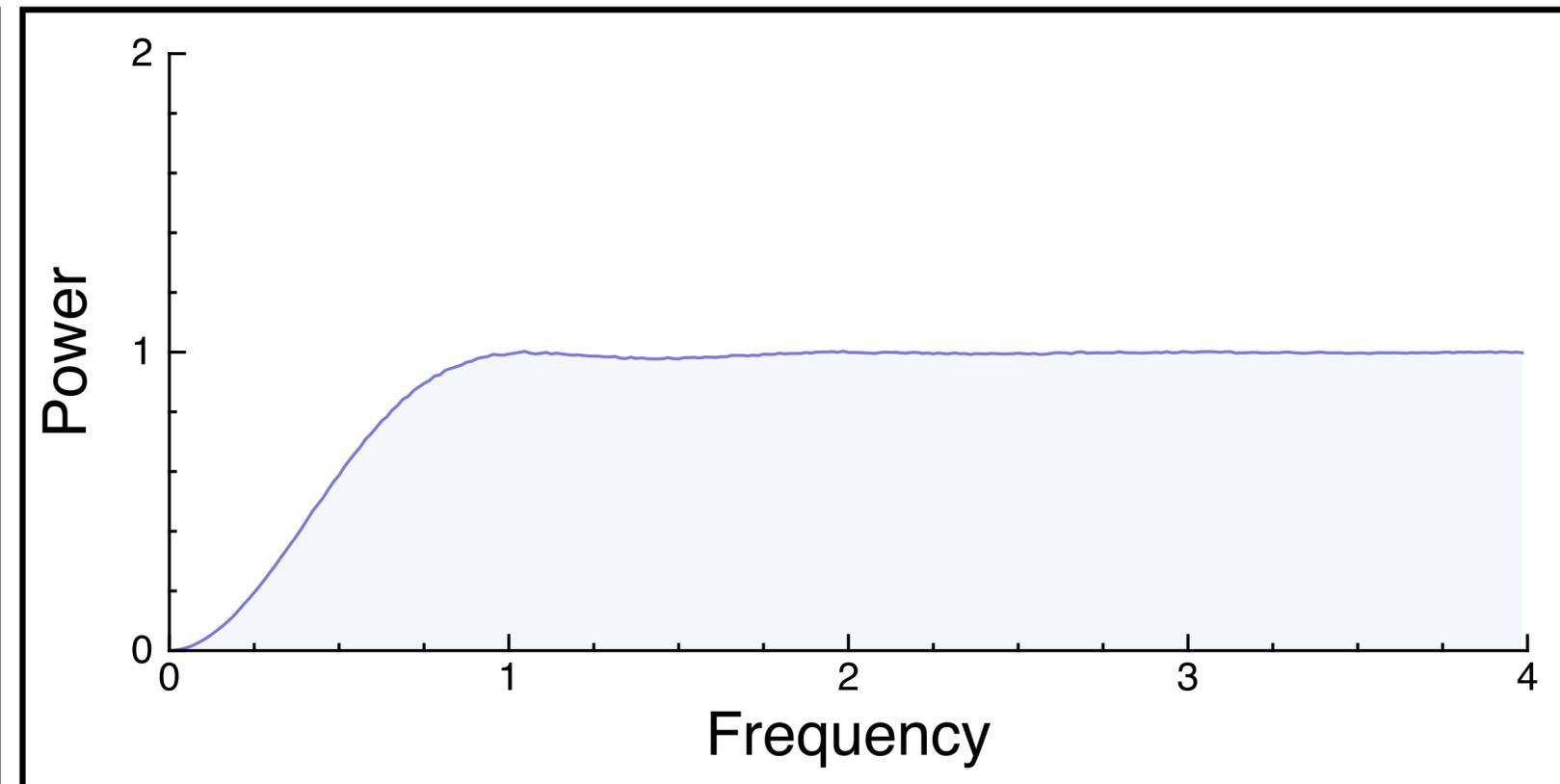
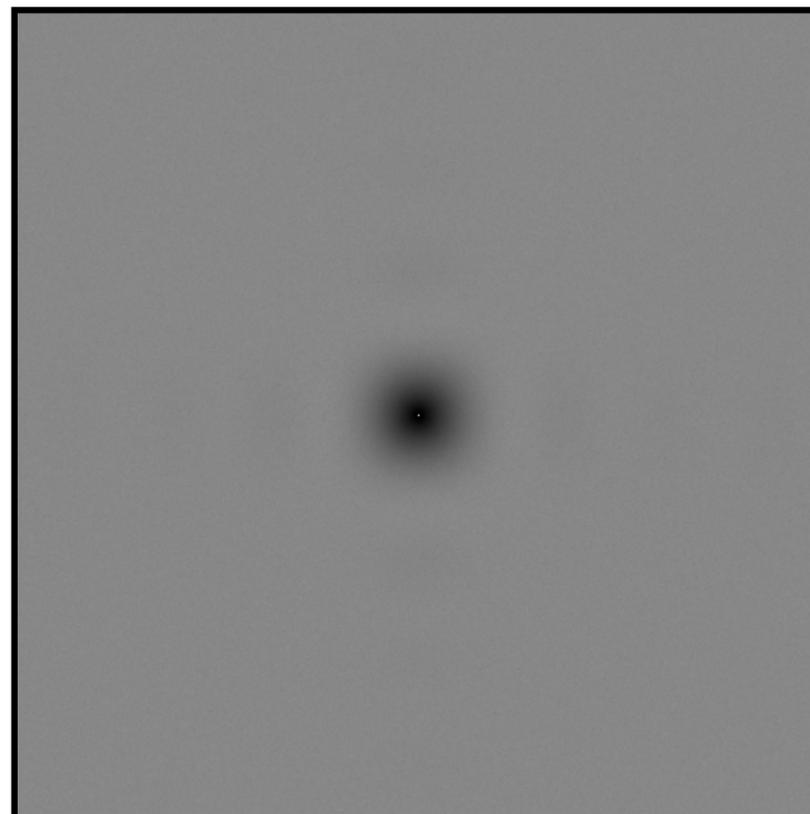
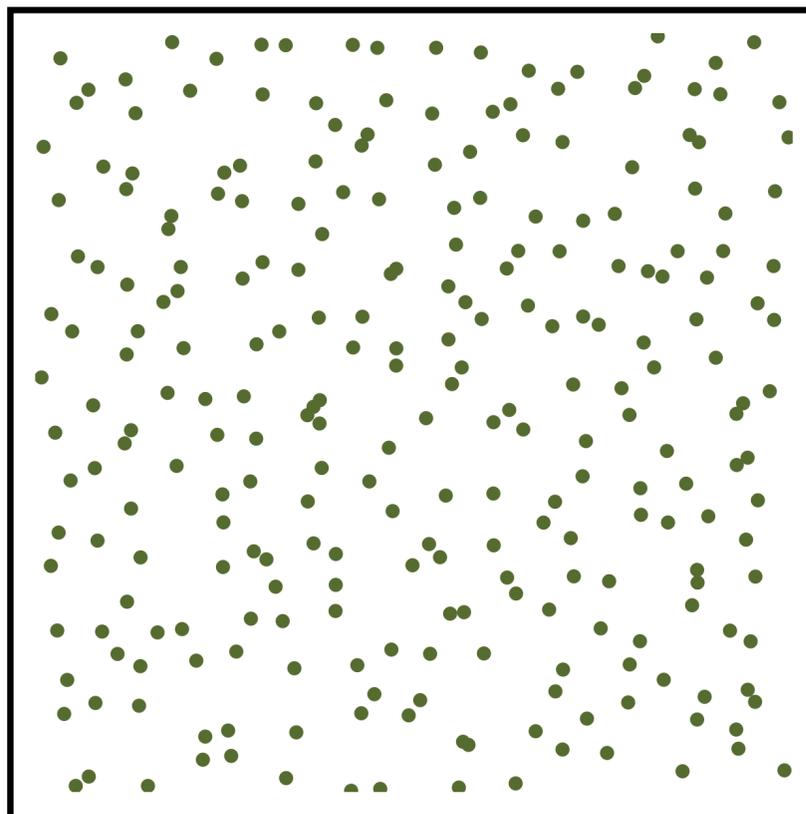


# Jittered Sampling

Samples

Expected power spectrum

Radial mean

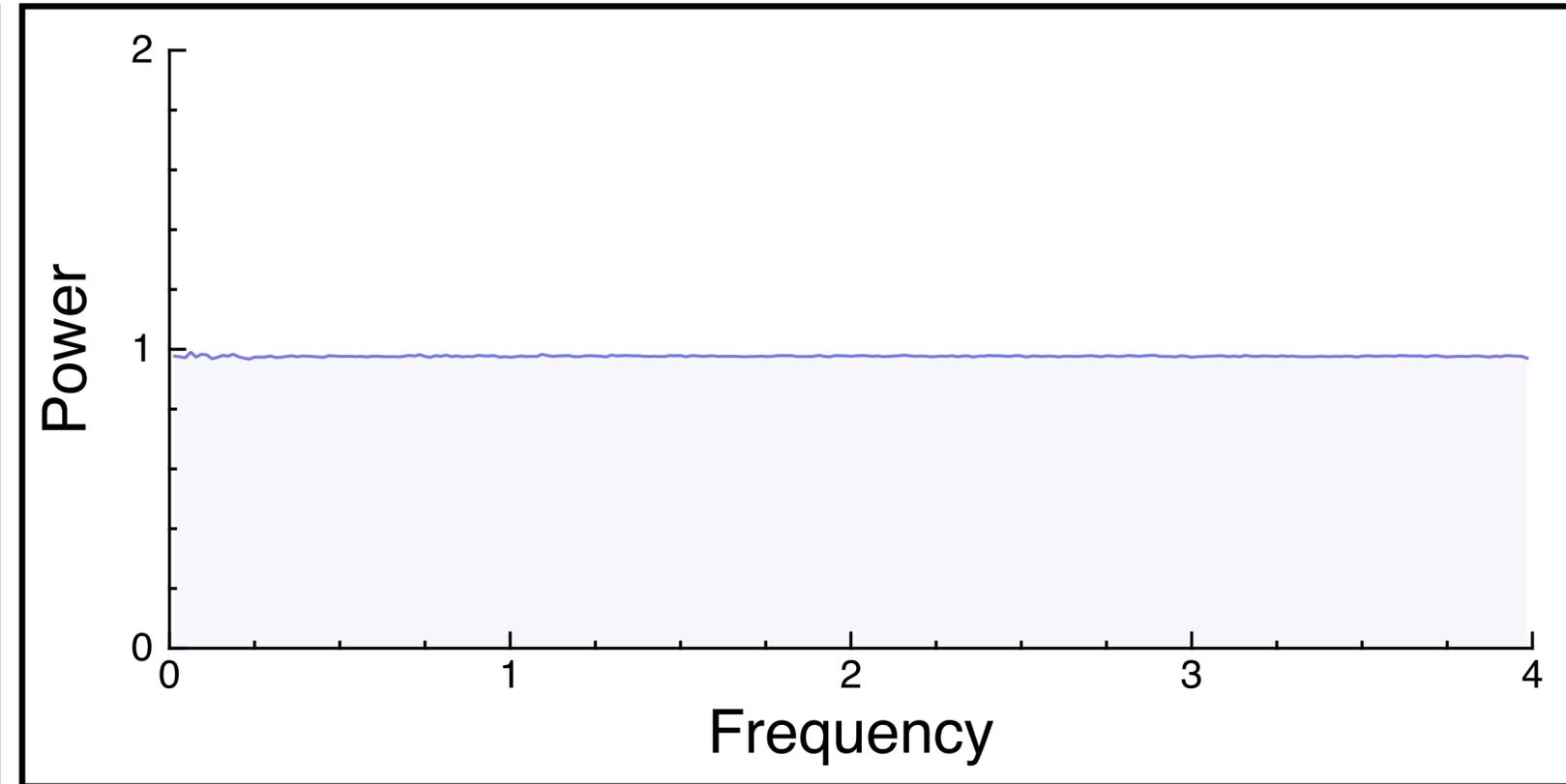
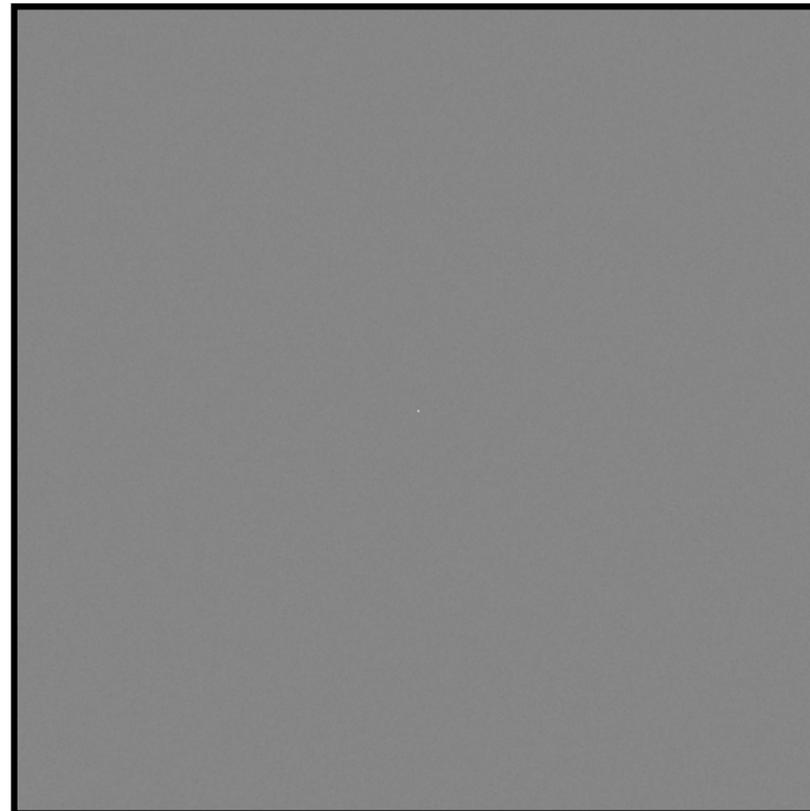
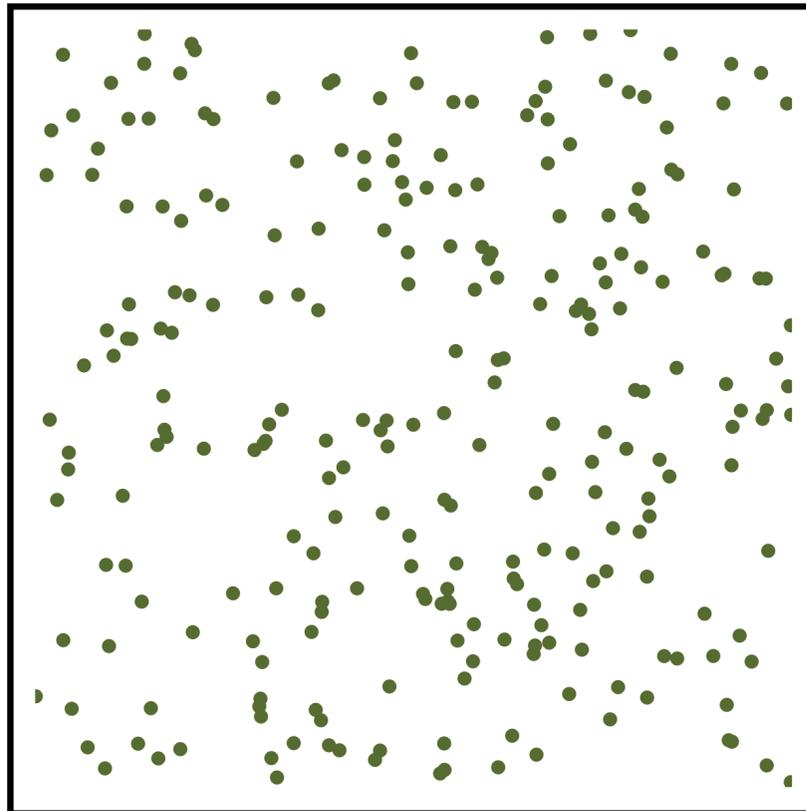


# Independent Random Sampling

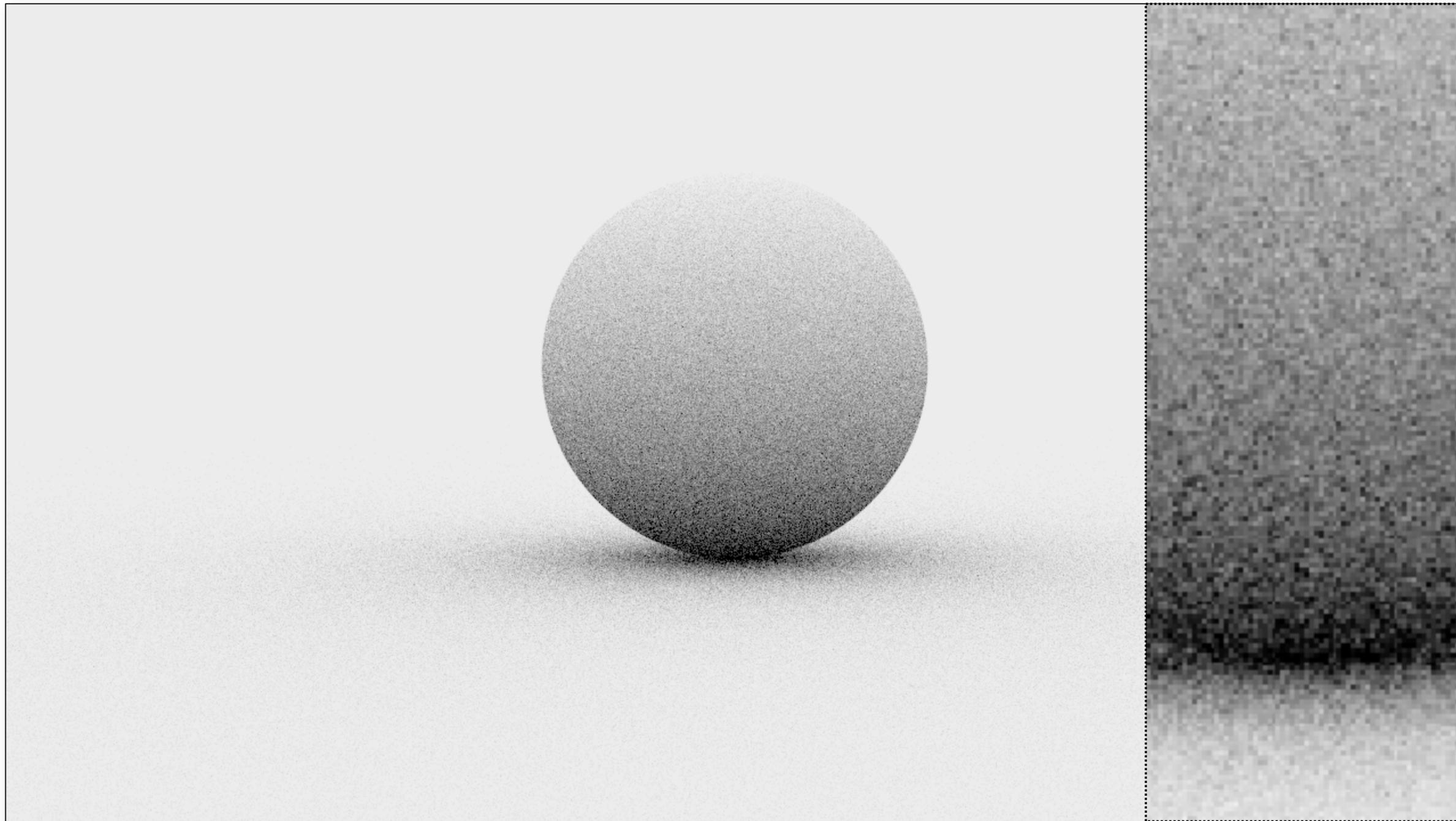
Samples

Expected power spectrum

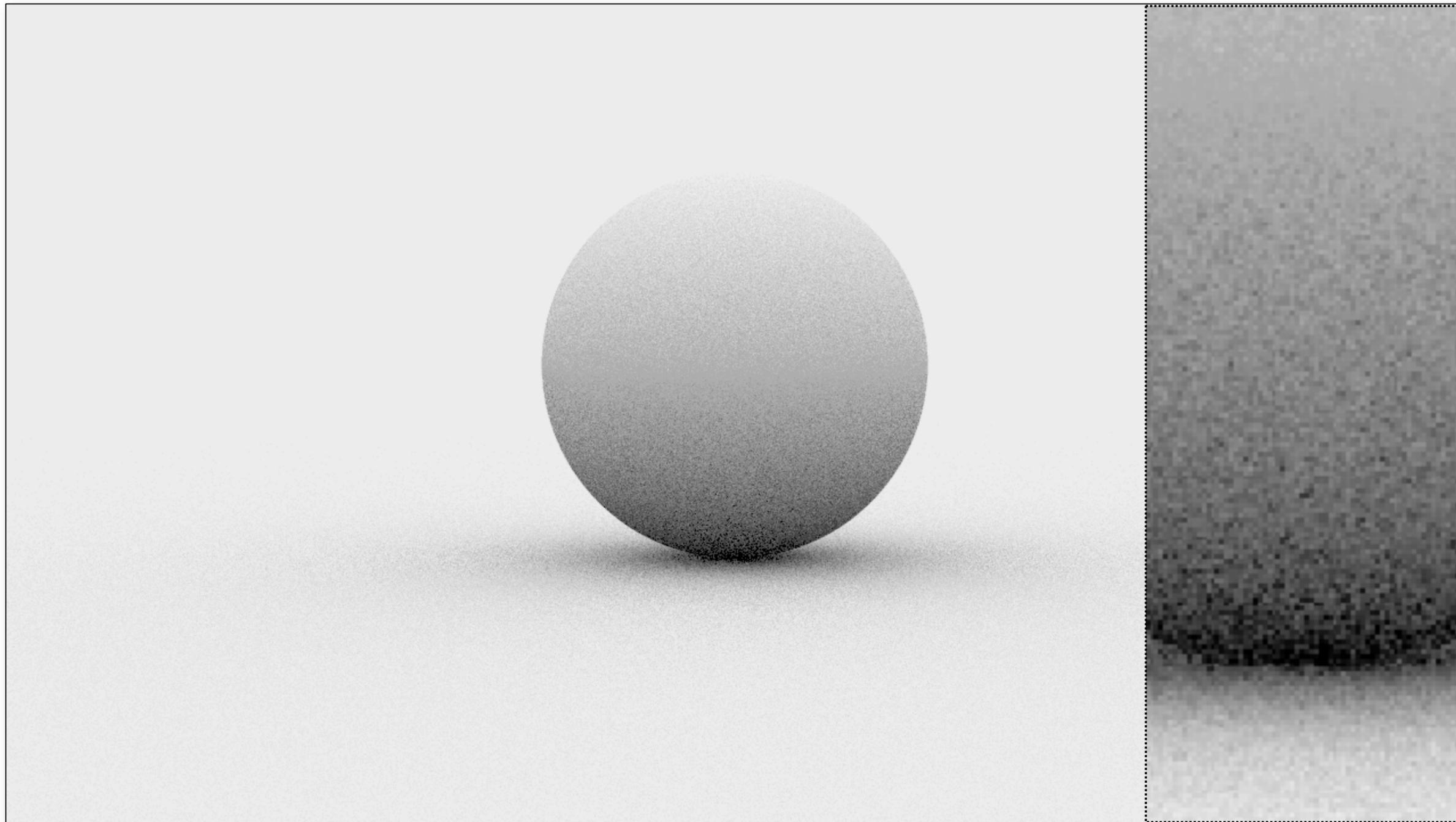
Radial mean



# Monte Carlo (16 random samples)



# Monte Carlo (16 jittered samples)



# Stratifying in Higher Dimensions

---

Stratification requires  $O(N^d)$  samples

- e.g. pixel (2D) + lens (2D) + time (1D) = 5D

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  - splitting 3 times in 5D =  $3^5 = 243$  samples!

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  - splitting 2 times in 5D =  $2^5 = 32$  samples
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Inconvenient for large  $d$

- cannot select sample count with fine granularity

# Uncorrelated Jitter [Cook et al. 84]

---

# Uncorrelated Jitter [Cook et al. 84]

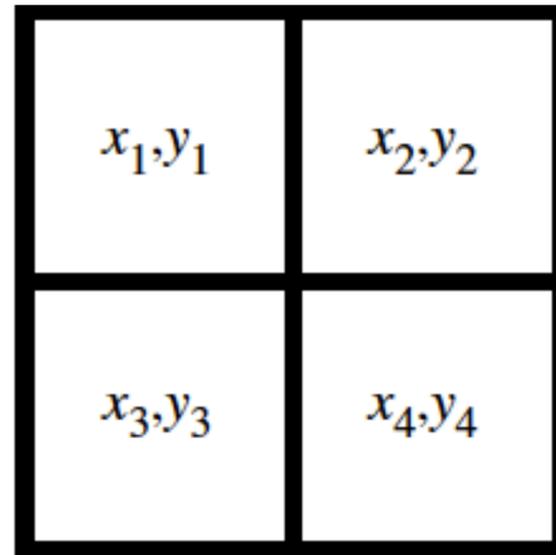
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Compute stratified samples in sub-dimensions

# Uncorrelated Jitter [Cook et al. 84]

Compute stratified samples in sub-dimensions

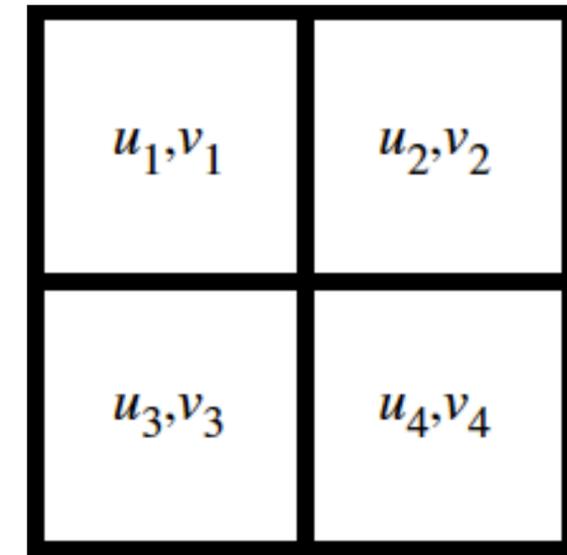
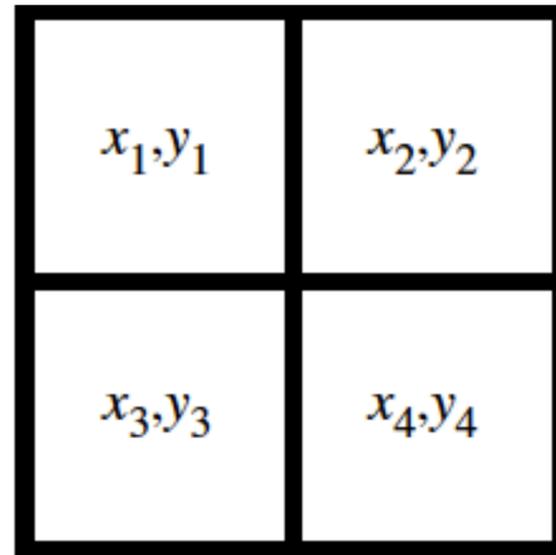
- 2D jittered  $(x,y)$  for pixel



# Uncorrelated Jitter [Cook et al. 84]

Compute stratified samples in sub-dimensions

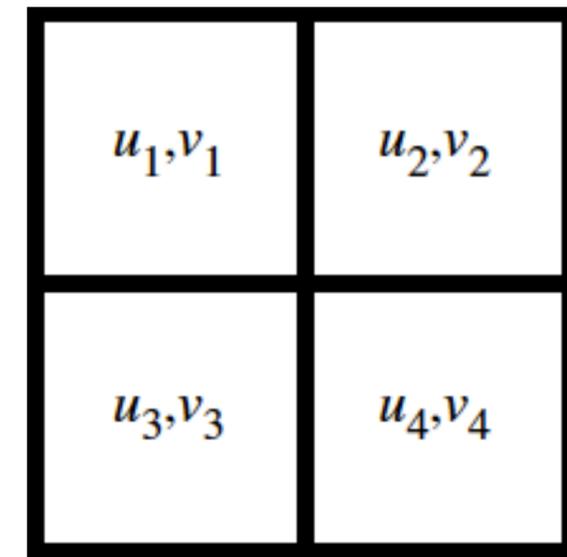
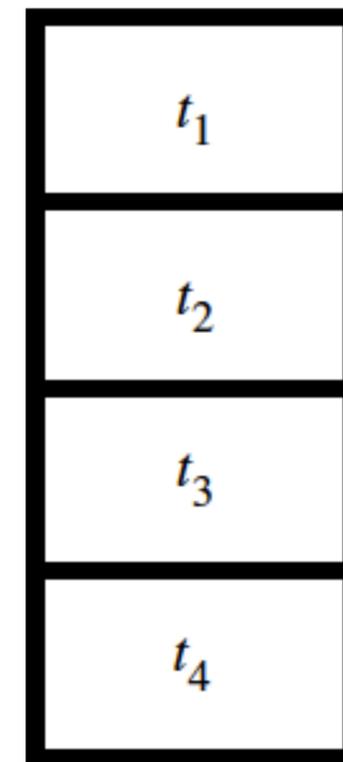
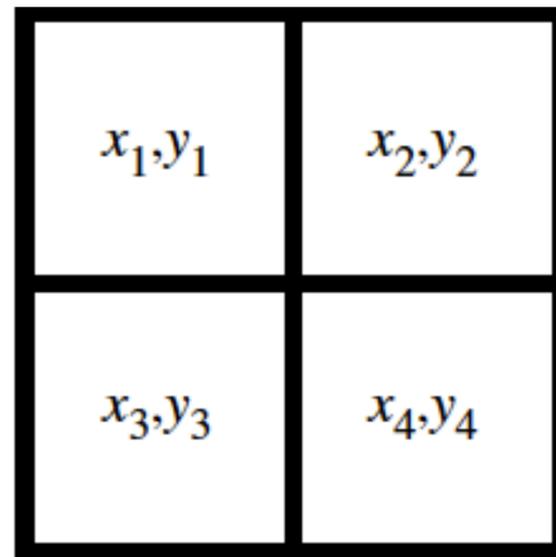
- 2D jittered  $(x,y)$  for pixel
- 2D jittered  $(u,v)$  for lens



# Uncorrelated Jitter [Cook et al. 84]

Compute stratified samples in sub-dimensions

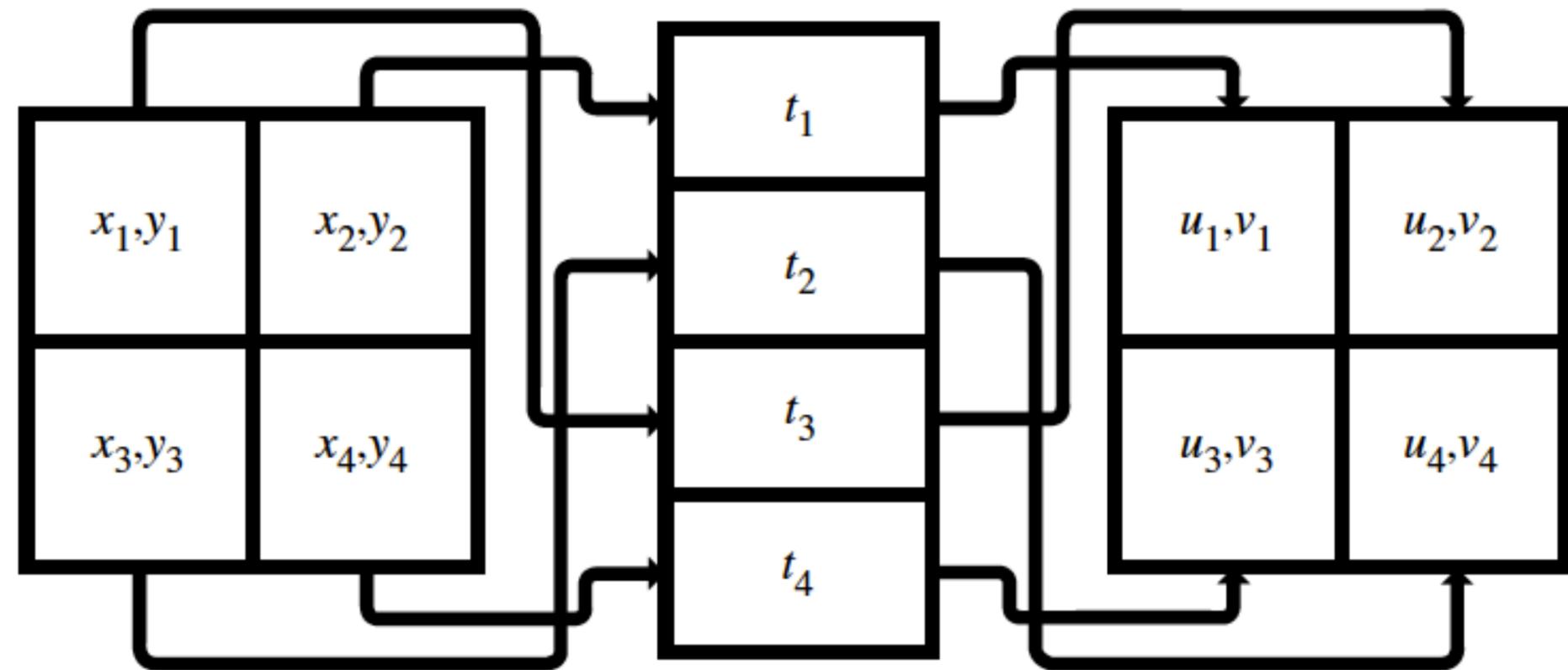
- 2D jittered  $(x,y)$  for pixel
- 2D jittered  $(u,v)$  for lens
- 1D jittered  $(t)$  for time



# Uncorrelated Jitter [Cook et al. 84]

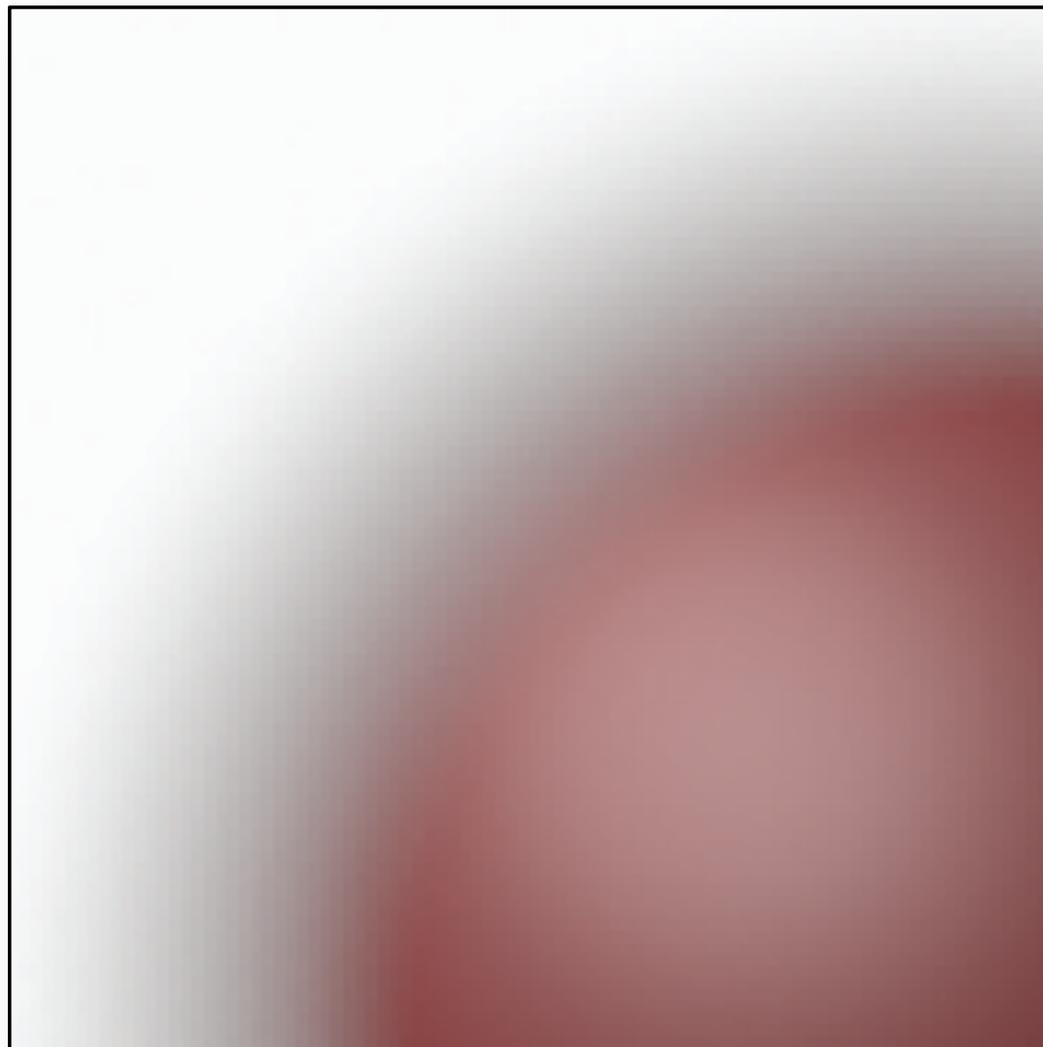
Compute stratified samples in sub-dimensions

- 2D jittered  $(x,y)$  for pixel
- 2D jittered  $(u,v)$  for lens
- 1D jittered  $(t)$  for time
- combine dimensions in random order

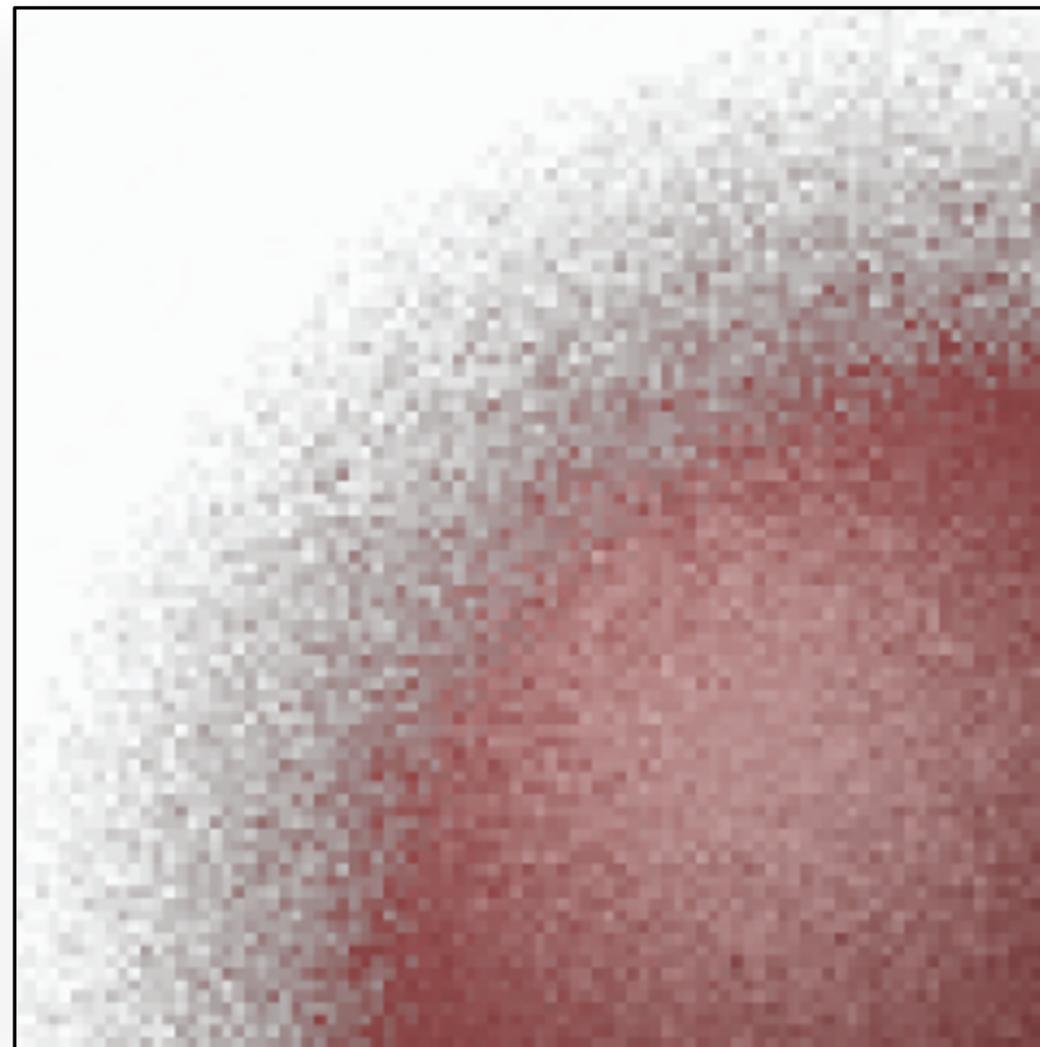


# Depth of Field (4D)

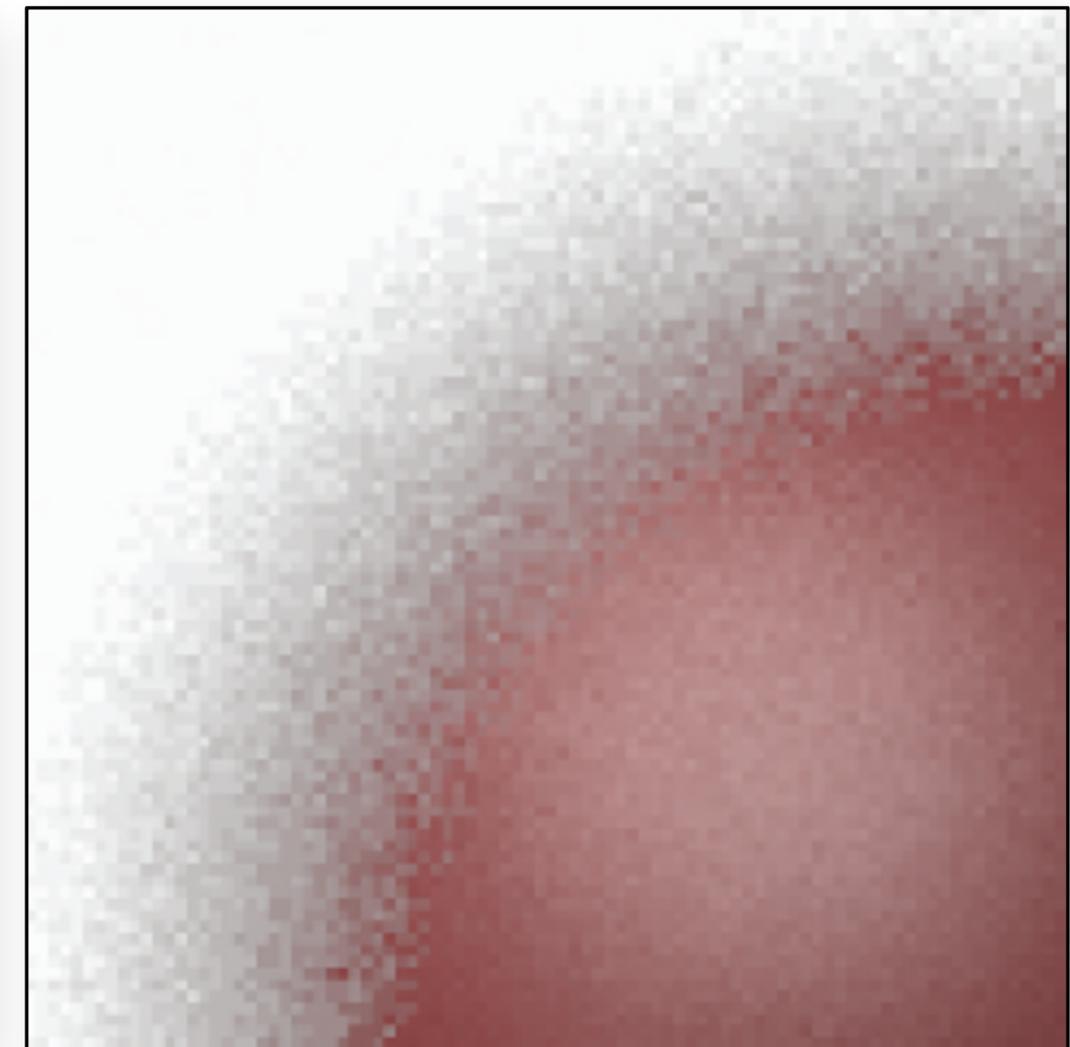
Reference



Random Sampling



Uncorrelated Jitter



# Uncorrelated Jitter → Latin Hypercube

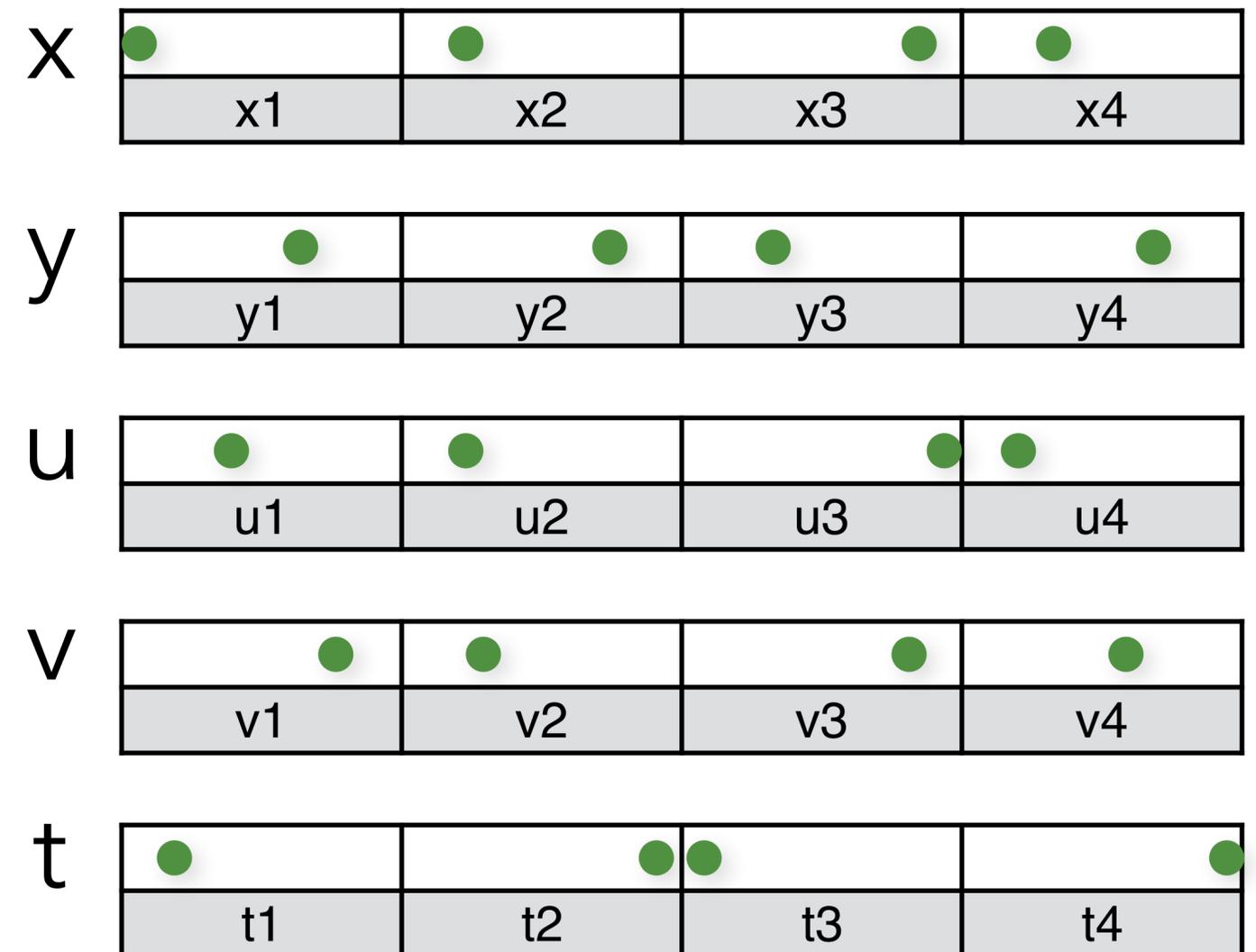
---

Stratify samples in each dimension separately

# Uncorrelated Jitter → Latin Hypercube

Stratify samples in each dimension separately

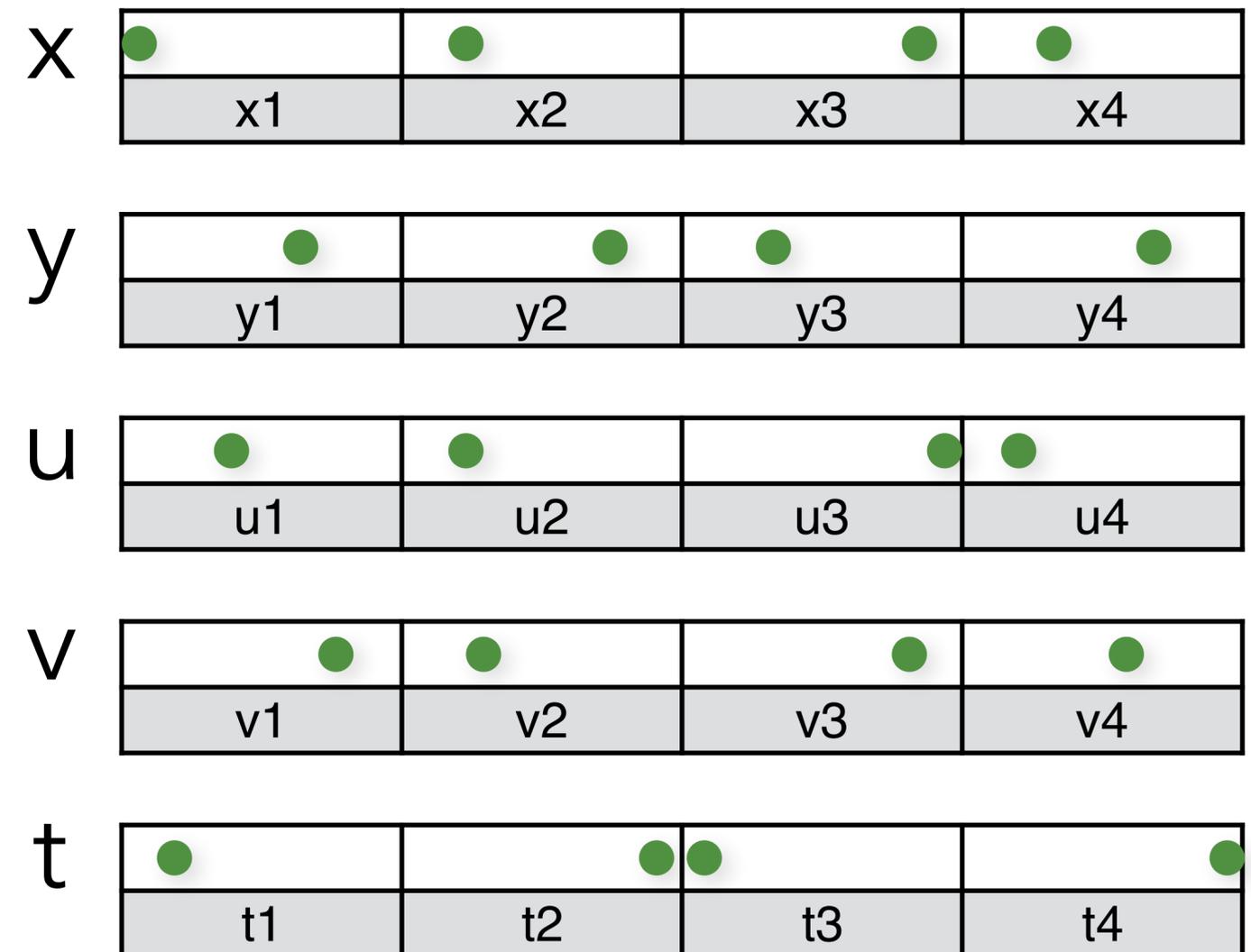
- for 5D: 5 separate 1D jittered point sets



# Uncorrelated Jitter → Latin Hypercube

Stratify samples in each dimension separately

- for 5D: 5 separate 1D jittered point sets
- combine dimensions in random order

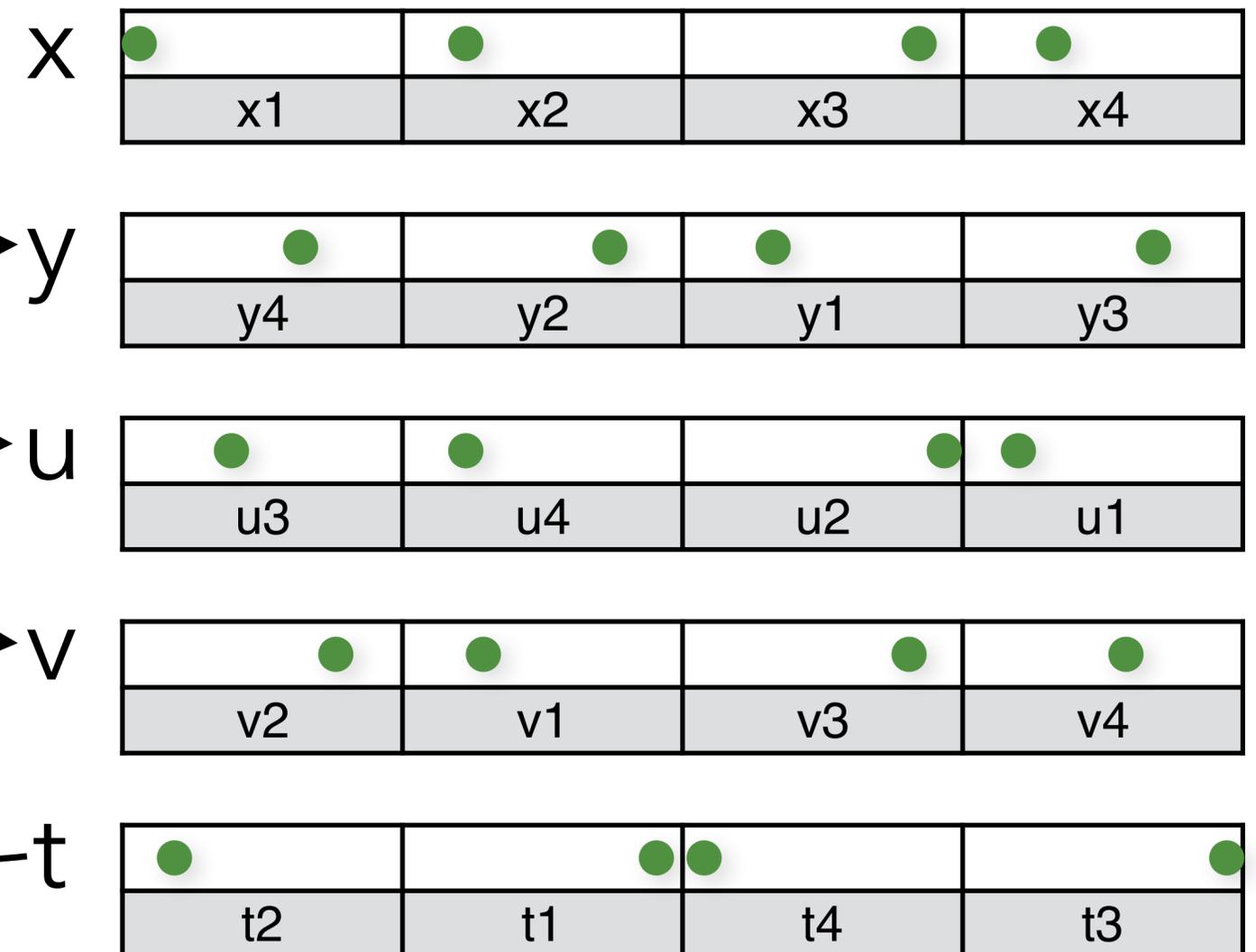


# Uncorrelated Jitter → Latin Hypercube

Stratify samples in each dimension separately

- for 5D: 5 separate 1D jittered point sets
- combine dimensions in random order

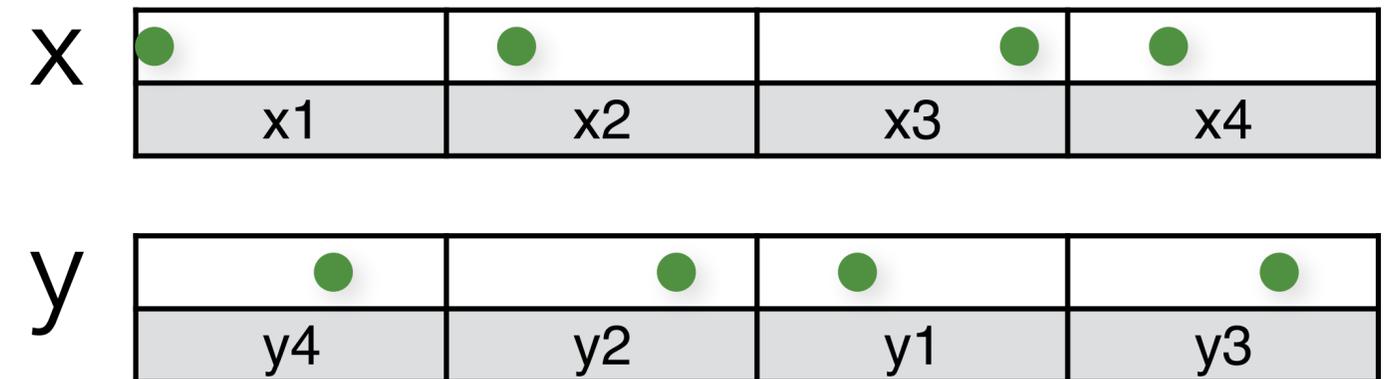
Shuffle order



# N-Rooks = 2D Latin Hypercube [Shirley 91]

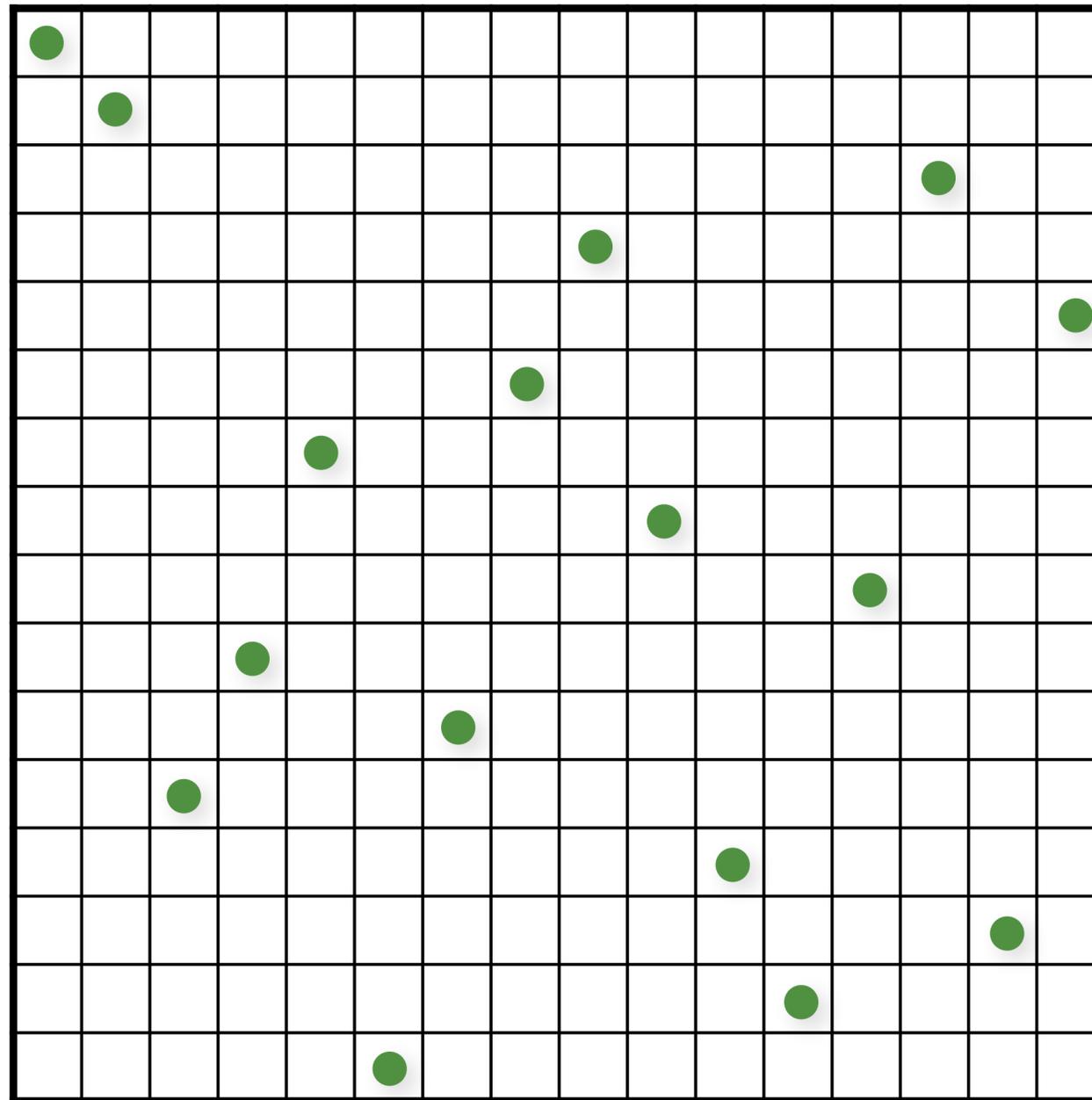
Stratify samples in each dimension separately

- for **2D**: **2** separate 1D jittered point sets
- combine dimensions in random order



# Latin Hypercube (N-Rooks) Sampling

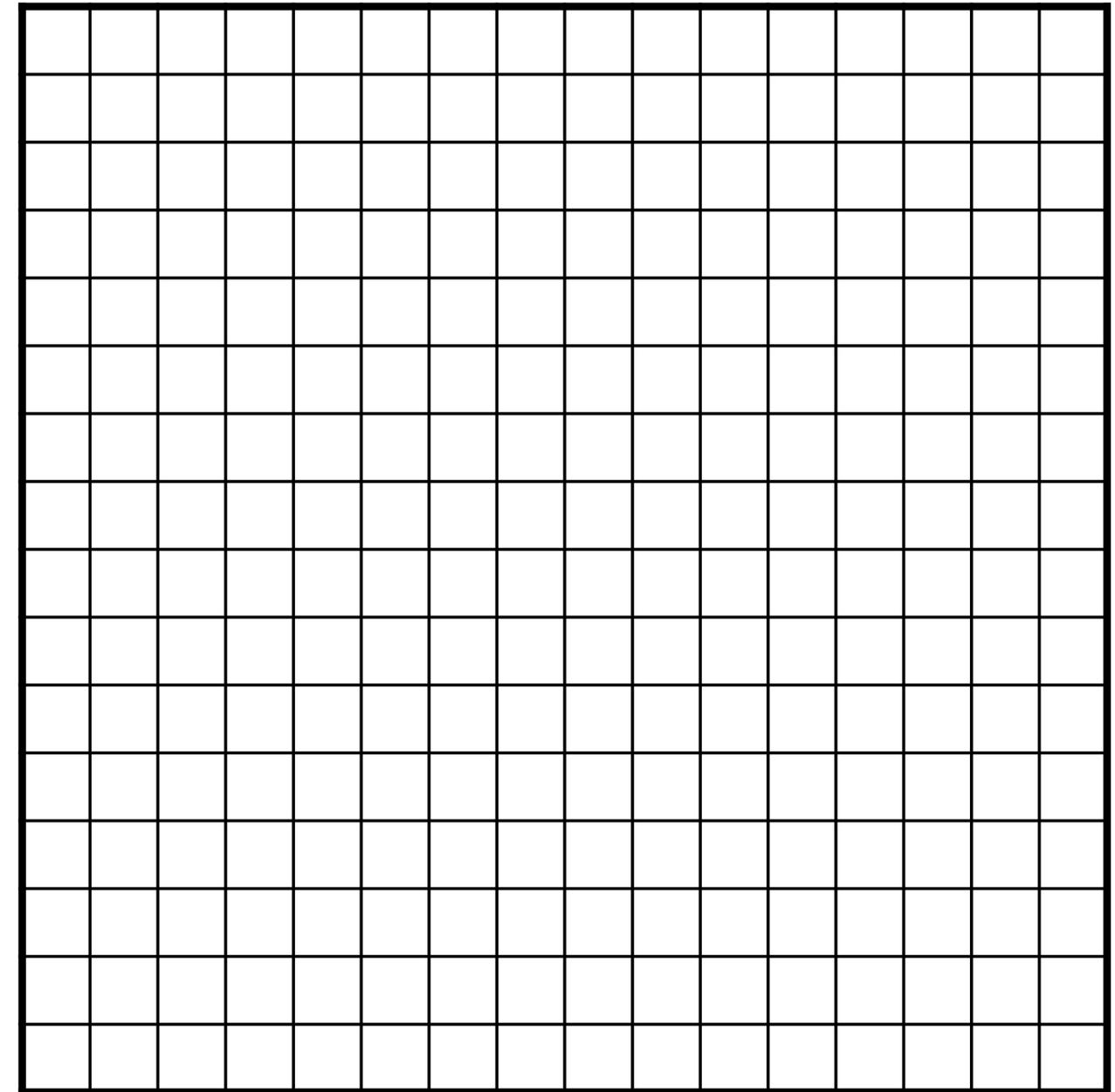
[Shirley 91]



# Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;
```

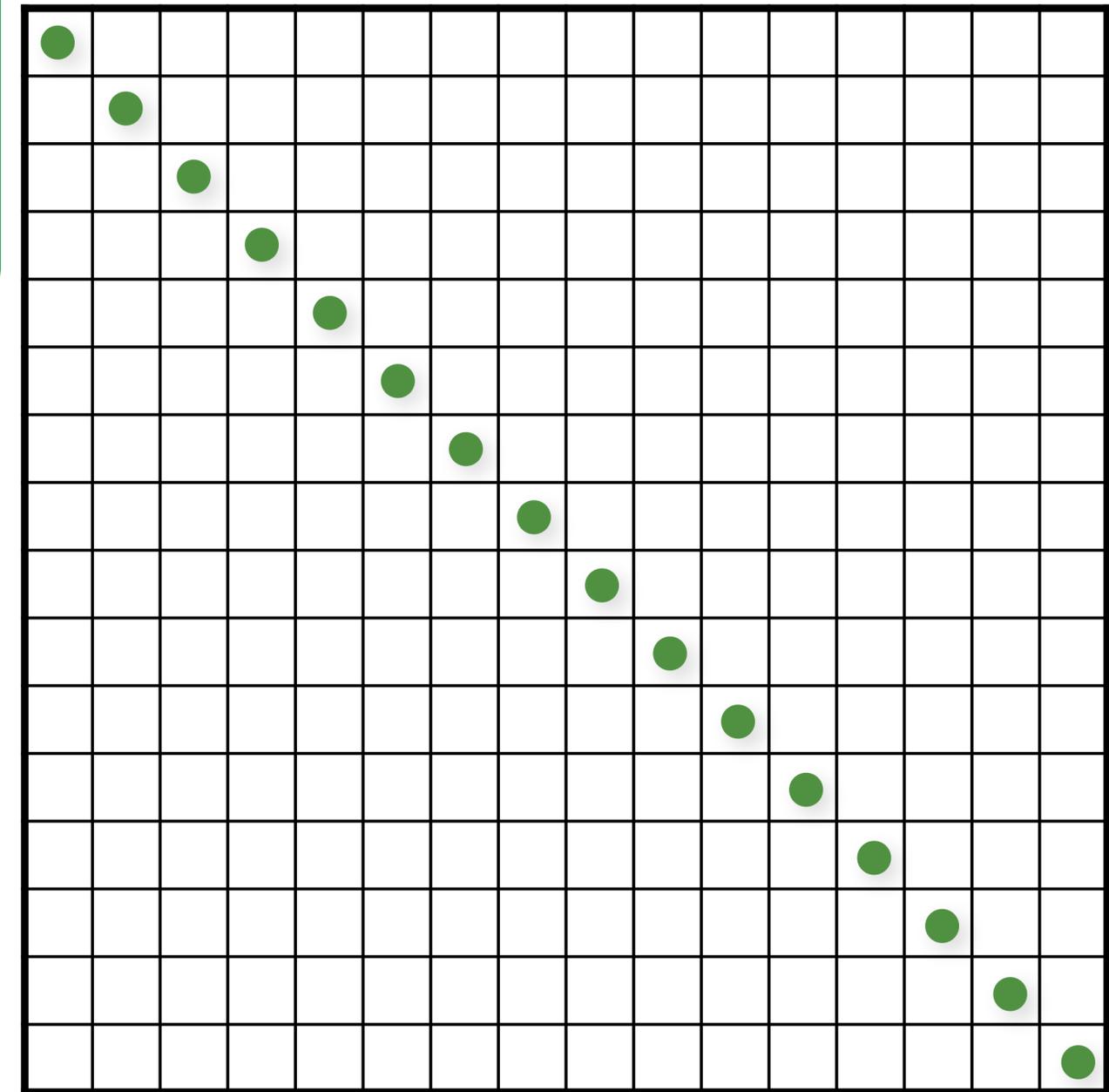
```
// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));
```



# Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal  
for (uint d = 0; d < numDimensions; d++)  
    for (uint i = 0; i < numS; i++)  
        samples(d,i) = (i + randf())/numS;
```

```
// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```



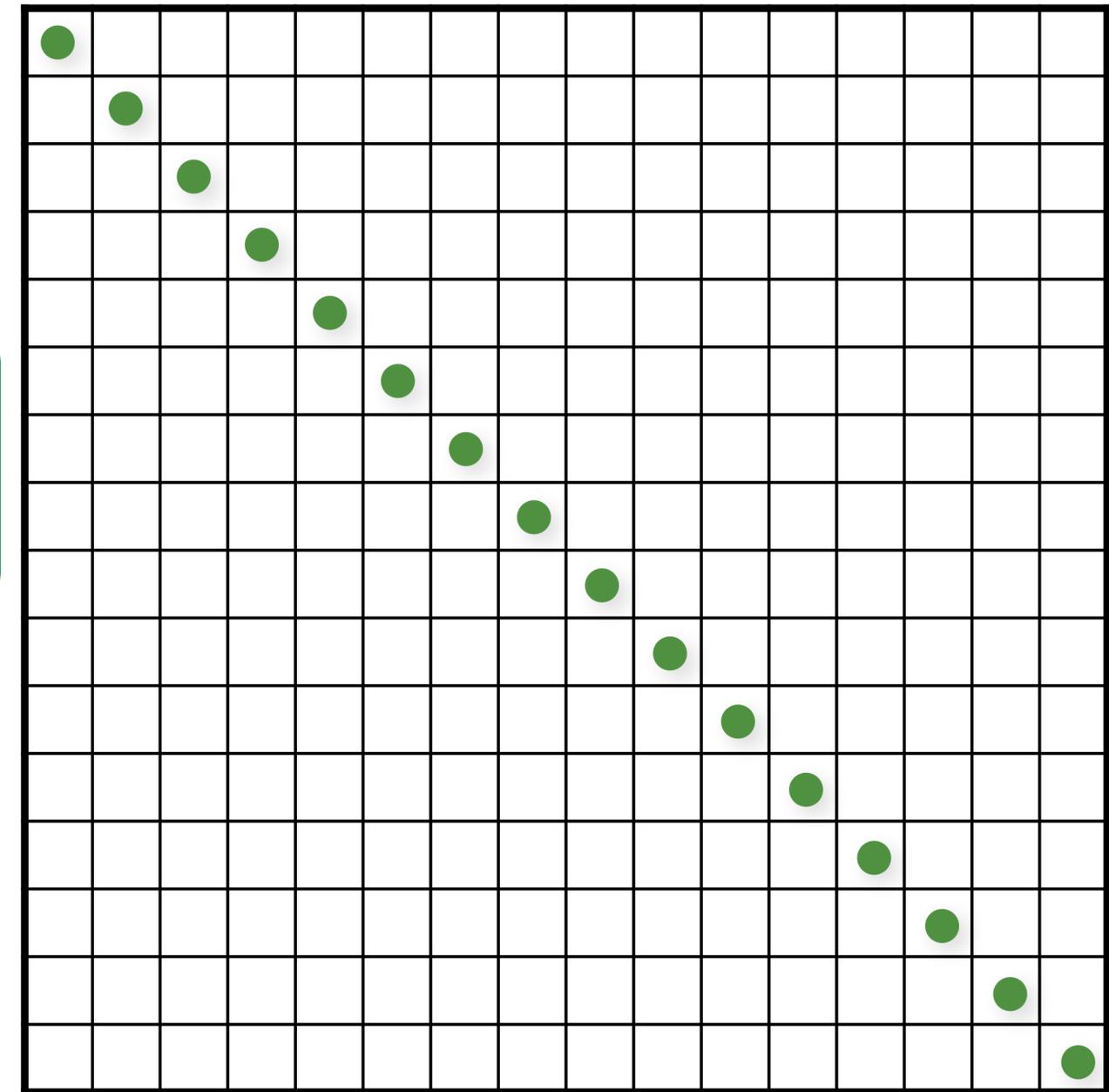
Initialize

23

# Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal  
for (uint d = 0; d < numDimensions; d++)  
    for (uint i = 0; i < numS; i++)  
        samples(d,i) = (i + randf())/numS;
```

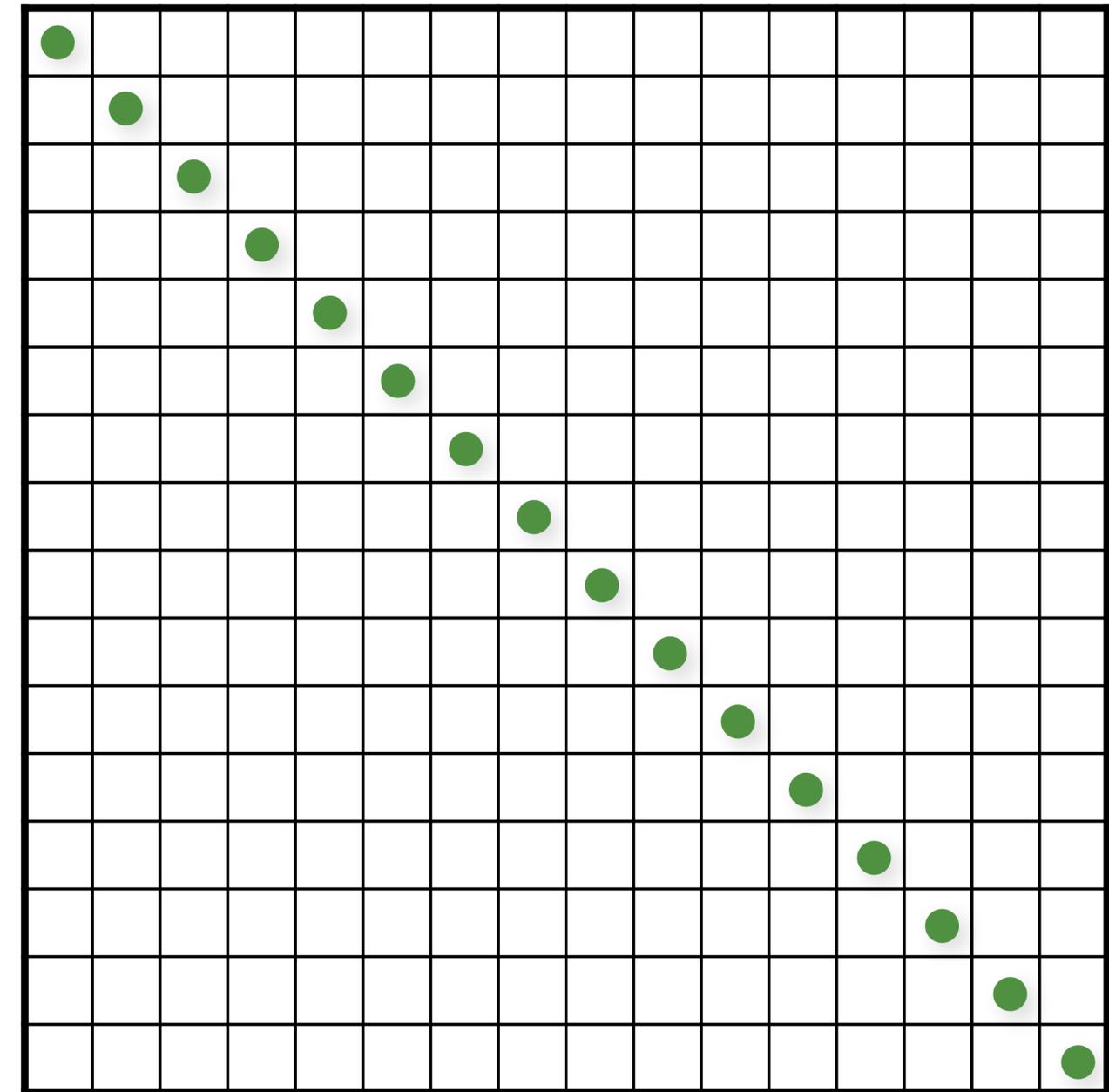
```
// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```



# Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal  
for (uint d = 0; d < numDimensions; d++)  
    for (uint i = 0; i < numS; i++)  
        samples(d,i) = (i + randf())/numS;
```

```
// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```



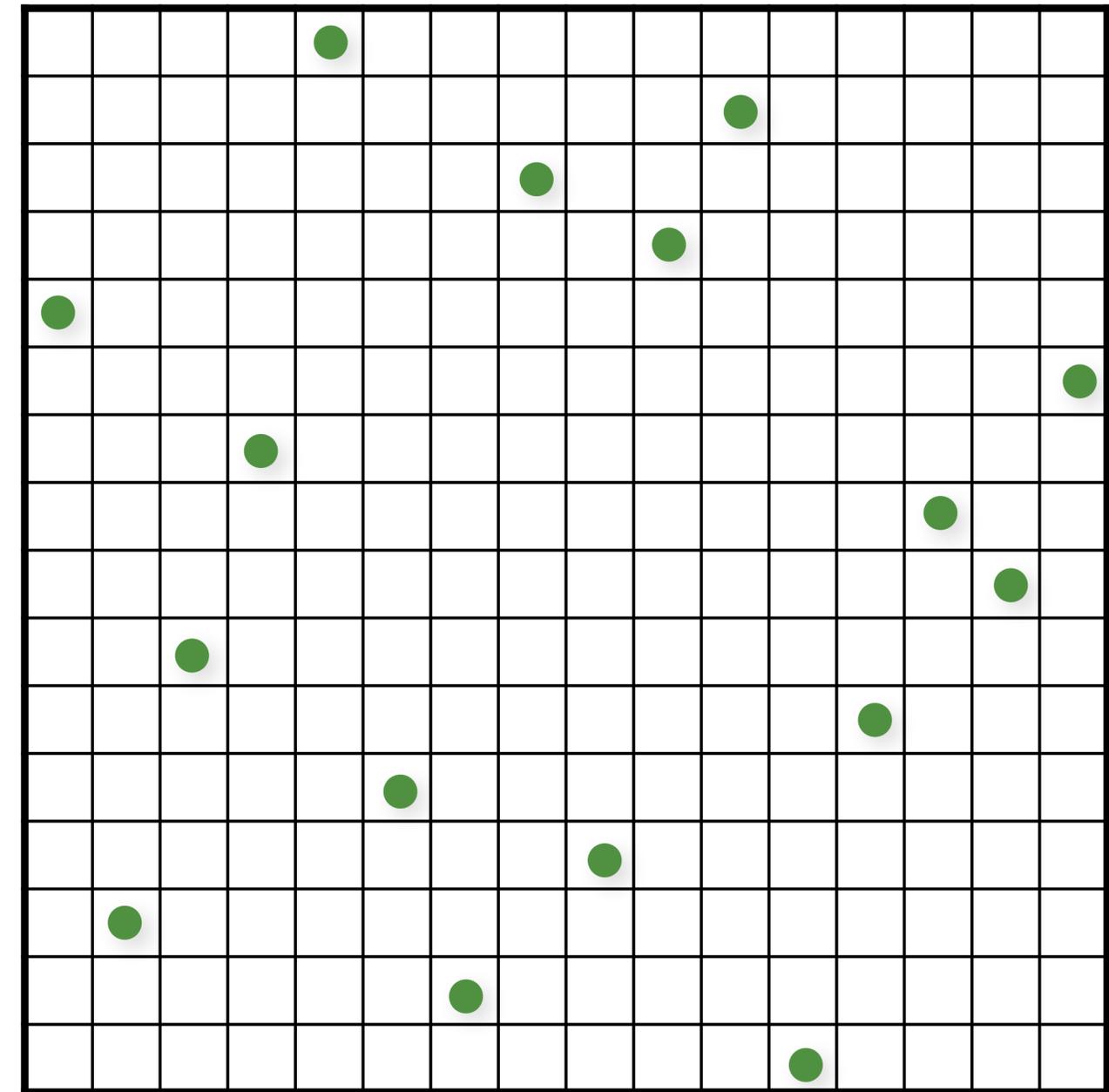
Shuffle rows

24

# Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal  
for (uint d = 0; d < numDimensions; d++)  
    for (uint i = 0; i < numS; i++)  
        samples(d,i) = (i + randf())/numS;
```

```
// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```

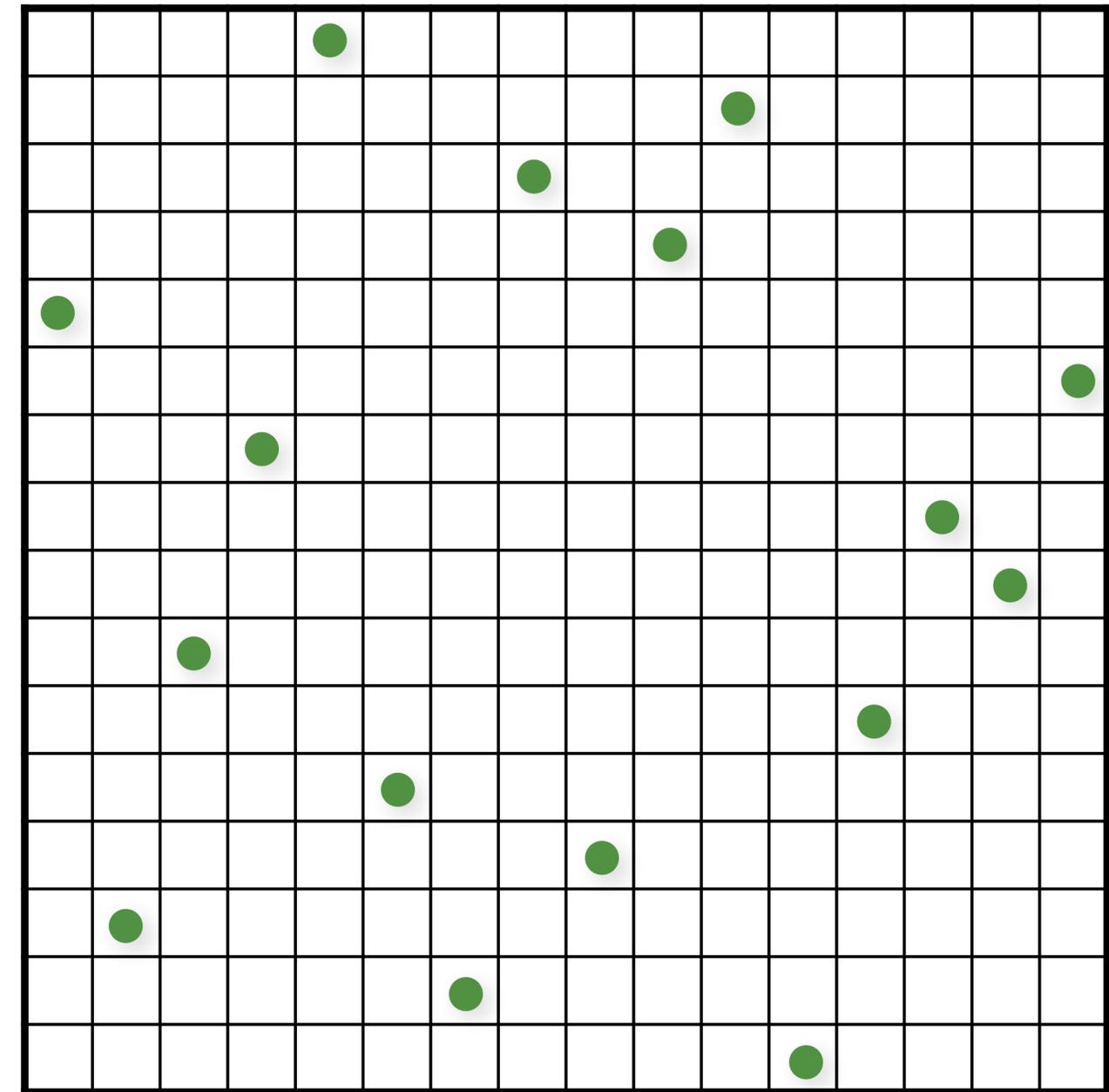


Shuffle rows

# Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;
```

```
// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));
```

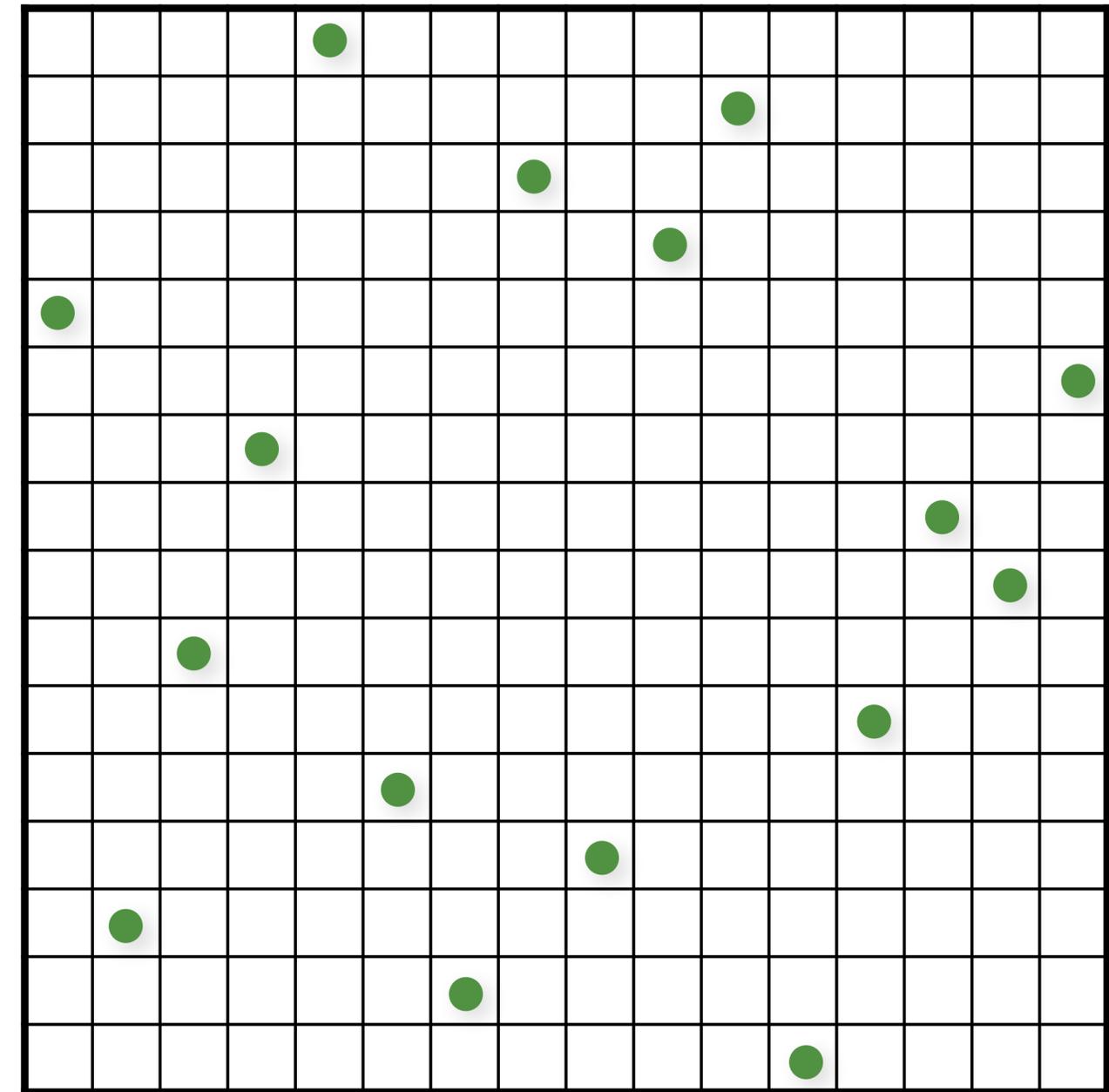


Shuffle rows

# Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal  
for (uint d = 0; d < numDimensions; d++)  
    for (uint i = 0; i < numS; i++)  
        samples(d,i) = (i + randf())/numS;
```

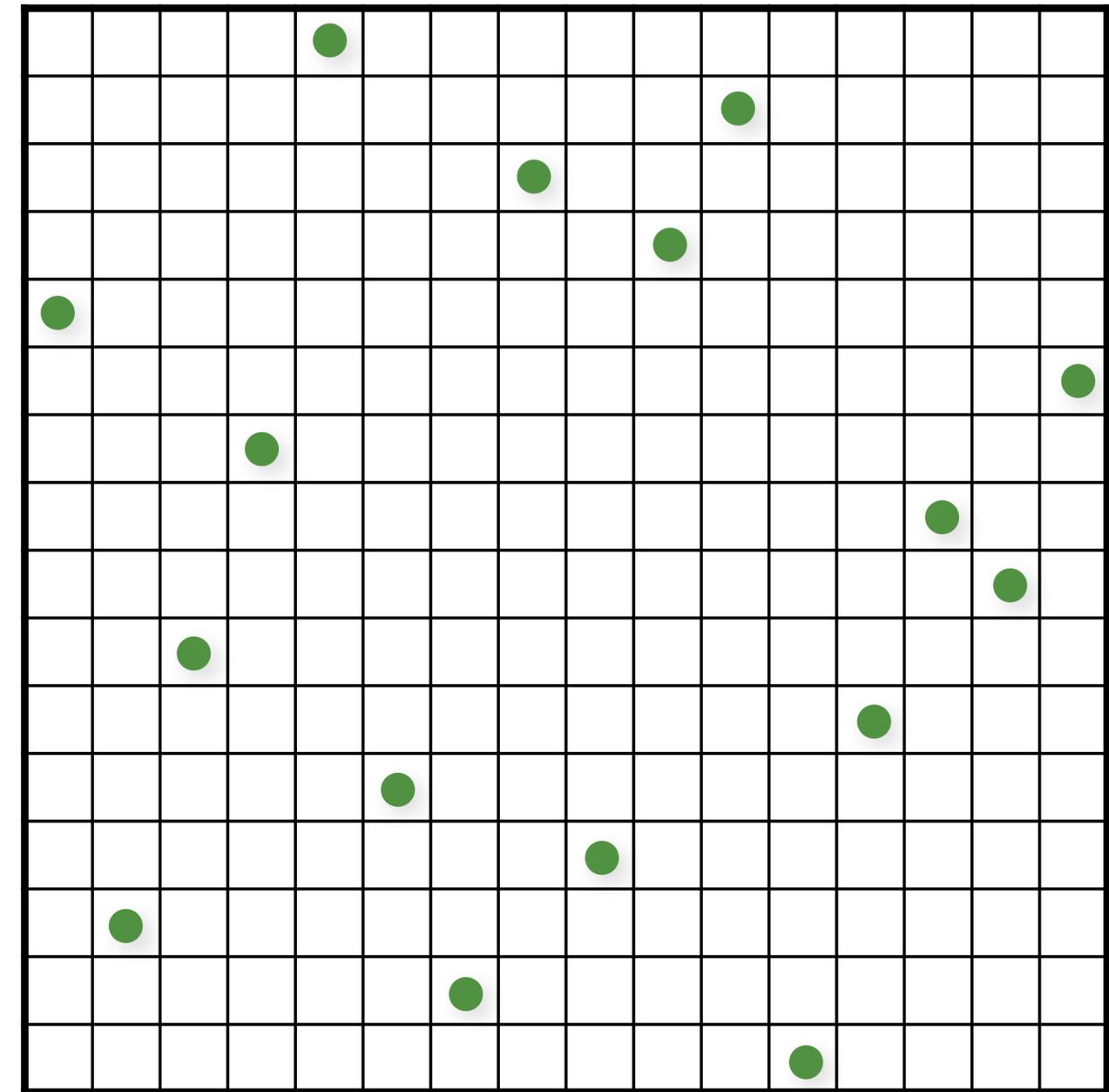
```
// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```



# Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;
```

```
// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));
```

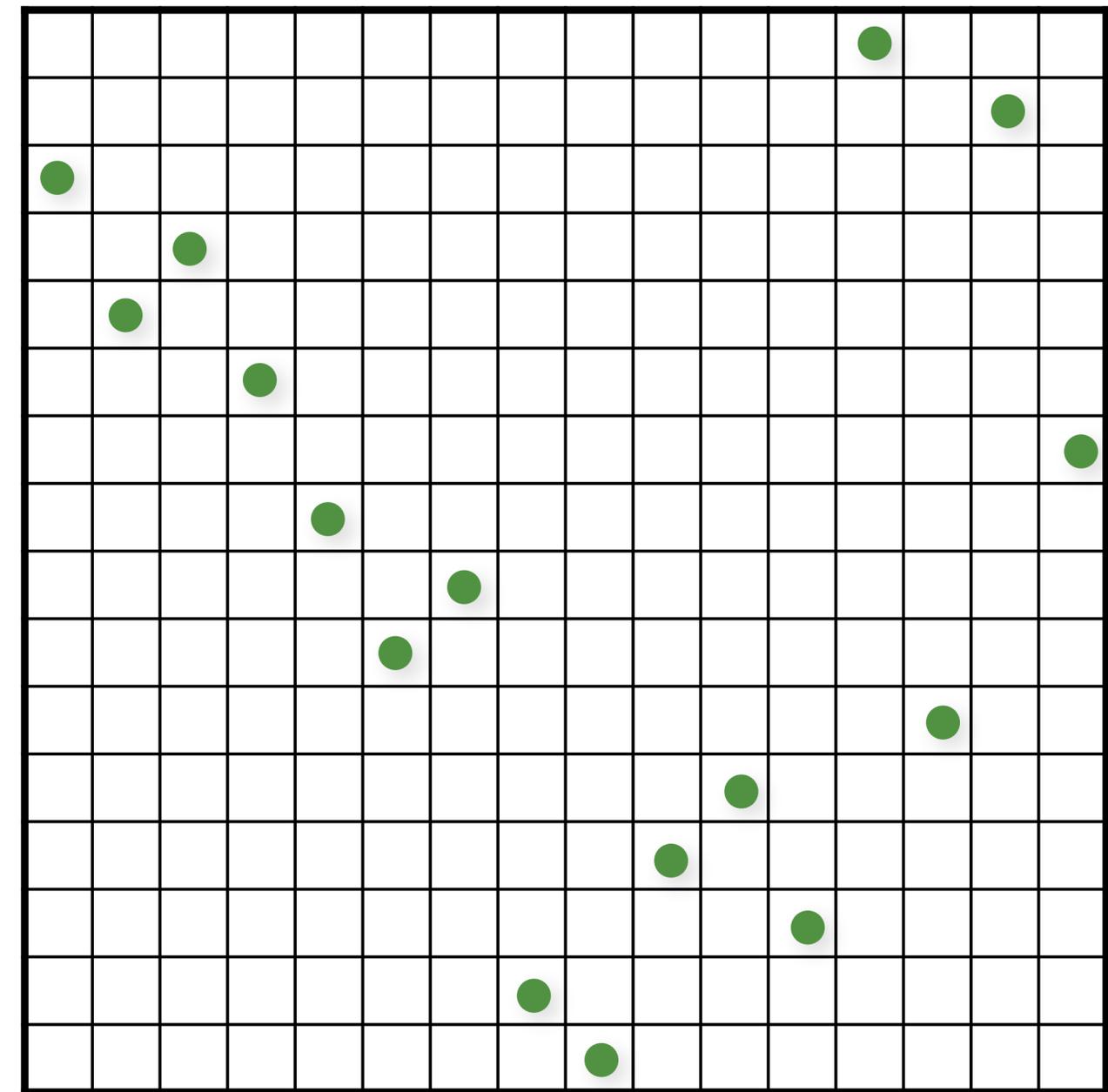


Shuffle columns

# Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal  
for (uint d = 0; d < numDimensions; d++)  
    for (uint i = 0; i < numS; i++)  
        samples(d,i) = (i + randf())/numS;
```

```
// shuffle each dimension independently  
for (uint d = 0; d < numDimensions; d++)  
    shuffle(samples(d,:));
```

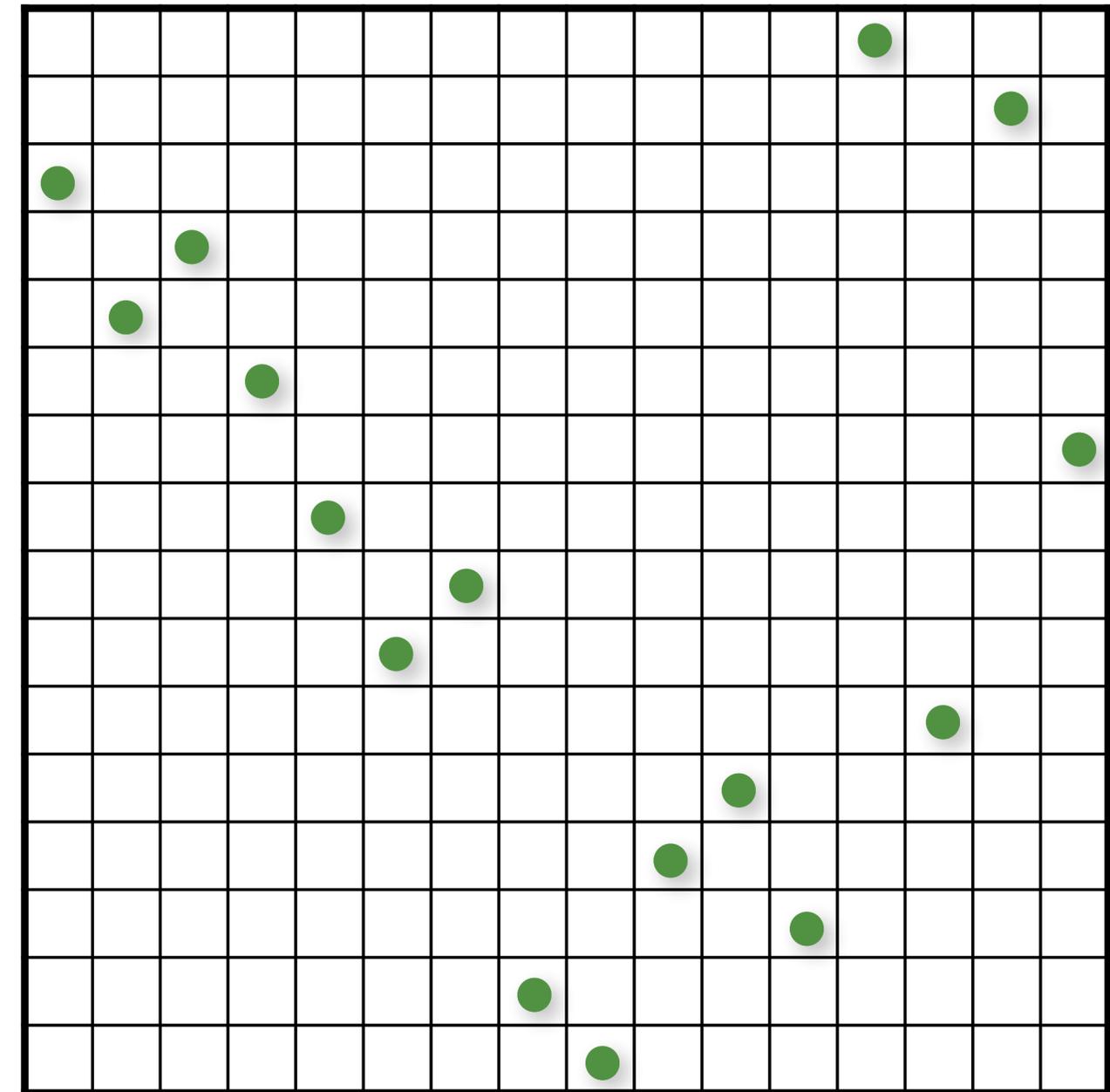


Shuffle columns

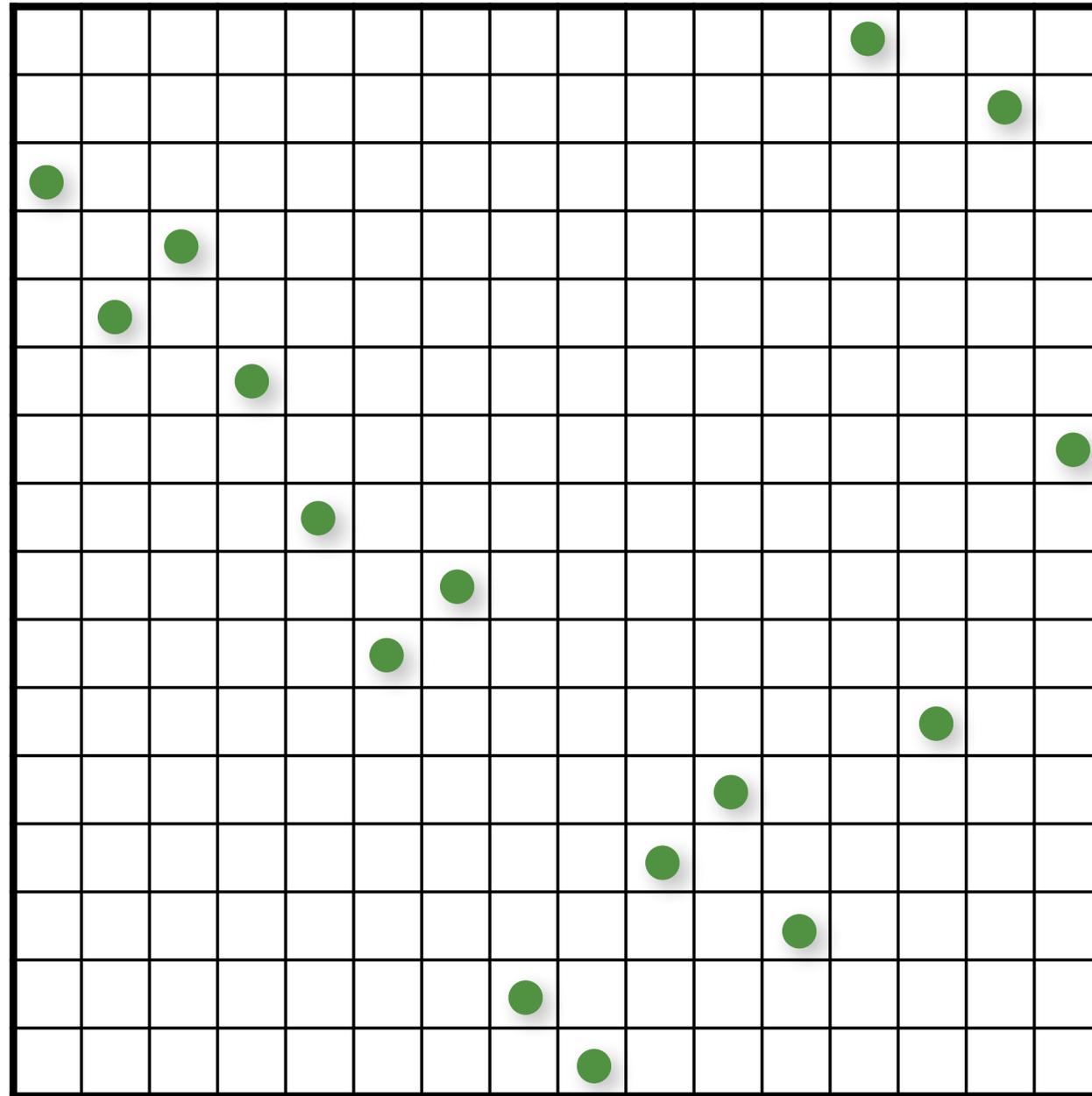
# Latin Hypercube (N-Rooks) Sampling

```
// initialize the diagonal
for (uint d = 0; d < numDimensions; d++)
    for (uint i = 0; i < numS; i++)
        samples(d,i) = (i + randf())/numS;
```

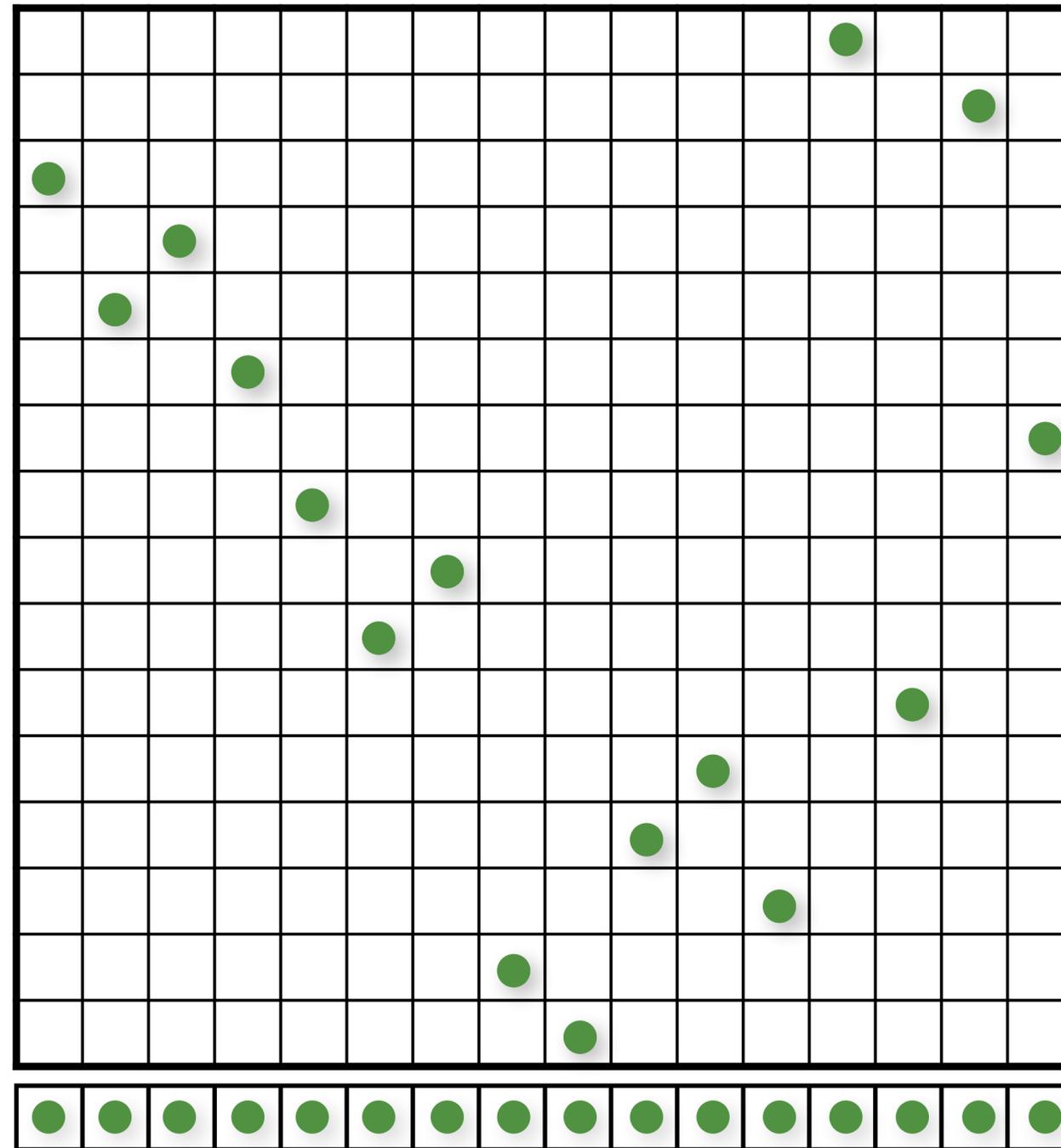
```
// shuffle each dimension independently
for (uint d = 0; d < numDimensions; d++)
    shuffle(samples(d,:));
```



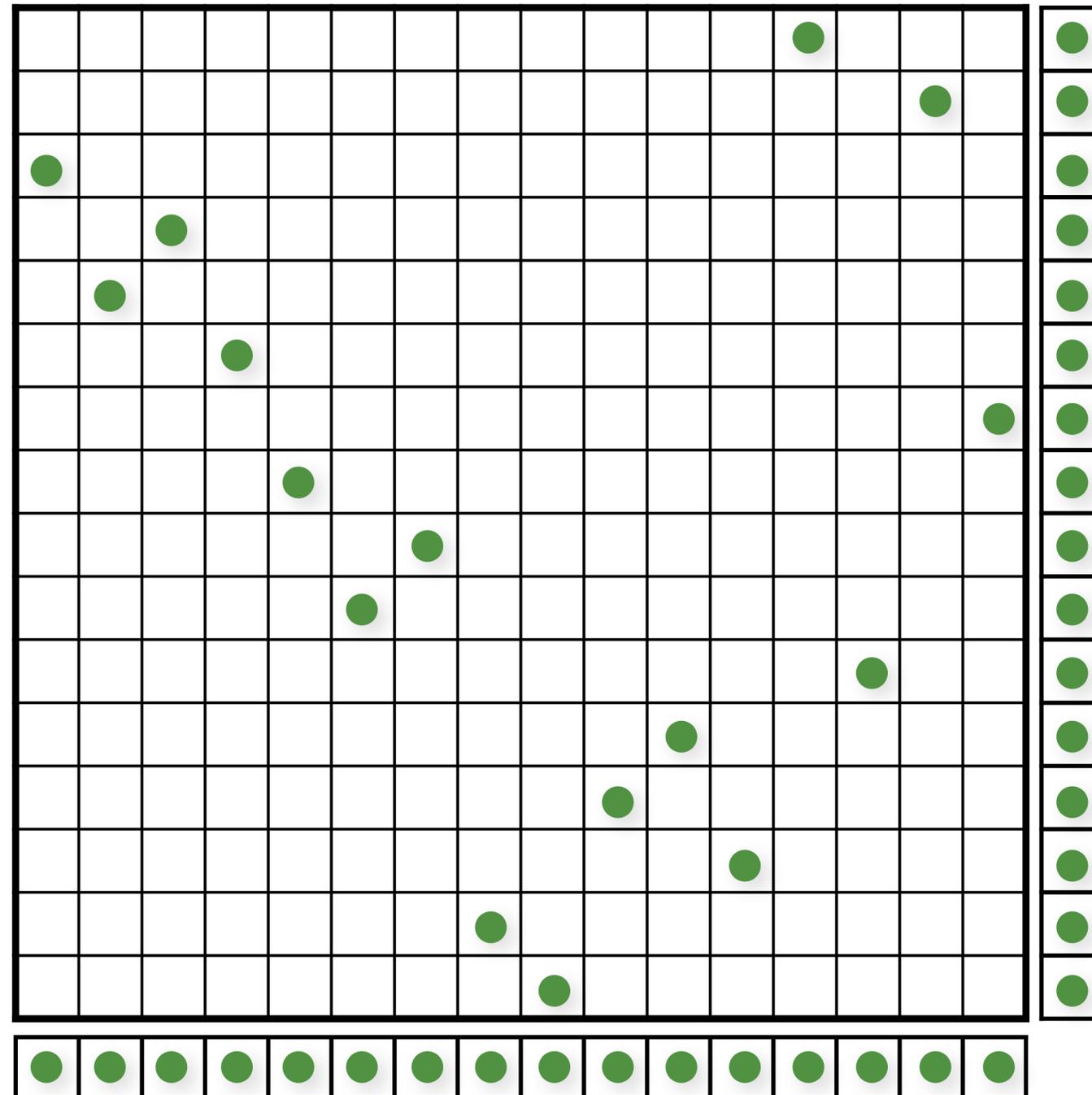
# Latin Hypercube (N-Rooks) Sampling



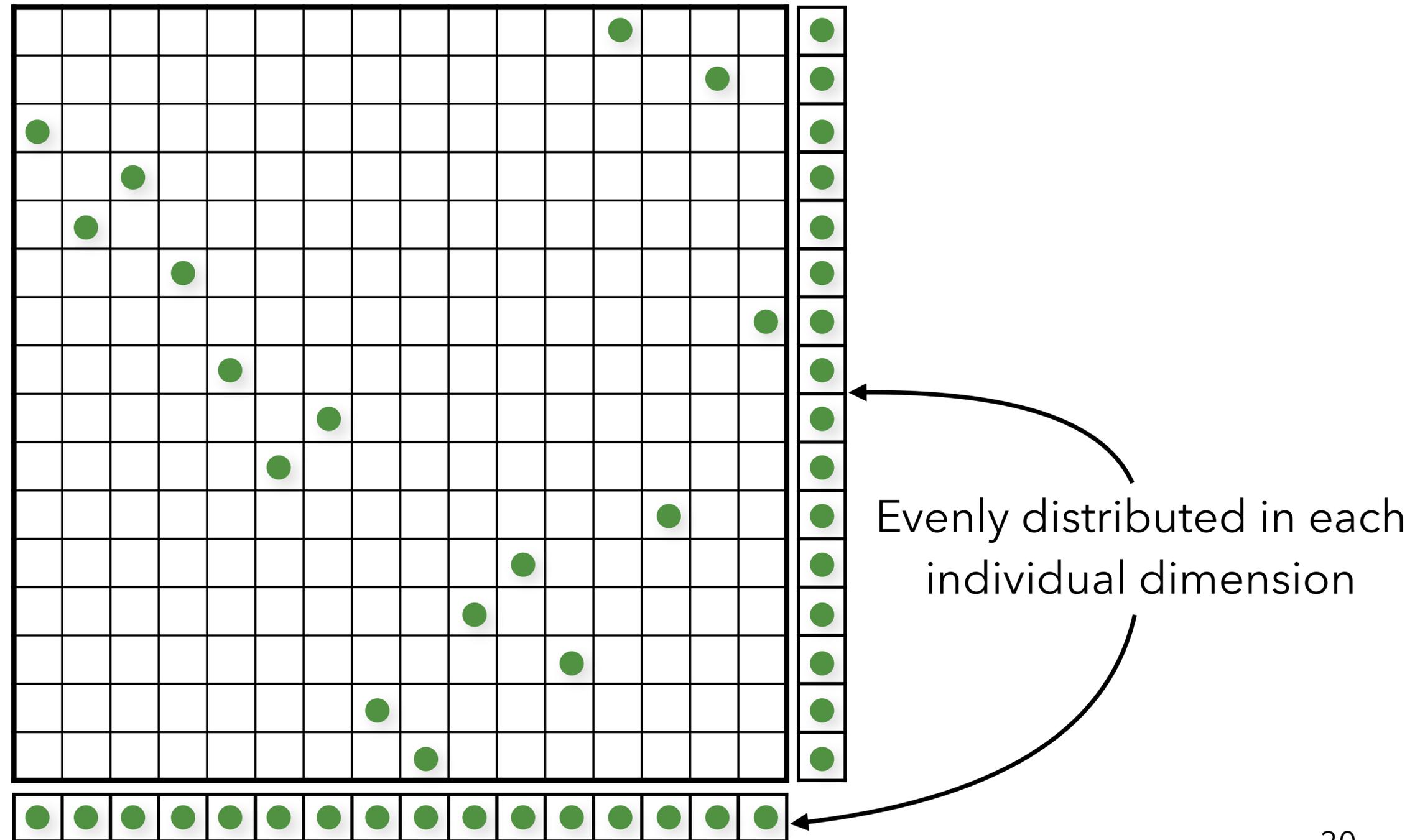
# Latin Hypercube (N-Rooks) Sampling



# Latin Hypercube (N-Rooks) Sampling

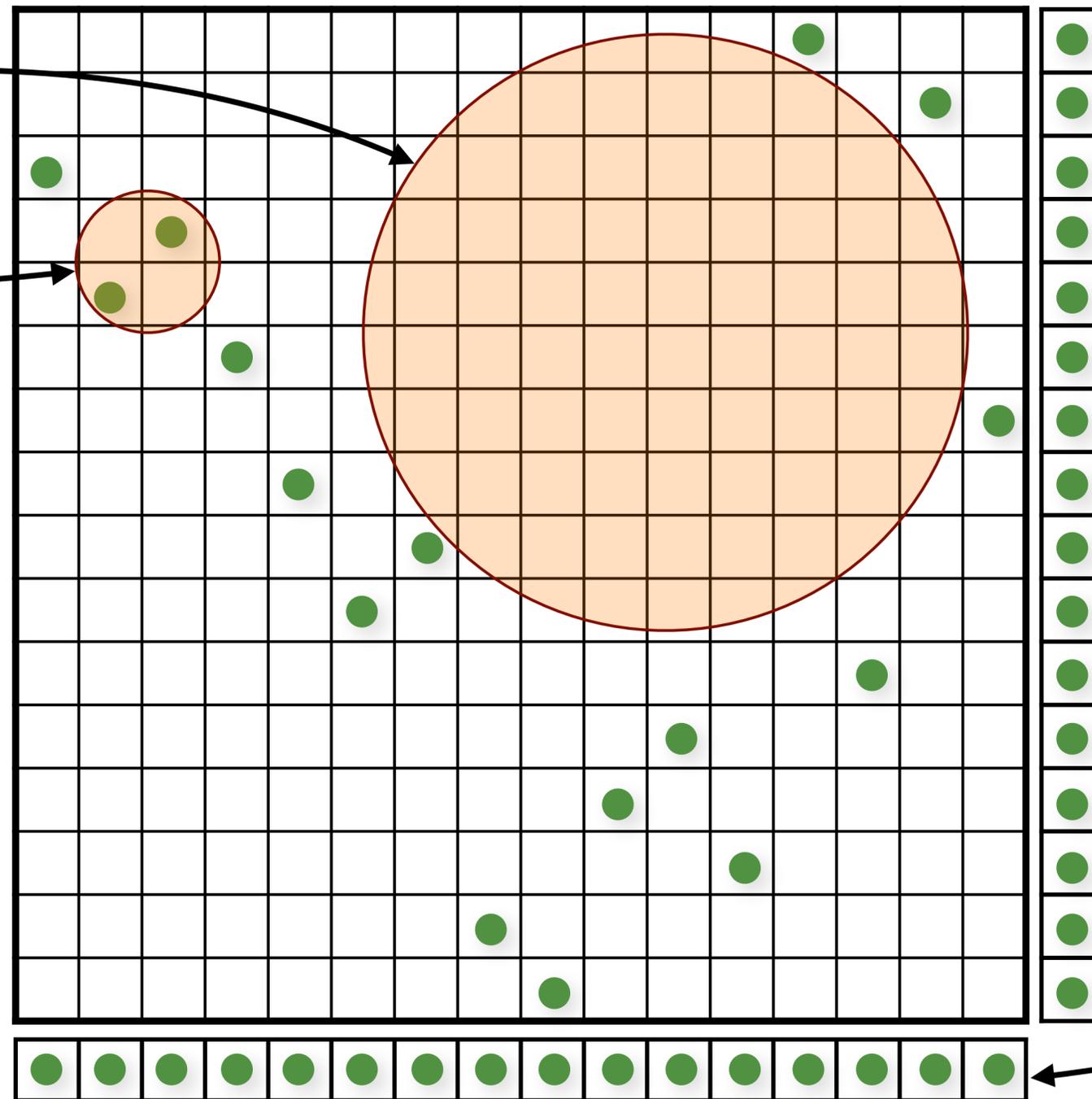


# Latin Hypercube (N-Rooks) Sampling



# Latin Hypercube (N-Rooks) Sampling

Unevenly distributed  
in n-dimensions



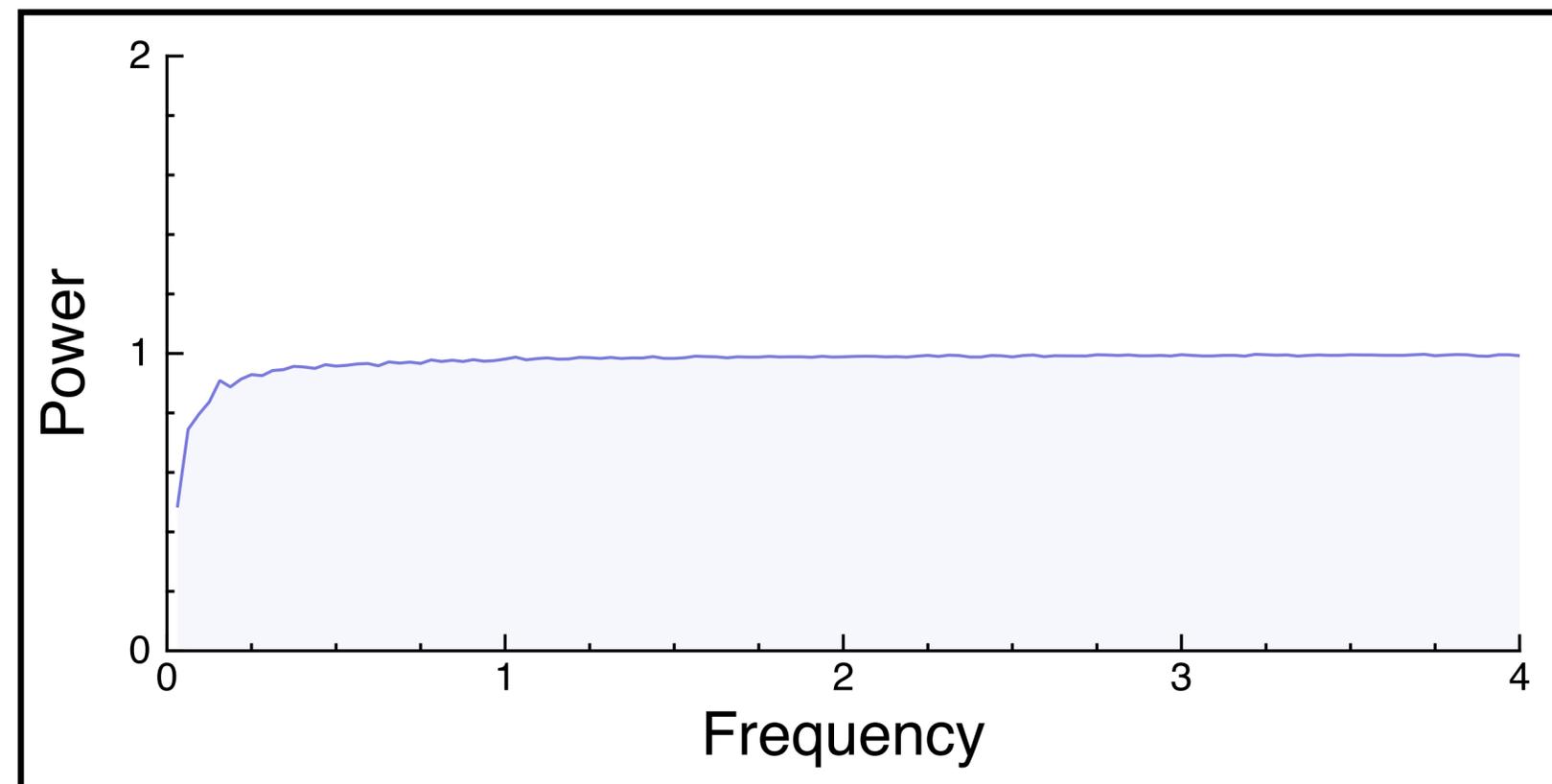
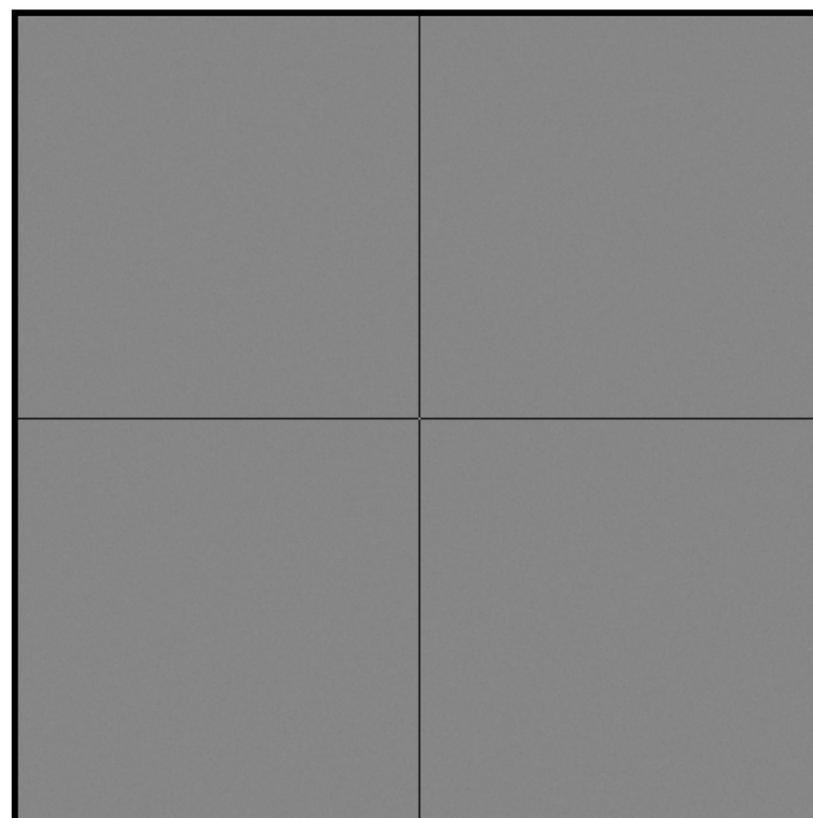
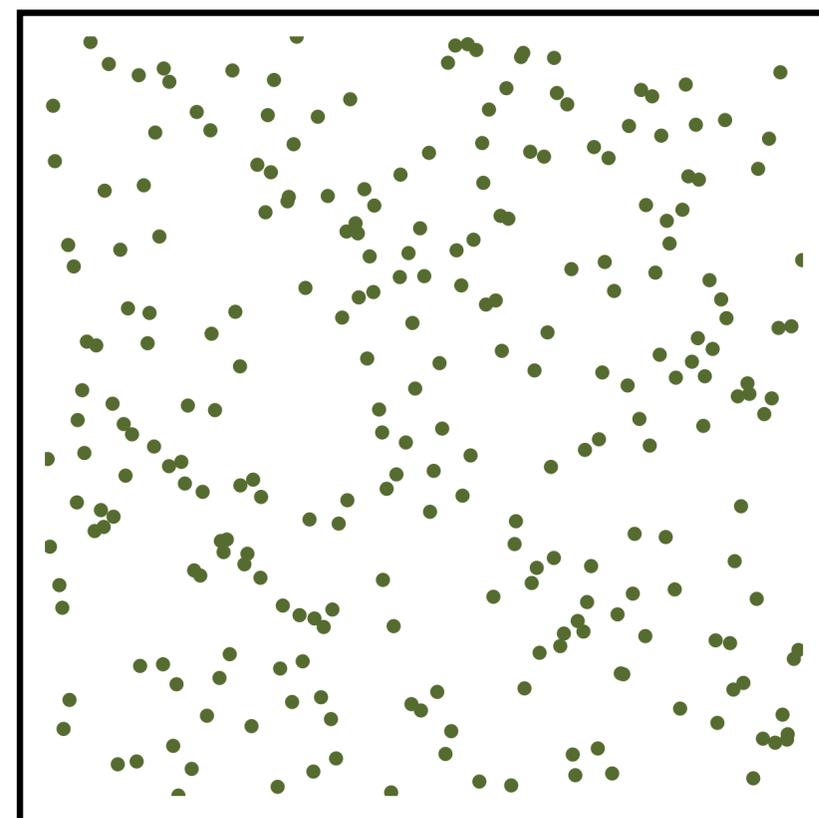
Evenly distributed in each  
individual dimension

# N-Rooks Sampling

Samples

Expected power spectrum

Radial mean

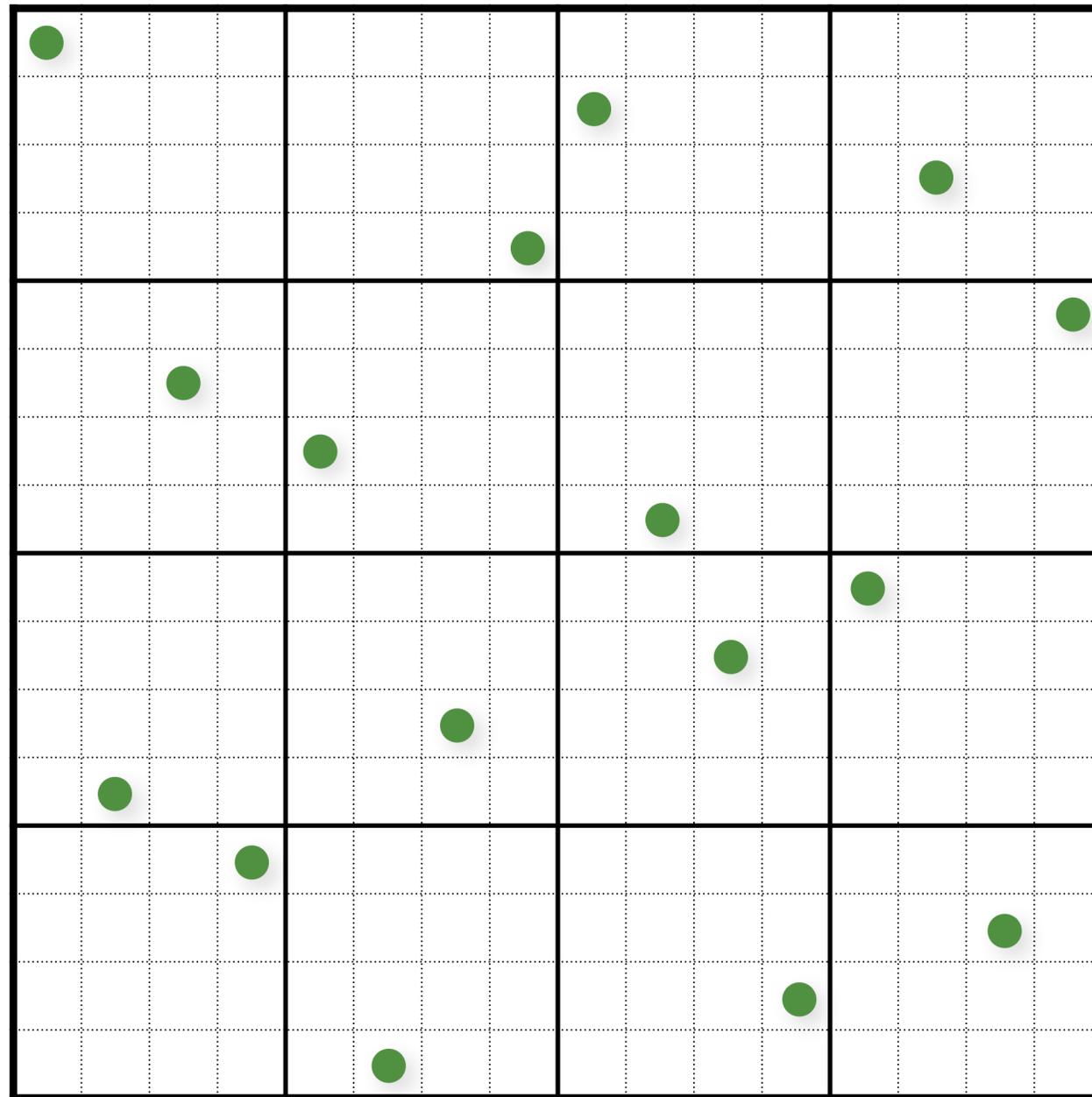


# Multi-Jittered Sampling

Kenneth Chiu, Peter Shirley, and Changyaw Wang.  
“Multi-jittered sampling.” In *Graphics Gems IV*, pp.  
370–374. Academic Press, May 1994.

- combine N-Rooks and Jittered stratification constraints

# Multi-Jittered Sampling



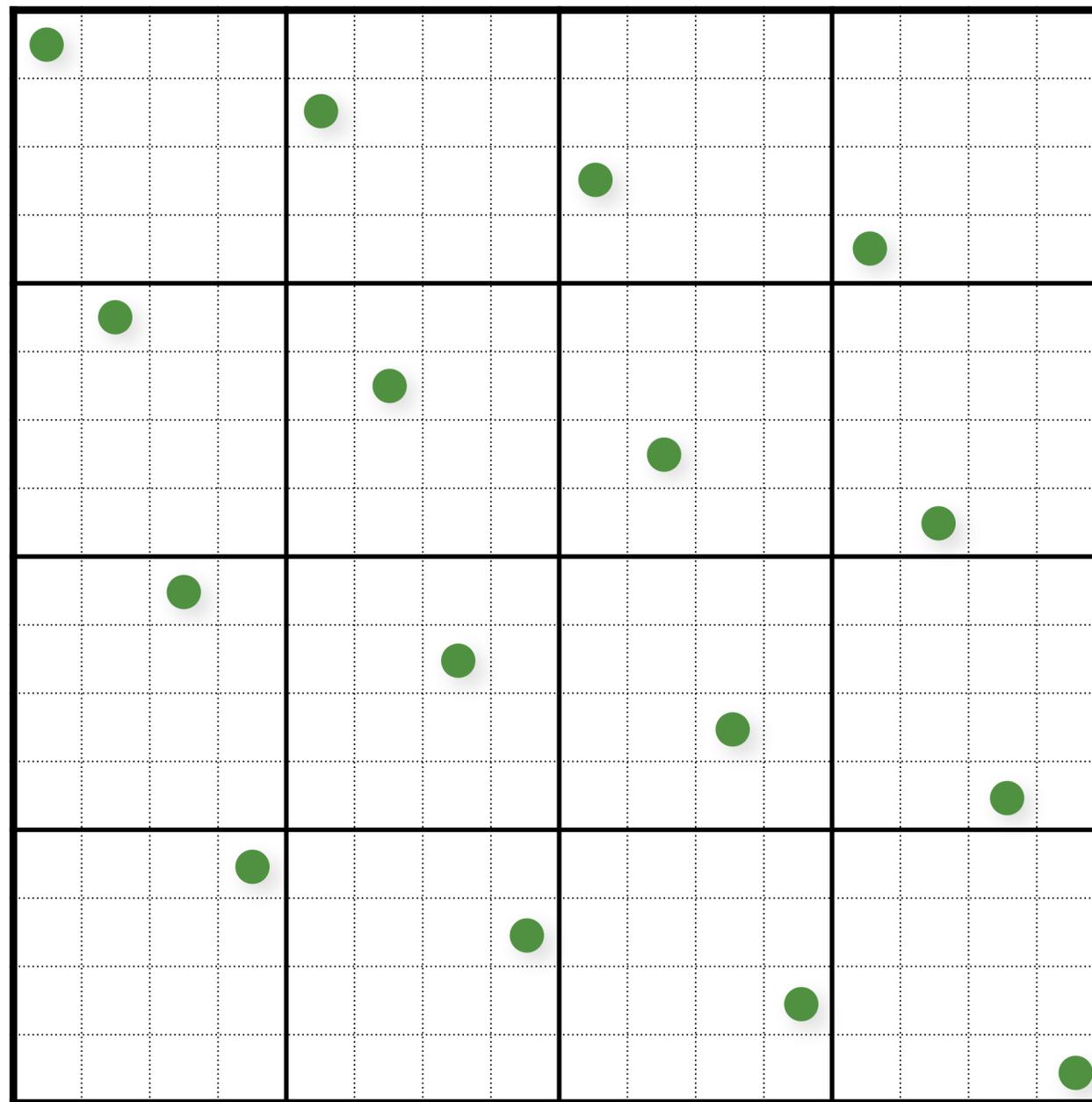
# Multi-Jittered Sampling

```
// initialize
float cellSize = 1.0 / (resX*resY);
for (uint i = 0; i < resX; i++)
    for (uint j = 0; j < resY; j++)
    {
        samples(i,j).x = i/resX + (j+randf()) / (resX*resY);
        samples(i,j).y = j/resY + (i+randf()) / (resX*resY);
    }
```

```
// shuffle x coordinates within each column of cells
for (uint i = 0; i < resX; i++)
    for (uint j = resY-1; j >= 1; j--)
        swap(samples(i, j).x, samples(i, randi(0, j)).x);
```

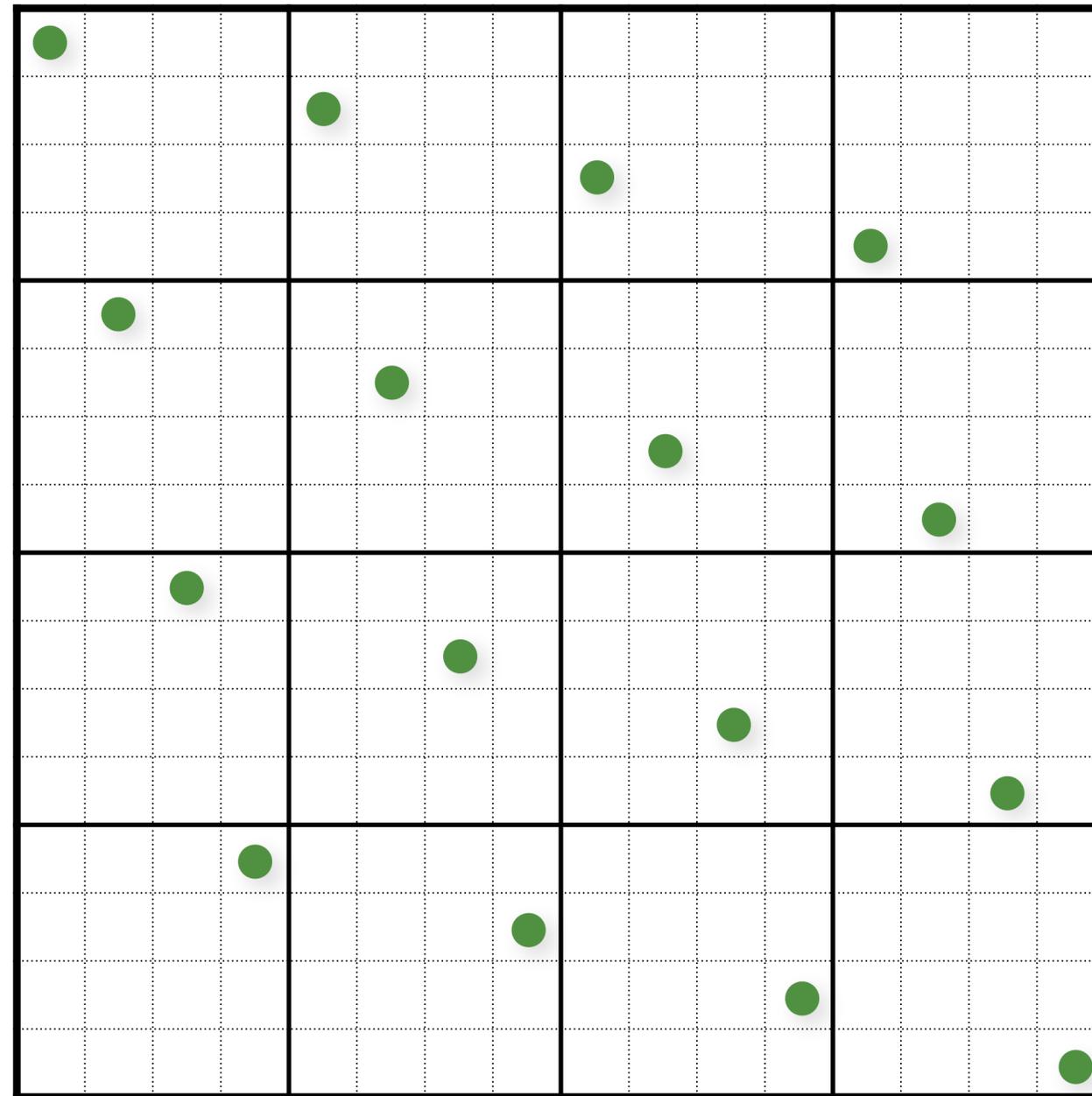
```
// shuffle y coordinates within each row of cells
for (unsigned j = 0; j < resY; j++)
    for (unsigned i = resX-1; i >= 1; i--)
        swap(samples(i, j).y, samples(randi(0, i), j).y);
```

# Multi-Jittered Sampling



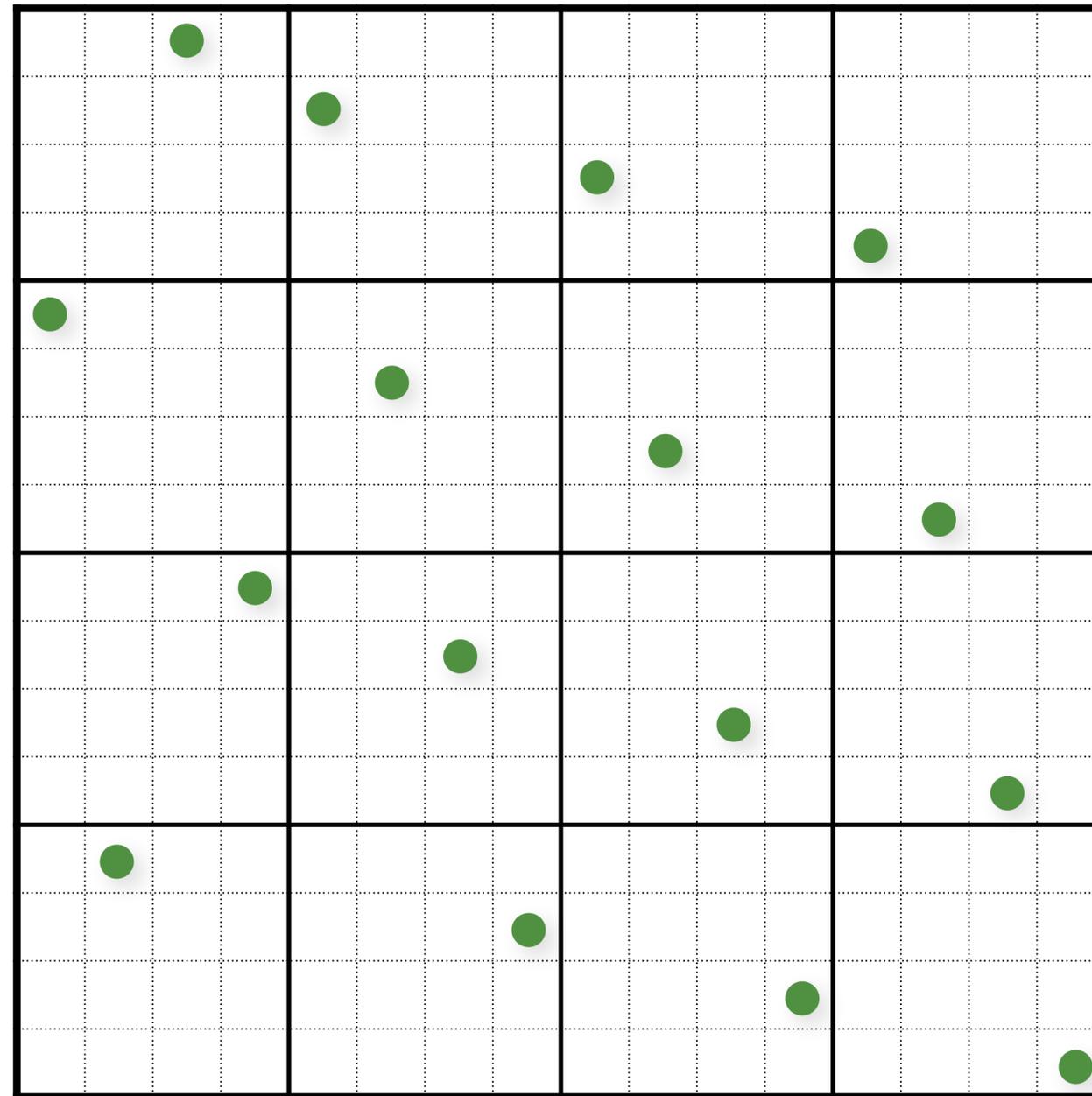
Initialize

# Multi-Jittered Sampling



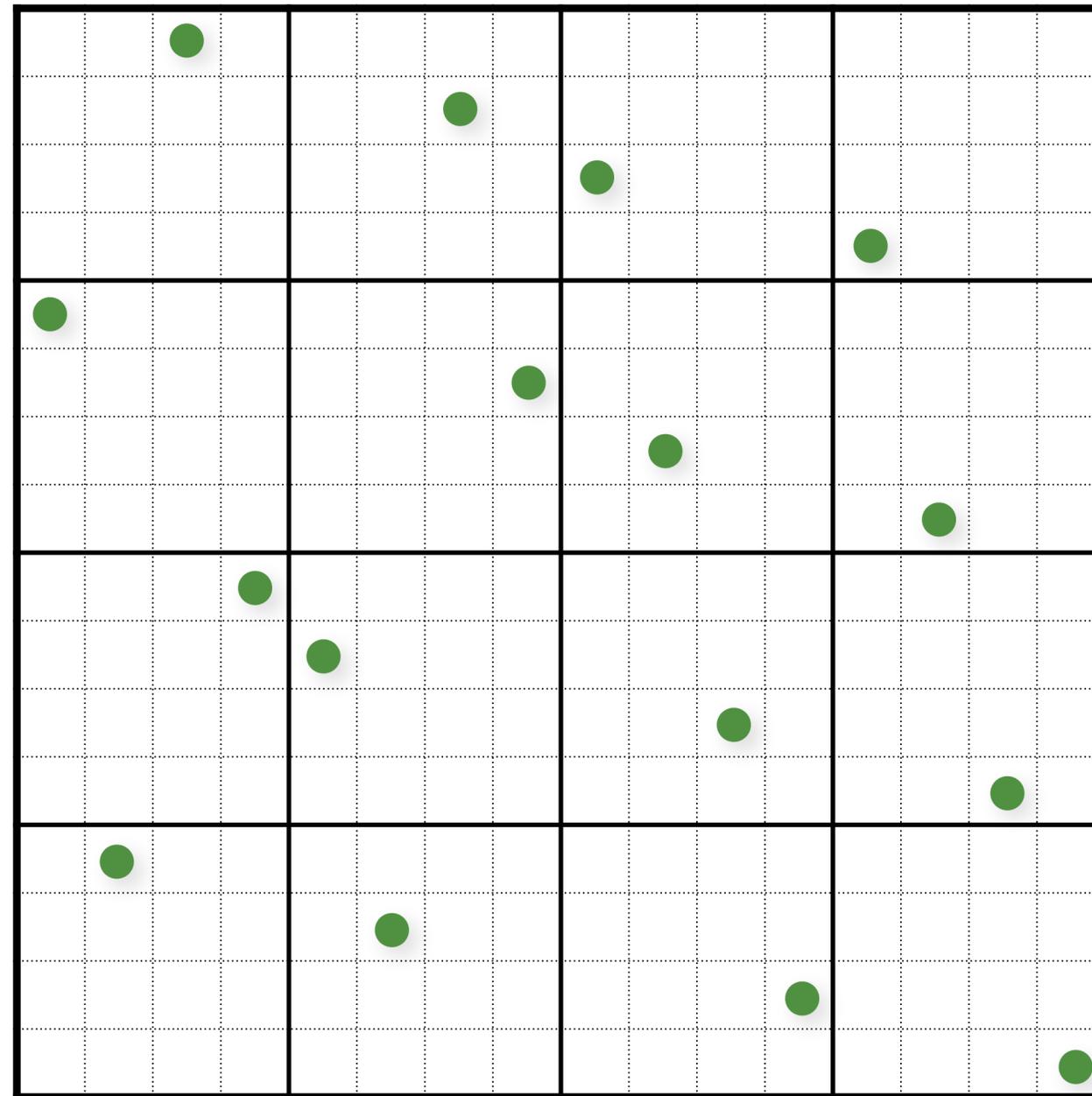
Shuffle x-coords

# Multi-Jittered Sampling



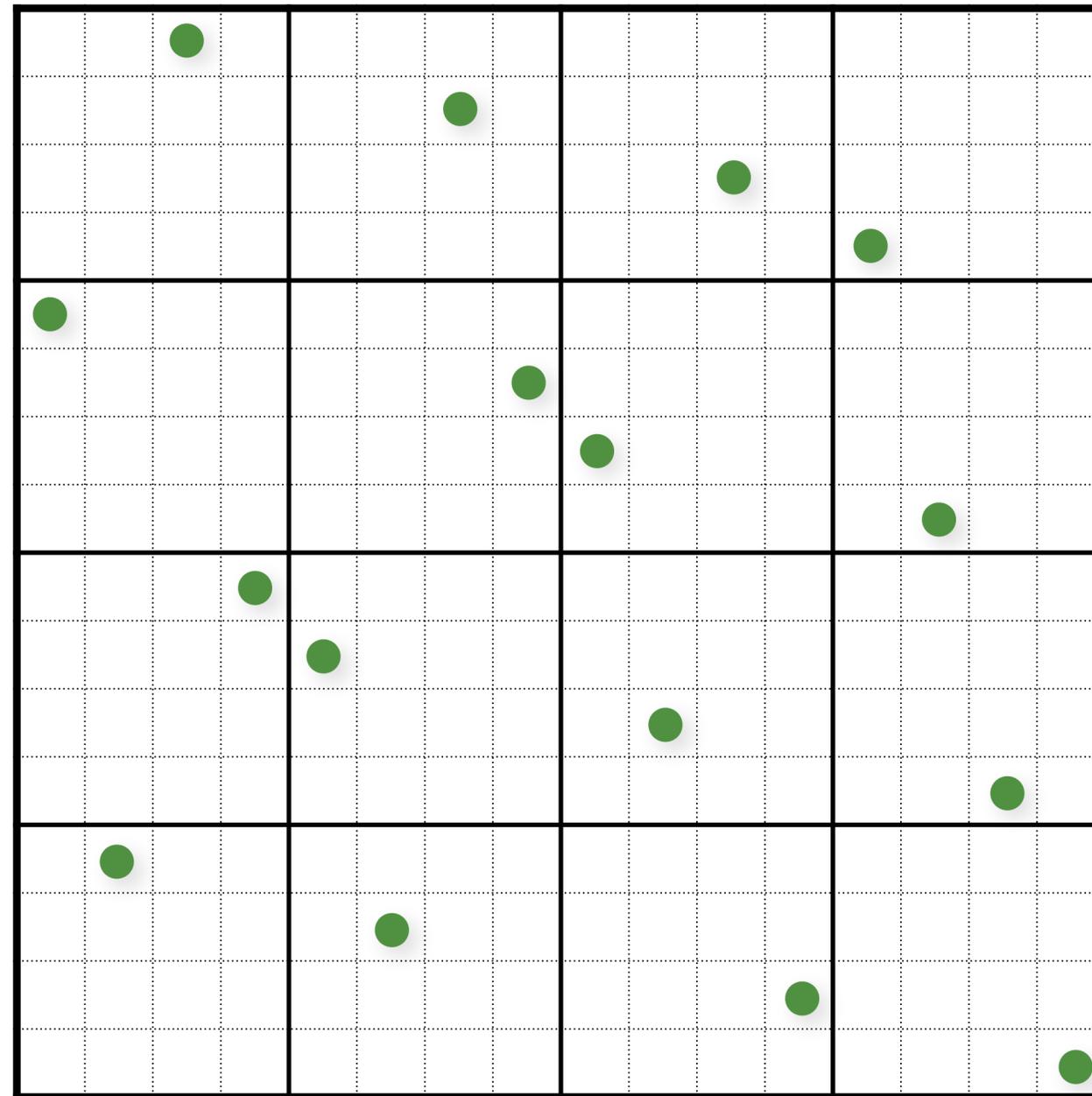
Shuffle x-coords

# Multi-Jittered Sampling



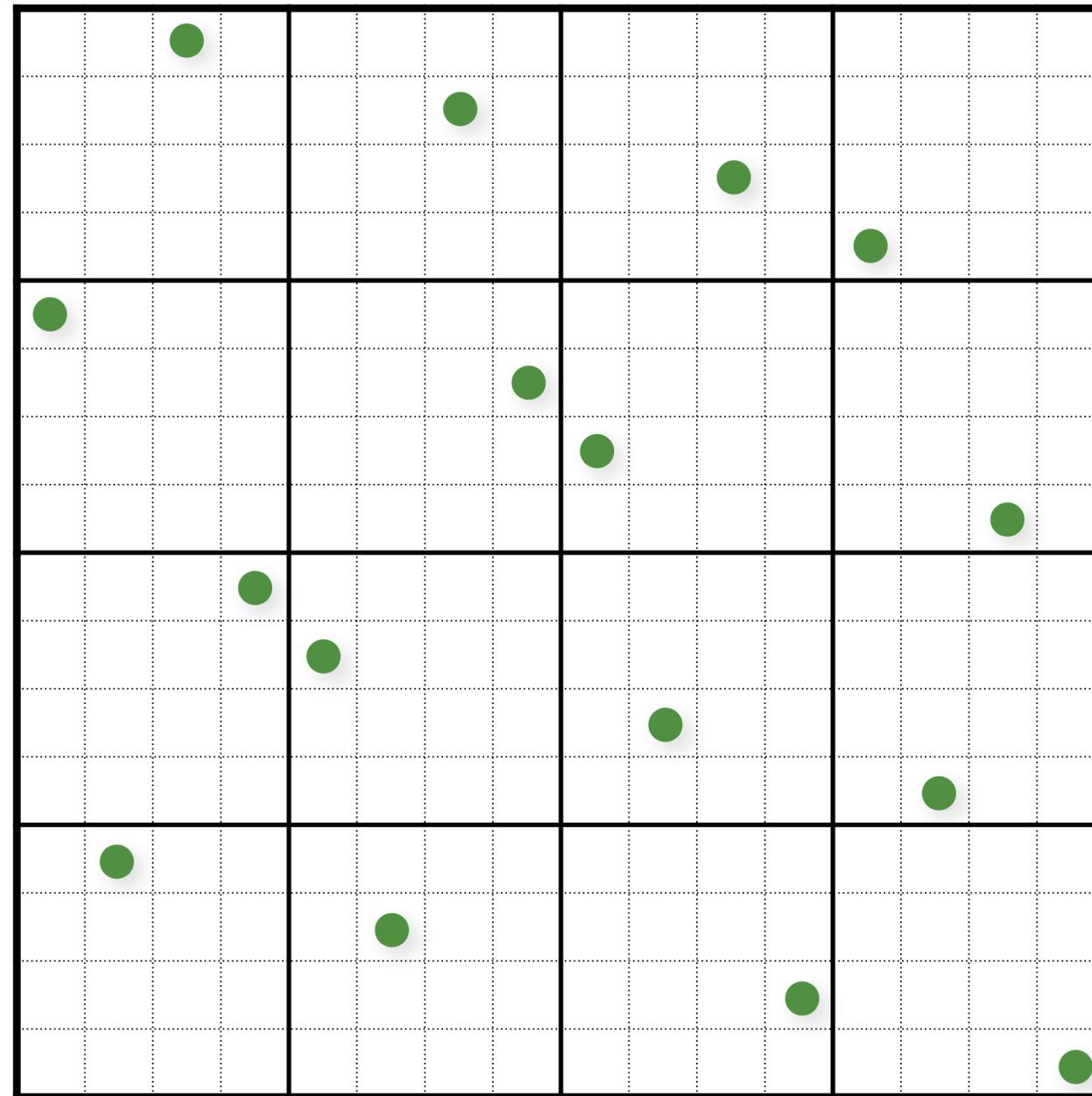
Shuffle x-coords

# Multi-Jittered Sampling



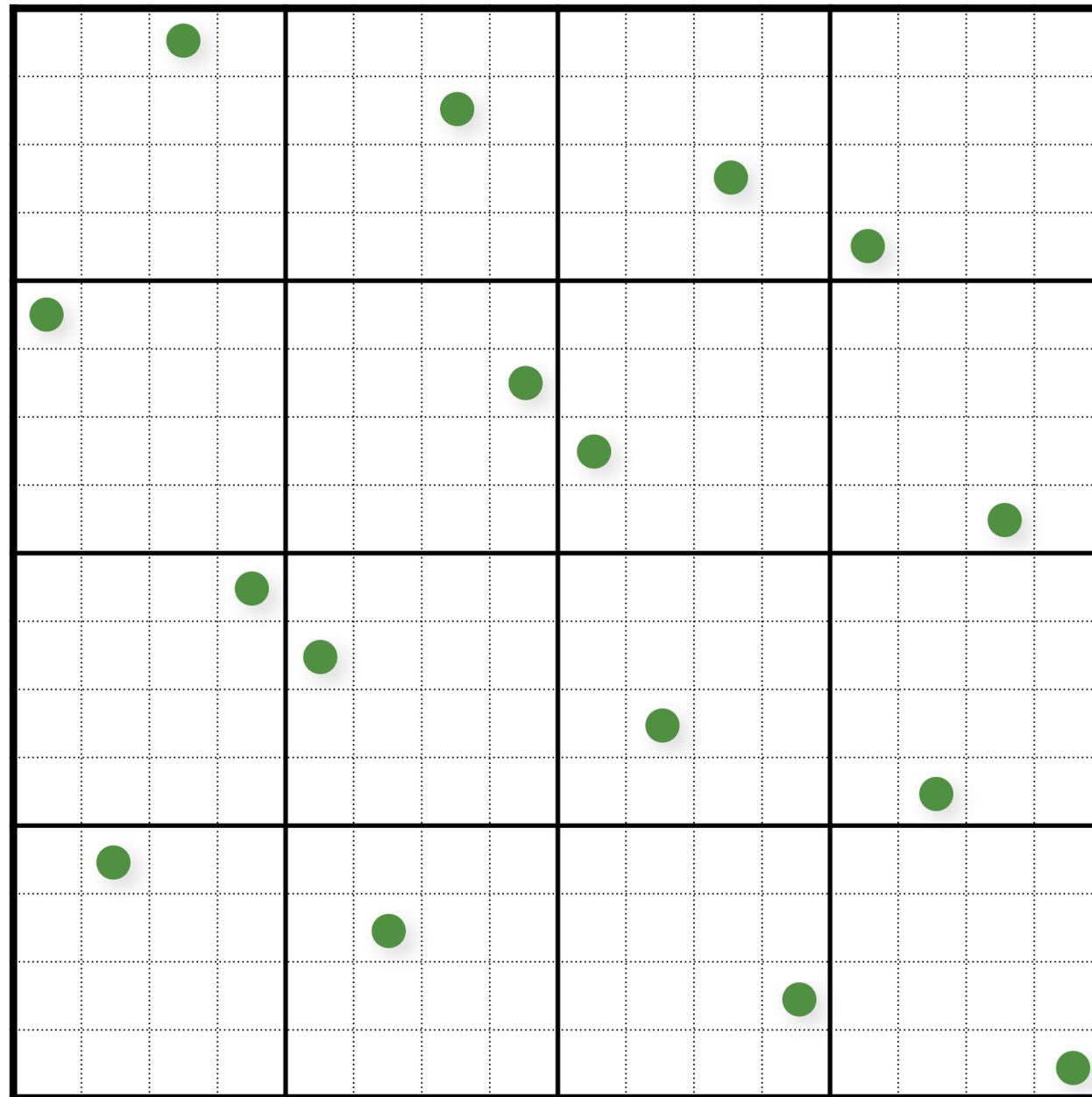
Shuffle x-coords

# Multi-Jittered Sampling

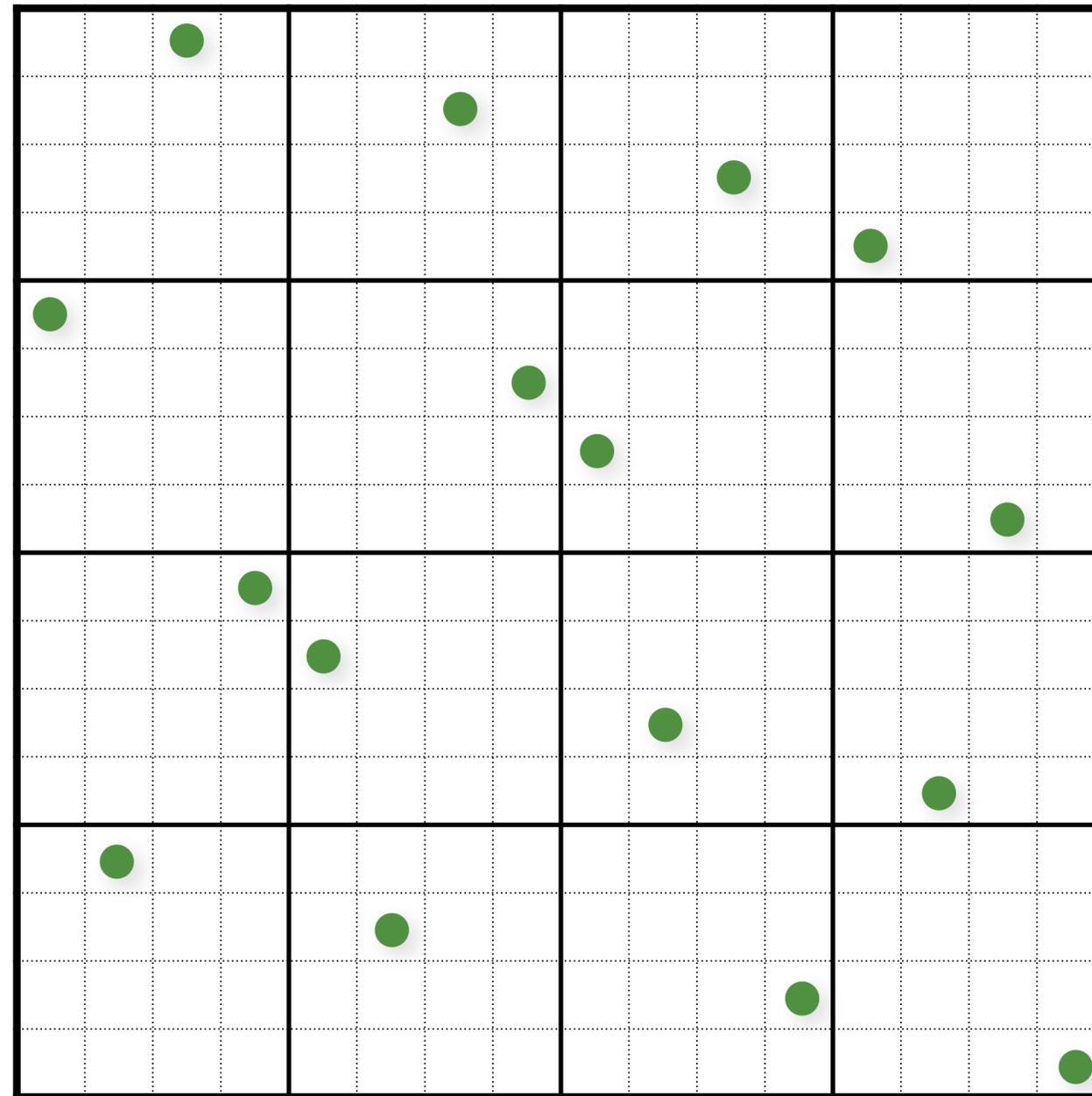


Shuffle x-coords

# Multi-Jittered Sampling

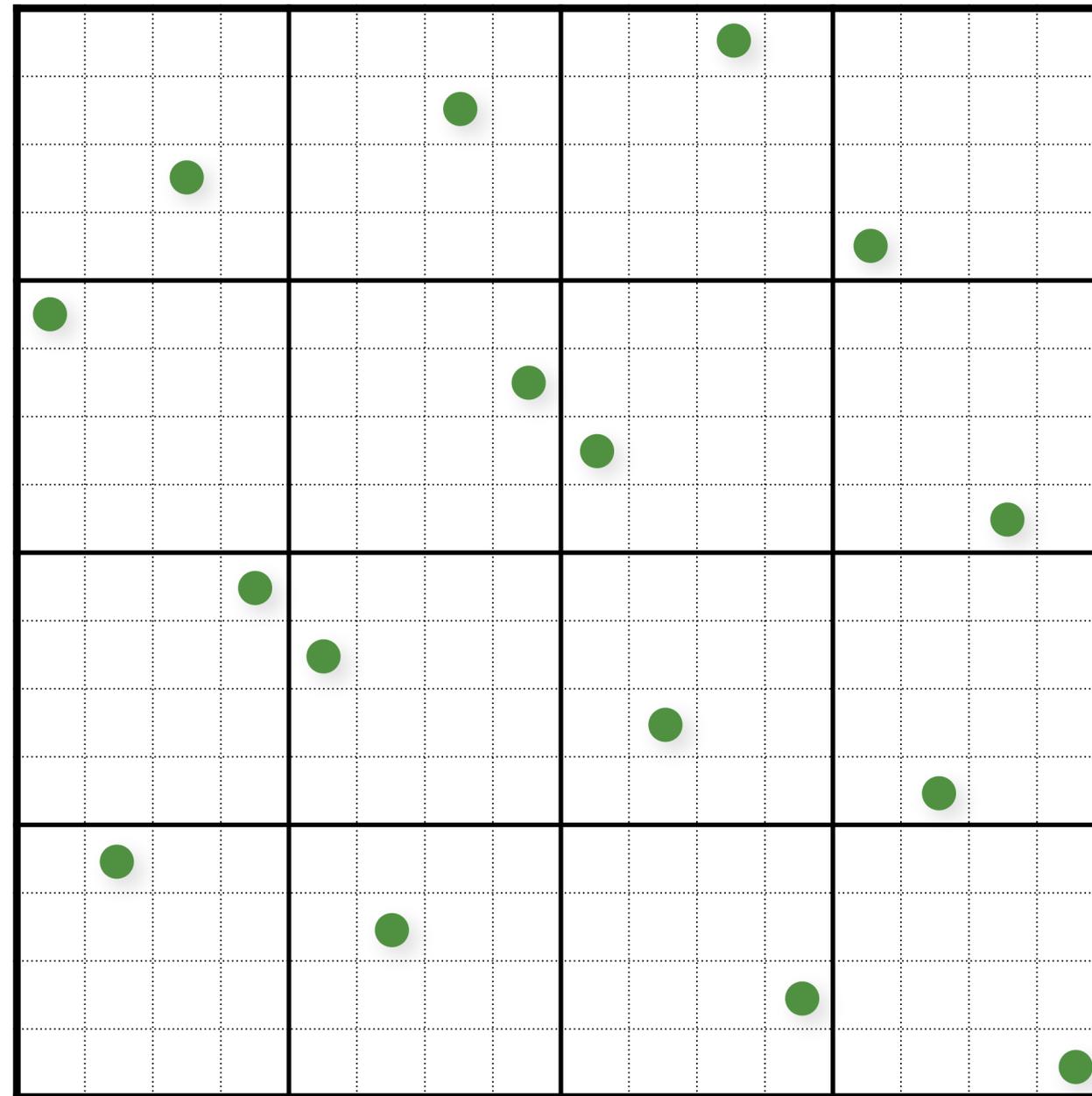


# Multi-Jittered Sampling



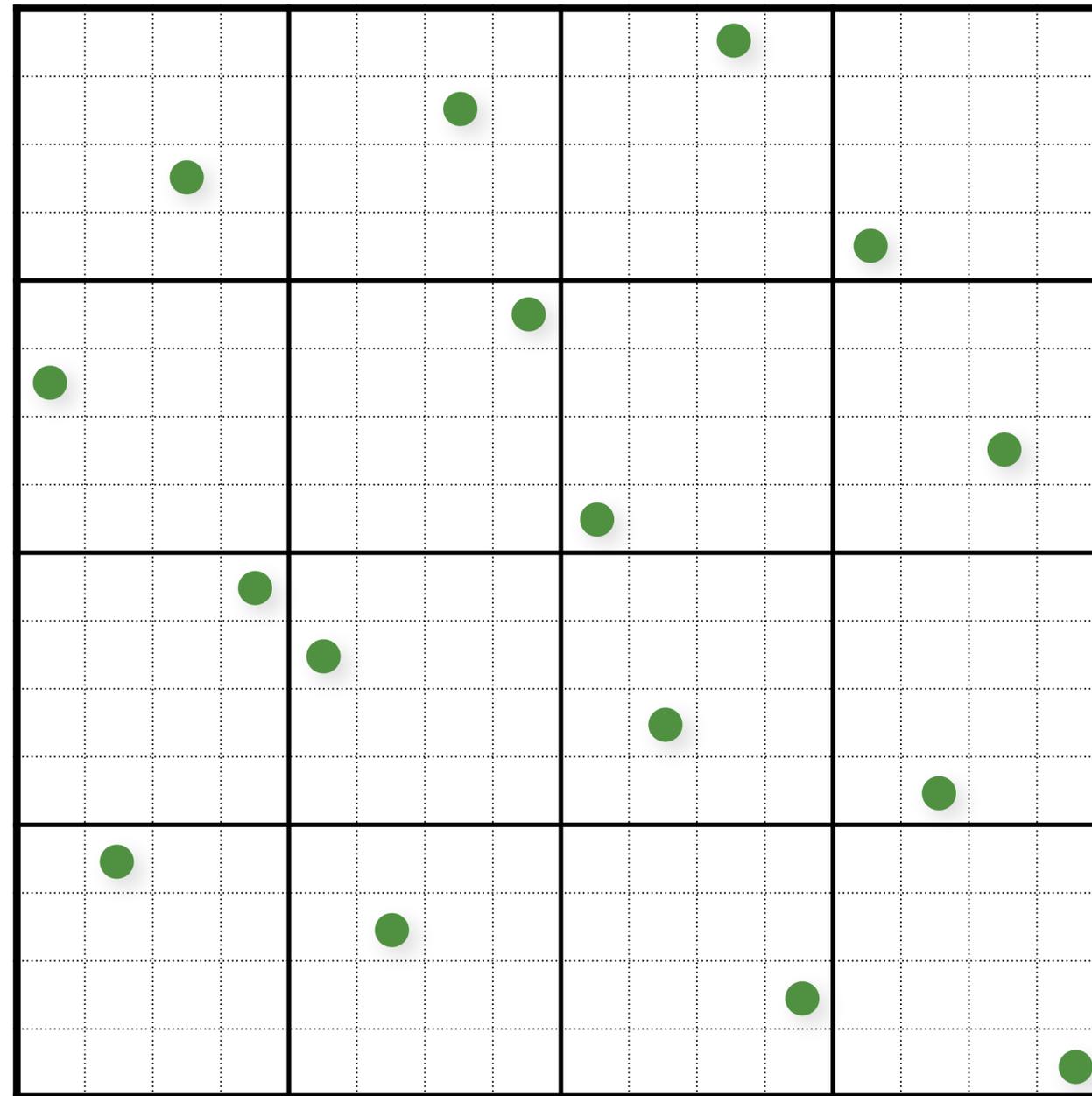
Shuffle y-coords

# Multi-Jittered Sampling



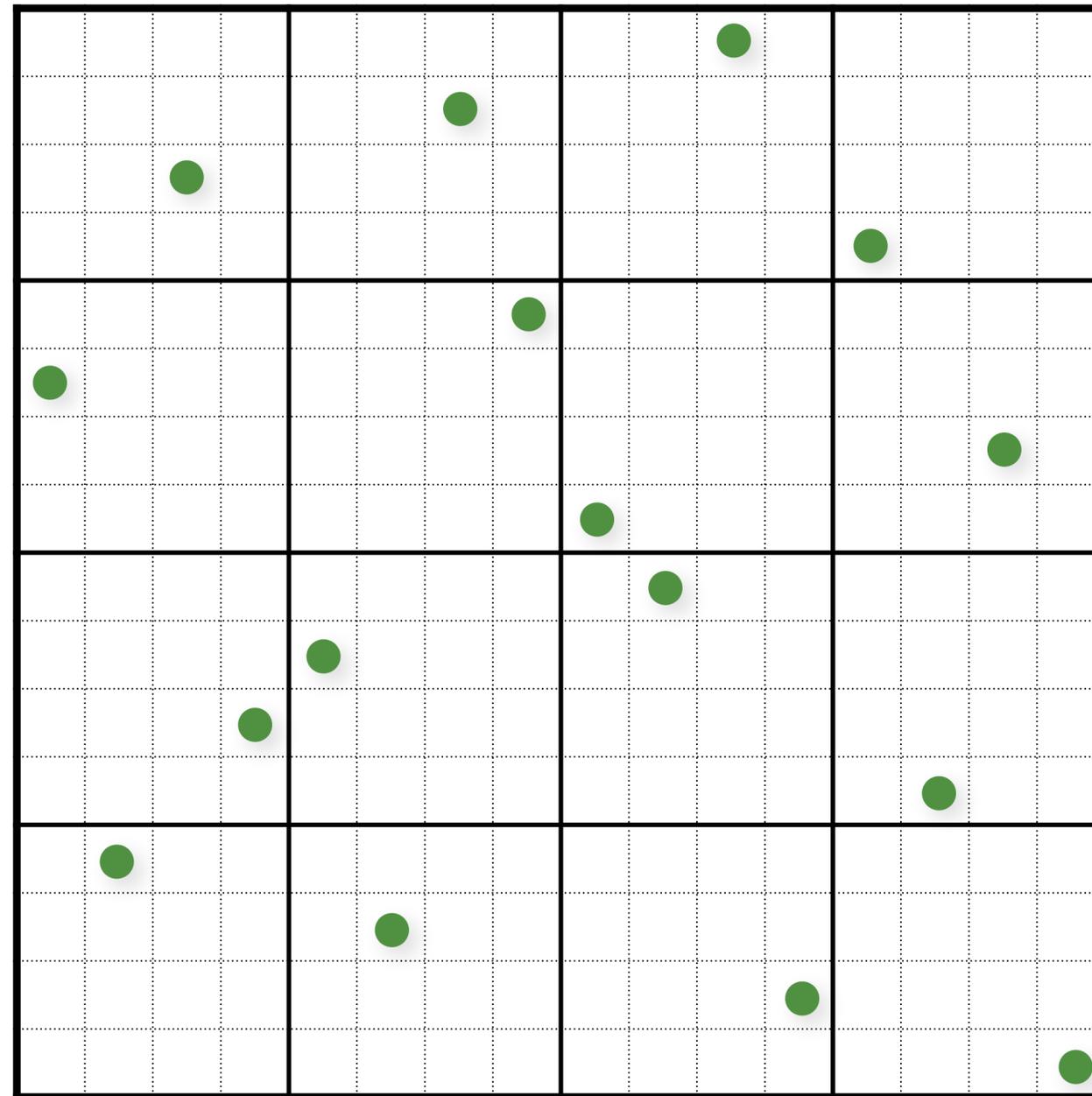
Shuffle y-coords

# Multi-Jittered Sampling



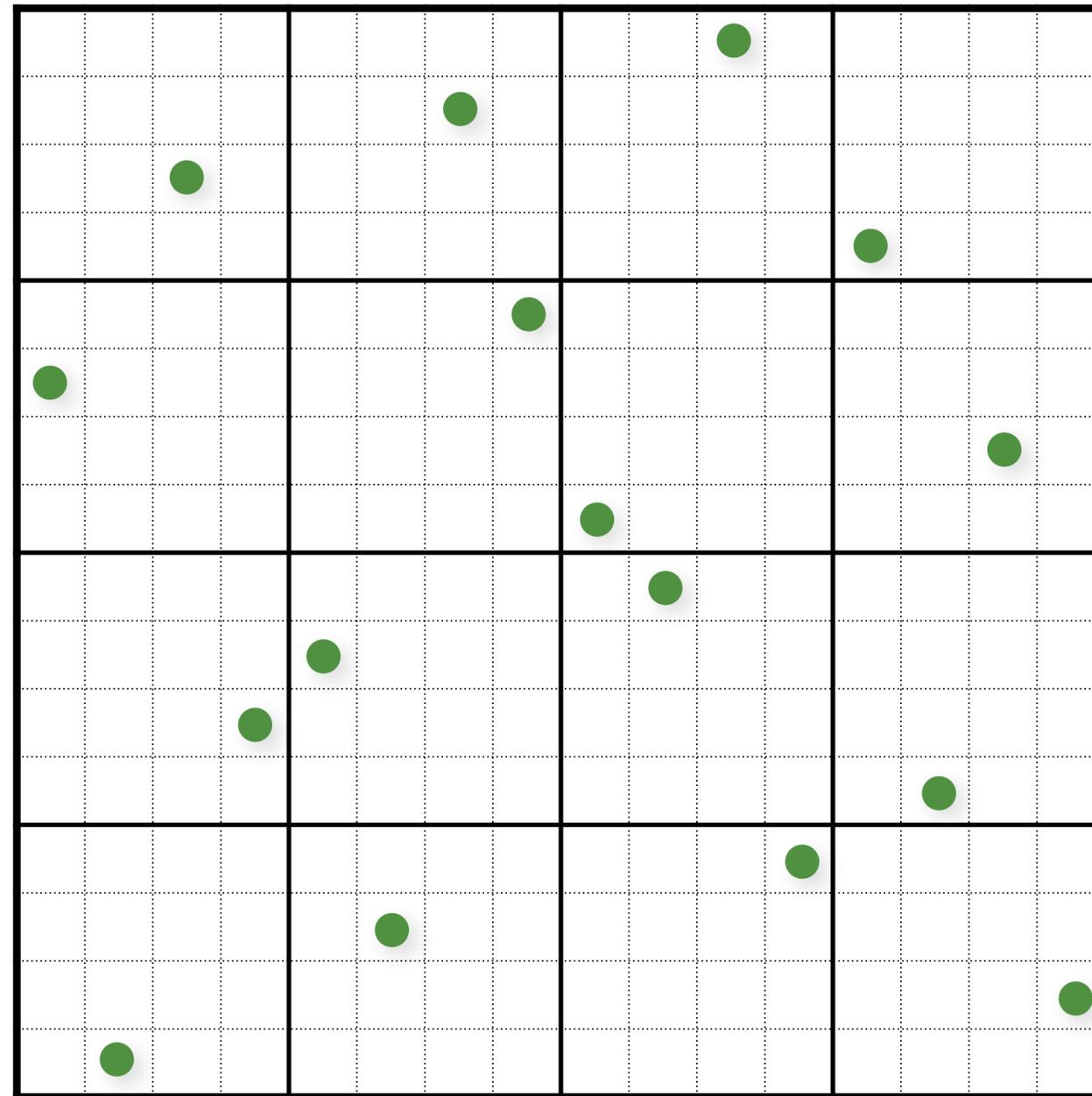
Shuffle y-coords

# Multi-Jittered Sampling



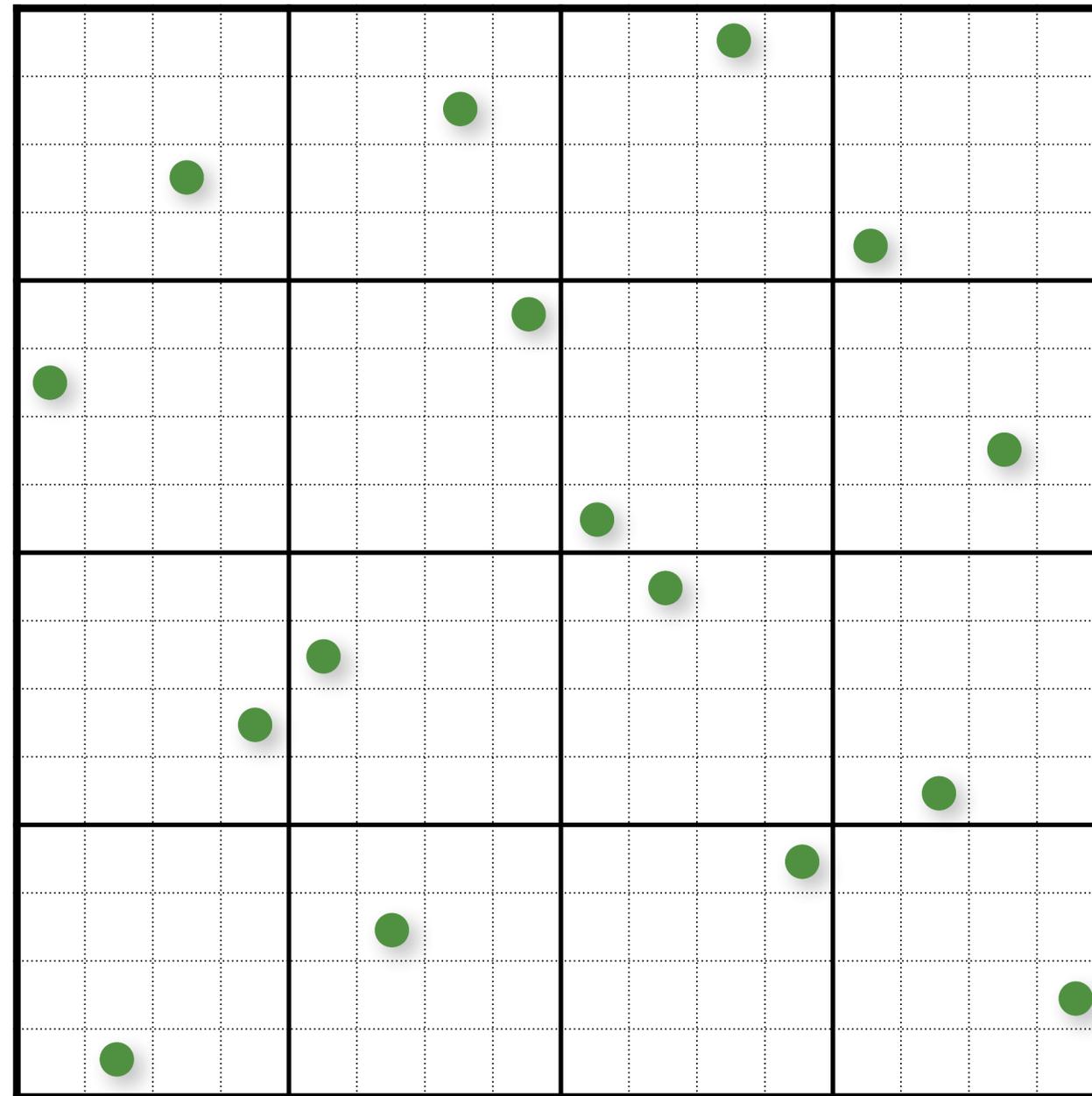
Shuffle y-coords

# Multi-Jittered Sampling

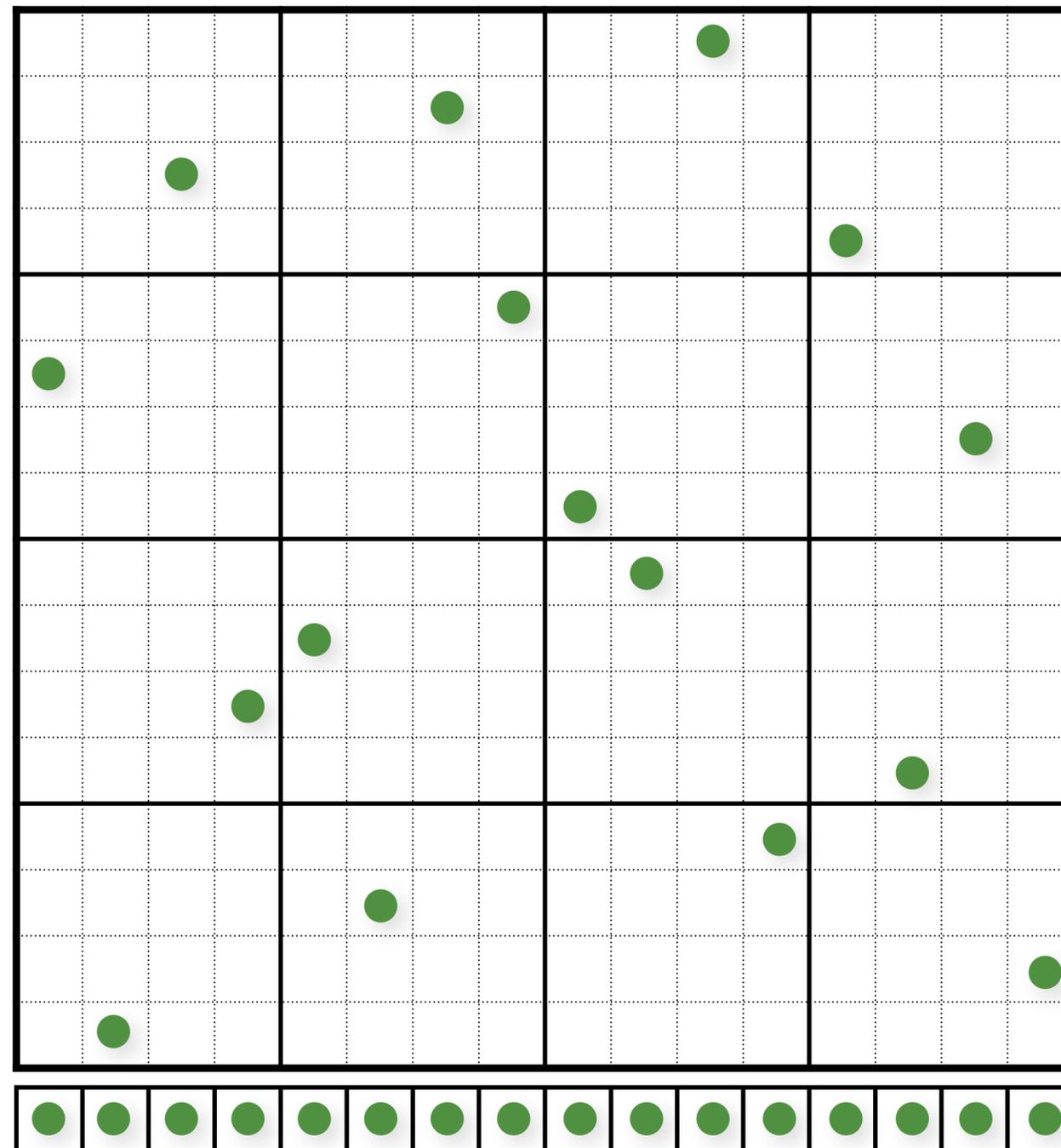


Shuffle y-coords

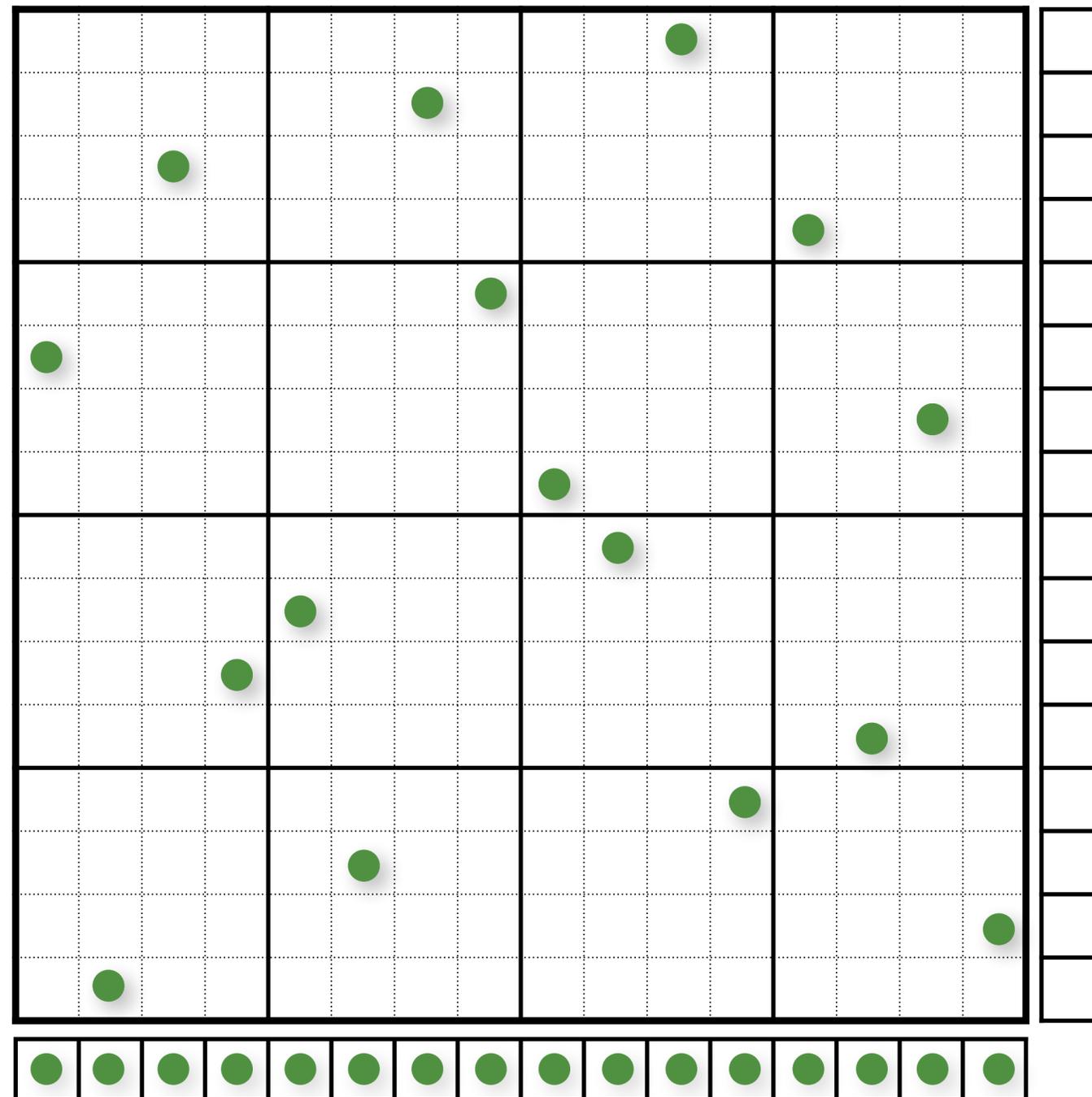
# Multi-Jittered Sampling (Projections)



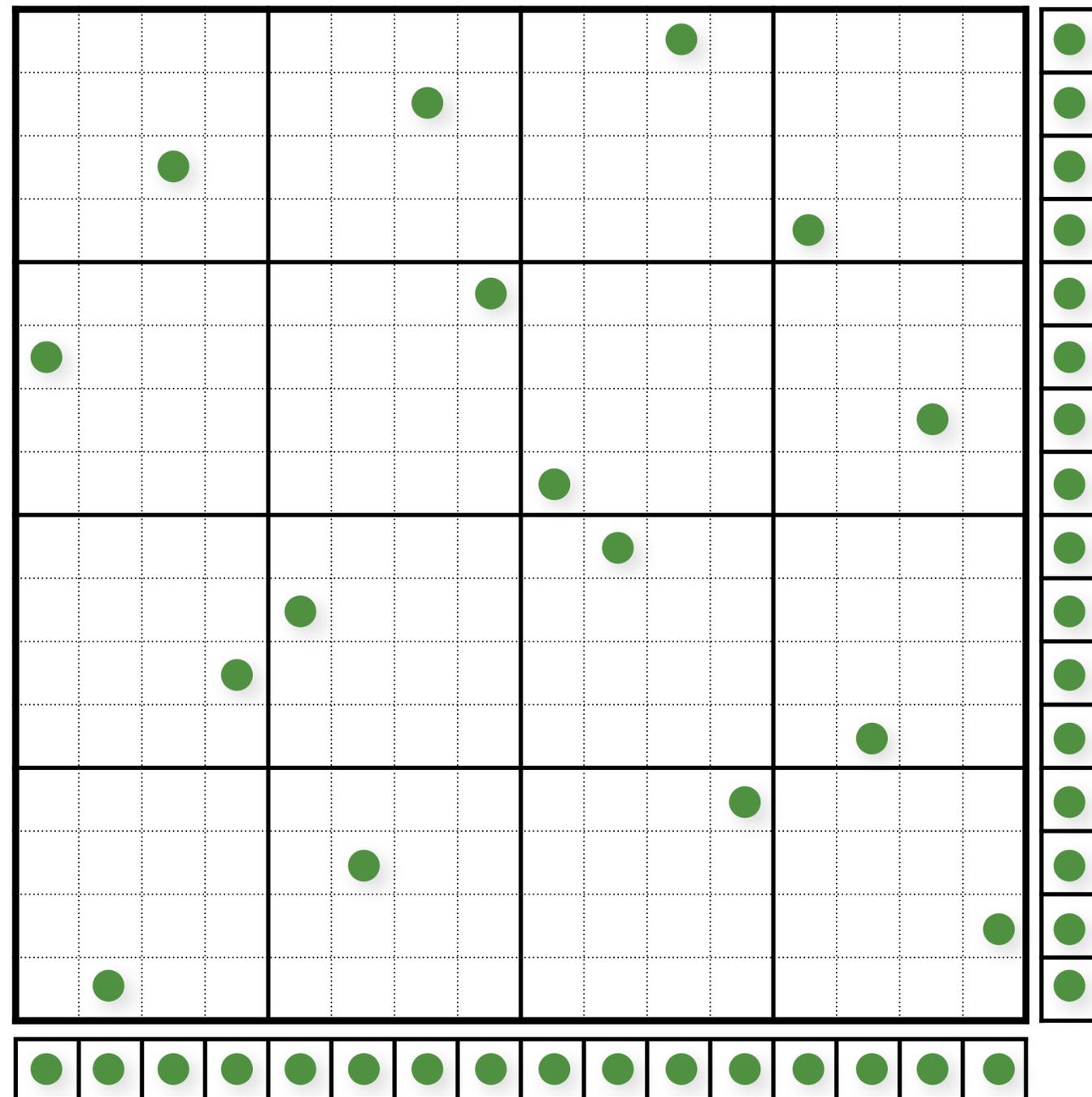
# Multi-Jittered Sampling (Projections)



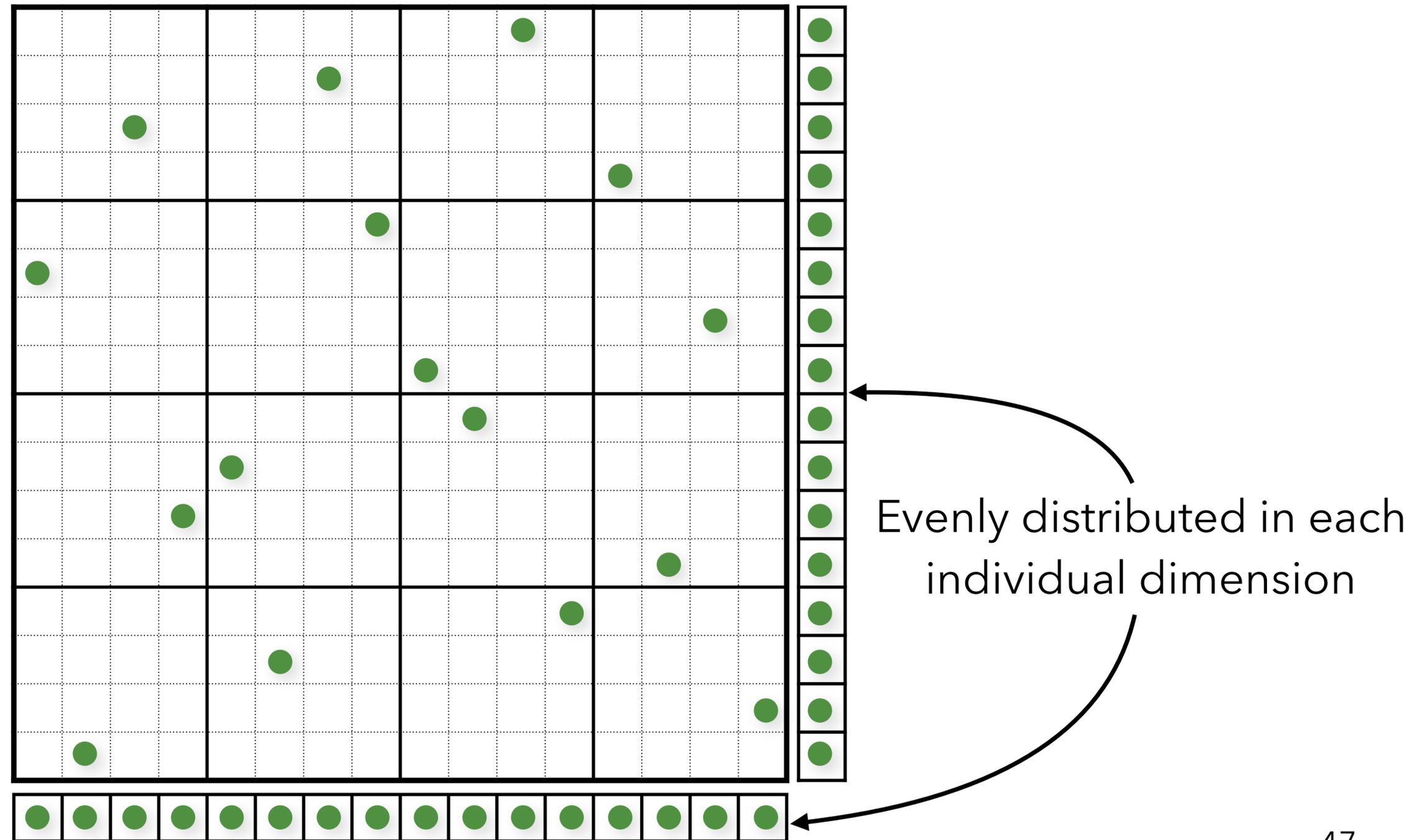
# Multi-Jittered Sampling (Projections)



# Multi-Jittered Sampling (Projections)

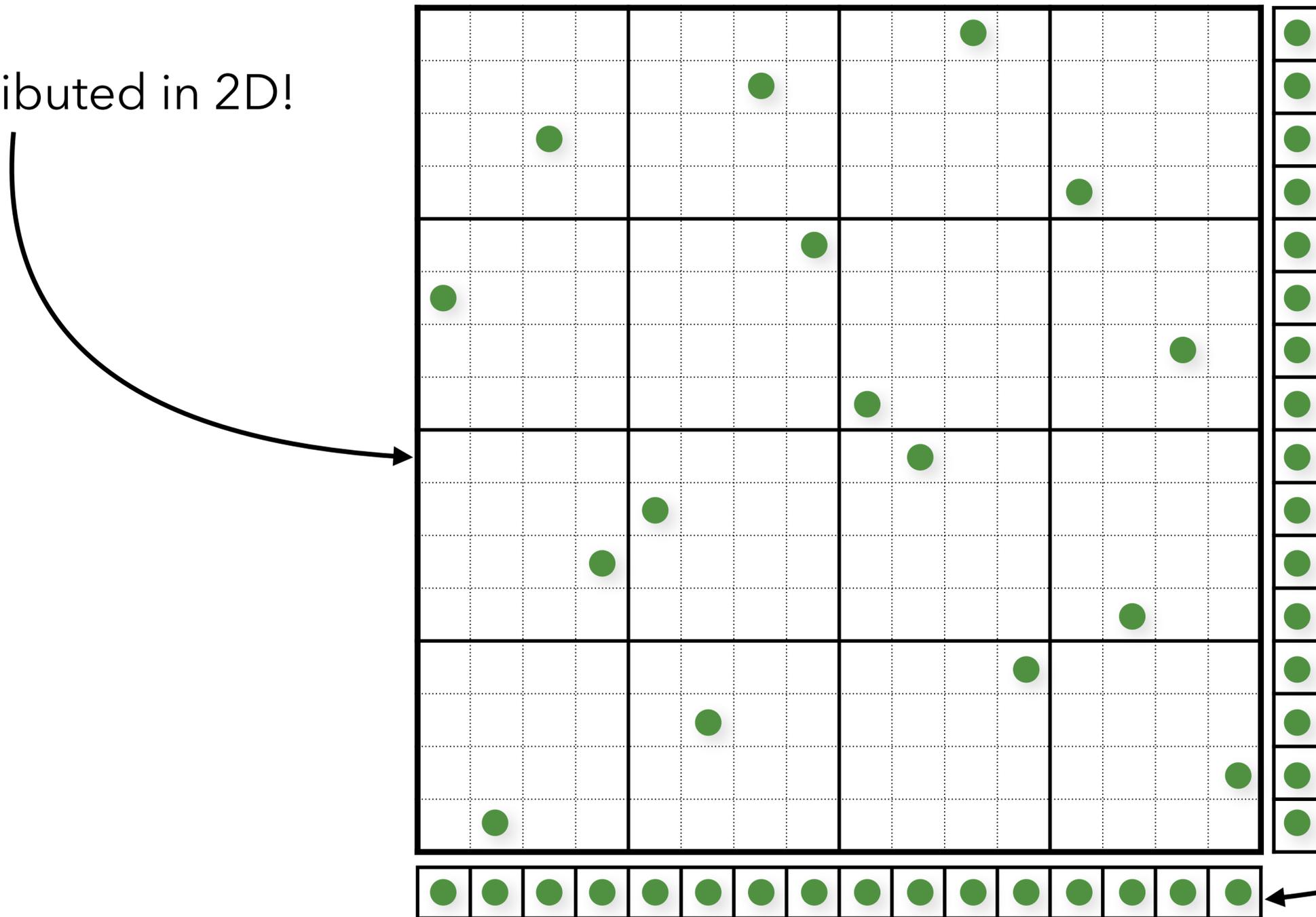


# Multi-Jittered Sampling (Projections)



# Multi-Jittered Sampling (Projections)

Evenly distributed in 2D!



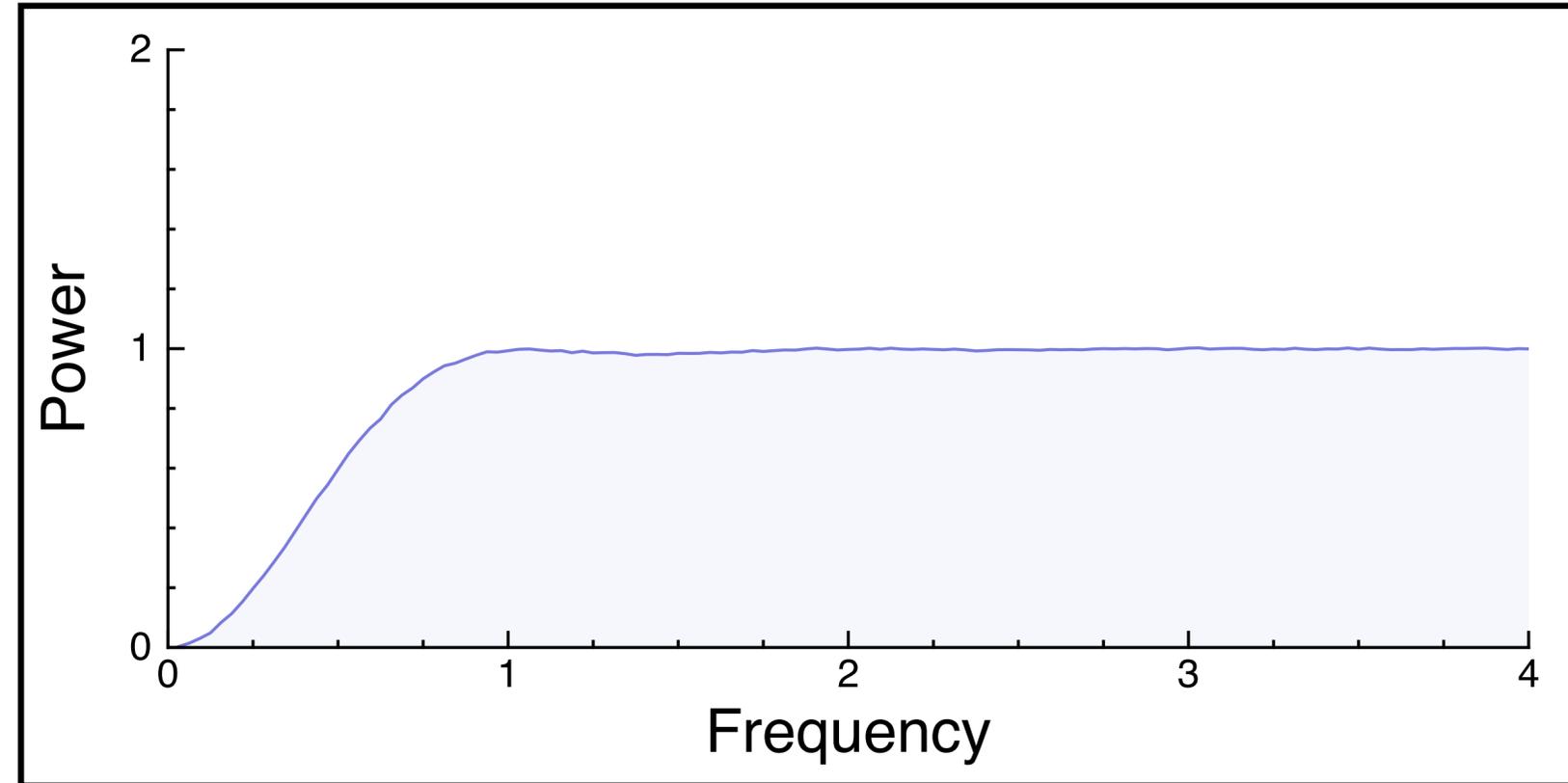
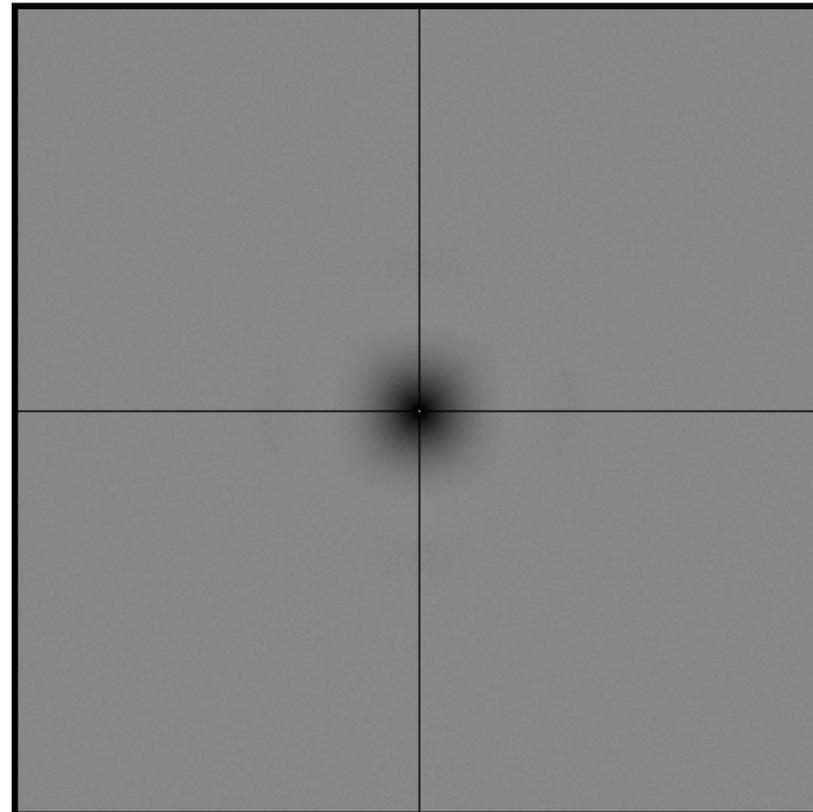
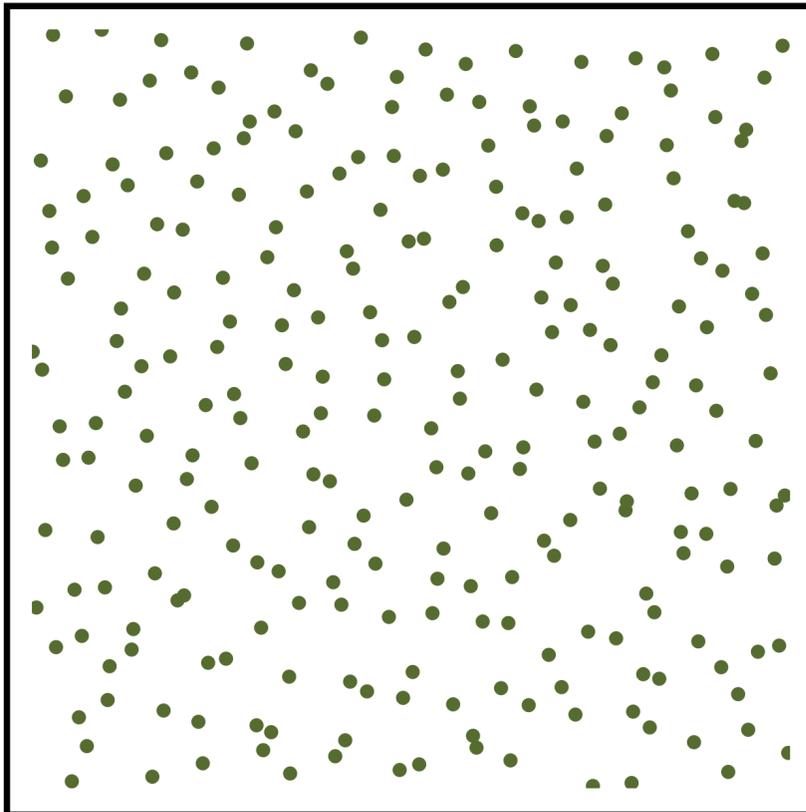
Evenly distributed in each individual dimension

# Multi-Jittered Sampling

Samples

Expected power spectrum

Radial mean

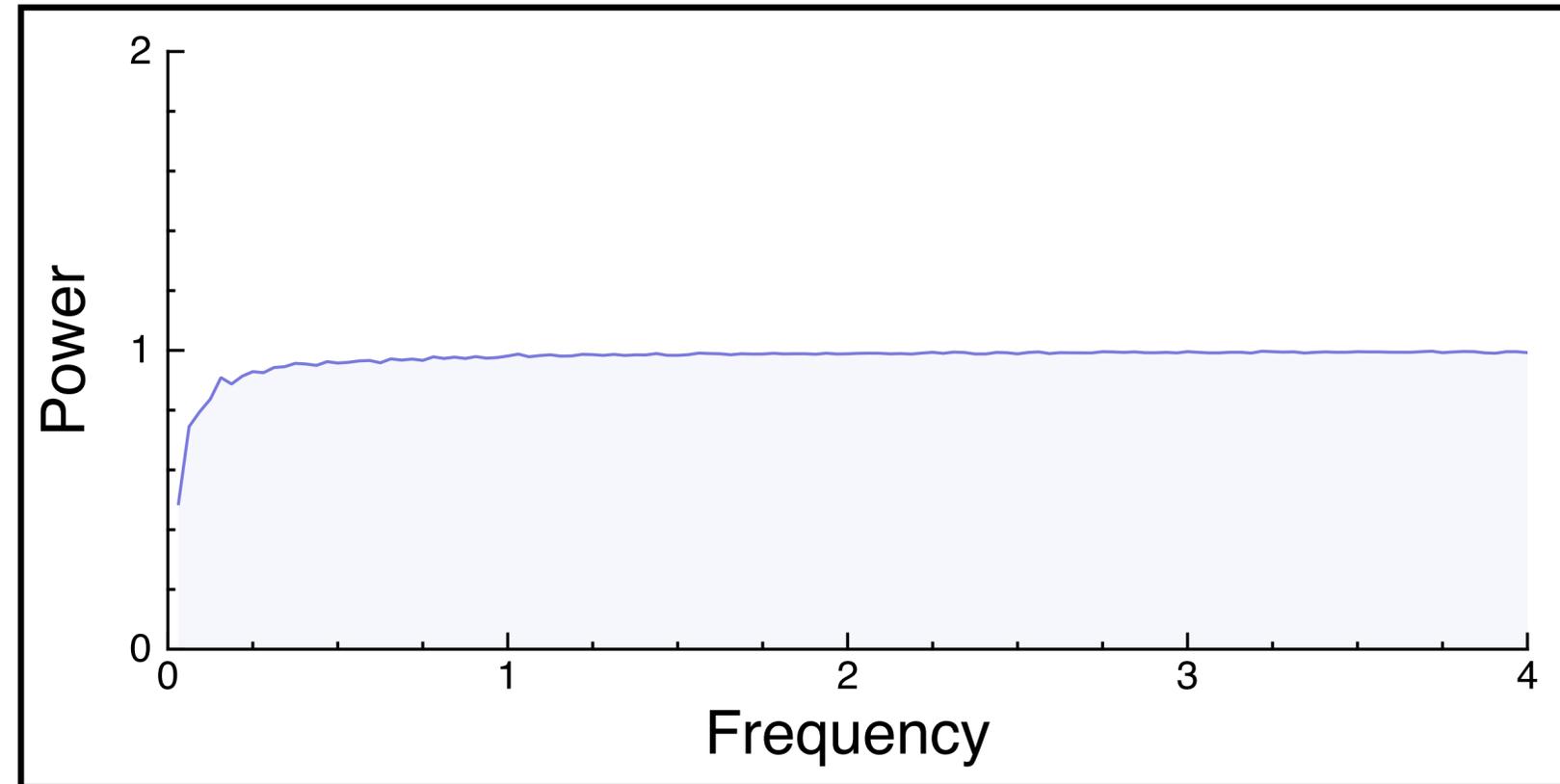
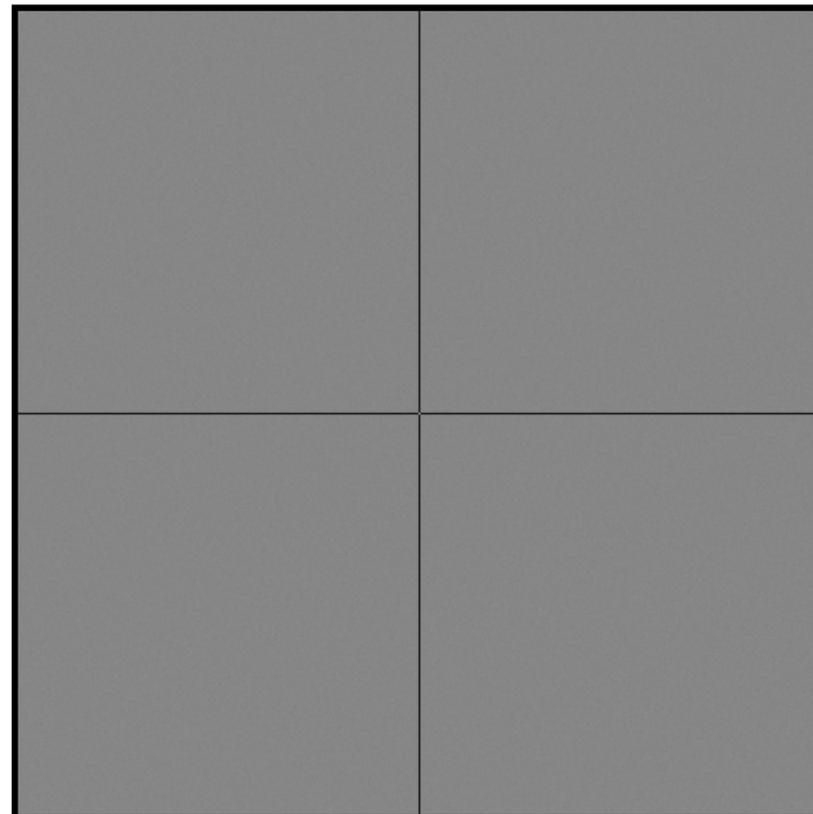
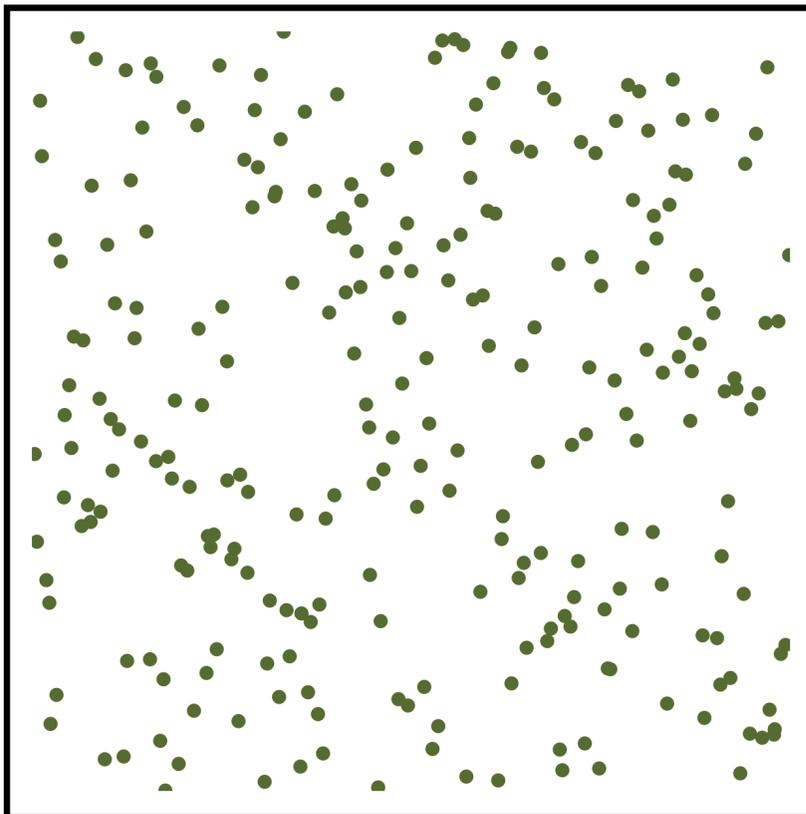


# N-Rooks Sampling

Samples

Expected power spectrum

Radial mean

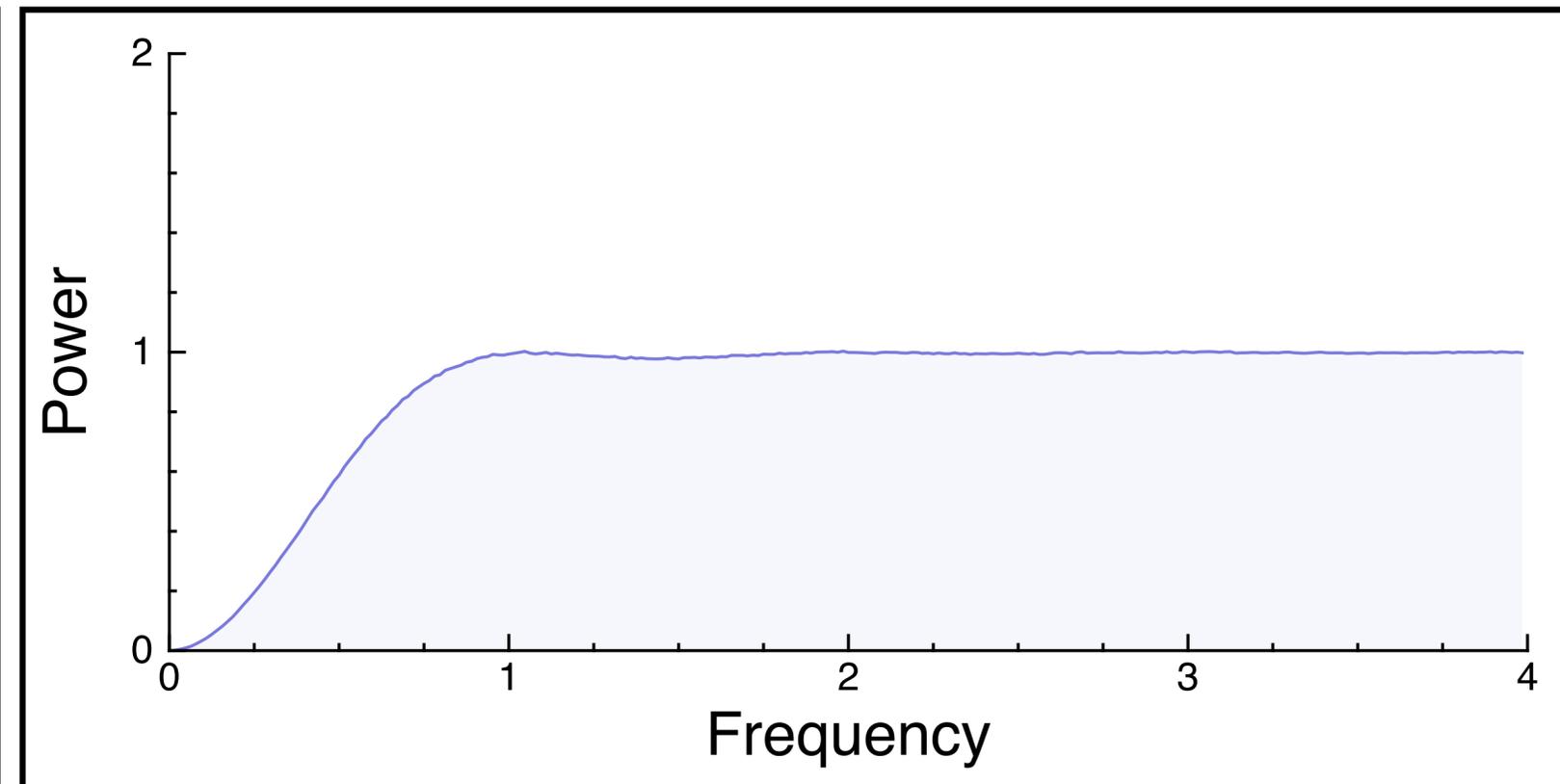
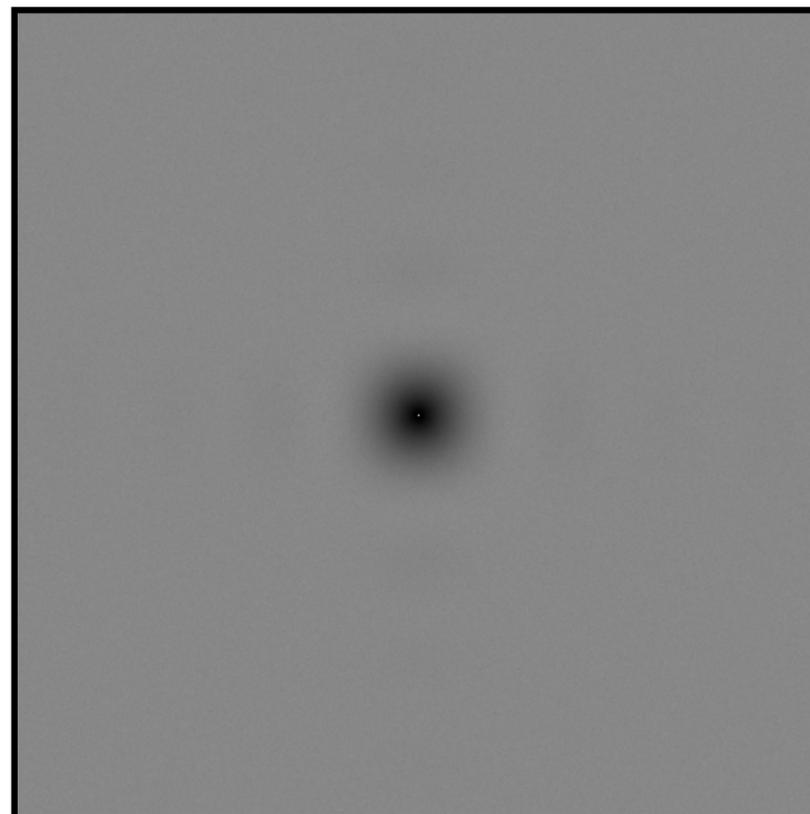
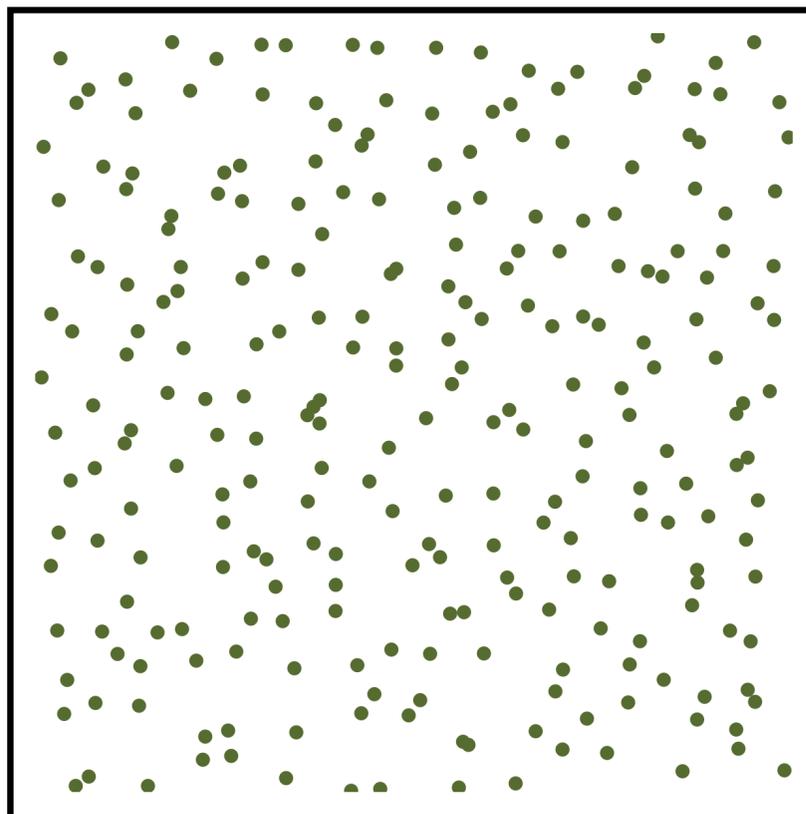


# Jittered Sampling

Samples

Expected power spectrum

Radial mean



# Poisson-Disk/Blue-Noise Sampling

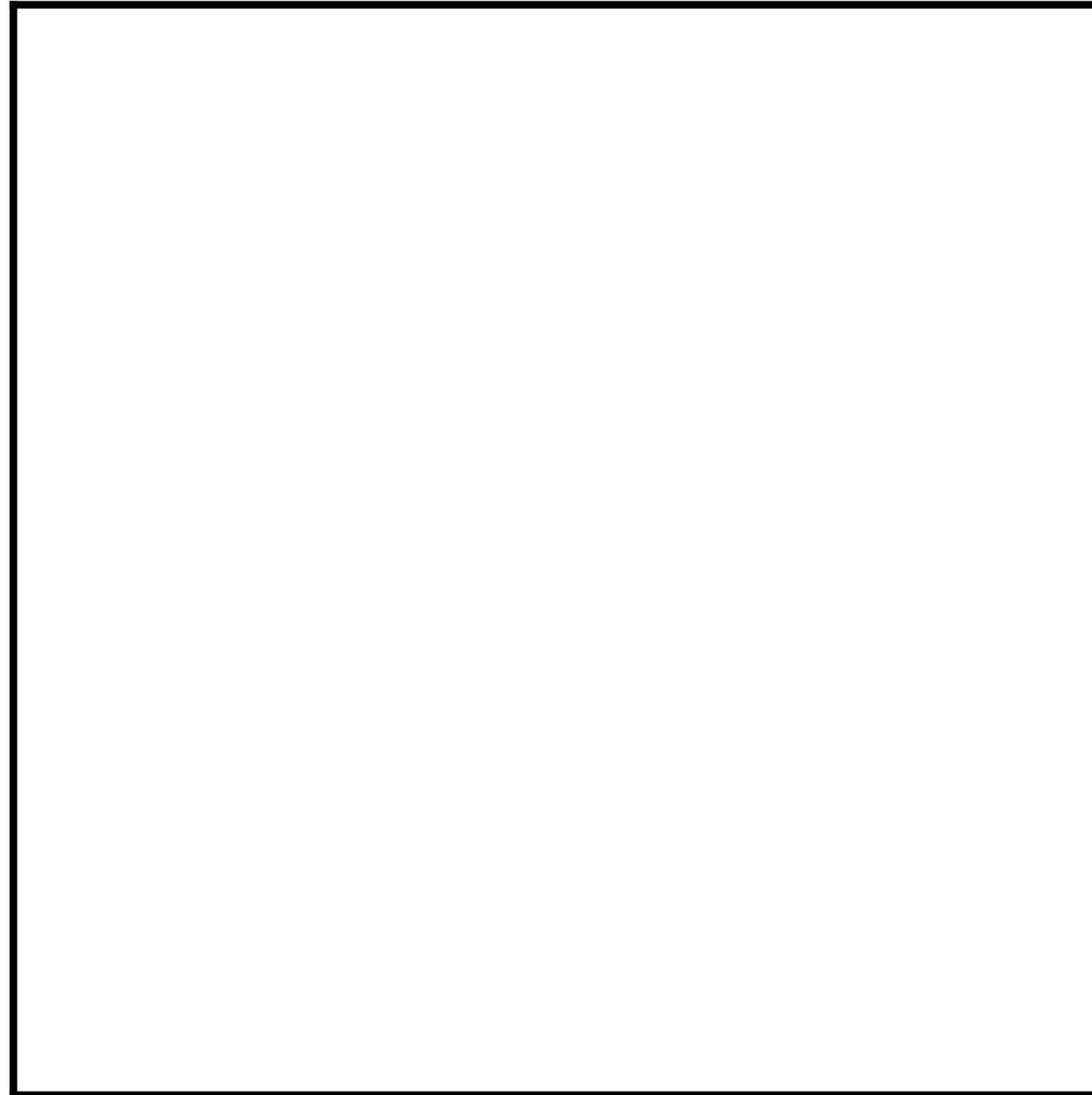
Enforce a minimum distance between points

Poisson-Disk Sampling:

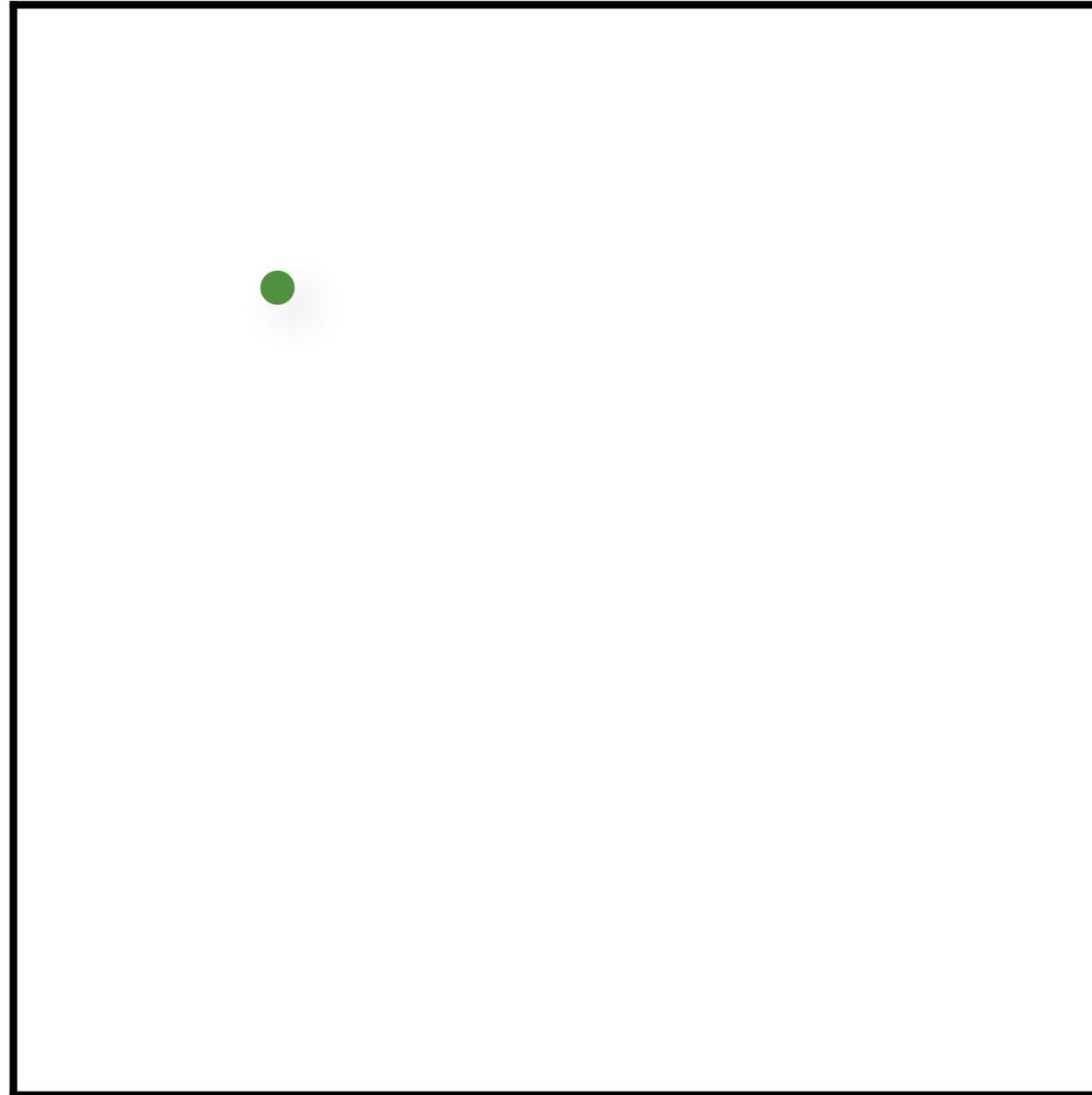
- Mark A. Z. Dippé and Erling Henry Wold. "Antialiasing through stochastic sampling." *ACM SIGGRAPH*, 1985.
- Robert L. Cook. "Stochastic sampling in computer graphics." *ACM Transactions on Graphics*, 1986.
- Ares Lagae and Philip Dutré. "A comparison of methods for generating Poisson disk distributions." *Computer Graphics Forum*, 2008.

# Random Dart Throwing

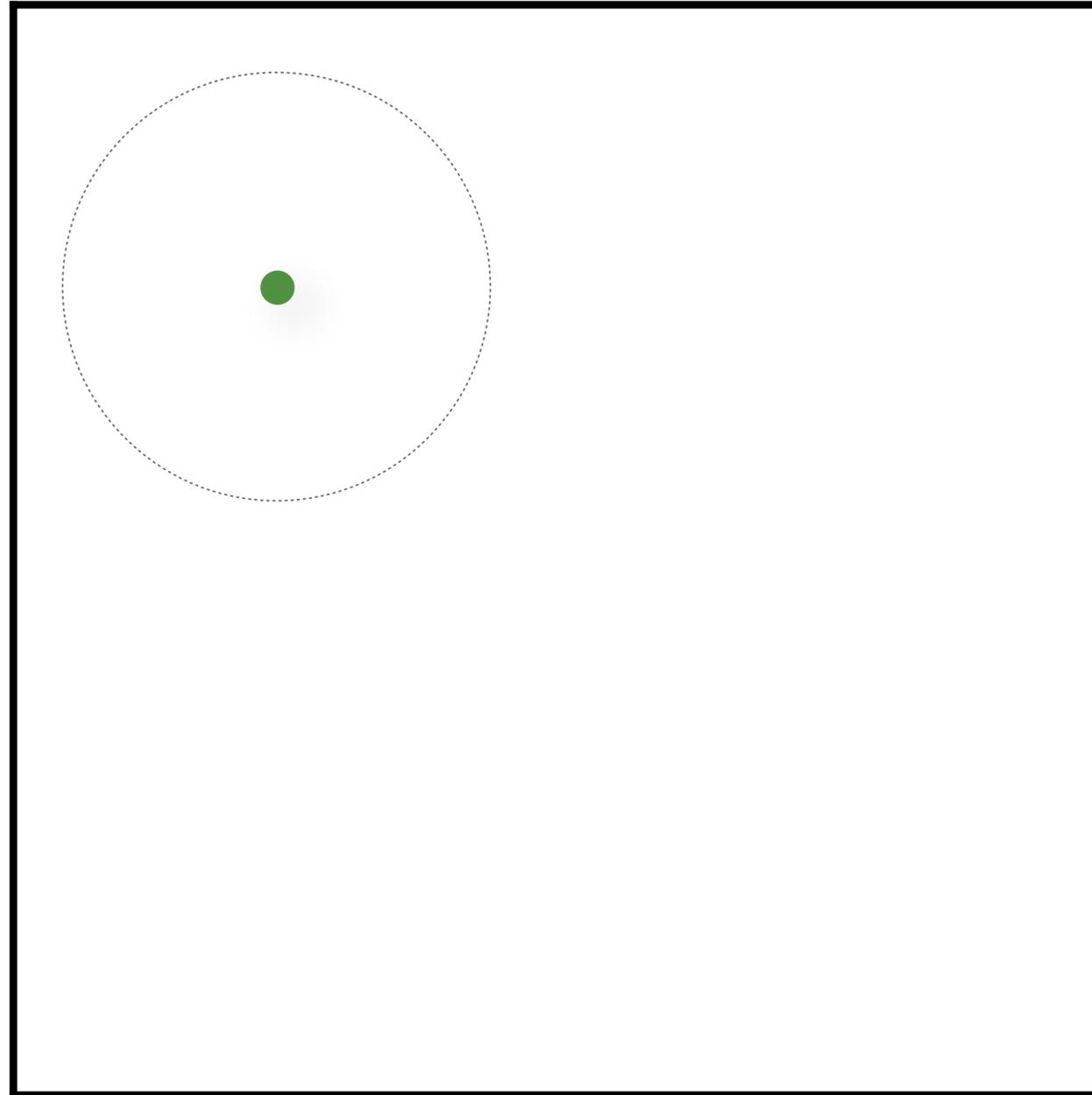
---



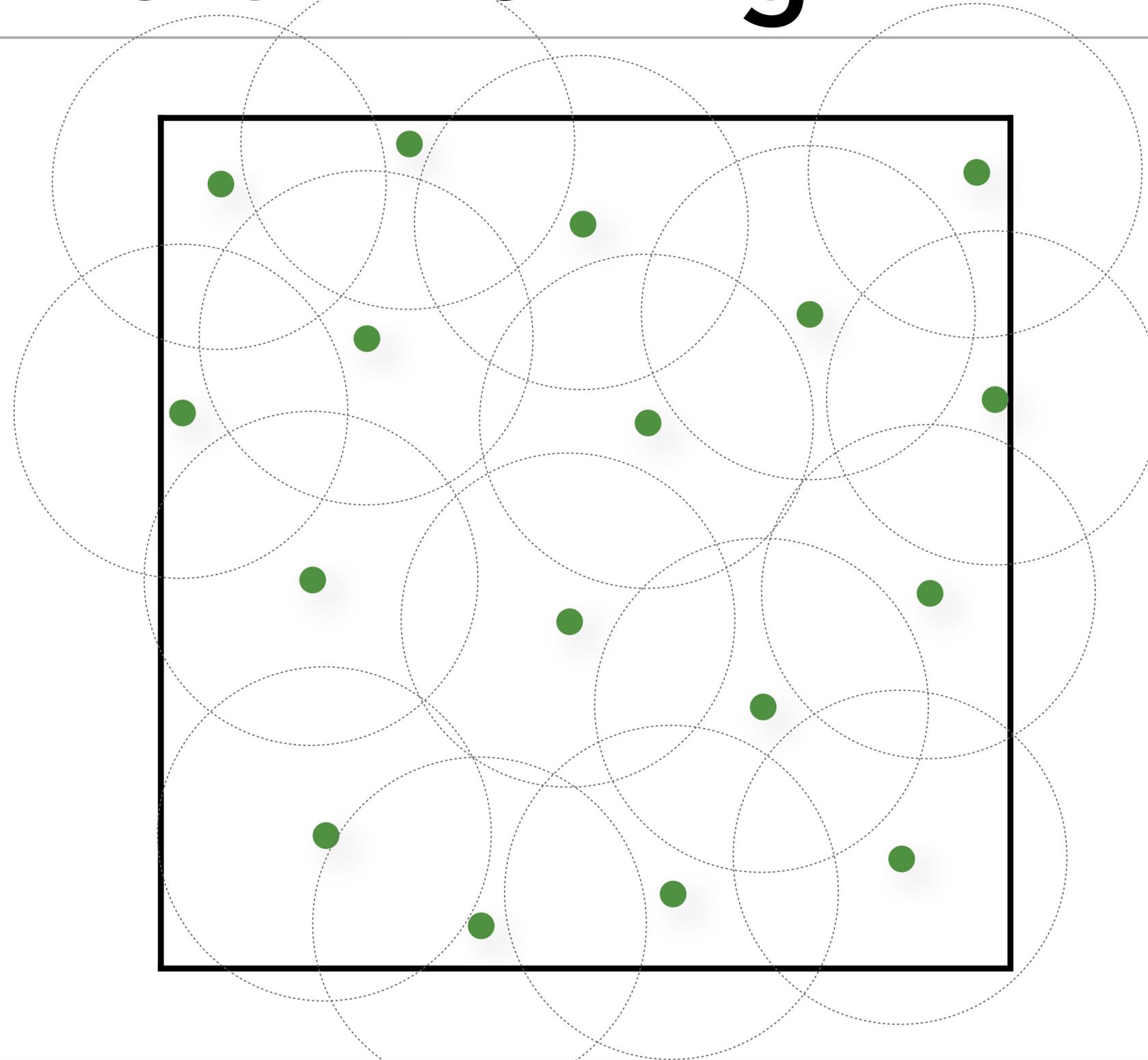
# Random Dart Throwing



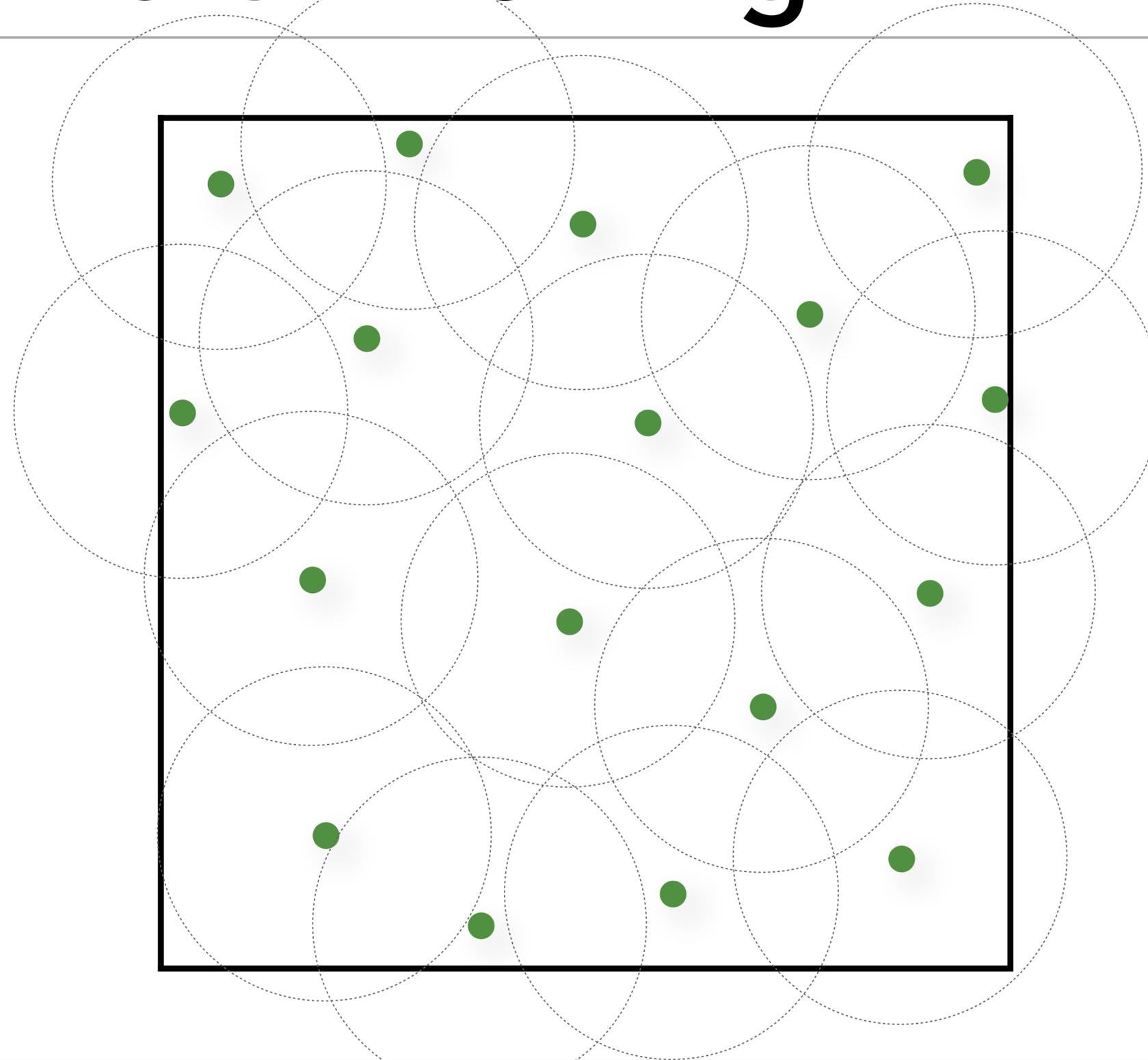
# Random Dart Throwing



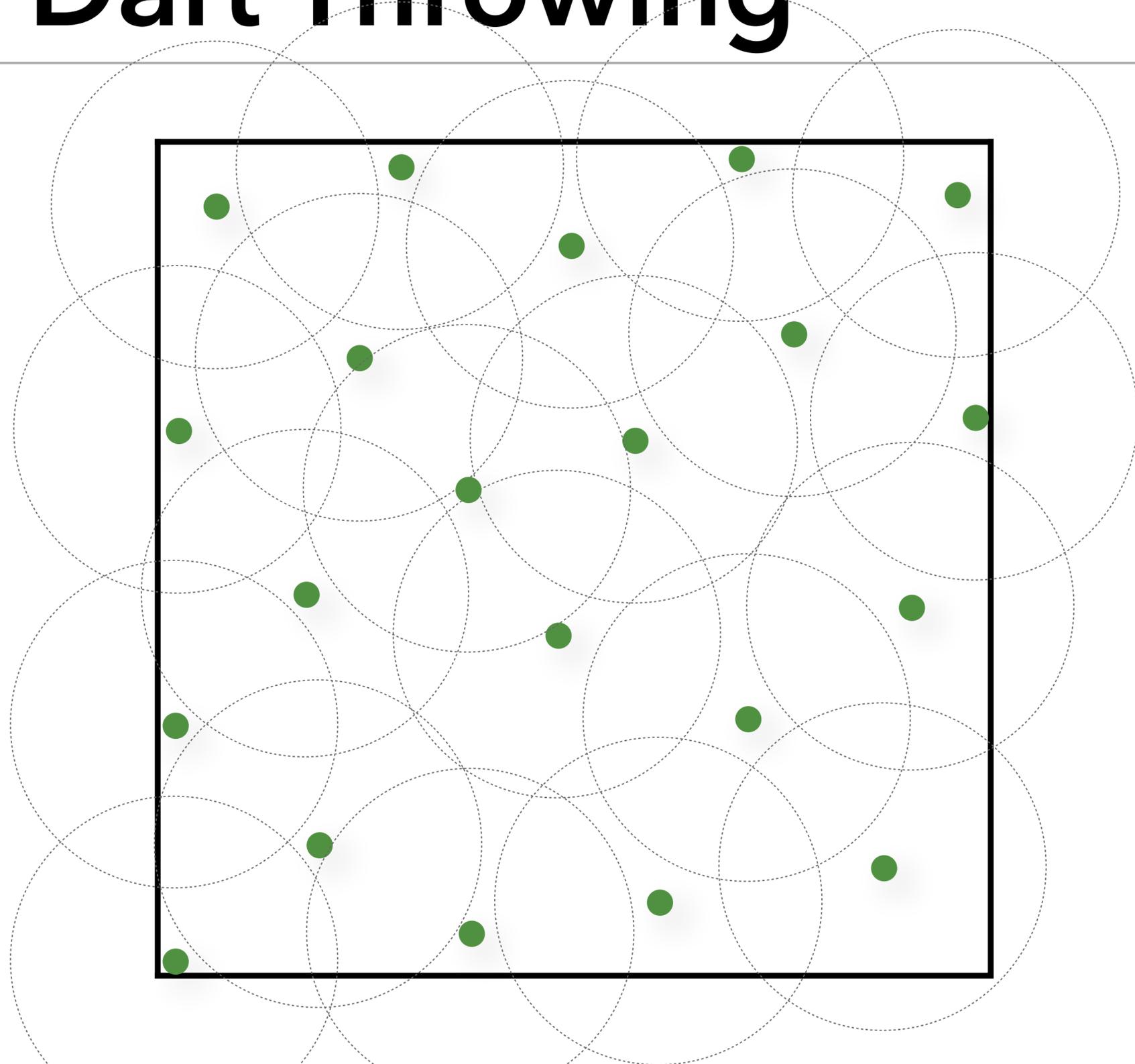
# Random Dart Throwing



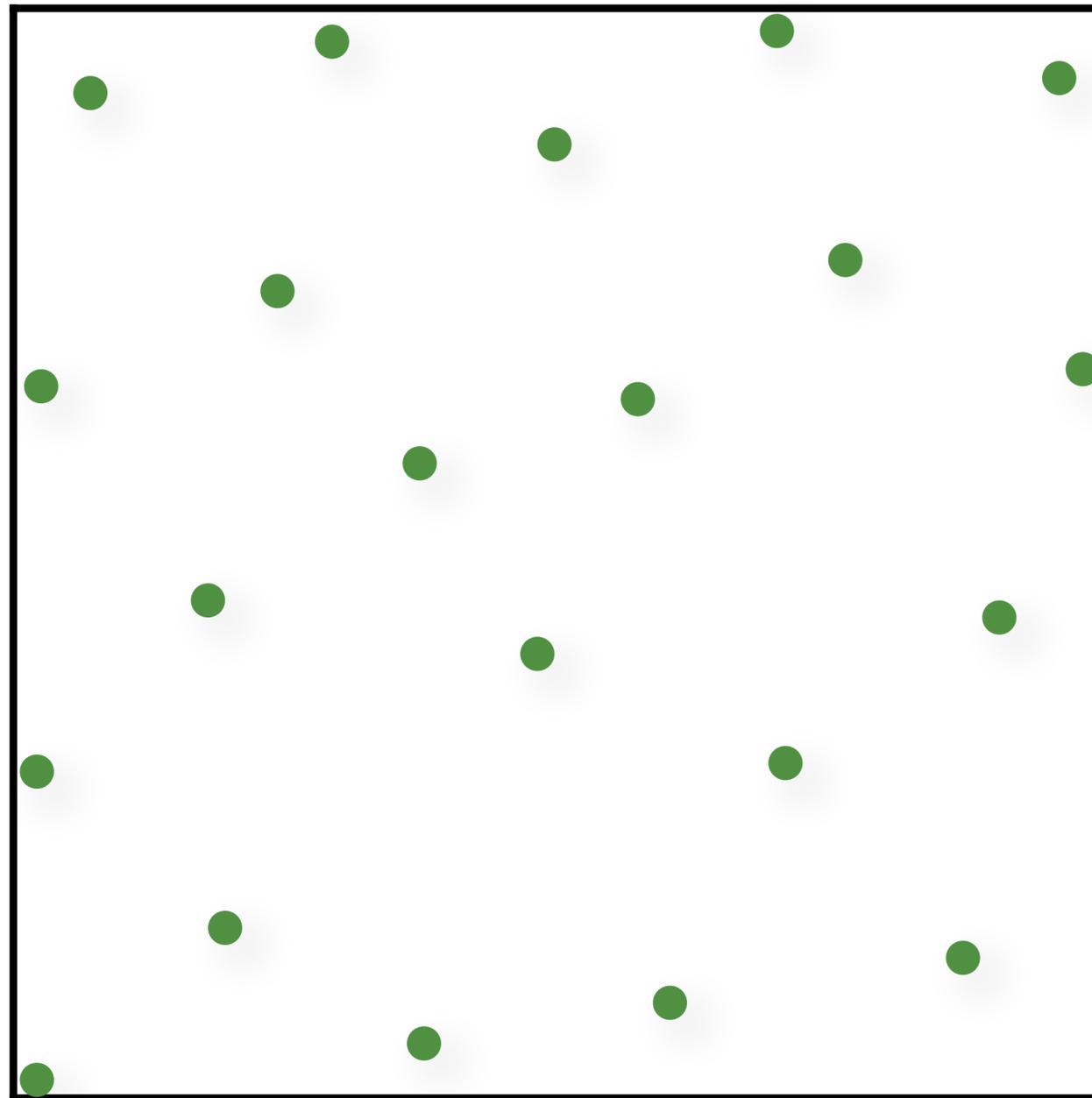
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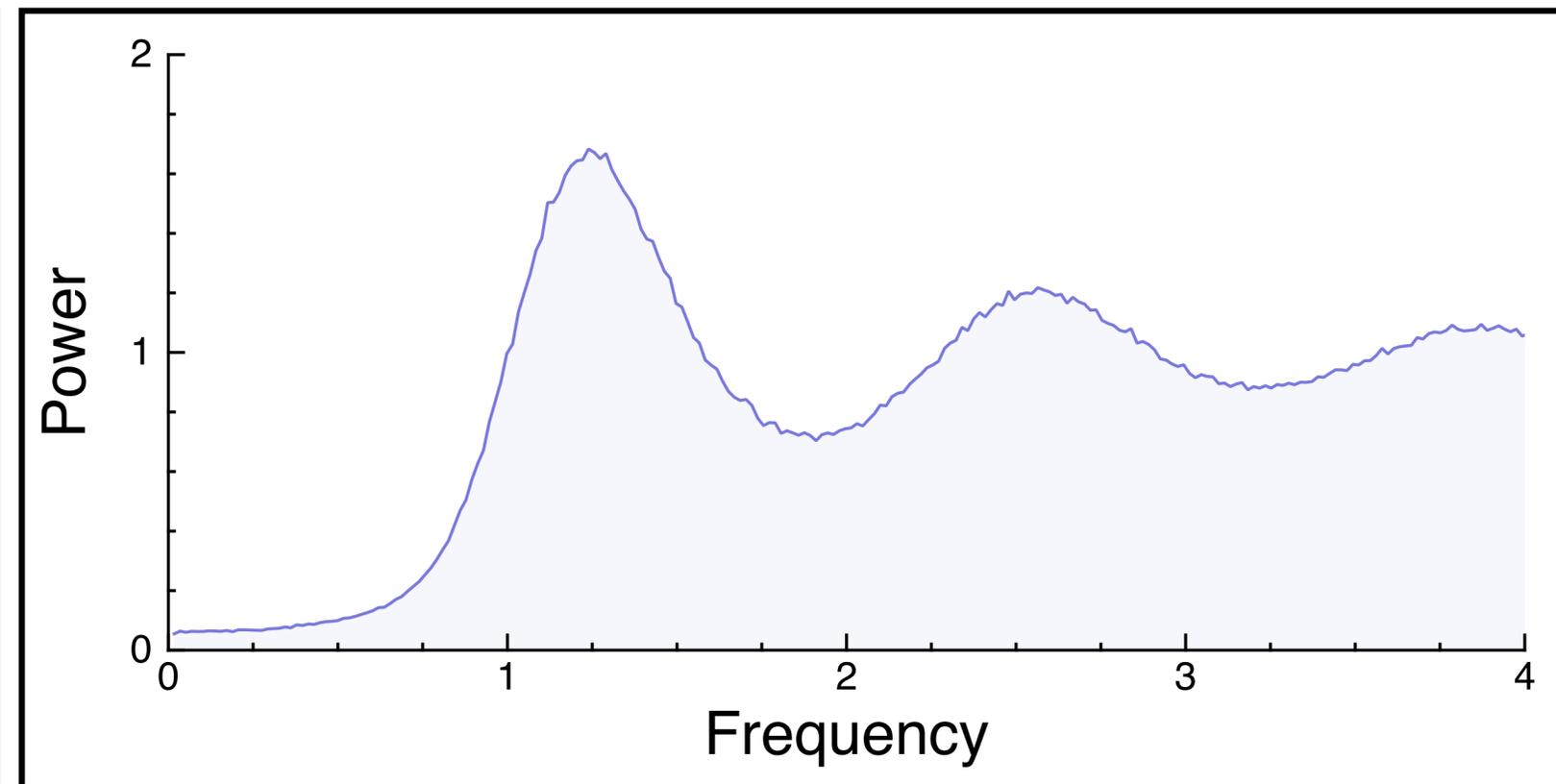
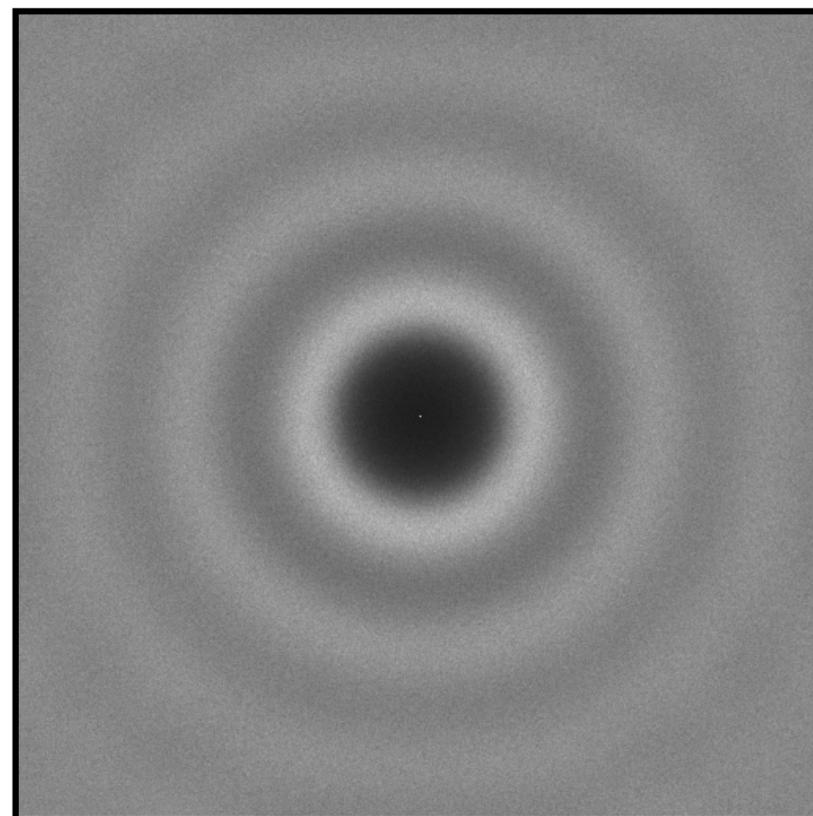
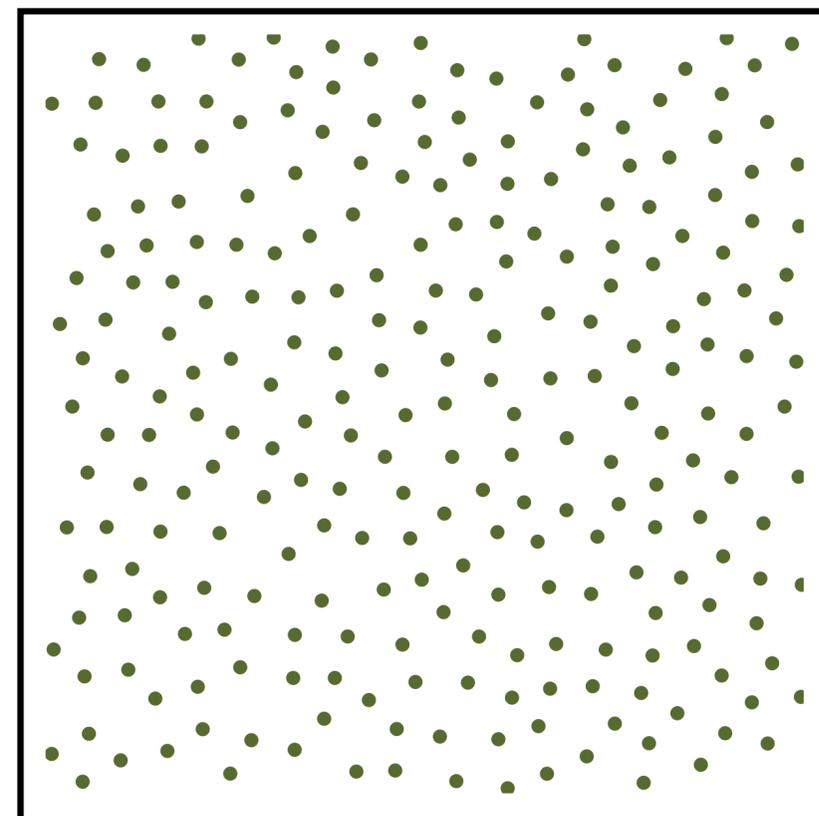


# Poisson Disk Sampling

Samples

Expected power spectrum

Radial mean



# Blue-Noise Sampling (Relaxation-based)

---

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---

1. Initialize sample positions (e.g. random)

# Blue-Noise Sampling (Relaxation-based)

---

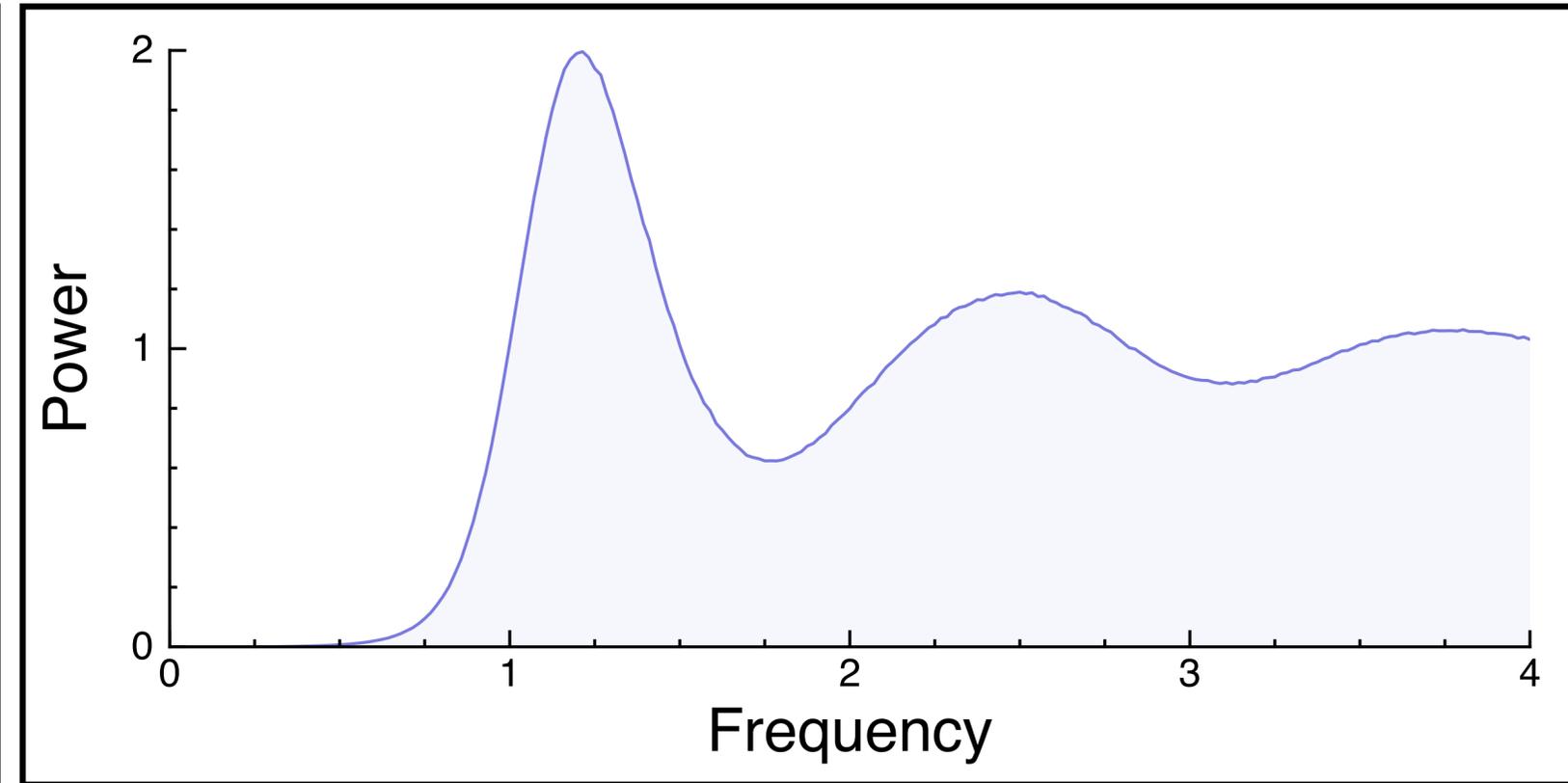
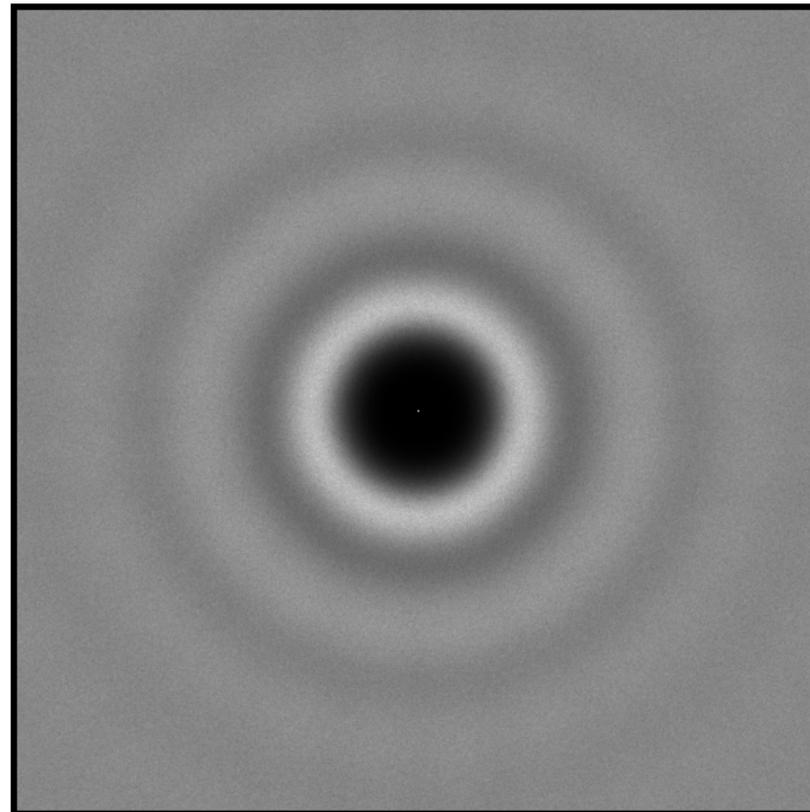
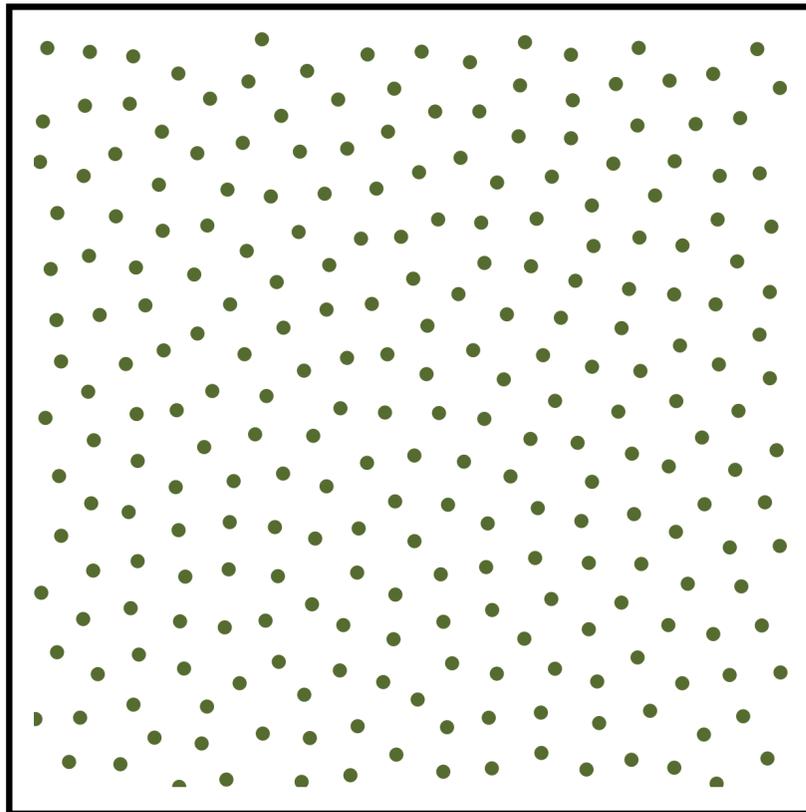
1. Initialize sample positions (e.g. random)
2. Use an iterative relaxation to move samples away from each other.

# CCVT Sampling [Balzer et al. 2009]

Samples

Expected power spectrum

Radial mean

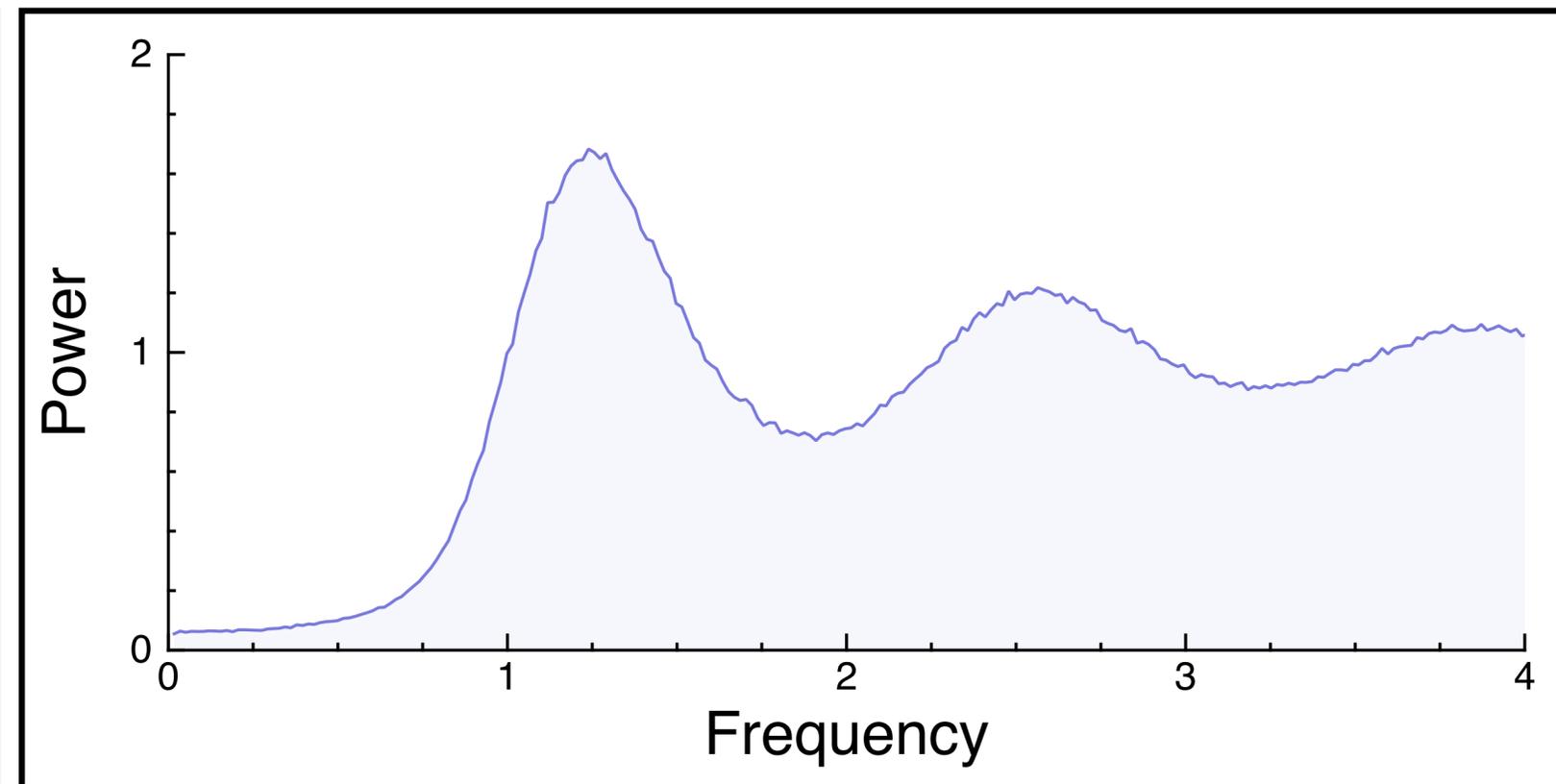
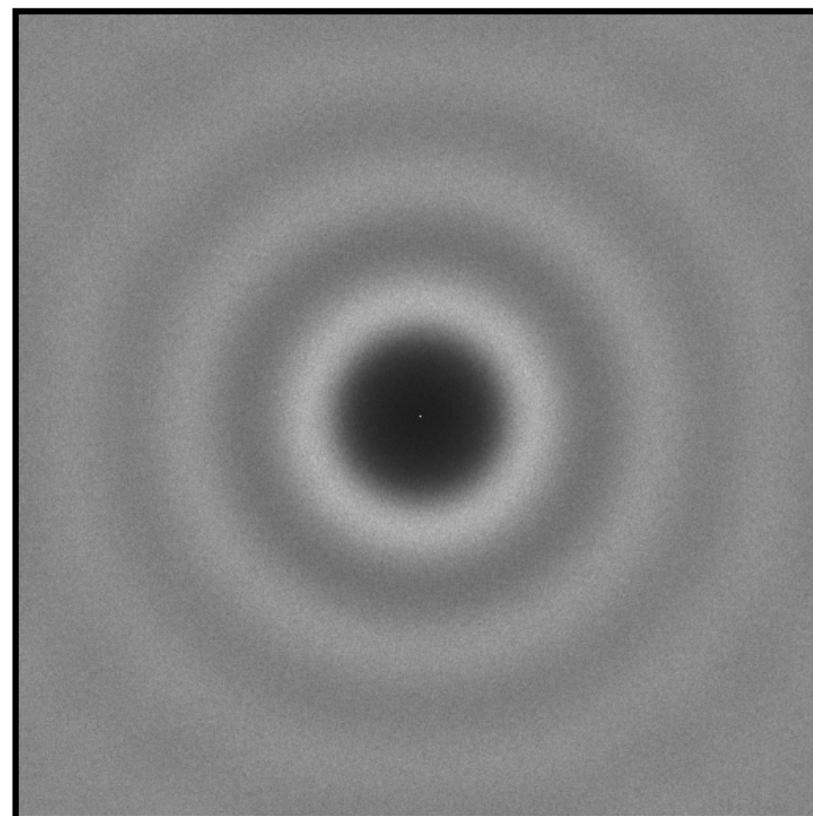
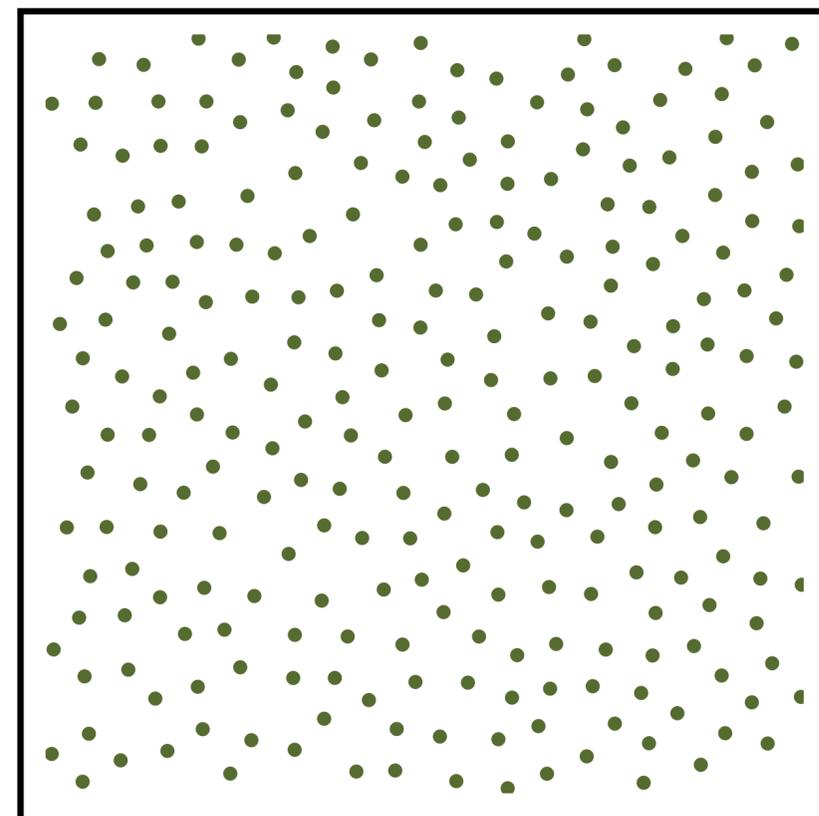


# Poisson Disk Sampling

Samples

Expected power spectrum

Radial mean



# Low-Discrepancy Sampling

---

**Deterministic** sets of points specially crafted to be evenly distributed (have low discrepancy).

Entire field of study called Quasi-Monte Carlo (QMC)

# The Van der Corput Sequence

Radical Inverse  $\Phi_b$  in base 2

$k$	Base 2	$\Phi_b$
-----	--------	----------

Subsequent points “fall into biggest holes”

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2	10	.01 = 1/4



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Subsequent points “fall into biggest holes”

$k$	Base 2	$\Phi_b$
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2	10	.01 = 1/4
3	11	.11 = 3/4



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3	11	.11 = 3/4
4	100	.001 = 1/8



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4	100	.001 = 1/8
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4	100	.001 = 1/8
5	101	.101 = 5/8
6	110	.011 = 3/8

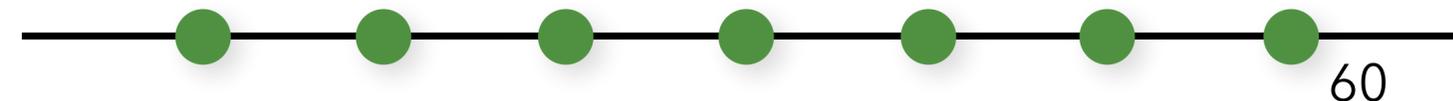


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$k$	Base 2	$\Phi_b$
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4	100	.001 = 1/8
5	101	.101 = 5/8
6	110	.011 = 3/8
7	111	.111 = 7/8

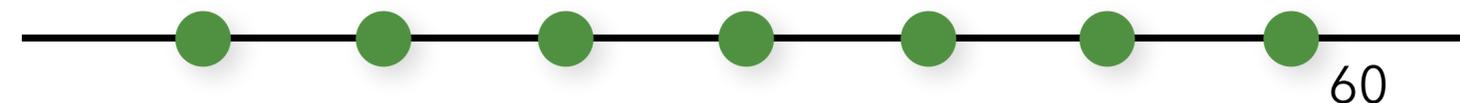


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Radical Inverse  $\Phi_b$  in base 2

Subsequent points “fall into biggest holes”

$k$	Base 2	$\Phi_b$
1	1	.1 = 1/2
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5	101	.101 = 5/8
6	110	.011 = 3/8
7	111	.111 = 7/8
...		



# Halton and Hammersley Points

**Halton:** Radical inverse with different base for each dimension:

$$\vec{x}_k = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$$

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**Hammersley:** Same as Halton, but first dimension is  $k/N$ :

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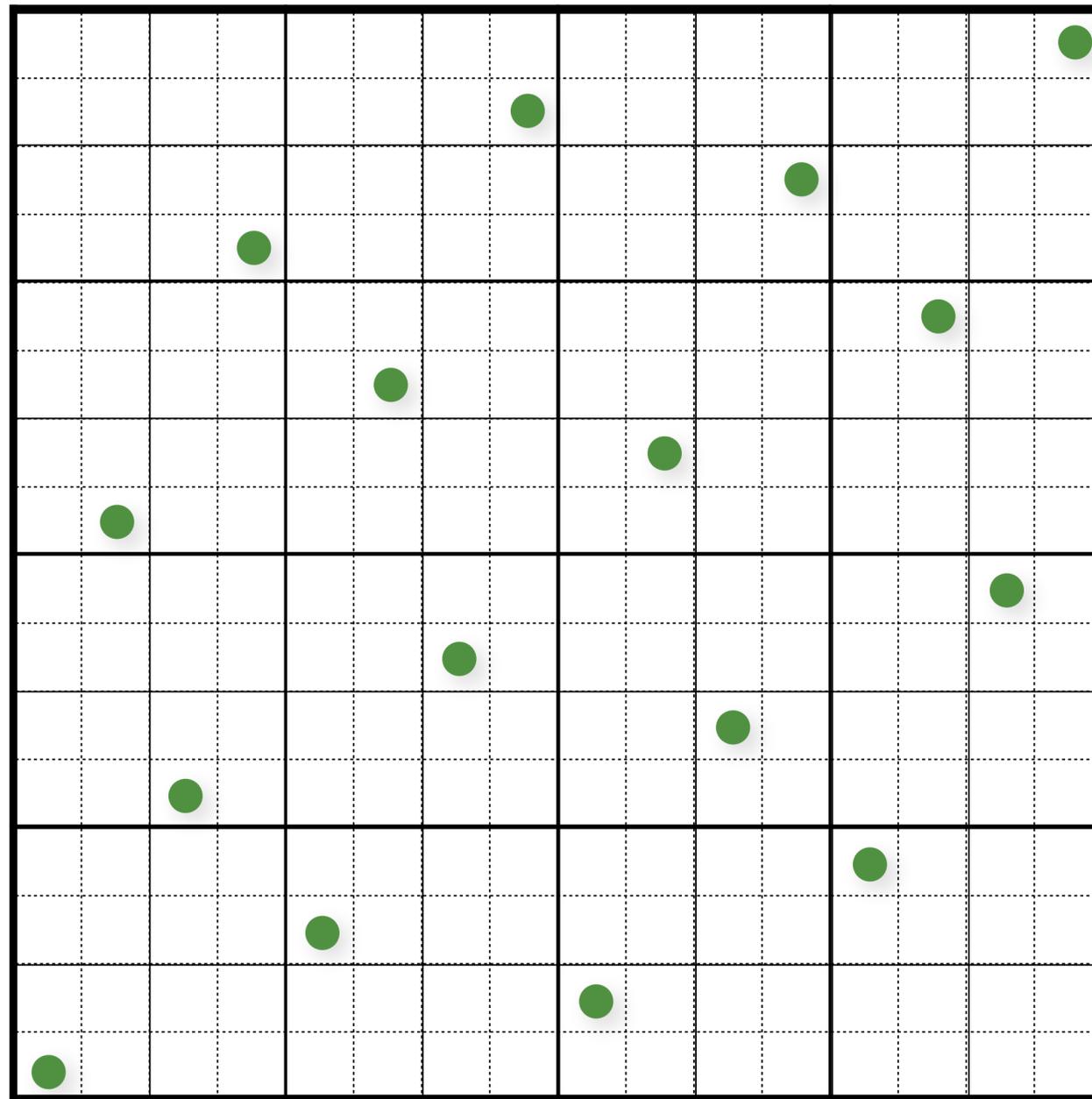
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$$\vec{x}_k = (k/N, \Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$$

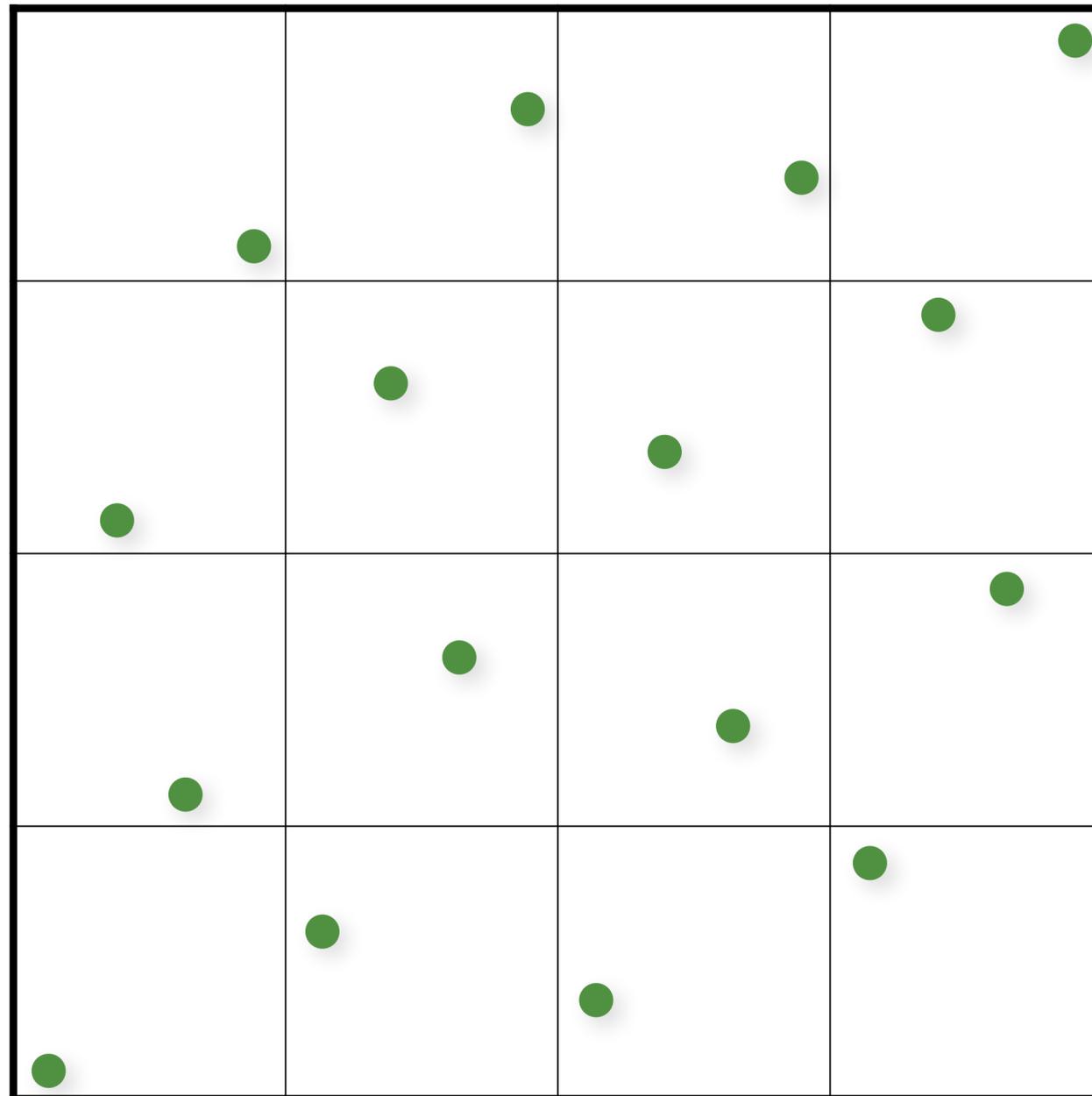
- Not incremental, need to know sample count,  $N$ , in advance

# The Hammersley Sequence



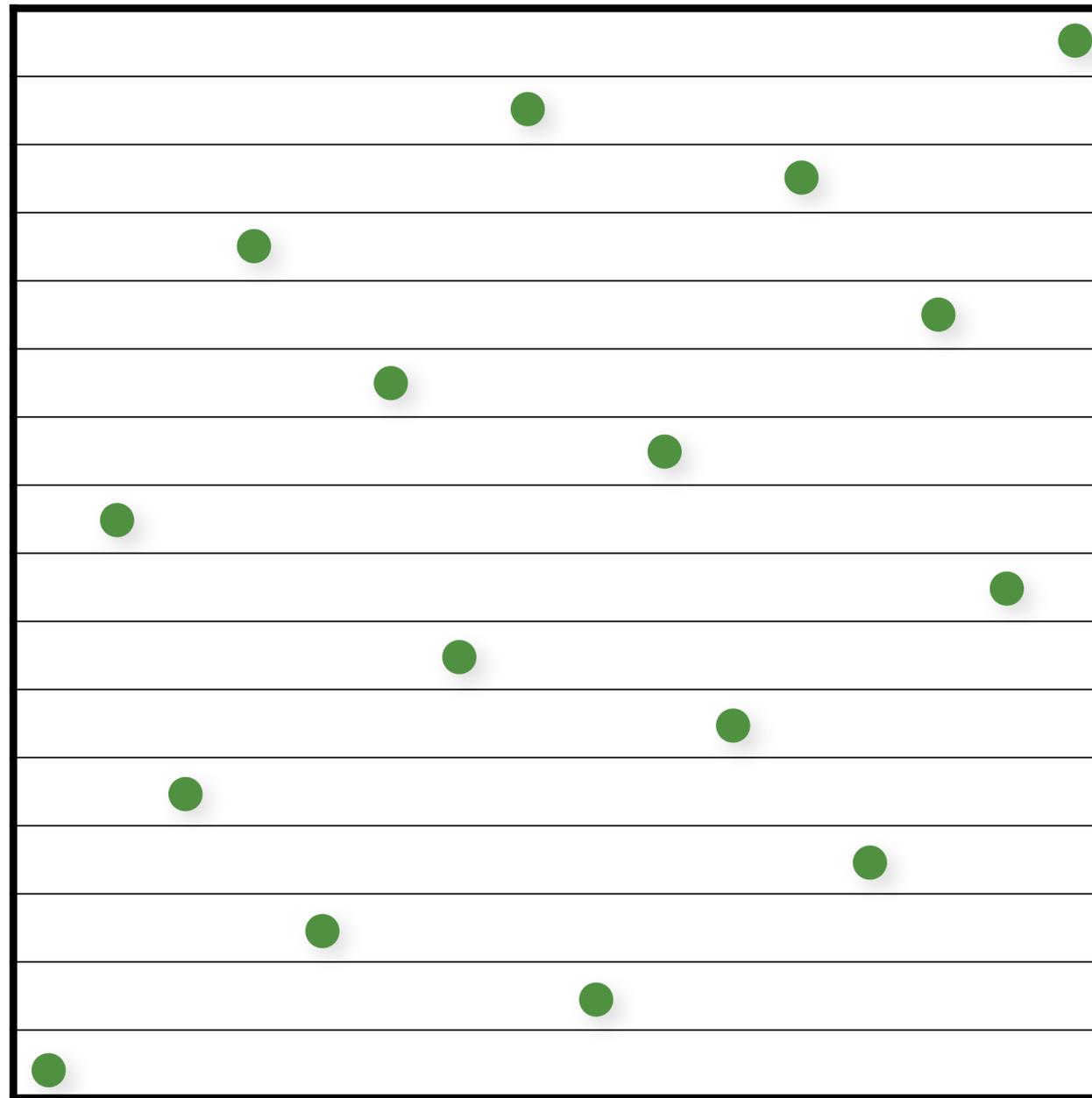
1 sample in each "elementary interval"

# The Hammersley Sequence



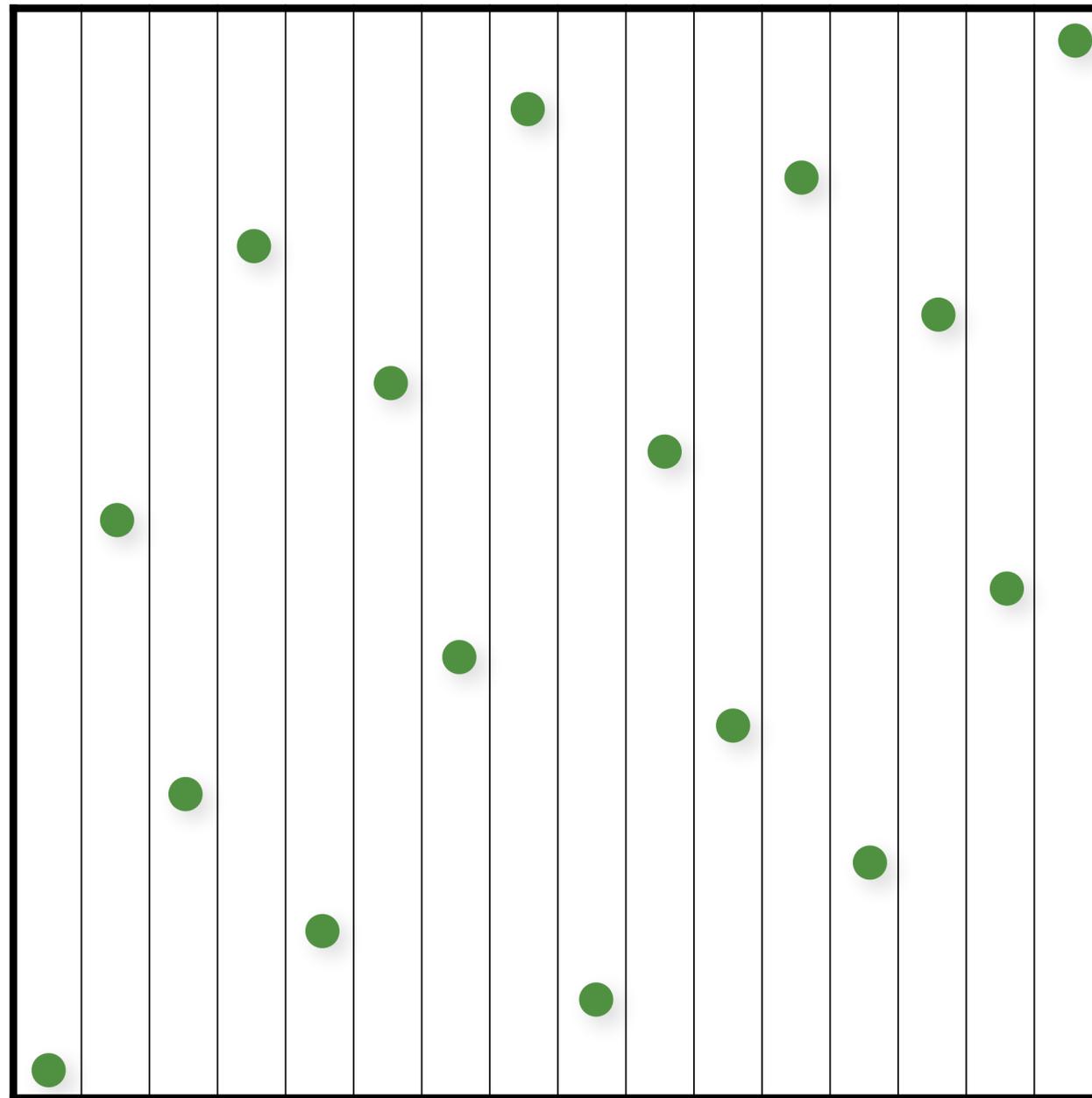
1 sample in each "elementary interval"

# The Hammersley Sequence



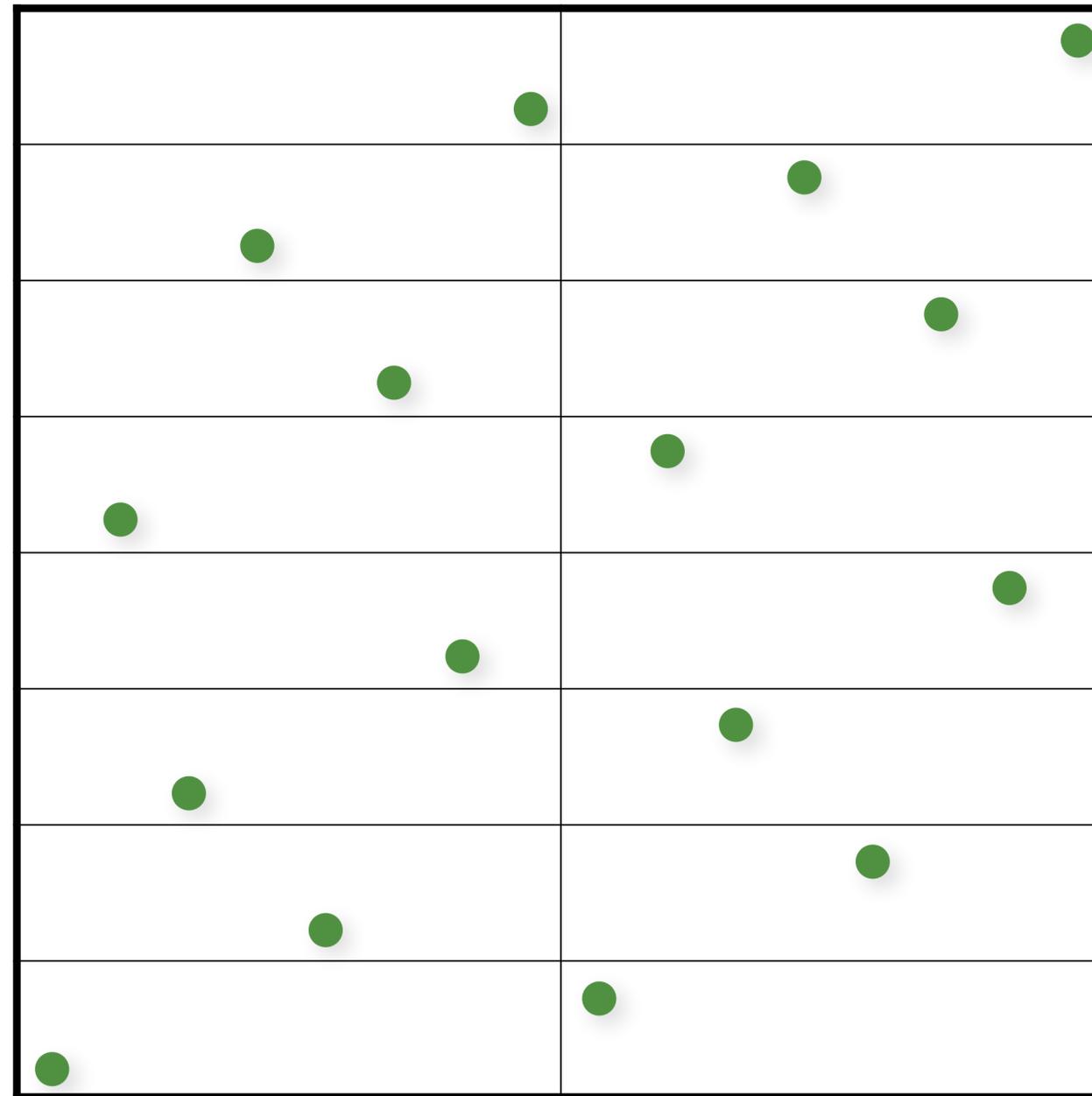
1 sample in each "elementary interval"

# The Hammersley Sequence



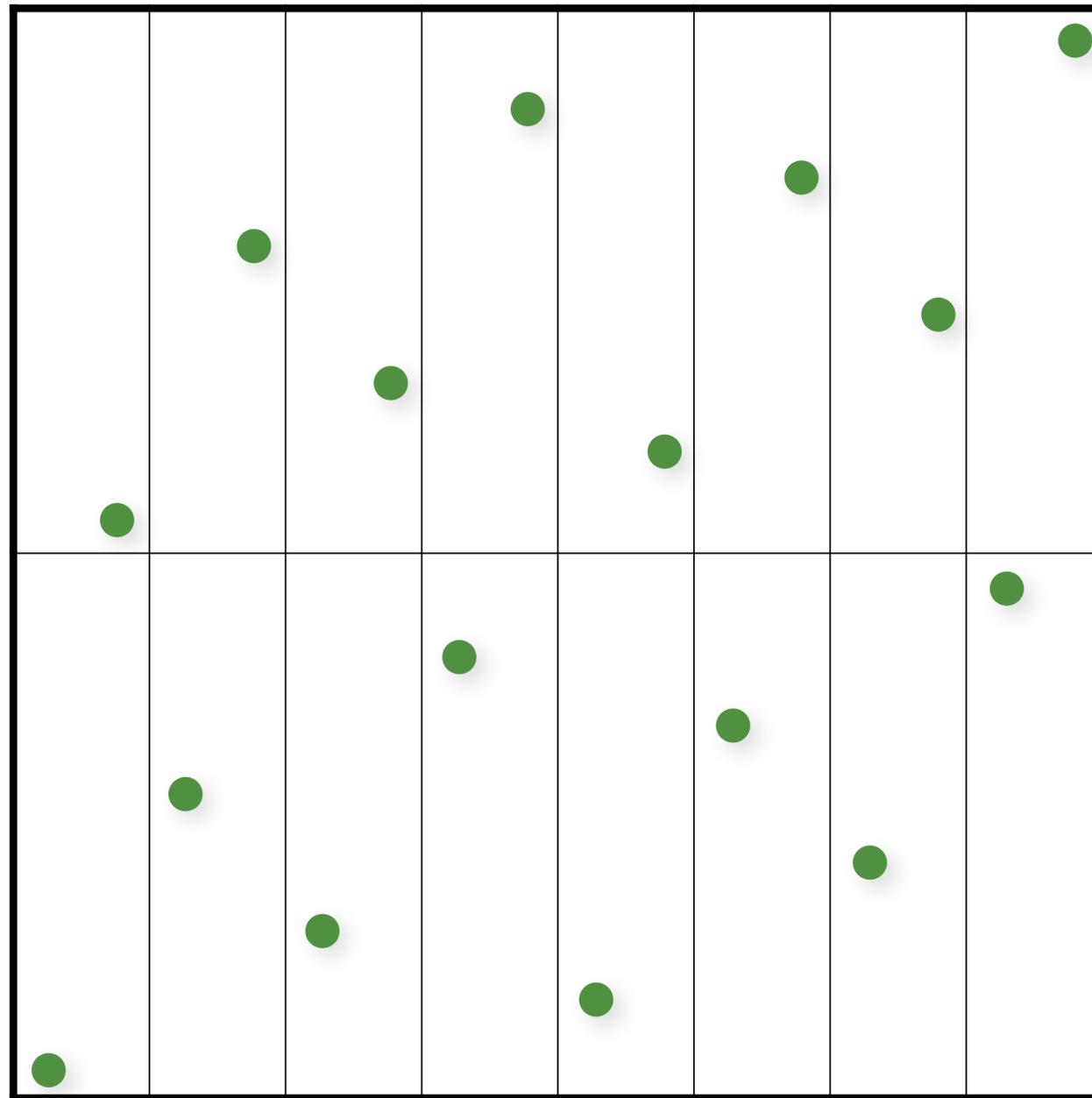
1 sample in each "elementary interval"

# The Hammersley Sequence



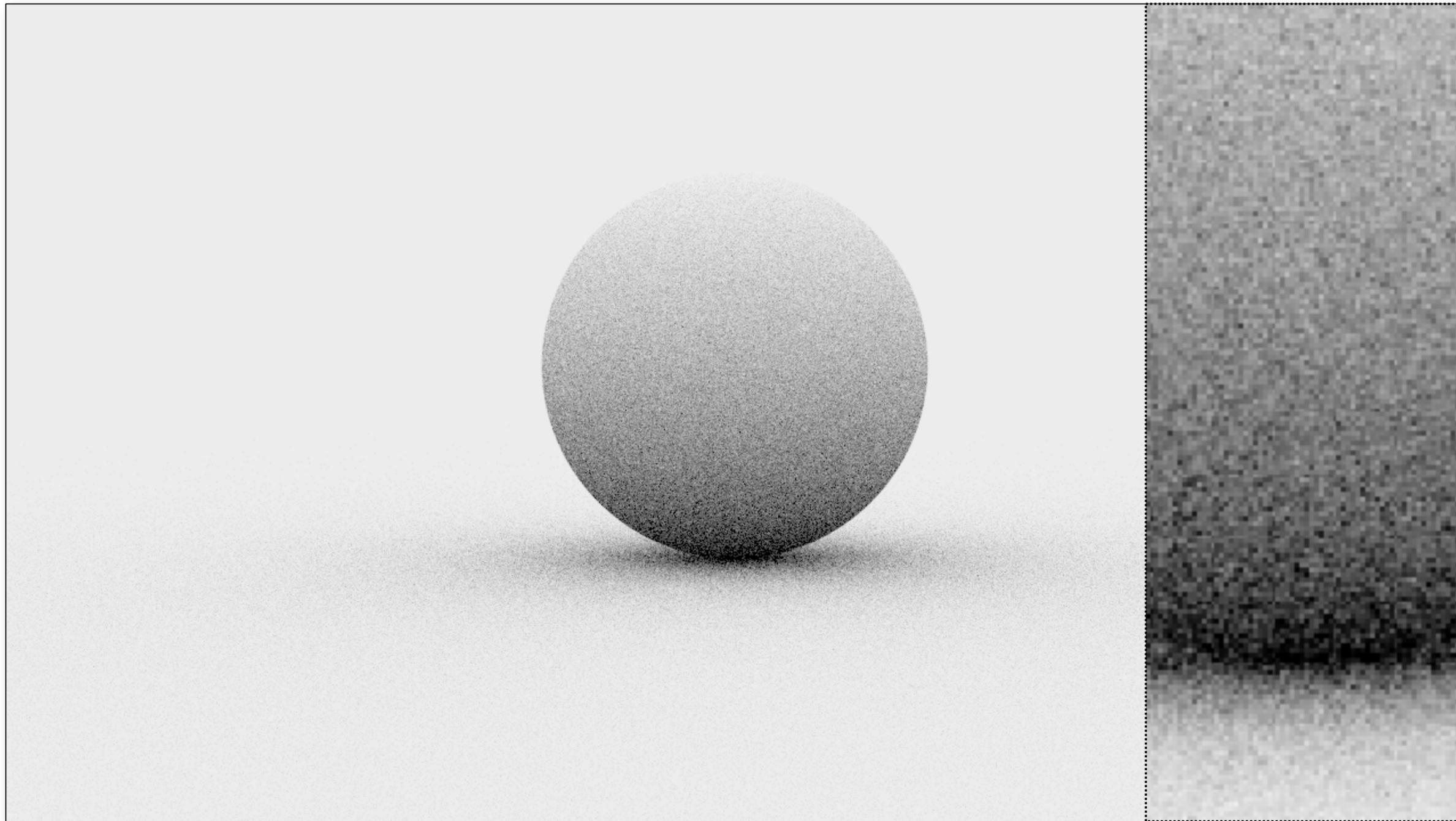
1 sample in each "elementary interval"

# The Hammersley Sequence

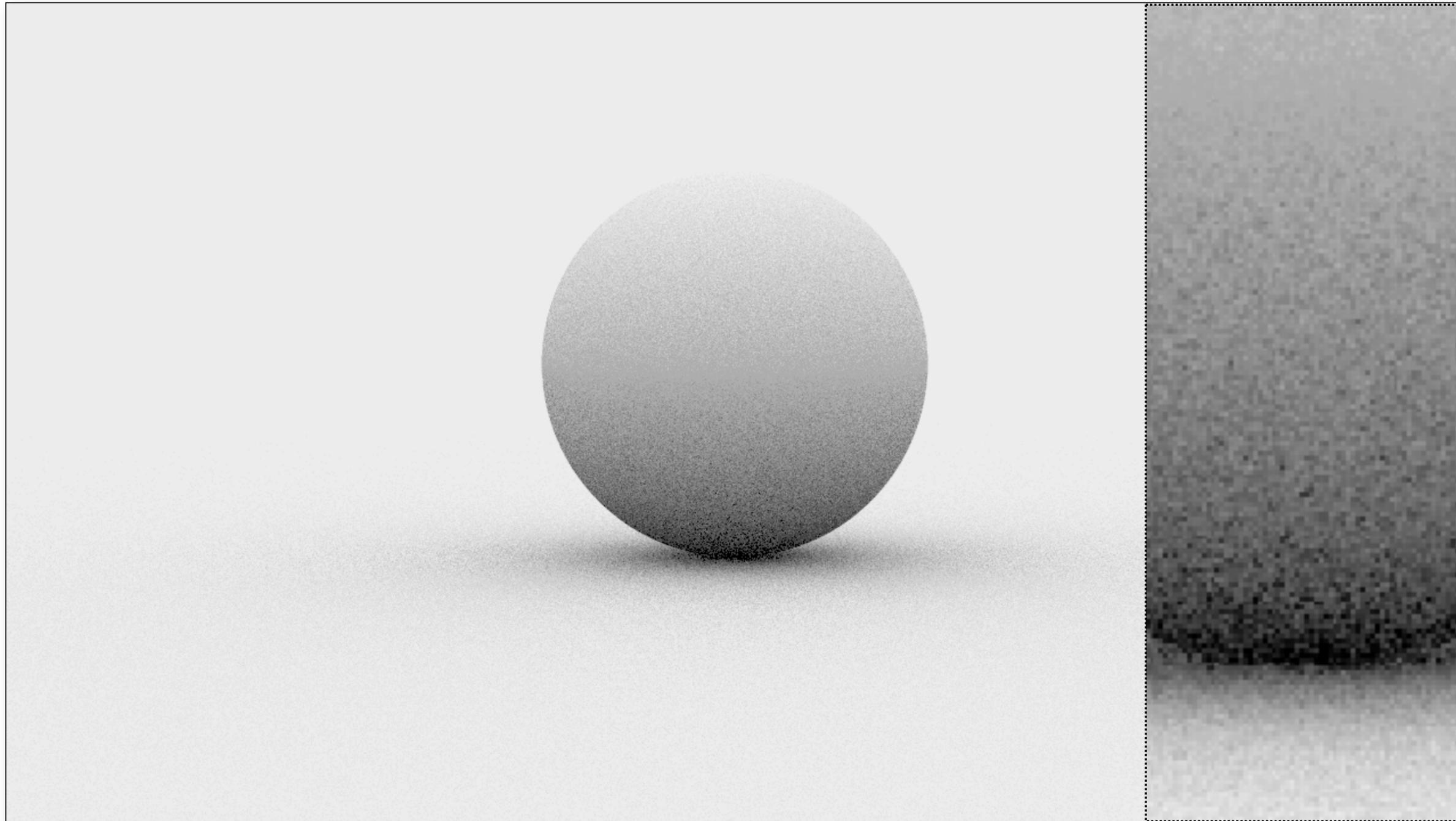


1 sample in each "elementary interval"

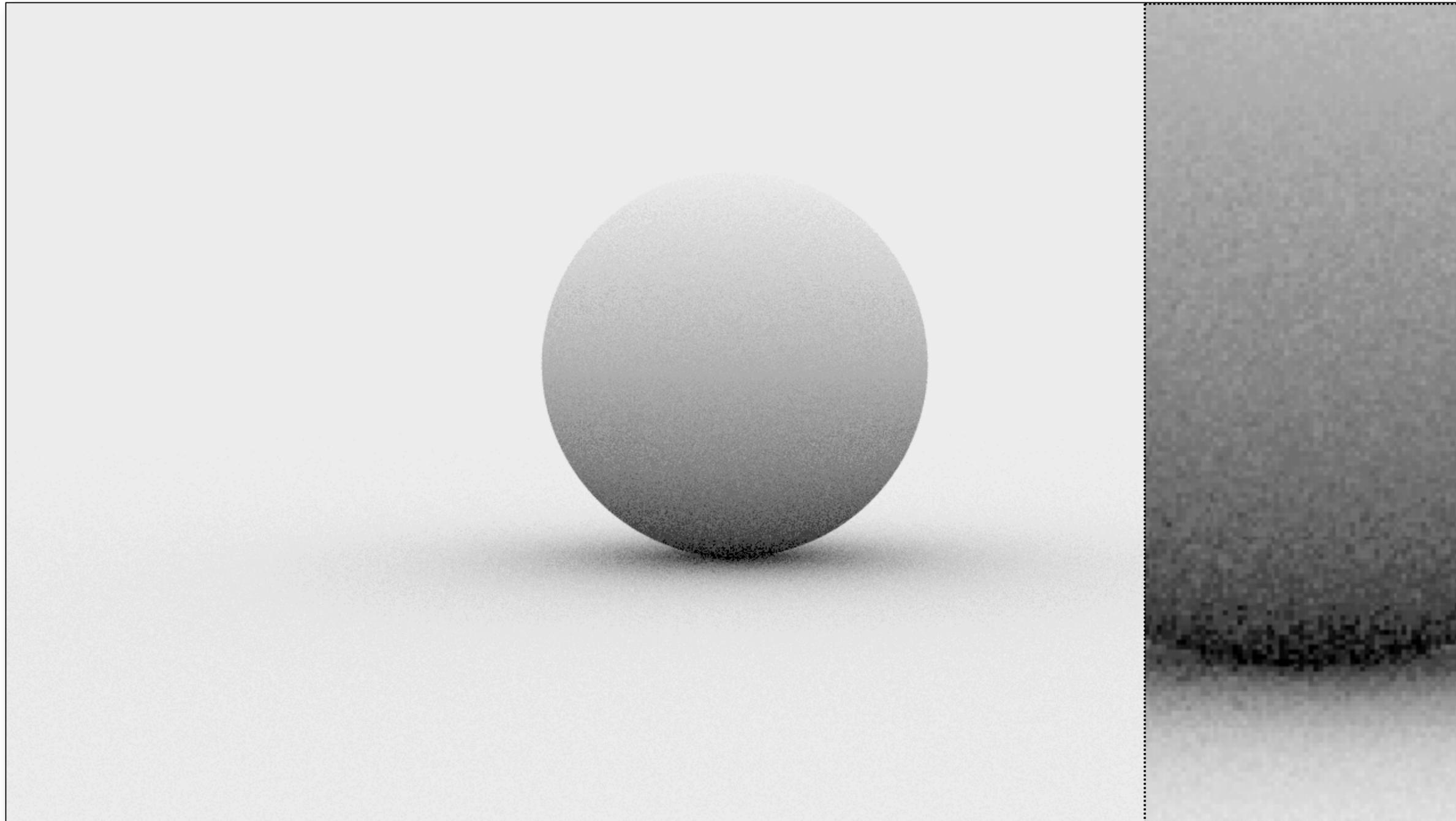
# Monte Carlo (16 random samples)



# Monte Carlo (16 jittered samples)



# Scrambled Low-Discrepancy Sampling



# More info on QMC in Rendering

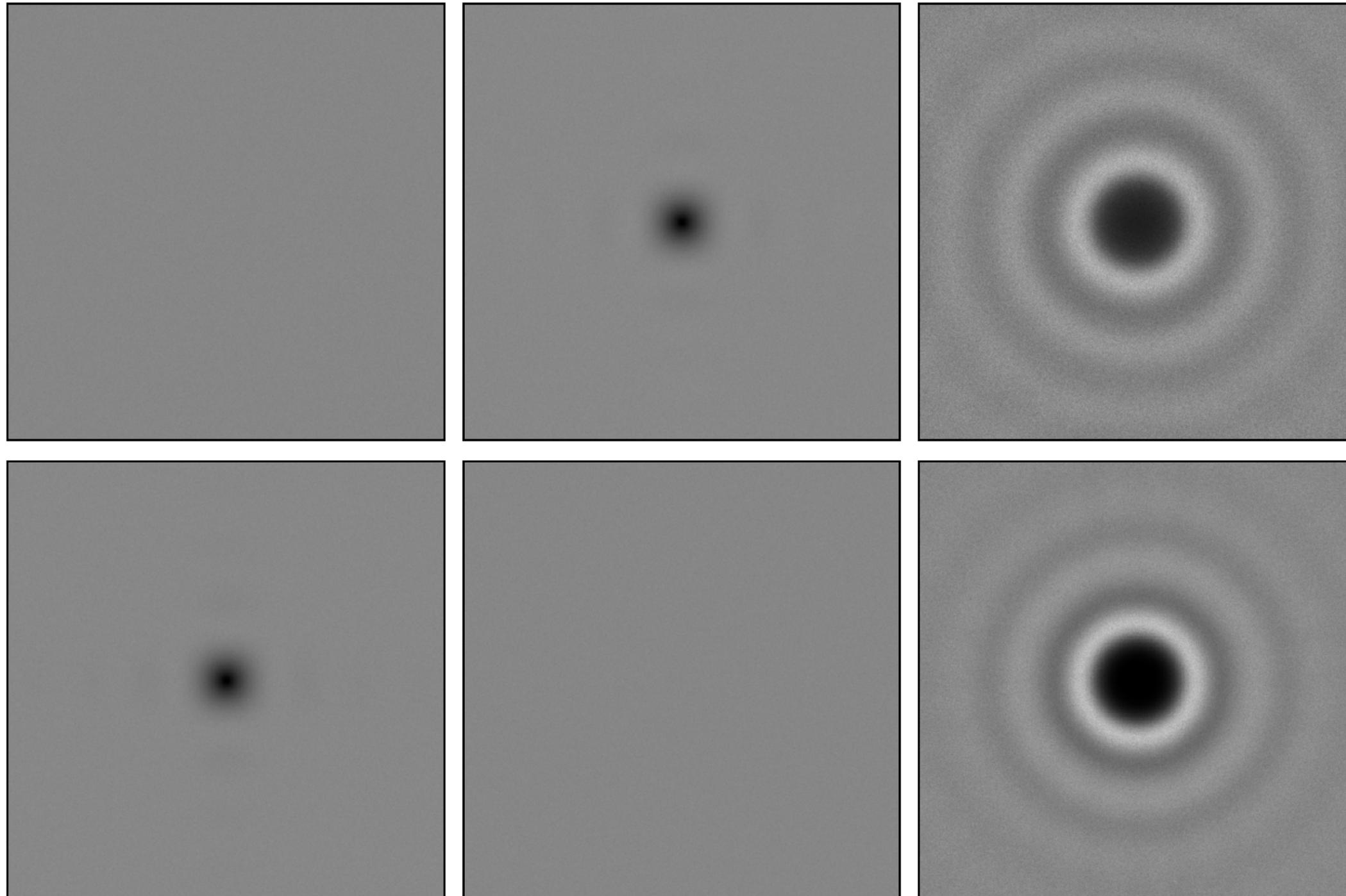
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S. Premoze, A. Keller, and M. Raab.

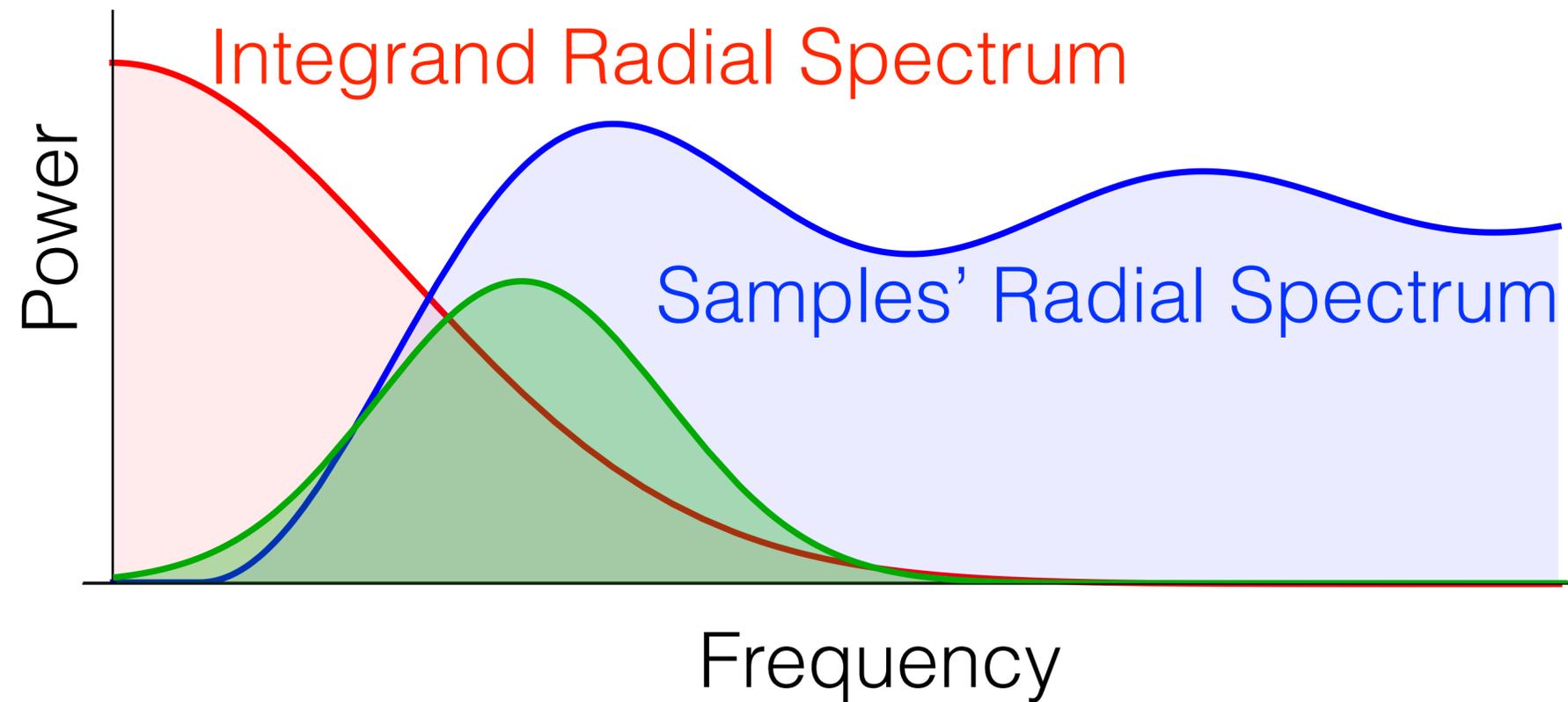
*Advanced (Quasi-) Monte Carlo Methods for Image Synthesis.*

In SIGGRAPH 2012 courses.

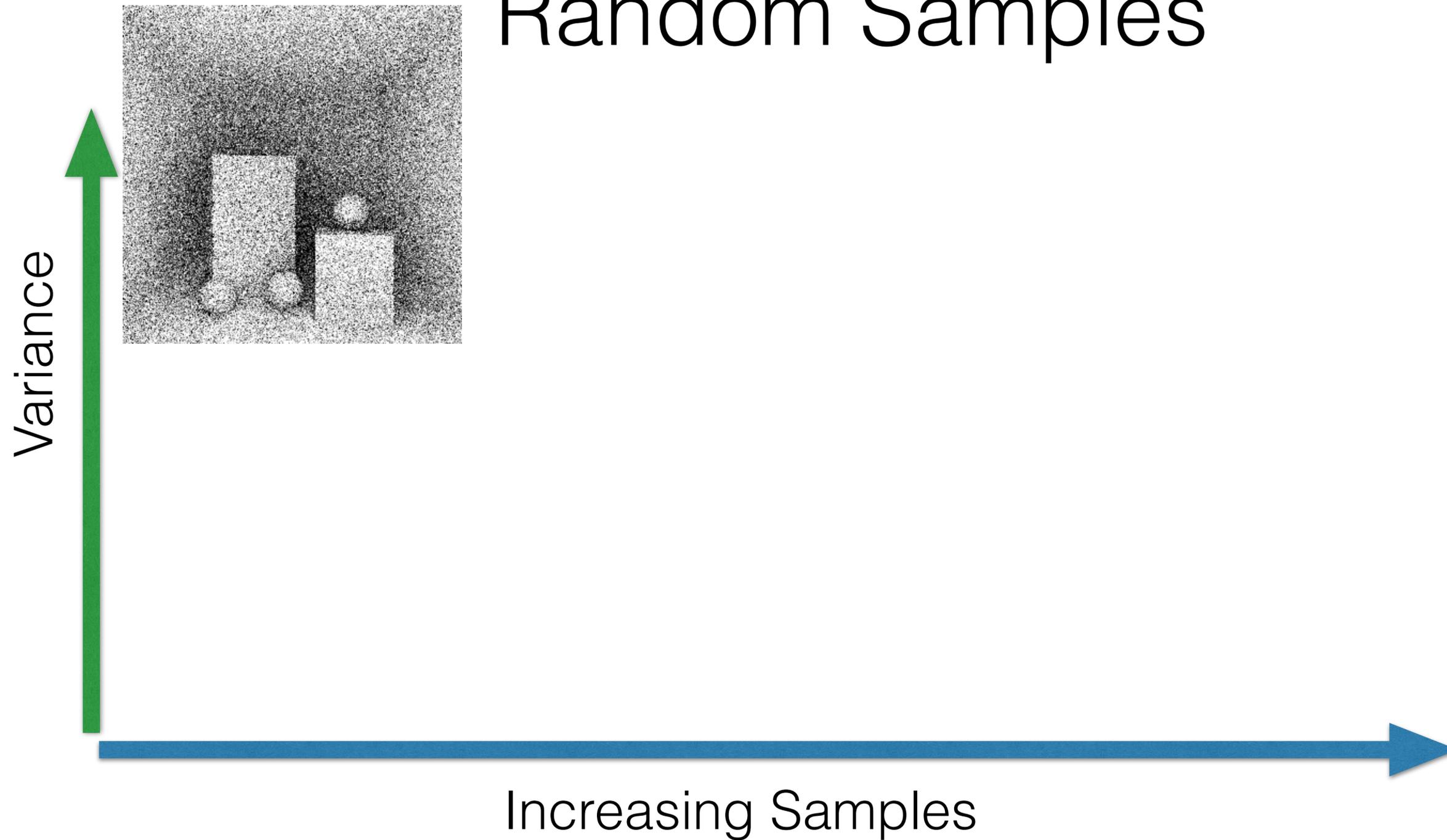
# How can we predict error from these?



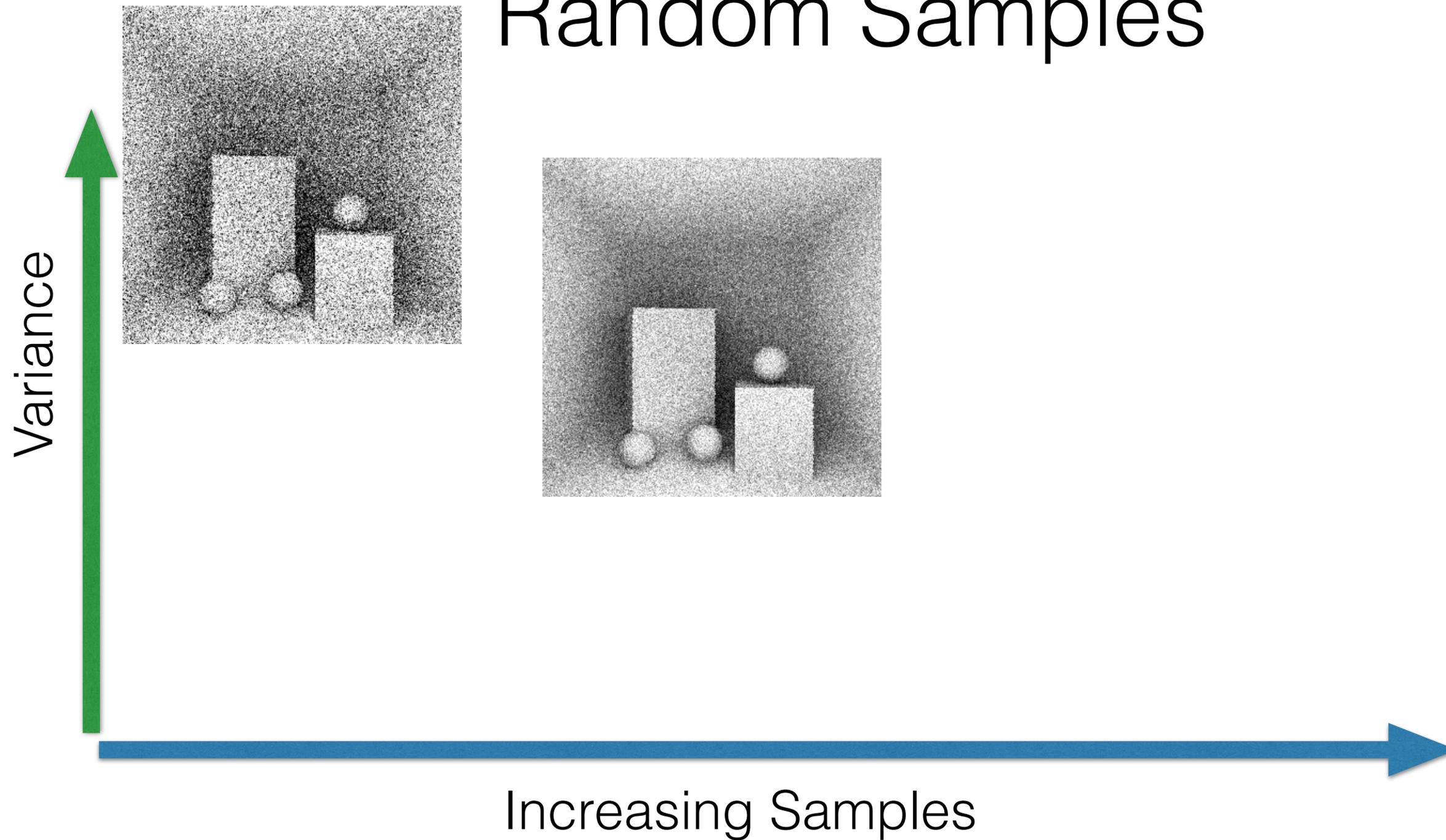
## Part 2: Formal Treatment of MSE, Bias and Variance



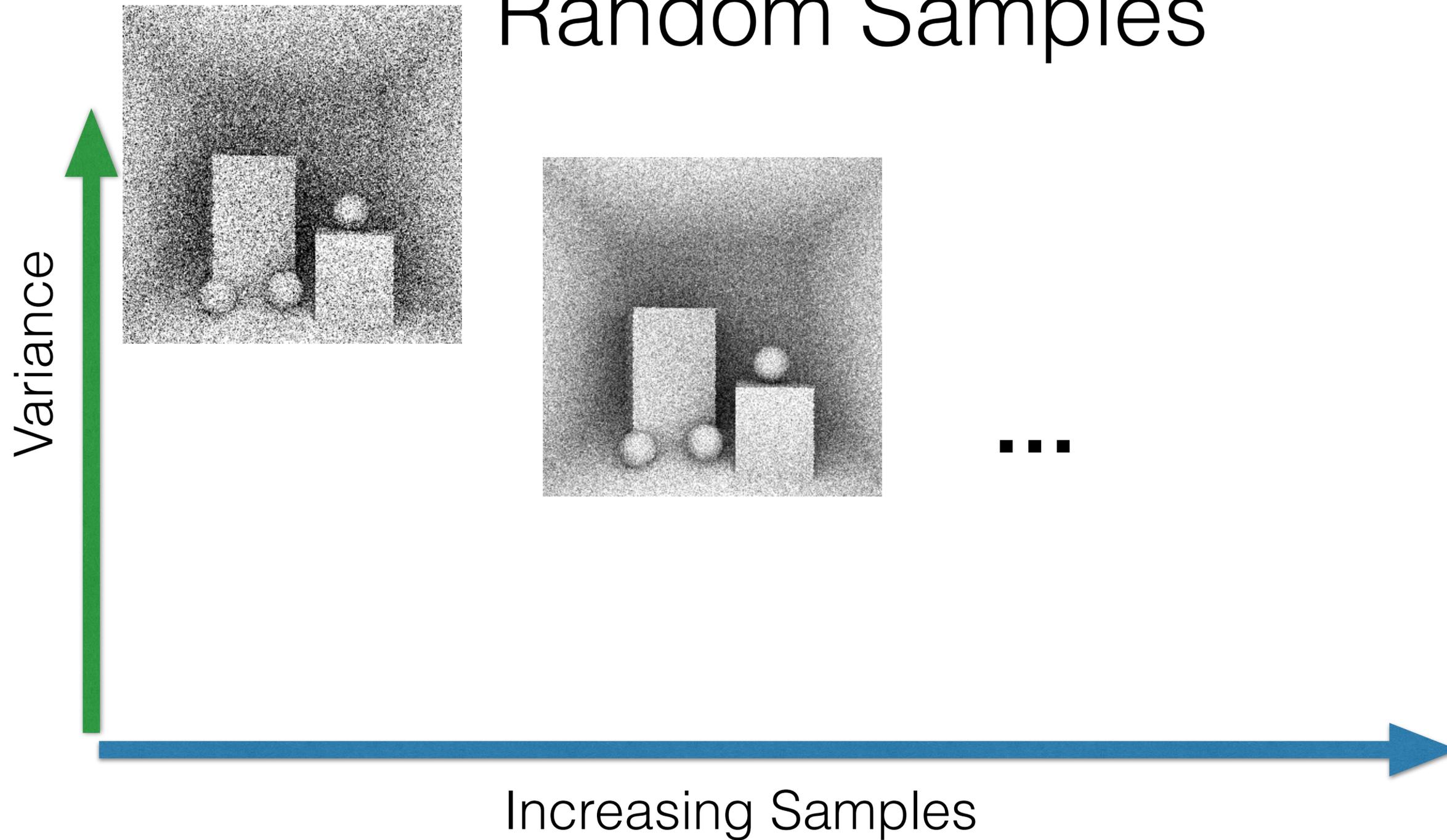
# Convergence rate for Random Samples



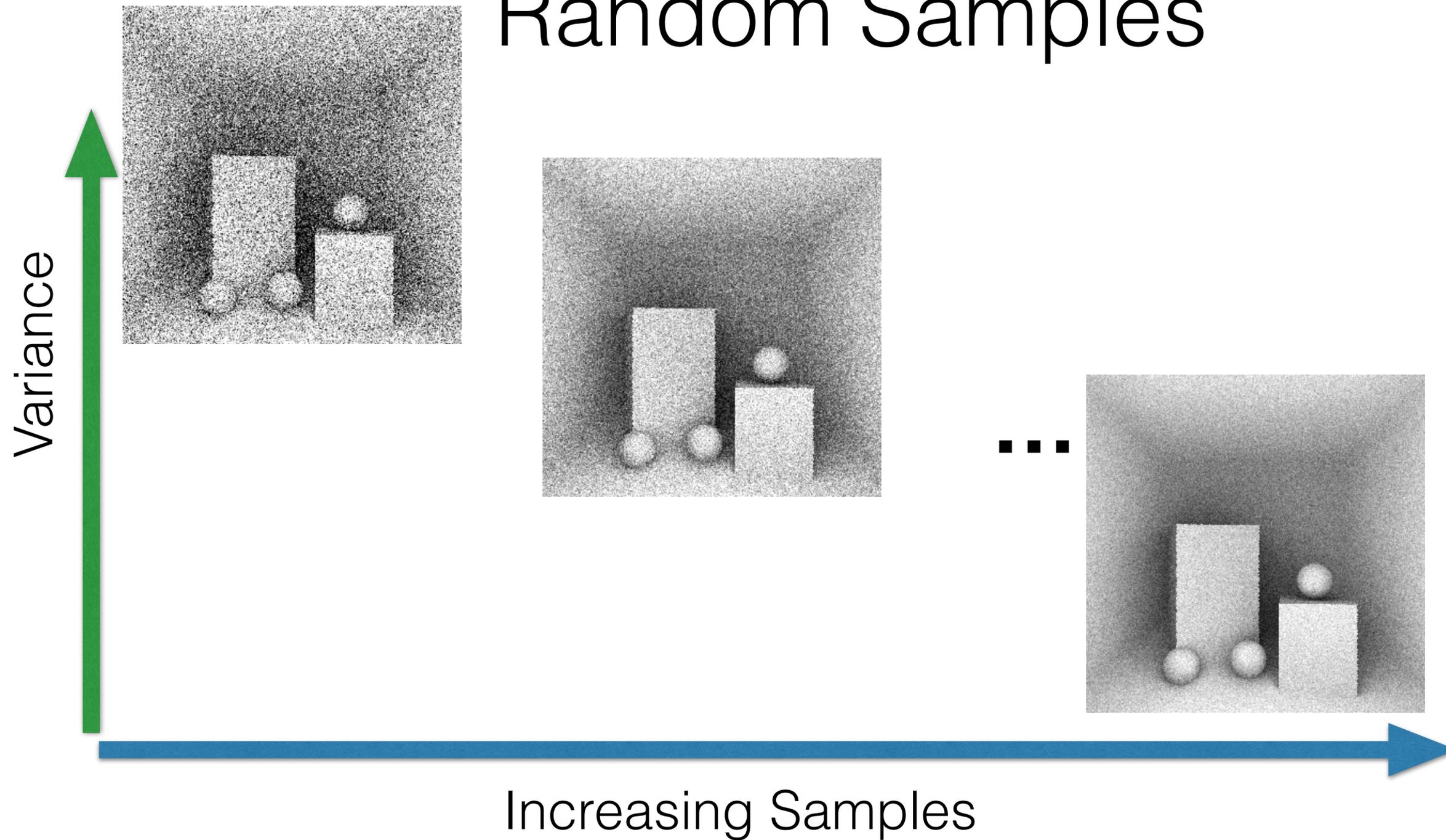
# Convergence rate for Random Samples



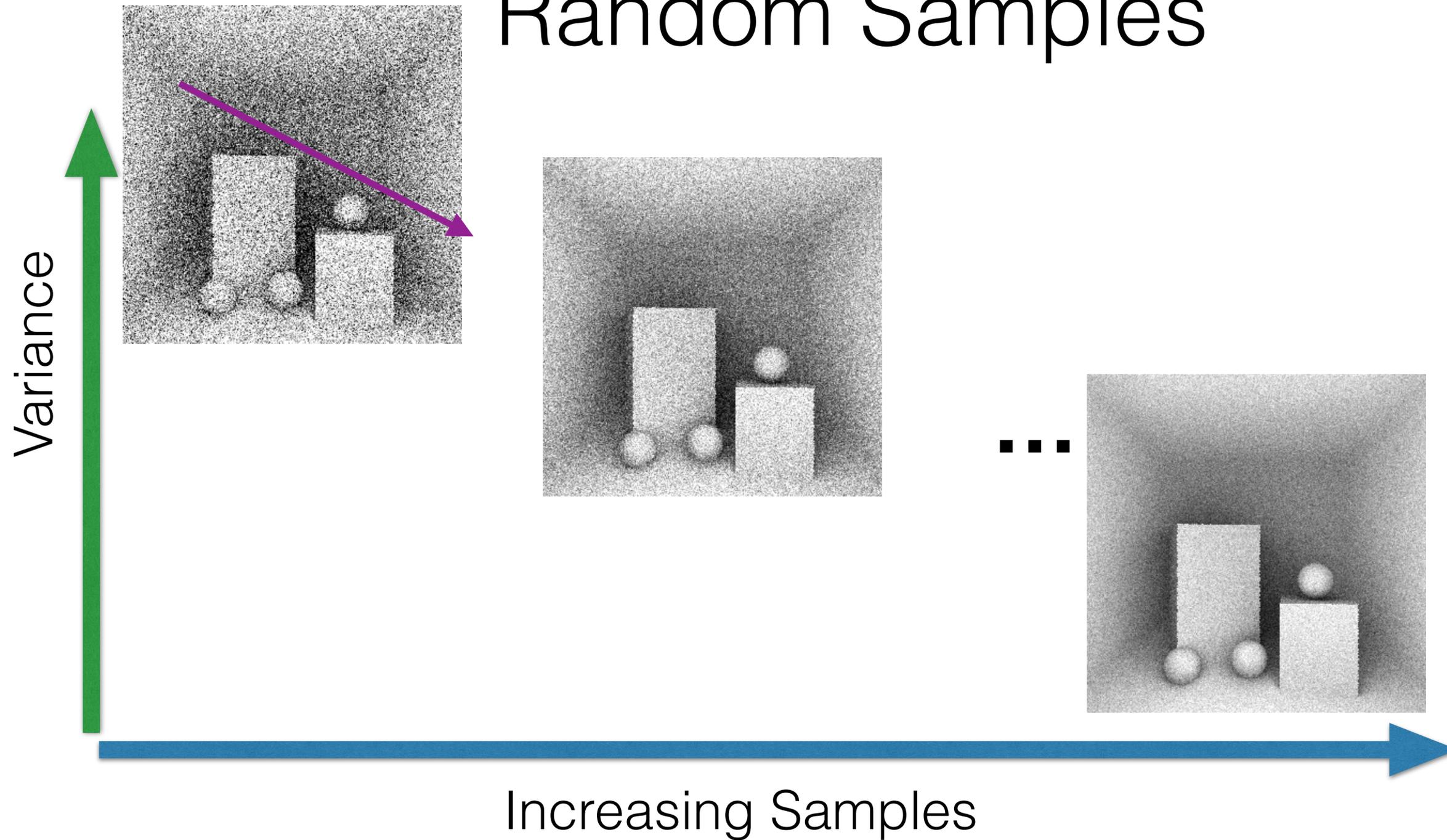
# Convergence rate for Random Samples



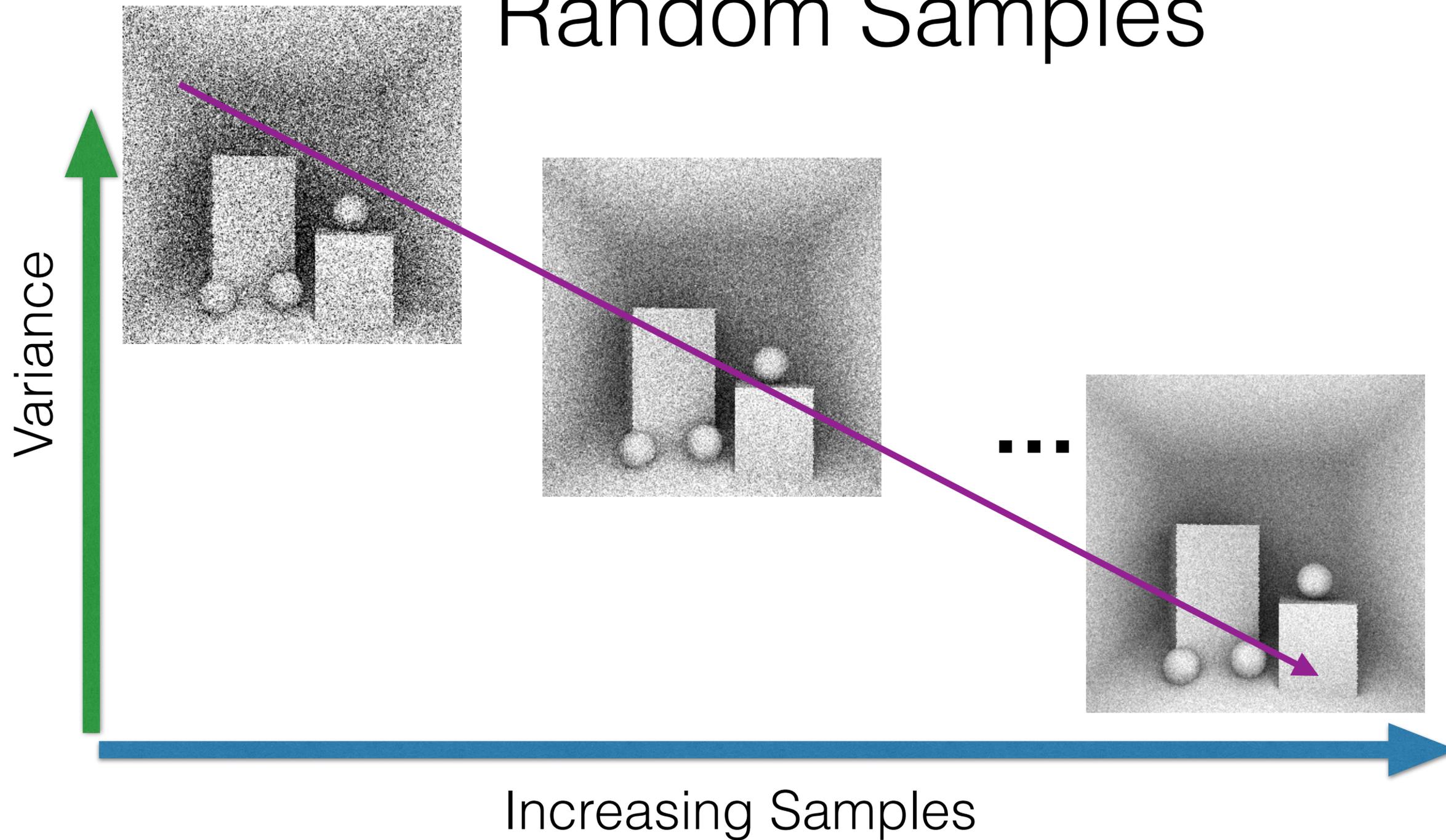
# Convergence rate for Random Samples



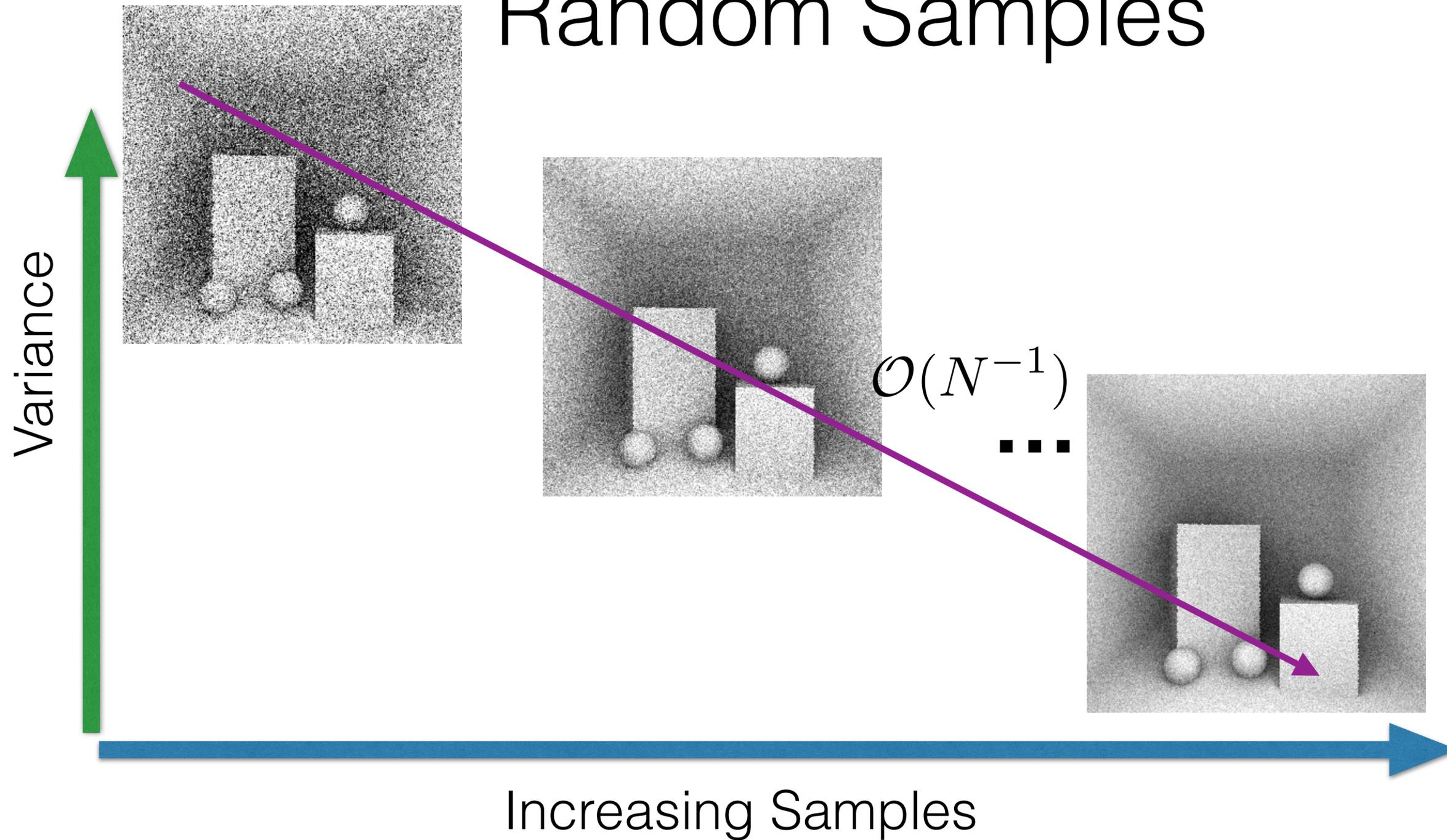
# Convergence rate for Random Samples



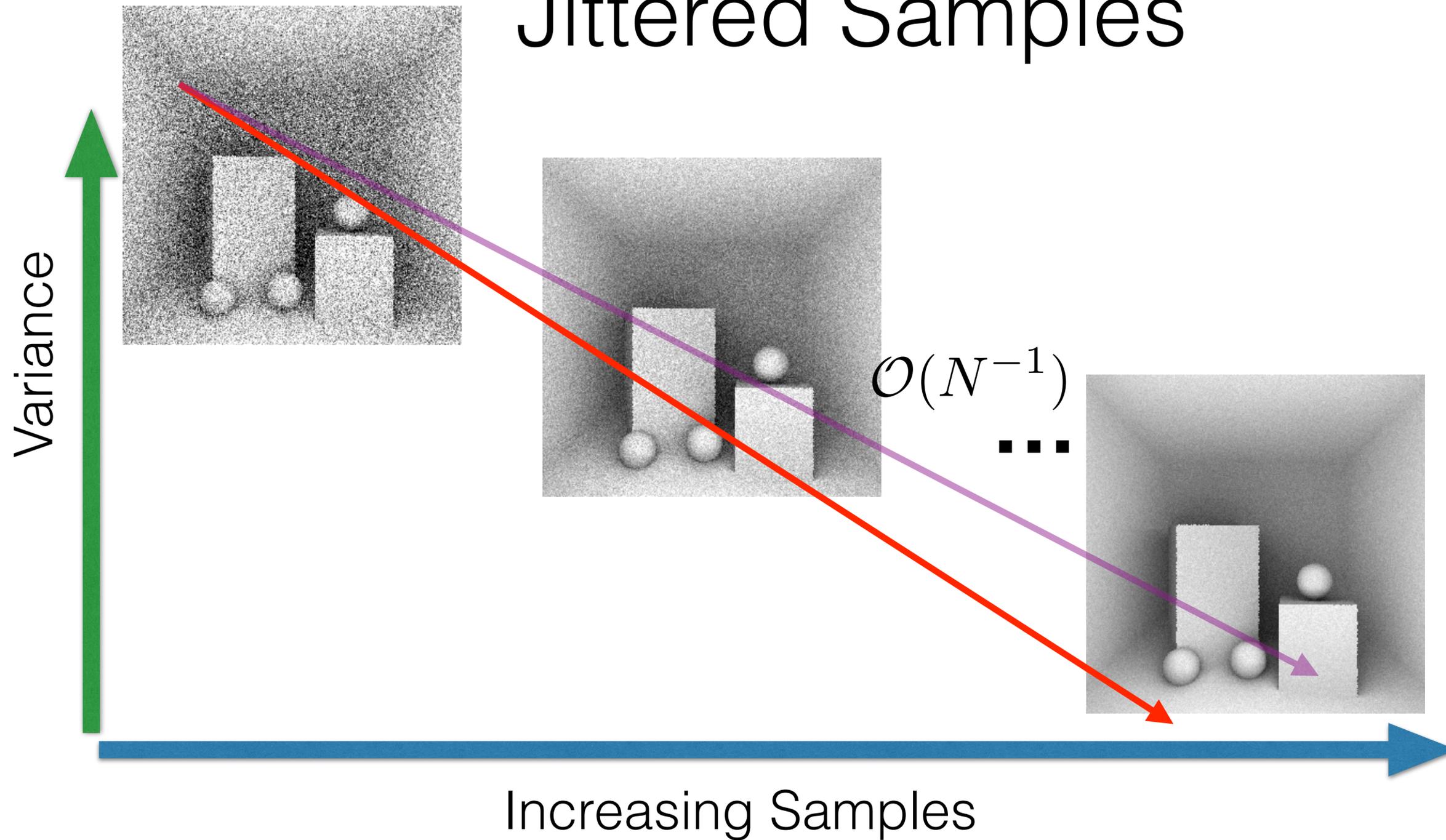
# Convergence rate for Random Samples



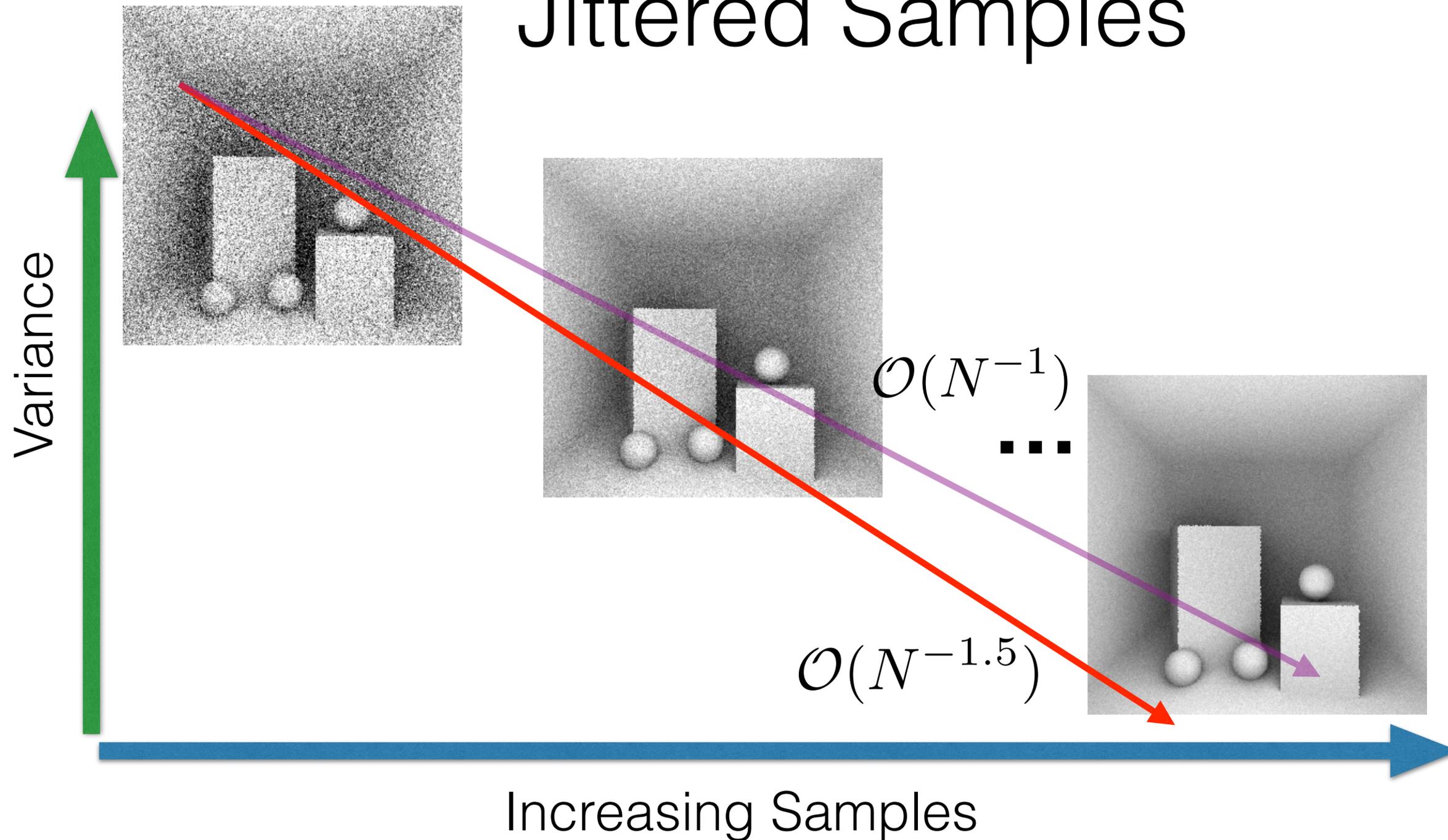
# Convergence rate for Random Samples



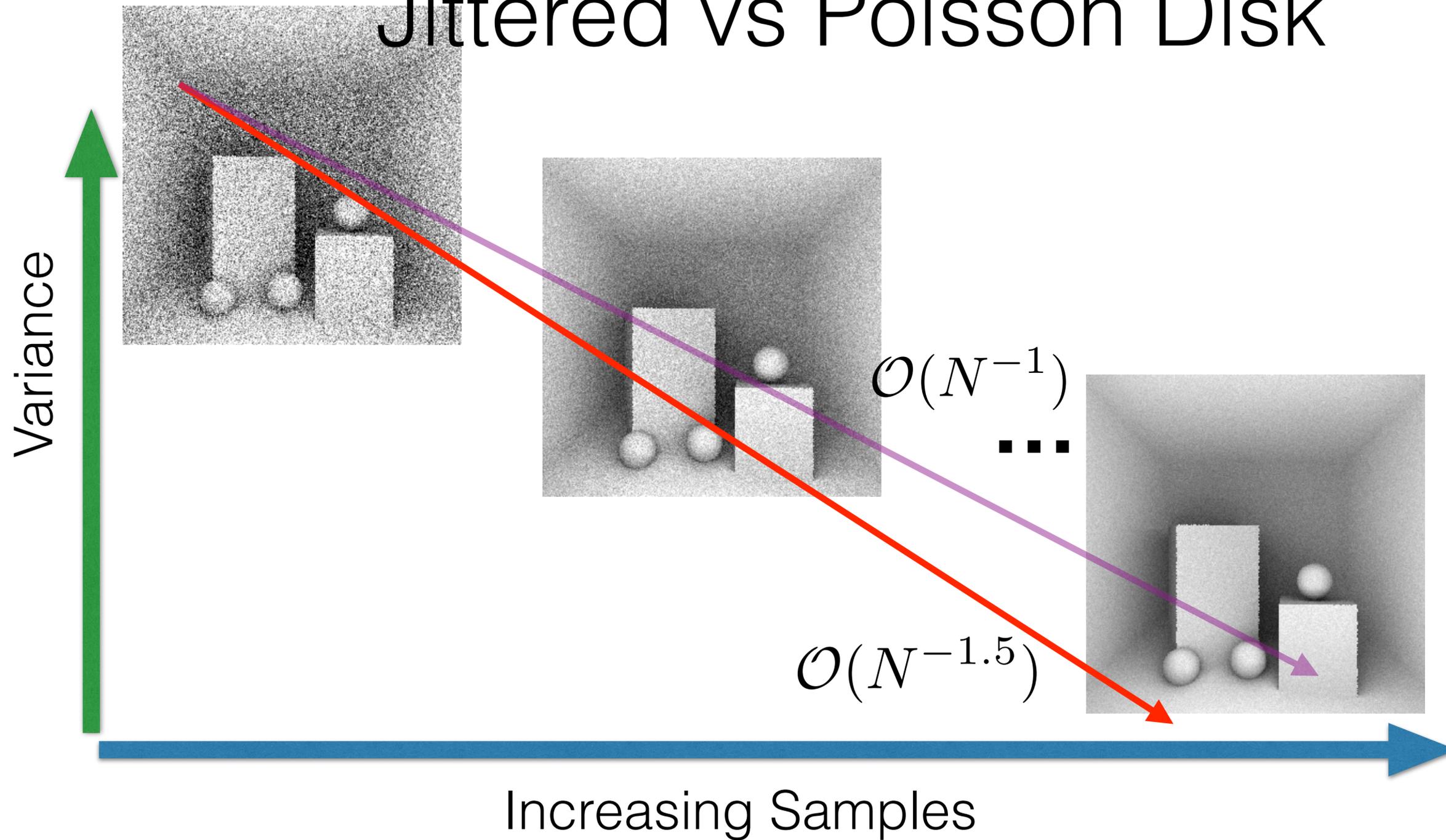
# Convergence rate for Jittered Samples



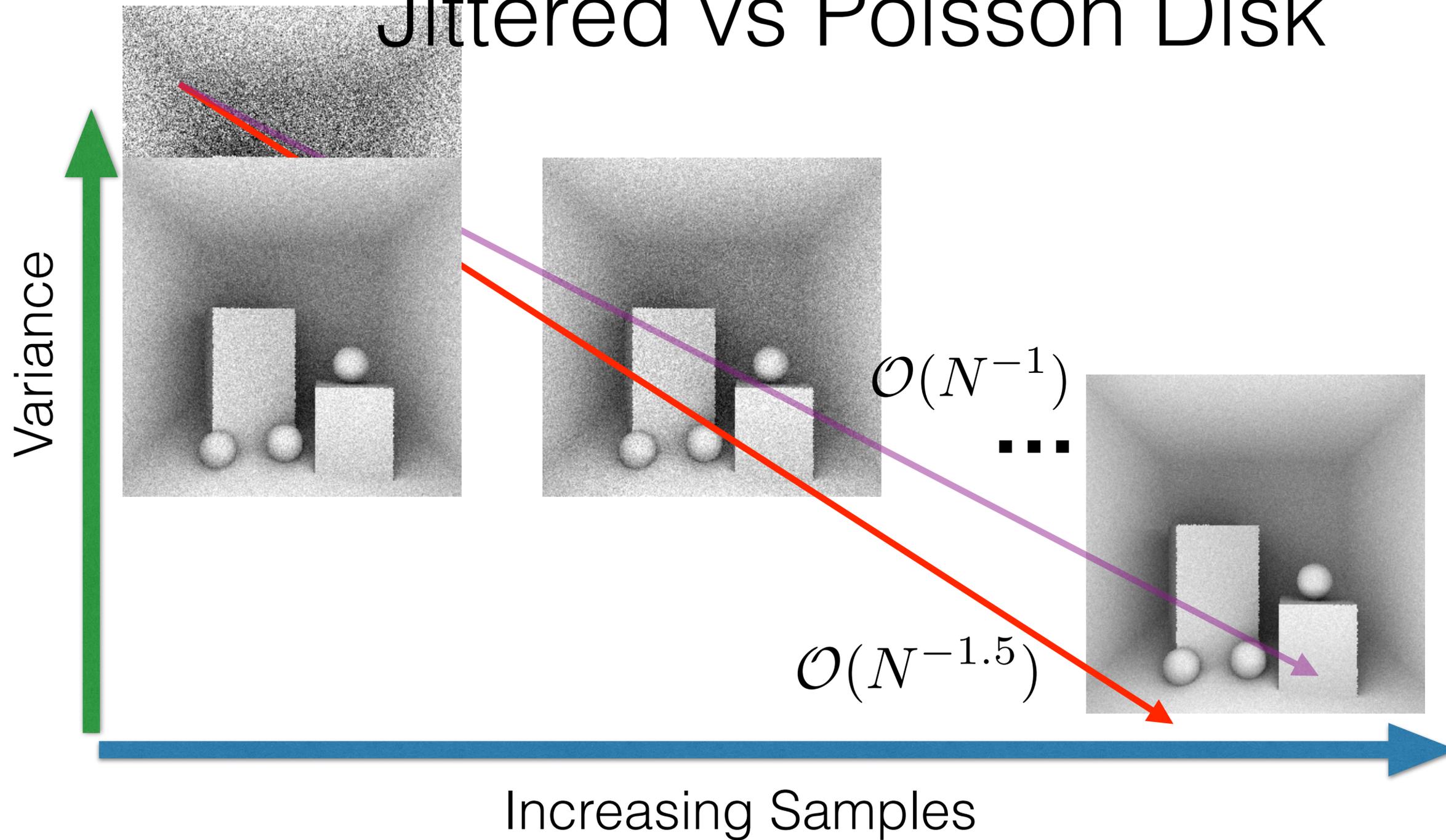
# Convergence rate for Jittered Samples



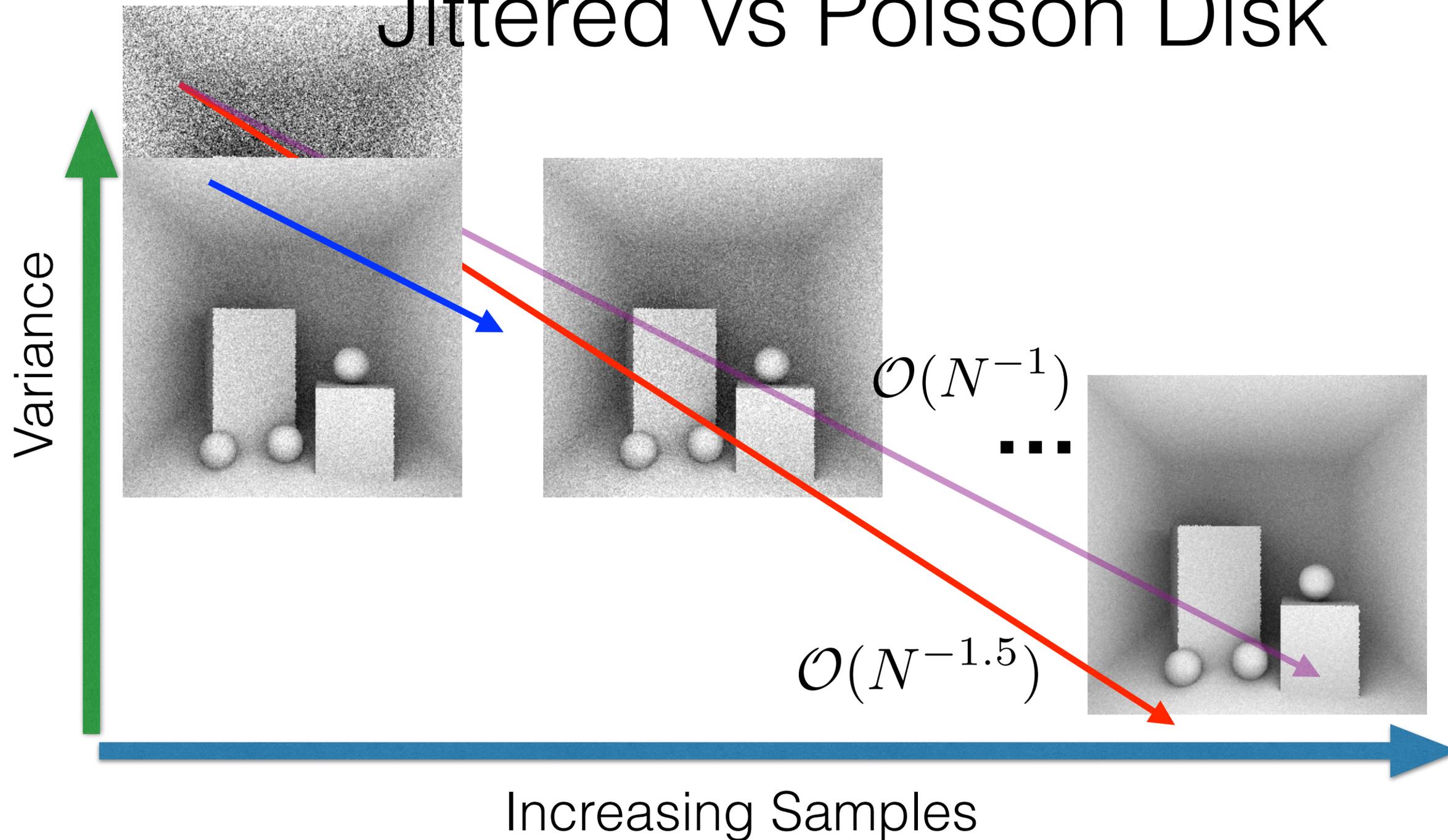
# Convergence rate Jittered vs Poisson Disk



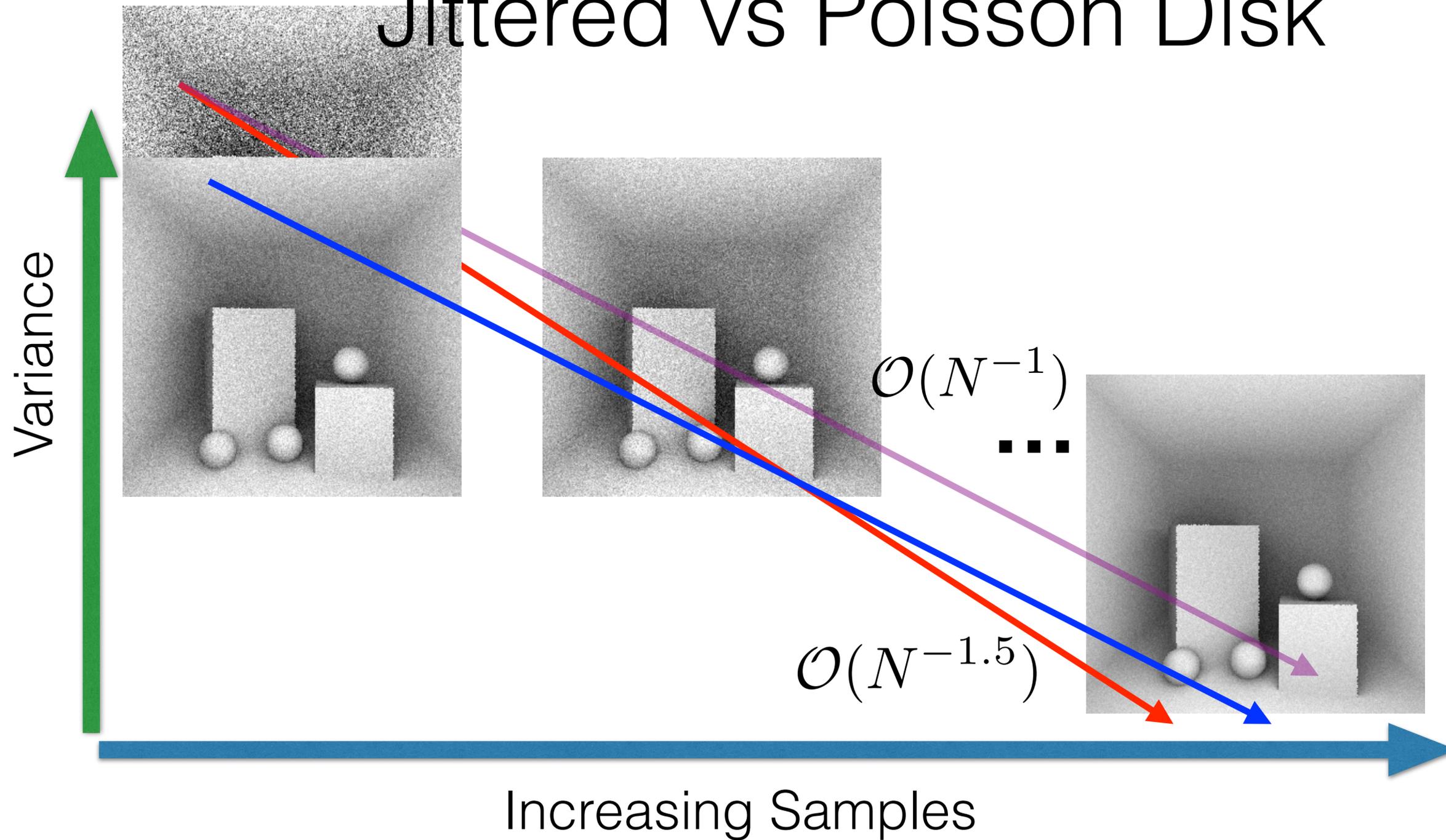
# Convergence rate Jittered vs Poisson Disk



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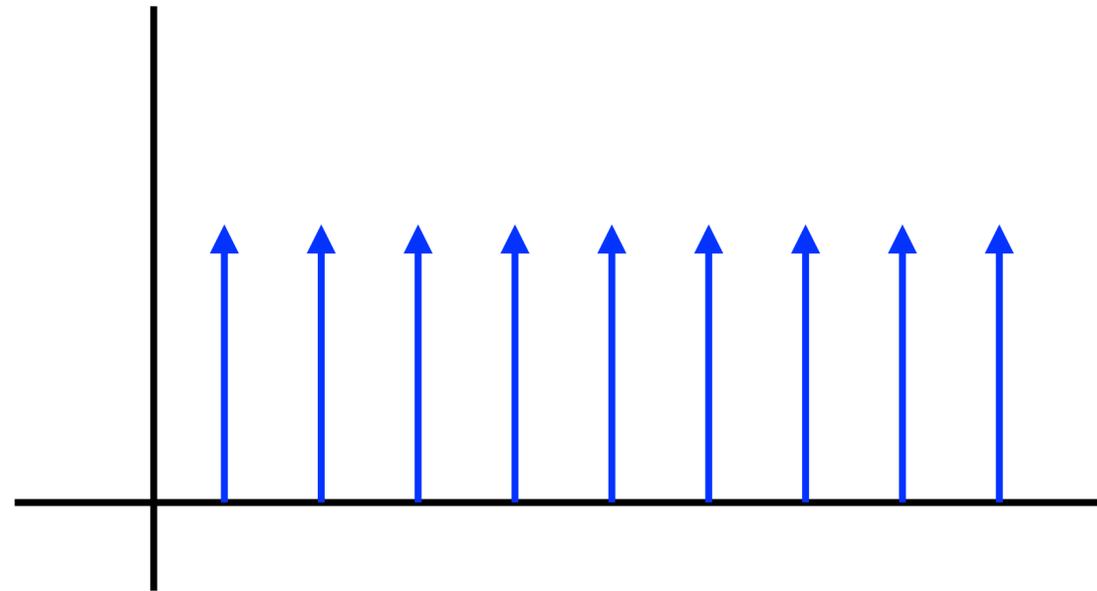
# Convergence rate Jittered vs Poisson Disk



# Samples and function in Fourier Domain

Spatial Domain

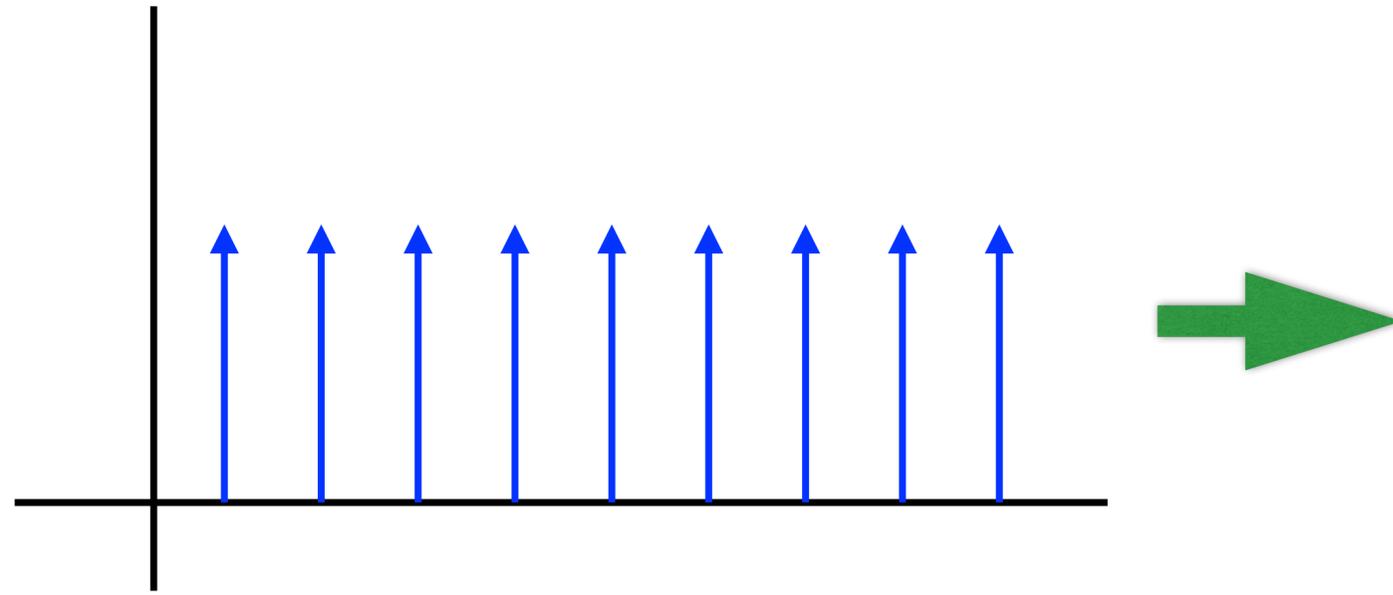
Fourier Domain



# Samples and function in Fourier Domain

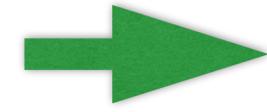
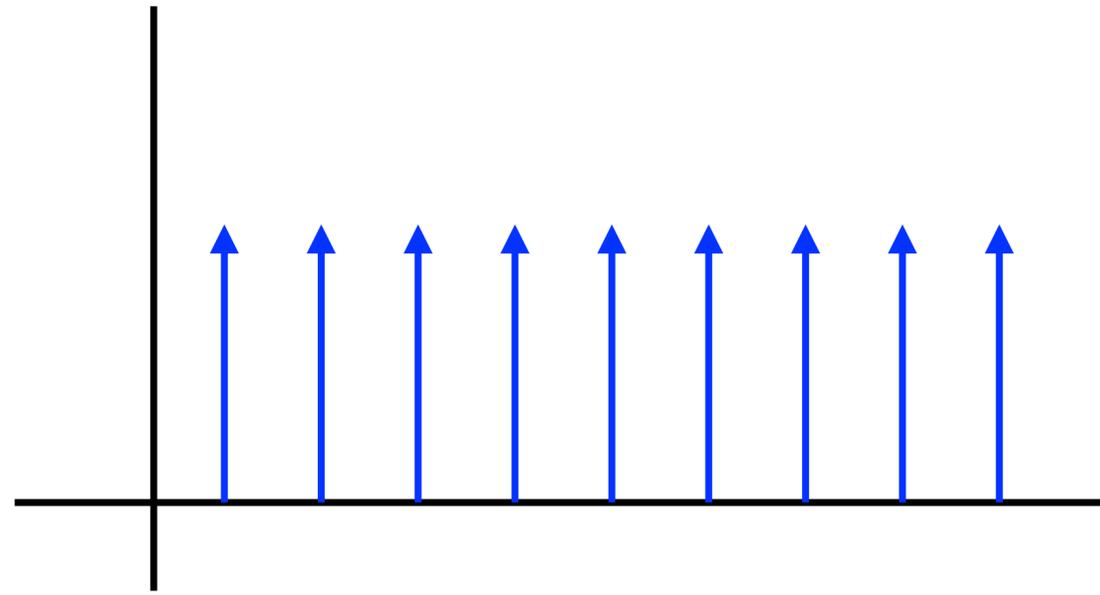
Spatial Domain

Fourier Domain

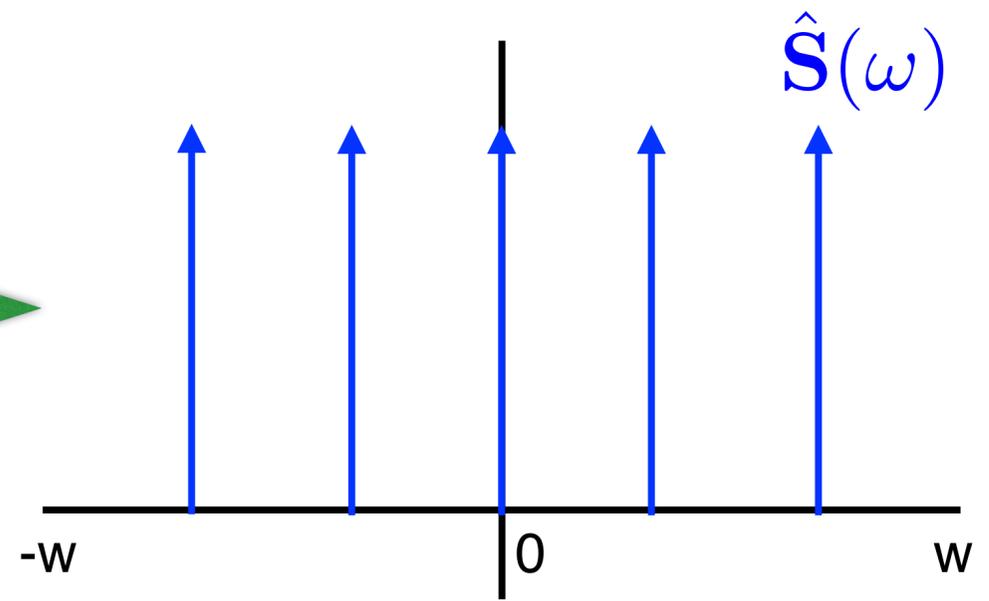


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Spatial Domain

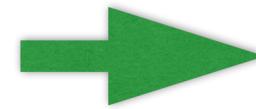
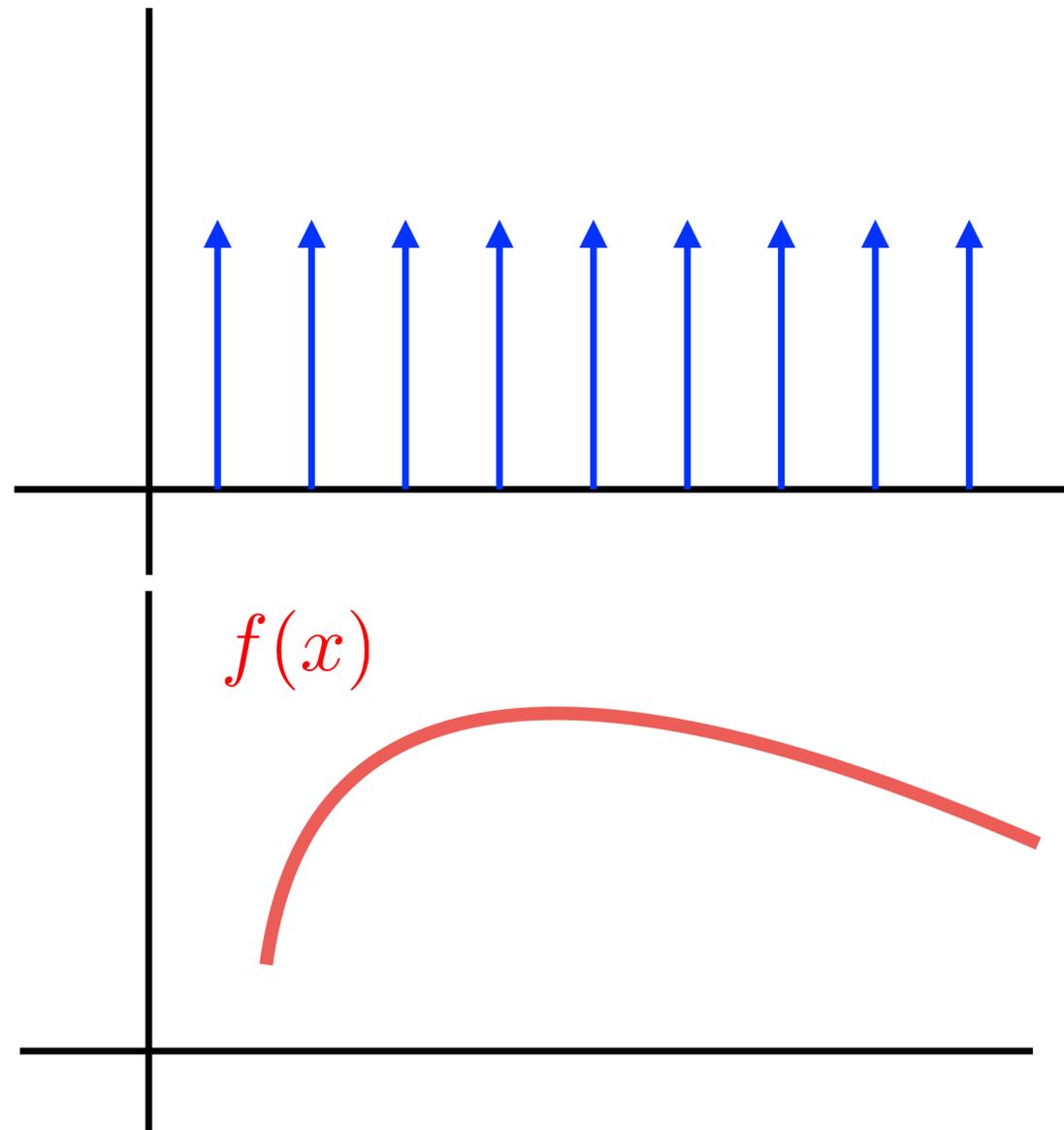


Fourier Domain

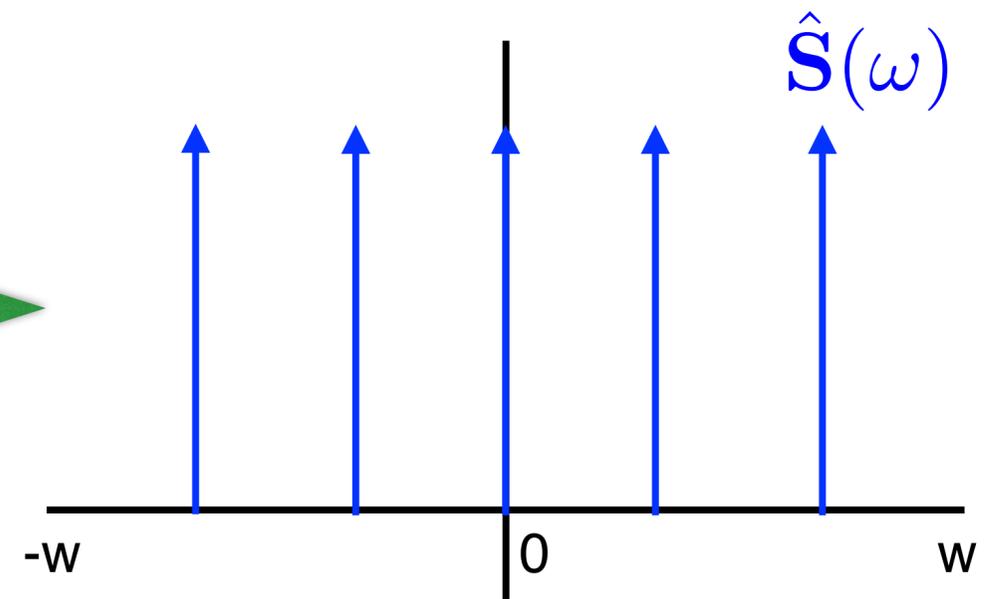


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Spatial Domain

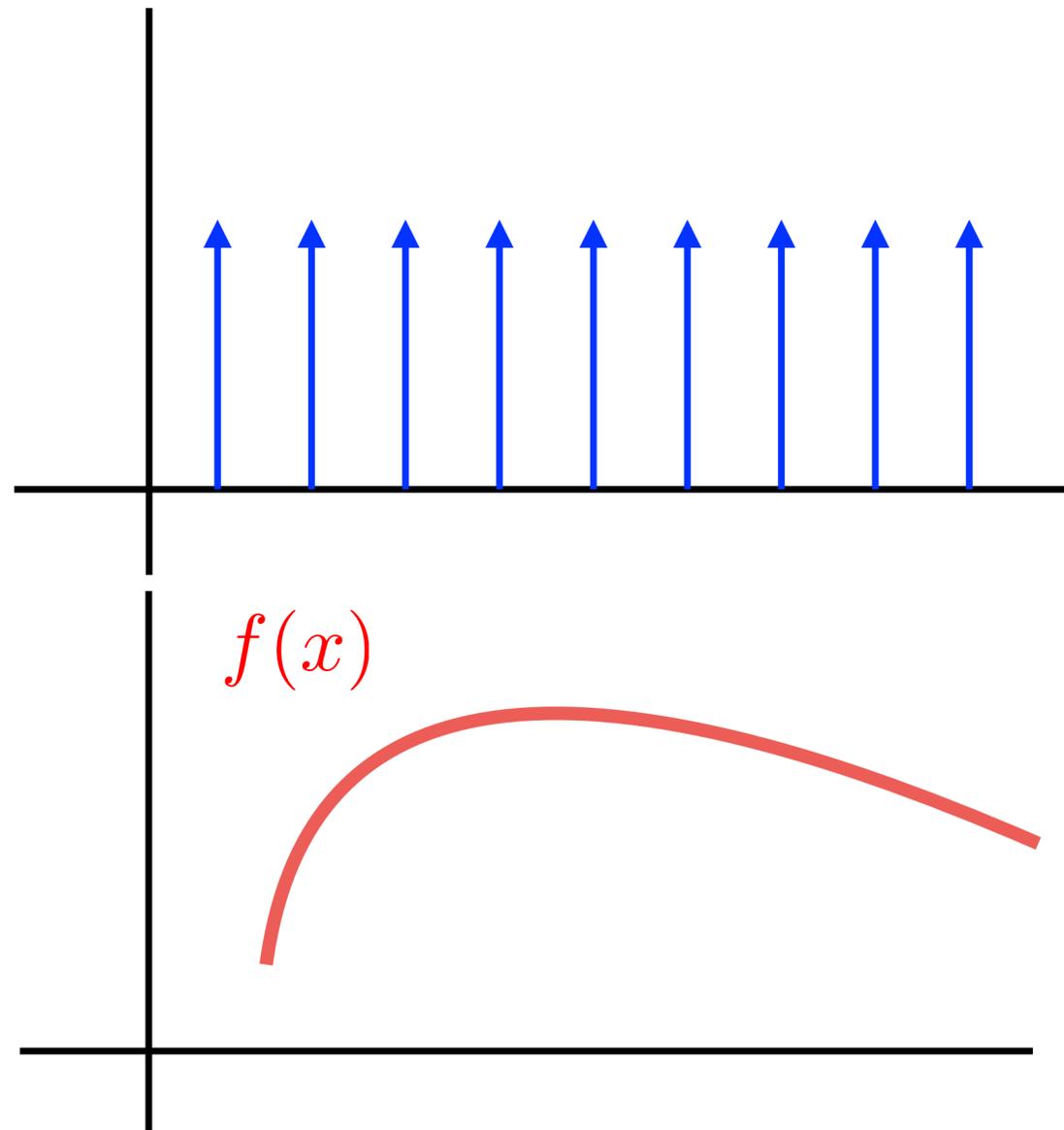


Fourier Domain

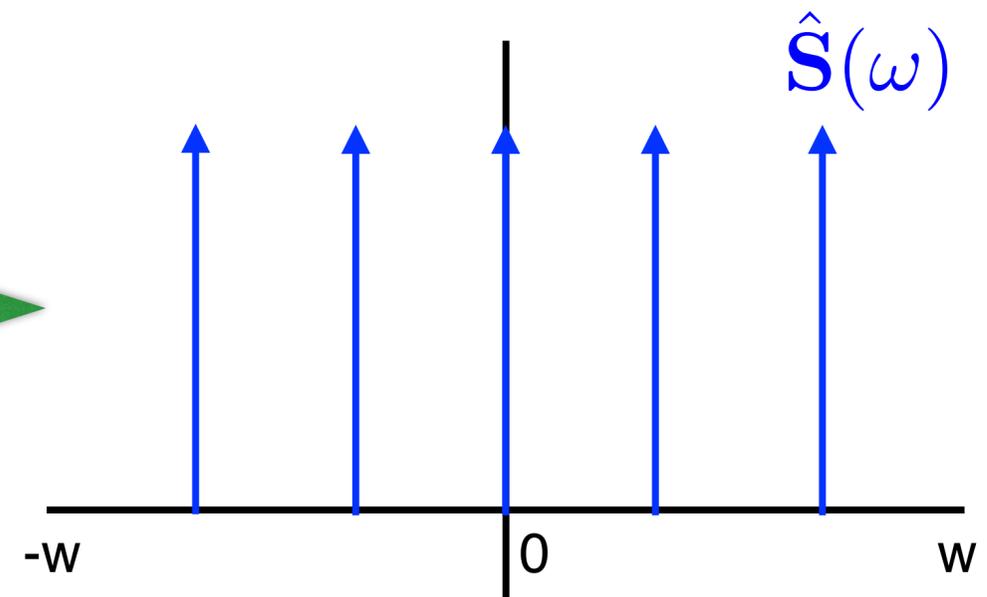


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Spatial Domain



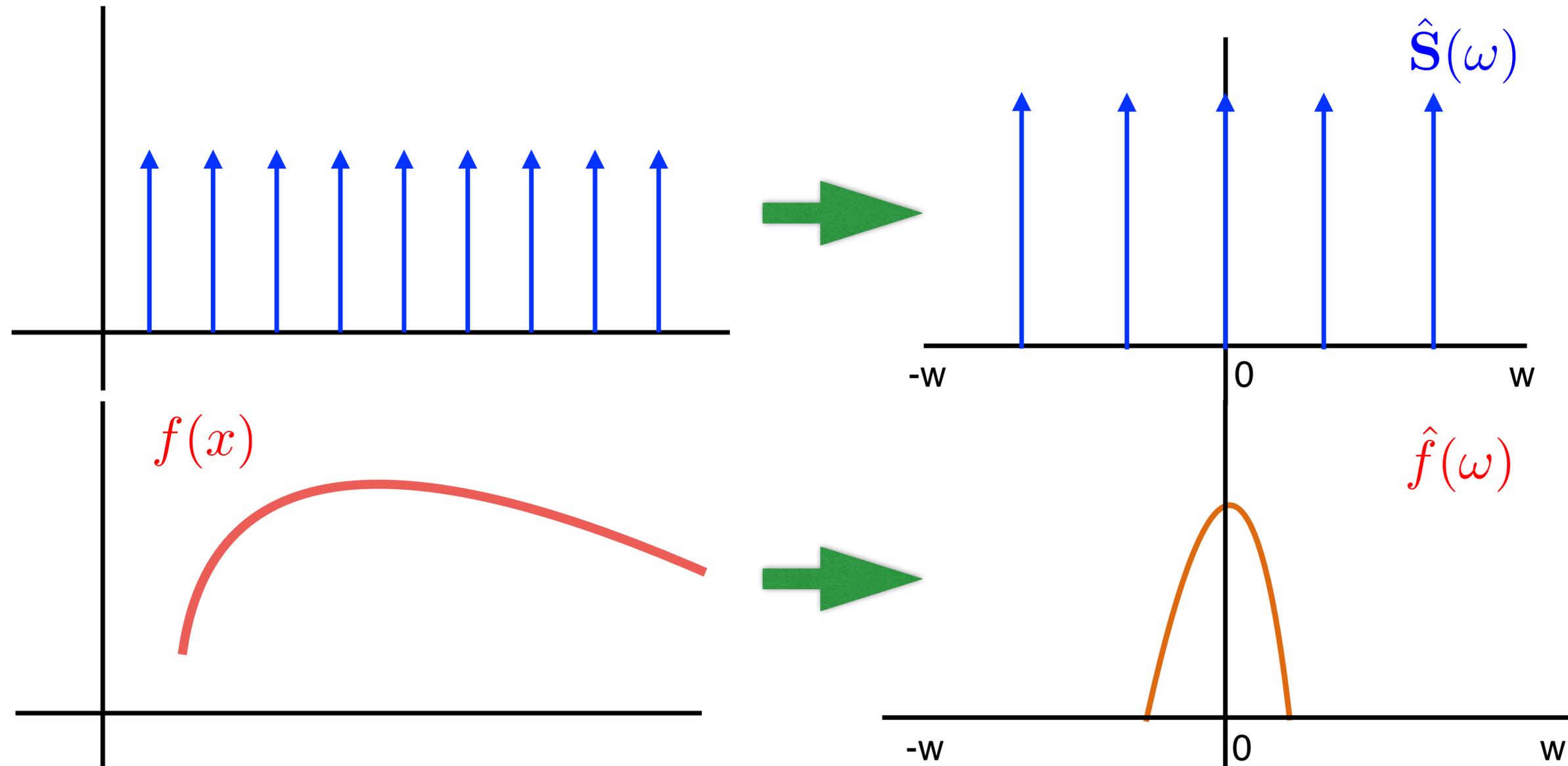
Fourier Domain



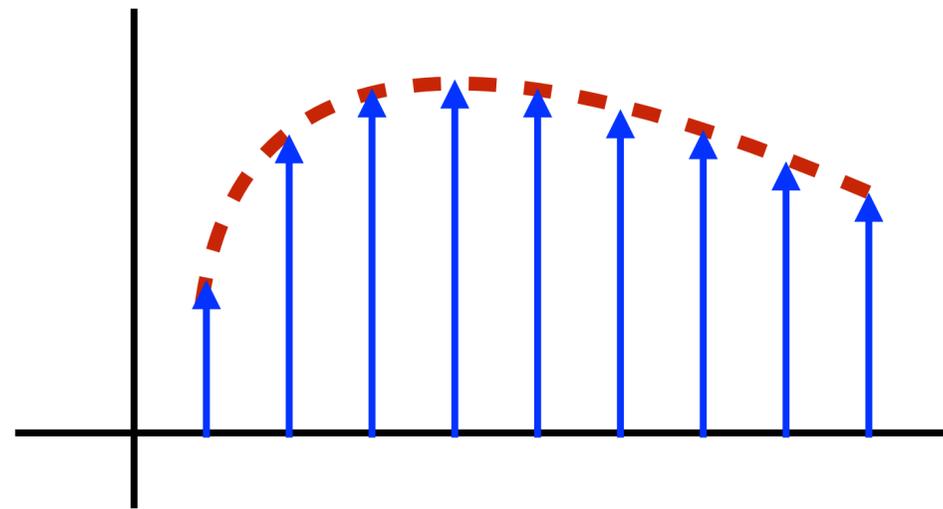
# Samples and function in Fourier Domain

Spatial Domain

Fourier Domain

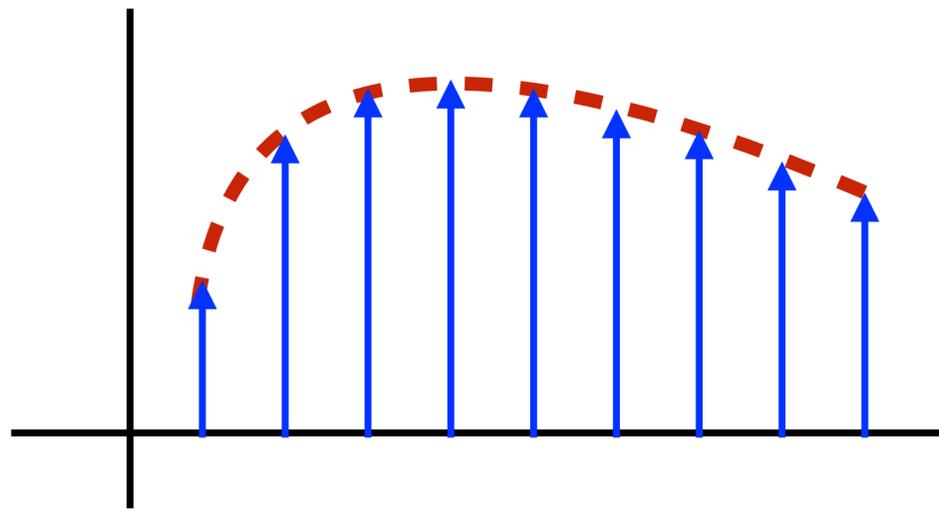


# Sampling in Primal Domain is Convolution in Fourier Domain



$$f(x) \mathbf{S}(x)$$

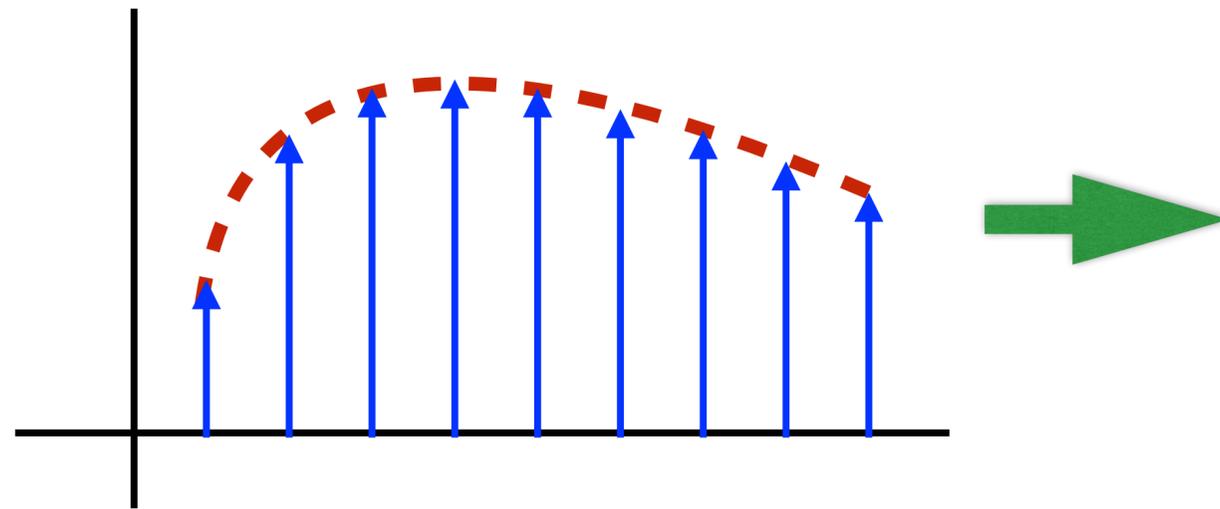
# Sampling in Primal Domain is Convolution in Fourier Domain



$$f(x) \mathbf{S}(x)$$

Fredo Durand [2011]

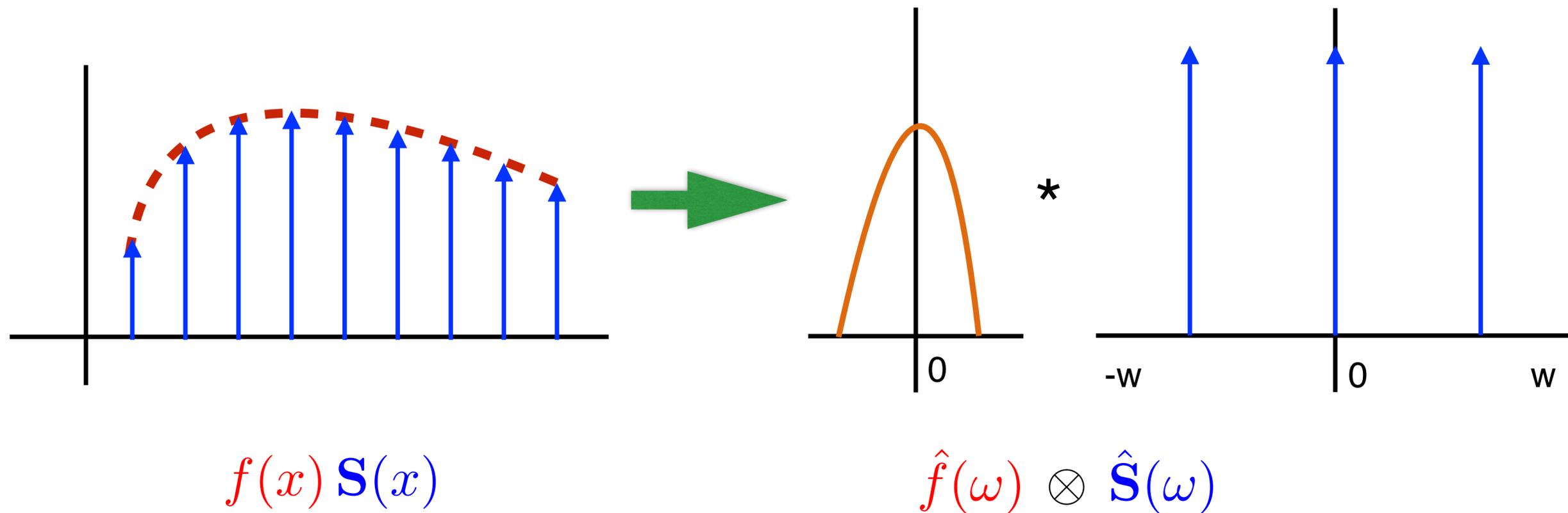
# Sampling in Primal Domain is Convolution in Fourier Domain



$$f(x) \mathbf{S}(x)$$

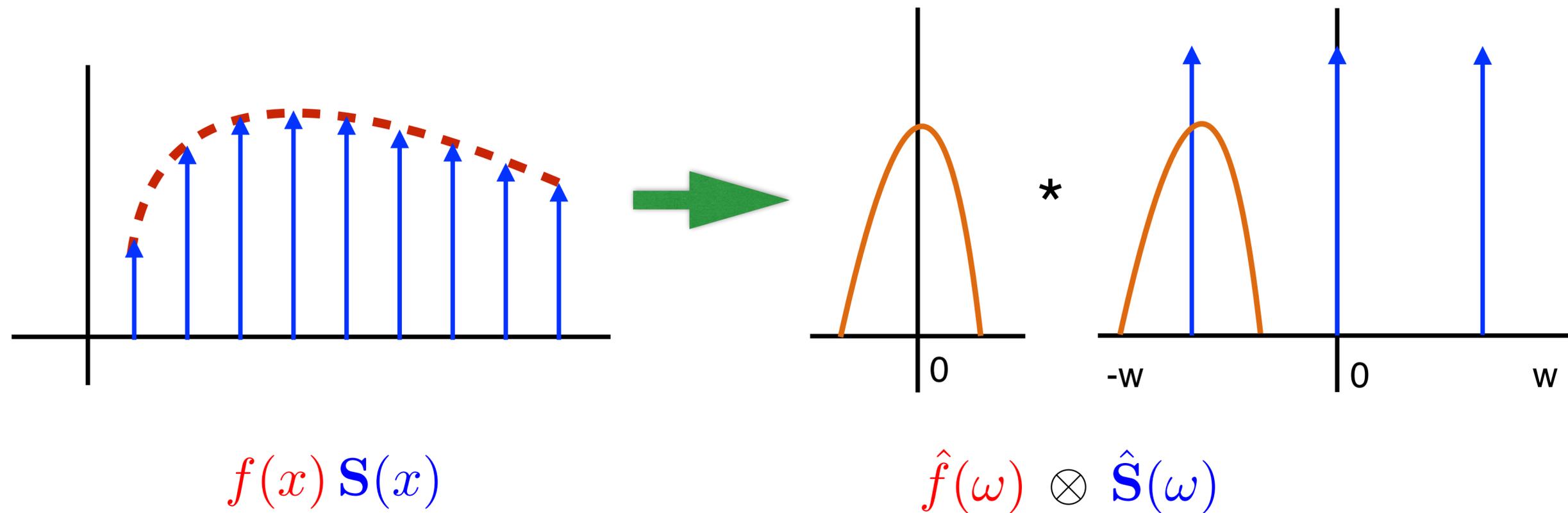
Fredo Durand [2011]

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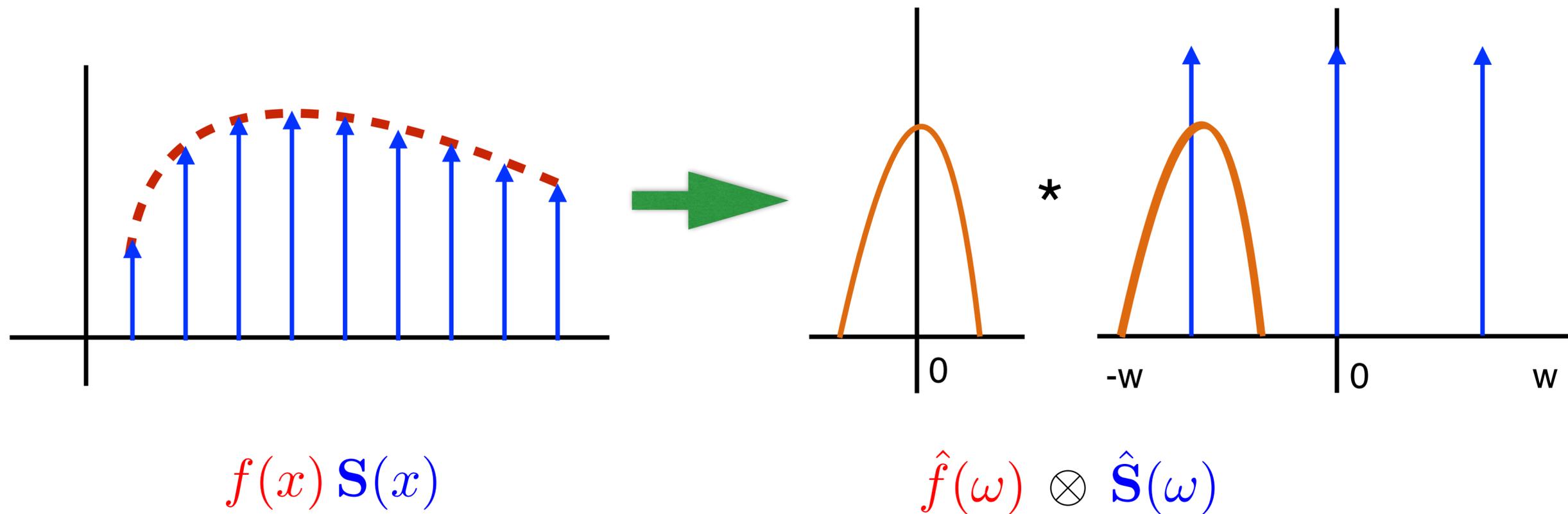
Fredo Durand [2011]

# Sampling in Primal Domain is Convolution in Fourier Domain



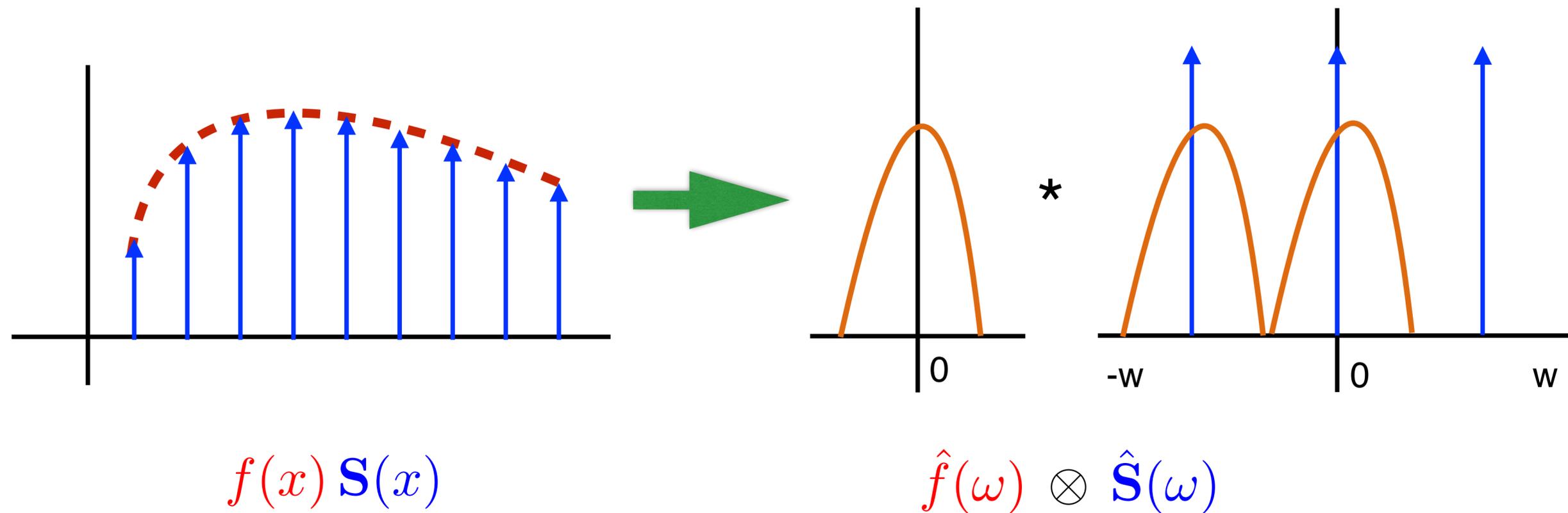
Fredo Durand [2011]

# Sampling in Primal Domain is Convolution in Fourier Domain



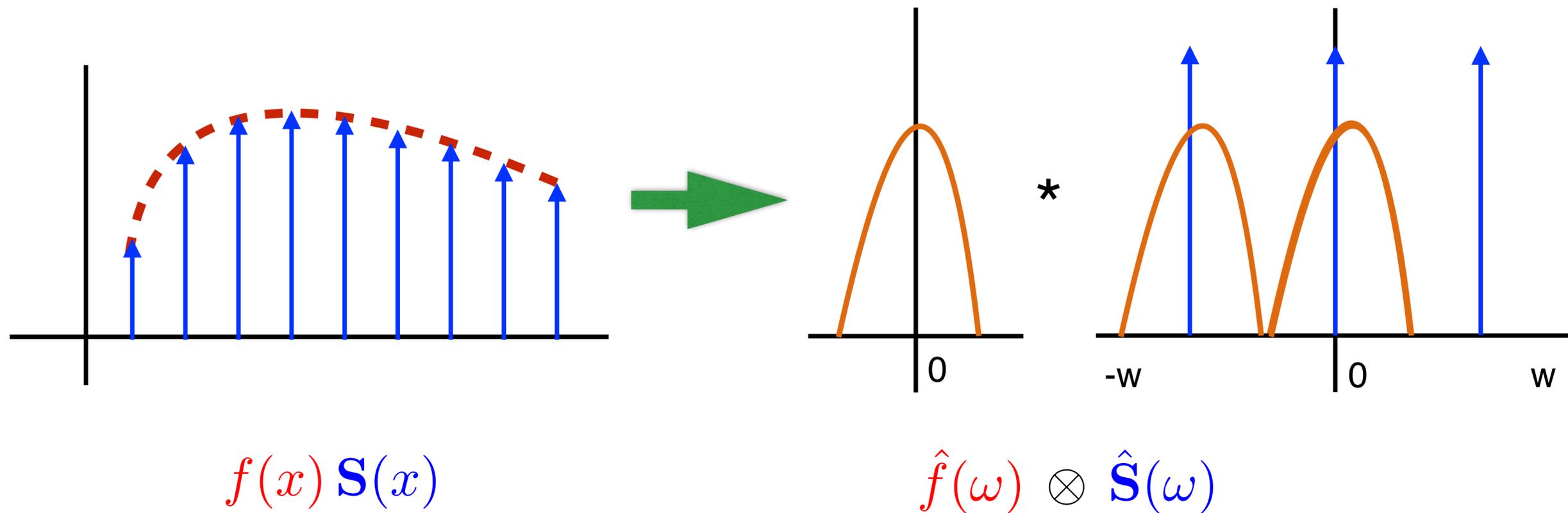
Fredo Durand [2011]

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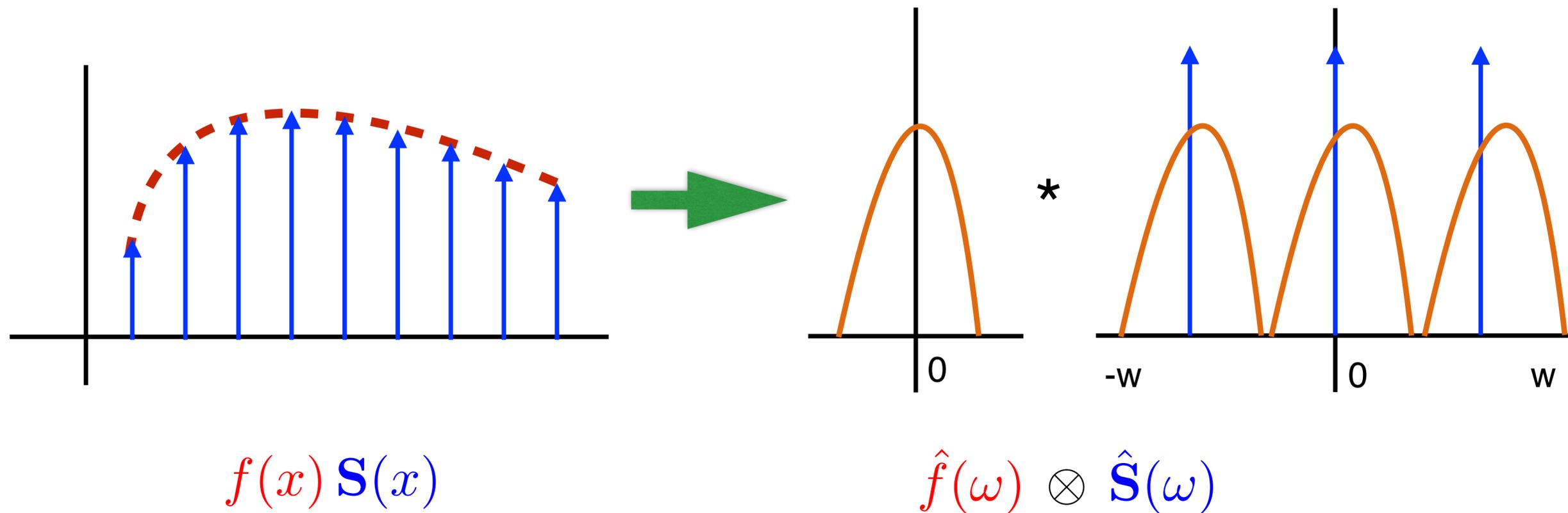
Fredo Durand [2011]

# Sampling in Primal Domain is Convolution in Fourier Domain



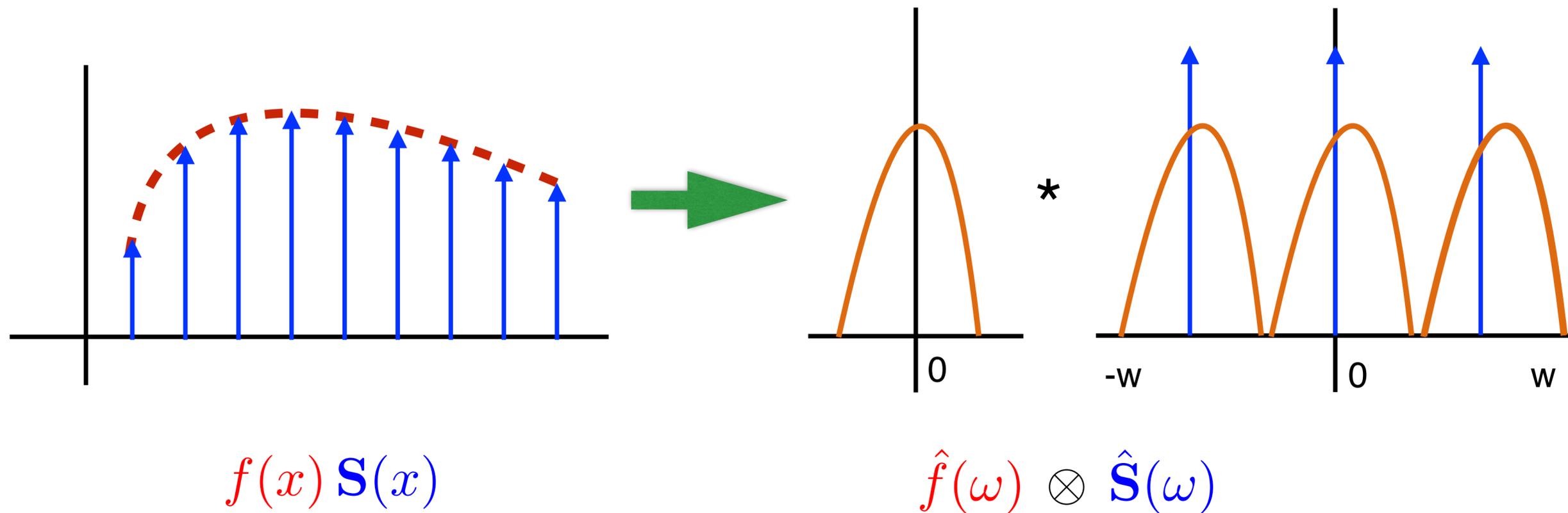
Fredo Durand [2011]

# Sampling in Primal Domain is Convolution in Fourier Domain



Fredo Durand [2011]

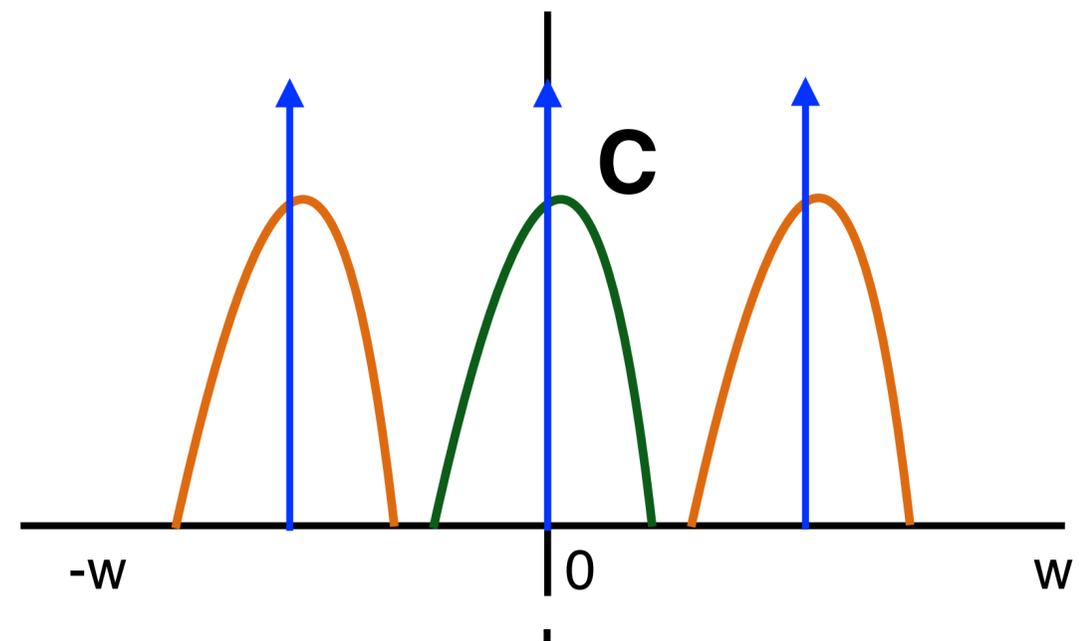
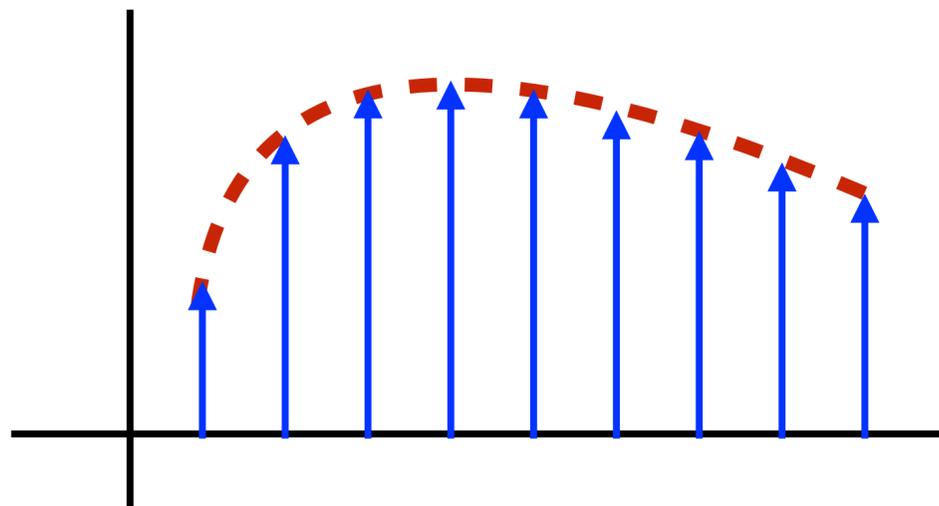
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Fredo Durand [2011]

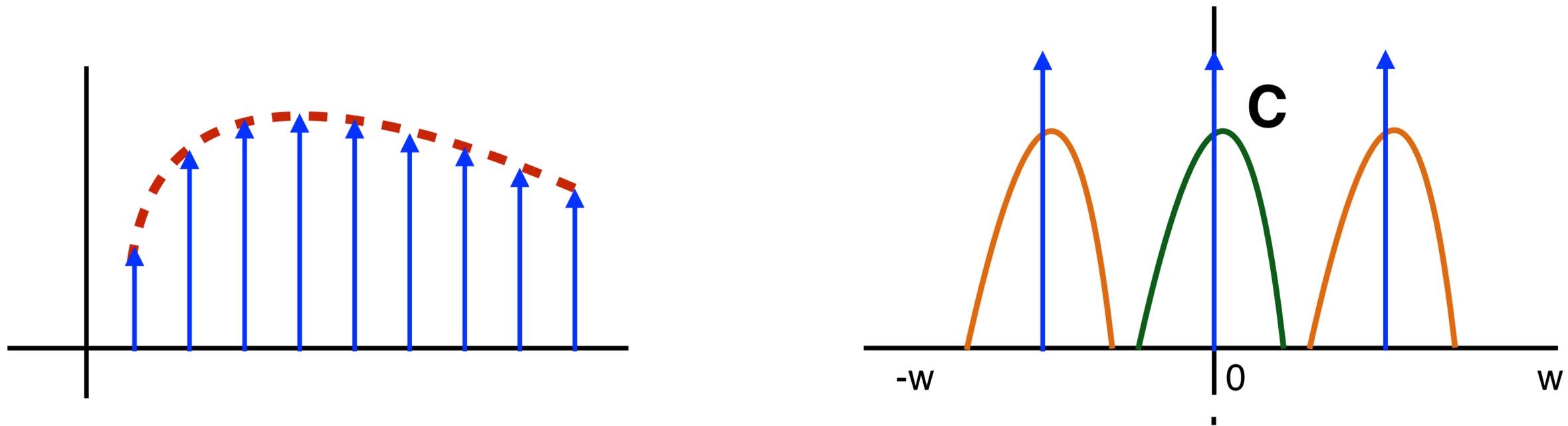
# Aliasing in Reconstruction

High Sampling Rate



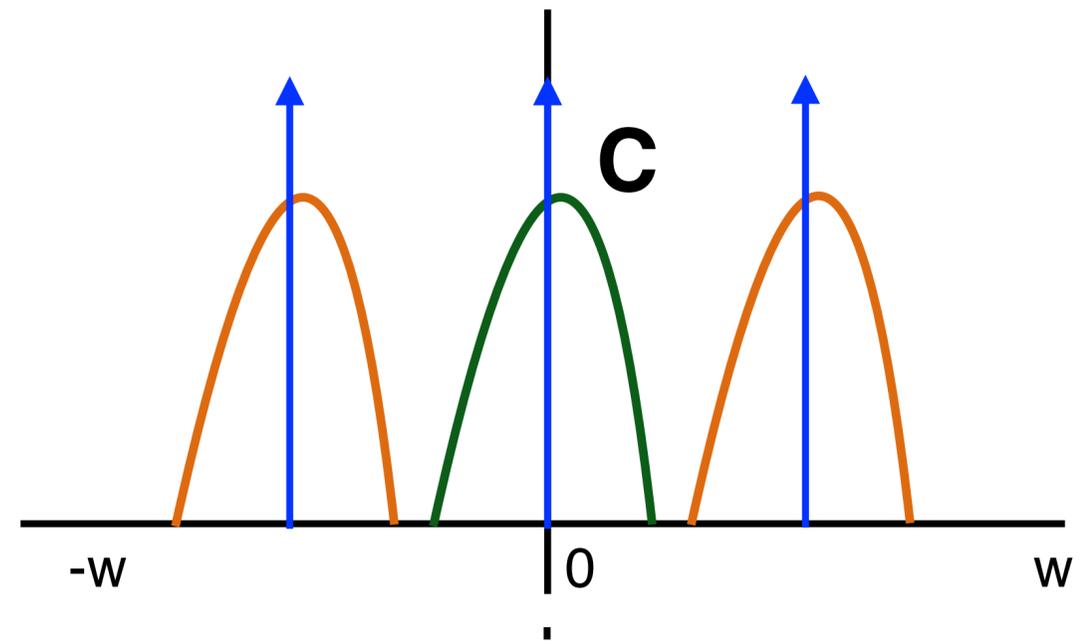
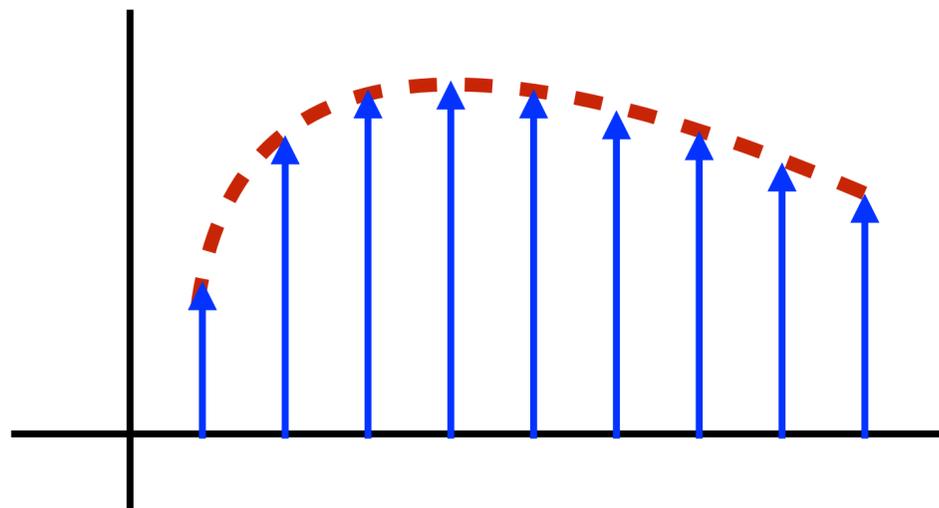
# Aliasing in Reconstruction

High Sampling Rate



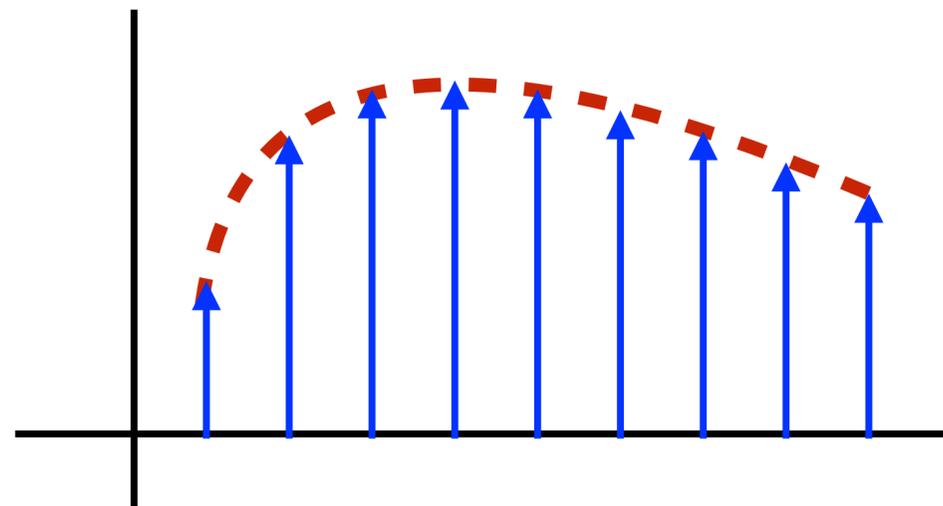
# Aliasing in Reconstruction

High Sampling Rate  
Low Sampling Rate

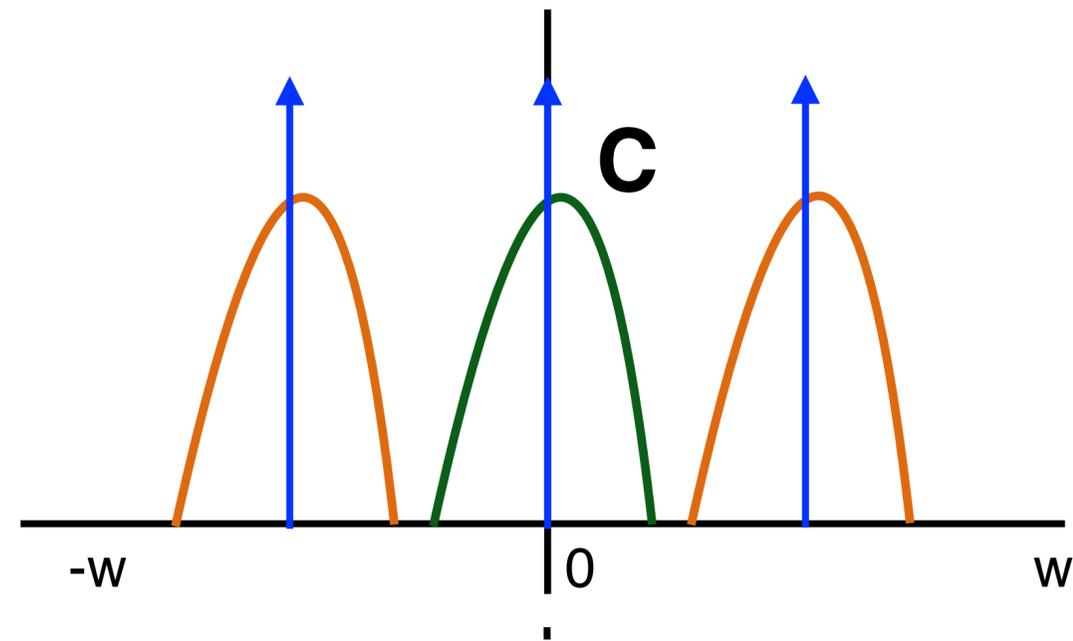
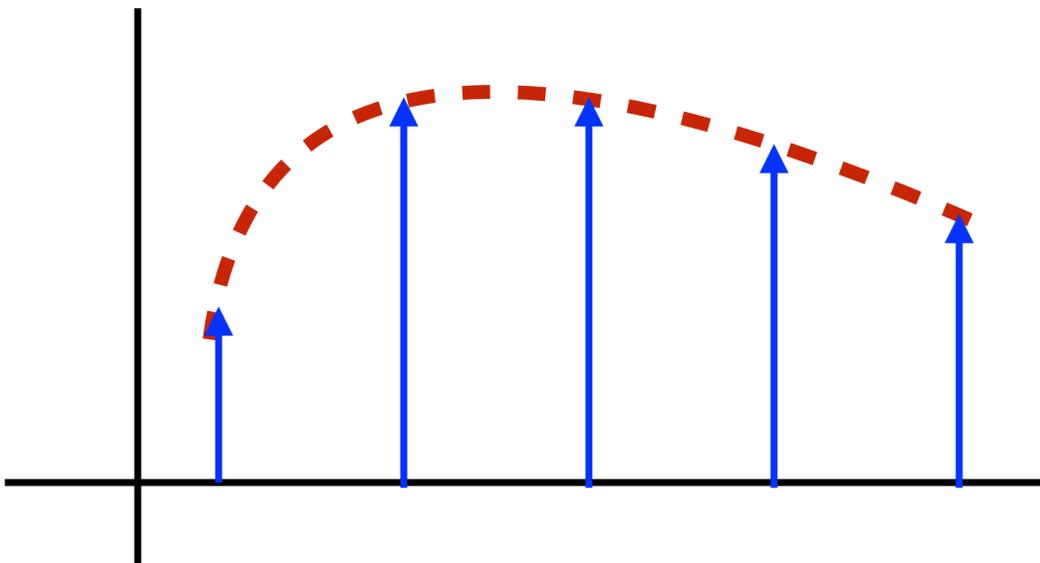


# Aliasing in Reconstruction

High Sampling Rate

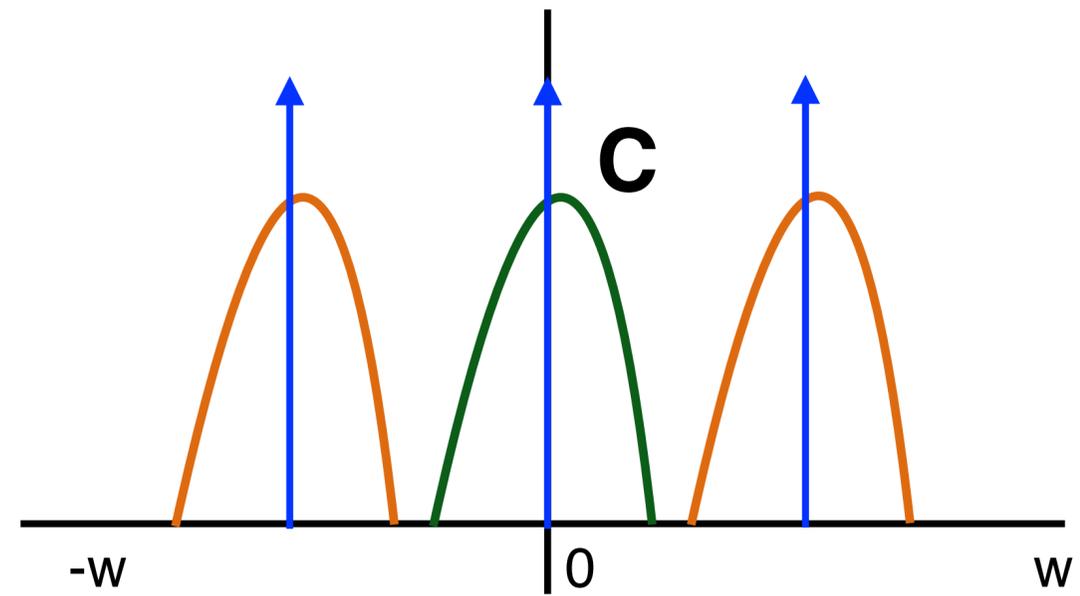
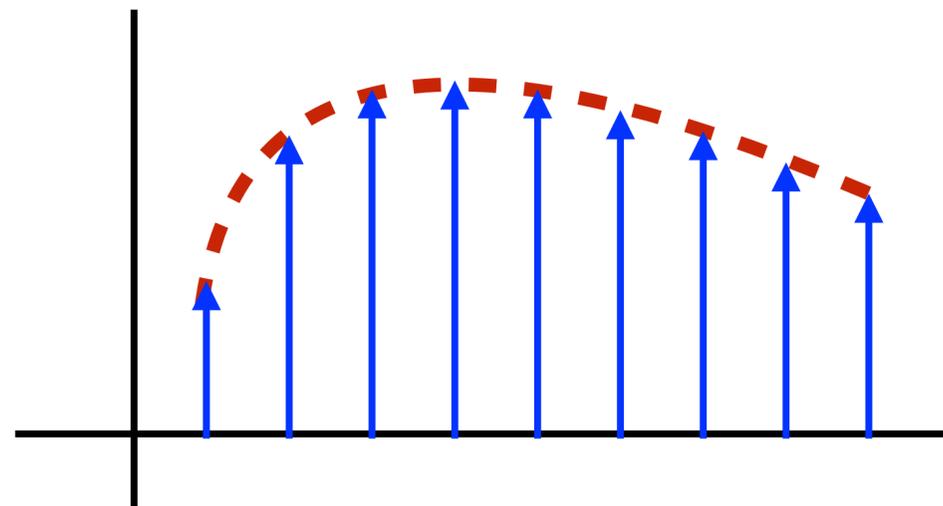


Low Sampling Rate

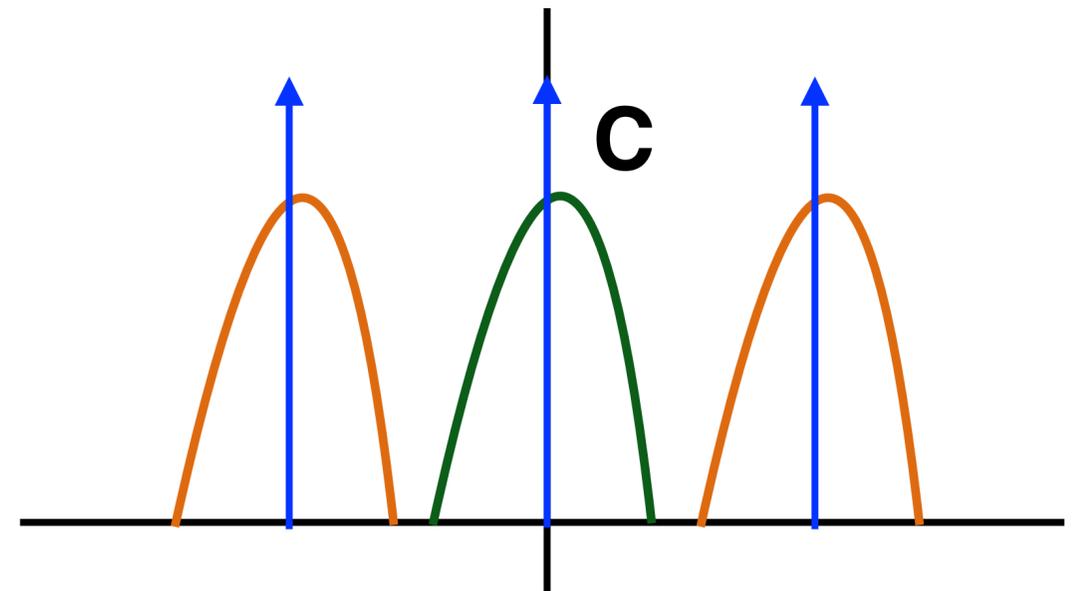
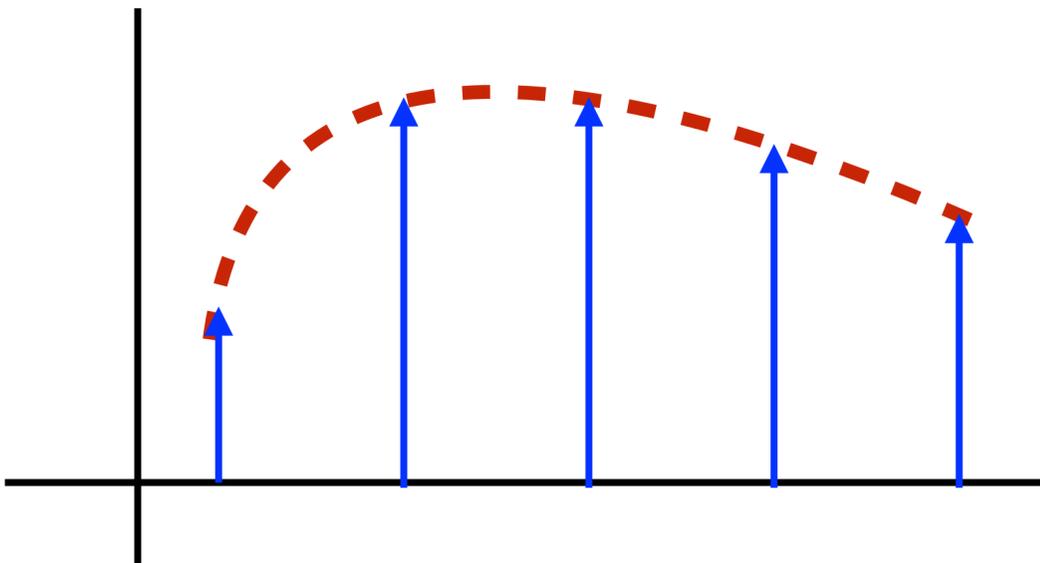


# Aliasing in Reconstruction

High Sampling Rate

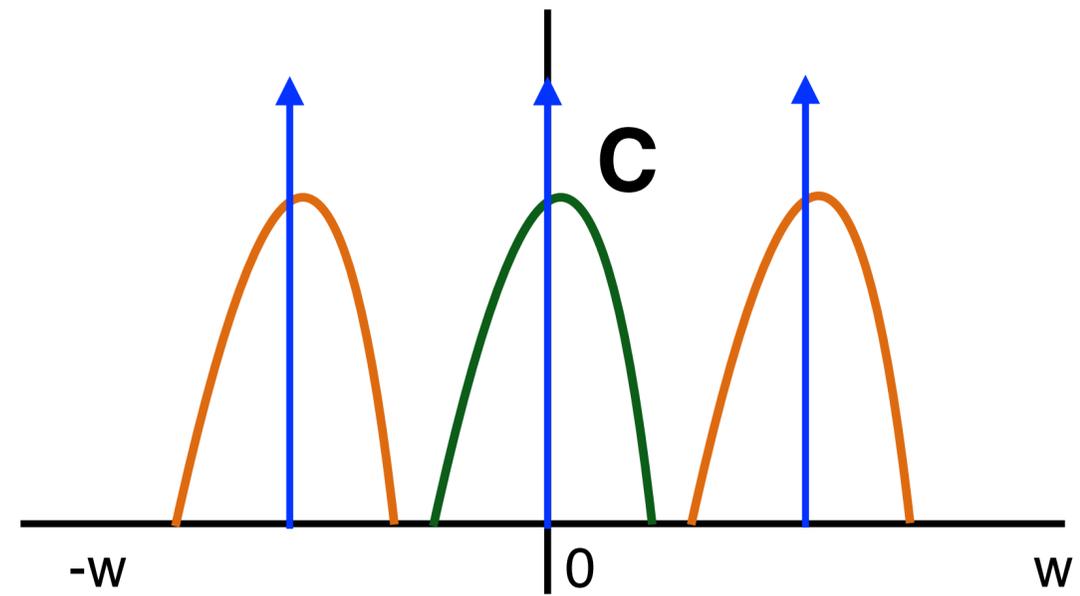
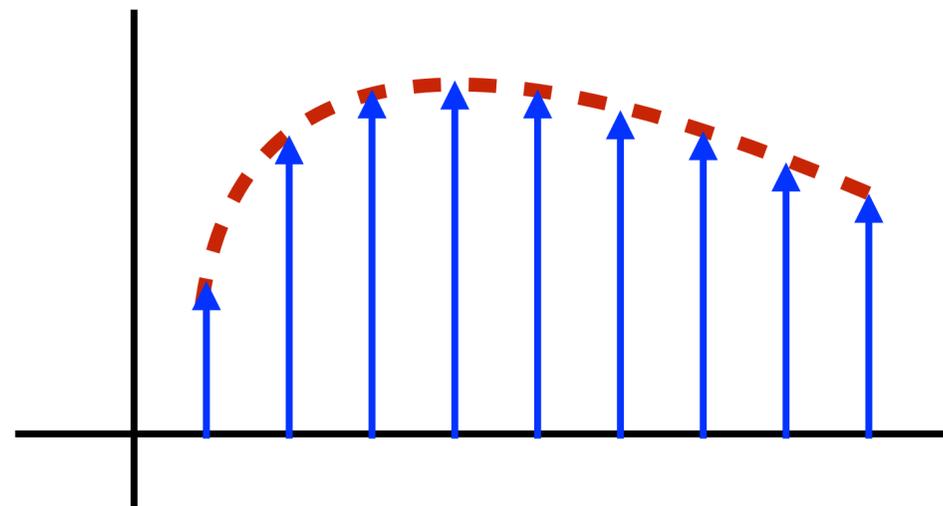


Low Sampling Rate

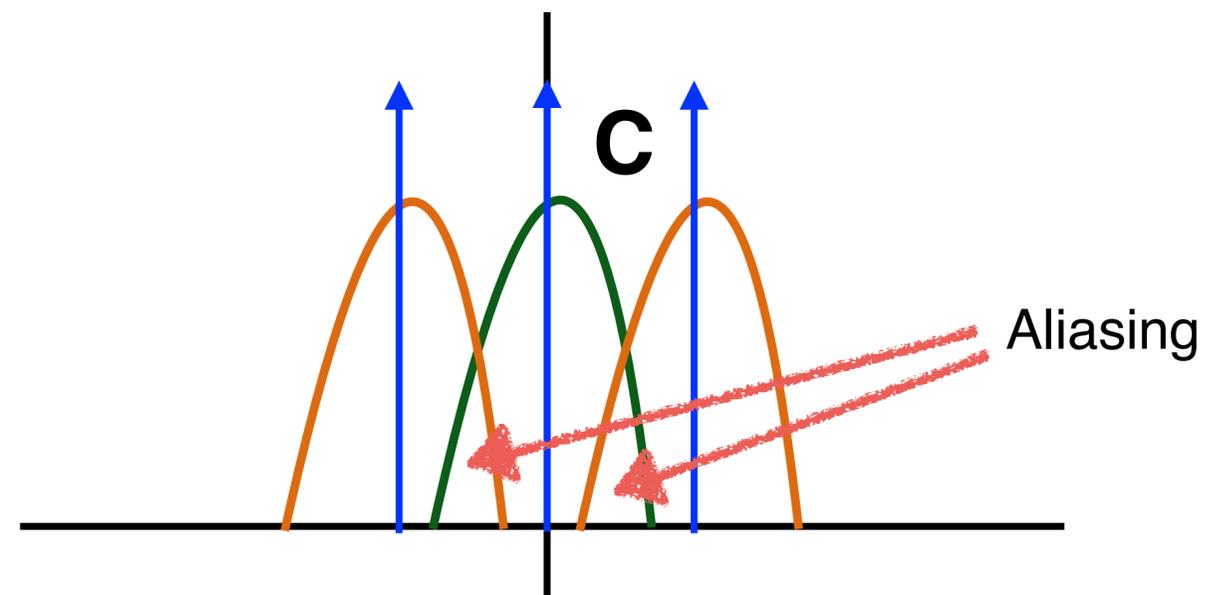
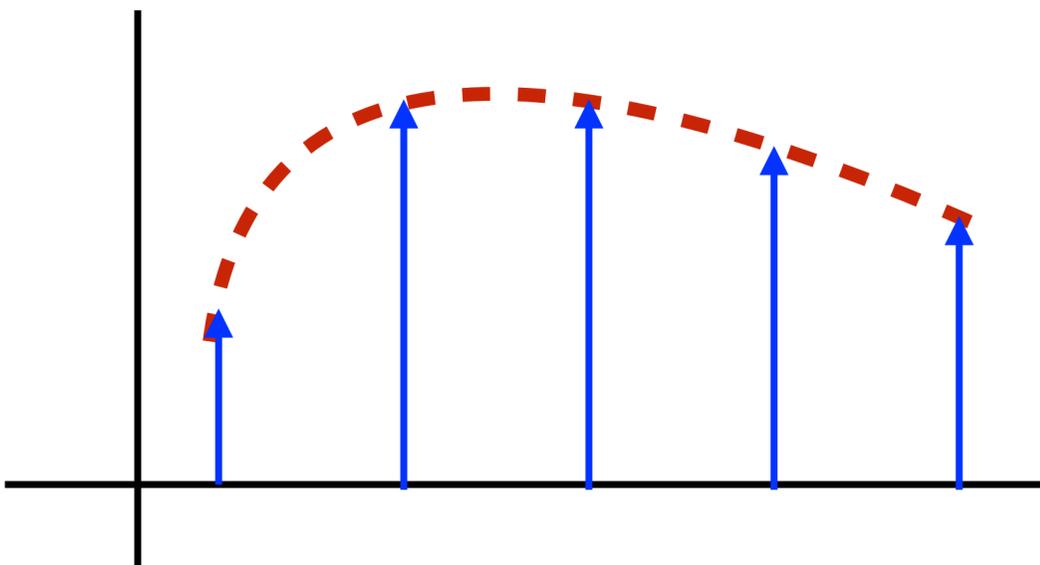


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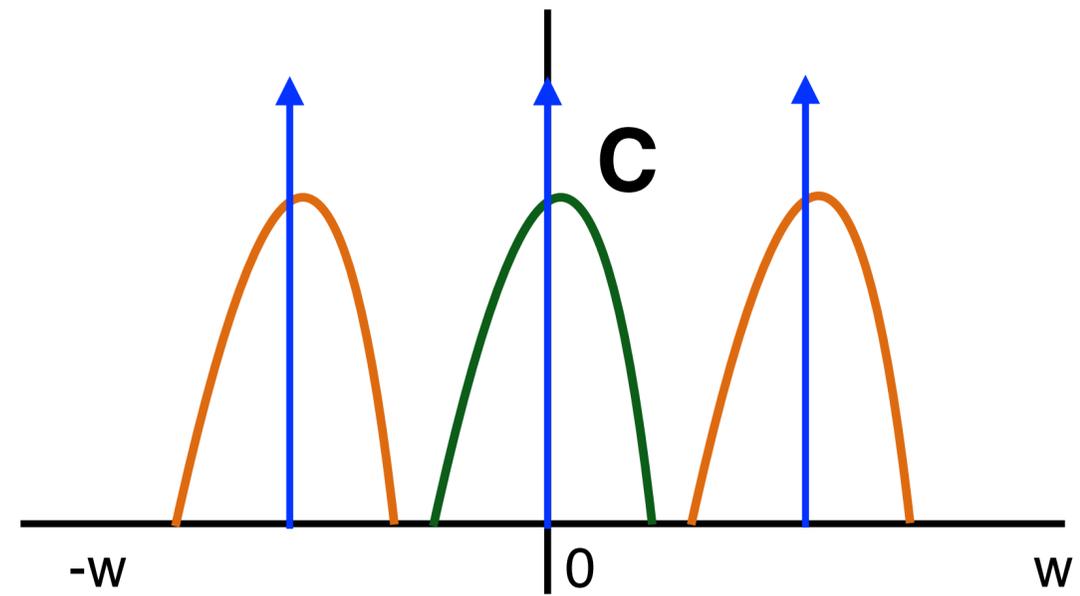
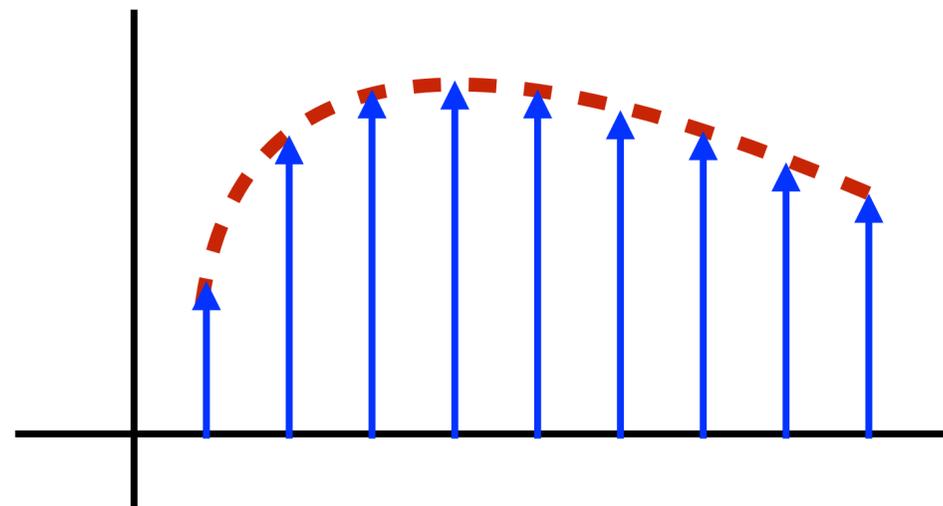


Low Sampling Rate

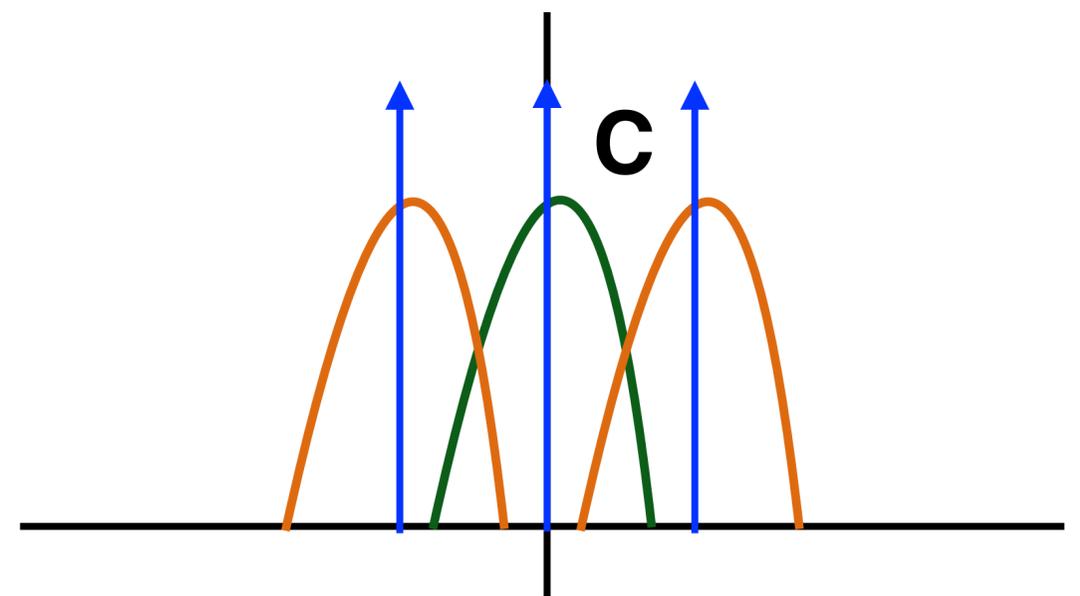
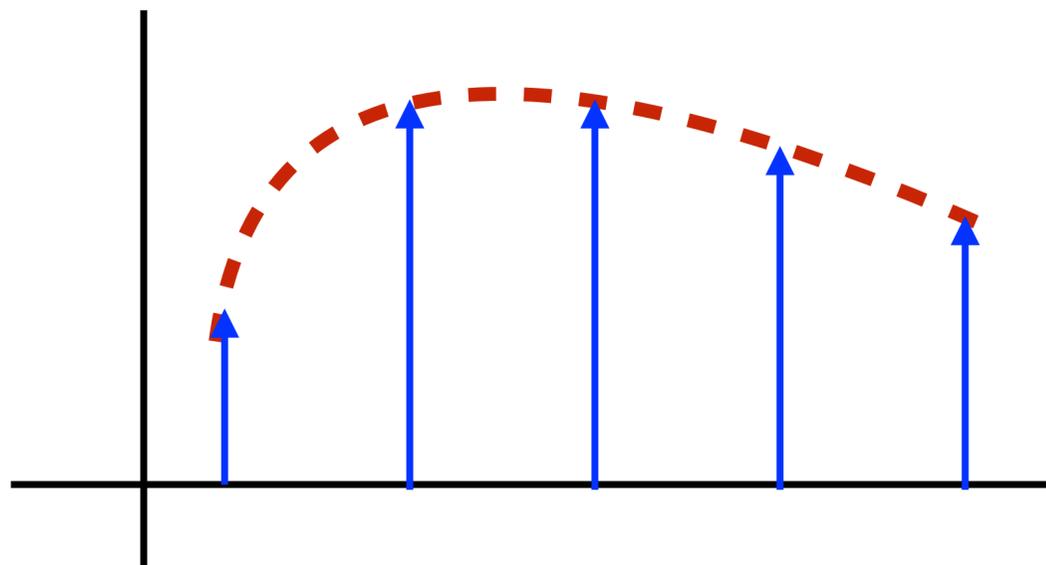


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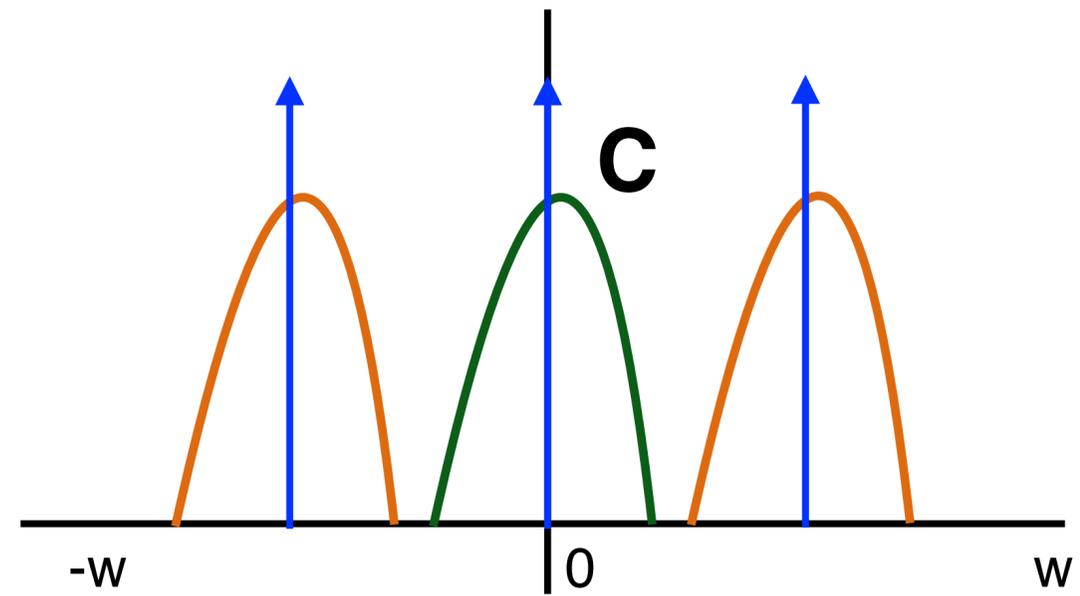
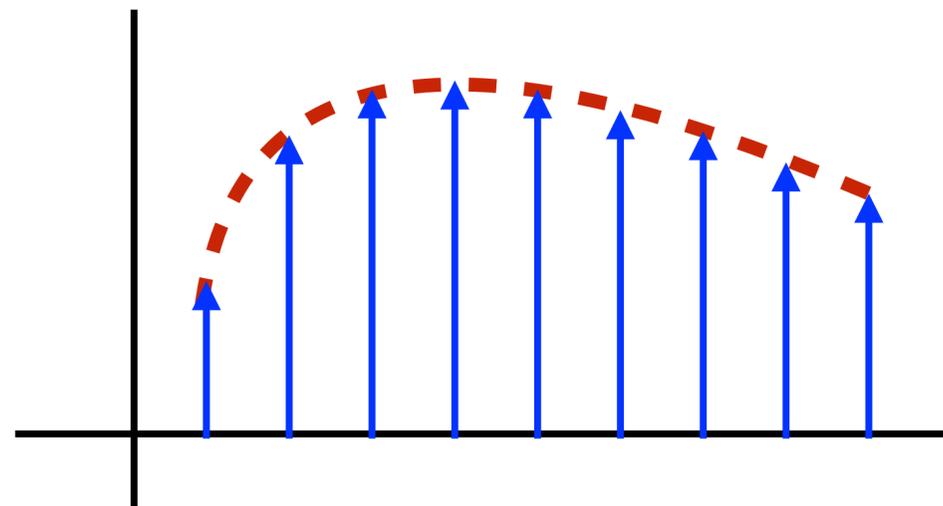


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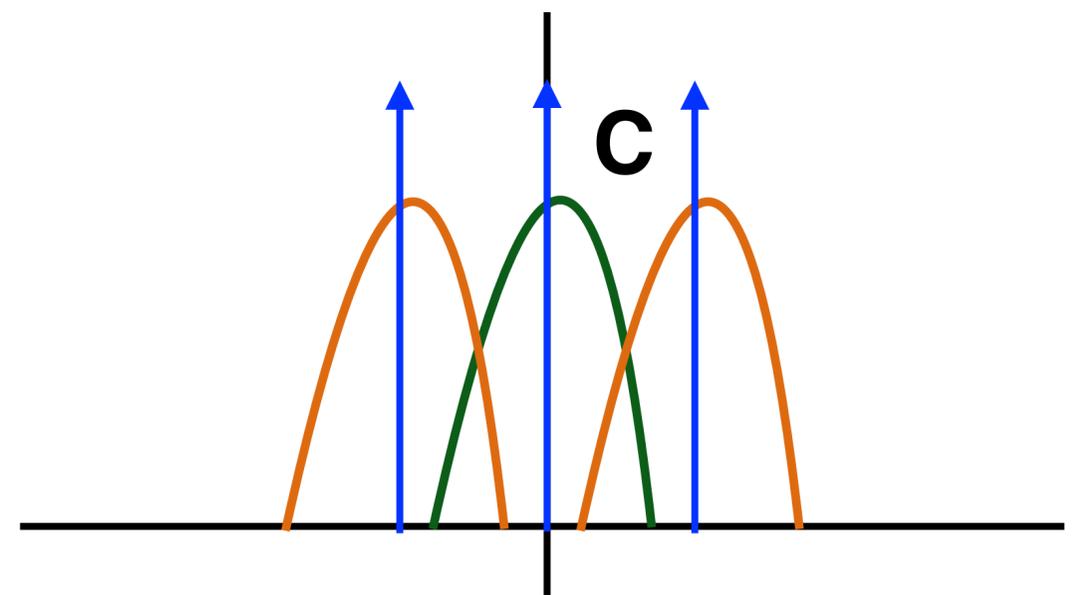
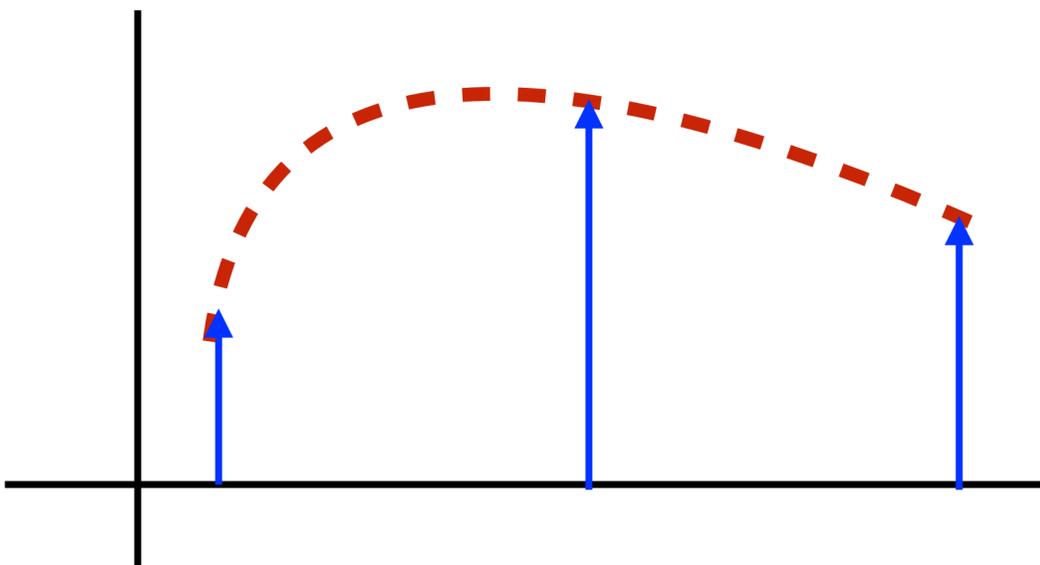


# Error in Monte Carlo Integration

High Sampling Rate

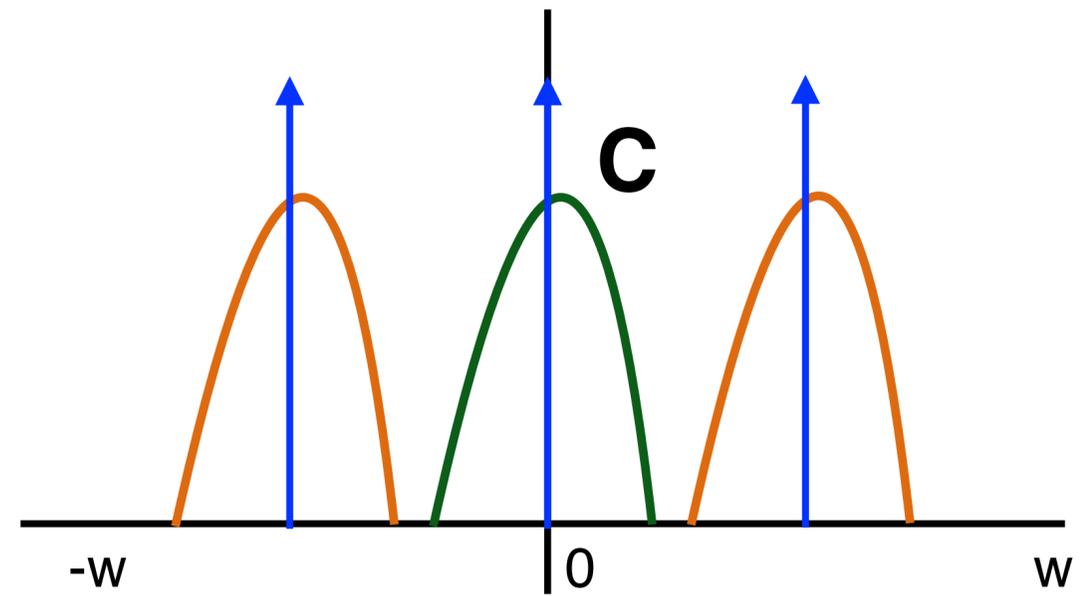
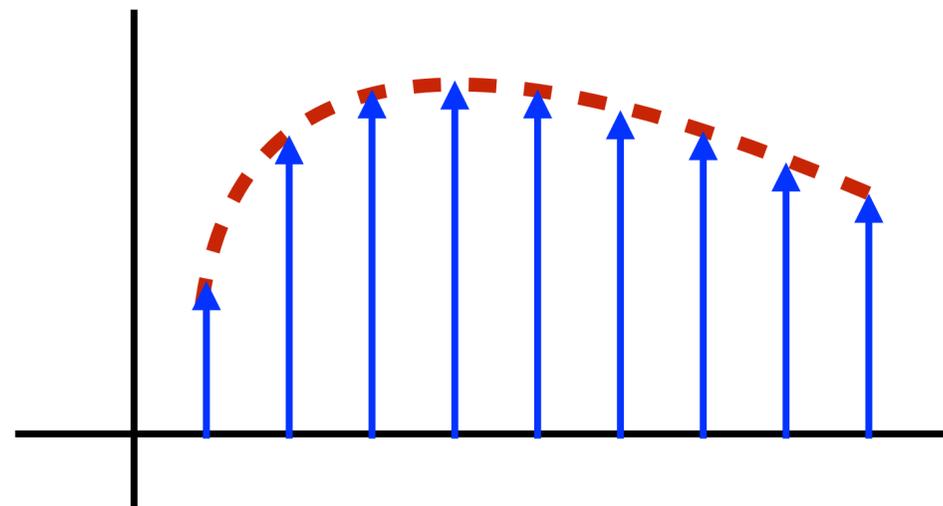


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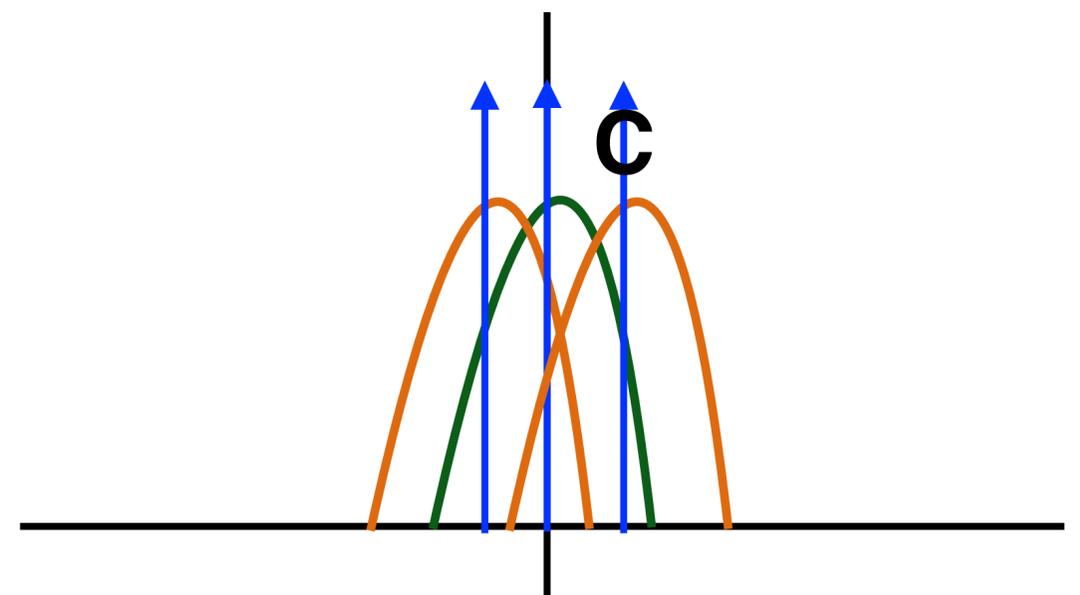
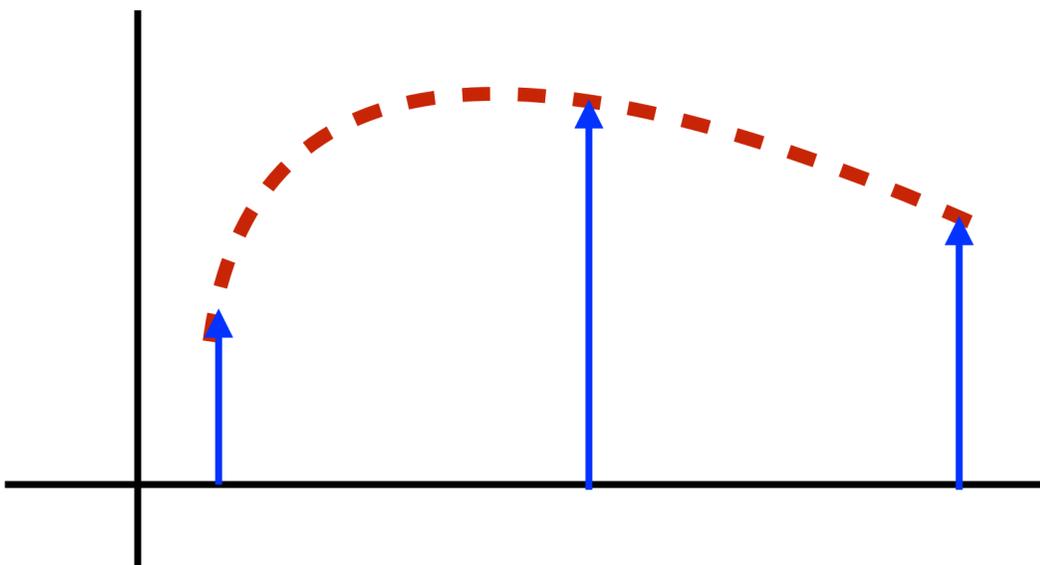


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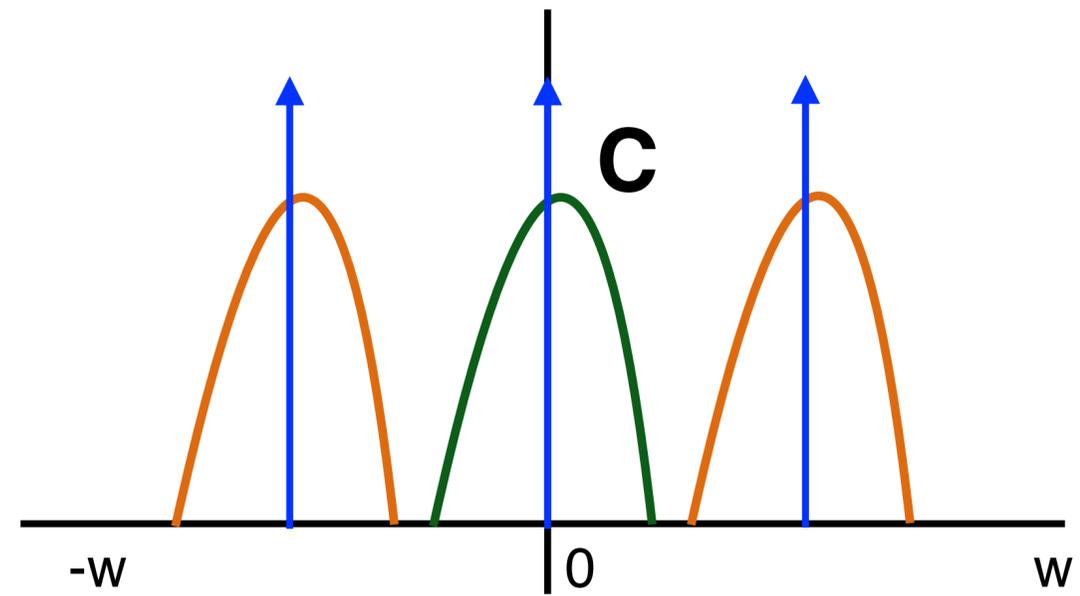
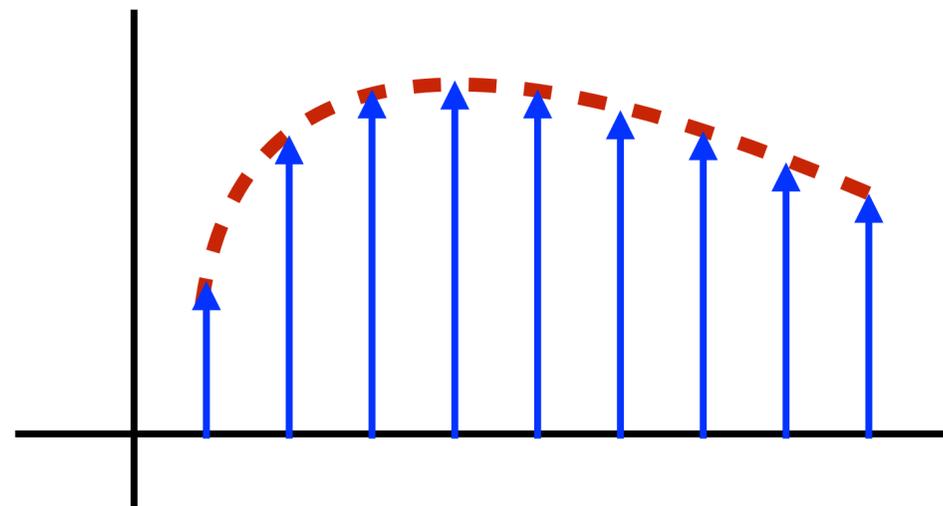


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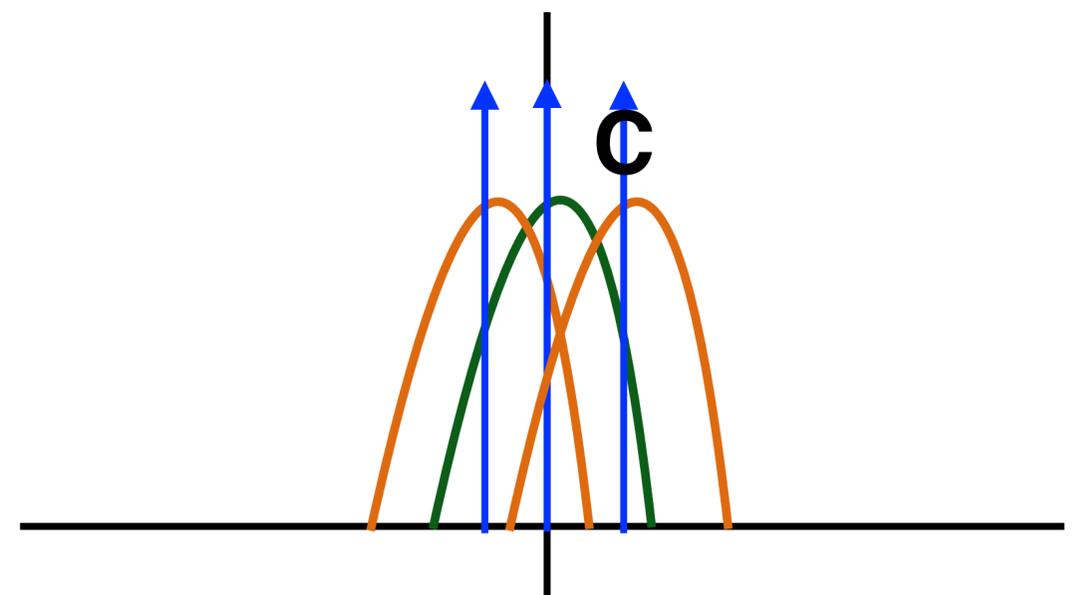
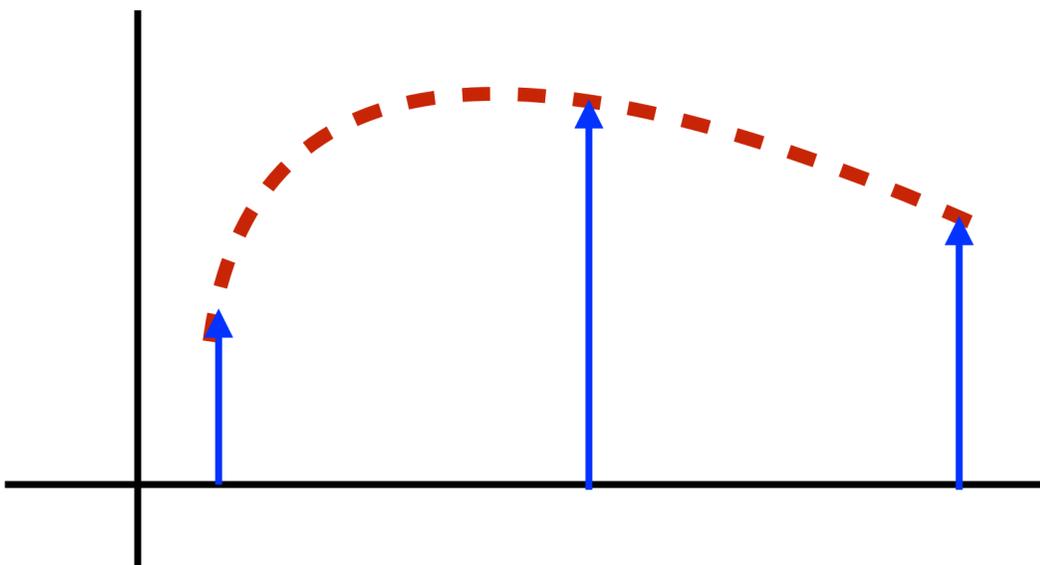


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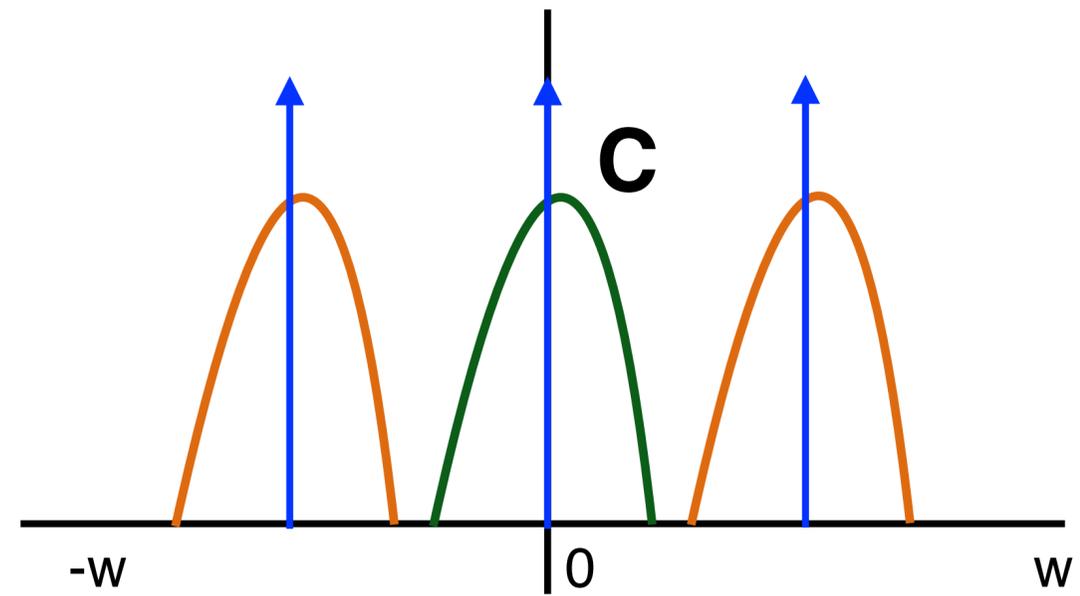
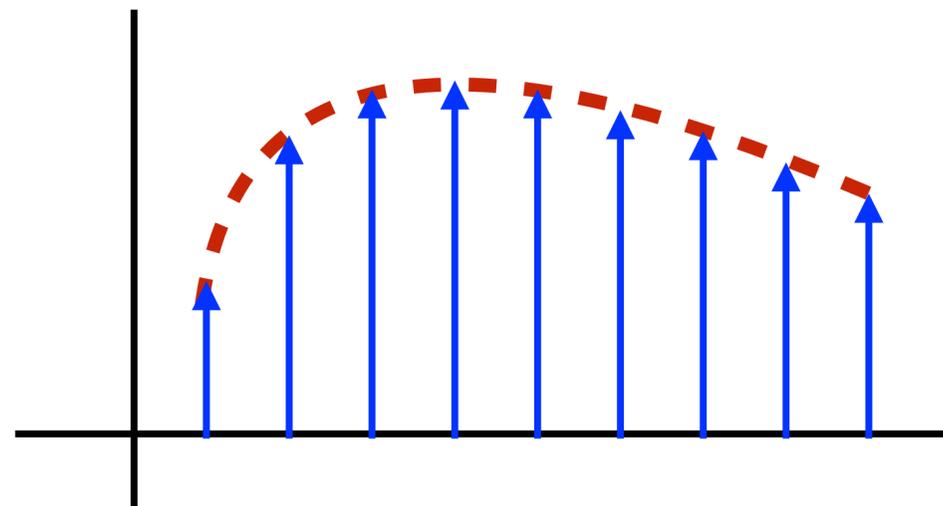


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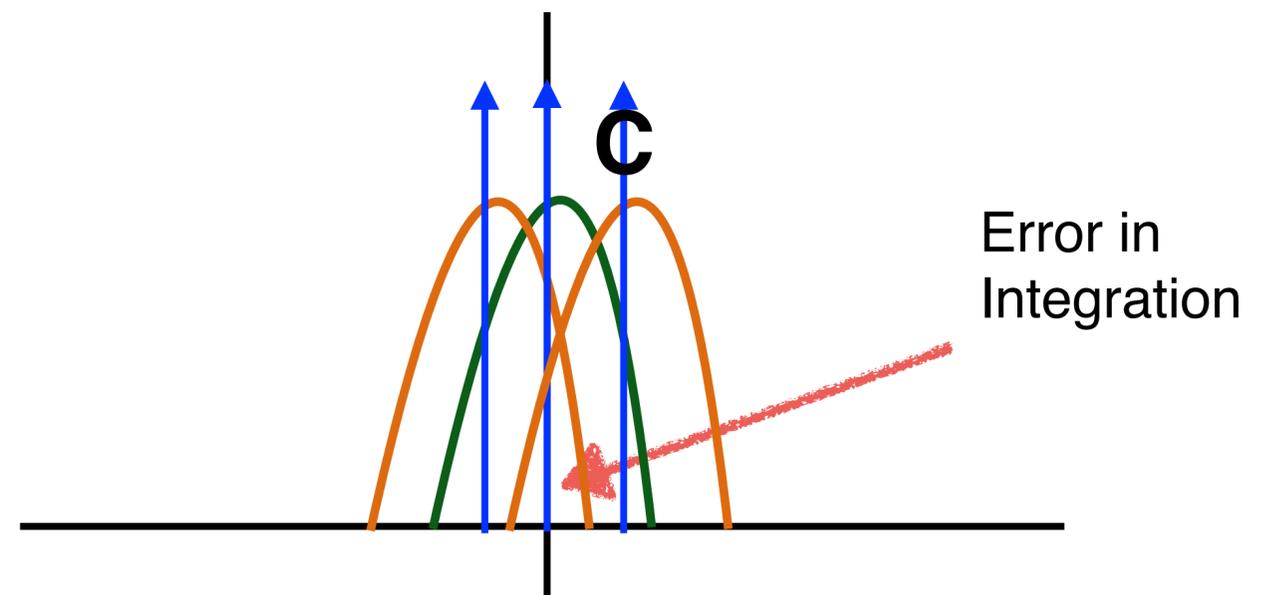
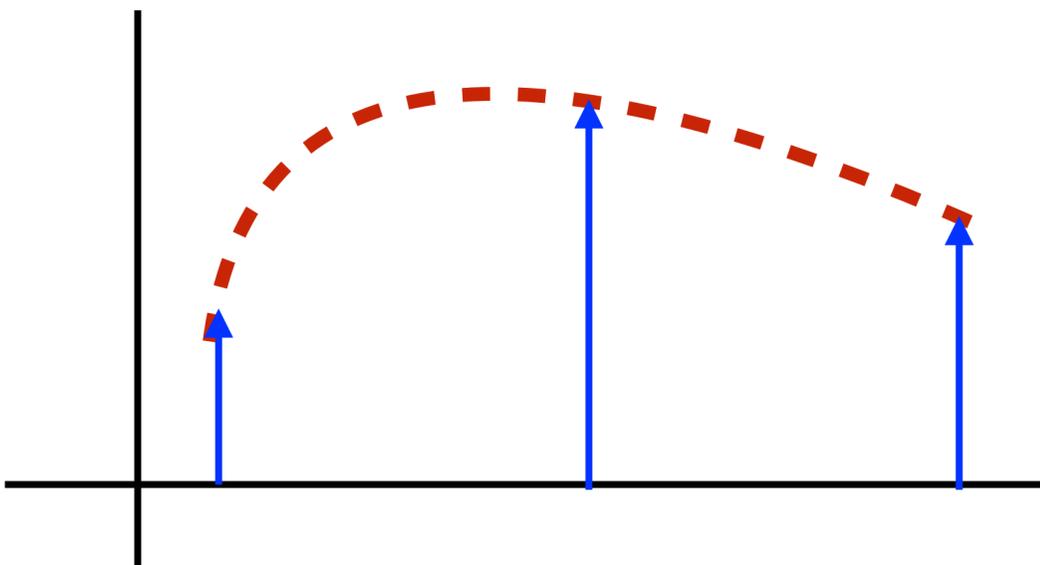


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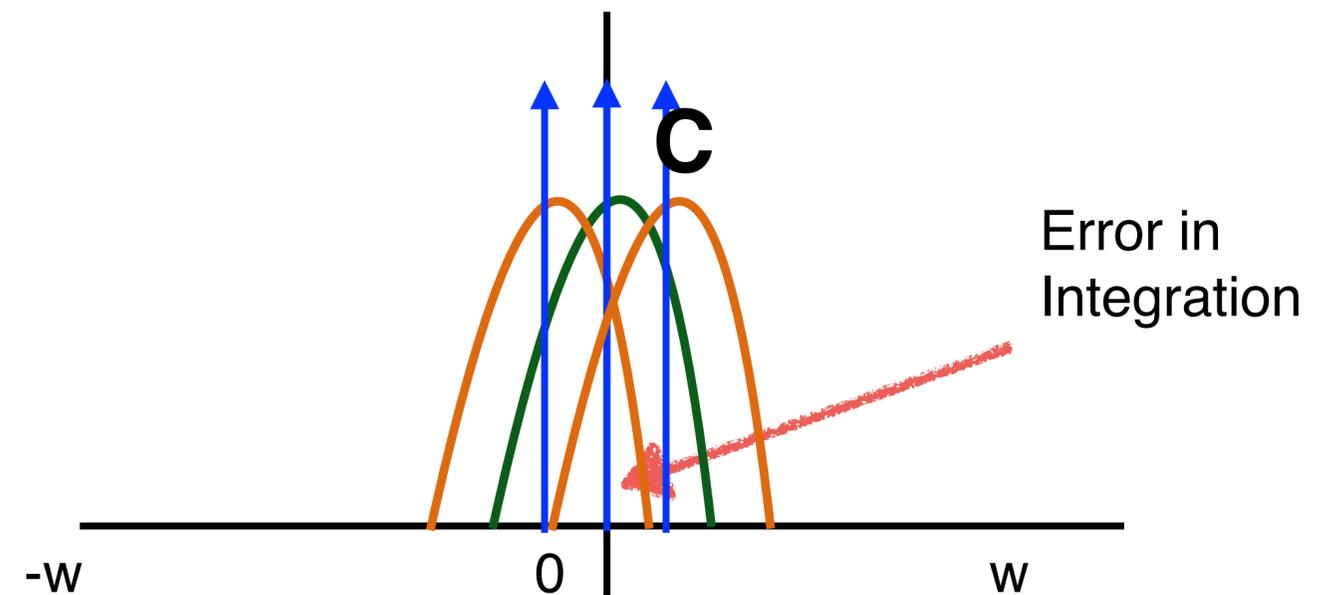
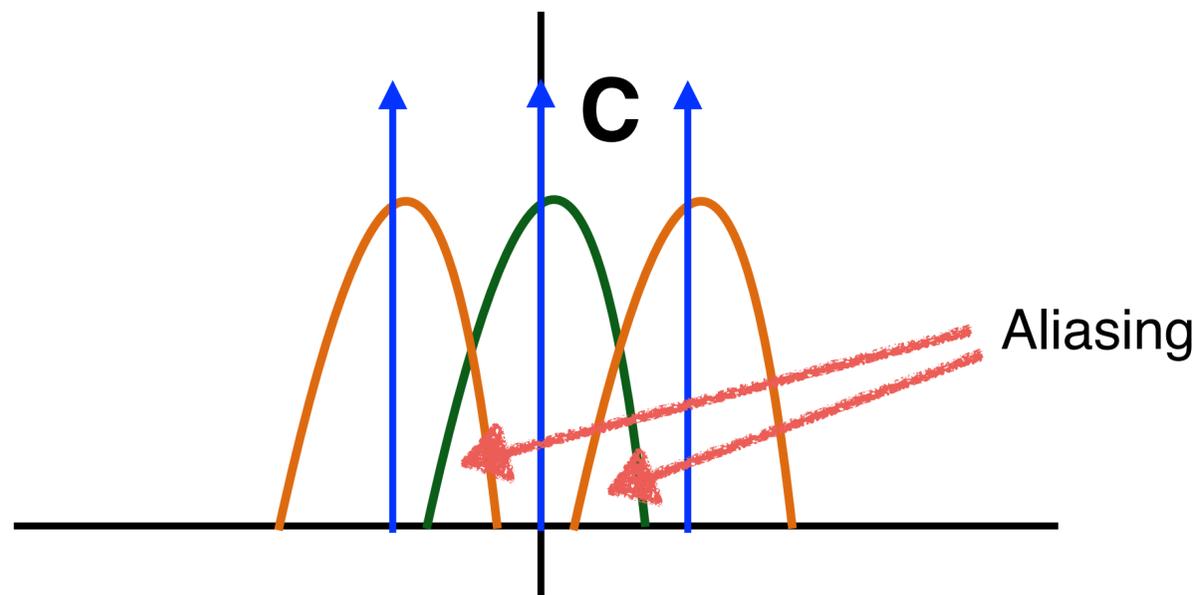
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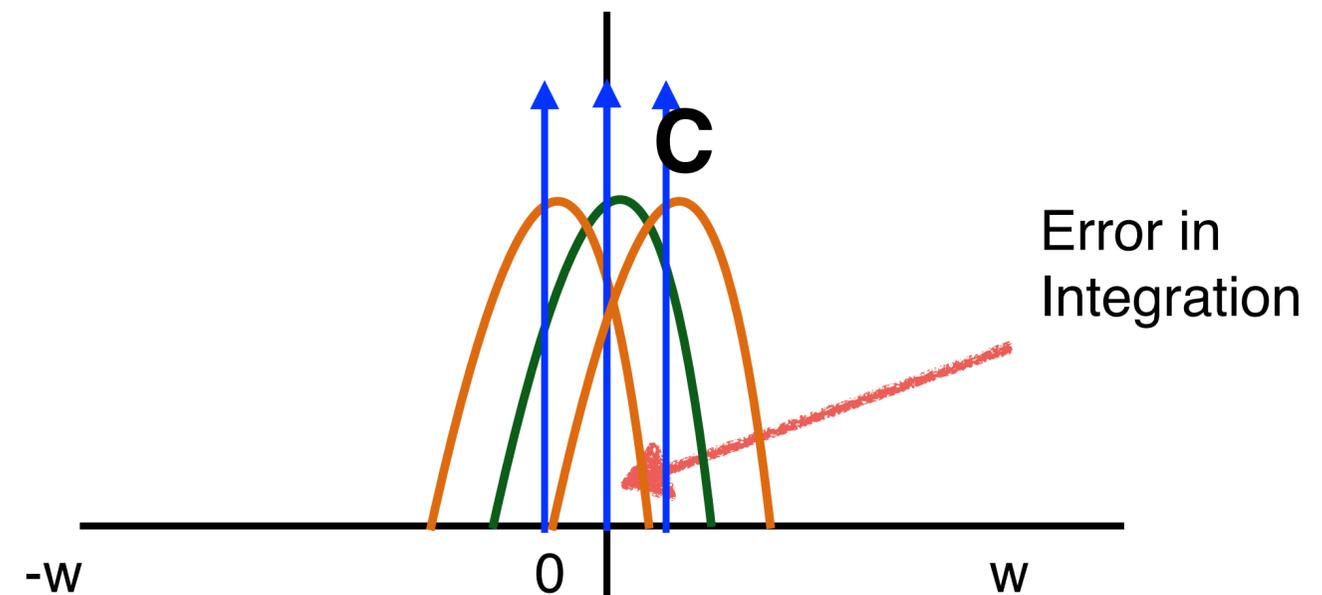
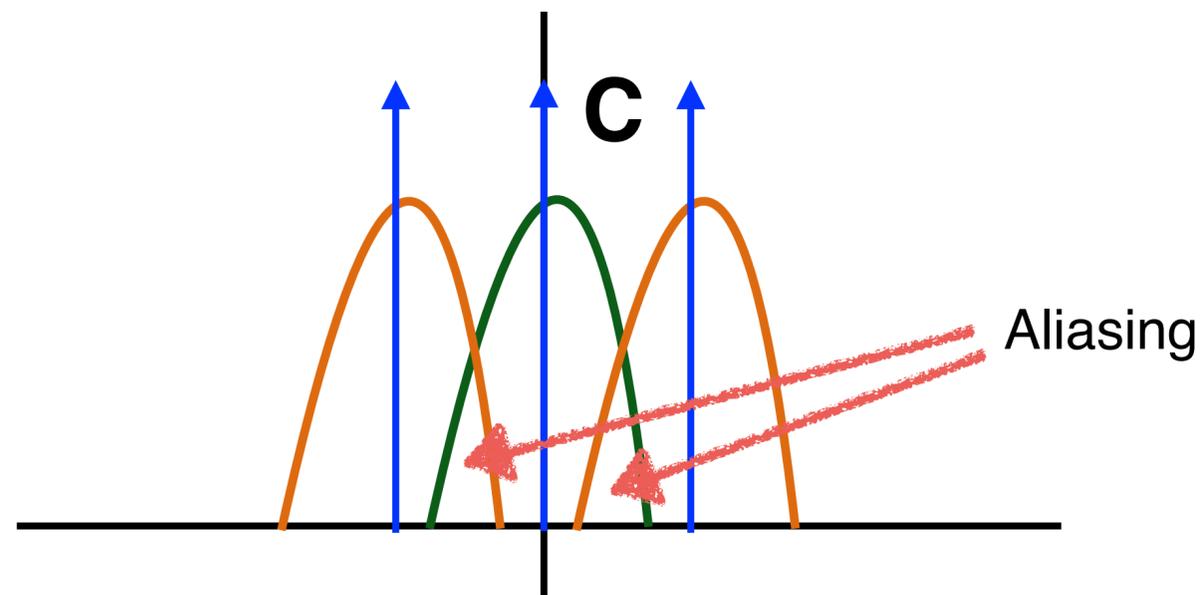


# Aliasing (Reconstruction) vs. Error (Integration)



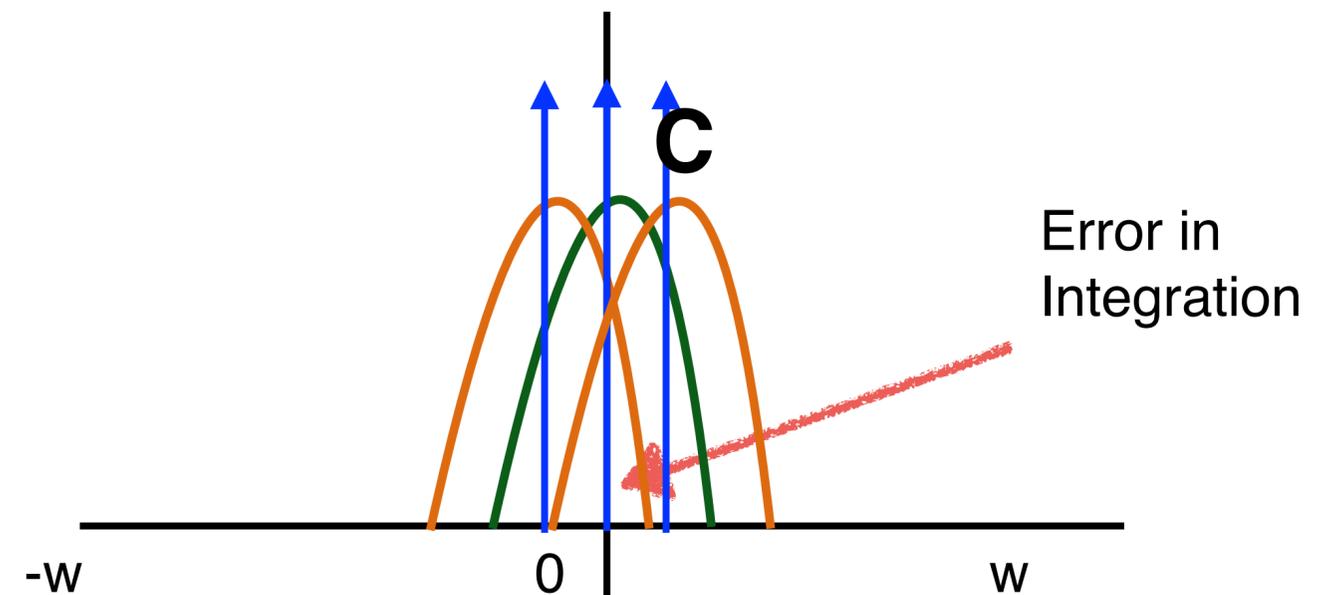
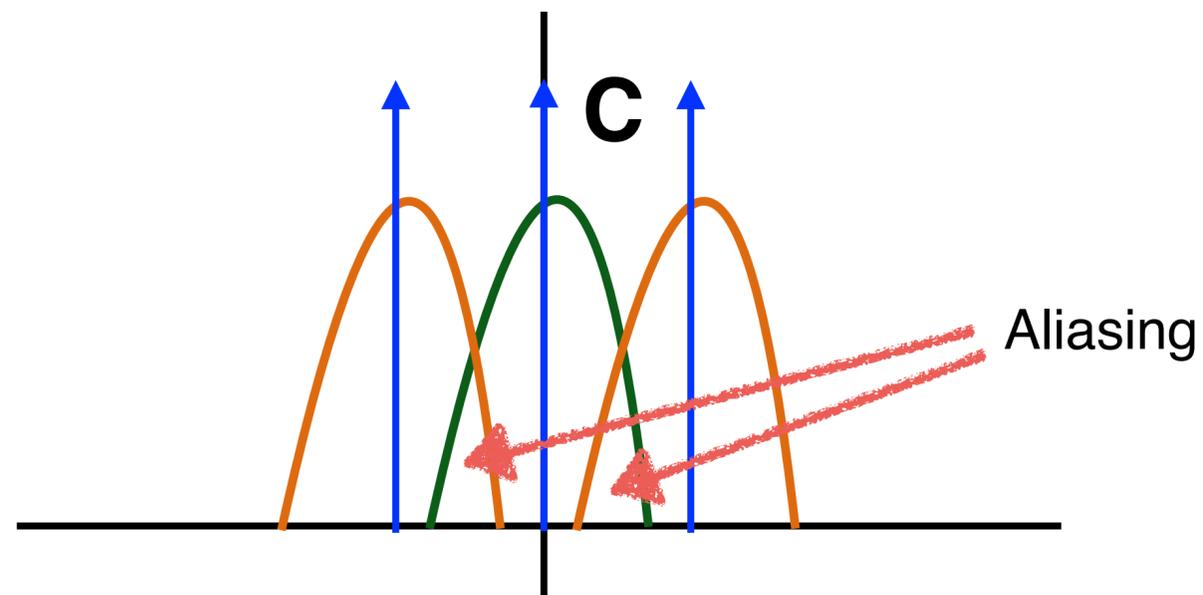
# Aliasing (Reconstruction) vs. Error (Integration)

Fredo Durand [2011]  
Belcour et al. [2013]



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# Integration in the Fourier Domain

# Integration is the DC term in the Fourier Domain

Spatial Domain:

$$I = \int_D f(x) dx$$

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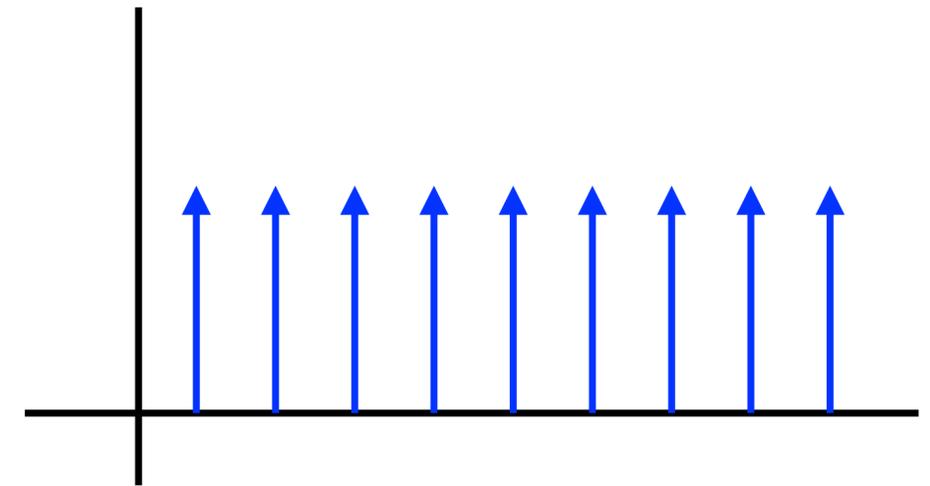
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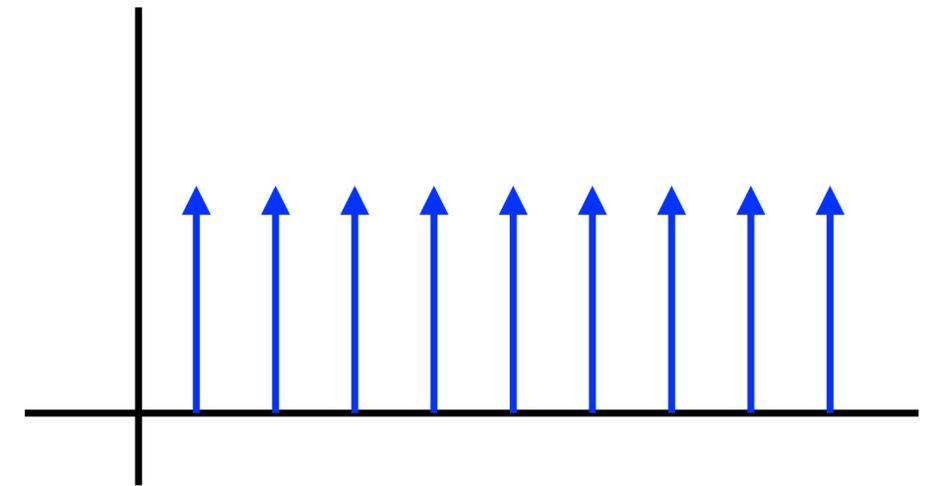
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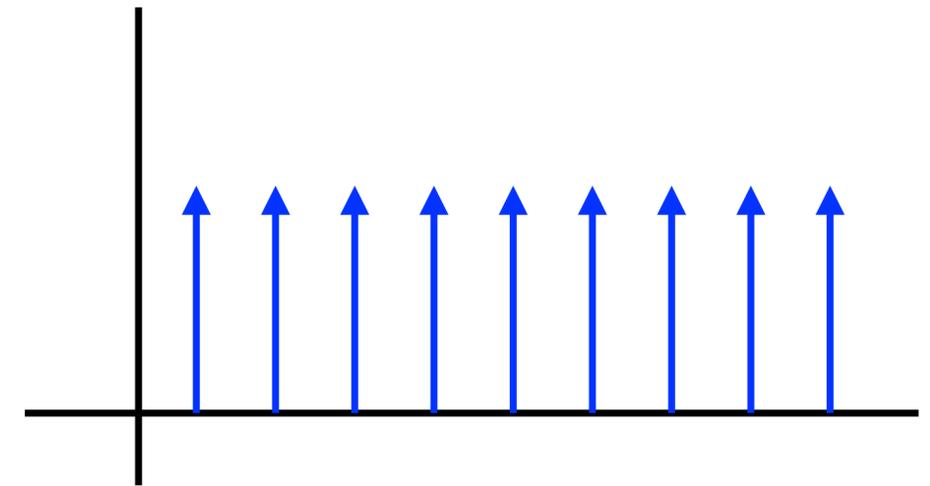
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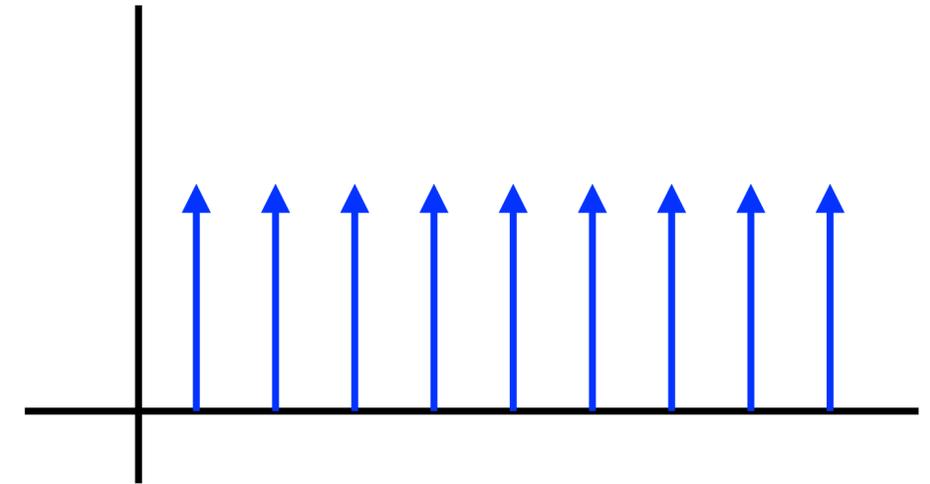
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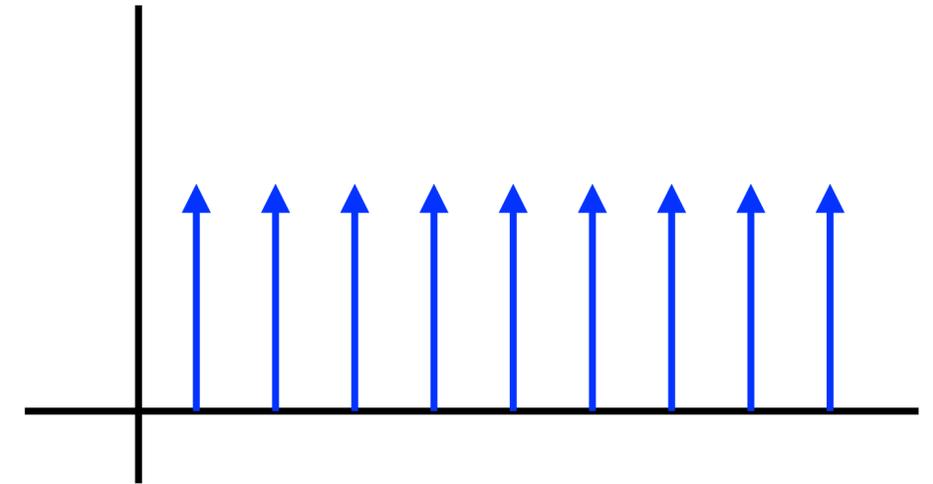
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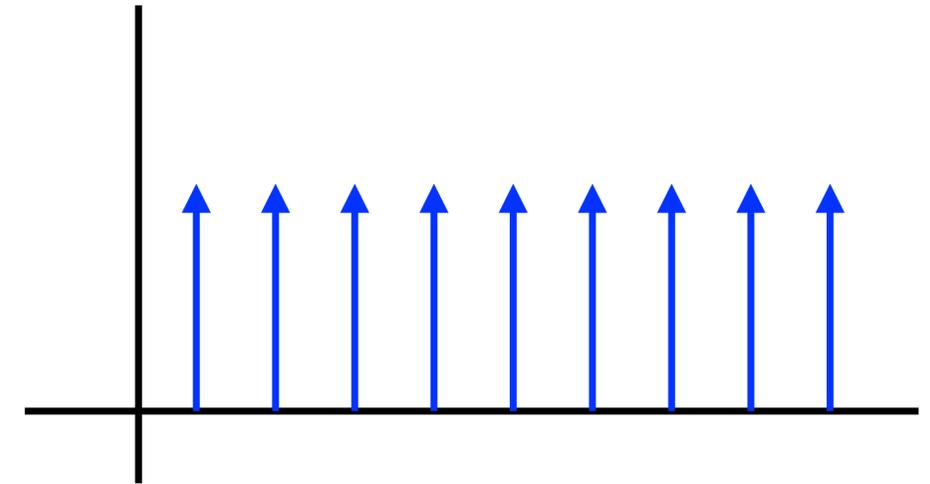
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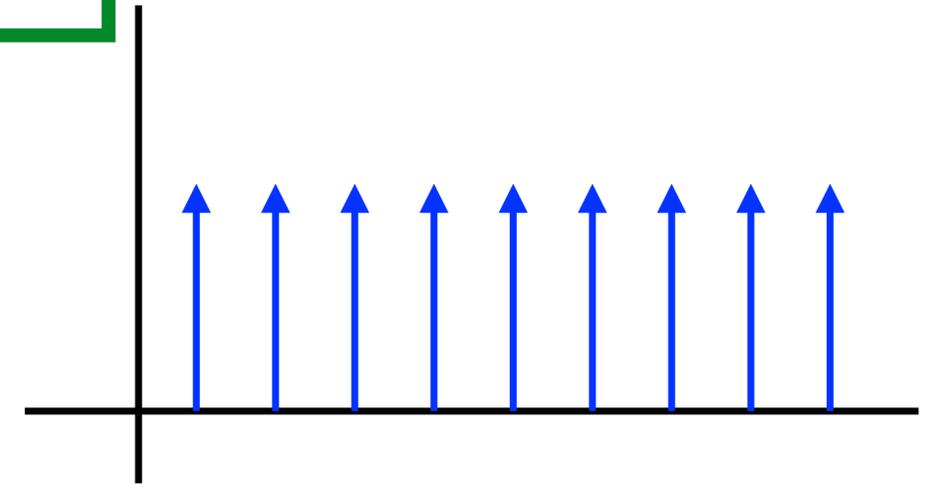
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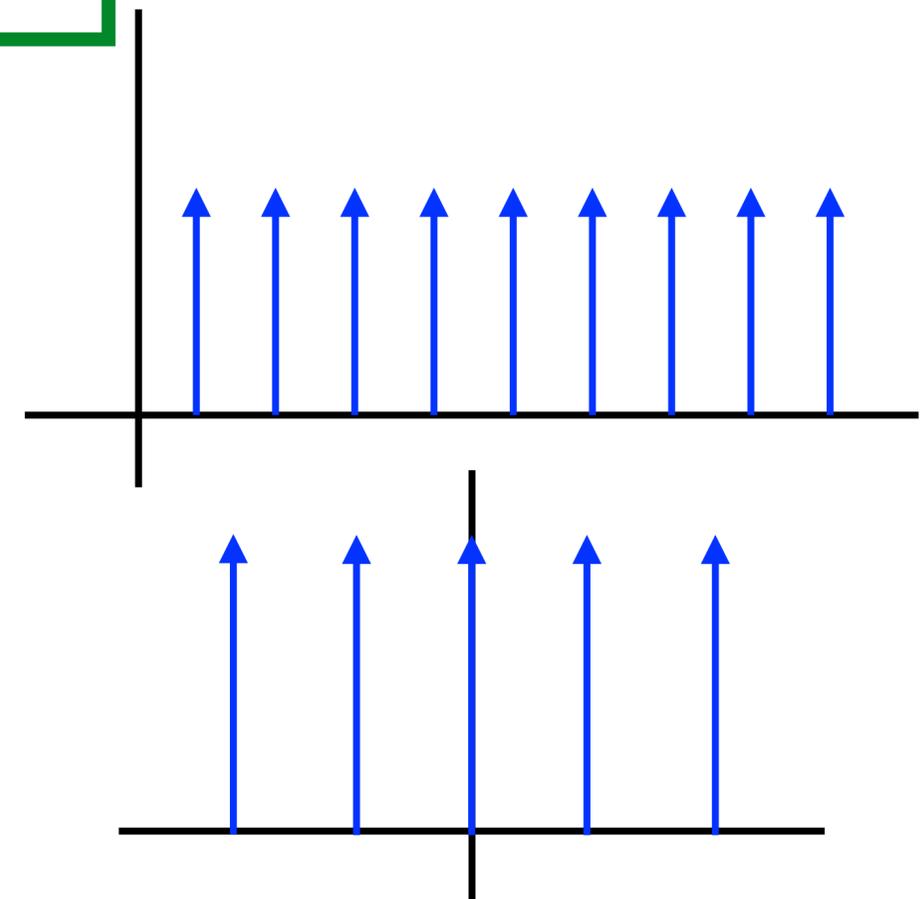


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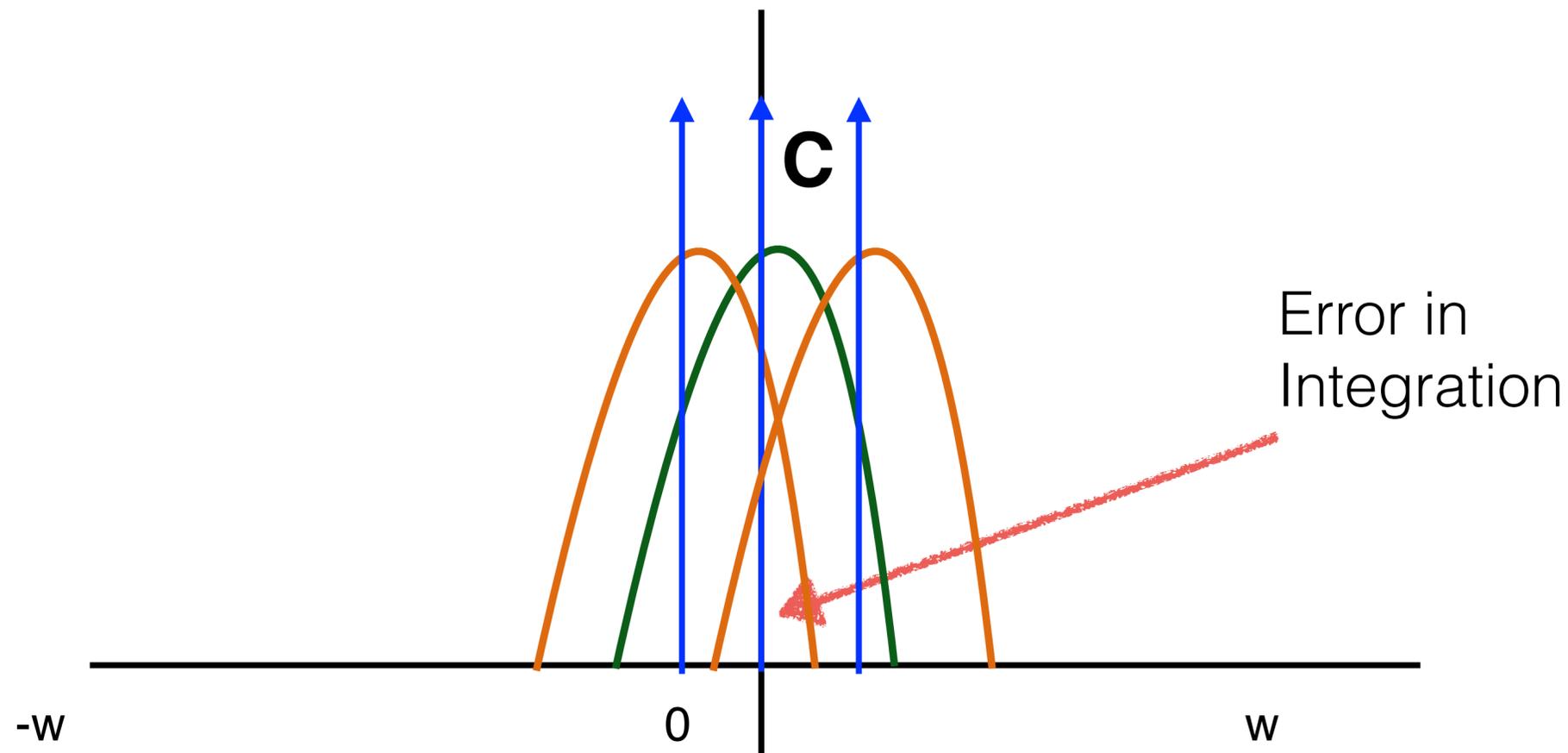
$$\hat{\mathbf{S}}(\omega) = \frac{1}{N} \sum_{k=1}^N e^{-i2\pi\omega x_k}$$



# How to Formulate Error in Fourier Domain ?

$$I = \hat{f}(0)$$

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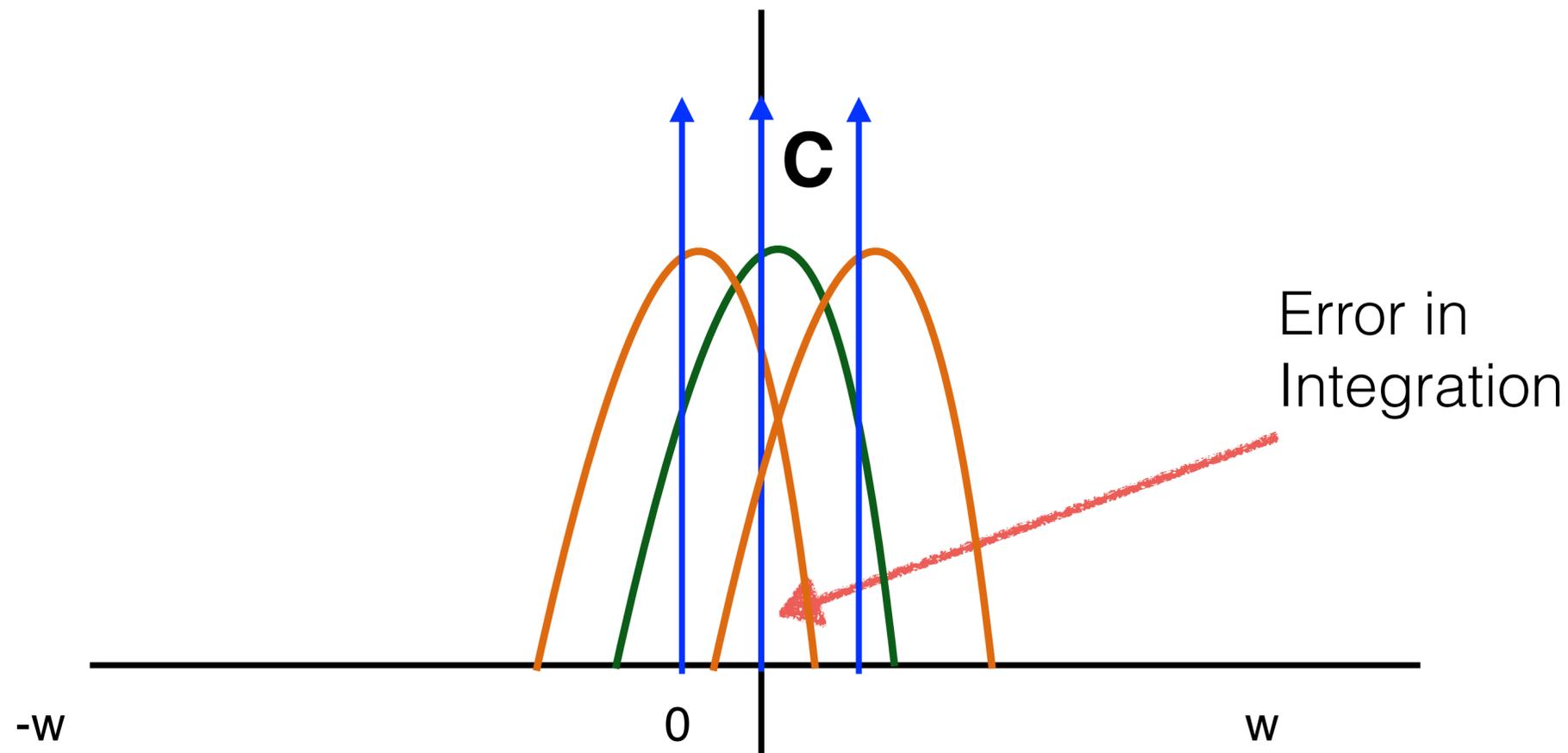


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Monte Carlo Estimator

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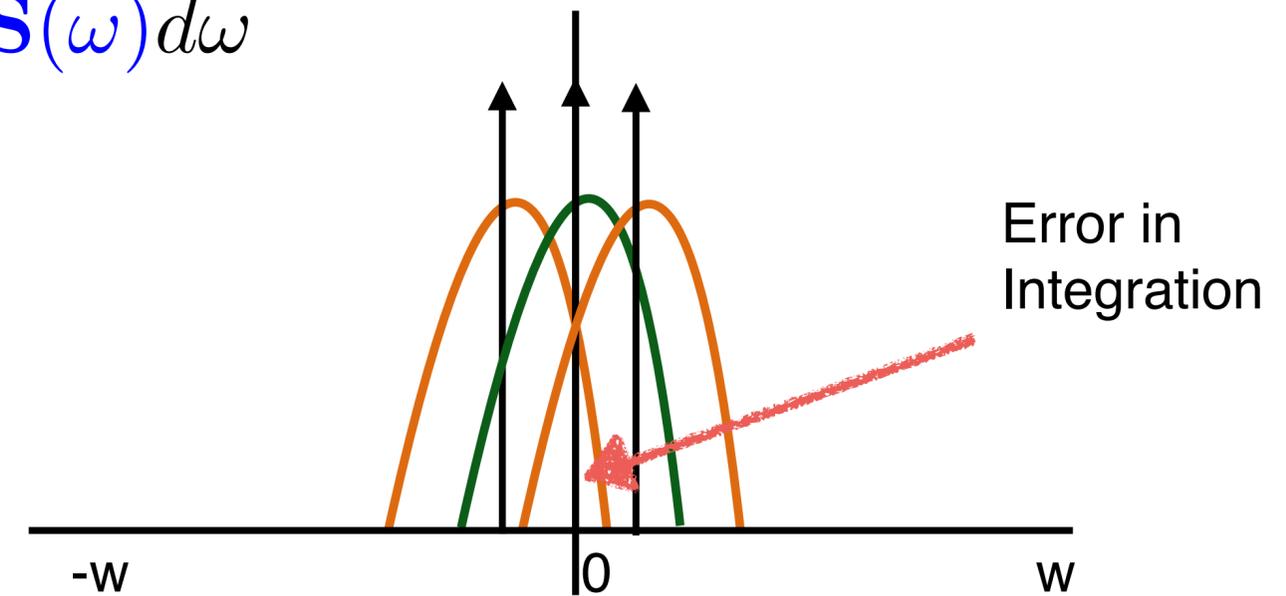
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Fredo Durand [2011]

$$\text{Error} = \text{Bias}^2 + \text{Variance}$$

# Properties of Error

- Bias
- Variance

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- Variance:  $\text{Var}(I - \mu_N)$

**Subr and Kautz [2013]**

# Bias in the Monte Carlo Estimator

# Bias in Fourier Domain

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To obtain an unbiased estimator:

**Subr and Kautz [2013]**

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To obtain an unbiased estimator:

**Subr and Kautz [2013]**

$$\langle \hat{\mathbf{S}}(\omega) \rangle = 0$$

for frequencies other than zero

How to obtain  $\langle \hat{\mathbf{S}}(\omega) \rangle = 0$  ?

# Complex form in Amplitude and Phase

$$\langle \hat{\mathbf{S}}(\omega) \rangle = |\langle \hat{\mathbf{S}}(\omega) \rangle| e^{-\Phi(\langle \hat{\mathbf{S}}(\omega) \rangle)}$$

# Complex form in Amplitude and Phase

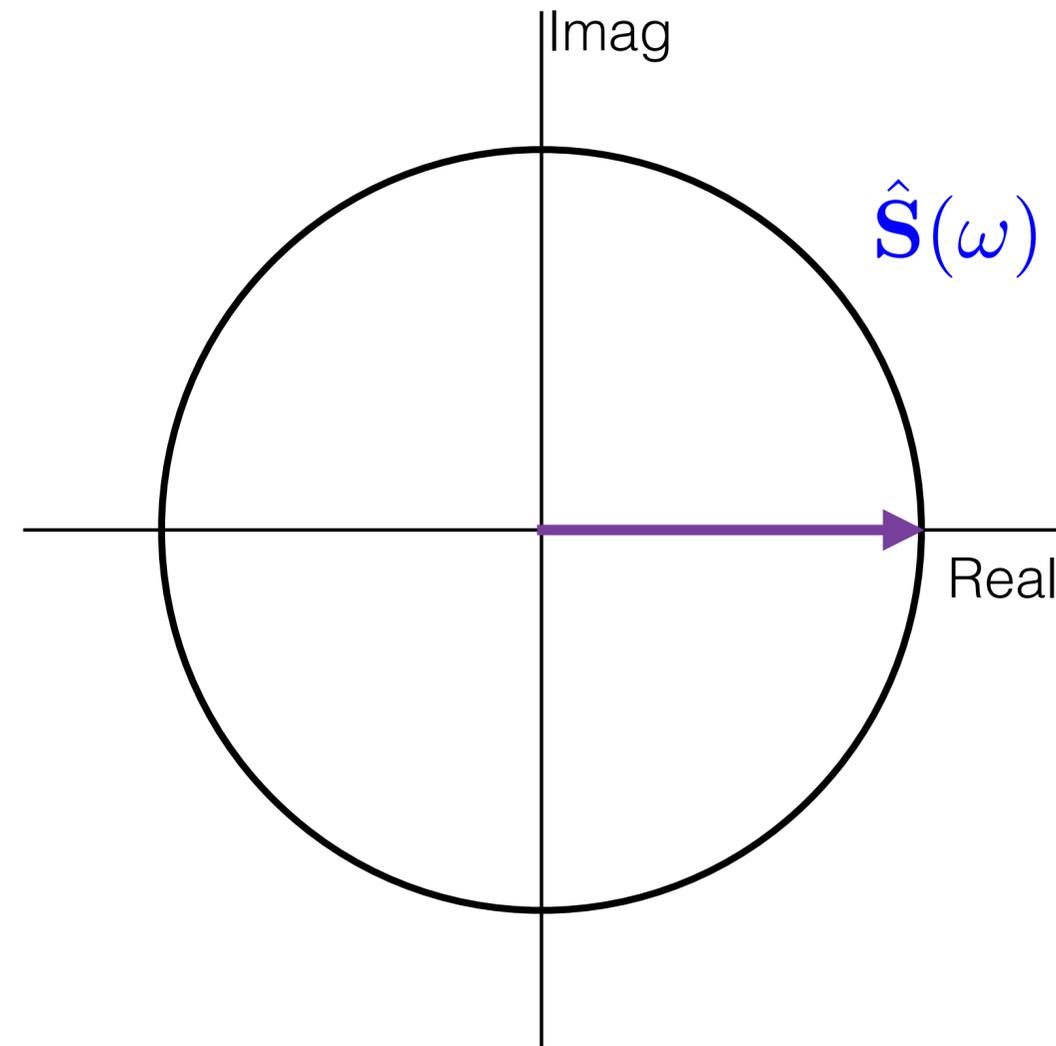
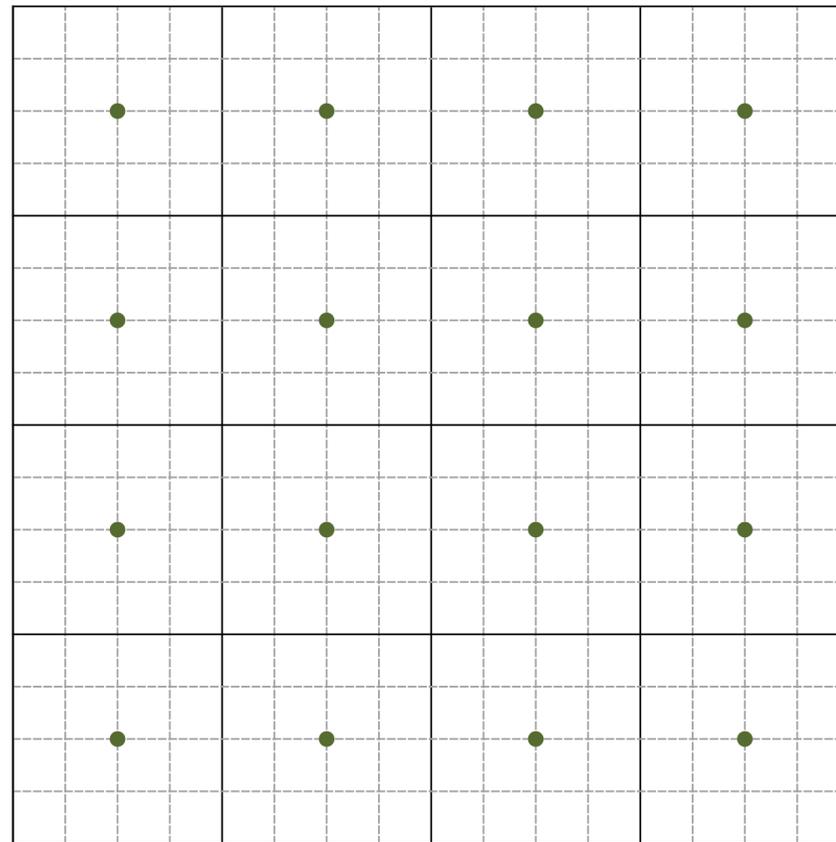
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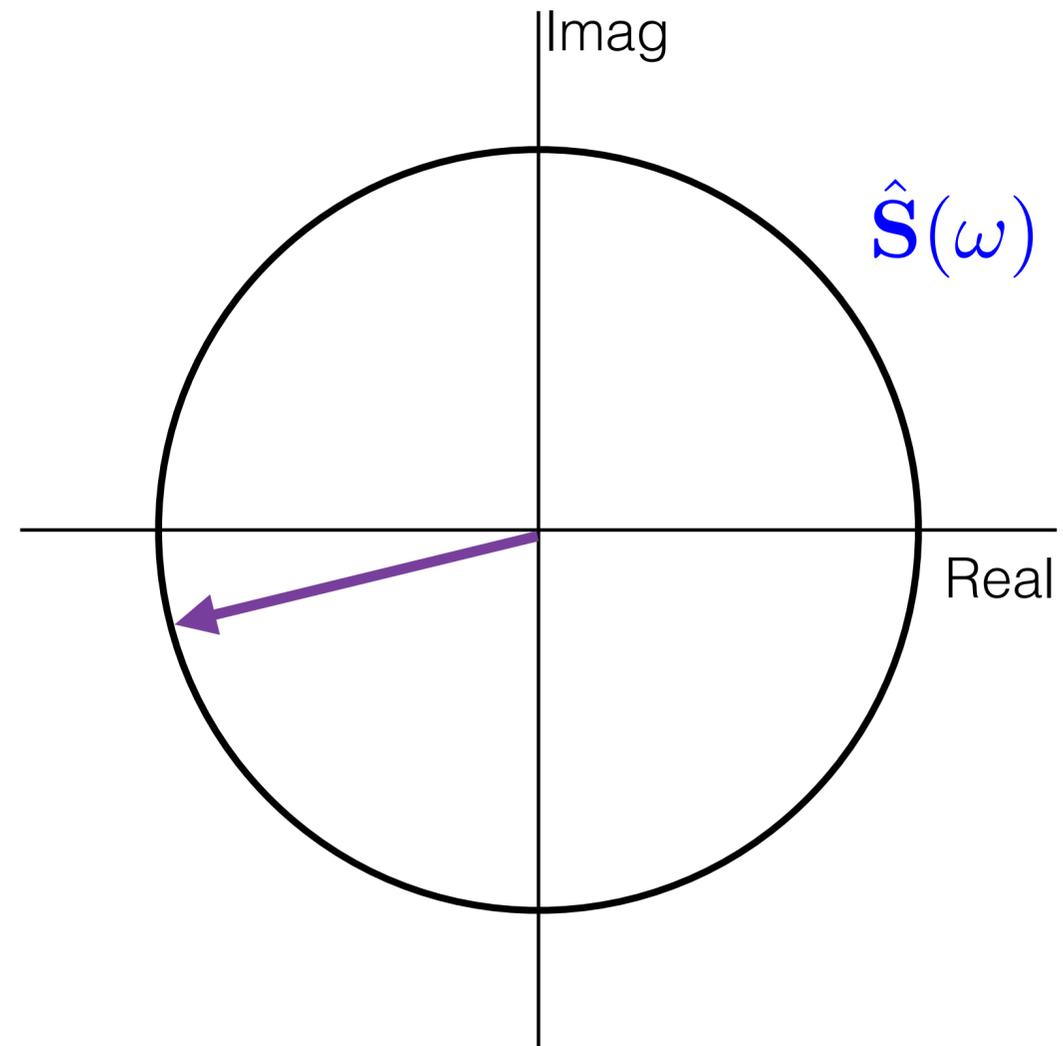
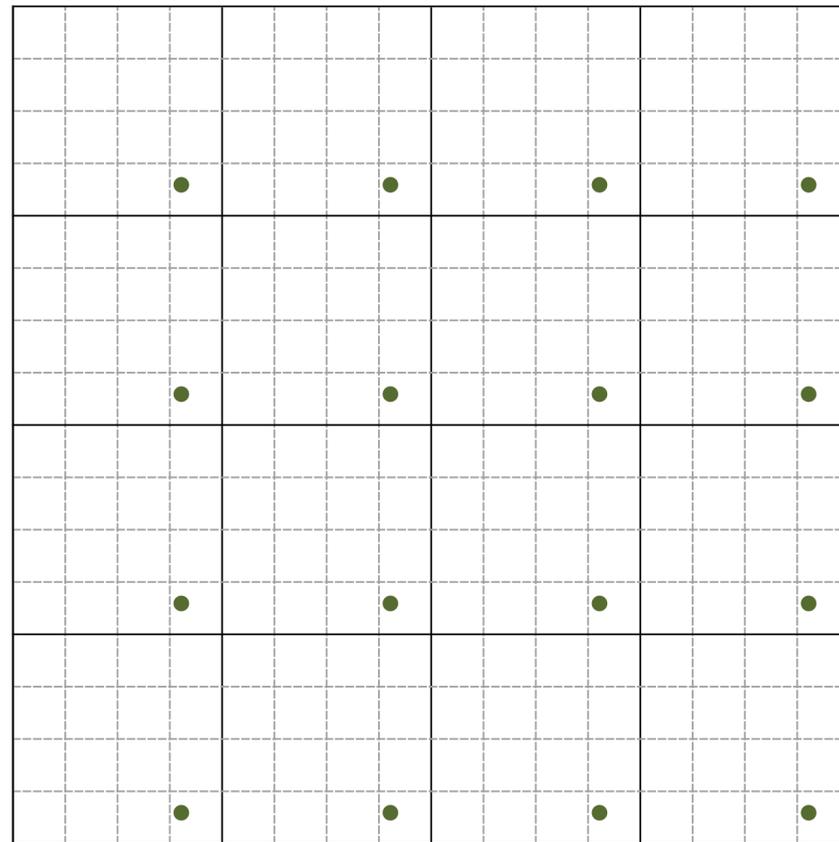
# Phase change due to Random Shift

For a given frequency  $\omega$



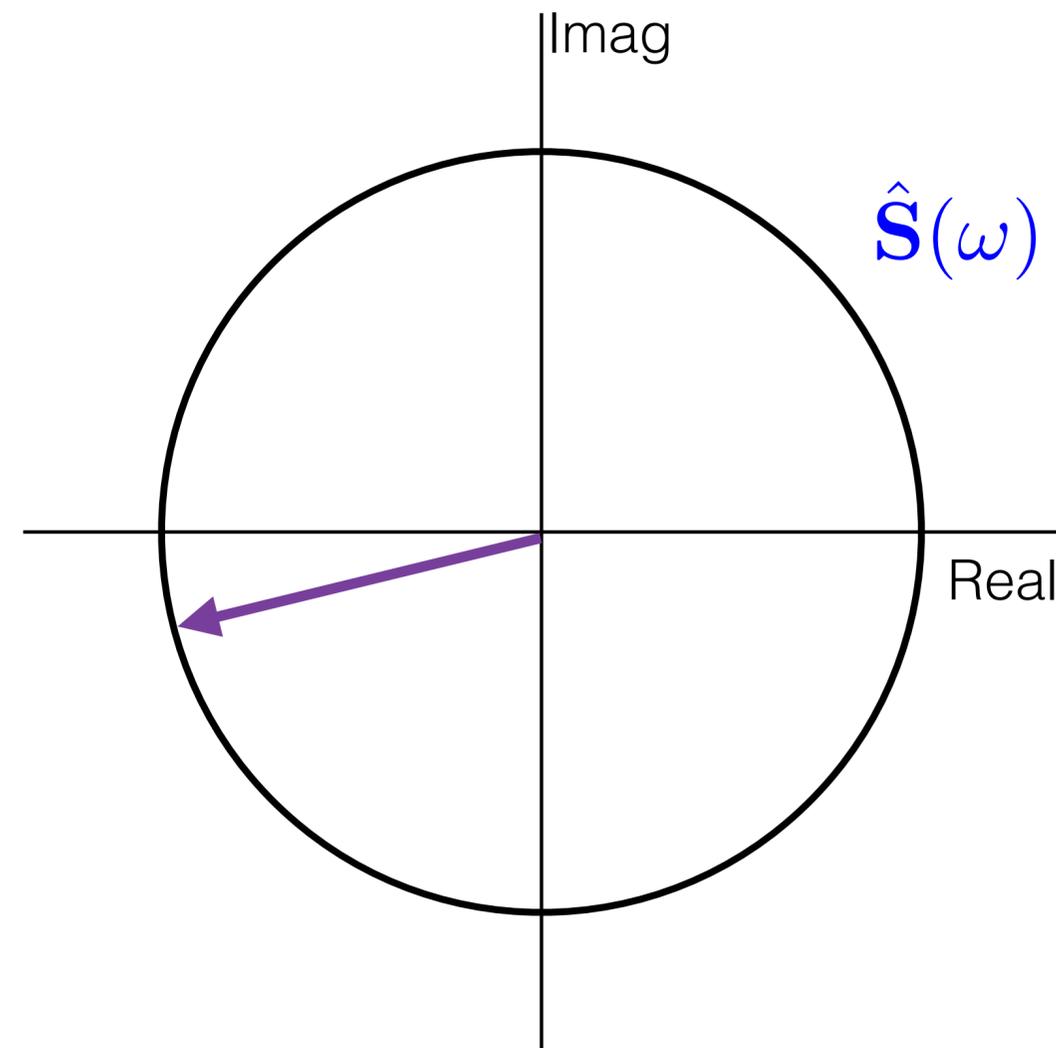
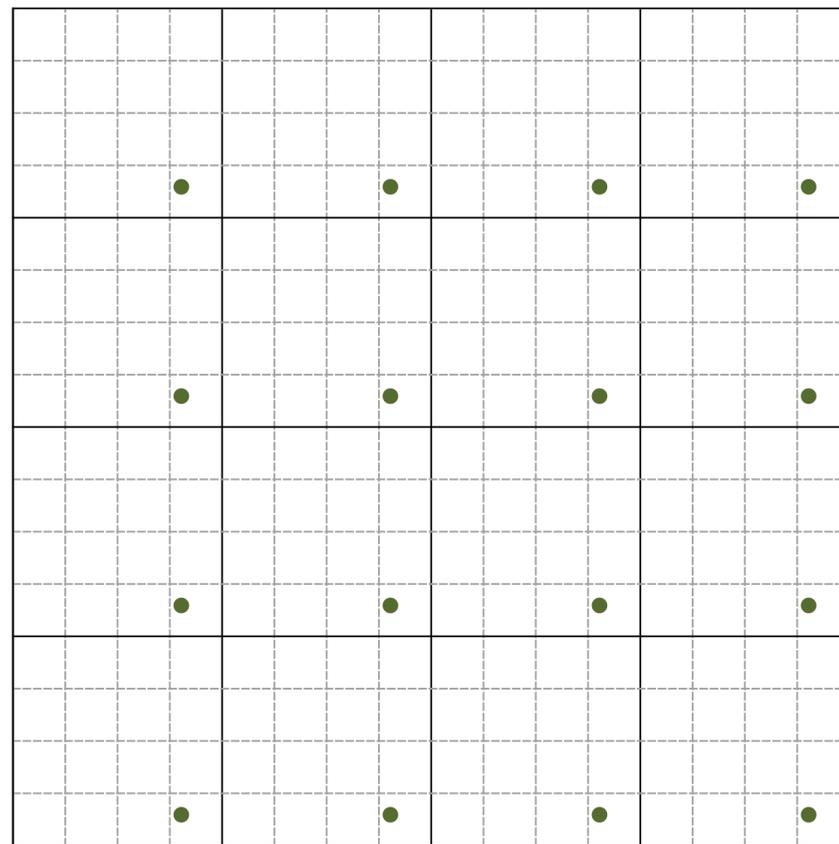
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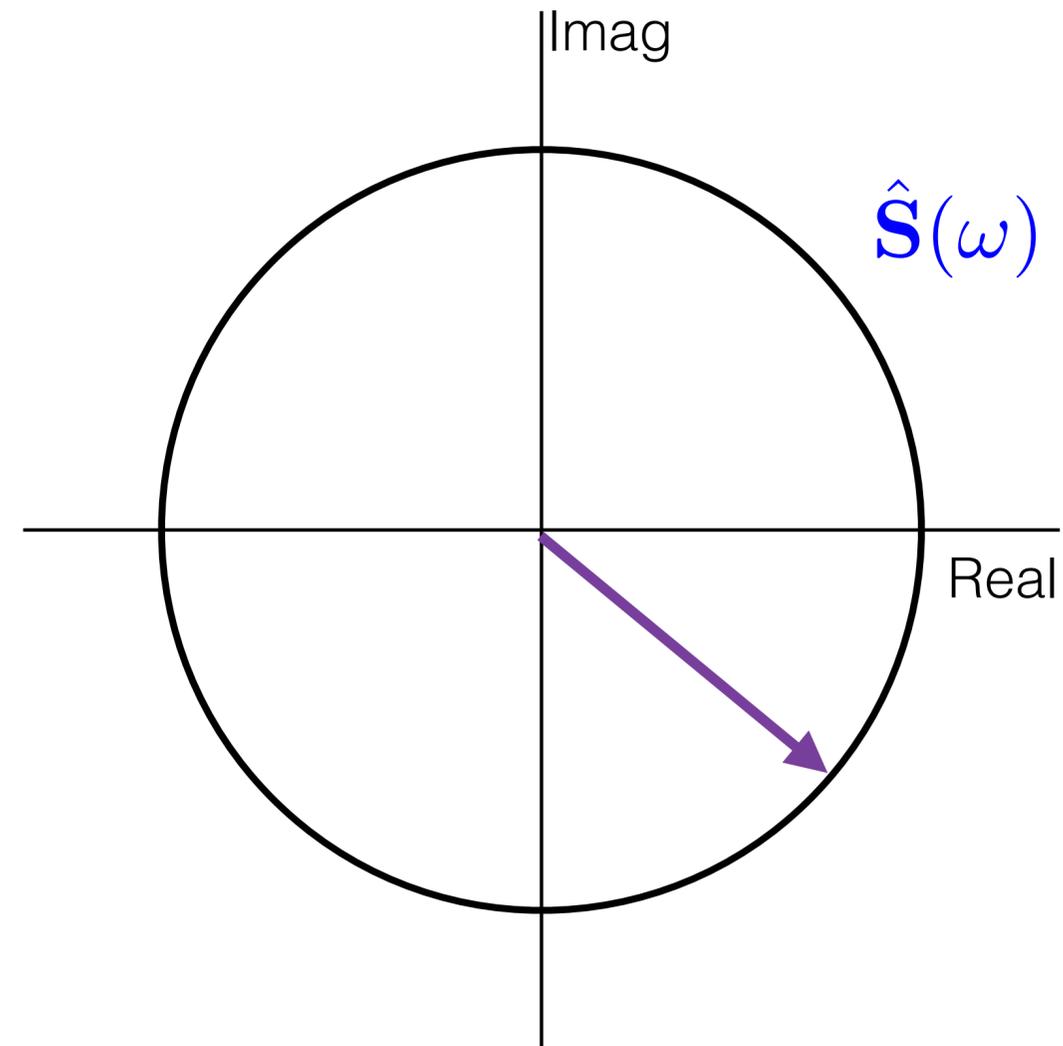
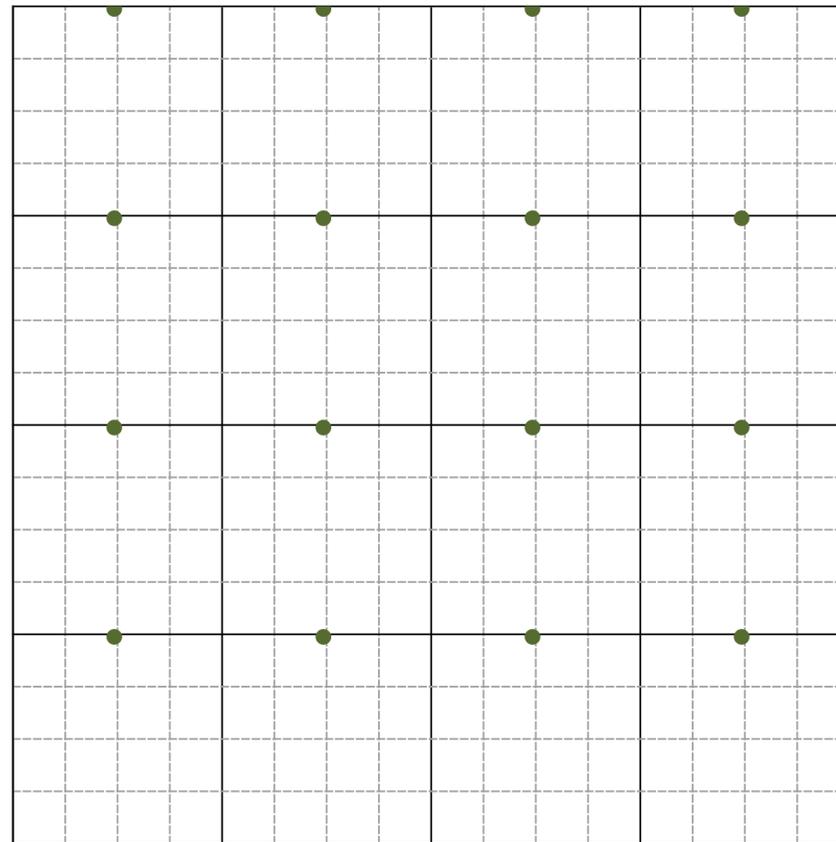
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**Pauly et al. [2000]**  
**Ramamoorthi et al. [2012]**

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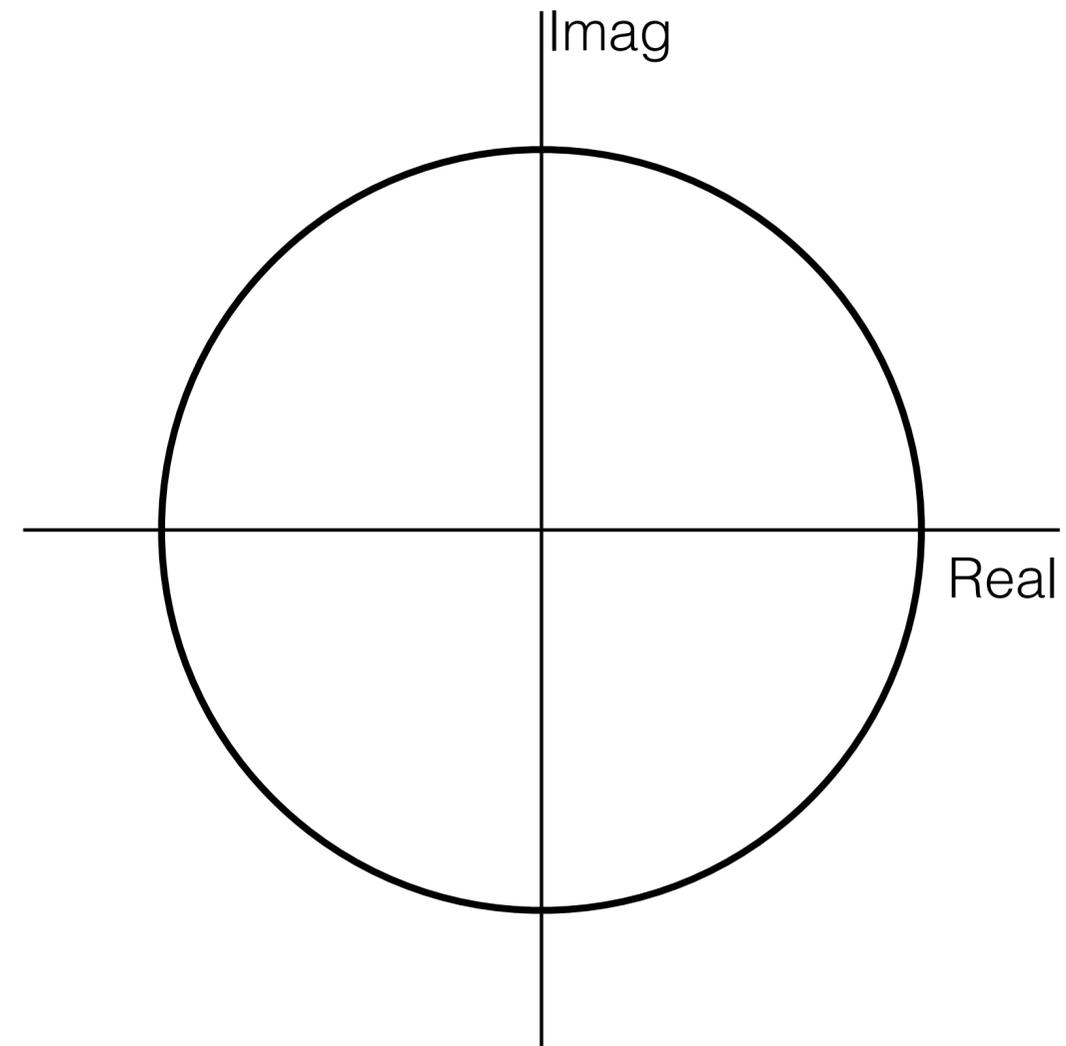
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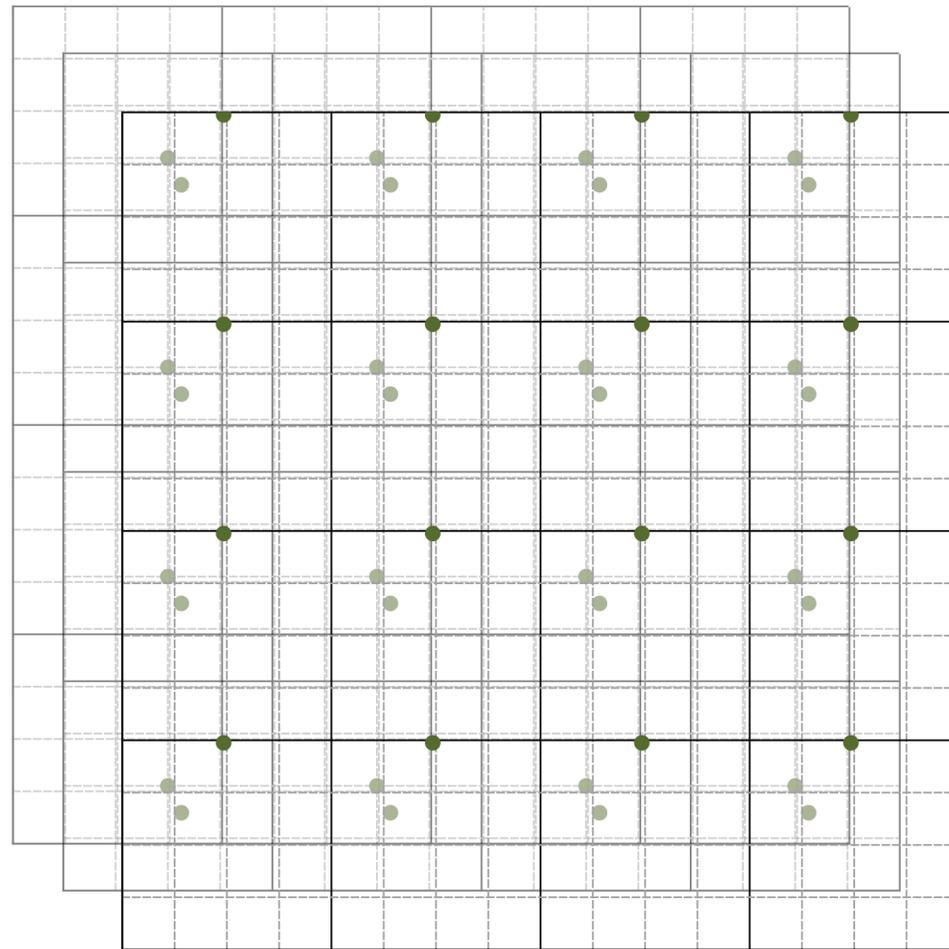
Multiple realizations

For a given frequency  $\omega$

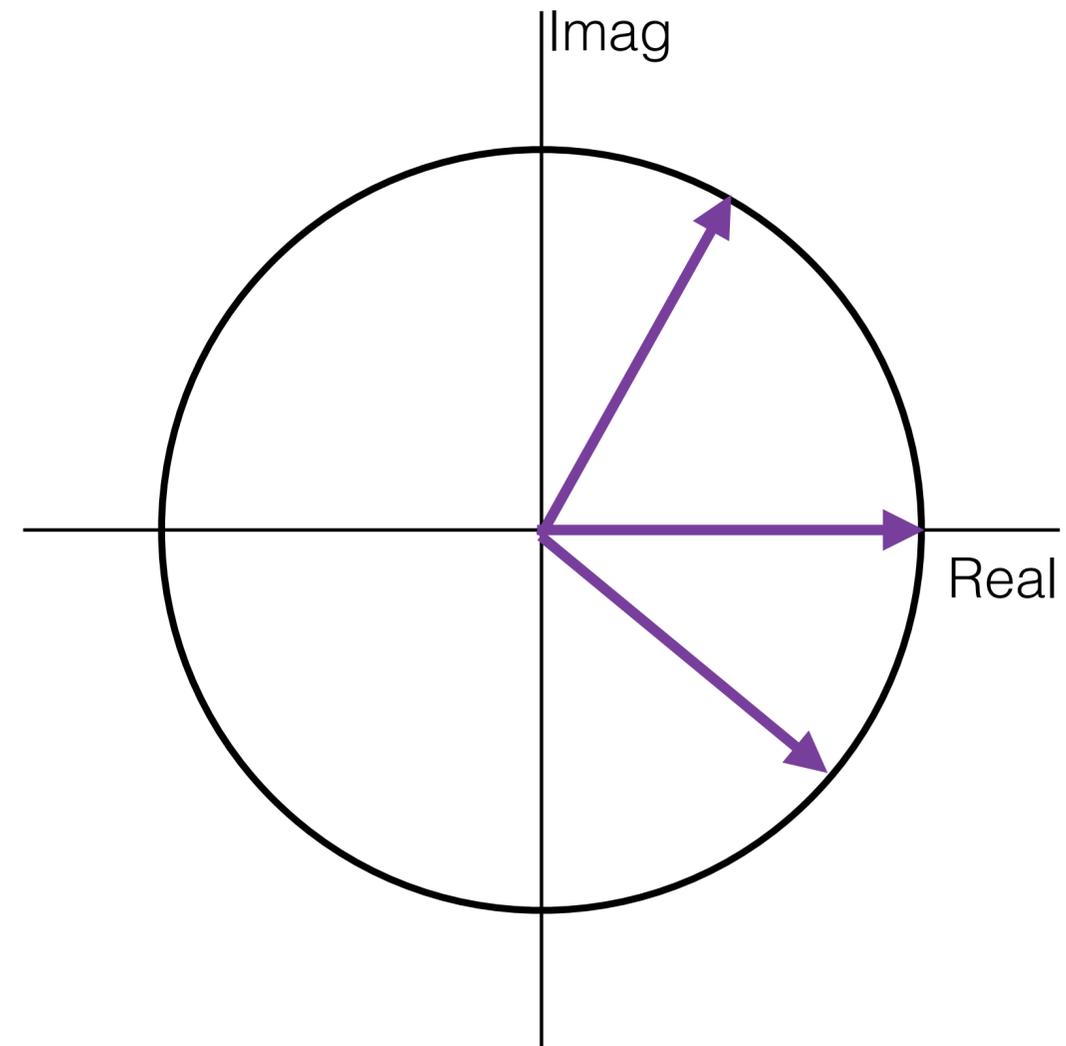


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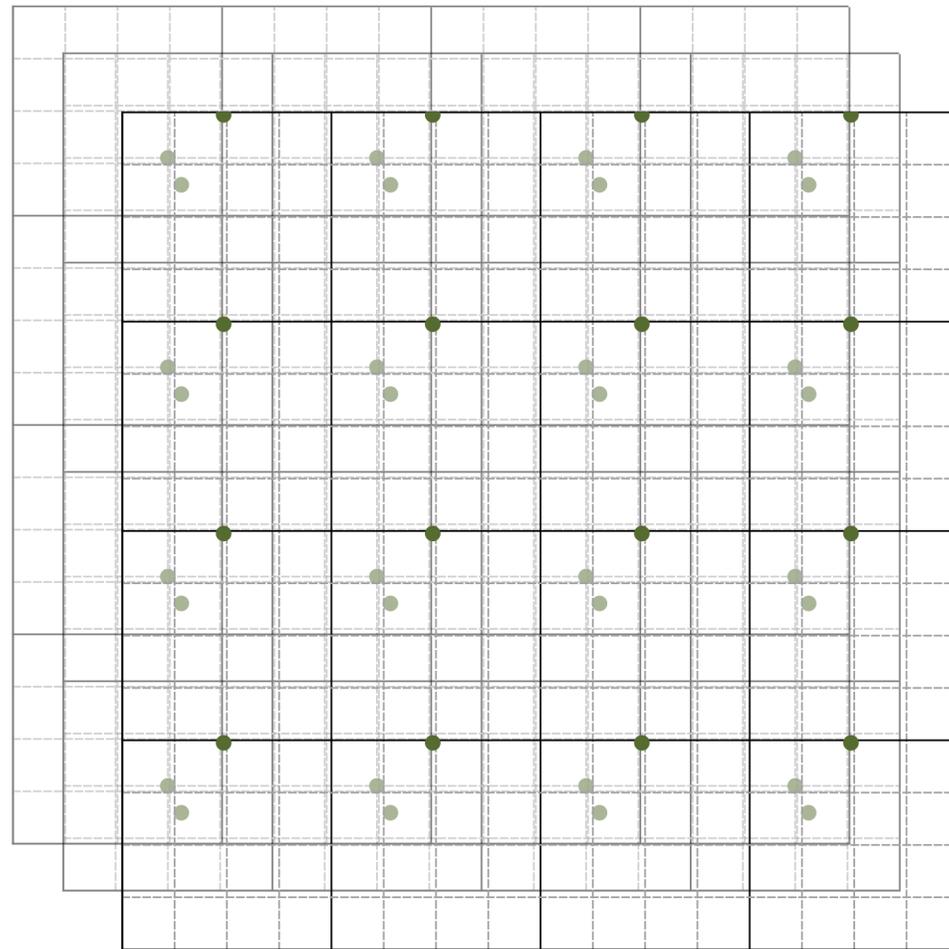


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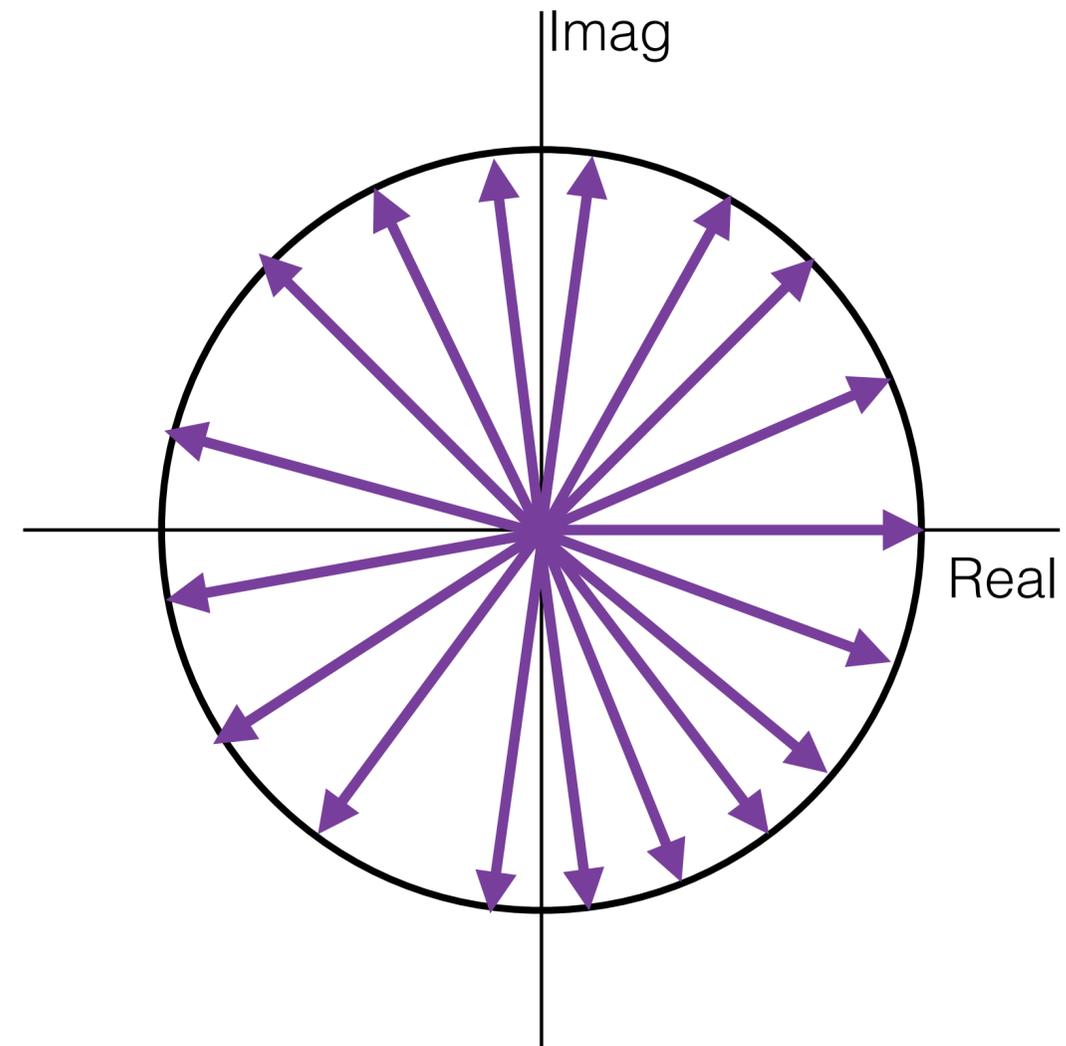


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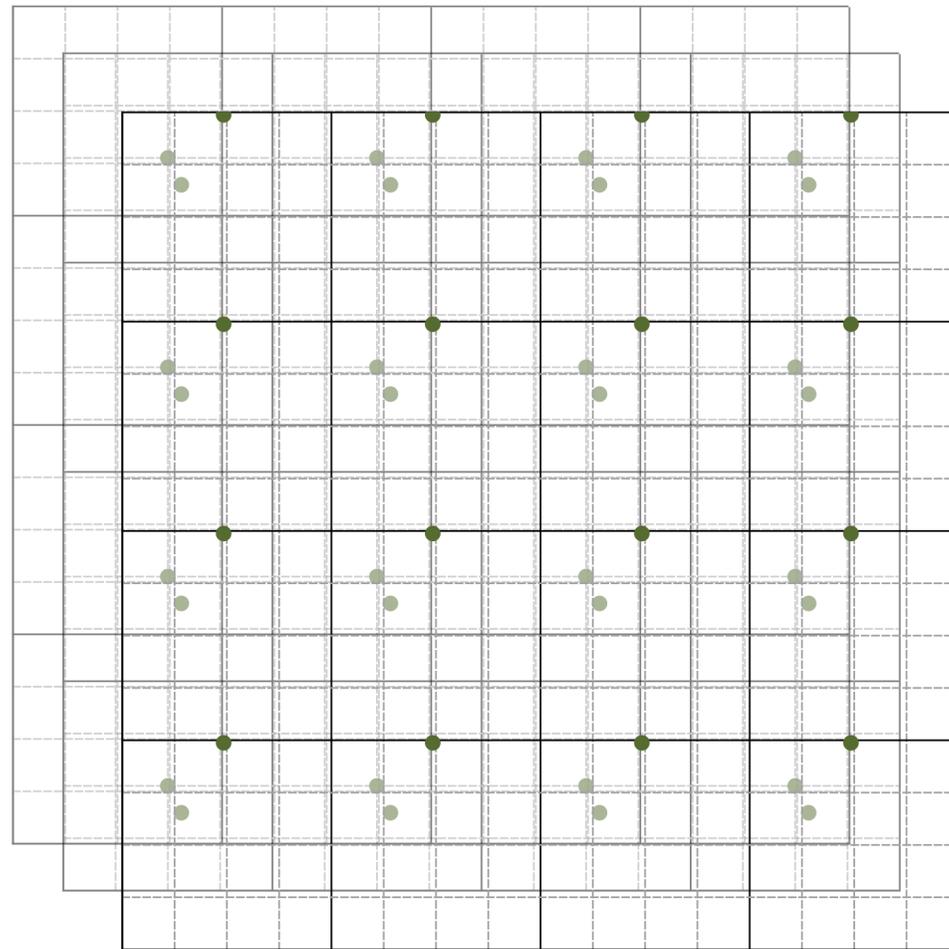


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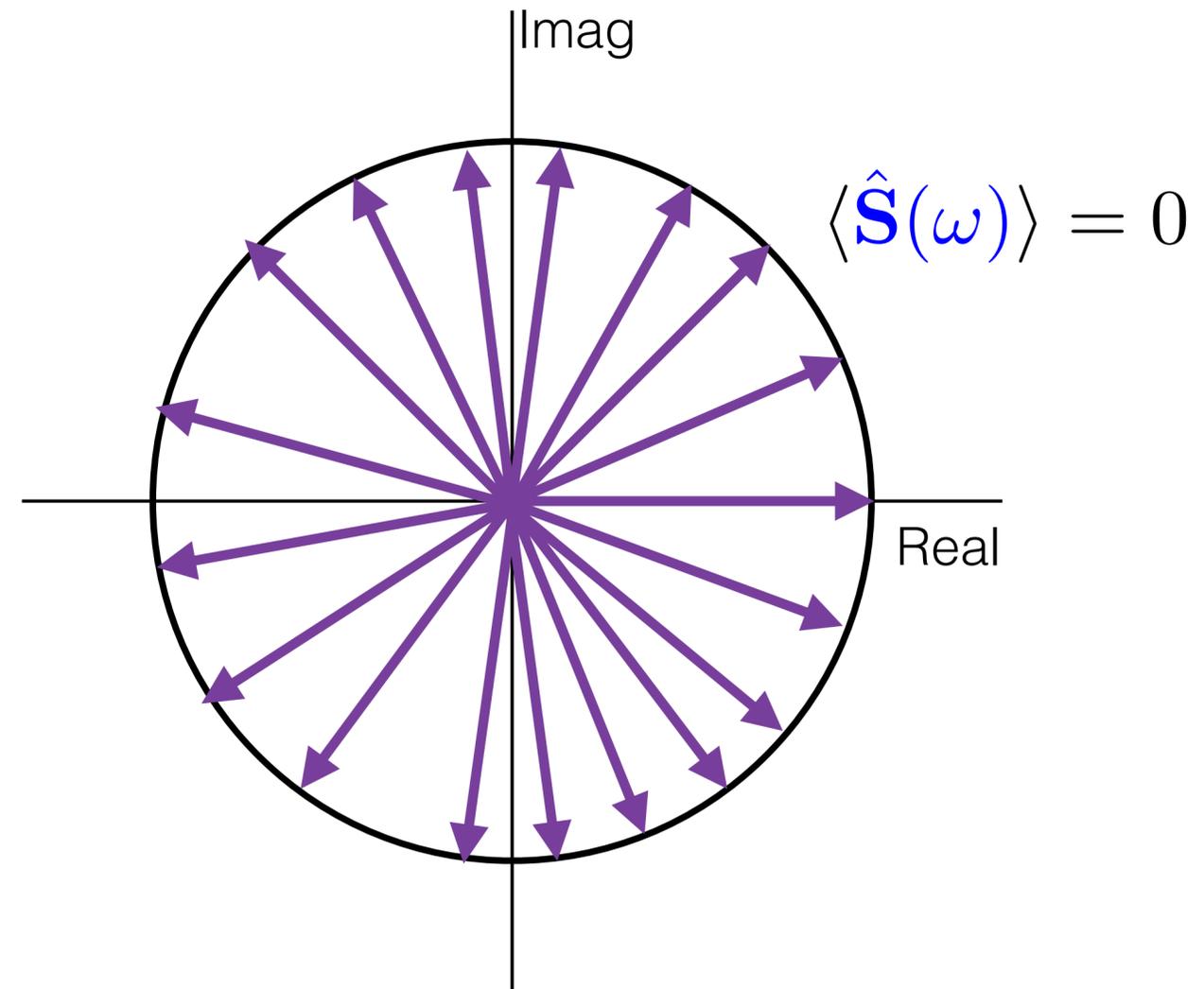


# Phase change due to Random Shift

Multiple realizations

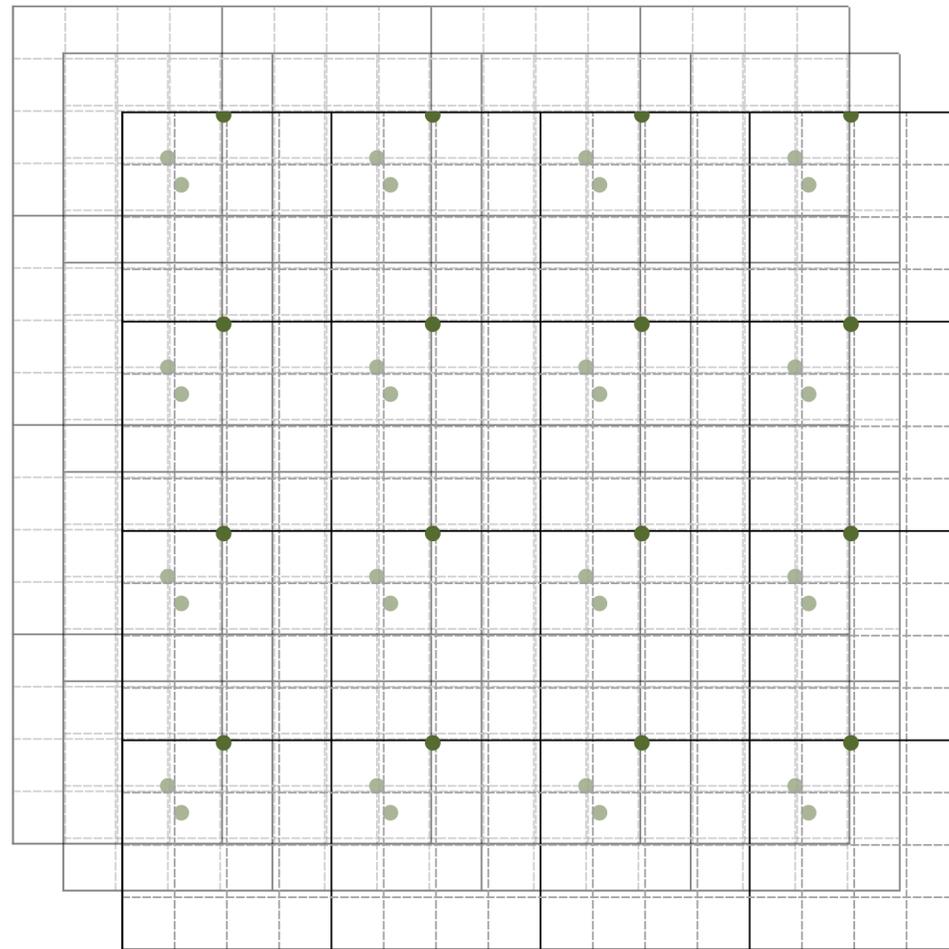


For a given frequency  $\omega$

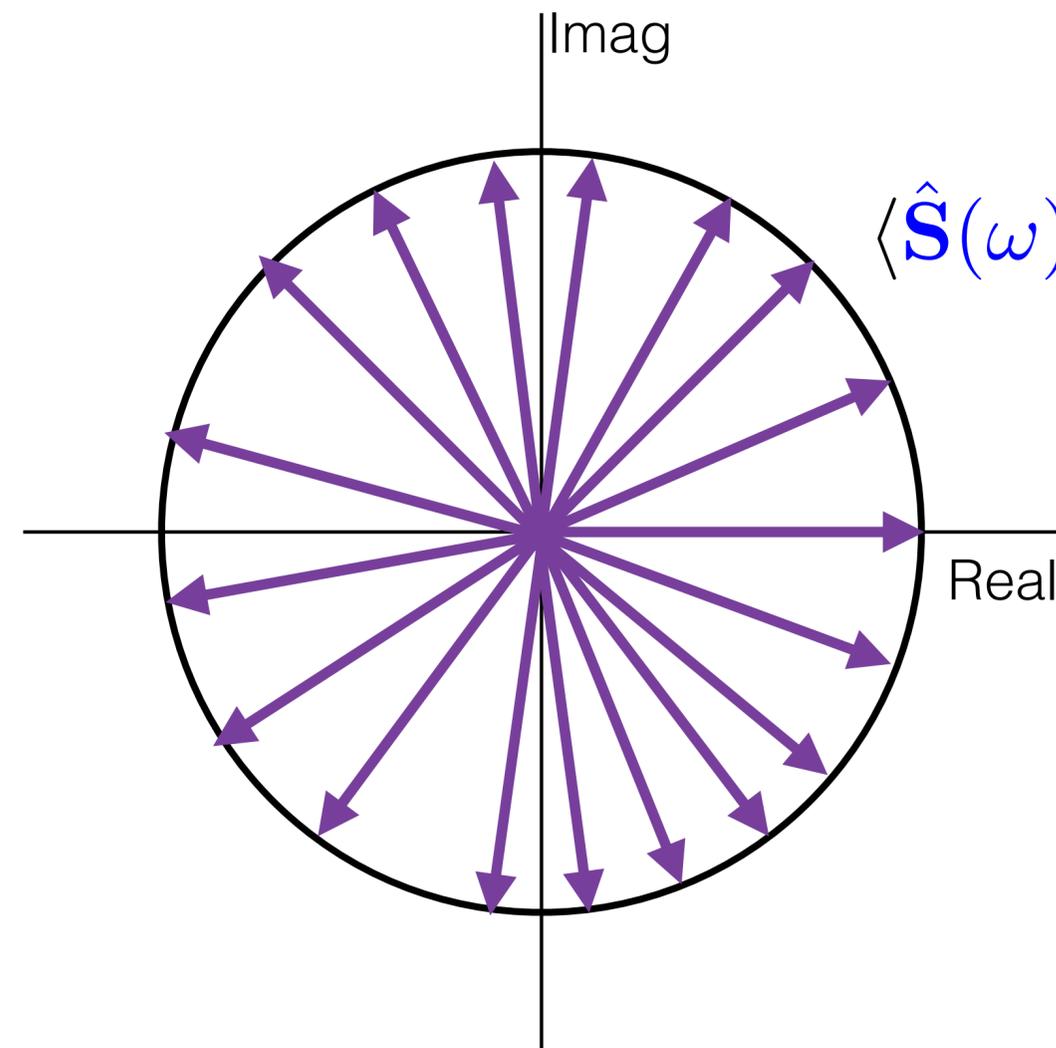


# Phase change due to Random Shift

Multiple realizations



For a given frequency  $\omega$



$$\langle \hat{S}(\omega) \rangle = 0 \quad \forall \omega \neq 0$$

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- Homogenization allows representation of error only in terms of variance
- We can take any sampling pattern and homogenize it to make the Monte Carlo estimator unbiased.

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where,

$$P_f(\omega) = |\hat{f}^*(\omega)|^2 \quad \text{Power Spectrum}$$

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**Subr and Kautz [2013]**

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This is a general form, both for homogenised as well as non-homogenised sampling patterns

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**Pilleboue et al. [2015]**

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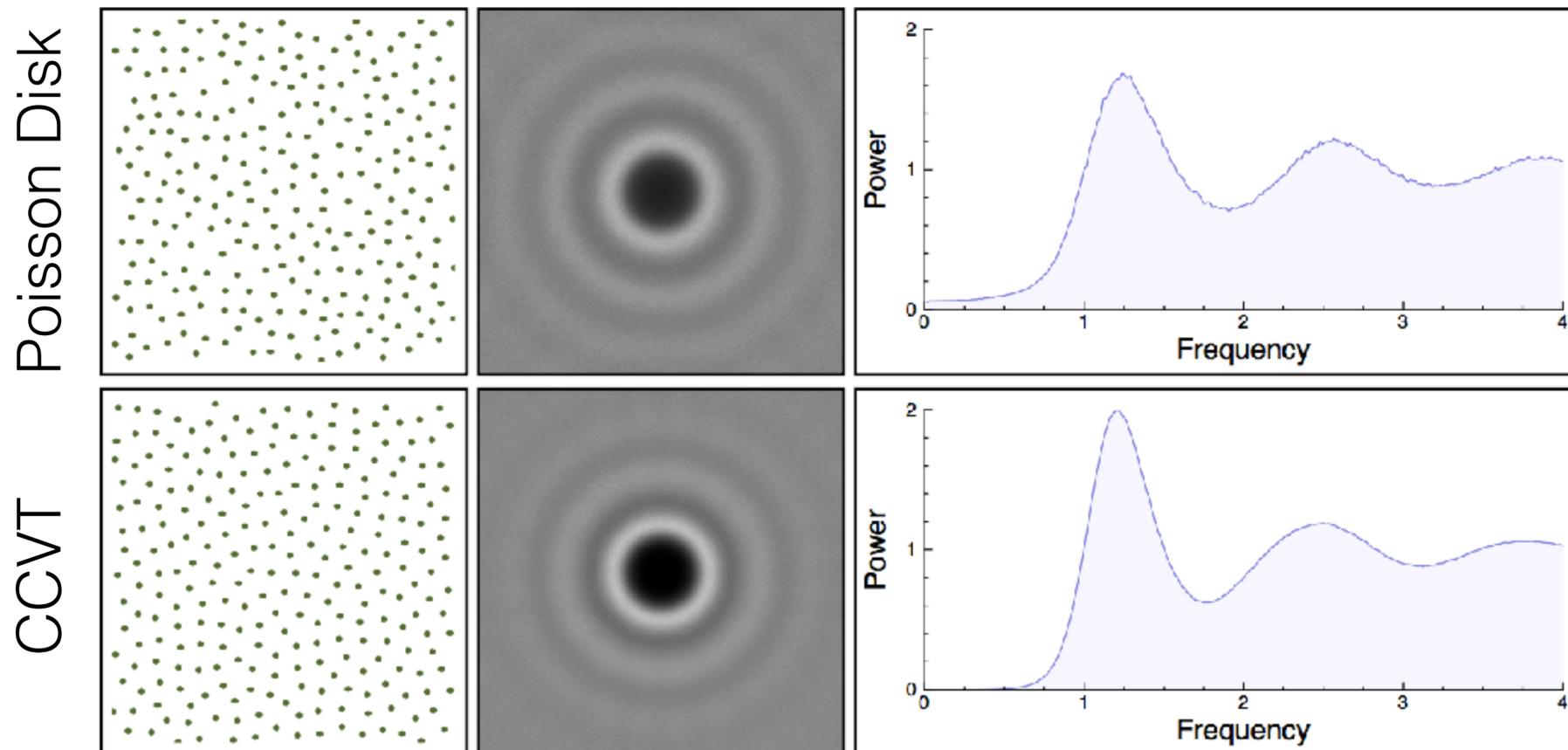
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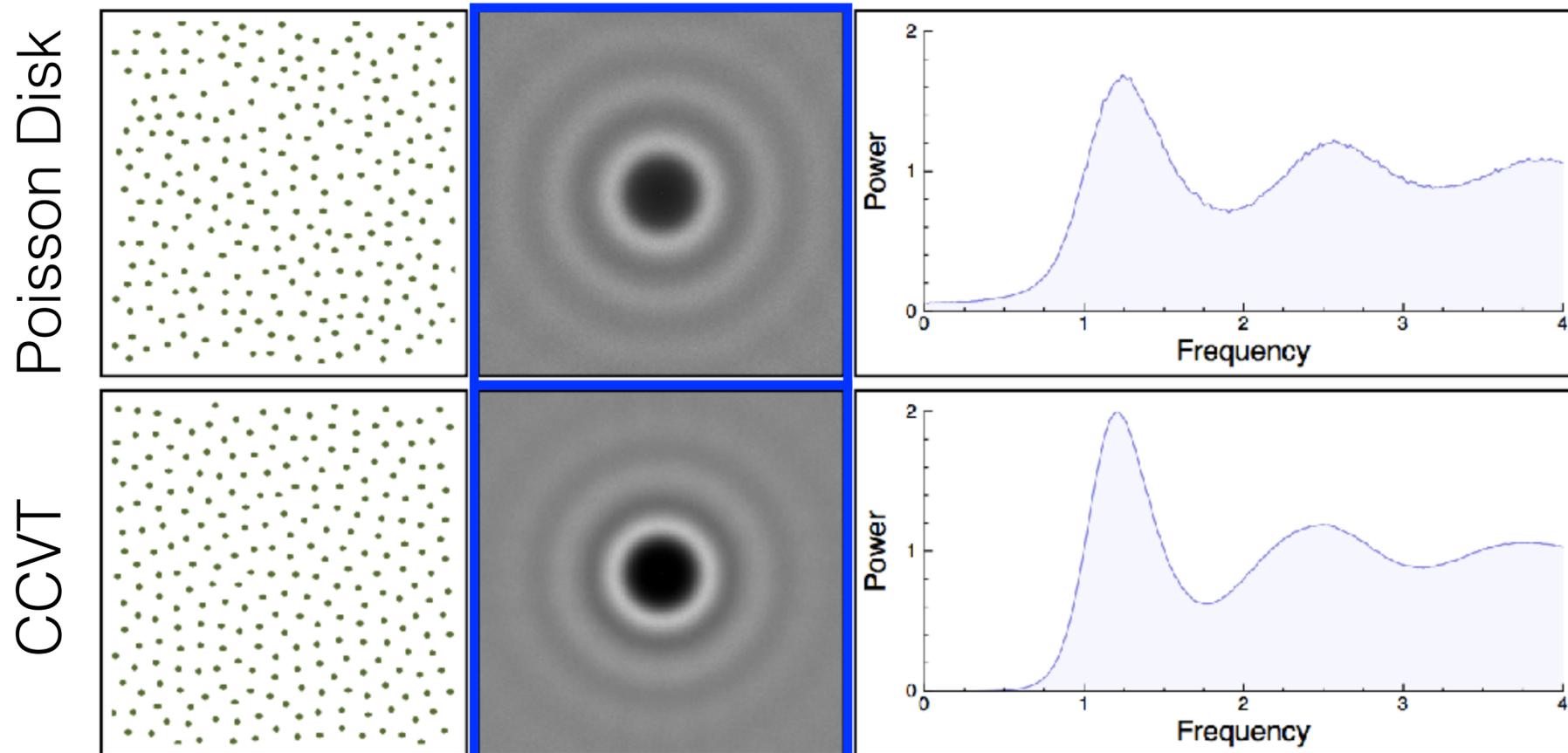
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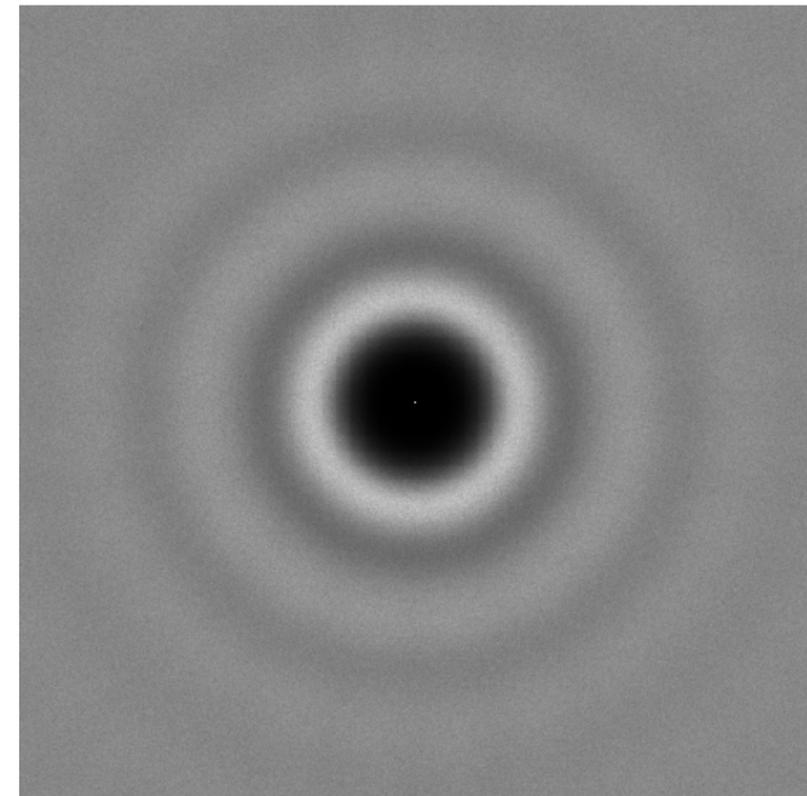
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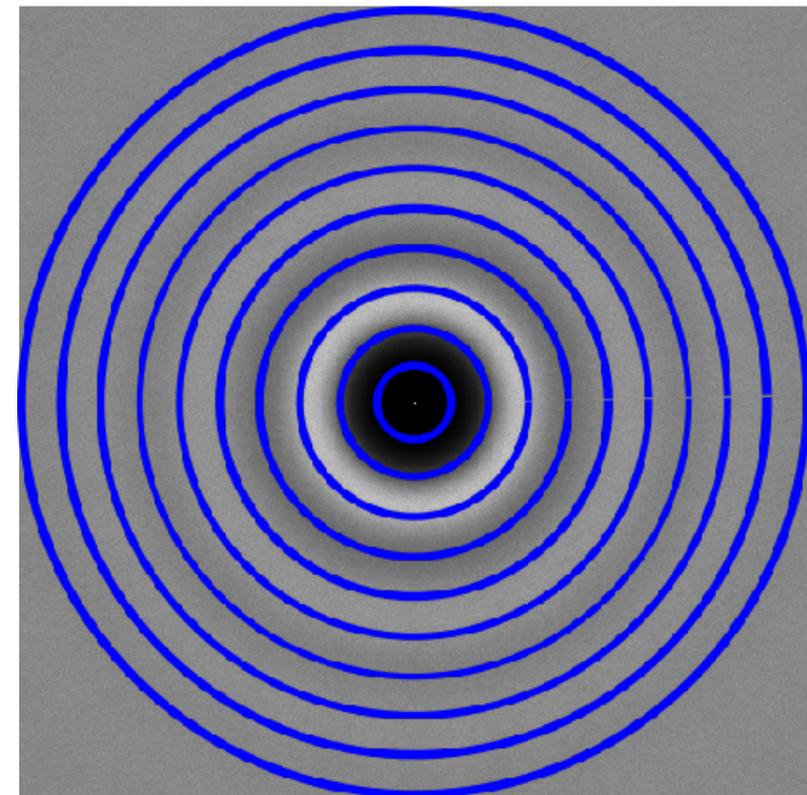
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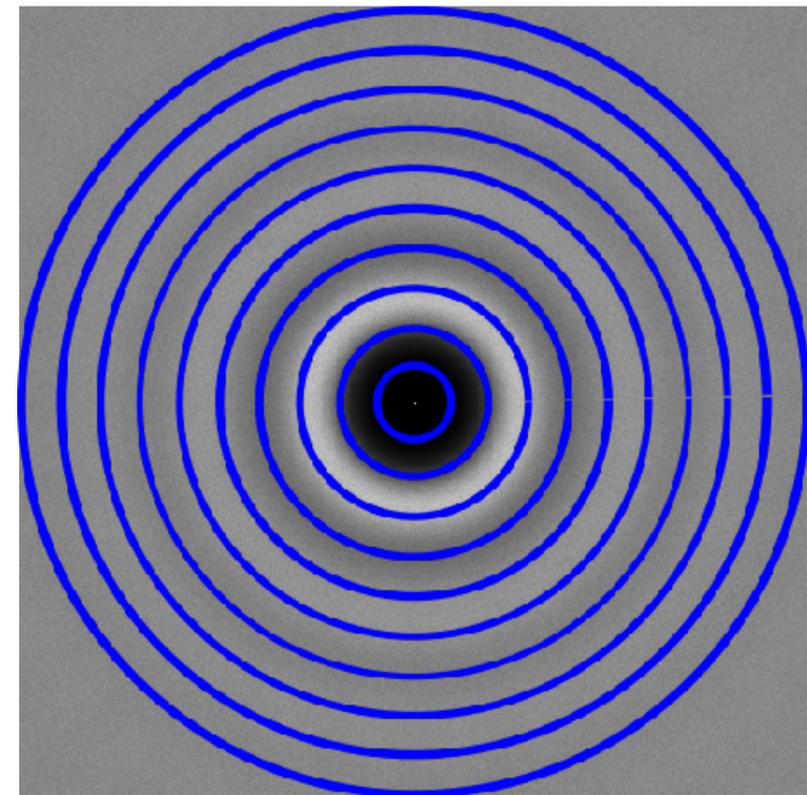


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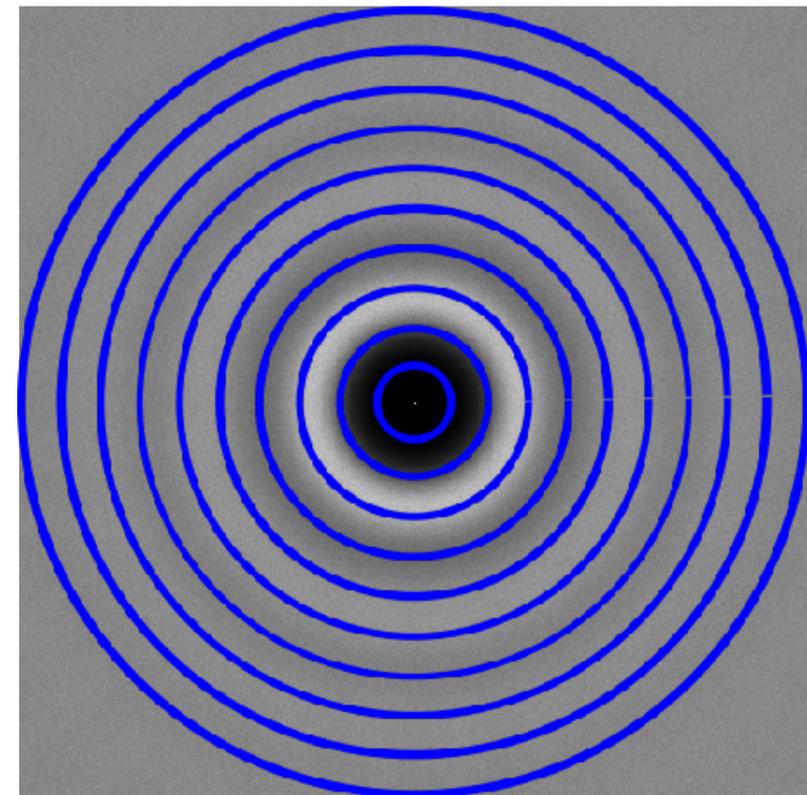


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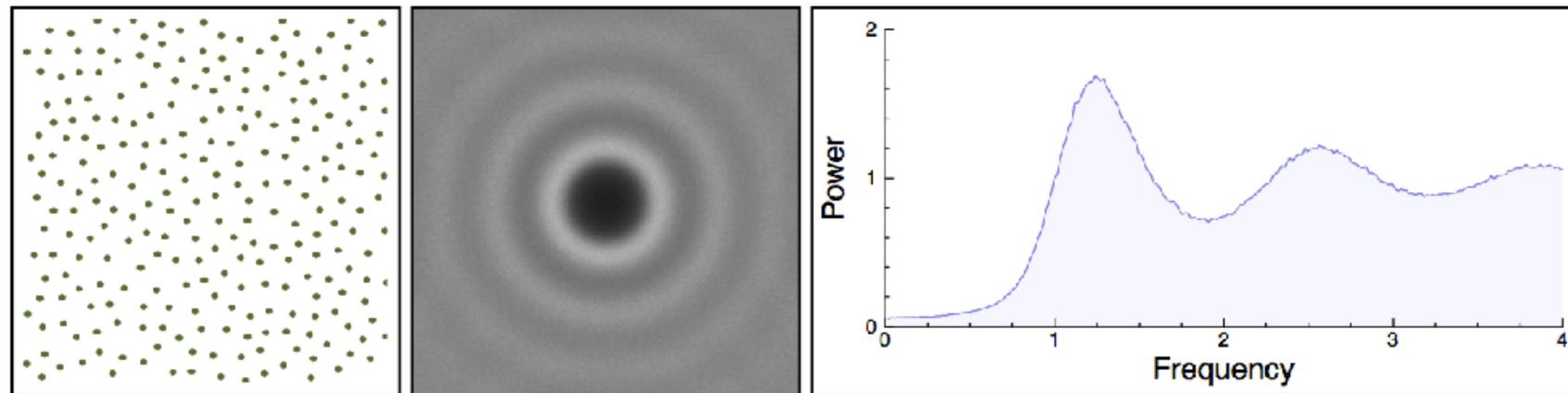
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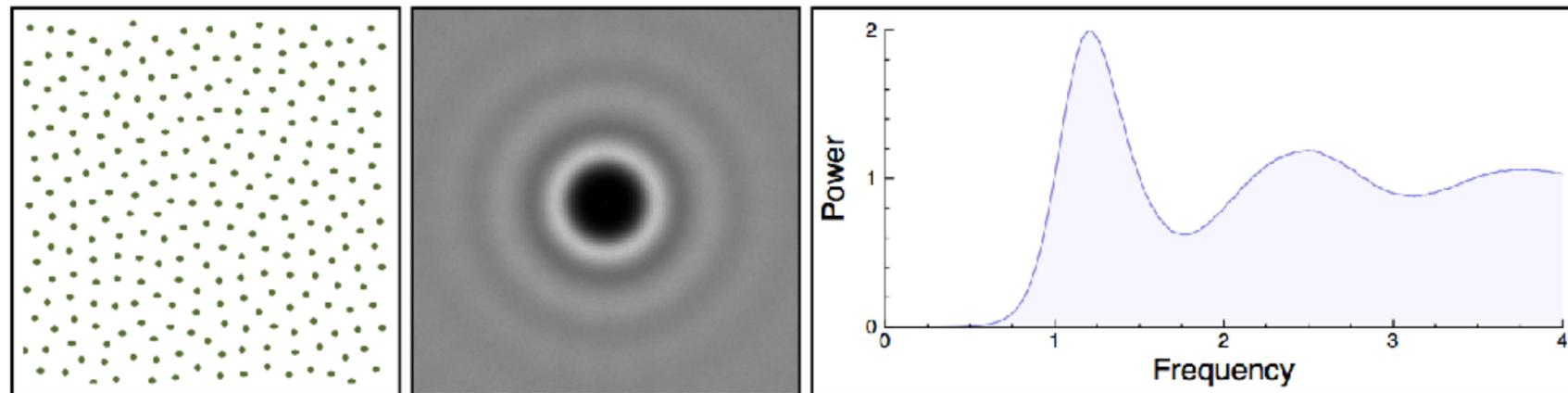
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Poisson Disk

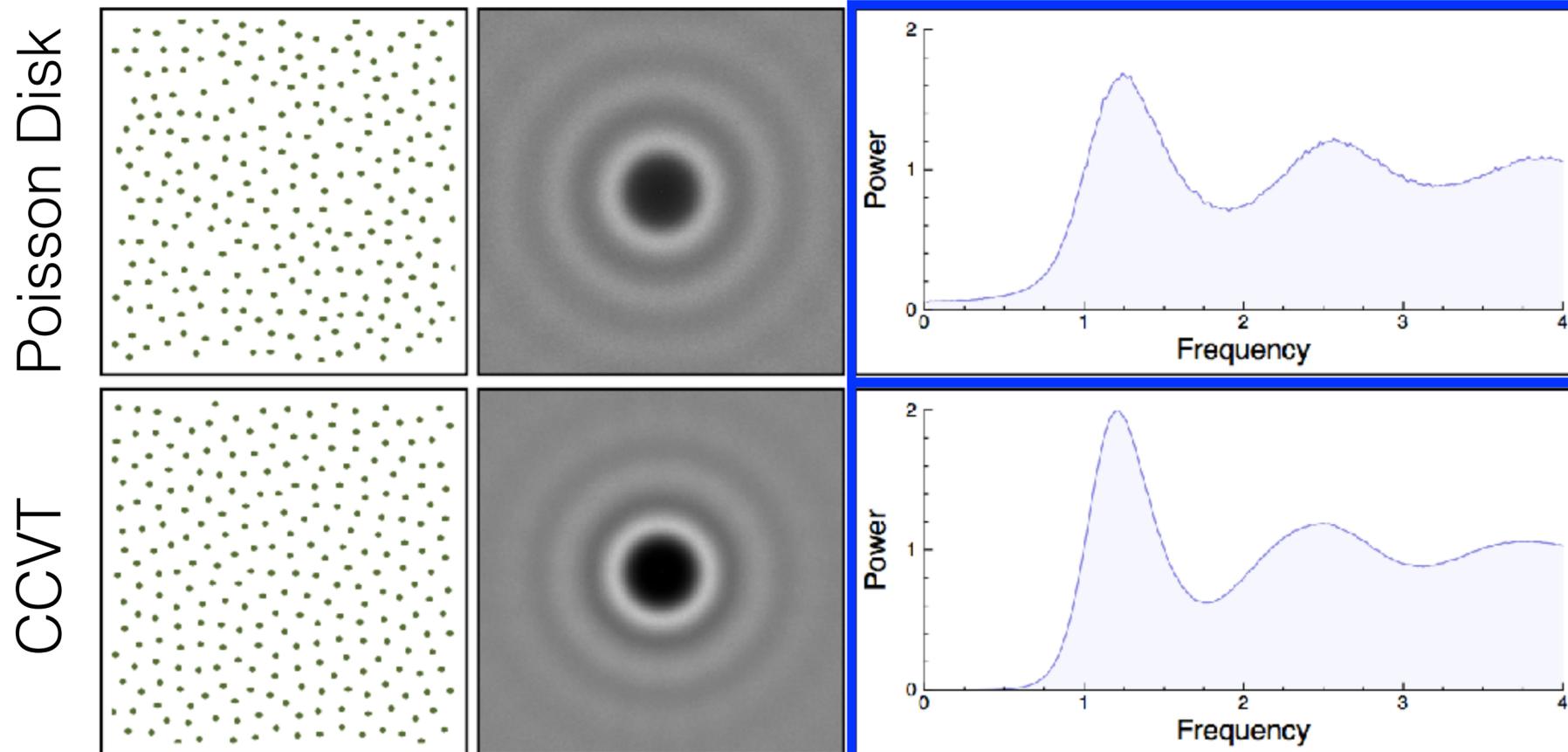


CCVT



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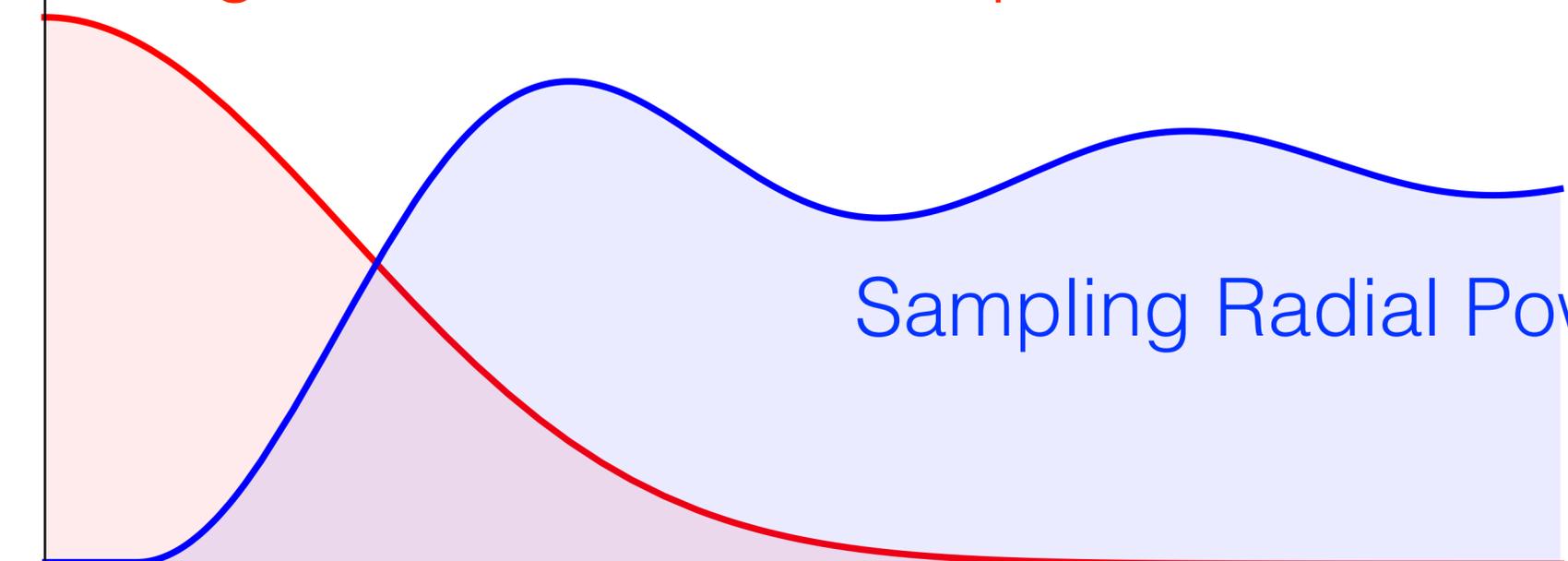
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Integrand Radial Power Spectrum



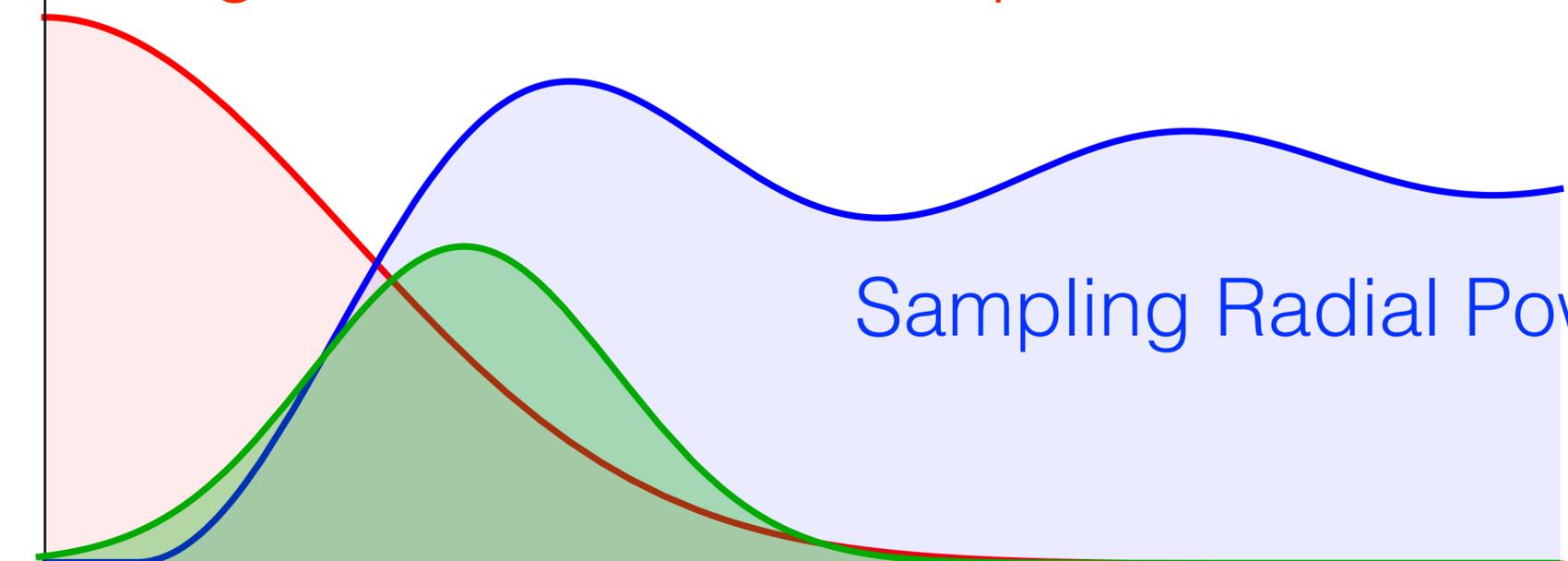
Sampling Radial Power Spectrum

For given number of Samples

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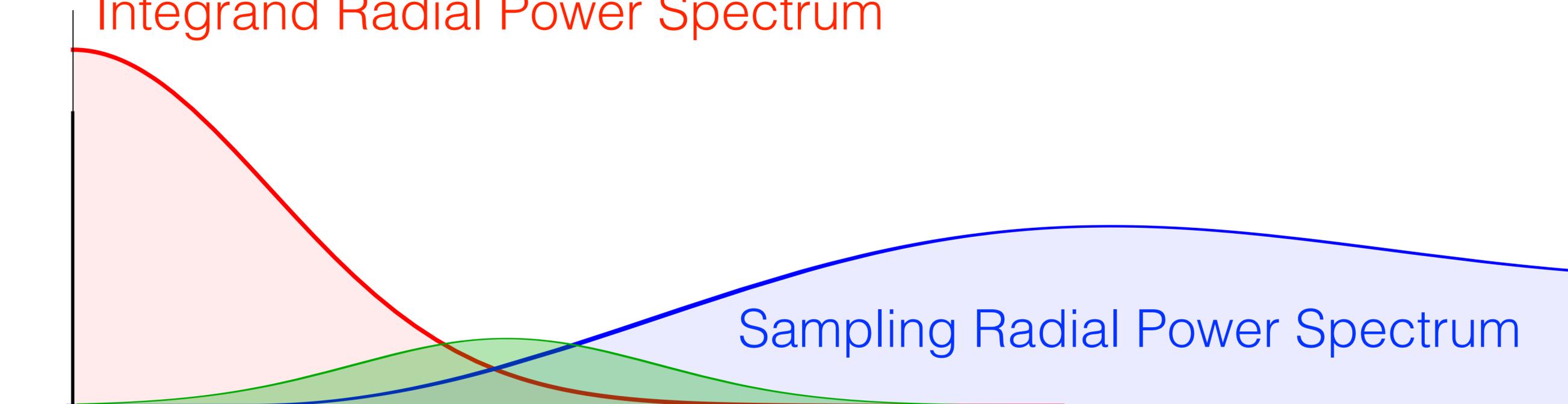
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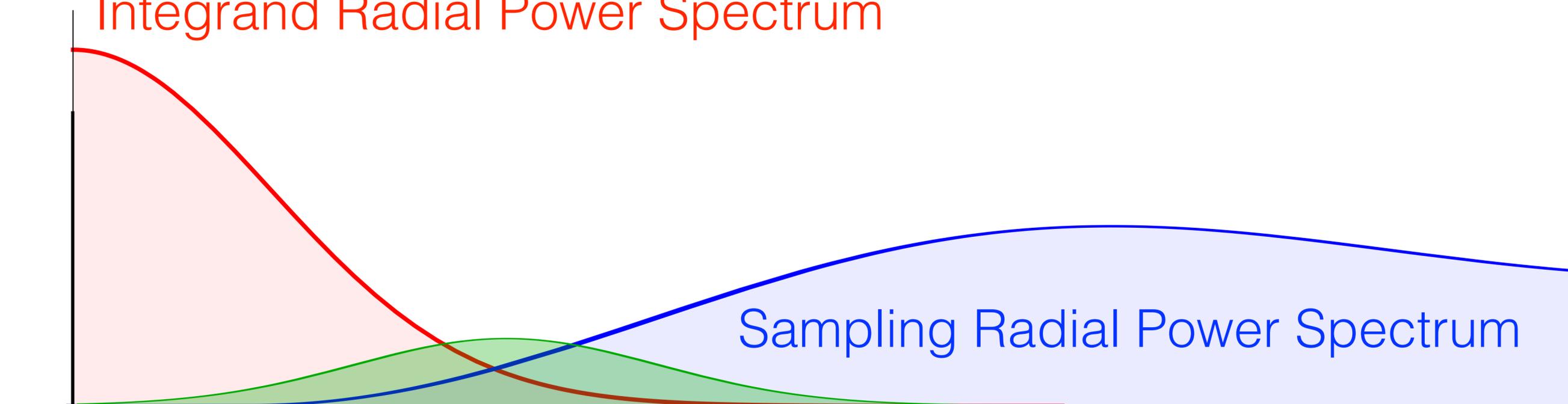


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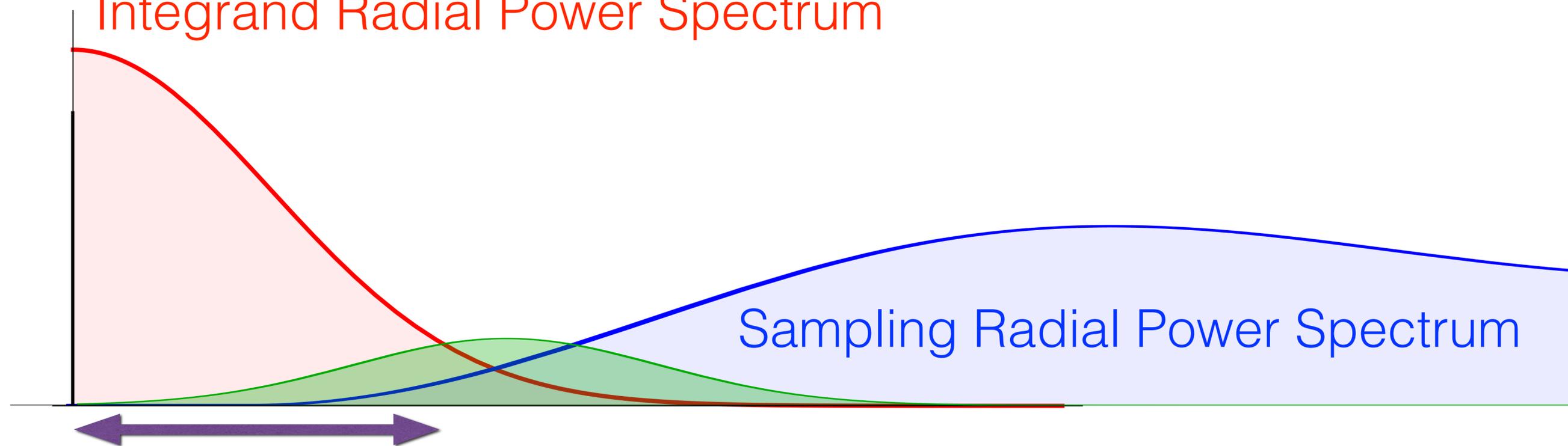


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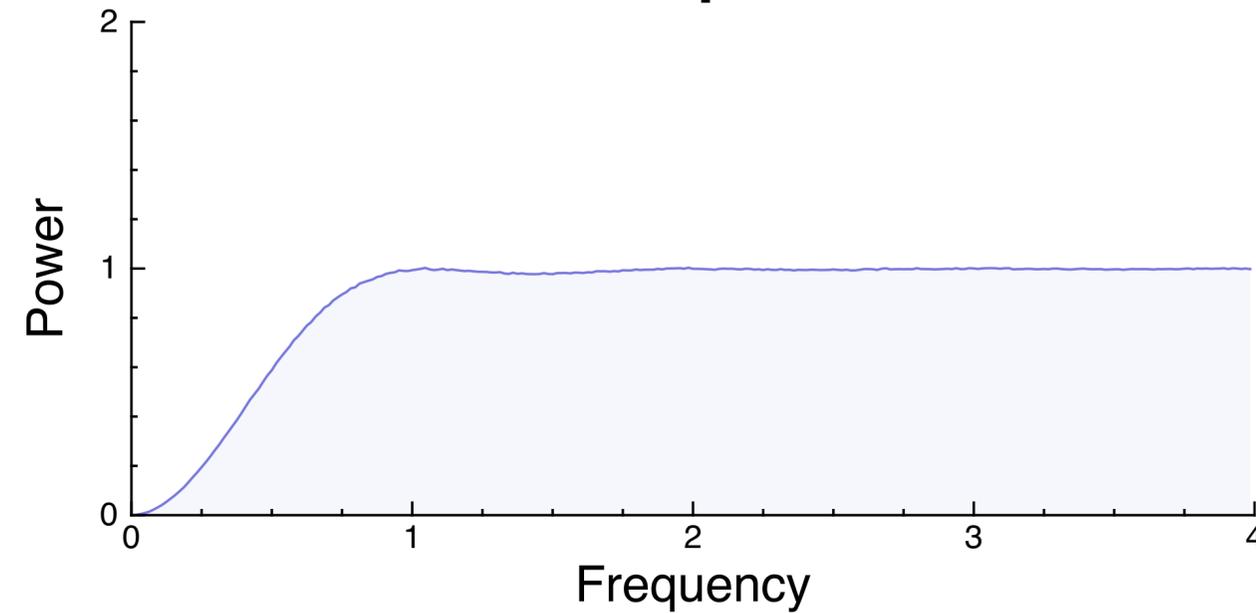
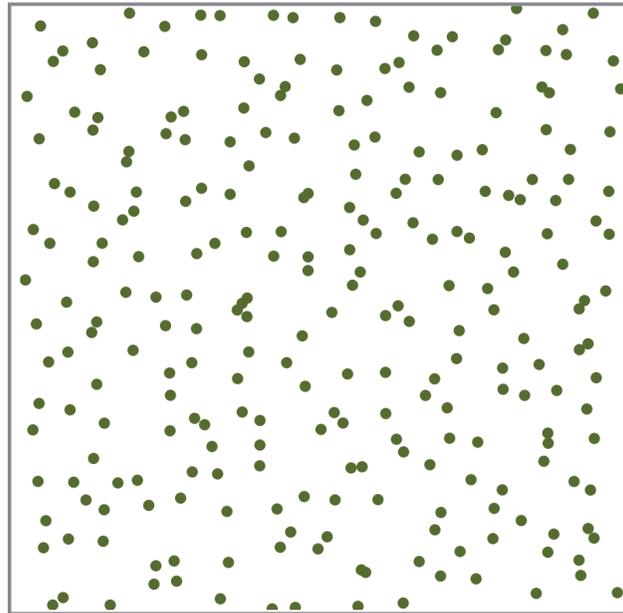
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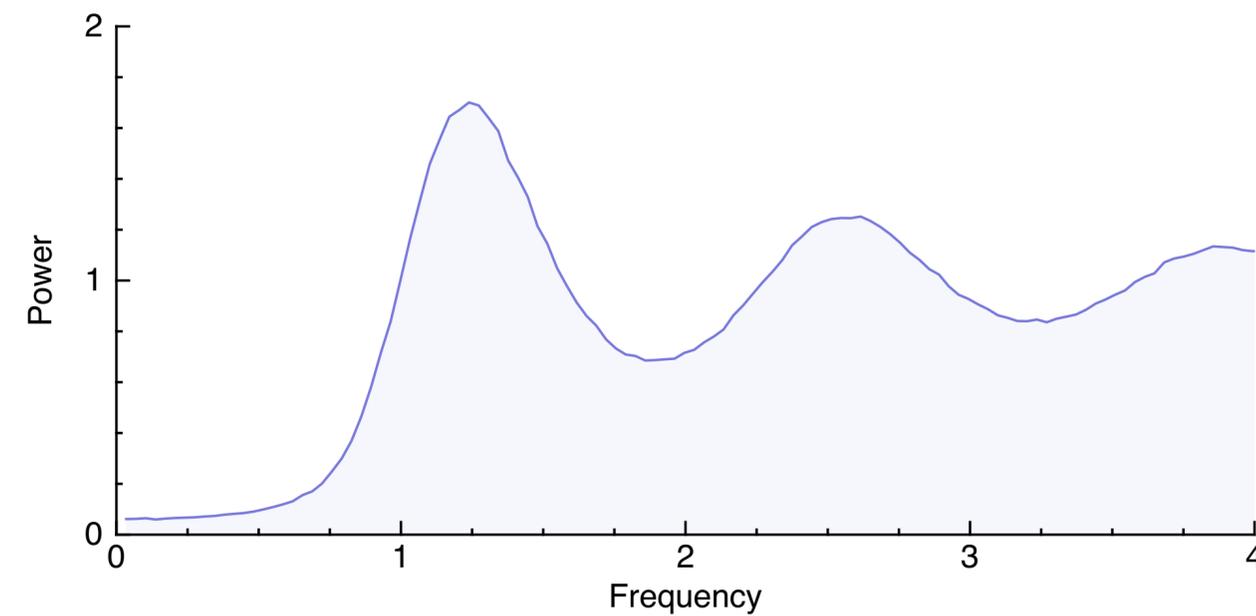
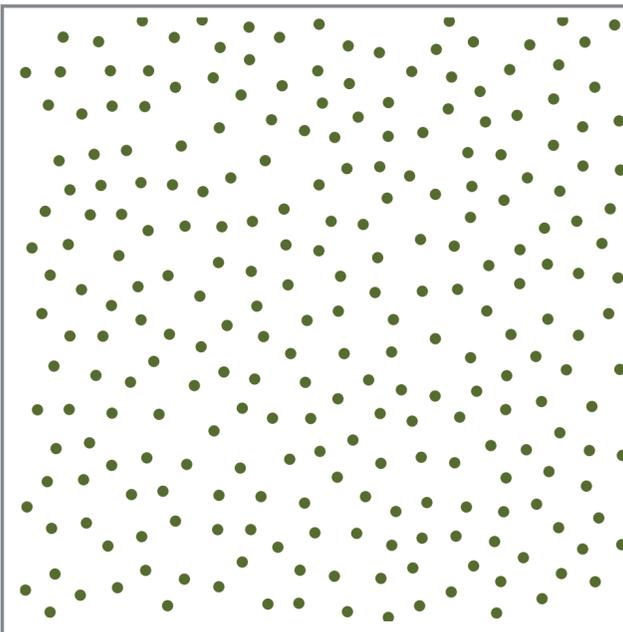
For given number of Samples

# Spatial Distribution vs Radial Mean Power Spectra

Jitter



Poisson Disk



# For 2-dimensions

Samplers	Worst Case	Best Case
Random		
Jitter		
Poisson Disk		
CCVT		

**Pilleboue et al. [2015]**

# For 2-dimensions

Samplers	Worst Case	Best Case
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# For 2-dimensions

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Jitter	$\mathcal{O}(N^{-1.5})$	
Poisson Disk		
CCVT		

**Pilleboue et al. [2015]**

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Poisson Disk	$\mathcal{O}(N^{-1})$	$\mathcal{O}(N^{-1})$
CCVT	$\mathcal{O}(N^{-1.5})$	

**Pilleboue et al. [2015]**

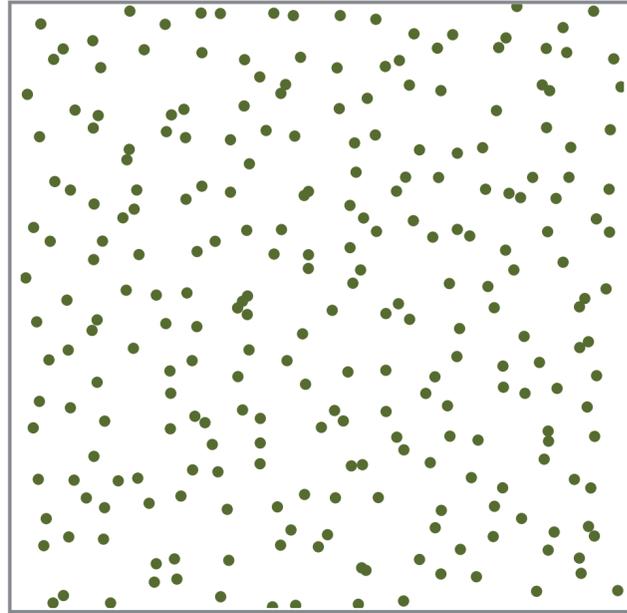
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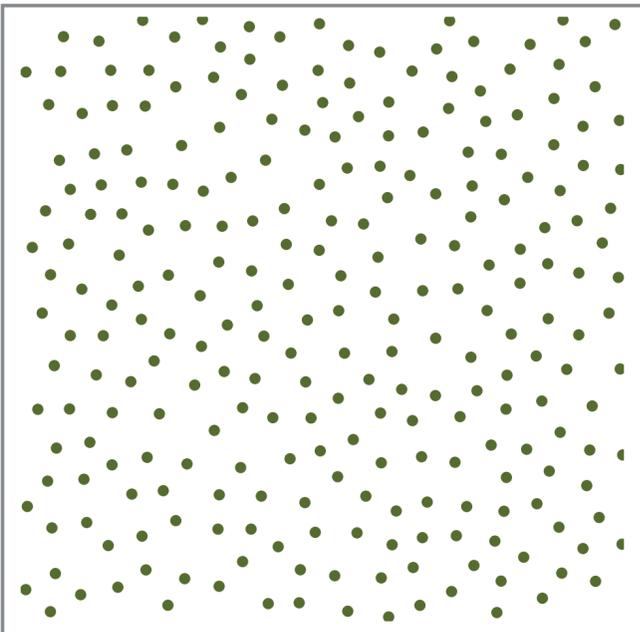
**Pilleboue et al. [2015]**

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Jitter



Poisson Disk

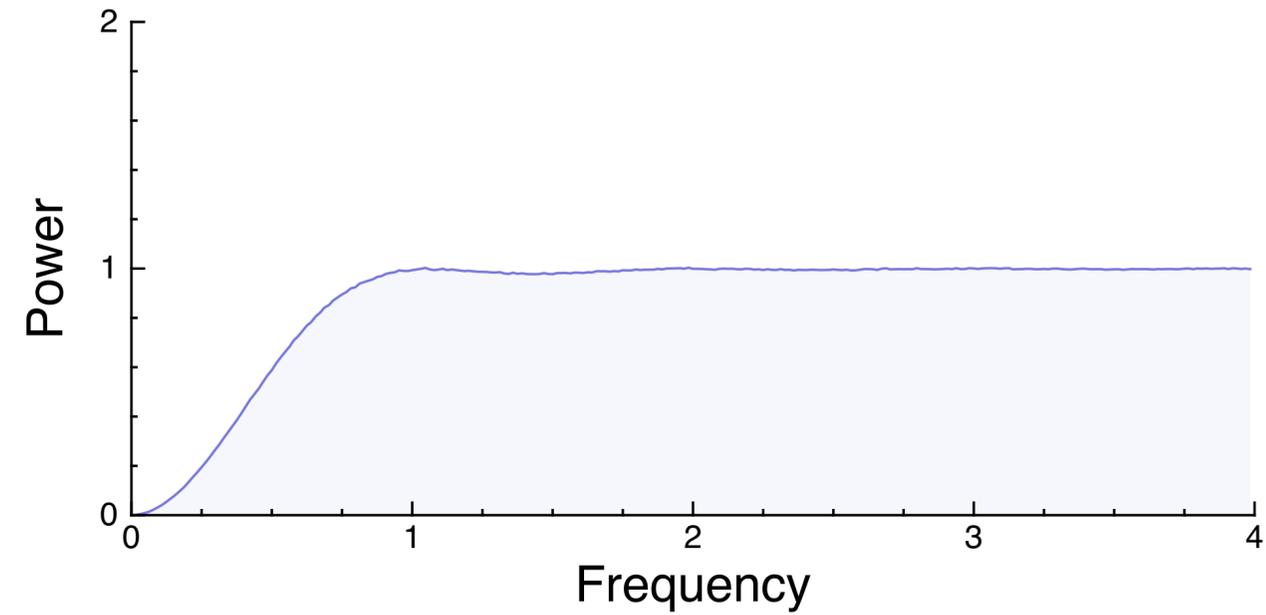


Samplers	Worst Case	Best Case
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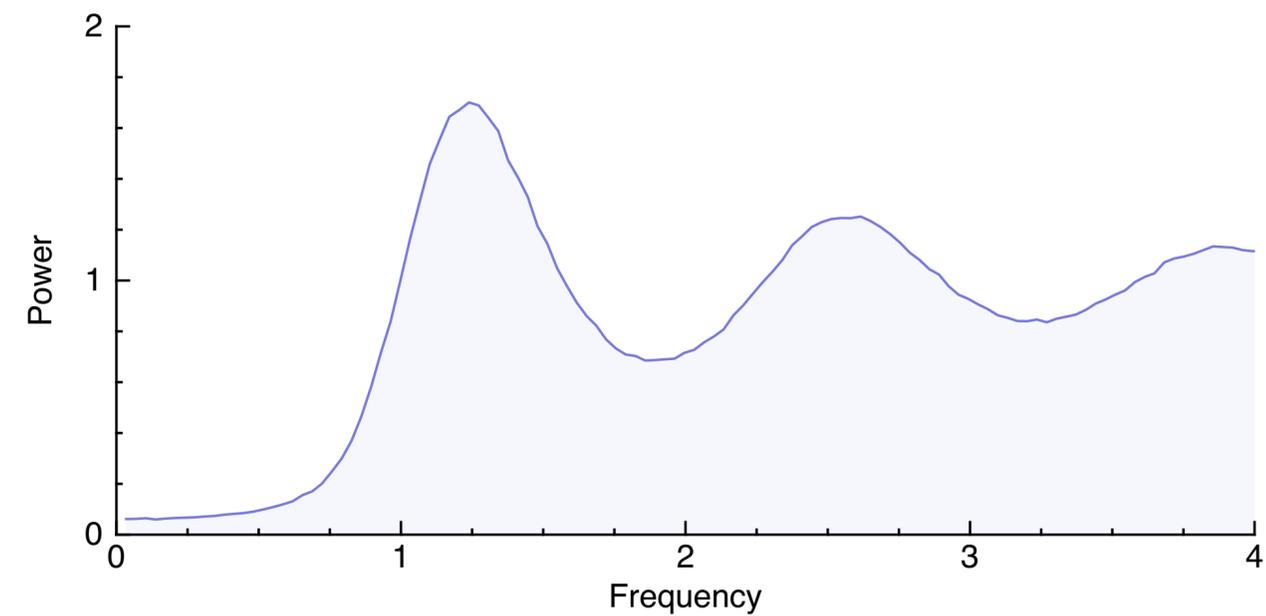
Pilleboue et al. [2015]

# Low Frequency Region

Jitter

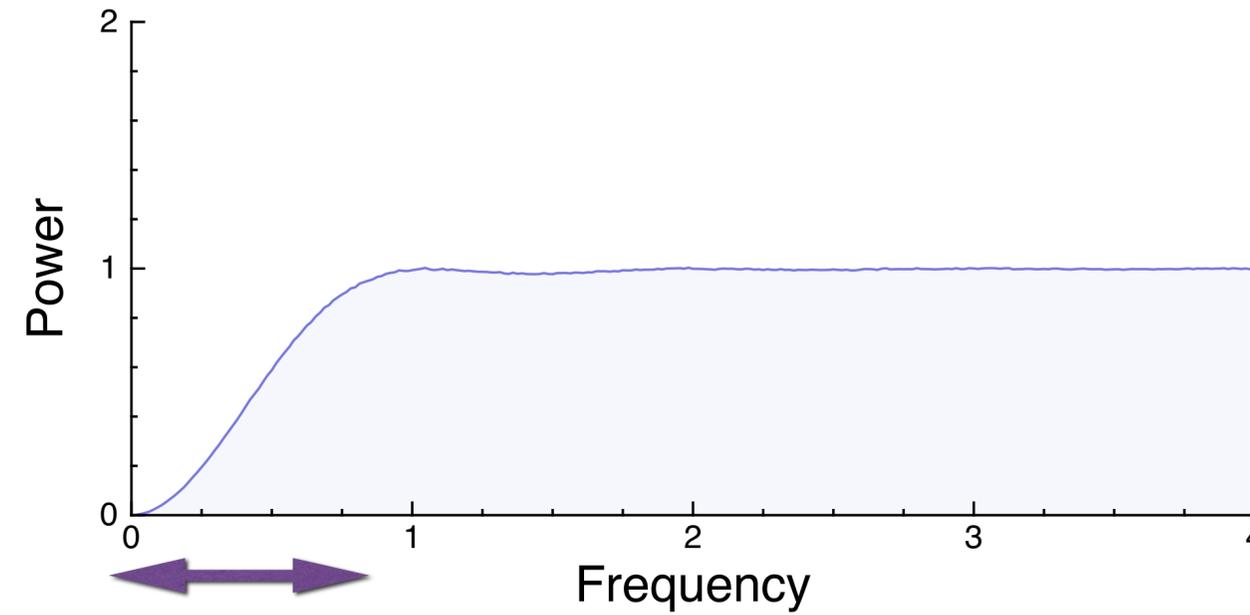


Poisson Disk

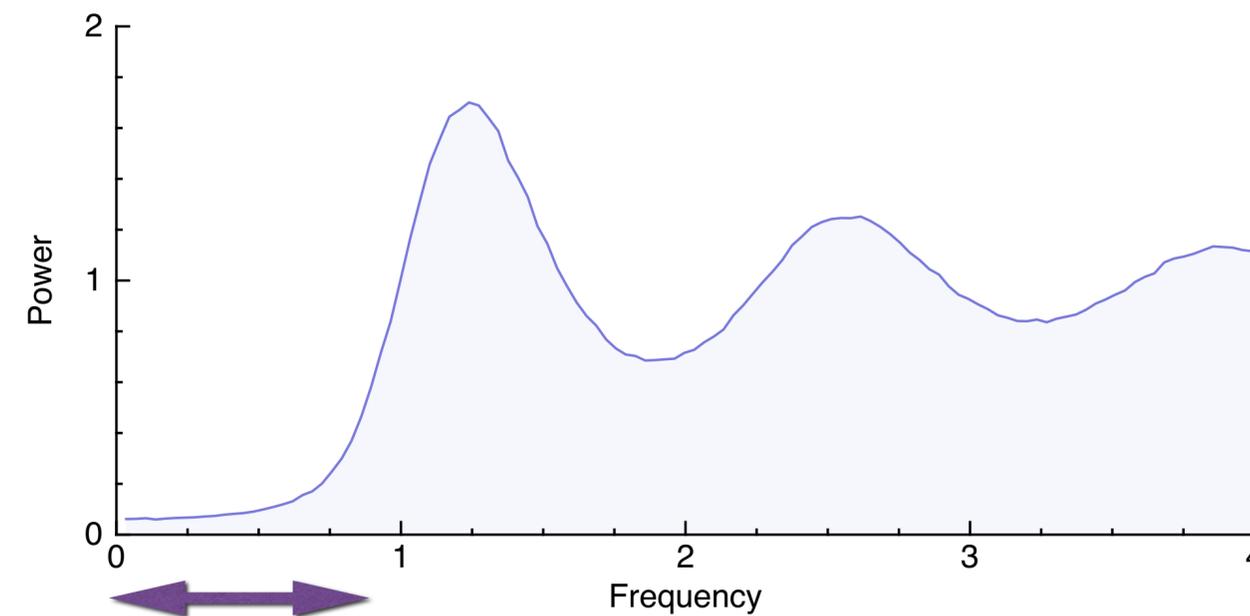


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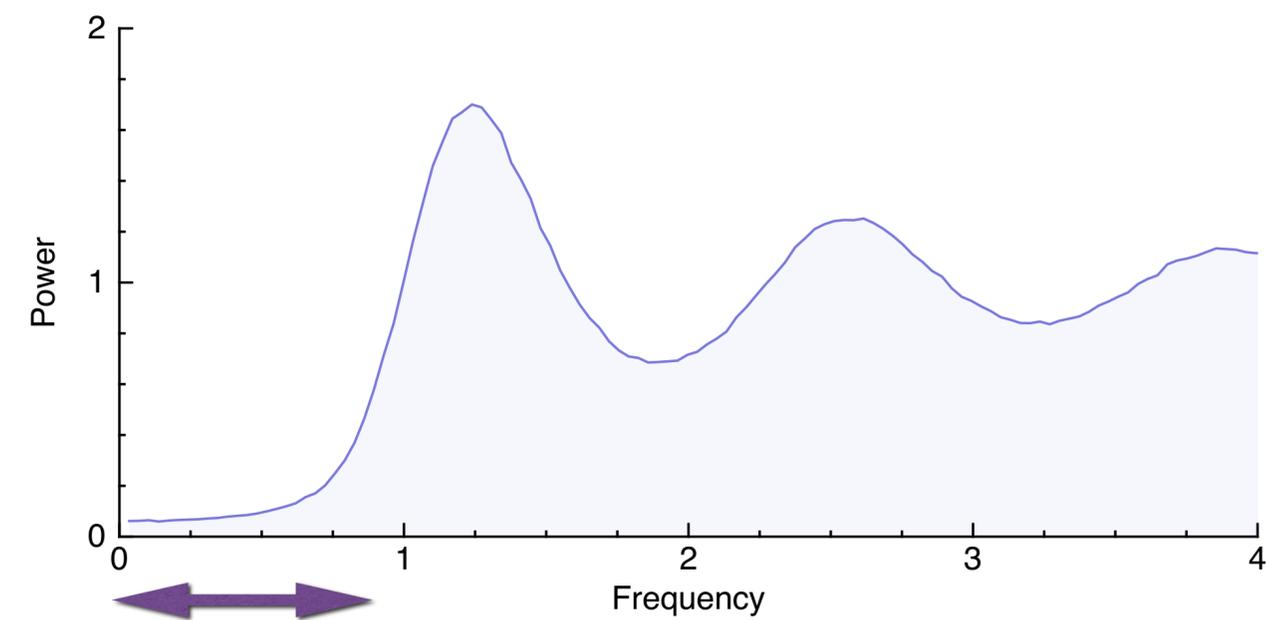
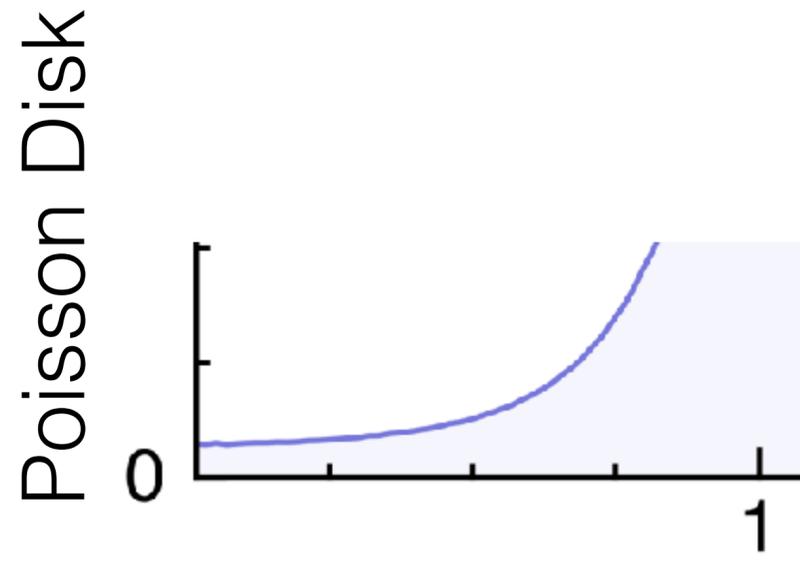
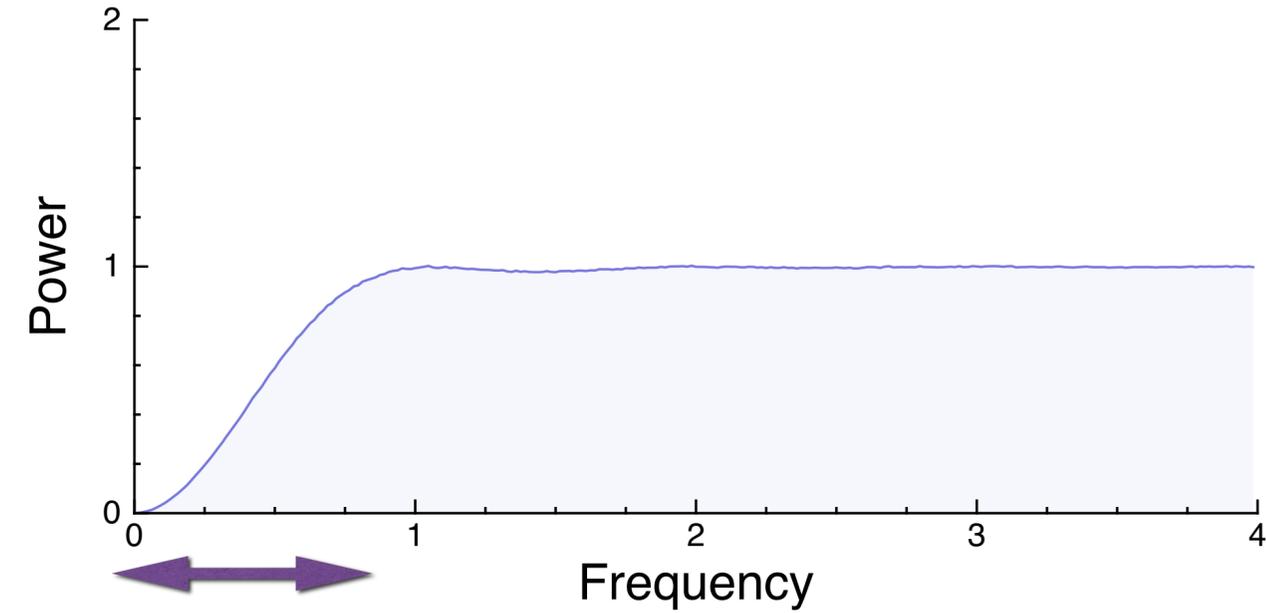
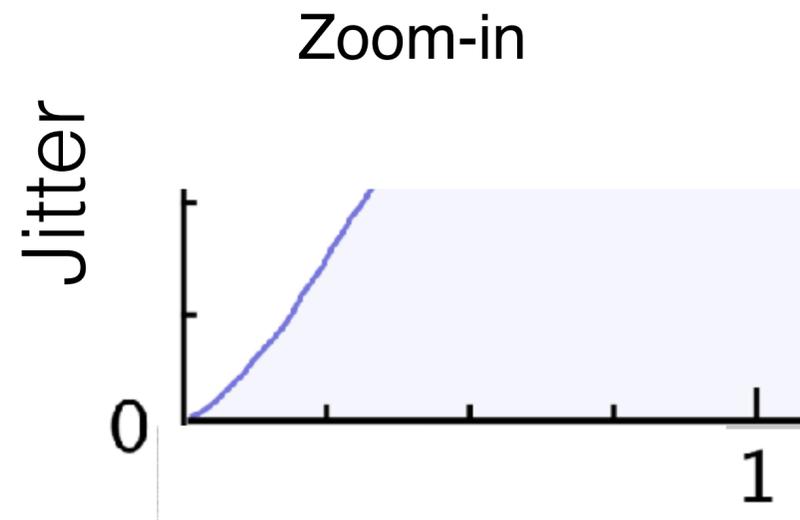
Jitter



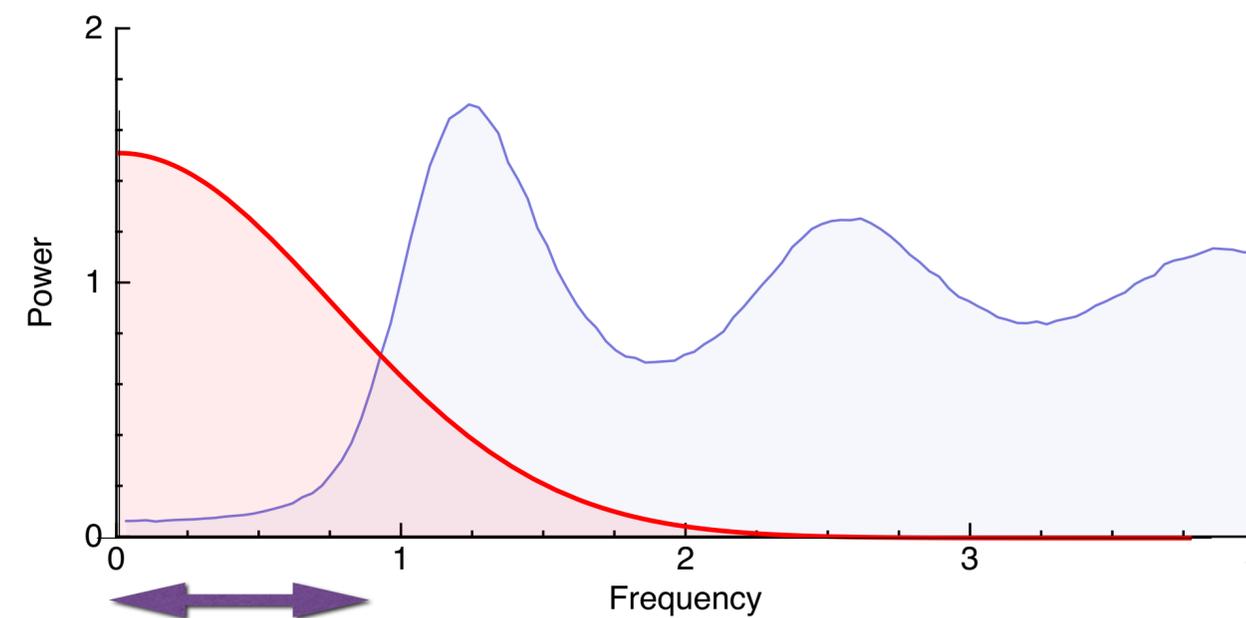
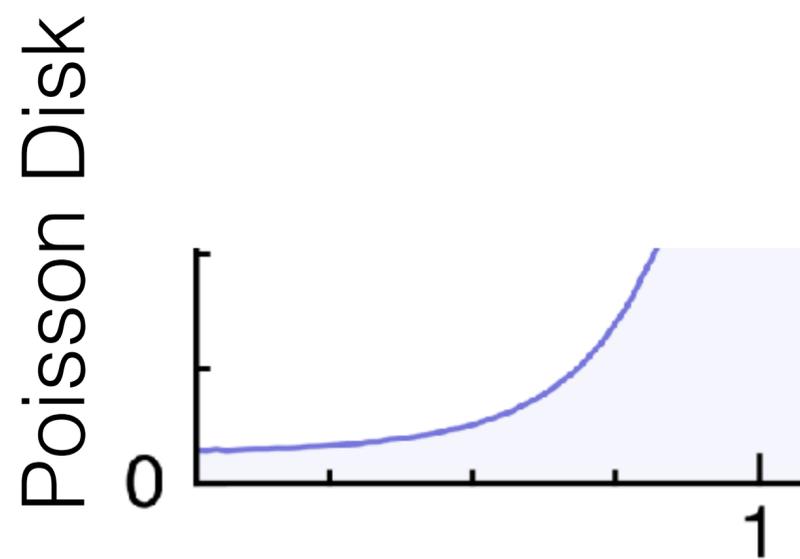
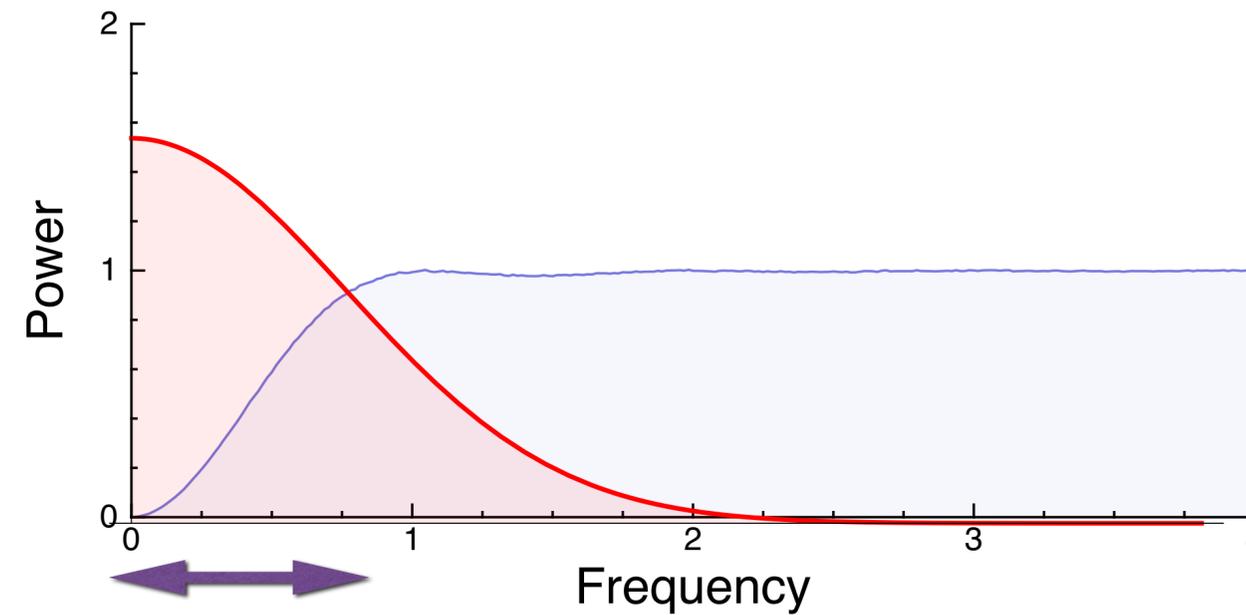
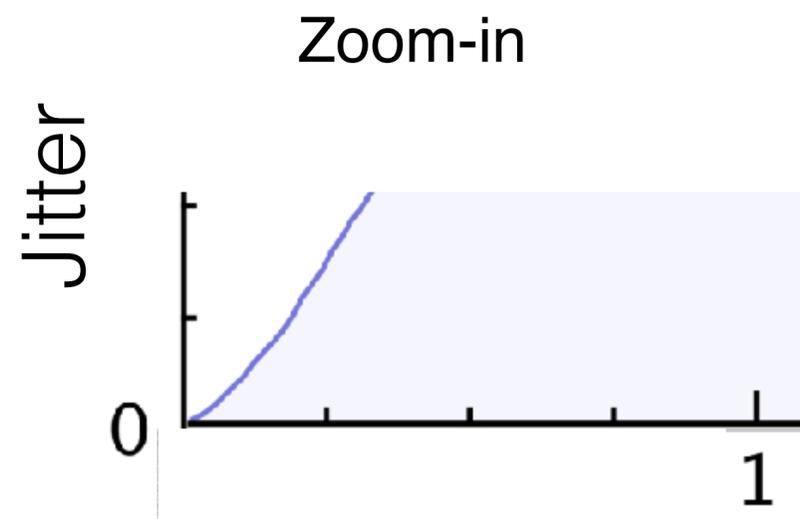
Poisson Disk



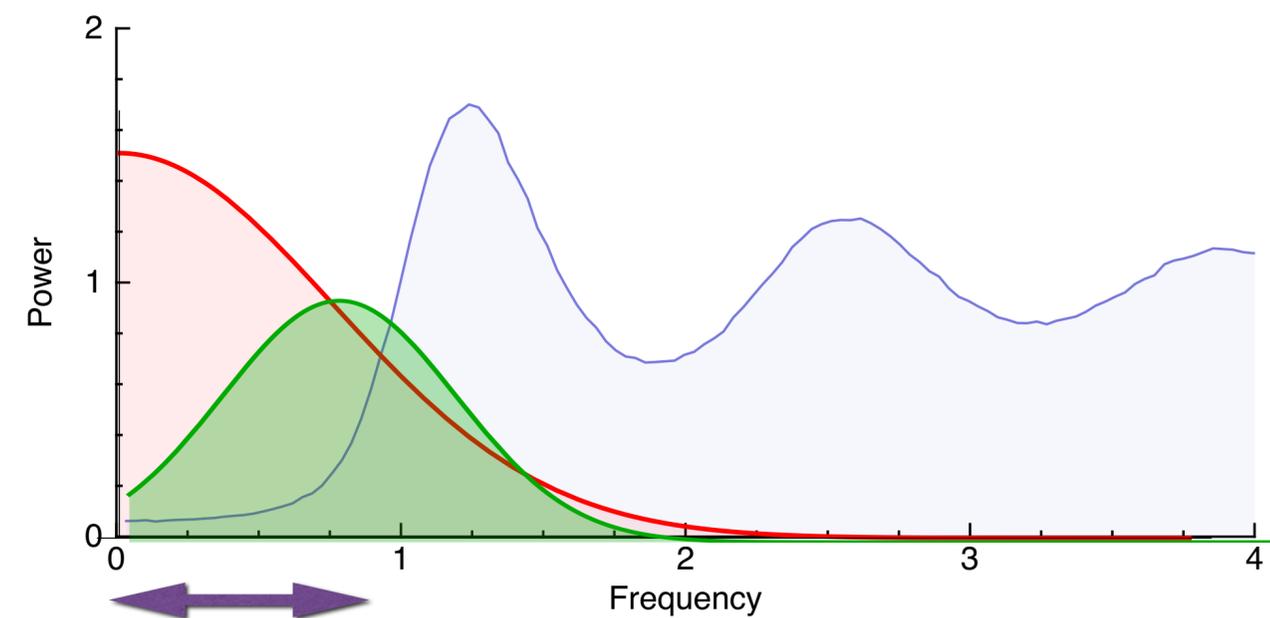
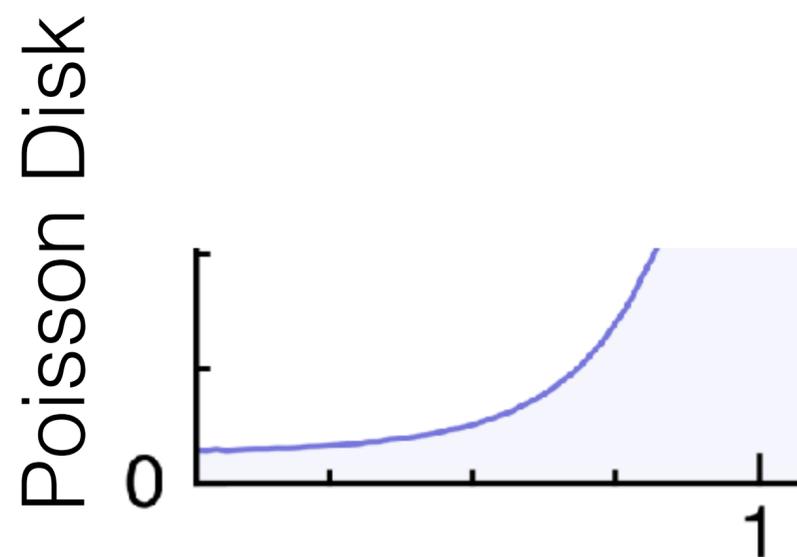
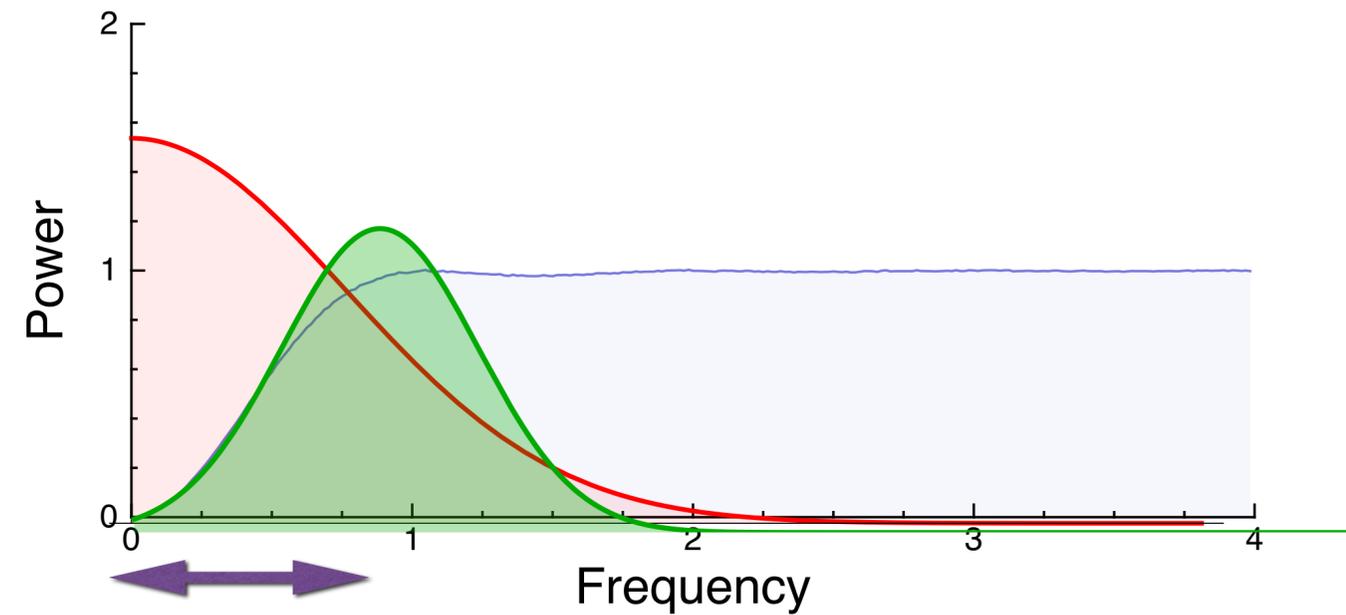
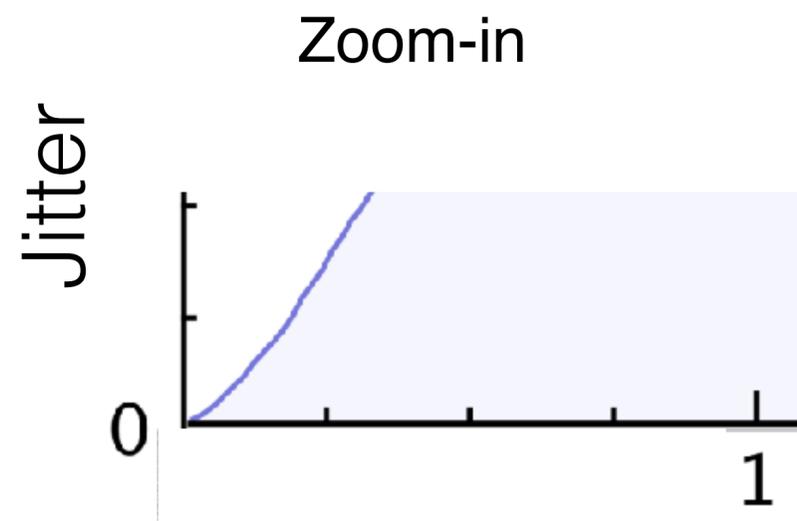
# Low Frequency Region



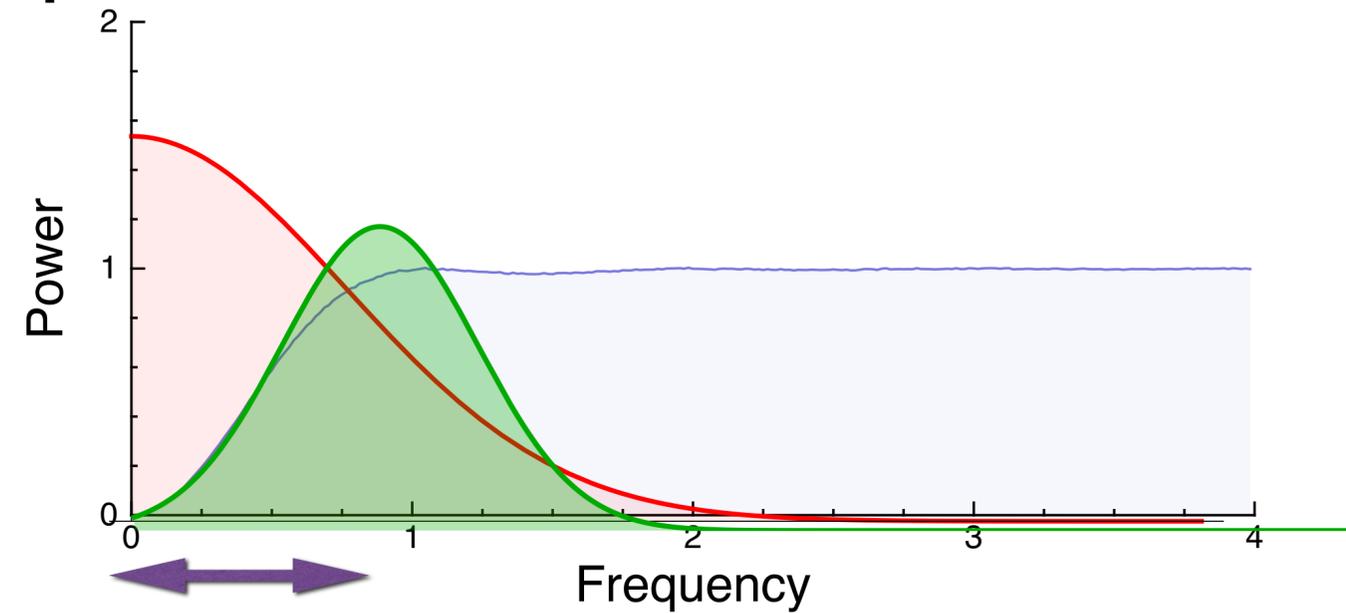
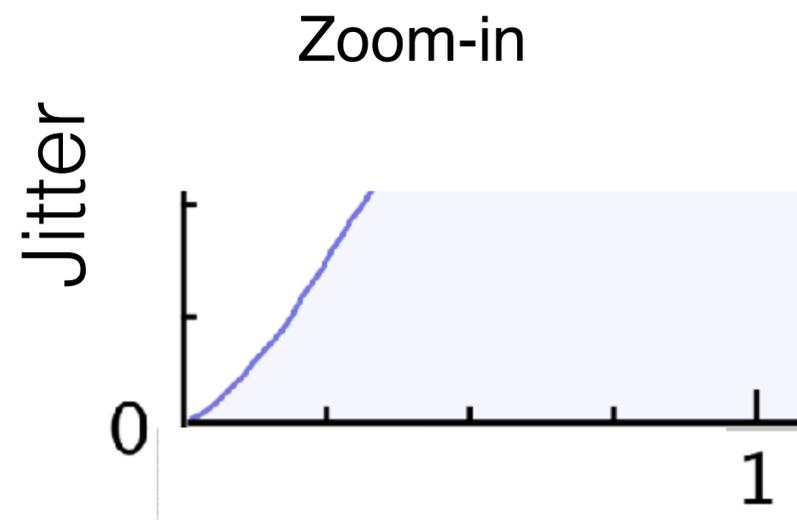
# Variance for Low Sample Count



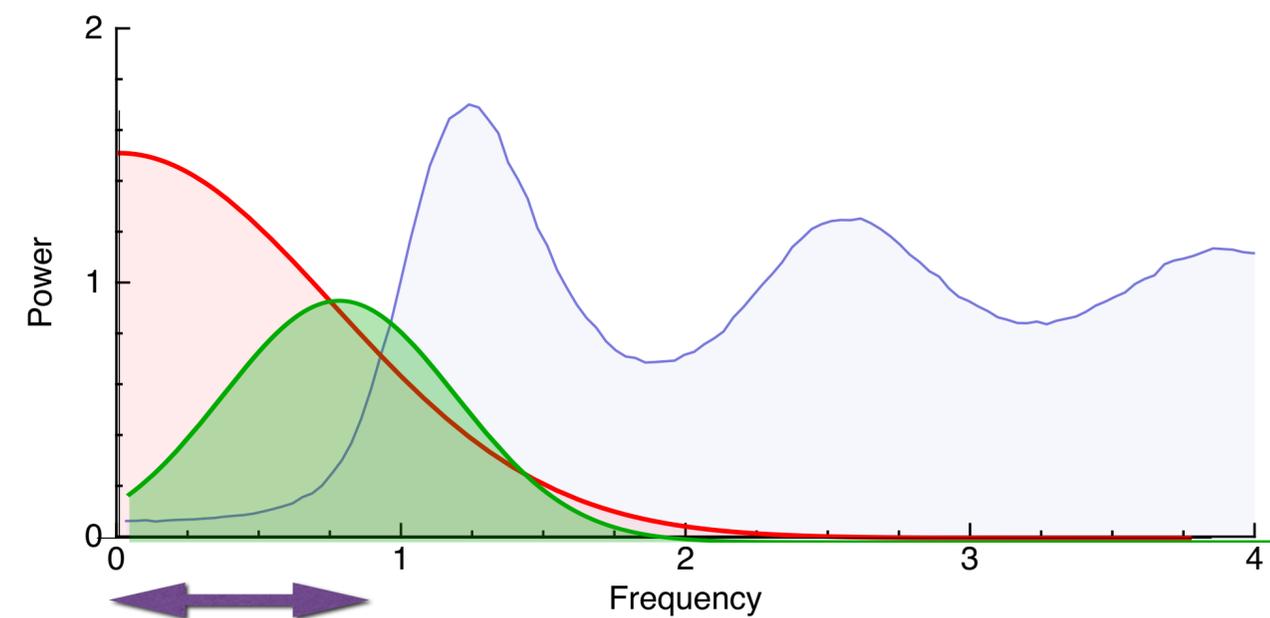
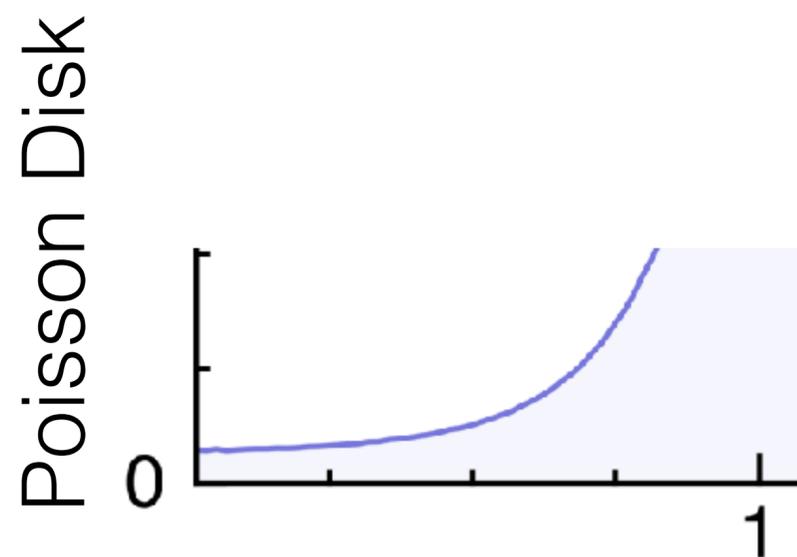
# Variance for Low Sample Count



# Variance for Increasing Sample Count



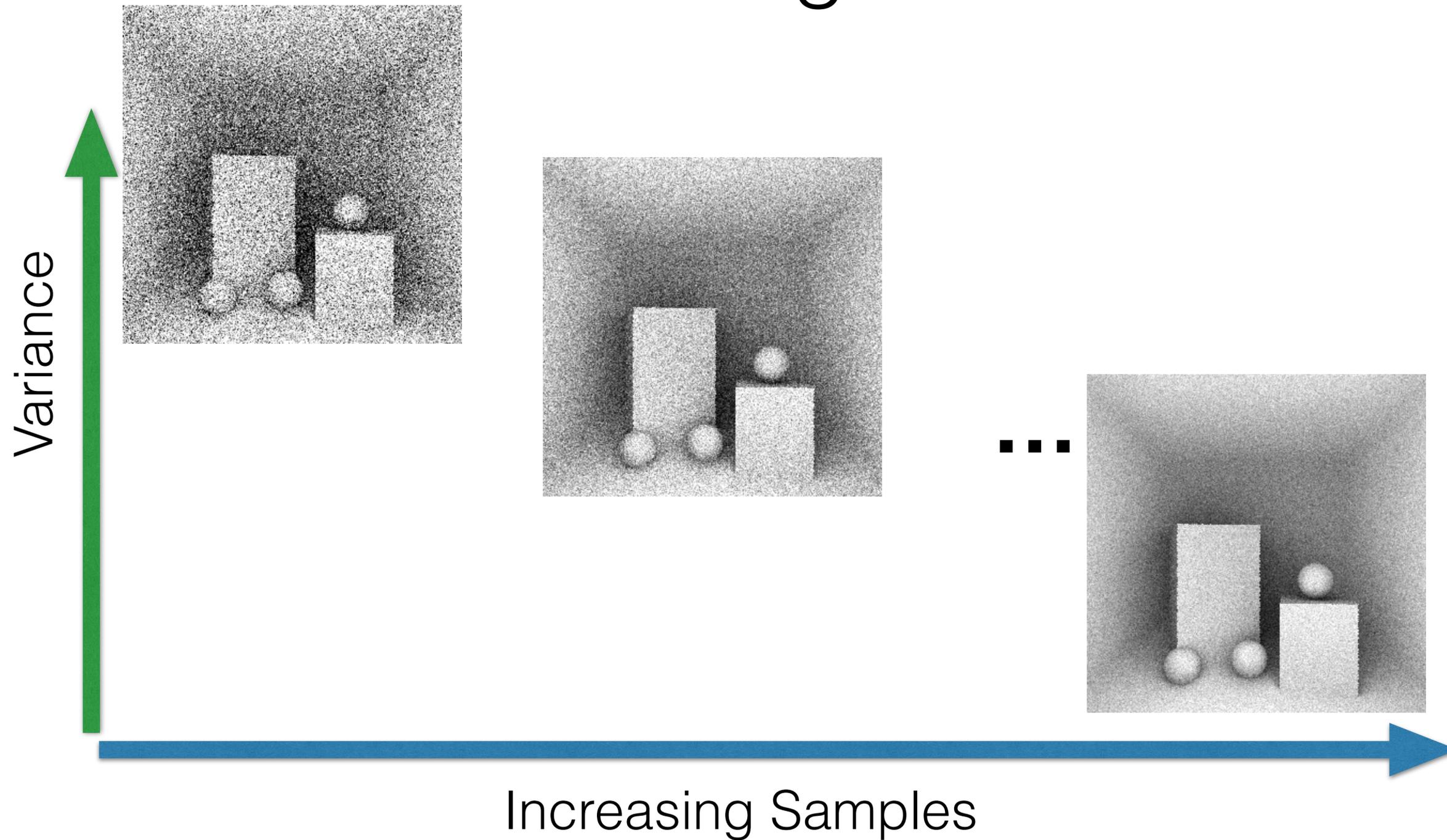
$$\mathcal{O}(N^{-2})$$



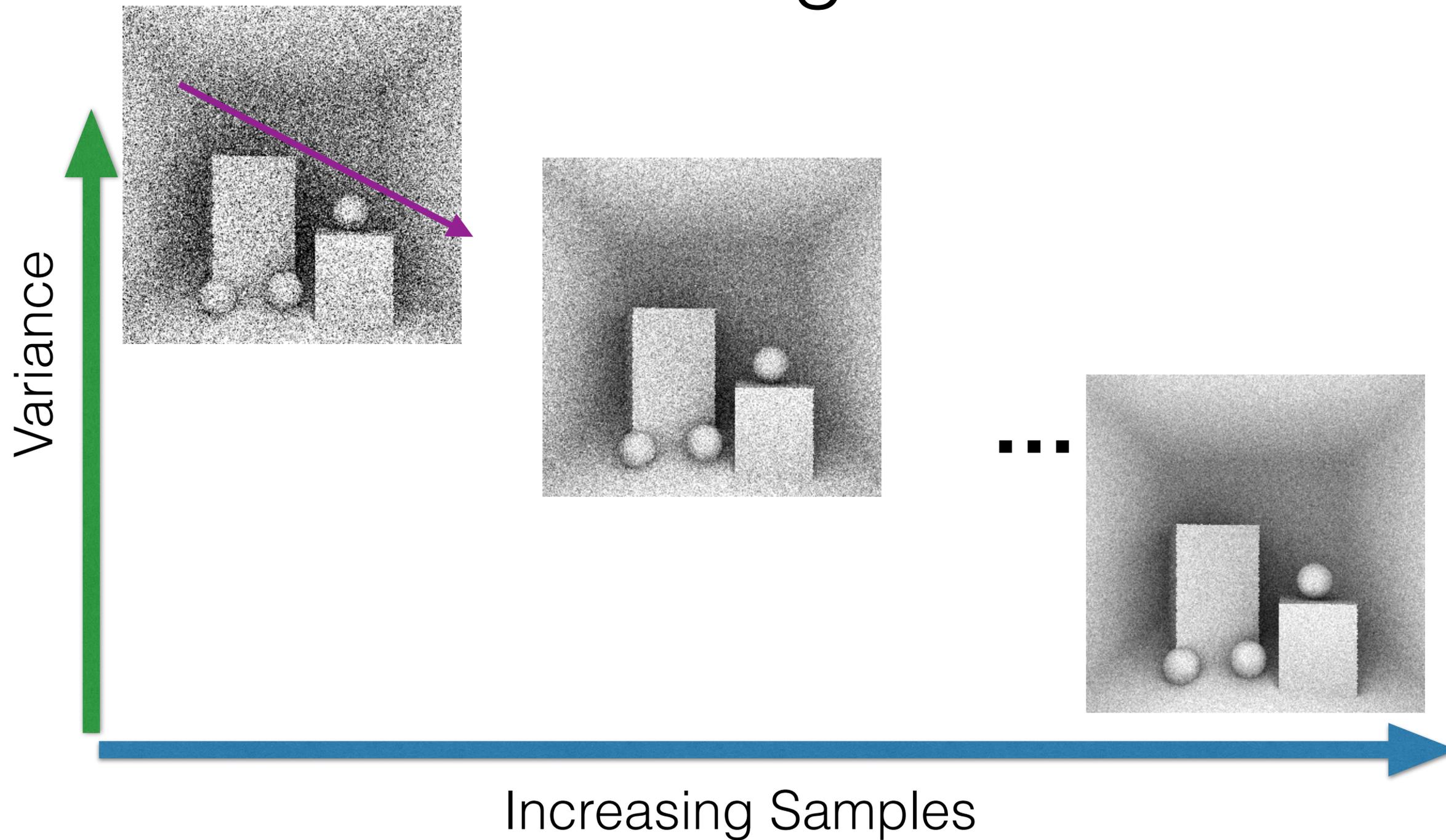
$$\mathcal{O}(N^{-1})$$

# Experimental Verification

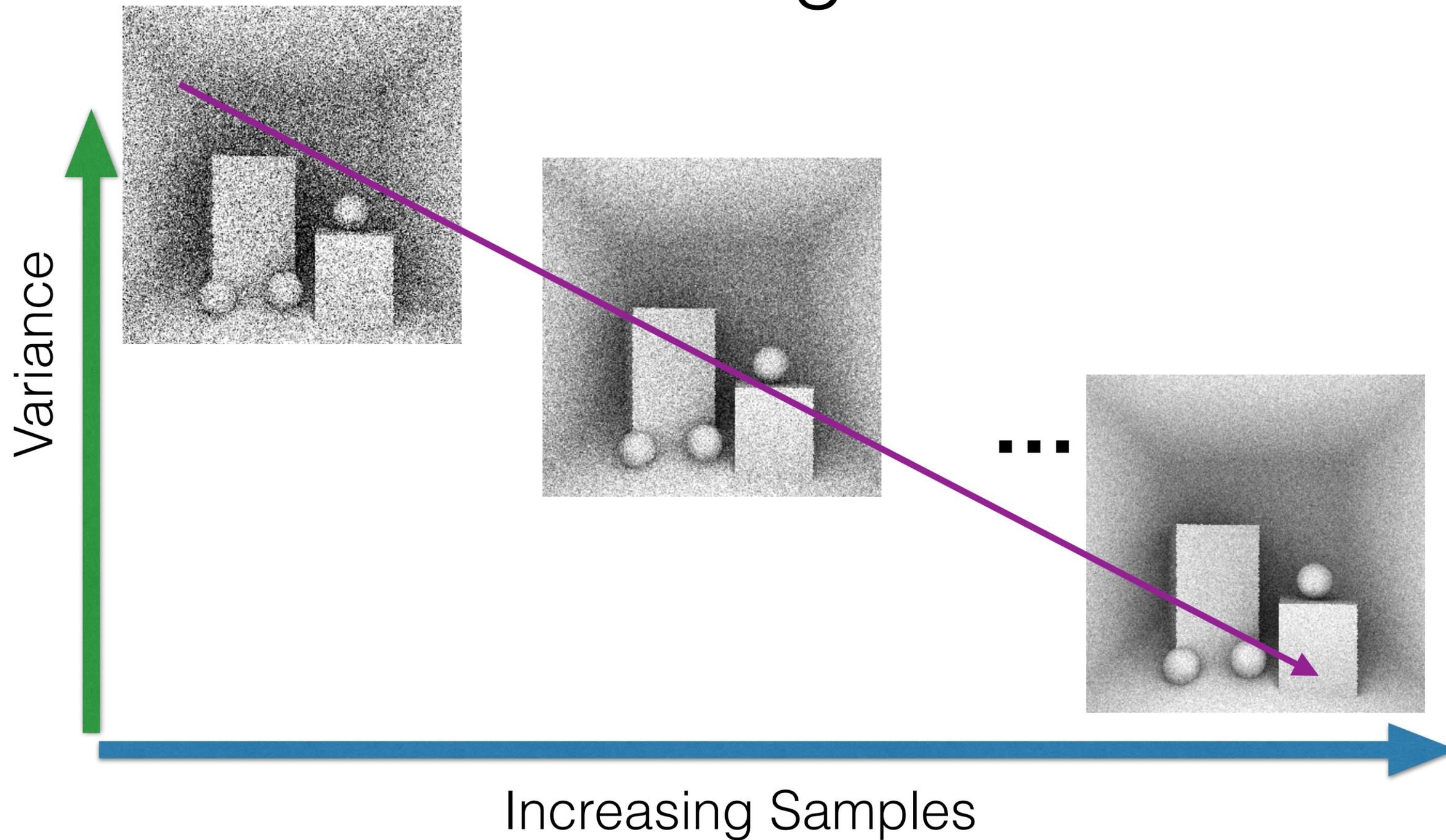
# Convergence rate



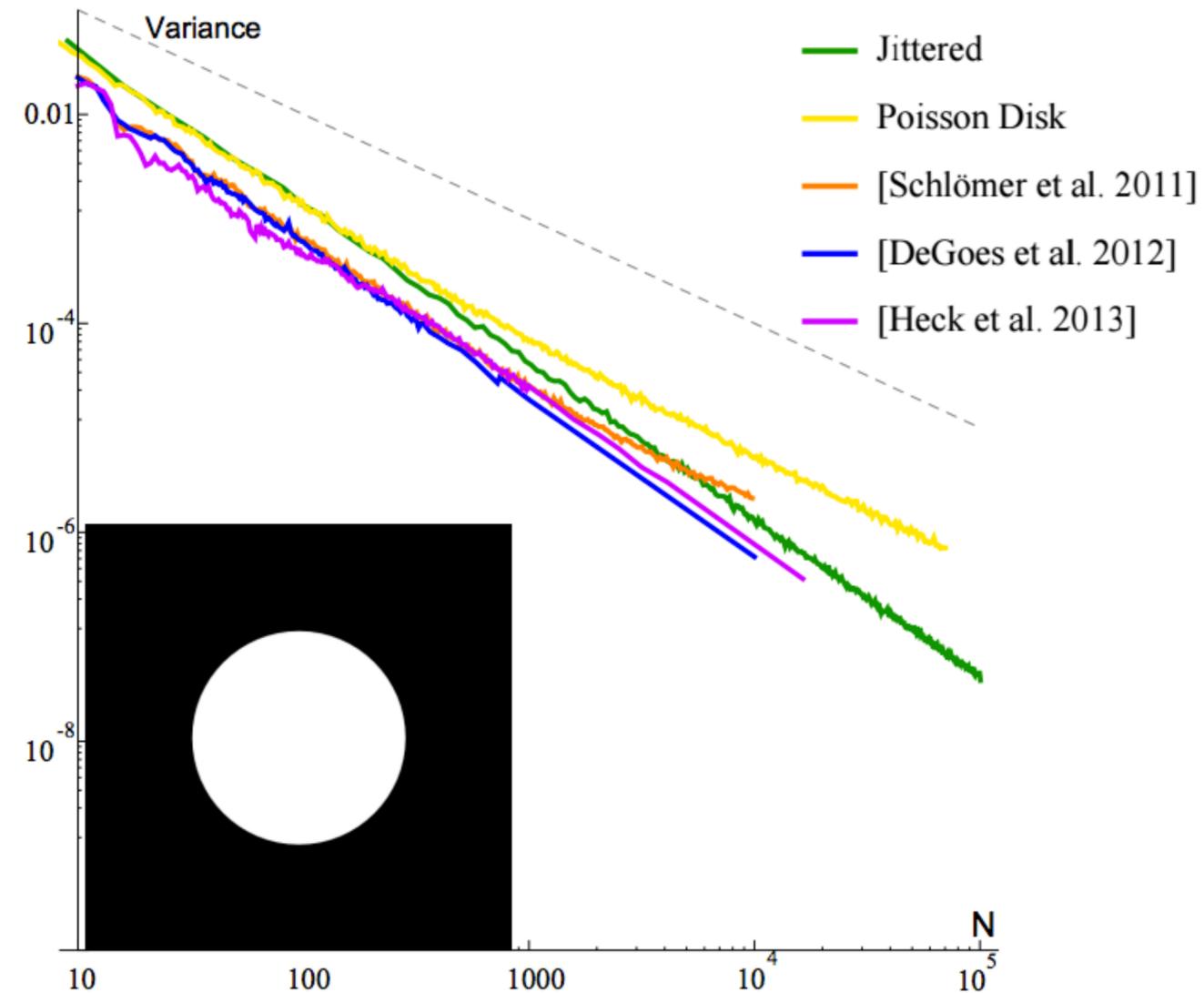
# Convergence rate



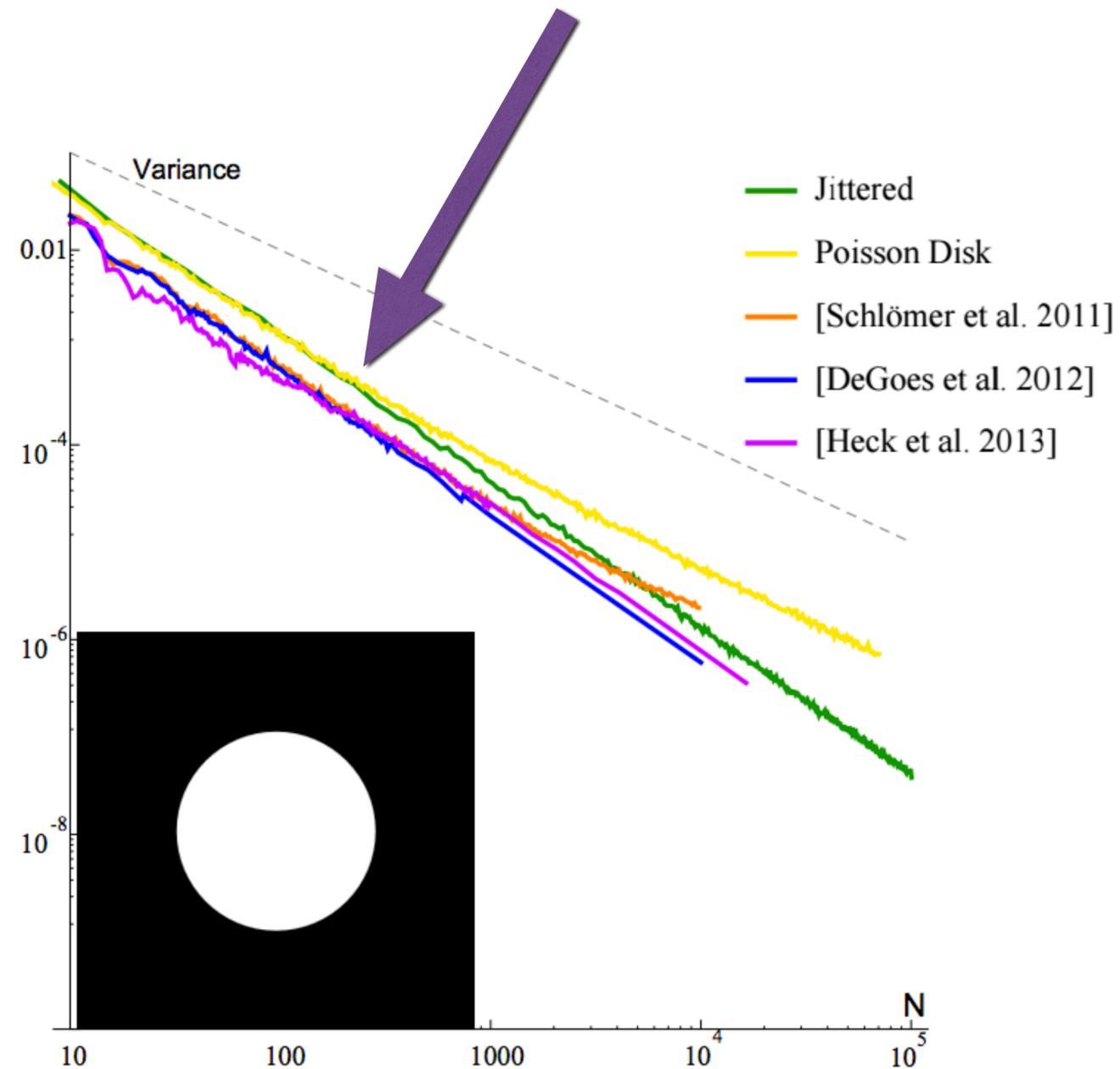
# Convergence rate



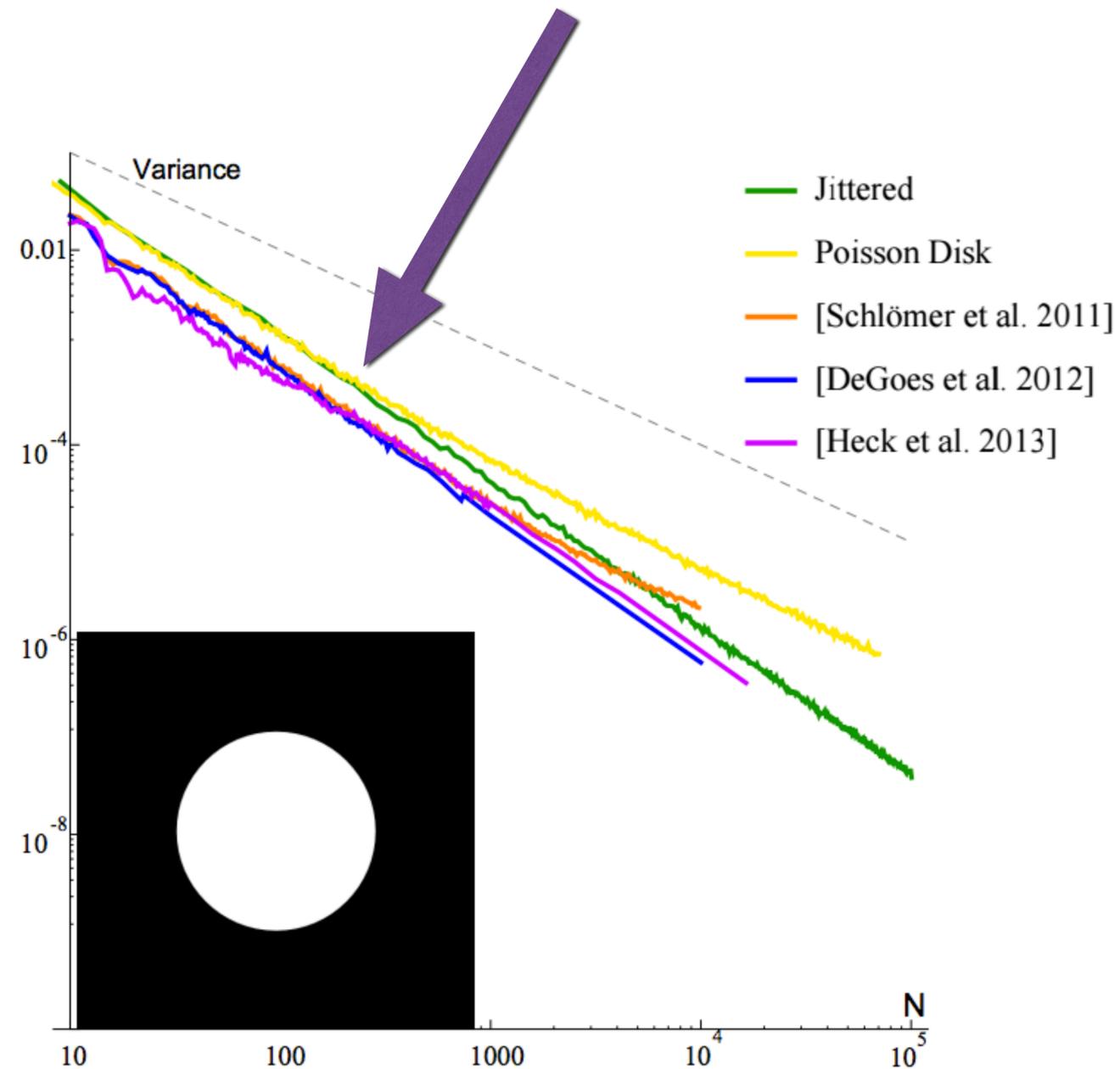
# Disk Function as Worst Case



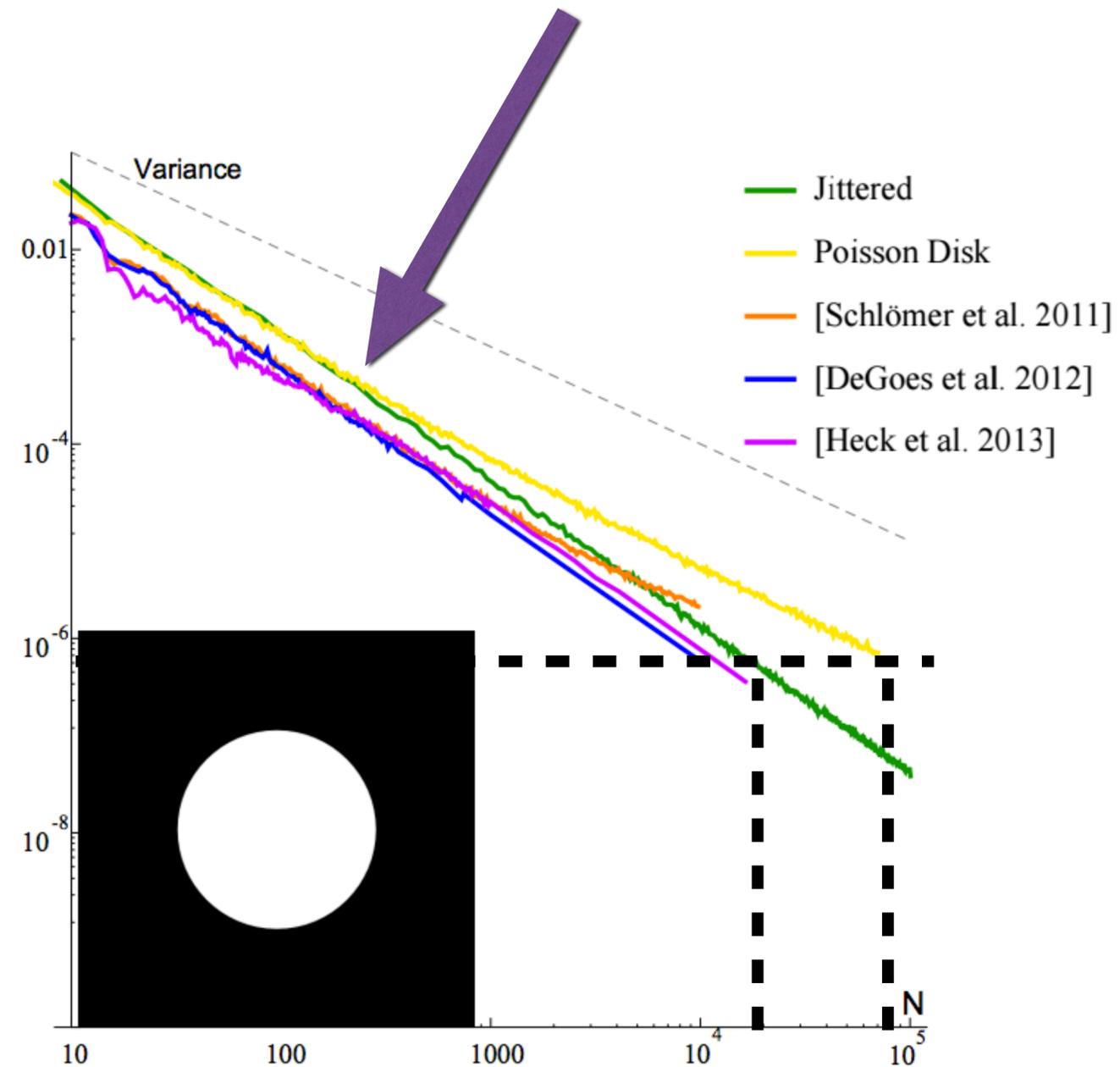
# Disk Function as Worst Case



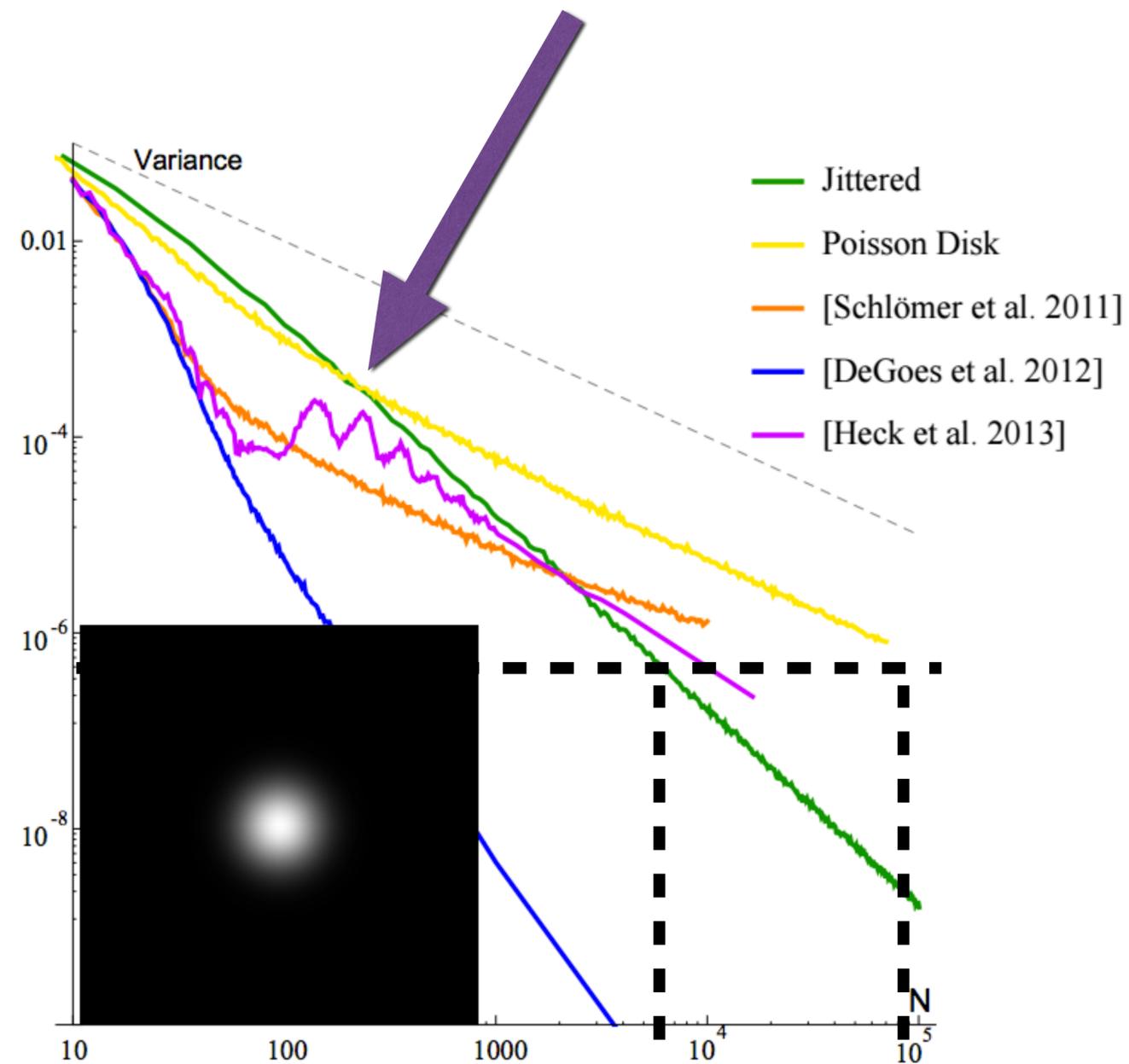
# Disk Function as Worst Case



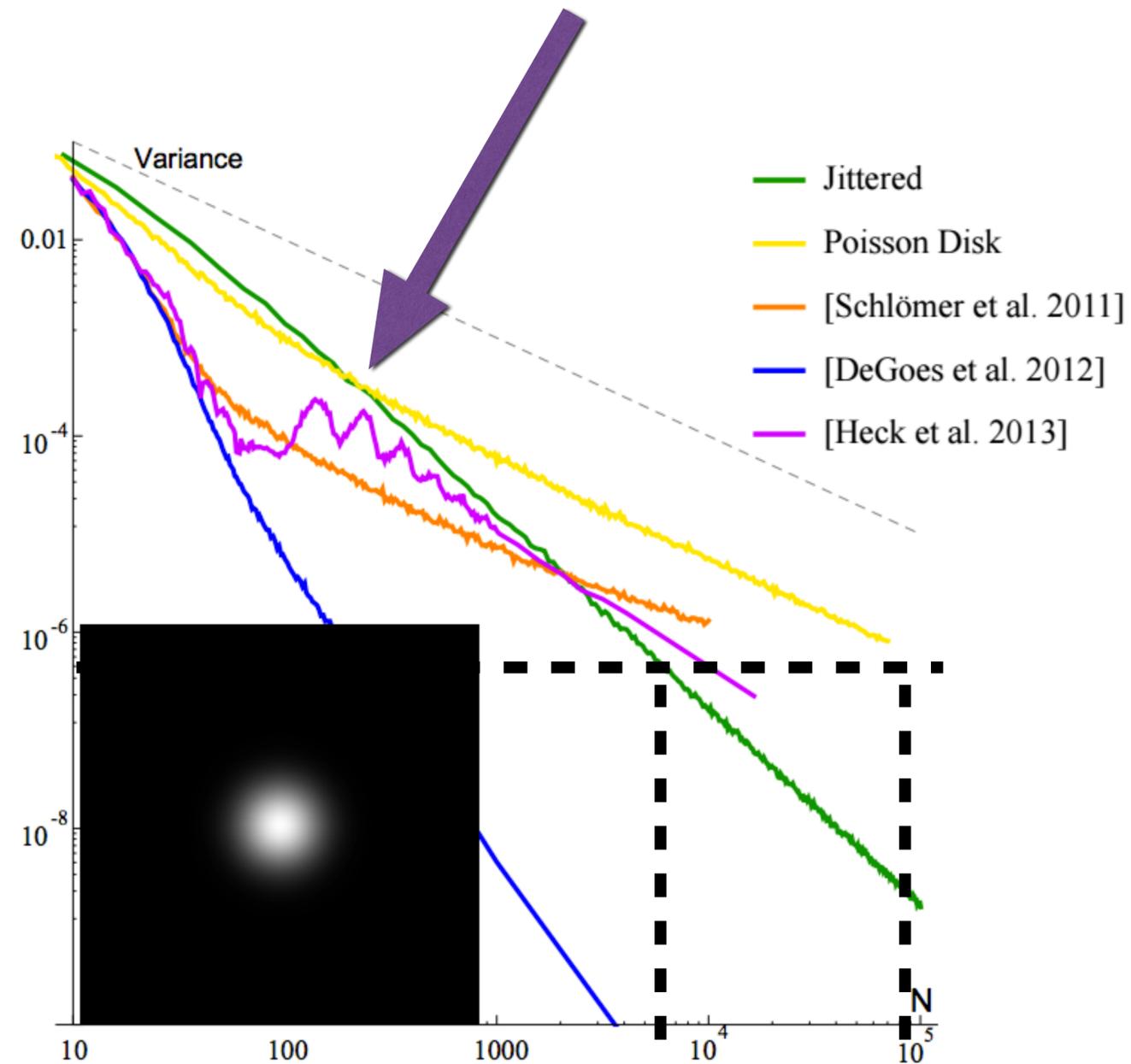
# Disk Function as Worst Case



# Gaussian as Best Case



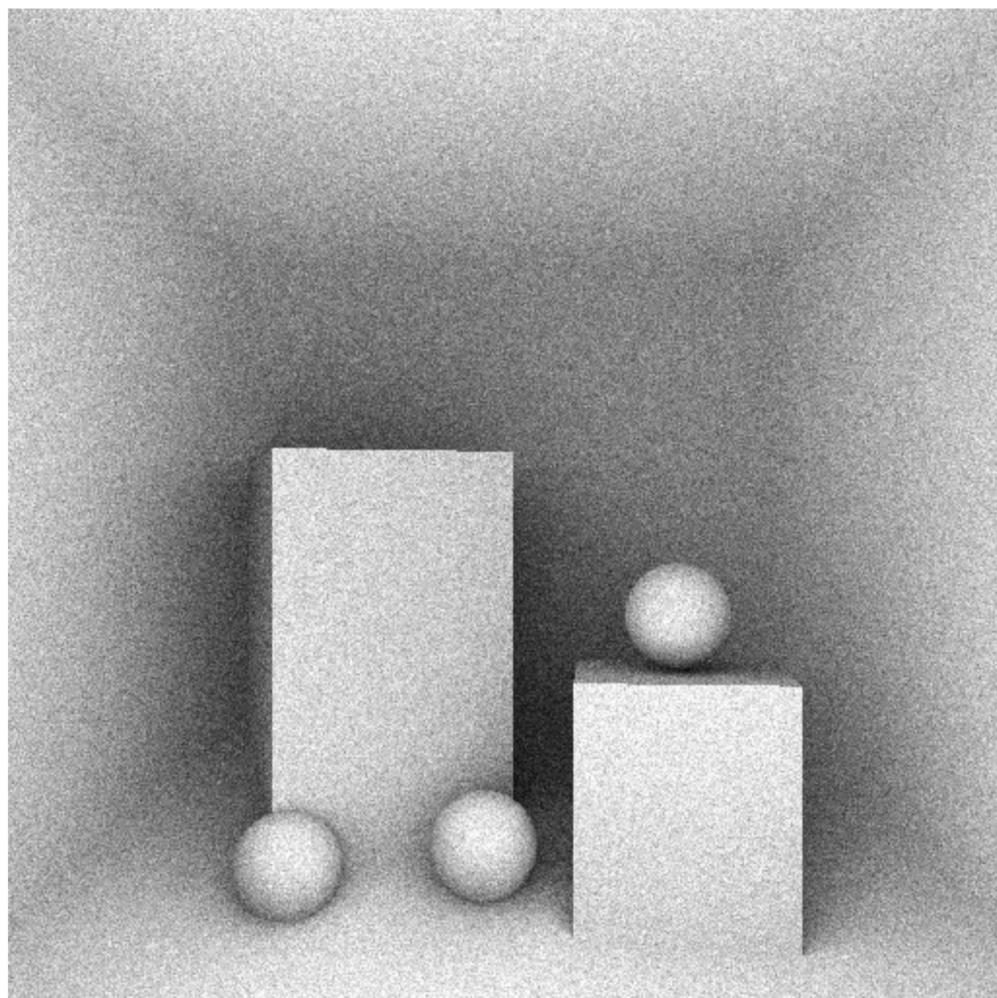
# Gaussian as Best Case



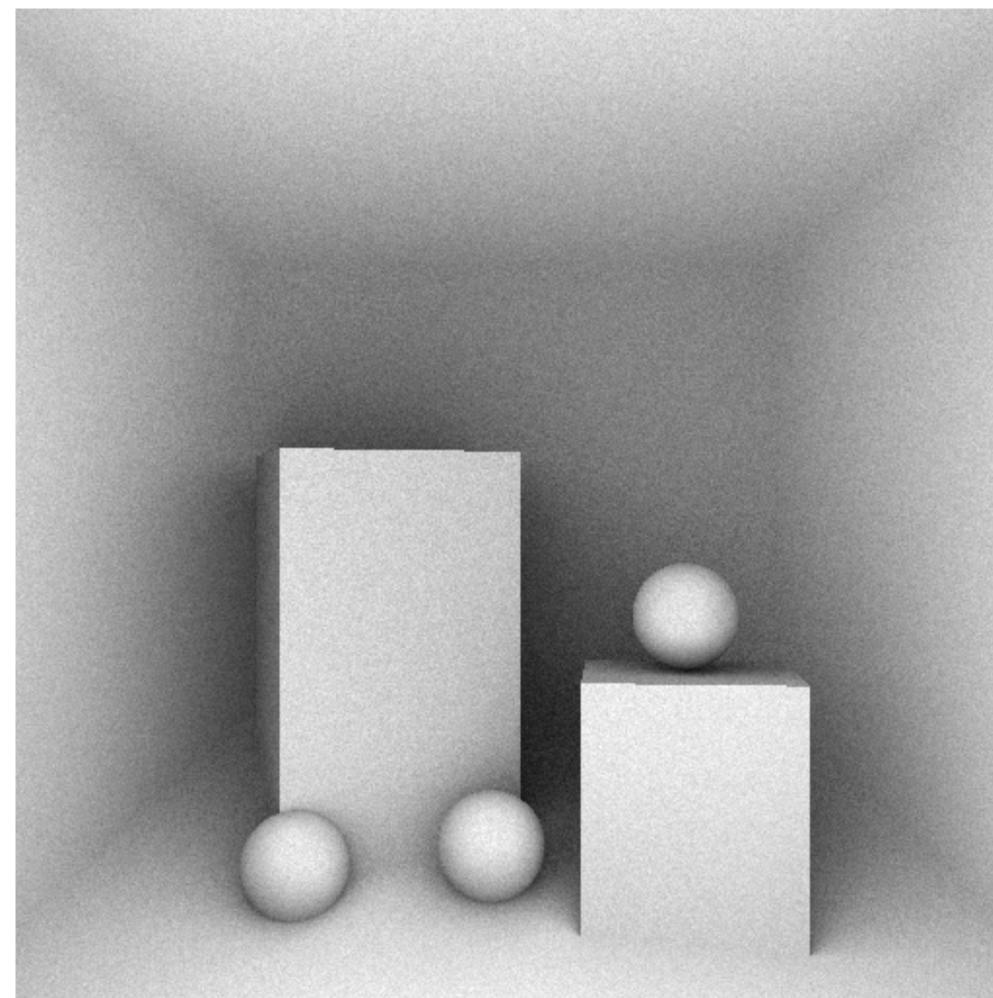
# Ambient Occlusion Examples

# Random vs Jittered

96 Secondary Rays



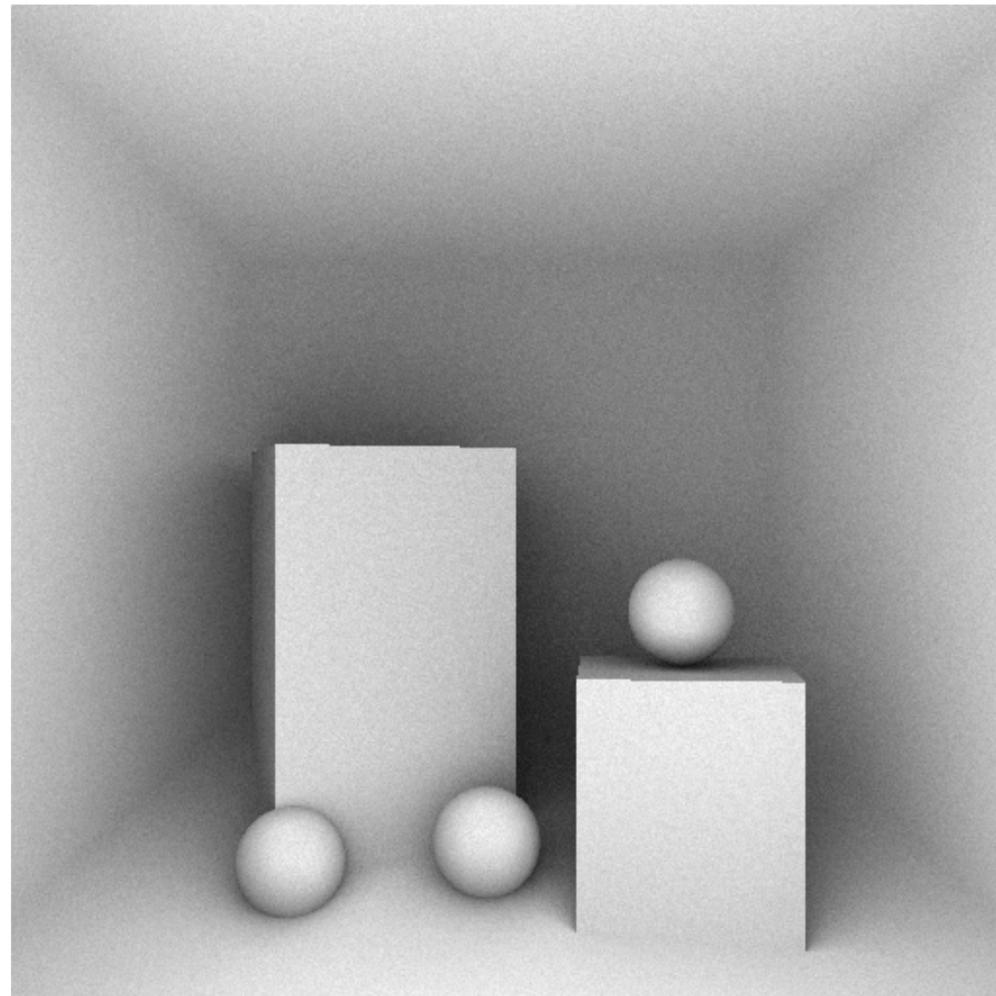
MSE:  $4.74 \times 10^{-3}$



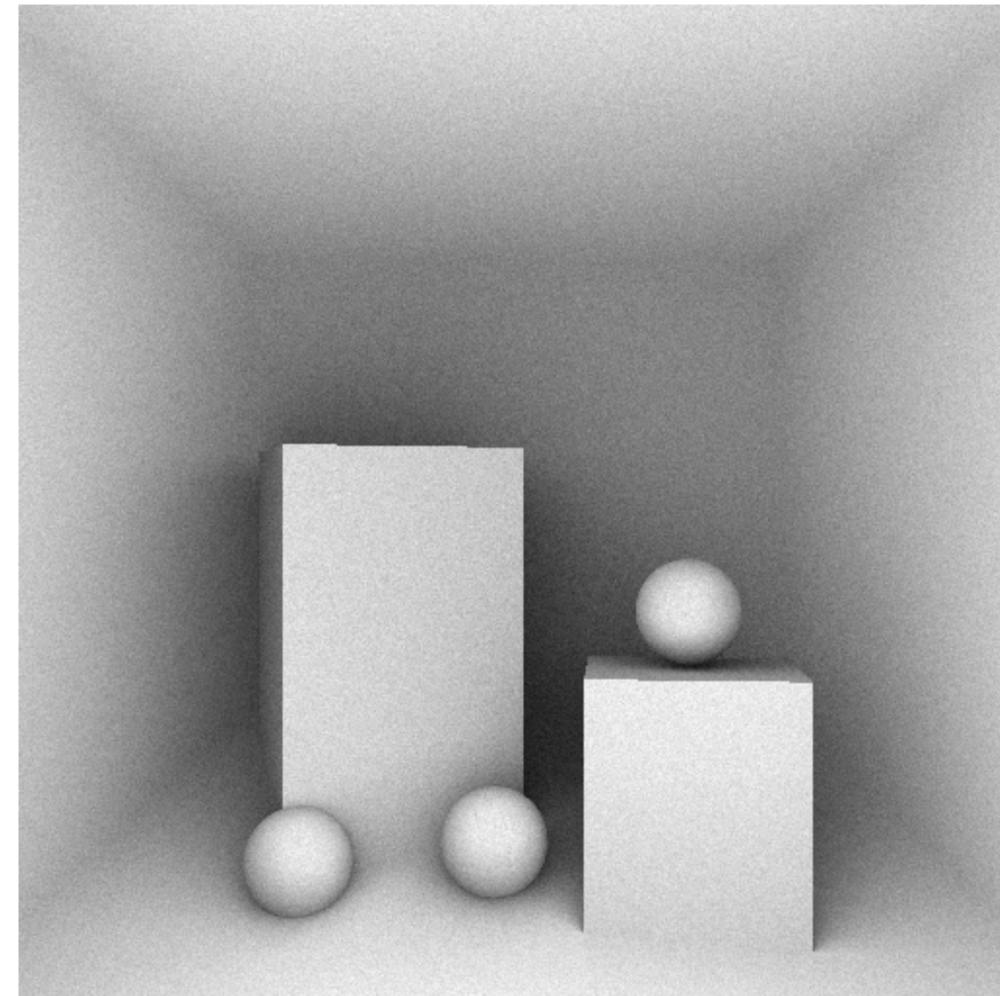
MSE:  $8.56 \times 10^{-4}$

# CCVT vs. Poisson Disk

96 Secondary Rays

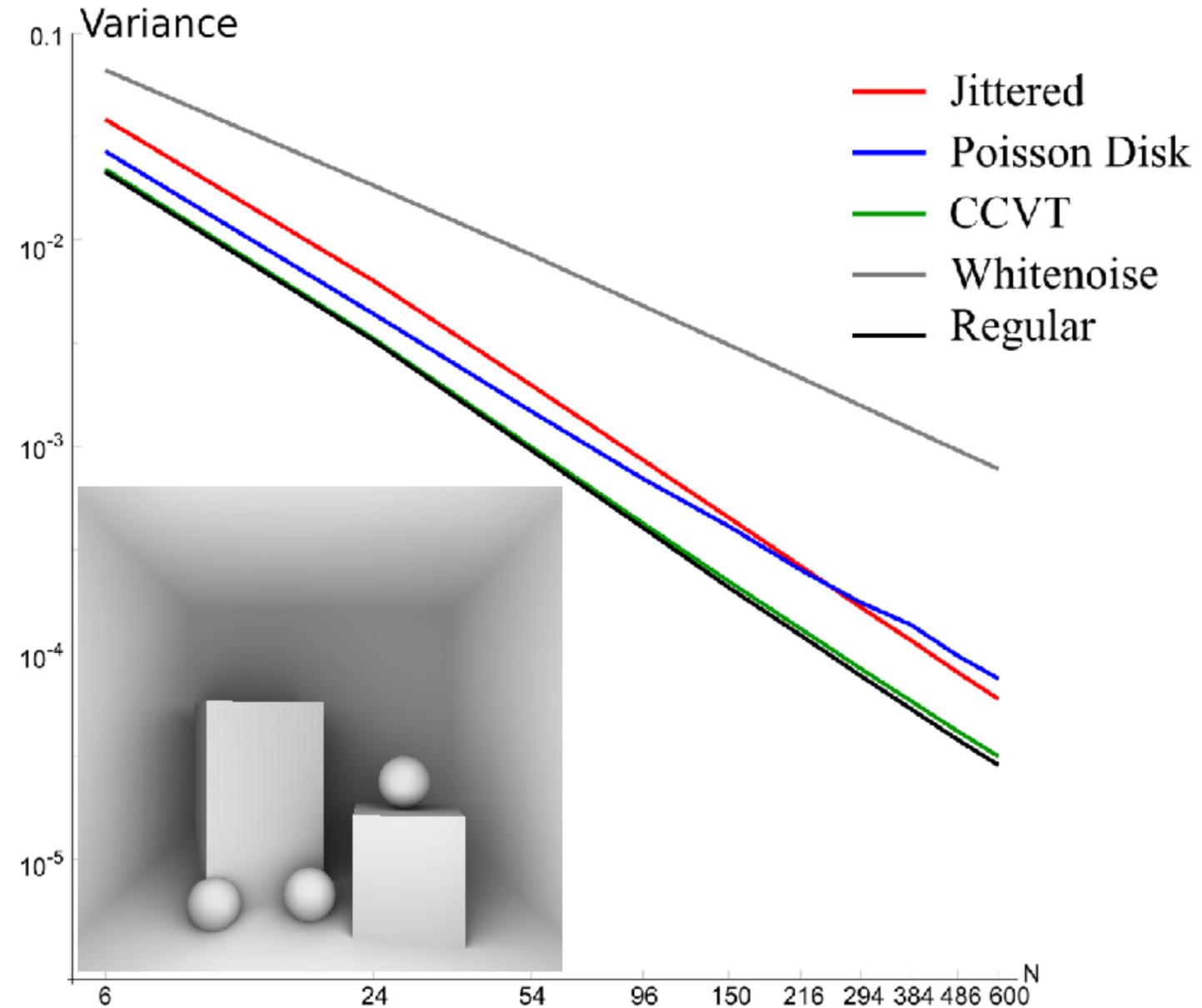


MSE:  $4.24 \times 10^{-4}$

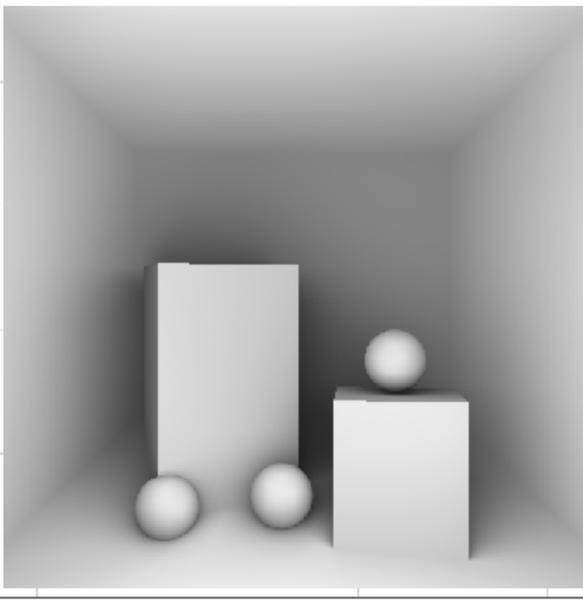
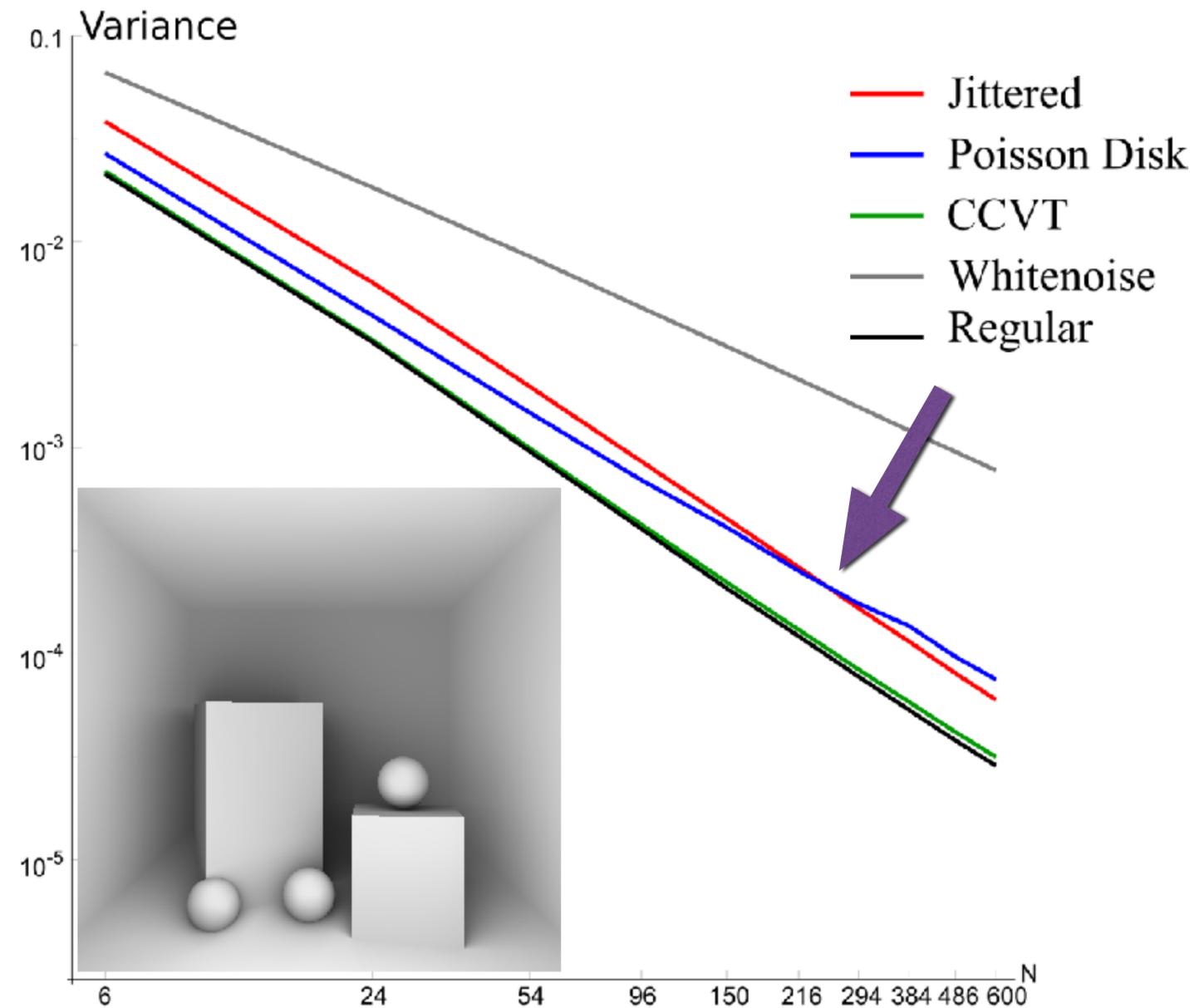


MSE:  $6.95 \times 10^{-4}$

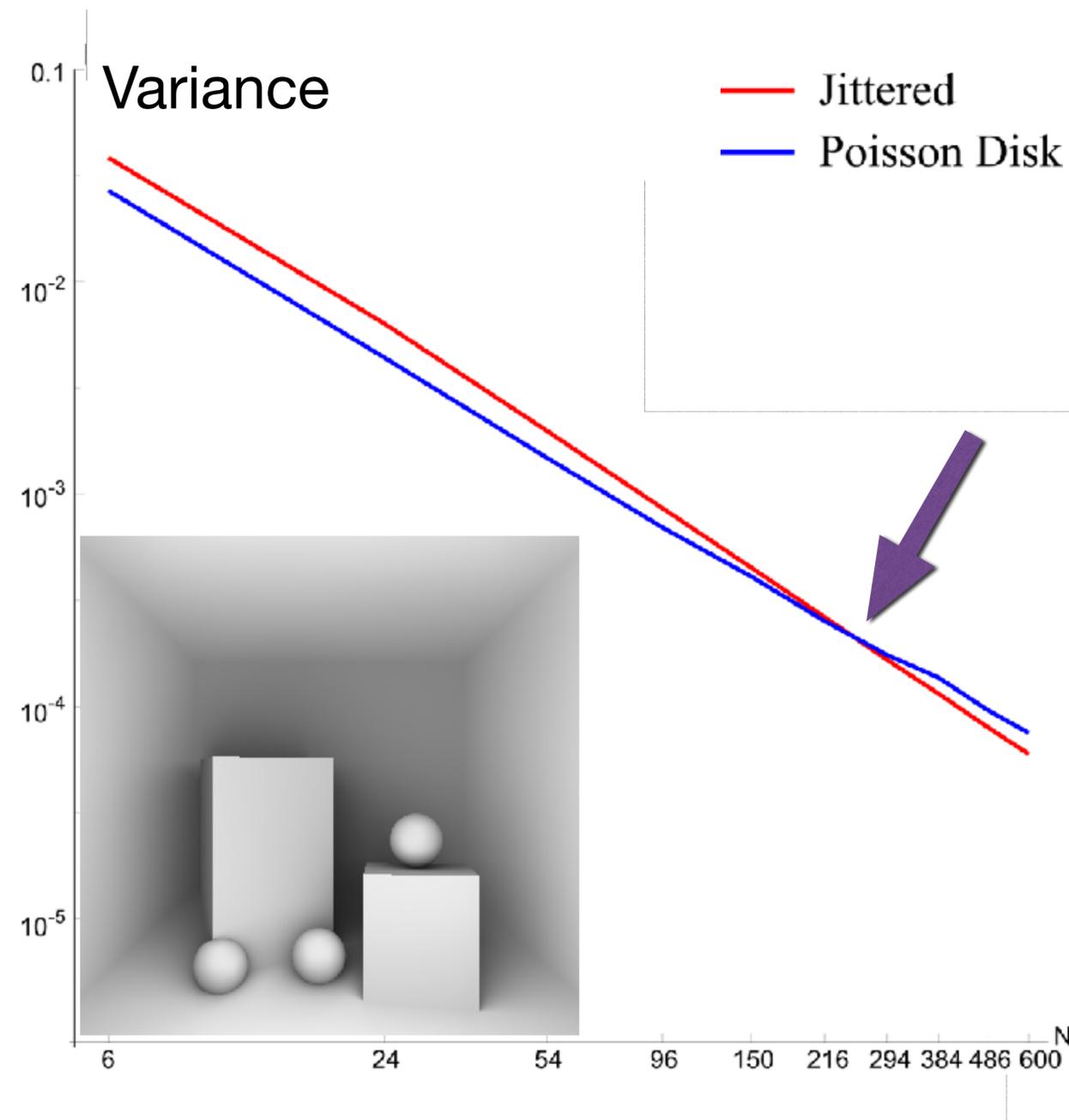
# Convergence rates



# Convergence rates



# Jittered vs Poisson Disk



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- For real time rendering, blue noise samples are more effective in reducing variance for a given number of samples