

## Curves and splines



## Upcoming lectures

- Some more advanced geometry (today & Thursday)
- GPU / Real-time rendering
	- Camera models and clipping
		- How to encode perspective cameras as a matrix and project your geometry on the screen
	- Rasterization
		- How to compute pixel occupancy from projected triangles
	- Graphics APIs
		- How to interface with your GPU and get it to do stuff
	- Shader programming
		- How to program the GPU
	- Shadow algorithms
		- How to get shadows if you cannot afford ray tracing

#### Today and Thursday: some more advanced geometry





## Curves



### What are curves?

- A line that is not straight
- Sequence of points that takes you from  $a$  to  $b$





## Fun fact

• If you look for info online, search engines are slightly more helpful if you search for the singular "curve" rather than its plural form



#### Parametric curves

• A useful way to describe a curve



 $\cdot$  t is the "travel distance" or "time" along the curve



## A familiar example

• The ray equation you have used this whole time is a parametric curve

 $r(t) = o + td$ 

• e.g.,





## Wait, what do we even need those curves for?



### Example: Modelling hair and fibers



- With curves, we can describe intricate geometries like these with a few control points
- With triangle meshes, this would be millions of vertices



### Example: Modelling smooth surfaces



- Curve / spline: A few control points
- Mesh: requires millions of triangles for similar result



## Example: Interpolating keyframes in animations





Keyframes only and the settlement of the Bézier interpolation



#### Example: 2D vector graphics and fonts





## Smoothness



## $C^0$  continuity

•  $c(t)$  is continuous, but not differentiable





## $C^1$  continuity

• first derivative  $\frac{d}{dt}$  $dt$  $c(t)$  is  $\mathcal{C}^0$  continuous



- And so on: For  $C^n$ , the nth derivative has to be  $C^{n-1}$  continuous
- Typically,  $C^2$  is desired for a perceptually smooth result



# Defining and modelling curves



#### Control point interpolation





## Cubic Bézier curves

- Polynomial interpolation
- 4 control points  $P_1 ... P_4$ ,  $t \in [0,1]$

$$
c(t) = (1-t)^3 P_1 + 3(1-t)^2 t P_2 + 3(1-t) t^2 P_3 + t^3 P_4
$$



- Interpolate smoothly from  $P_1$  to  $P_4$
- $P_2$  and  $P_3$  "act like magnets" to steer the curve in-between
- Explicit tangents:
	- $P_2 P_1$  is the tangent at  $P_1$
	- Allows smoothly connecting curves
- Convex hull property:
	- All points  $c(t)$  inside convex hull of  $\{P_1, P_2, P_3, P_4\}$



## de Casteljau's algorithm (here for cubic Bézier curves)

- Faster & numerically stable compared to direct computation
- Recursive linear interpolation

- 1. Compute  $Q_1 = tP_1 + (1 t)P_2$ 
	- Same for  $Q_2$  and  $Q_3$
- 2. Compute  $R_1 = tQ_1 + (1-t)Q_2$ 
	- Same for  $R_2$
- 3. Compute result as  $tR_1 + (1 t)R_2$





#### de Casteljau's algorithm





# Splines

Stitching curves together



## A "spline" is a piecewise polynomial function

- We *could* use a single high-degree polynomial curve
- But:
	- Difficult to fit / model
	- Numerical issues

- Splines stitch low-order polynomial curves instead
	- Simple
	- Numerically stable (if done well)



#### Piecewise Bézier spline





#### Quiz time! How smooth is this Bézier spline?





#### And what about this one?





## Smoothness of piecewise cubic Bézier splines

- The "handles" (control polygon edges) have to
	- Align  $(C^1)$
	- Be of same length  $(C^2)$



## Bézier curves and splines are popular, but not the only option

- B-Splines
- Catmull-Rom splines
- Hermite splines



## Rendering splines: Fibers



#### Hair, fur, grass, ...







## Defining a fiber with a curve and a width

• e.g., "thicken" a Bézier curve





### Flat fibers

• Always face the ray





## Cylinder fibers

• Sweep a circle along the curve







## Ribbon fibers

• Flat, orientation is fixed and interpolated between control points





## Ray-tracing a fiber

- Same root-finding problem as always:
	- take the ray equation
	- substitute into the spline equation
	- solve
- Expensive, so some clever culling (using the convex hull) is beneficial

• <https://pbr-book.org/4ed/Shapes/Curves>



#### The curve lies inside the convex hull of the control points



The convex hull of a point-set / mesh / polygon is the smallest polygon / polyhedron that contains all points



# Rendering splines: Smooth surfaces



## Tensor product surface

• "Extrudes" a curve into a surface, by following another curve



• The hair curves we discussed just now are special cases of this idea



## Example: bilinear patch

- Tensor product of two linear curves
- Useful shape for modelling:
	- Connects 4 vertices
	- But does not force them to be coplanar





## Example: Bézier surface

- Same idea as a bilinear patch
- But with Bézier curves

- Aligning Bézier patches nicely is harder than curves
	- **→ NURBS (non-uniform rational B-spline surface)**
	- ➔ Dedicated modelling tools (used by CAD software)





## Ray-tracing a spline surface

- We *can* directly intersect a ray and a spline patch
- This is a root-finding problem
	- Substitute ray equation into spline equation and solve
	- Same as any other ray-object intersection test
- But: For higher-degree polynomials, this is *expensive*



## Tessellation

- Approximate the spline surface with a triangle mesh
- For a 2D tensor product surface:
	- Subdivide the  $u \times v$  domain with a regular grid
	- Evaluate spline position for each grid corner
	- Create triangles (or bilinear patches) with those vertices





## Summary



## Today: Curves and splines

- Smooth interpolation of control points
- Many uses (2D vector graphics, fonts, key-frame interpolation in animation, ...)
- In our focus area (static-scene rendering):
	- Modelling hair, grass, and similar fine structures
	- Modelling smooth surfaces



## Next up: Subdivision surfaces

- Uses ideas from curves and splines
- Subdivide coarse geometry so it becomes more smooth

