### **Computer Graphics**

- Distribution Ray Tracing -

Philipp Slusallek

### Overview

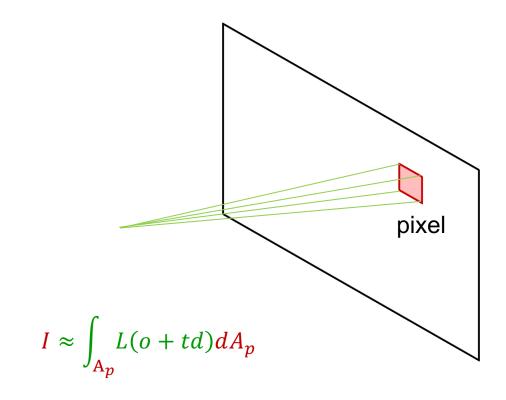
- Other Optical Effects
  - Not yet included in Whitted-style ray tracing
- Stochastic Sampling
- Distribution Ray-Tracing
- Outlook towards Realistic Image Synthesis lecture
  - → next semester

### **Problems**

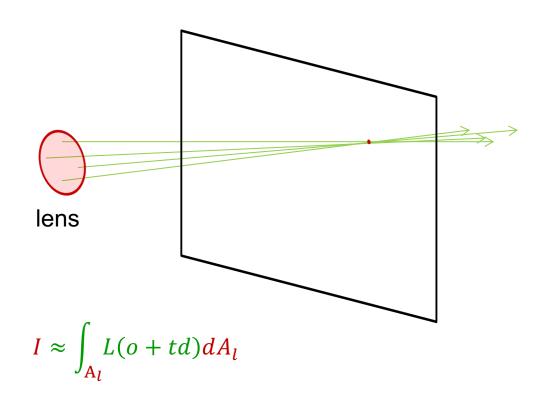
- Anti-aliasing
- Depth of field
- Motion blur
- BRDF
- Area Lights

## **Anti-aliasing**

- Anti-aliasing
- Depth of field
- Motion blur
- BRDF
- Area Lights

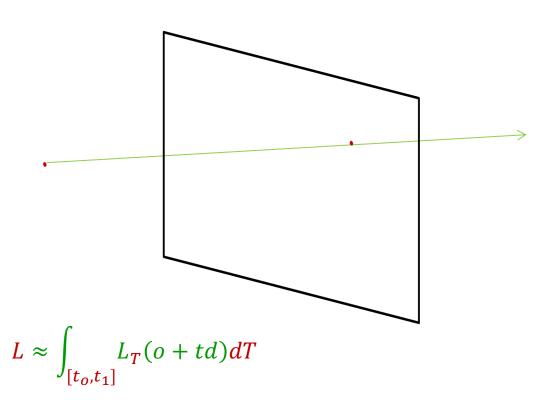


- Anti-aliasing
- Depth of field
- Motion blur
- BRDF
- Area Lights



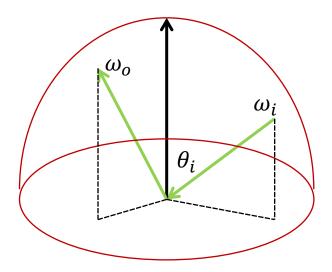
### Motion blur

- Anti-aliasing
- Depth of field
- Motion blur
- BRDF
- Area Lights



### **BRDF**

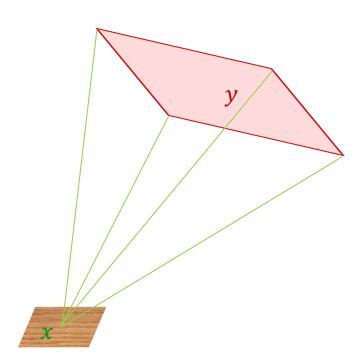
- Anti-aliasing
- Depth of field
- Motion blur
- BRDF
- Area Lights



$$L_o = L_e + \int_{\Omega_+} f_r L_i \cos \theta_i \, d\omega_i$$

# **Area Lights**

- Anti-aliasing
- Depth of field
- Motion blur
- BRDF
- Area Lights

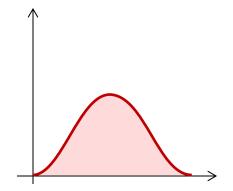


$$E_i = \int_A V(x, y_A) \frac{\cos \theta_A}{\|x - y_A\|^2} dA$$

# Integration by MC-Sampling

- Need to integrate over many features or many dimensions
  - Anti-aliasing
  - Depth of field
  - Motion blur
  - BRDF
  - Area Lights

$$I = \int_{D} f(x) dx_{D}$$

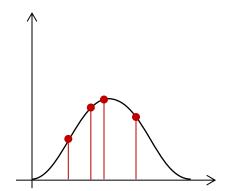


- Solution: Monte-Carlo (MC) Integration
  - Stochastic sampling of the domain
  - Averaging of results, weighted by probability
  - Careful choice of samples essential for good results



$$I \approx \frac{D}{n} \sum_{i=1}^{n} \frac{f(x_i)}{p(x_i)}$$

$$x_i \text{ sampled } \propto p(x)$$



### STOCHASTIC SAMPLING

(VERY SHORT INTRO)

### Random Number

#### Random Number

- Uniformly distributed
- $-\xi$  in [0, 1)

#### Pseudo-Random Number

- Linear congruential generator
- Mersenne-Twister
- **—** ...
- Speed / evenness trade-off

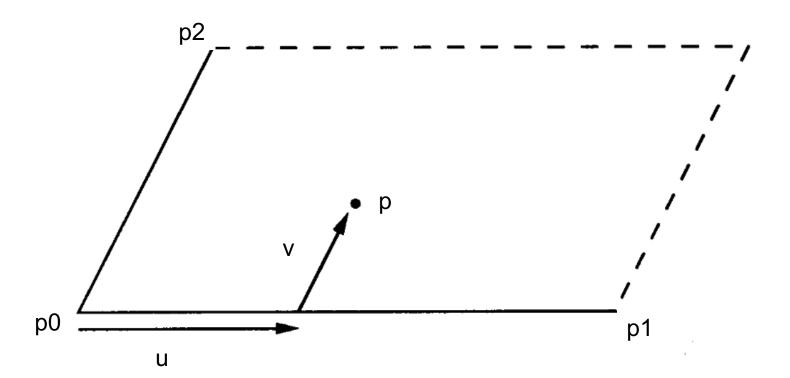
## Parallelogram Sampling

#### Parametric Form

$$- p(u,v) = p_0 + u(p_1 - p_0) + v(p_2 - p_0) = (1 - u - v)p_0 + up_1 + v p_2$$

#### Random Sampling

$$- p(\xi_1, \xi_2)$$



## Triangle Sampling

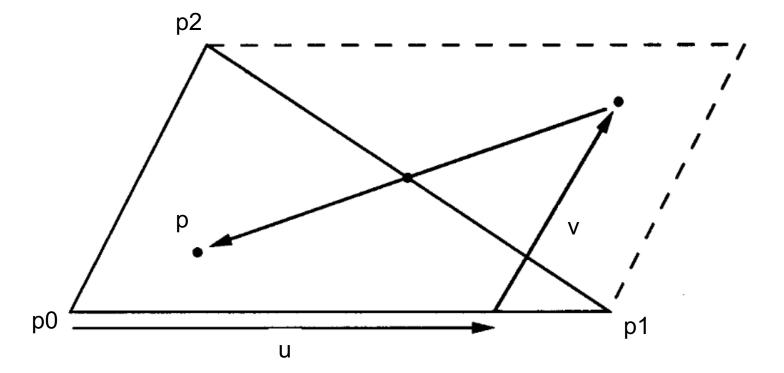
#### Parametric Form

$$- p(u,v) = (1 - u - v)p_0 + up_1 + v p_2$$

### Random Sampling

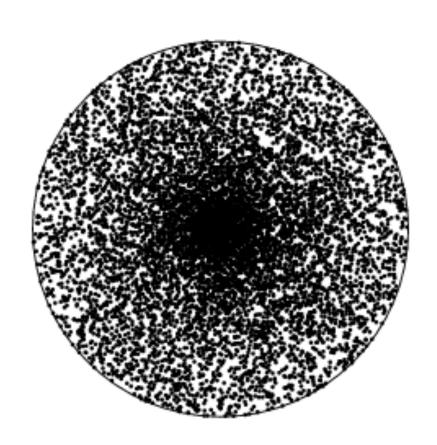
- if 
$$\xi_1 + \xi_2 < 1$$
:  $p(\xi_1, \xi_2)$ 

- if 
$$\xi_1 + \xi_2 > 1$$
:  $p(1 - \xi_1, 1 - \xi_2)$ 



# Disc Sampling

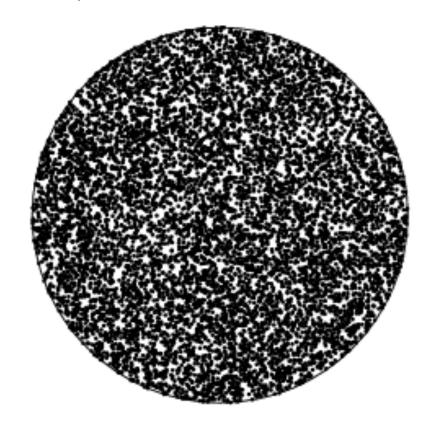
- Parametric Form
  - $p(u, v) = Polar2Cartesian(R v, 2 \pi u) // disc radius R$
- Naïve Sampling (wrong!)
  - $p(\xi_1, \xi_2)$



## Disc Sampling

- Parametric Form
  - p(u, v) = Polar2Cartesian(R v, 2 π u) // disc radius R
- Correct Sampling
  - $-p(\xi_1,\sqrt{\xi_2})$
  - Results in uniform sampling over area

 For other cases, see Phil Dutre's Global Illumination Compendium at

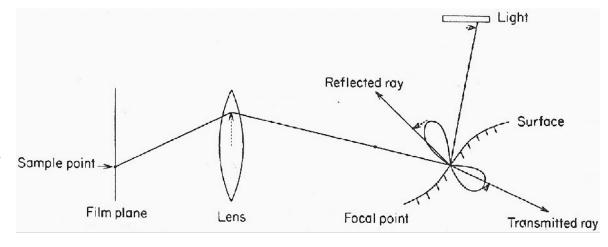


http://people.cs.kuleuven.be/~philip.dutre/GI/TotalCompendium.pdf

### **DISTRIBUTION RAY-TRACING**

## Distribution Ray Tracing

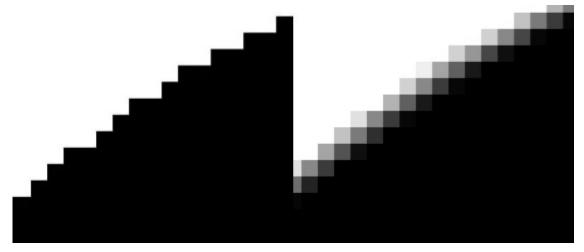
- Apply random sampling for many aspects in RT
  - Pixel
    - Anti-aliasing
  - Lens
    - · Depth of field
  - Time
    - Motion blur
  - BRDF
    - Glossy reflections & refractions
  - Area Lights
    - Soft shadows
  - Based on paper:
     R. Cook et al.,
     Distributed Ray Tracing,
     Siggraph'84



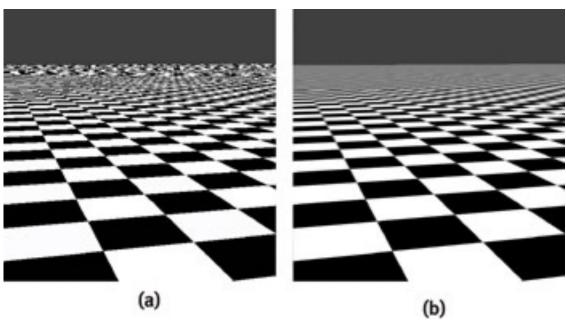
# **Anti-Aliasing**

#### Artifacts

Jagged edges



Aliased patterns



## **Anti-Aliasing**

#### Basic Method

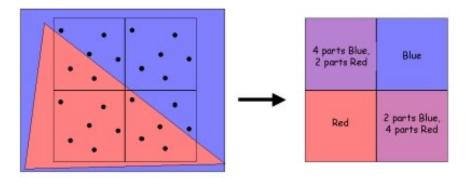
- Plain average
- Box filter f(x, y) = 1

$$- L = \frac{\sum_{i=1}^{n} L(\xi_{i1}, \xi_{i2})}{n}$$

### Filtering

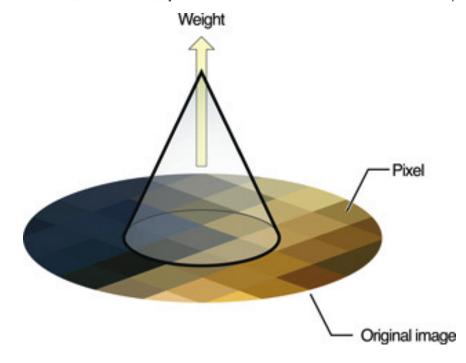
- Weighted average
- Filter f(x, y)

$$- L = \frac{\sum_{i=1}^{n} f(\xi_{i1}, \xi_{i2}) L(\xi_{i1}, \xi_{i2})}{\sum_{i=1}^{n} f(\xi_{i1}, \xi_{i2})}$$



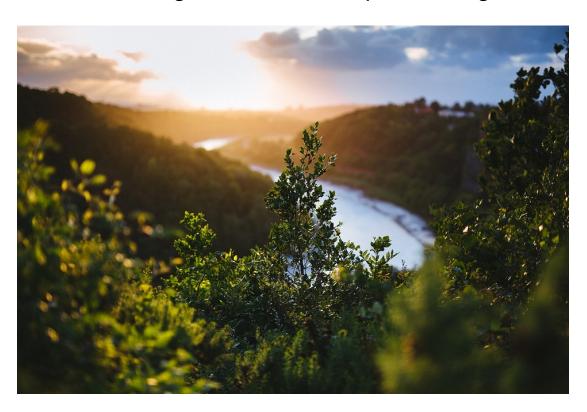
Pixel

Anti-Alias Sample



#### Real Camera

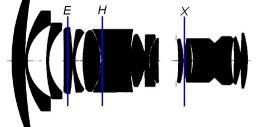
- Lenses that focus one distance onto the image
  - Stronger effect for larger apertures
- Blurred features except for focal plane
  - Larger distance from plane larger blur





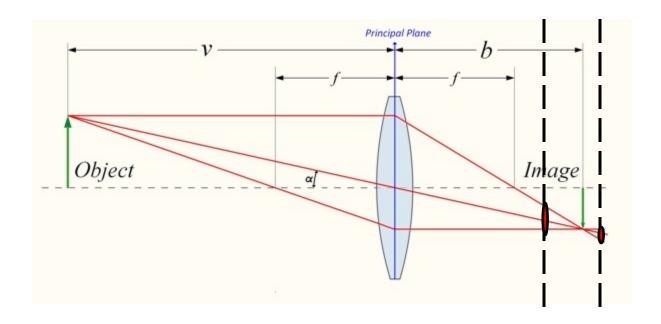






#### Thin Lens

- Focus light rays from point on object onto image plane
  - Sharp features at focal plane
  - Blurred features before/beyond focal plane
- Depth of field: depth range with acceptably small circle of confusion
  - Smaller than one pixel



### Compute ray through lens center

Compute focus point P<sub>f</sub> on focal plane, determined by P<sub>b</sub> and P<sub>c</sub>

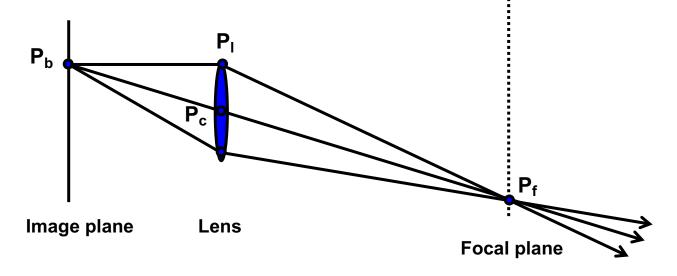
### Compute new ray origin

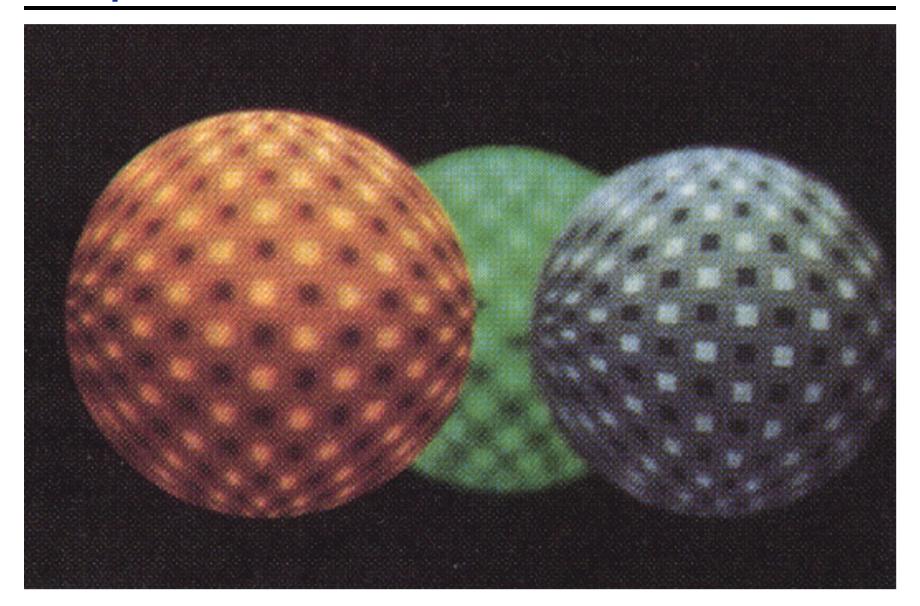
- Sample coordinates (x, y) of aperture diameter
  - Compute P<sub>I</sub>: ray.origin = P<sub>c</sub> + x \* camera.right + y \* camera.up
- Might include modeling the shape of the aperture

### Compute new ray direction

- Compute ray.direction =  $P_f - P_l \rightarrow \text{vector from } P_l \text{ to } P_f$ 

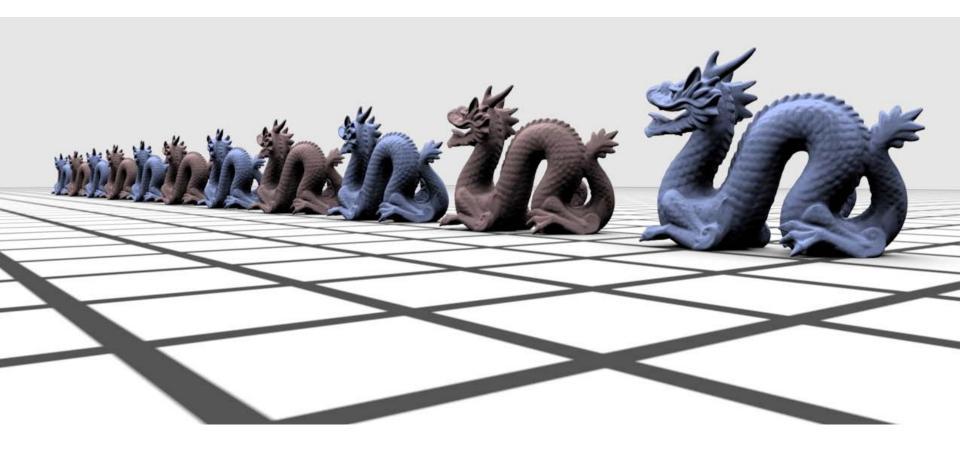
Normalize



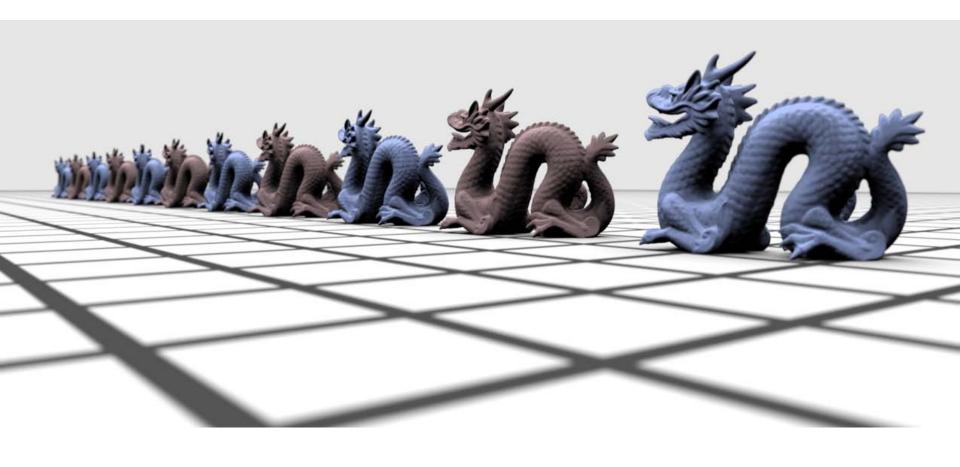


Cook et al. Siggraph'84

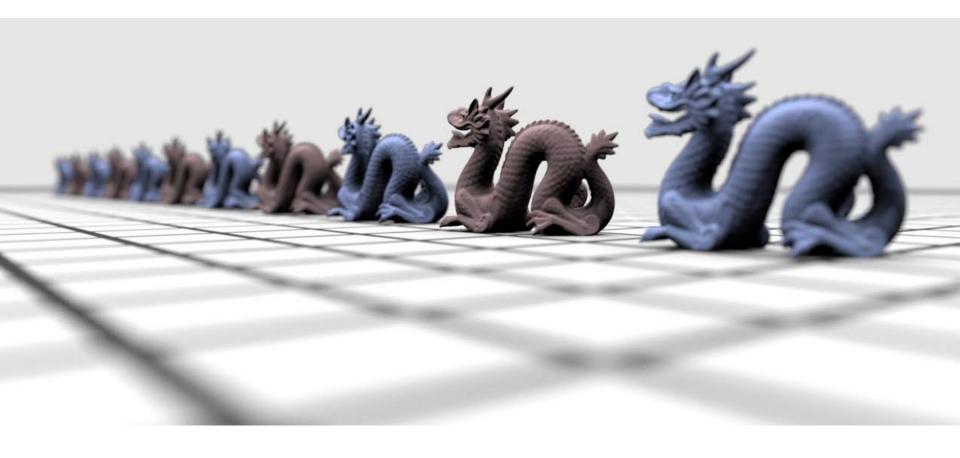
Zero Aperture



Small Aperture



Large Aperture



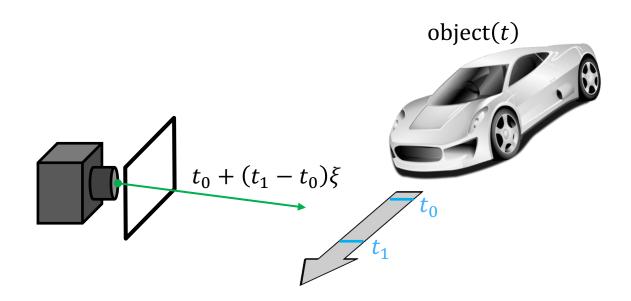
Very Large Aperture



### **Motion Blur**

#### Real Camera

- Finite exposure time
- Shutter opening at t<sub>0</sub>
- Shutter closing at t<sub>1</sub>



### **Motion Blur**

#### Real Camera

- Finite exposure time
- Shutter opening at t<sub>0</sub>
- Shutter closing at t<sub>1</sub>

#### Approach

- Sample time t in  $[t_0, t_1)$ :  $t = t_0 + \xi (t_1 t_0)$
- Assign time t to new camera ray/path
- Models with moving camera and/or moving objects in the scene
  - Time-dependent transformations
  - Transform objects or inverse-transform ray to proper positions at t
- Assume instantaneous opening and closing
  - Can be generalized by modeling shape of aperture over time

#### Gotchas

Acceleration structures built over dynamic objects

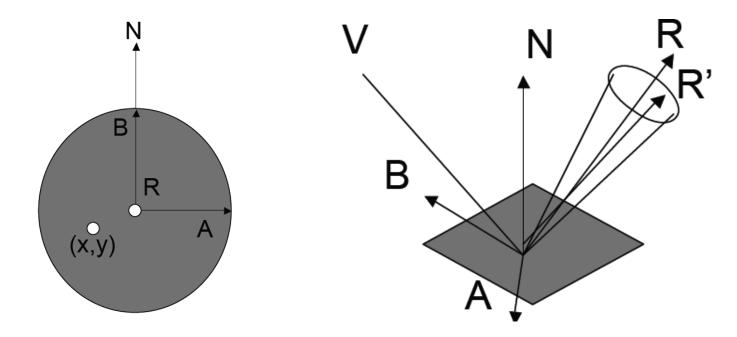
## **Motion Blur**



Cook et al. Siggraph'84

## Fuzzy Reflections/Refractions

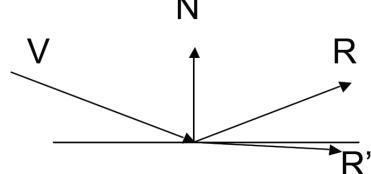
- Real Materials
  - Never perfectly smooth surfaces
- Empirical Approach
  - Compute orthonormal frame around reflected/refracted direction
  - Sample coordinates (x, y) on disc: ray.direction += x \* A + y \* B
- Or better use cos<sup>n</sup> sampling (→ GI Compendium)



## Fuzzy Reflections/Refractions

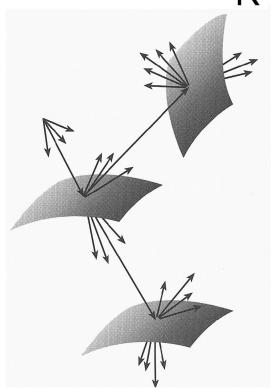
#### Gotchas

- Perturbed ray may go inside
- Check sign of dot product with N
- Ignore rays on wrong side (bias!)

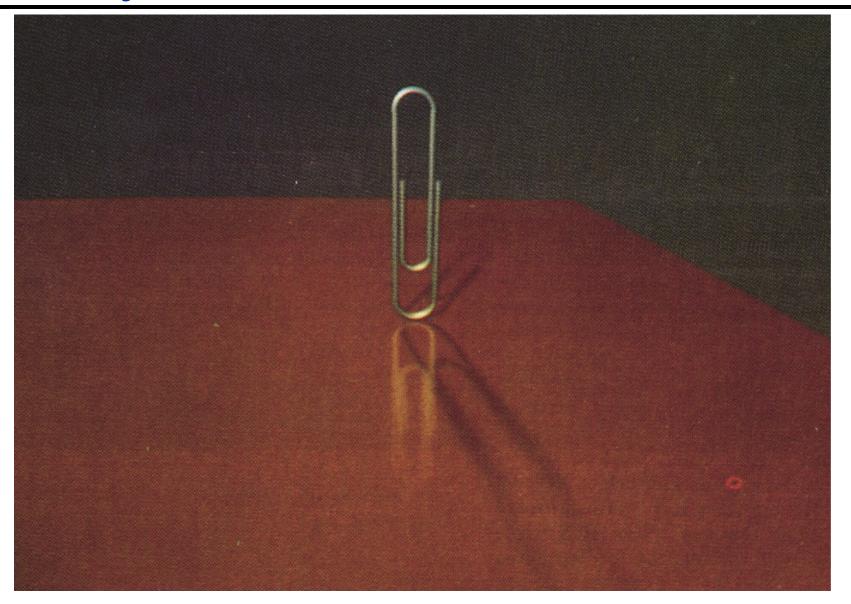


#### Inter-Reflections/Refractions

- Recursively repeat process
  - At surfaces with corresponding materials

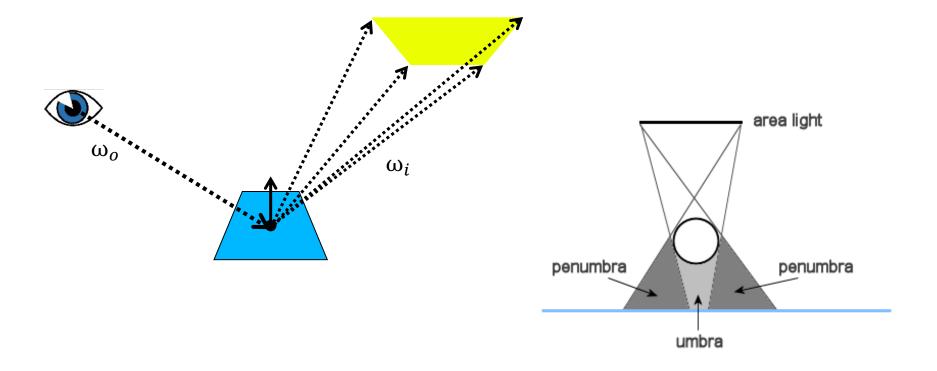


# Fuzzy Reflections/Refractions



### **Soft Shadows**

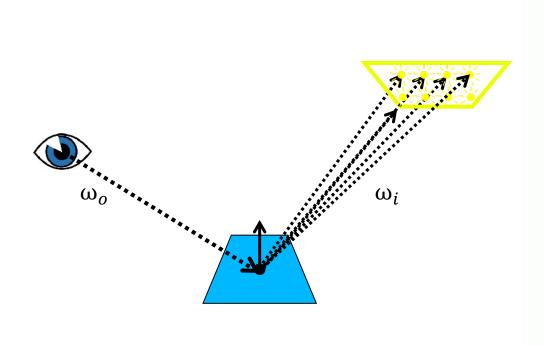
- Real Light Sources
  - Finite area

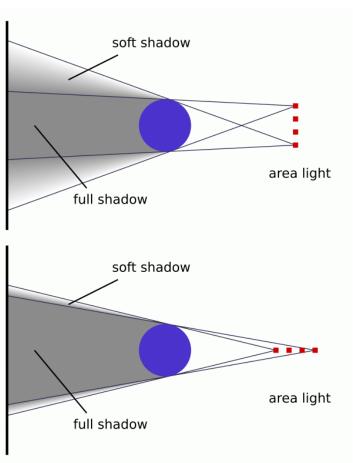


### Soft Shadows

### Approach

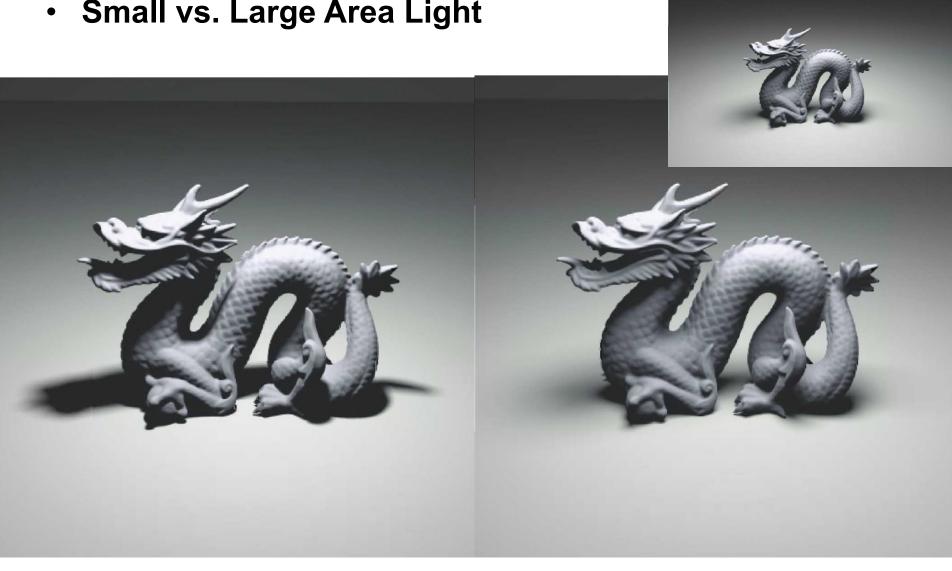
- Random sample point on surface of light source
- Scale intensity by area and cosine





### **Soft Shadows**

Small vs. Large Area Light



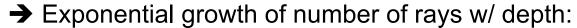
## Distribution Ray-Tracing

- It can do all of these things:
  - Anti-aliasing
  - Depth of field
  - Motion blur
  - BRDF
  - Area Lights
- It's great, right?
- Or is it?

### **Combined Effects**

#### High-Dimensional Sampling Space

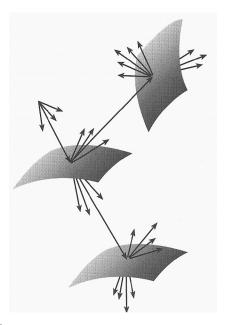
- number of anti-aliasing samples
- x number of lens samples
- x number of time samples
- x number of material samples
- x number of light samples



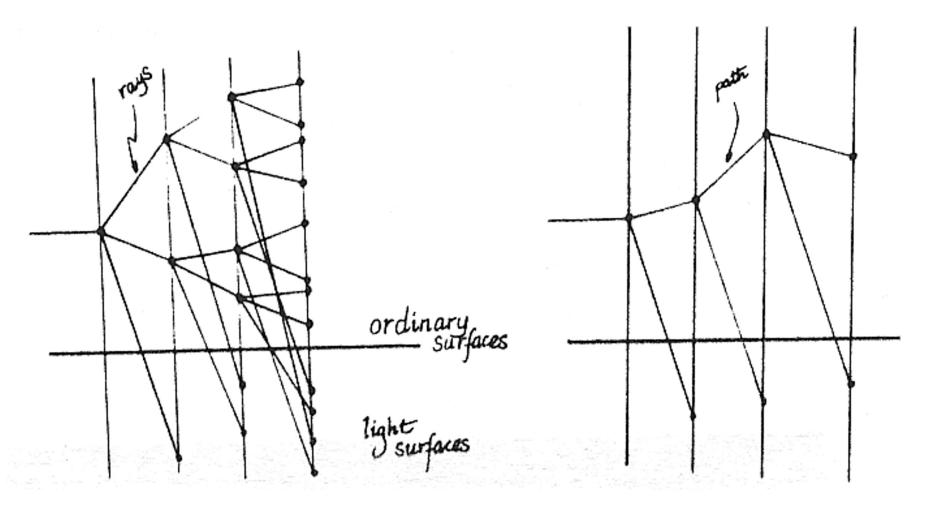
- Reflection <1 at each bounce → exponentially less contribution with each additional bounce
- →Exponentially increasing number of higher-order rays, with exponentially decreasing effect on final pixels
- This approach is (exponentially bad)<sup>2</sup>

#### Solution: Path-Based Approach

- Avoid exponential growth in ray tree
- Pick a single sample at each step: → Create a sample path
- Average results over several paths per pixel → path tracing (RIS)
  - Theoretical underpinning: Monte-Carlo Integration



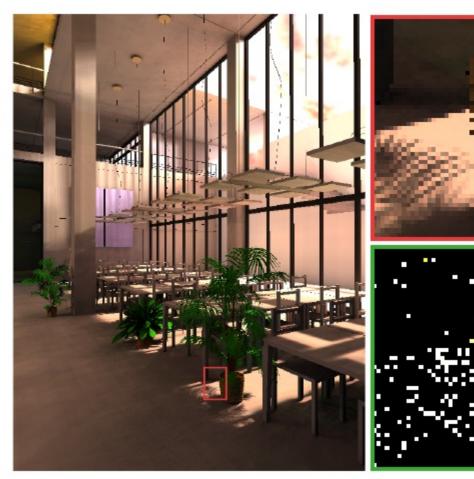
# Comparison to Path Tracing



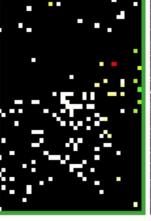
Distribution Ray Tracing

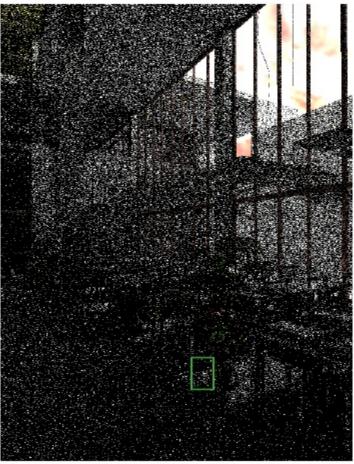
Path Tracing

- Importance Caching for Complex Illumination
  - By Iliyan Georgiev et al., Eurographics 2012

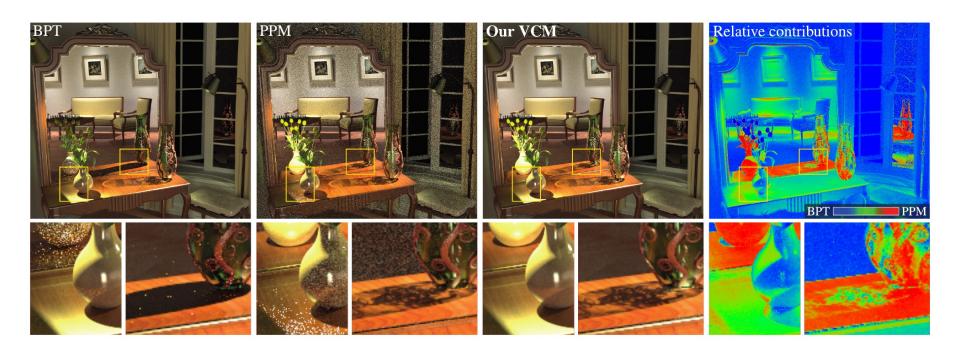




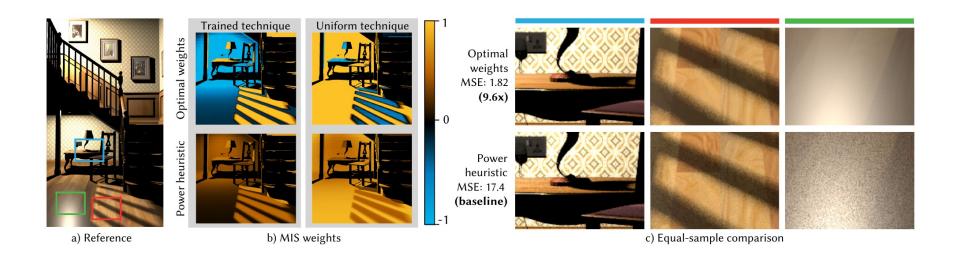




- Light Transport Simulation with Vertex Connection and Merging (VCM)
  - By Iliyan Georgiev et al., Siggraph 2012



- Optimal Multiple Importance Sampling
  - By Pascal Grittmann, Jarozlav Krivanek, et al., Siggraph 2019



### Variance-Aware Path Guiding

By Alexander Rath, Pascal Grittmann, et al., Siggraph 2020

